

ENS1161 Computer Fundamentals

Module 5

Applications, programming languages and translation

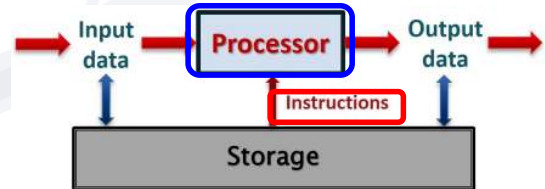
Module Objectives

On completion of this module, students should be able to:

- ▶ Explain the differences between high-level languages (HLLs) and assembly language, and the advantages and disadvantages of writing programs in each of these.
- ▶ Describe the process of translating programs into executable binary code, including the translator tools used.
- ▶ Explain how HLL program control structures are implemented using conditional branch instructions.
- ▶ Explain what a stack is and how it functions.
- ▶ Explain how subroutine calls and returns work, including the role of the stack in these processes.

Moving forward..

- ▶ Last module:
 - How the ALU works
 - Flags (condition codes)
 - Arithmetic and Logic instructions
 - Some instructions that use condition codes
- ▶ Focus of this module: Programs
 - Programming languages
 - Programming 'tools' that convert programs to binary code



Introduction

- ▶ **Module Scope**
 - Levels of programming languages
 - Control structures in programming
 - Tools to convert program code to machine language
 - Roles, advantages and limitations

Using computing devices

- ▶ There are a wide variety of computing devices
 - From embedded systems in appliances, to mobile phones and laptops to desktop computers and servers.



- ▶ We use these devices though a wide variety of **applications (apps)**

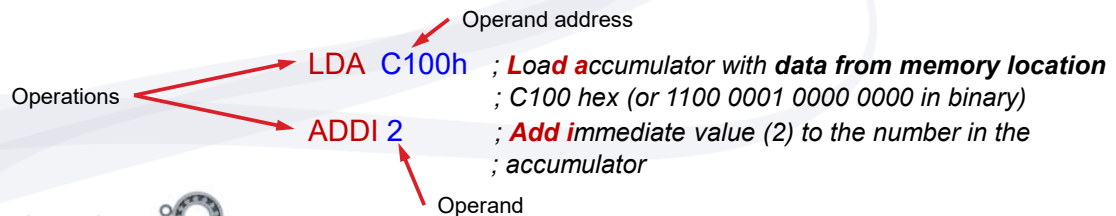


Types of software *(recap Module 1)*

- ▶ 2 broad categories:
 - **Operating system**
 - Main function is to control the hardware and enable other software to interface with the hardware
 - Also acts as 'control program' for other applications
 - e.g. Windows, macOS, Android
 - **Application software**
 - Designed to perform a certain type of function
 - E.g. wordprocessor, browser, spreadsheet, etc.
 - *Operating systems covered in more detail in Module 9*

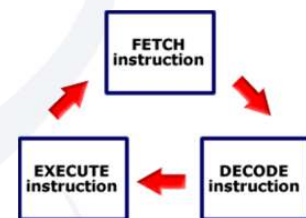
What is a program? *(recap Module 2)*

- ▶ A program is a series of **instructions**
 - stored in the memory sub-system
 - **fetch**ed and **exec**uted sequentially
- ▶ Each instruction consists of two parts
 - an **operation**
 - an **operand** or **operand address**
 - **data** / **location of the data** on which to perform the **operation**



How a Computer System Works *(recap)*

- ▶ A processor needs a set of **instructions**
 - tells it what **operations** to perform on what **data**
- ▶ **Instructions** (**programs**) are stored in **memory**
- ▶ The microprocessor:
 - **fetch**es an **instruction** from memory
 - **dec**odes it, and
 - **exec**utes the specified **operation**
- ▶ Sequence of **fetch**, **dec**ode and **exec**ute continues indefinitely
 - Until reach an instruction to stop or powered off



Instruction Set *(recap Module 2)*

- ▶ A processor can ONLY execute the **set of instructions** it was built to understand
 - *The set of operations a processor can perform*
 - **Different** for every processor family
- ▶ Each instruction (or variation of it) has a unique **opcode**
 - Also called **object code** or **machine code**
- ▶ Each instruction requires specific series of simple steps to complete the required operation
 - Normally done by a built-in *microprogram* (or *microcode*) in the Control Unit
 - Generates the controls signals for the instruction in the right order and at the right time
 - In the *Execution* phase, each opcode results in a separate microprogram being run

Instruction set and programs

- ▶ **Instruction**: **binary code** interpreted by the CPU to perform an action
- ▶ A **program** is a series of **instructions** in binary that the processor can read and interpret
- ▶ Difficult for humans to write programs in 1s and 0s, so programs are written in more 'human-like' programming languages
 - E.g. assembler, C, Java, Python
- ▶ These programs are **translated** to binary using **other programs**
 - Assemblers, compilers

Assembly language *(recap Module 2)*

- ▶ A program is a series of instructions in **binary** that the processor can read and interpret (*decode*)
- ▶ Difficult to write programs in 1s and 0s, so use *assembly language*
- ▶ **Assembly language**
 - programs use 3 or 4 character **mnemonic** English abbreviations
 - mnemonics correspond to the binary **opcodes** that the processor understands
 - E.g. **LDA** = 1011 0110 (*B6* in hexadecimal), **ADDI** = 1011 1010 (*BAh*)
 - translated to binary using an **assembler** program

LDA C100h ; **Load** accumulator with **data from memory location**
; C100 hex (or 1100 0001 0000 0000 in binary)
ADDI 2 ; **Add** immediate value (2) to the number in the
; accumulator

1011 0110
1100 0001
0000 0000
1011 1010
0000 0010



Assembler

- ▶ An **assembler** is a program that converts *assembly language* programs to **object code** (binary code / machine language)
 - The process of conversion is called *assembly* or *assembling*
- ▶ Also allows programmers to use **symbolic names**
 - for data, functions and locations within programs
 - The assembler will work out (*resolve*) the actual memory addresses during assembly

MOV AL, first_val ; 1st value into register AL
ADD AL, second_val ; add the 2nd value to AL
MOV result, AL ; store the answer in result

MOV AL, 100h
ADD AL, 101h
MOV 130h, AL

Addresses
resolved
by assembler

0100 1010
0000 0001
0000 0000
0000 0010
0000 0001
0000 0001
0100 1000
.....



Advantages of programming in assembly

- ▶ There are some advantages of programming in assembly language over machine code:

- Programmers can work with **symbolic names**
 - As opposed to just binary code or numeric addresses
- Assemblers can **detect** certain **errors**
 - Syntax errors, invalid addressing modes, etc.
- Programs can be **optimised**
 - Can be tailored to take full advantage of hardware features
 - However, requires understanding of processor architecture and operation
- If done properly, code can be more **compact**

```
MOV AL, first_val
ADD AL, second_val
MOV result, AL
```

Limitations of assembly language

- ▶ Requires knowledge of the particular **processor's instruction set**
 - One-to-one between processor instruction and assembly code
- ▶ Requires understanding of the **processor's architecture**
 - Registers available, addressing modes
- ▶ The programs are **not portable**
 - Programs are tied to a particular processor or family of processors
 - Can't be run on other types of processors
- ▶ Quite cumbersome
 - Code / steps linked to the way the particular processor works
 - Does not reflect the way human's think or describe their processes

- ▶ **Solution: High-level languages**

```
MOV AL, first_val
ADD AL, second_val
MOV result, AL
```

```
; 1st value into register AL
; add the 2nd value to AL
; store the answer in result
```

High-level languages

- ▶ Programming languages that are designed for human programmers
- ▶ Problem-oriented
 - Focuses on program logic
- ▶ **Abstracts** away the machine level details
 - Programmer does not need to know the underlying processor hardware architecture / components
- ▶ Makes **code portable**
 - Not tied to a particular processor / instruction set / architecture
- ▶ *Examples of HLL: C, Java, Python*

result := first_val + second_val ;

Compiler

- ▶ High-level programs will still need to be translated down to machine code before it can be executed on a processor
- ▶ Process is carried out by an application called a **compiler**
 - **Compiler** processes **HLL program code** and generates **assembler code** for the target processor
 - **Assembler** then processes that to generate **object code** (*executable binary code*)
 - **Note:** The process consists of a number of stages – beyond the scope of this unit

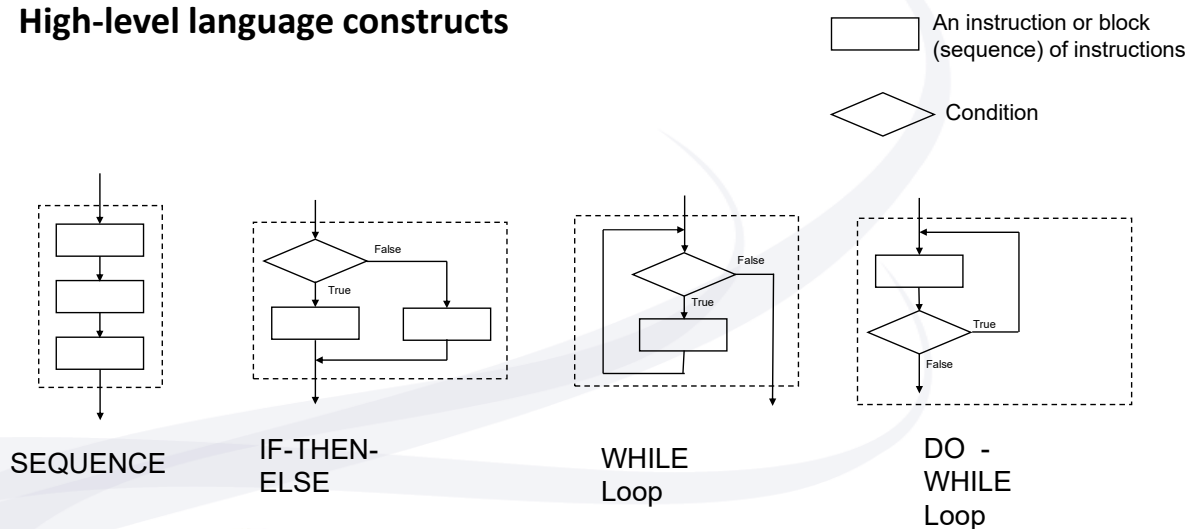


Program flow control

- ▶ Simplest program is a simple *straight-line* (**sequential**) program
- ▶ Execution is carried out on instructions stored sequentially in memory
 - limited to relatively simple programming tasks
- ▶ For more complex programs some form of **branching** (which includes **looping**) is usually required
- ▶ **Branching** allows the microprocessor to break out of the normal straight-line sequence
 - **Jump** or **branch** to a different section of code in **program memory** to continue executing instructions

Program flow control

▶ High-level language constructs



Jump and Branch Instructions

- **Unconditional jump**
 - Processor will *always* jump to the **new address** given (e.g. **JMP**)
 - **new address** loaded into PC
 - Refer addressing modes – Module 3
- **Conditional branch** instructions
 - more flexibility in program flow control
 - will alter the sequence of execution only when specific **conditions** are met
 - E.g. JZ, JNZ, JG, etc. (refer conditional branch instructions – Module 4)

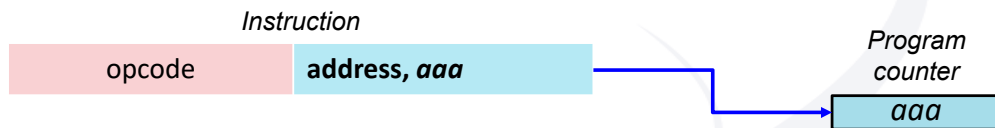
Conditional Branch Instructions (recap)

- ▶ Most **conditional branch** instructions are designed to be used after a **CMP** or arithmetic operation between two operands
 - e.g. A and B
- Action whether to **branch (jump)** or not based on particular flags

Mnemonic	Condition	Mnemonic	Condition
JA	A > B (unsigned)	JC	C flag = 1
JAЕ	A ≥ B (unsigned)	JNC	C flag = 0
JB	A < B (unsigned)	JNO	O flag = 0
JBE	A ≤ B (unsigned)	JNP	P flag = 0
JE	A = B (Z = 1)	JNS	S flag = 0
JG	A > B (signed)	JNZ	Z flag = 0
JL	A < B (signed)	JO	O flag = 1
JNA	A ≥ B (unsigned)	JPE	P flag = 1
JNE	A ≠ B	JS	S flag = 1
JNL	A < B	JZ	Z flag = 1

Absolute program addressing *(recap Module 3)*

- ▶ Also known as *direct* mode
- ▶ The instruction specifies a value that is written directly to the PC register



- *Intel 8086* example
 - `JMP 02A3H` ; Program to **Jump** to location 02A3h

Relative program addressing *(recap Module 3)*

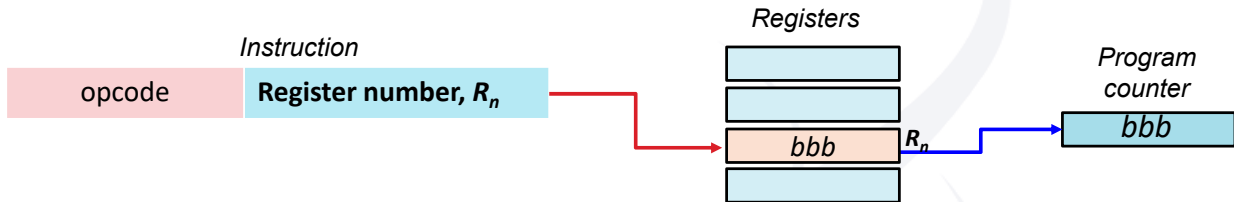
- ▶ The instruction specifies a value (positive or negative) that is added to the PC register
 - Causes the program to move forward or backward a certain number of bytes



- *Intel 8086* example
 - `JNZ 08` ; **Jump** if previous result is **Not Zero** forward 8 bytes

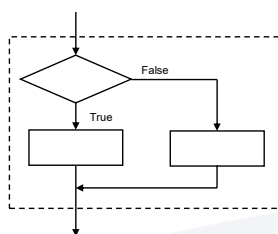
Indirect program addressing *(recap Module 3)*

- ▶ The program counter is loaded with the value from the register specified in the instruction



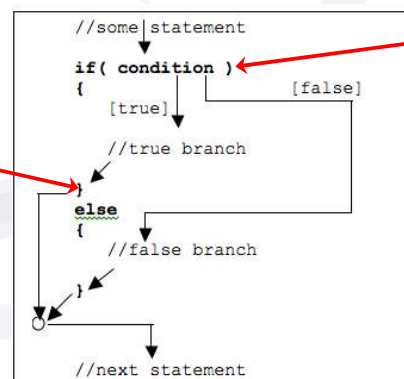
IF .. THEN .. ELSE

- ▶ IF **condition** = **TRUE** : **THEN** branch executed
- ▶ IF **condition** = **FALSE** : **ELSE** branch executed
- ▶ One conditional branch and one unconditional jump instruction required



IF-THEN-ELSE

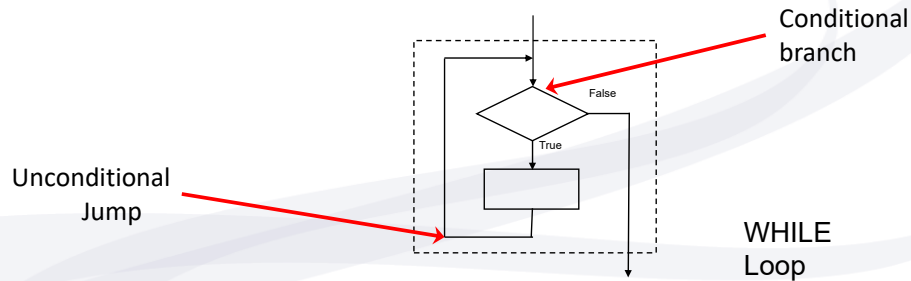
Unconditional
Jump



Conditional
branch

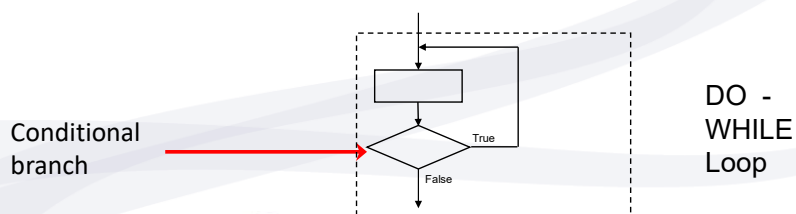
WHILE Loop

- ▶ Condition tested at the **start** of the loop
- ▶ IF condition = **True** THEN execute the loop code ELSE exit the loop
 - Similar to IF statement except that unconditional jump is back to the condition check
- ▶ Code in the loop is never run if condition is false the first time checked



DO – WHILE Loop

- ▶ Condition tested at the **end** of the loop
- ▶ IF condition = **True** THEN loop back to start (*DO*) ELSE continue next instruction (*exit the loop*)
 - Only requires 1 conditional branch instruction
 - Condition at the end of the loop
- ▶ The loop code will run at least once
 - even if condition is false the first time checked



Assembler features for flow control

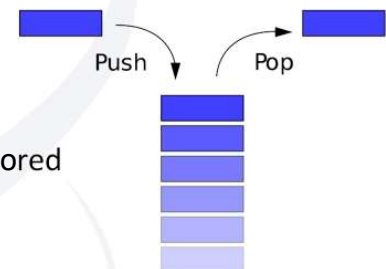
► Symbolic Addresses (Labels)

- One of the most useful features of assembly language programming:
 - **symbolic addresses** may be used
 - instead of **physical RAM** addresses

Address	Label	Mnemonic	Comments
0100	Start:	CMP AX, BX	; Compare registers AX and BX
0101		JNE Here	; Jump to label 'Here' if not equal ; (difference not 0)
0102		JMP FarAway	; Otherwise jump to label 'Faraway'
0103	Here:	; Code to be done if not equal
...
0200	Faraway:		; Some code fragment elsewhere for 'ELSE'

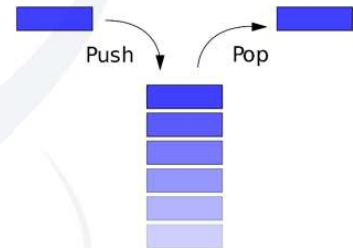
Stack

- A data structure (memory locations)
 - Primarily for temporary storage of information
- Storing ('**pushing**') a word
 - puts it at "top" of stack
 - location address is one word less than the previous word stored
- Words must be read ('**popped**') from the **top of stack**
 - in the opposite order from that in which they were placed
- The stack is referred to as being **last in, first out** or **LIFO**
- The address of the top of the stack is stored in the **Stack Pointer** register (**SP**)



Stack

- ▶ An important concept in programming
- ▶ Used by **programmers** :
 - Temporary storage of **register** contents etc.
- ▶ Used by the **processor** :
 - Storage of **return addresses** and other critical information
 - During **subroutine calls** (*covered next*)
 - Also for **interrupt service routines** (*covered in Module 8*)

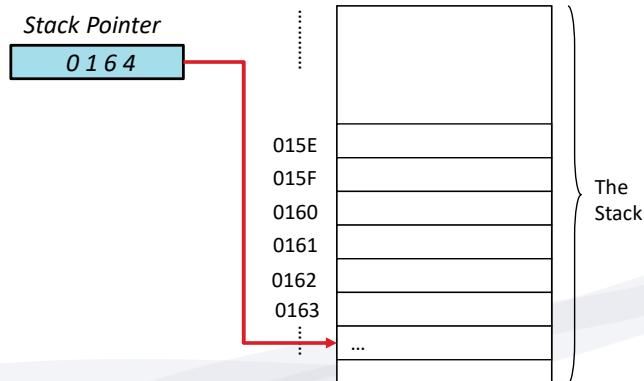


Stack Instructions

- ▶ **8086 Stack Instructions**
 - The processor controls the **stack pointer (SP)** during these operations
- ▶ **PUSH Reg / Mem**
 - Decrements **SP** by 2 (*stores 16-bit values, 2 bytes*)
 - Moves pointer up to new 'top of stack'
 - Copies contents of the specified **register** or **memory** location onto the **stack**
- ▶ **POP Reg / Mem**
 - Copies data from the **top of the stack** (pointed to by **SP**)
 - Then loads the data into the specified **register** or **memory** location
 - Increments **SP** by 2
 - Moves pointer down to new 'top of stack'

Pushing onto the stack

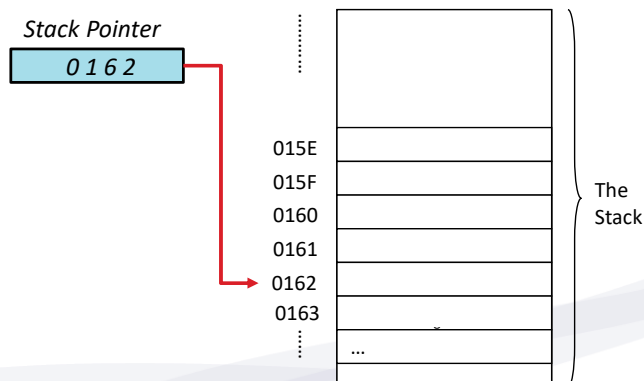
- **Example**



- 3 words stored onto the **stack**:
 - Word A
 - then B
 - finally Word C
- Initially **SP** = **address** 0164h

Pushing onto the stack

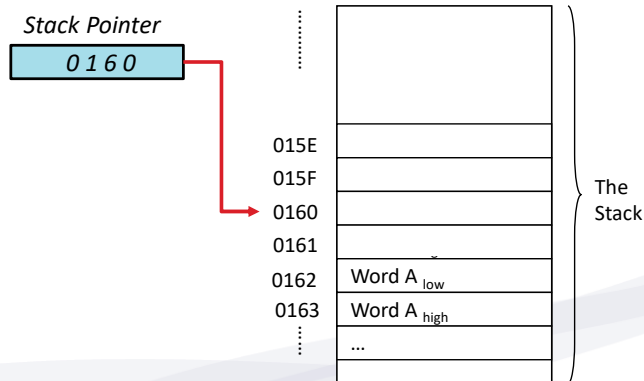
- **Example**



- 3 words stored onto the **stack**:
 - Word A
 - then B
 - finally Word C
- Initially **SP** = **address** 0164h
- When Word A pushed:
 - **SP** automatically decremented to point to 0162h
 - Then Word A stored (*little endian*)

Pushing onto the stack

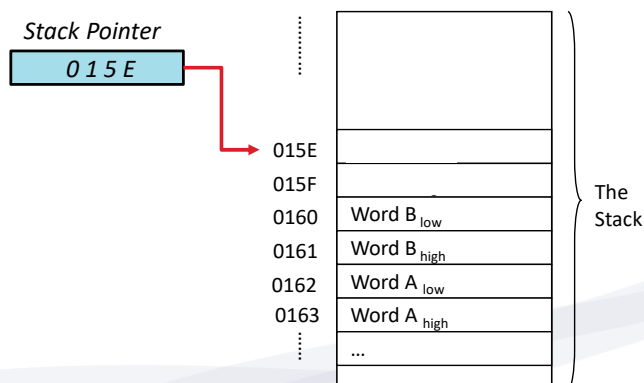
Example



- 3 words stored onto the **stack**:
 - Word A
 - then B
 - finally Word C
- Initially **SP** = **address** 0164h
- When Word A pushed:
 - **SP** automatically decremented to point to 0162h
 - Then Word A stored (*little endian*)
- Then Word B

Pushing onto the stack

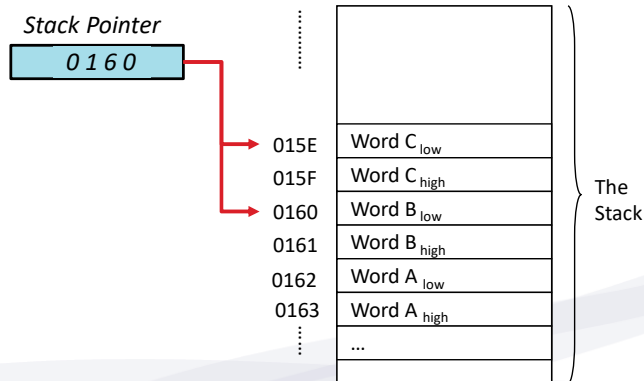
Example



- 3 words stored onto the **stack**:
 - Word A
 - then B
 - finally Word C
- Initially **SP** = **address** 0164h
- When Word A pushed:
 - **SP** automatically decremented to point to 0162h
 - Then Word A stored (*little endian*)
- Then Word B
- After Word C pushed:
 - **SP** will contain the address 015Eh
 - the new "**top**" of the stack
- Reverse process happens when '**popping off**' data from stack.

Popping off the stack

- **Example**

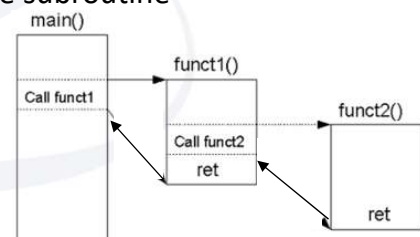


- Reverse process happens when 'popping off' data from stack.
- E.g POP AX
 - Top of stack data copied to register AX
 - Then **SP** automatically incremented to point to 0160h
 - the new "top" of the stack

Subroutines

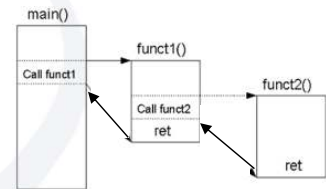
- ▶ **What is a Subroutine?**

- A **subroutine**:
 - is a **sequence of instructions** that perform a specific task
 - it is written once and stored in a specific area of memory
- When main program needs to perform that task:
 - the processor simply jumps to the address for the subroutine (**call**)
 - **executes** the code there
 - **returns** to original program when done



Calling a subroutine

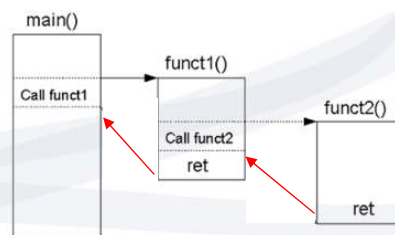
- ▶ Most processors have a **CALL** Instruction
 - Used to direct the processor to jump to a subroutine
 - Name may vary, but function is essentially the same
 - Operand provided gives the **subroutine address** to go to
 - The **subroutine address** is loaded into the **program counter (PC)**
 - Execution of subroutine continues as normal till the end of the routine
 - Program execution **returns** to calling routine (*next instruction*)



- ▶ How does processor now how to go back to **calling routine**?
 - The **PC** register contents are **pushed onto the stack** before new subroutine address is loaded

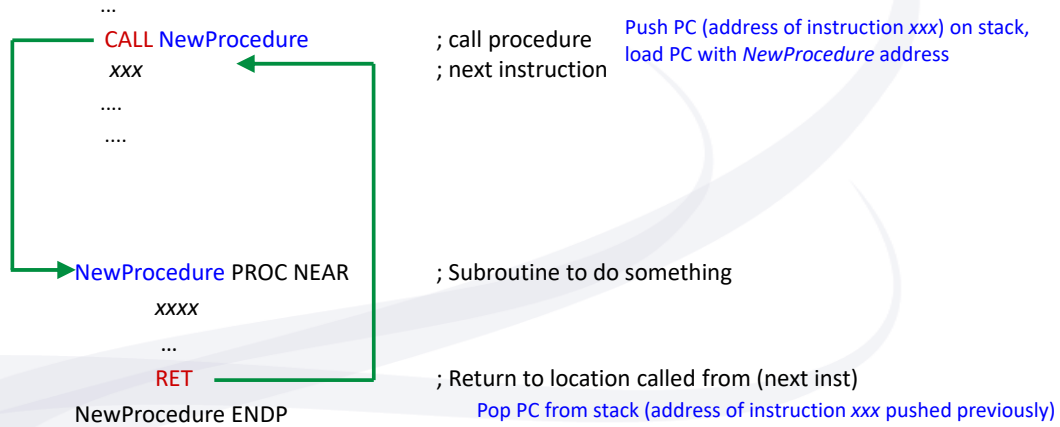
Returning from a subroutine

- ▶ Most processors have a Return (**RET**) instruction
- ▶ Used to direct the processor to return to the calling process
 - The **RET** instruction **pops the return address** back from the top of the stack into the **PC** register
 - Continues with next instruction after the initial CALL

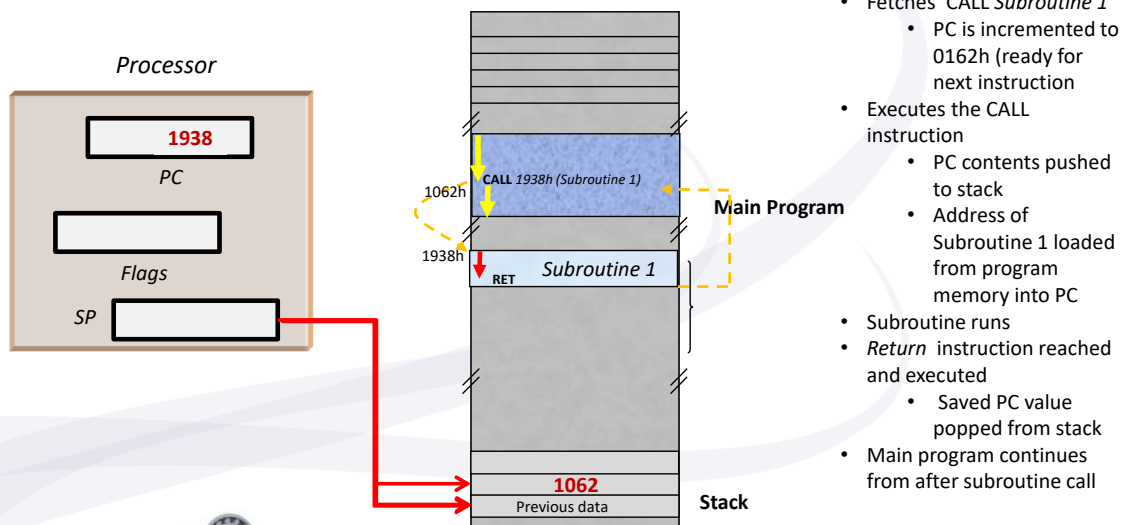


Subroutines

► Example using assembly language



Subroutine Calls

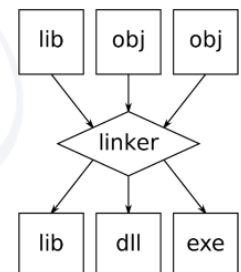


Why use subroutines?

- ▶ Allows for efficient and logical coding
 - Commonly used functions can be embedded in **subroutines** and called repeatedly as needed
 - Do need to repeat the code for a function over and over in the main program
 - Once tested, can be sure the routine works – less errors
- ▶ Allows for previously developed code to be used
 - E.g. **library** functions
- ▶ Allows code written in a different platform / language to be **linked**
 - Provided interface / parameter passing is correct
 - E.g. calling an assembly routine from a C program

Linker

- ▶ A linker is a program that combines various **object files** into a single **executable file**
 - A program may call many subroutines that sit in various libraries
 - The linker pulls in the required (called) library functions and creates a single executable (machine code) file that has all the required code.
- ▶ Linkers may also **relocate code**
 - Change the addresses of absolute jumps, load and stores
 - Based on where a program is loaded in memory



Assemblers, Compilers and Linkers

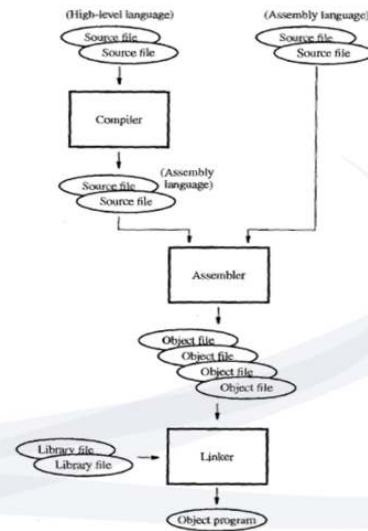


Figure 4.1 Overall flow for generating an object program.

(Hamacher, 2016)



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On completion of this module, students should be able to:

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- ▶ Describe the process of translating programs into executable binary code, including the translator tools used.
- ▶ Explain how HLL program control structures are implemented using conditional branch instructions.
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