Quantitative Model Checking of

Resourceconstrained Business Processes

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The Problem

- → Assume a loan providing business
- → Thousands of cases come in a day
- Such systems involve probability, nondeterminism and concurrency

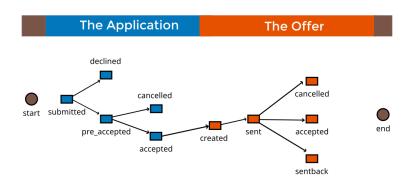
Primary question: will each case eventually be resolved in time?

The Problem

A complex question: do most cases get resolved in time?

→ When C cases arrive at a rate of λ per second, with probability $\geq p$, at least x% are completed within time t.

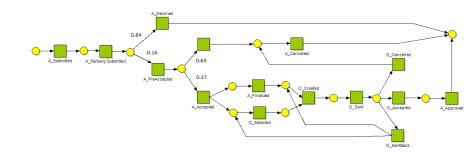
An individual case



(some edges are omitted)



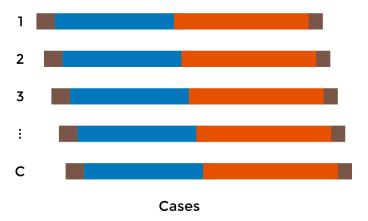
The Real-life Case





Resource-constrained Process







Resource-constrained Processes

An Individual case

- → Start state, finite set of tasks and final state
- → Tasks are combined in sequence or parallel
- → Probabilistic branches

Finite resources

- → Resource allocation strategies are simple
- → Often priority-based (platinum/gold/silver)

State-of-the-art Approach

- → Simulate an arbitrary number of times
- \rightarrow Claim that the probability $\geq p$ if p fraction satisfies the property
- → No sample size or error bound analysis

"simulation does not provide any proof"

Van der Aalst on using simulation for analyzing processes



Our Approach

→ Let's use quantitative model checking

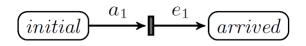
→ Rigorous modeling formalism

→ Statistical model checking for simulation

First Step: The Model

- → model tasks and resources as agents
- → agents interact among each other
- → fixed-duration real-time and cost
- → resource-contention brings nondeterminism

The Model



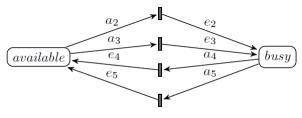
(i) the starter.

a: action *e*: event

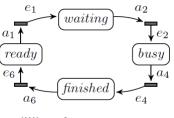
 p_e : probability, δ_e : duration



The Model



(ii) the resource



(iii) task A_Submitted



The Model

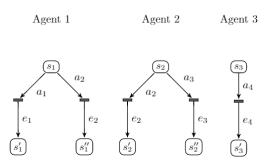
- \rightarrow r resources, C cases each with k_T tasks
- \rightarrow modeled with $r + C \times (k_T + 2)$ agents
- → Global state: product of local state of agents
- → A set of actions are enabled at a global state
- → Some of them are schedulable

Defining Schedulers

- → Given a global state, multiple set of schedulable actions
- → Need a scheduler to resolve it
- → Not trivial due to concurrency
- → Scheduler has to "obey" concurrency



Defining Schedulers



enabled: a_1, a_2, a_3, a_4

schedulable: $\{a_1, a_3, a_4\}$, $\{a_2, a_4\}$...

Snapshots

A snapshot includes

- \rightarrow a global state
- → a list of partially executed events
- with their time to completion from the current time point

Schedulers are defined in the snapshot space



Schedulers

- → The scheduler respects the partially executed events, by design
- → That is the only restriction
- → Finite memory schedulers
- → Given a scheduler, the transition system is a countably-infinite Markov chain



Defining Transition

- → Given a snapshot
 - → take the scheduled actions,
 - → set of events are chosen probabilistically
 - → those with minimum duration will complete first
 - → that defines the transition and the next snapshot
 - → The probability is the product of chosen event probabilities



Simulation with Guarantees

→ Use traditional statistical model checking

→ Sample size analysis

→ Error of simulation is bounded upfront

Experiments

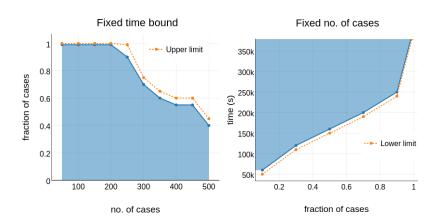
We are interested in:

When C cases arrive at 1 case per 10s, with probability ≥ 0.99 , x fraction are completed within t seconds.

Let's play with *x*, *C*, and *t*.



Experiments



(left) time bound is fixed, (right) total number of cases is fixed

Future Directions

- → Integrate with process mining
- → Compare schedulers and suggest improvements
- → Not much 'business' about this technique apply to generic processes

Thank you!

Questions?