

### Robotics, Autonomous systems



# Weekly Report N°14 for

School year 2023-2024

## RubbleScout,

"Navigating Chaos, Saving Lives"

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### **Objectives:**

- Begin the exploration of NVIDIA Jetson Nano capabilities.
- Experiment with AI models using a camera module.

#### **Activities Undertaken:**

#### 1. Jetson Nano Setup:

- Initialized the Jetson Nano development kit, setting up the necessary operating system and drivers.
- Familiarized with the software environment and available resources/documentation provided by NVIDIA.

#### 2. Al Experimentation:

- Connected a camera module to the Jetson Nano and ran sample AI programs to gauge the processing capabilities.
- Explored basic object detection and image processing functionalities as preliminary tests for potential search and rescue applications.

#### **Results and Observations:**

- **Jetson Nano Familiarization:** Successfully set up the Jetson Nano and began exploring its extensive AI capabilities, noting the ease of use and powerful processing potential.
- Al Model Testing: Initial Al tests with the camera module demonstrated the Jetson Nano's ability to handle real-time data analysis, a promising feature for integrating Al into RubbleScout's systems.

#### **Next Steps:**

- **Deep Learning Integration:** Plan more advanced tests using deep learning models tailored for object recognition and environmental analysis relevant to search and rescue scenarios.
- **Real-World Testing:** Implement the AI functionalities in more practical, real-world conditions to test their reliability and accuracy.
- **Performance Benchmarking:** Assess the Jetson Nano's performance benchmarks in various operational settings to ensure it meets the project's requirements.

#### Reflections:

This session marked the beginning of a pivotal phase in the RubbleScout project, delving into the capabilities of the NVIDIA Jetson Nano. The potential to enhance RubbleScout with Al-driven features promises a significant leap forward in its development. As the project moves into more complex Al implementations, the insights gained from this session will serve as a valuable foundation for future advancements.