

Lexium32: Inspired by simplicity!



Wiring of Lexium 32

For the minimum configuration the drive and the motor encoder must be connected, also the fieldbus (termination on both line ends), 24V external power supply and general power supply (3~ or 1~, depending on your device). Very important are the safety inputs STOA and STOB. If the limit switches are enabled they also need to be connected, otherwise they could be disabled with the commissioning tool.

If the wiring is ok the drive will go automatically to state 4 (rdy in the HMI).

Example of operation via fieldbus

The product is controlled via CANopen.

