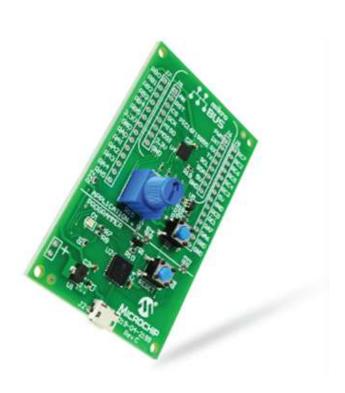


2016

# Interfacing Stepper motor with MPLAB Xpress Evaluation Board



siva A

Tenet Technetronics

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### Introduction

MPLAB Xpress IDE cost free development platform. It's cloud Based IDE available from microchip supporting PIC-based microcontrollers. The platform is comprised of code editor, build automation tools, debugger, code configurator. MPLAB Xpress IDE is an end-to-end solution enabling engineers to develop their applications from initial evaluation to final production.

### **Component Requirement**

### > Hardware:

- MPLAB Xpress evaluation tool
- Stepper motor
- ULN2003 motor driver IC

### > Software:

MPLAB Xpress IDE

Note: we have on board LED

### **Procedure**

## Step 1: Open MPLAB X IDE

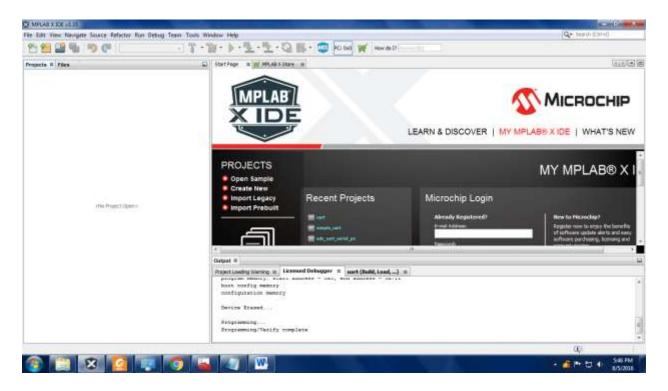


Figure 1 MPLAB X IDE main window

Step 2: start creating our new project. Go to File >> New Project. Select microchip embedded as well as standalone project then click next

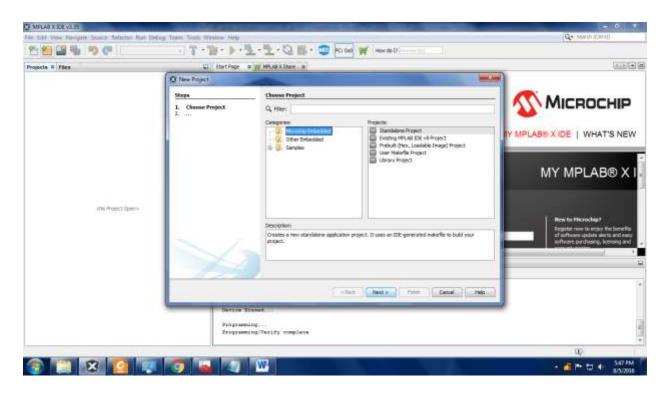


Figure 2 Open new project

Step 3: Select device pic16f18855, and click next.

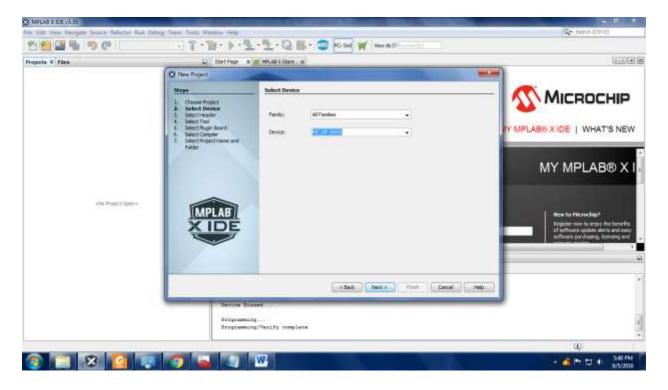


Figure 3 select Device

# **Step 4:** Now select tool **Licensed Debugger** and click **Next.**



Figure 4 Select Debugger

# **Step 5:** Now select tool select the **XC8compiler** and click **Next.**

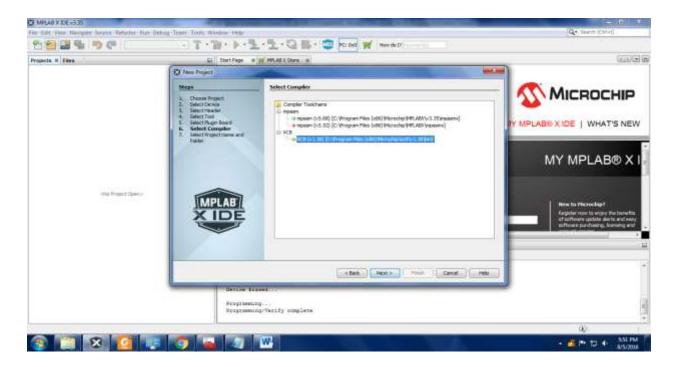


Figure 5 Select Compiler

# Step 6: Now give project name and project location folder and click finish.

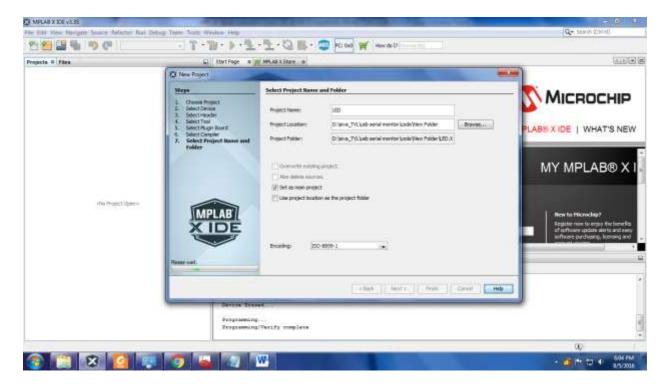


Figure 6 Assign project name

Step 7: Now we can see our project onto the workspace. Then, go to File >> New file then choose file type c as main file then click next.

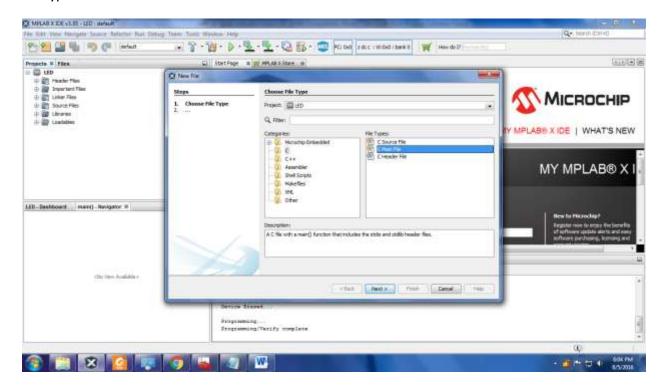


Figure 7 Add new file

# **Step 8:** Now give file name and file location folder and click finish.

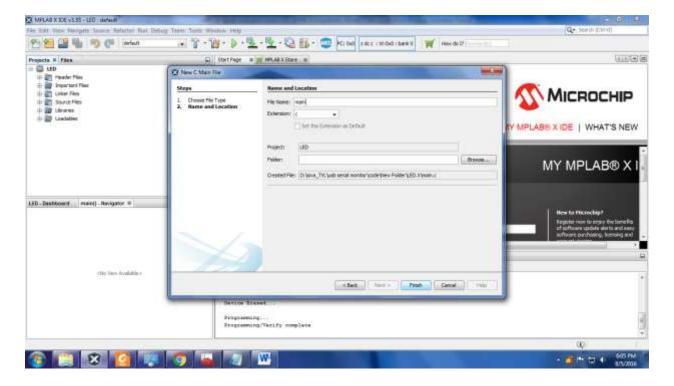


Figure 8 name the file

**Step 9:** Erase the template in editor window. Then type following code in the editor window.

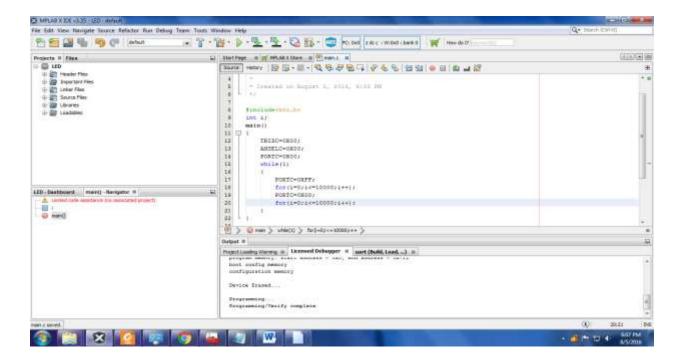


Figure 9 Editor Window with Code

### **SOURCE CODE:**

```
#include<htc.h>
int i;
main()
{
                                    //Port-B set as output
    TRISB=0X00;
                                    //port-B set as Digital IO
    ANSELB=0X00;
    PORTB=0X00;
                                    // Clear port-B
    while(1)
                                    // continues execution
    {
        RB0=0;
        RB4=0;
        RB2=0;
        RB3=1;
        for(i=0;i<=30000;i++); //delay
        RB0=0;
        RB4=0;
        RB2=1;
        RB3=0;
        for(i=0;i<=30000;i++);
                                    //delay
        RB3=0;
```

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```
RB0=0;
       RB4=1;
       RB2=0;
       for(i=0;i<=30000;i++);
                              //delay
       RB0=1;
       RB4=0;
       RB2=0;
       RB3=0;
       for(i=0;i<=30000;i++);
                              //delay
   }
}
```

**Step 10**: After writing code, save it then Go to Run >> Clean and Build main project.

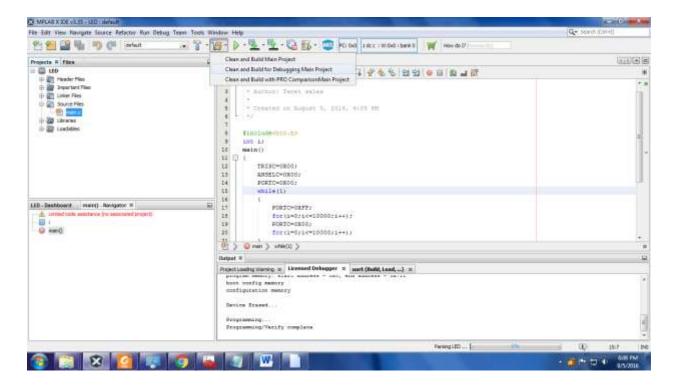
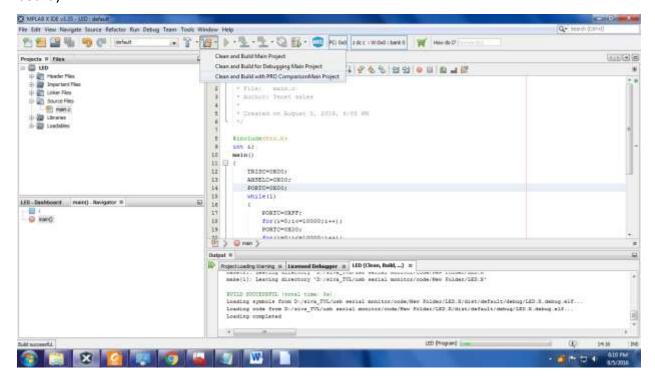
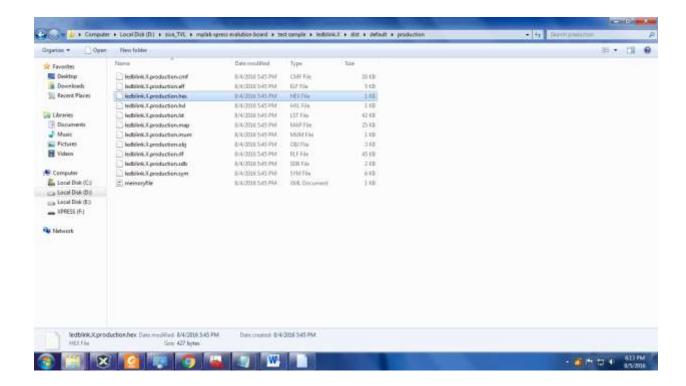


Figure 10 Build the project

**Step 11:** Now, if all goes well connect the Micro B cable to PIC16F18855 (pic demonstration board)



**Step 12:** To upload the project file, copy your hex file (.hex) past to your device. Ensure your device connection.



## **Output:**

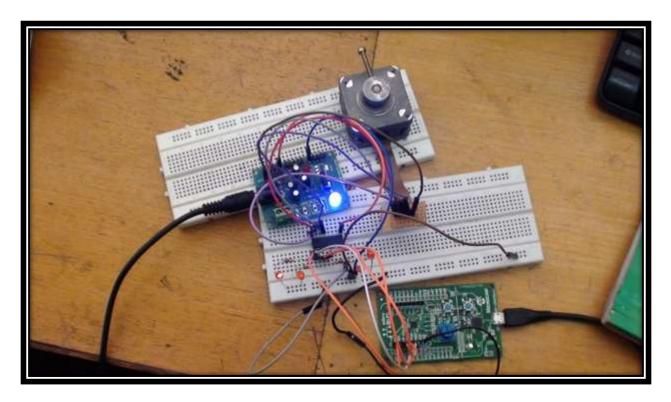


Figure 12 output

# For product link:

http://www.tenettech.com/product/8828/mplab-xpress-development-board

For more information please visit: www.tenettech.com

For technical query please send an e-mail: info@tenettech.com