

2016

Interfacing SenseHat With Raspberry Pi



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Introduction:

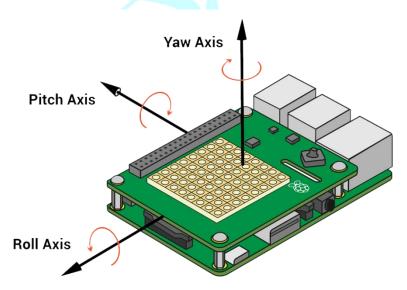
Raspberry Pi is a credit card sized computer that plugs into a computer monitor or TV, and uses standard keyboard and mouse. It's capable of doing everything you'd expect a desktop computer to do, from browsing the internet and playing high-definition video, to making spreadsheets, word-processing, and playing games. Here we are going to interface sensehat with Raspberry Pi.

Hardware Requirements:

- 1. Raspberry Pi board.
- 2.Sense Hat

Sensehat:

The Sense HAT is an add-on board for Raspberry Pi, made especially for the Astro Pi mission – it launched to the International Space Station in December 2015 – and is now available to buy.



The Sense HAT has an 8×8 RGB LED matrix, a five-button joystick and includes the following sensors:

- Gyroscope
- Accelerometer
- Magnetometer
- Temperature
- Barometric pressure
- Humidity

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Code:

Printing letter on LED Matrix

```
fromsense_hat import SenseHat

from time import sleep

sense=SenseHat()

sense.show_letter('T',text_colour=[255,0,0])

sense.clear()
```

Print Message on LED Matrix

```
fromsense_hat import SenseHat

from time import sleep

sense=SenseHat()

while 1:

sense.show_message("Tenet Technetronics")

sleep(1)
```

Measuring Temperature with Sensehat:

```
fromsense_hat import SenseHat

from time import sleep

sense=SenseHat()

while 1:

data=sense.get_temperature()

print("Temperature is %s C",data)

sleep(1)
```

Measuring Humidity with Sensehat:

```
fromsense_hat import SenseHat

from time import sleep

sense=SenseHat()

while 1:

data=sense.get_humidity()

print("Humidity is %s is"%data)

sleep(1)
```

Measuring Pressure with Sensehat:

```
fromsense_hat import SenseHat

from time import sleep

sense=SenseHat()

while 1:

data=sense.get_pressure()

print("Pressure is %s millibars",data)

sleep(1)
```

Measuring Accelerometer with Sensehat:

fromsense_hat import SenseHat

```
from time import sleep

sense=SenseHat()

while 1:

data=sense.get_accelerometer()

print("p: {pitch}, r: {roll}, y: {yaw}".format(**data))

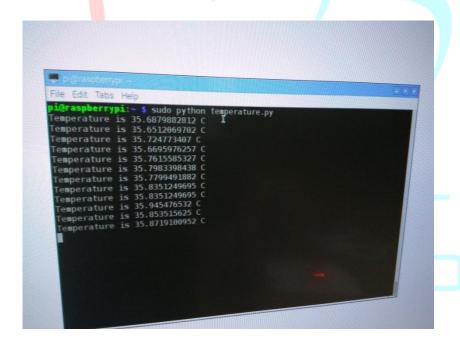
sleep(1)
```

Measuring Gyroscope with Sensehat:

```
fromsense_hat import SenseHat
from time import sleep
sense=SenseHat()
while 1:
    data=sense.get_gyroscope()
    print("p: {pitch}, r: {roll}, y: {yaw}".format(**data))
    sleep(1)
```

Output:

Experiment 1: Temperature



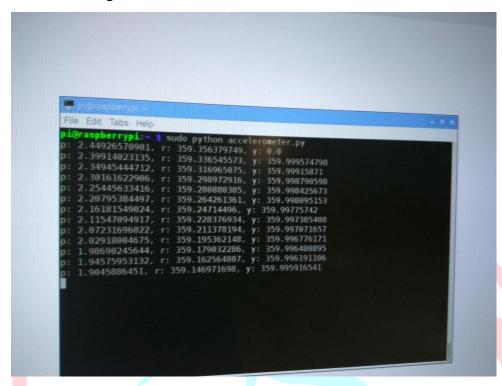
Experiment 2: Printing Letter on LED Matrix



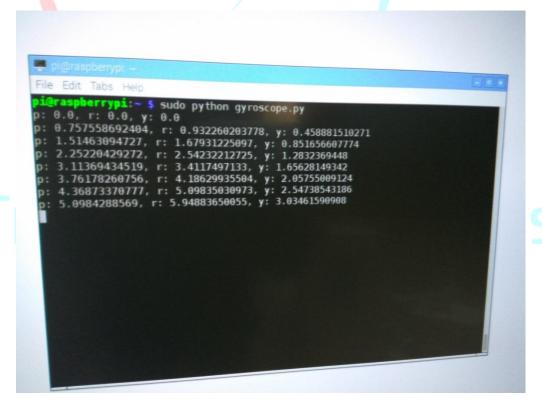
Experiment 3: Measuring Humidity

```
Error: name 'data' is not defined
raspherrypi:~ $ sudo nano humidity.py
raspherrypi:~ $ sudo python humidity.py
 i@raspberrypi:~ $ suc
dumidity is 41.862679
Humidity is 42.465569
 fumidity is 42.360062
 fumidity is 42.375137
 łumidity is 42.061634
Humidity is 42.115894
Humidity is 42.221397
Humidity is 42.019432
Humidity is 42.022446
Humidity is 41.980244
dumidity is 42.278671
fumidity is 41.986271
Humidity is 41.624535
Humidity is 41.898853
fumidity is 42.788116
fumidity is 42.492699
Humidity is 42.308819
Humidity is 42.329918
Humidity is 42.384178
Humidity is 42.233456
```

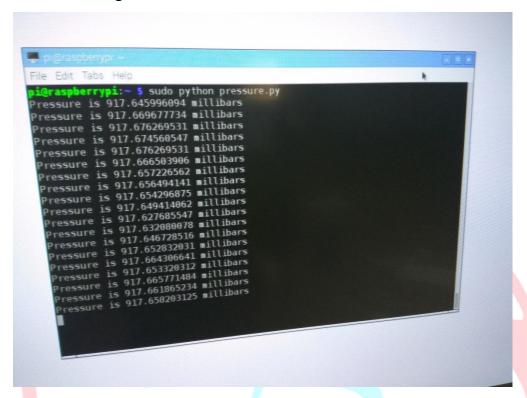
Experiment 4: Measuring Accelerometer



Experiment 5: Measuring Gyro



Experiment 6: Measuring Pressure



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