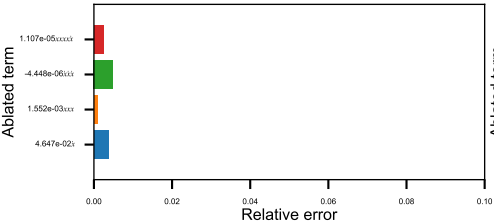


Derivative \ddot{x} Dynamics x 