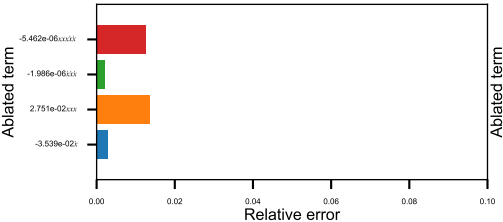


Derivative  $\ddot{x}$ Dynamics  $x$ 