

MultiHU-TD: Multifeature Hyperspectral Unmixing Based on Tensor Decomposition

Online Seminar for Tensor Network Reading Group
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Table of Contents

1 Introduction

2 Related Works

3 MultiHU-TD

- Algorithmic Implementation
- Interpretability: Tensor-based Unmixing, ASC, and ELMM
- Third-mode feature examples

4 Experimental Discussion

- Experimental Setup
- Experimental Validation

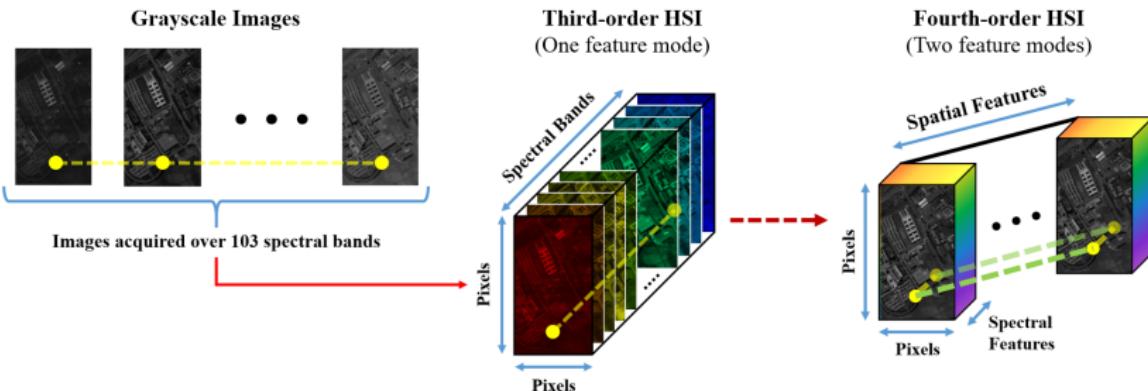
5 Conclusion

Introduction

Introduction

Hyperspectral Images (HSI)

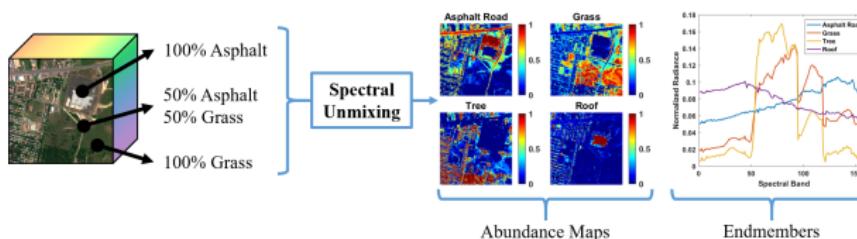
- A Hyperspectral image (HSI) consists of a **third-order** arrangement of grayscale images.



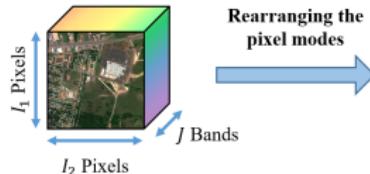
Classical (matrix-based) Hyperspectral Unmixing

Linear Mixing Model (LMM)

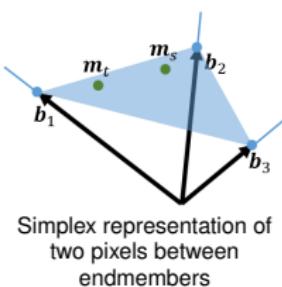
- Blind separation of the materials of a scene into **abundance maps** and **endmembers**
- Linear Mixing Model:** $\mathbf{m}_{i,:}^T = \sum_{r=1}^R a_{ir} \mathbf{b}_{:,r}^T \iff \mathbf{M} = \mathbf{AB}^T$, with the constraints:
 - Nonnegativity: $\mathbf{A} \succeq 0, \mathbf{B} \succeq 0$
 - Abundance Sum-to-one Constraints (ASC): $\sum_{r=1}^R a_{ir} = 1$



Three-way HSI



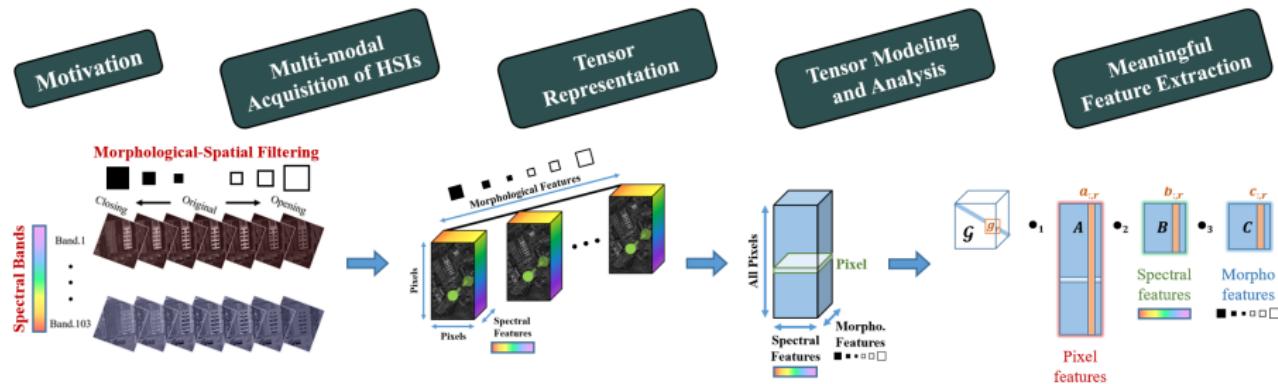
$$\begin{aligned} \text{Matrix } \mathbf{M} &= \\ \mathbf{A} &= \\ \mathbf{B}^T &= \\ \mathbf{a}_{i,:} &= \\ \mathbf{b}_{:,r} &= \\ R &= \\ \sum_{r=1}^R a_{ir} &= 1 \end{aligned}$$



Motivation

Motivation

- 1 Enhancing **feature extraction** in HSI unmixing with additional features.
- 2 Conservation of the **multi-feature multi-modal arrangement** of data as **tensors**.
- 3 **Low-rank** representation of the data.
- 4 Incorporating the **Abundance Sum-to-one Constraint (ASC)** in tensor decomposition.
- 5 Flexibility of imposing constraints on each mode separately.
- 6 Lack of a **generalized and interpretable framework** for such applications.



Proposal

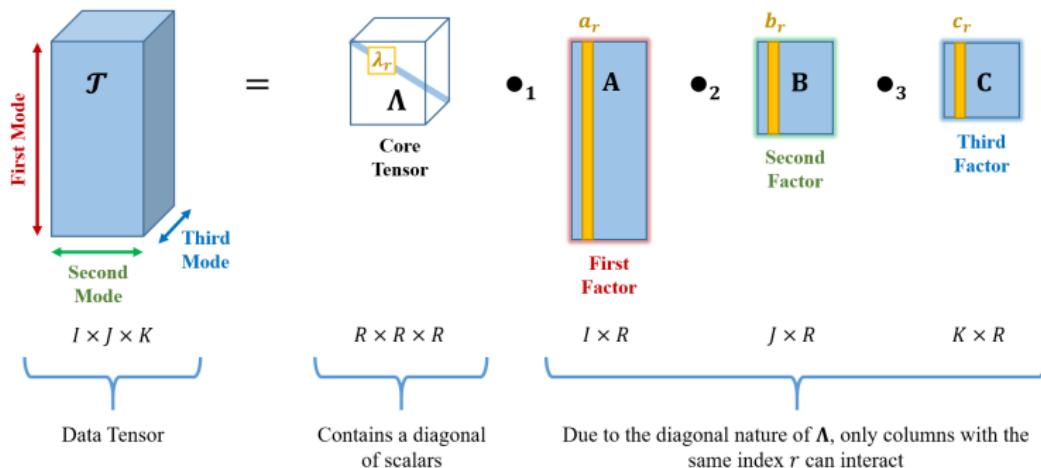
In this work...

- 1 We propose “MultiHU-TD”, an interpretable methodological framework for **low-rank** “Multi-feature Hyperspectral Unmixing based on Tensor Decomposition”.
- 2 “MultiHU-TD” is based on the **Canonical Polyadic decomposition** (CPD) and incorporates the **Abundance Sum-to-one Constraint** (ASC).
- 3 We provide mathematical, physical and graphical **interpretation** of the extracted features.
- 4 We provide **analogies** with the classical matrix-based spectral unmixing of HSIs.

Canonical Polyadic Decomposition (CPD)

Tucker Form

- CPD reveals the **tensor rank**, usually denoted by R , which is the minimum number of terms for the CPD to hold exact.
- For **feature extraction**, columns with different indices should not interact.



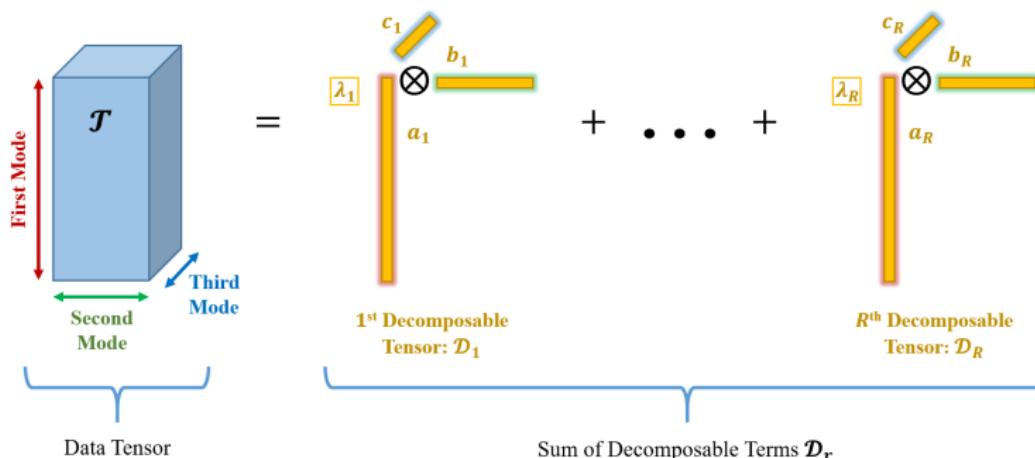
Canonical Polyadic Decomposition (CPD)

Sum of Rank-1 Terms

- The CPD of a rank- R tensor can be written as follows:

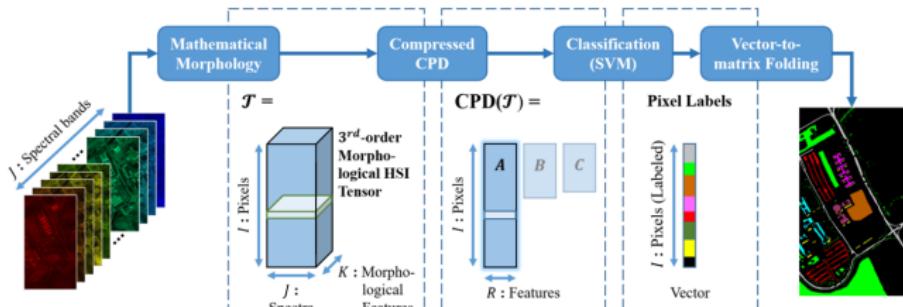
$$\mathcal{T} = \sum_{r=1}^R \lambda_{rrr} (\mathbf{a}_{:,r} \otimes \mathbf{b}_{:,r} \otimes \mathbf{c}_{:,r}) = \sum_{r=1}^R \lambda_{rrr} (\mathcal{D}_r) \quad (1)$$

- Then, \mathcal{D}_r is an N -th order tensor which represents the composition of the physical properties defined by the vectors composing it, good for **material extraction**.

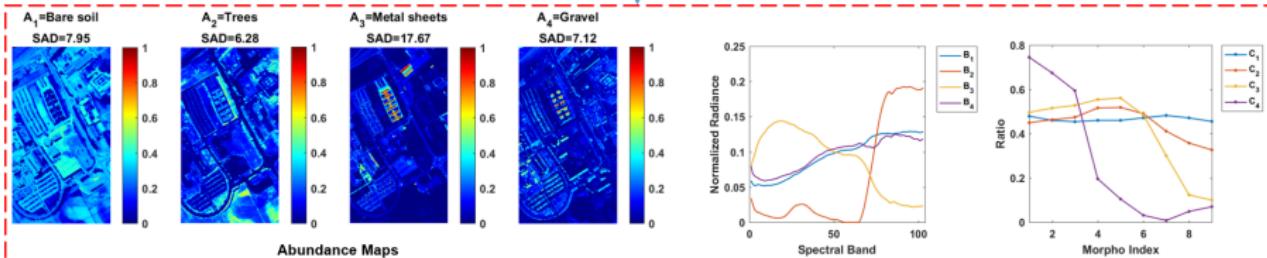


Related Works

From Multi-feature HSI Supervised Classification... [Jouni et al. 2020]



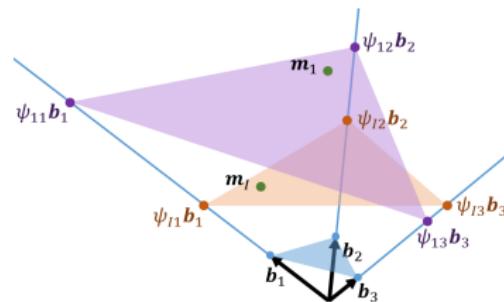
Explore the features



From Matrix-based Spectral Unmixing...

Extended LMM [Drumetz et al. 2016]

- Extended LMM (ELMM) deals with pixel-wise **spectral variability**. For instance:
 $m_i = \sum_{r=1}^R a_{ir} f_i(b_r) = \sum_{r=1}^R a_{ir} b_r^{(i)} = \sum_{r=1}^R a_{ir} \psi_{ir} b_r$
- We are interested in ELMM since it shares a lot of similarities with CPD.



ELMM: Simplex representation of two pixels between **scaled versions** of the endmembers

$$\left[\begin{array}{c} \text{Matrix } M \\ m_{i,:} \\ (I \times J) \end{array} \right] = \left(\begin{array}{c} A \\ a_{i,:} \\ (I \times R) \end{array} \right) \odot \left(\begin{array}{c} \Psi \\ \psi_i \\ (I \times R) \end{array} \right) \quad \left(\begin{array}{c} B \\ b_{:,r} \\ (J \times R) \end{array} \right)^T$$

$$\left[\begin{array}{c} m_{1,:} \\ (I \times J) \end{array} \right] = \left(\begin{array}{c} a_{1,:} \\ (I \times R) \end{array} \right) \odot \left(\begin{array}{c} \Psi^{(1)} \\ (\mathbf{R} \times \mathbf{R}) \end{array} \right) \quad \left(\begin{array}{c} B \\ b_{:,r} \\ (J \times R) \end{array} \right)^T$$

$$\left[\begin{array}{c} m_{I,:} \\ (I \times J) \end{array} \right] = \left(\begin{array}{c} a_{I,:} \\ (I \times R) \end{array} \right) \odot \left(\begin{array}{c} \Psi^{(I)} \\ (\mathbf{R} \times \mathbf{R}) \end{array} \right) \quad \left(\begin{array}{c} B \\ b_{:,r} \\ (J \times R) \end{array} \right)^T$$

MultiHU-TD

AO-ADMM-ASC with Nonnegativity and Sparsity

Cost Function

- In **CPD**, we impose **nonnegativity** on all factor matrices, and **sparsity** and **ASC** on the abundances. The optimization problem is to solve the cost function:

$$\begin{aligned} & \underset{\mathbf{A}, \mathbf{B}, \mathbf{C}}{\operatorname{argmin}} \| \mathcal{T} - \mathbf{\Lambda}_1 \bullet \mathbf{A} \bullet \mathbf{B} \bullet \mathbf{C} \|_F^2 + \alpha \|\mathbf{A}\|_1 \\ \text{s.t. } & \mathbf{A} \succeq 0, \mathbf{B} \succeq 0, \mathbf{C} \succeq 0, \sum_{r=1}^R a_{i,r} = 1 \quad \forall i \in \{1, \dots, I\} \end{aligned} \quad (2)$$

- For the **ASC** solution, set the $(J+1)$ -th lateral slice and row vector of \mathcal{T} and \mathbf{B} as follows:
 - $\mathcal{T}_{:, J+1, K} = \delta \mathbf{1}_I$, i.e., $t_{i, J+1, K} = \delta \quad \forall i \in \{1, \dots, I\}$
 - $b_{J+1, r} = \delta c_{K, r}^{-1} \quad \forall r \in \{1, \dots, R\}$,
 which ensures that $\sum_{r=1}^R a_{i,r} = 1 \quad \forall i \in \{1, \dots, I\}$.
- Using AO-ADMM [Huang et al. 2016], the problem boils down to an alternating optimization of **ADMM subproblems** with respect to the factor matrices. For instance, with respect to \mathbf{A} :

$$\mathbf{A} = \underset{\mathbf{A}}{\operatorname{argmin}} \frac{1}{2} \| \tilde{\mathcal{T}}_{(1)} - \tilde{\mathbf{W}}_{(\mathbf{A})} \mathbf{A}^T \|_F^2 + \alpha \|\mathbf{A}\|_1 \quad \text{s.t. } \mathbf{A} \succeq 0 \quad (3)$$

where $\tilde{\mathbf{W}}_{(\mathbf{A})} = \tilde{\mathbf{B}} \odot \mathbf{C}$ represents the Khatri-Rao product [Comon. 2014].

Interpretability: Tensor-based ELMM

CPD and ELMM analogies

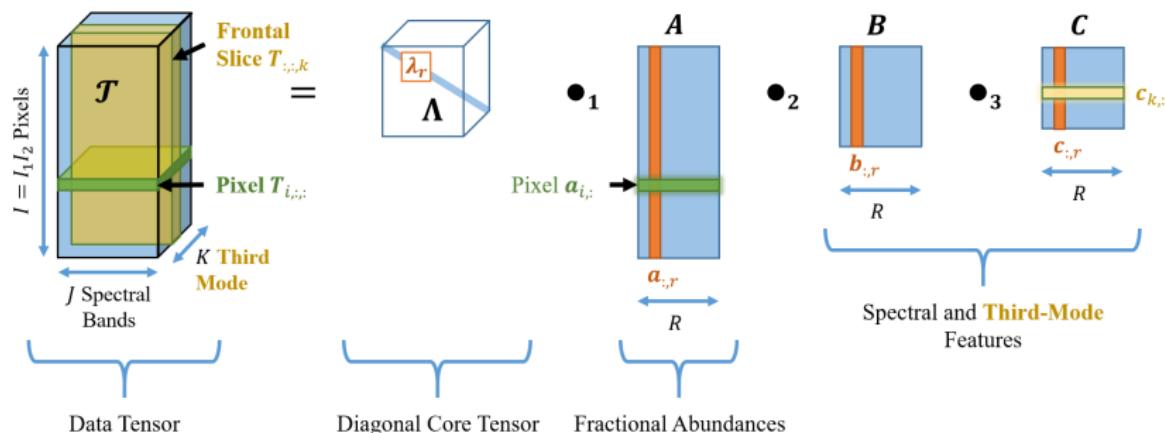
- CPD describes **frontal slice-based** spectral variability:

$$\mathbf{T}_{:, :, k} = \mathbf{A} \operatorname{Diag}\{\mathbf{c}_{k,:}\} \mathbf{B}^T = \mathbf{A} \Psi_{(k)} \mathbf{B}^T = \mathbf{A} \tilde{f}_k(\mathbf{B})^T \iff$$

$$\mathbf{t}_{i, :, k} = \sum_{r=1}^R a_{ir} c_{kr} \mathbf{b}_r = \sum_{r=1}^R a_{ir} f_k(\mathbf{b}_r) = \sum_{r=1}^R a_{ir} \mathbf{b}_r^{(k)}$$

- ELMM describes **pixel-based** spectral variability:

$$\mathbf{m}_i = \sum_{r=1}^R a_{ir} \psi_{ir} \mathbf{b}_r = \sum_{r=1}^R a_{ir} f_i(\mathbf{b}_r) = \sum_{r=1}^R a_{ir} \mathbf{b}_r^{(i)}$$



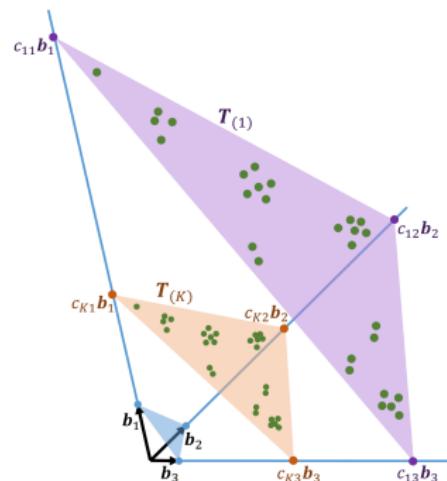
Interpretability: Tensor-based ASC

MultiHU-TD: Generalized Interpretation

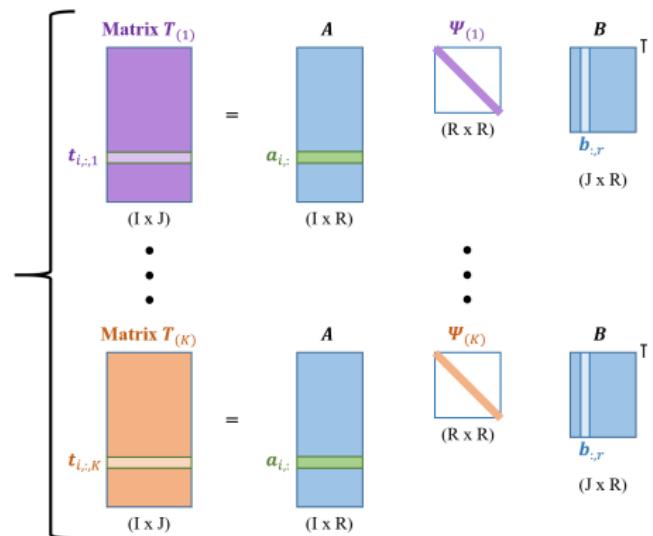
- The frontal slices have **common factors \mathbf{A}** and **\mathbf{B}** .
- Each frontal slice can be represented as a simplex. The vertices are formed at the columns of $\mathbf{B}^{(k)}$.
- \mathbf{A} and \mathbf{B} are independent of the third-mode differences in the hyperspectral scene along the slices:

$$\mathbf{M}^{(\text{CPD})} = \mathbf{A} \mathbf{B}^T \quad (4)$$

- The rows of \mathbf{C} encode the third-mode variabilities, as \mathbf{A} and \mathbf{B} factorize the abundance and spectral features.

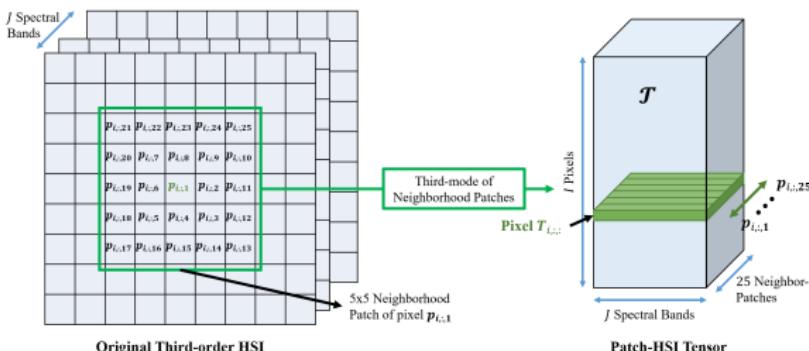


MultiHU-TD: There are K simplexes (as many as the frontal slices).

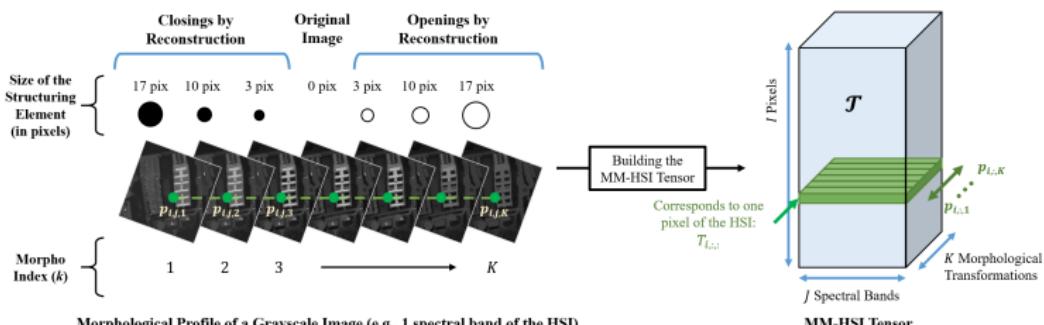


Third-mode feature examples

Patches and Mathematical Morphology



An illustration of constructing a 5×5 Patch-HSI tensors based on [Veganzones et al. 2016]

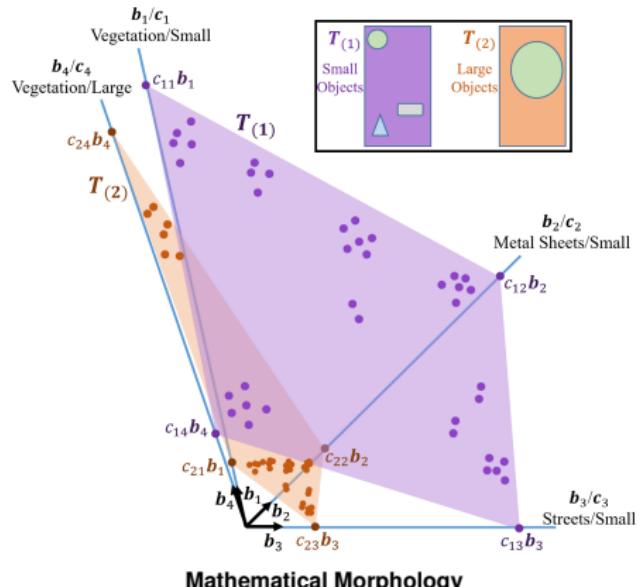
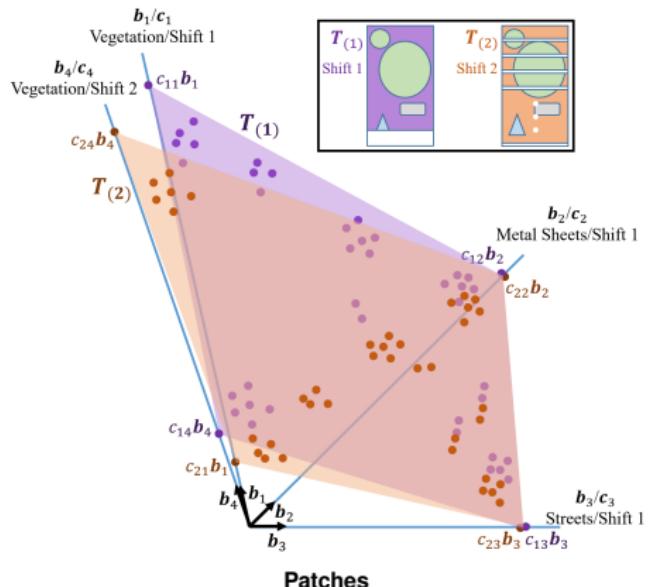


Morphological Profile of a Grayscale Image (e.g., 1 spectral band of the HSI)

An illustration of constructing a MM-HSI tensors based on [Jouni et al. 2020]

Third-mode feature examples

Geometric Interpretation of the Decomposed Factors

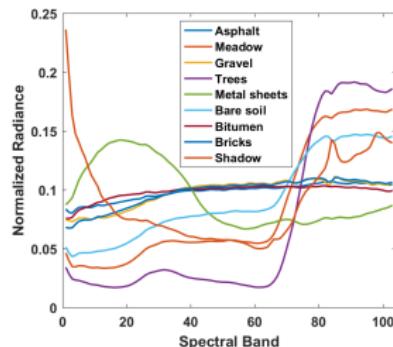
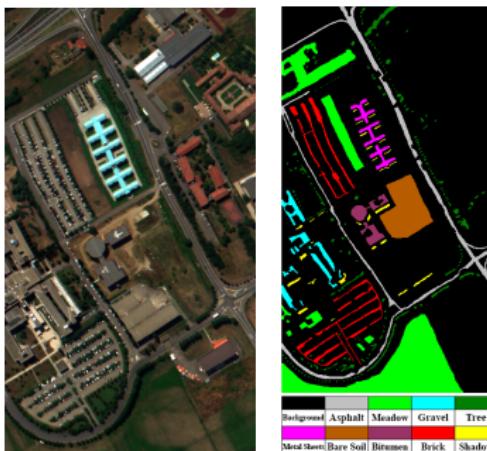


Experimental Discussion

Real HSI Data Sets¹

HSI Data Sets

- We use two real HSIs for testing, composed of a landscape of buildings, streets and vegetation of different materials and sizes.
 - Pavia University (on the left), with dimensions $610 \times 340 \times 103$.
 - Urban (on the right), with dimensions $307 \times 307 \times 162$.



Figures: Pavia HSI in false colors and its spatial groundtruth (GT)

¹We also test this framework using a synthetic HSI. The details are in the paper appendix.

Experimental Validation

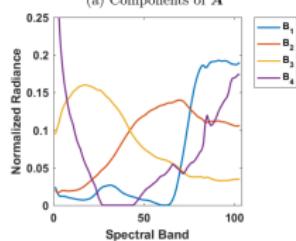
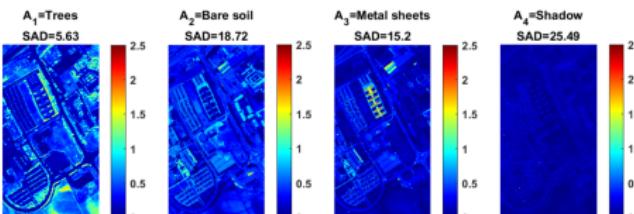
LMM (NMF) vs MultiHU-TD (Rank-4 AO-ADMM-ASC)

Qualitative Evaluation

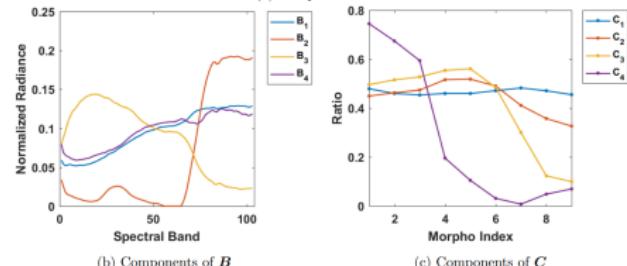
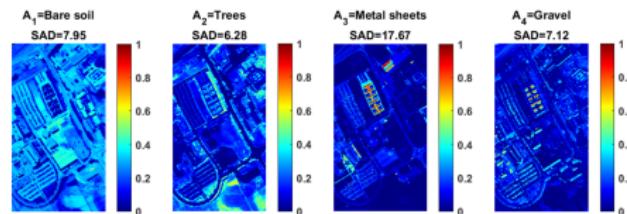
- LMM does not highlight all the features.
- MultiHU-TD with MM better highlights the features (shadow, asphalt, etc.).

	Trees	Bare Soil	Metal Sheets	Shadow
LMM	5.63	18.72	15.2	25.49
MultiHU-TD	6.28	7.95	17.67	7.12*

Table: Spectral Angular Distance (SAD), in degrees



Pavia. NMF results with ASC

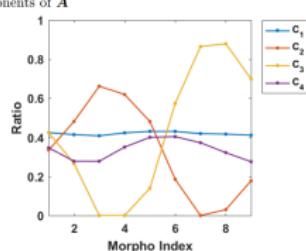
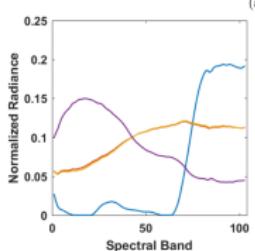
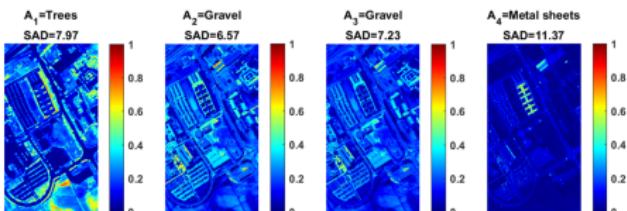
MM-HSI NCPD results for $R = 4$

Experimental Validation

Patches vs MM Features with $R = 4$

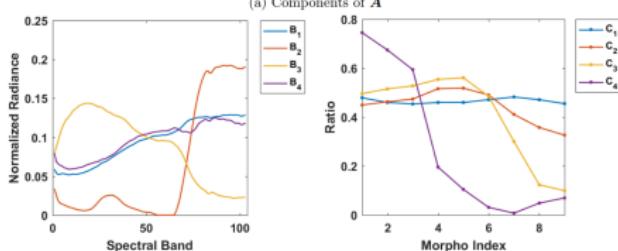
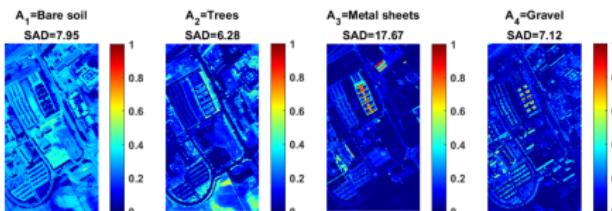
Qualitative Evaluation

- Patch MultiHU-TD “replicates” some features.
- MM MultiHU-TD highlights features based on morphological properties (scale, brightness).

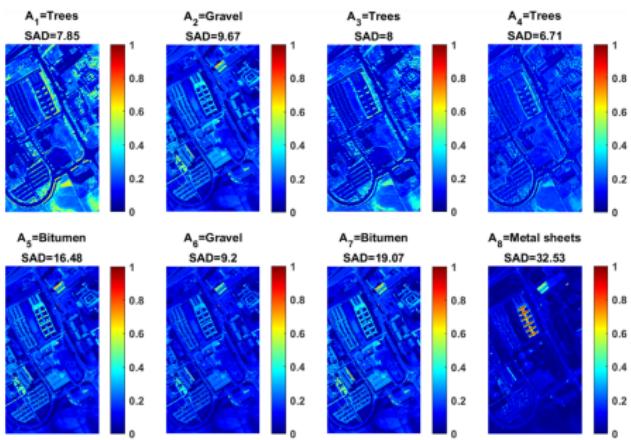
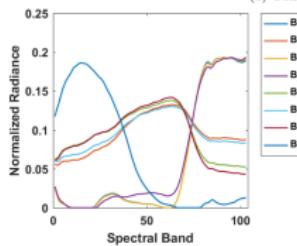
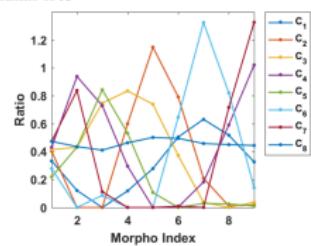
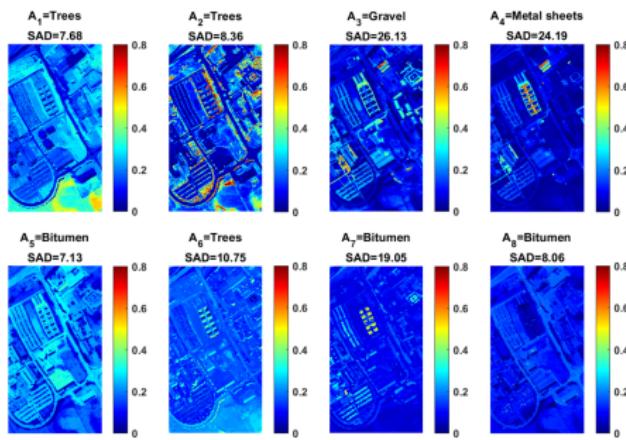
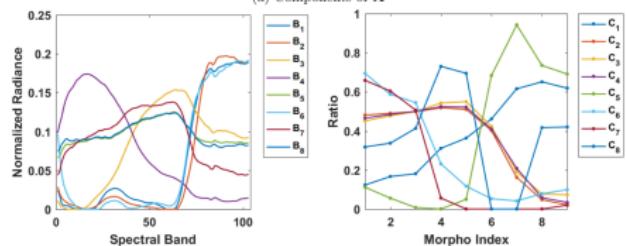
Patch-HSI NCPD results for $R = 4$

	Trees	Bare Soil	Metal Sheets	Gravel*
Patches	7.97	6.57	11.37	6.57*
MM	6.28	7.95	17.67	7.12*

Table: Spectral Angular Distance (SAD), in degrees

MM-HSI NCPD results for $R = 4$

Experimental Validation

Patches vs MM Features with $R = 8$ (a) Components of \mathbf{A} (b) Components of \mathbf{B} (c) Components of \mathbf{C} Patch-HSI NCPD results for $R = 8$ (a) Components of \mathbf{A} (b) Components of \mathbf{B} (c) Components of \mathbf{C}

NCPD results with ASC imposed

Conclusion

General Conclusions

Conclusions

- We proposed **MultiHU-TD**, a generalized and interpretable framework for multi-feature HSIs using tensor decomposition.
- We incorporated **Abundance Sum-to-one Constraints** in a tensor-based multi-feature blind source separation problem.
- MultiHU-TD **conserves the low-rankness** of the data by rearranging the modes of pixels. Incorporating spatial information as features **conserves the relevant neighborhood information** without losing the multi-modal data structure.
- We discussed the methodological and applicative aspects of multi-feature unmixing by:
 - Establishing **mathematical, graphical, and geometrical** analogies between matrix- and tensor-based source separation, and between the physical LMM and CPD.
 - Stressing the importance of using **physically meaningful features** (such as MM)

Perspectives

Perspectives

- Subspace representations of the factor matrices
- Exploring other types of tensor decomposition such as Block Term Decomposition
- Exploring other types of multi-feature representations of HSIs
- Semi-supervised classification
- Extend the study to multivariate function representations as tensors

Where to go from here?

- Subspace Learning of latent spaces
- Machine Learning for tensor analysis
- Tensor Networks for big multi-modal HSI representations

Thanks!

Thank you for your attention!

Example: Tensor vs Matrix Analysis

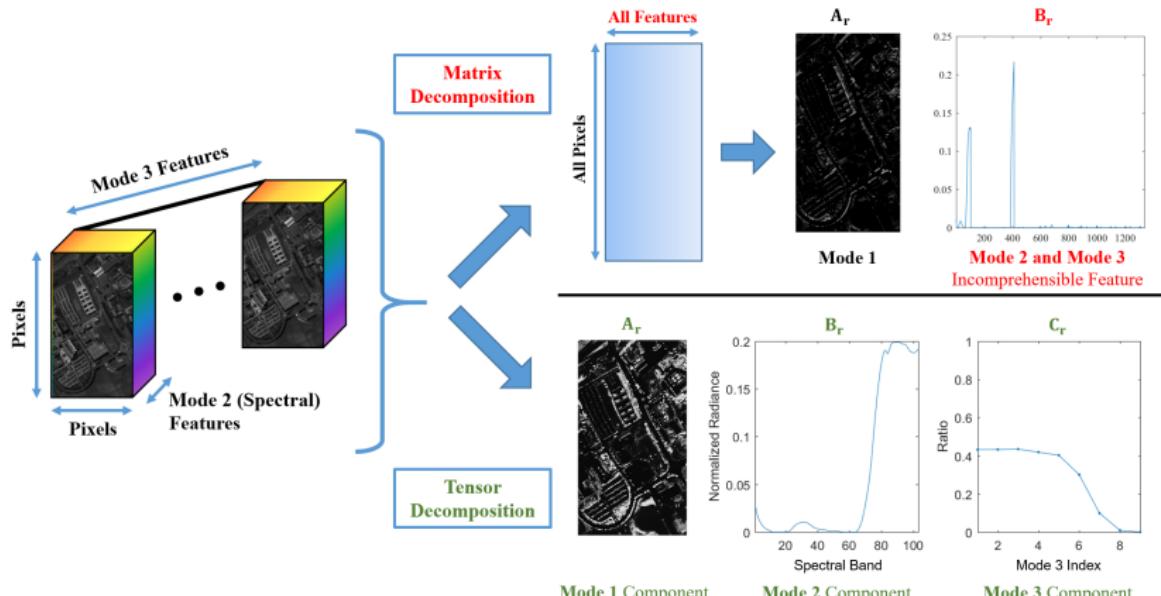
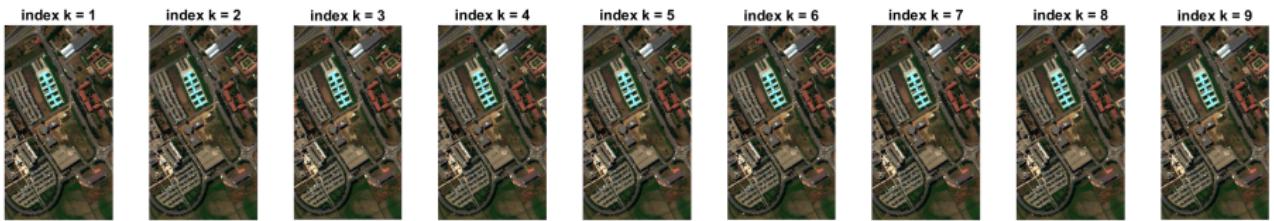


Figure: Example of the difference between matrix and tensor techniques given the same data set and physical component

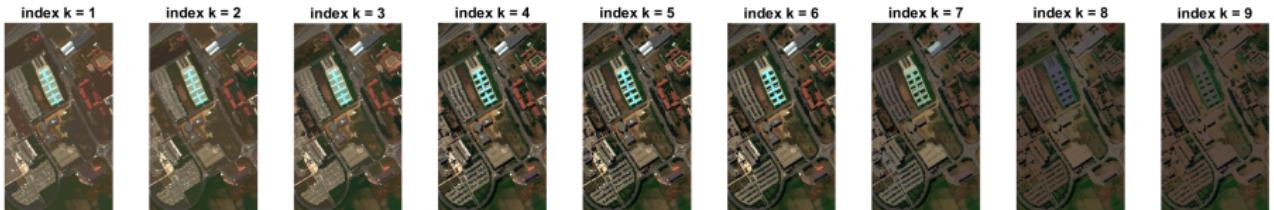
Example: Patch-HSI and MM-HSI Tensors

Physical Interpretation

- **Patch-HSI Tensors:** The frontal slices are slightly-shifted versions of each others.
- **MM-HSI Tensors:** The frontal slices represent physical spatial features.



Pavia HSI: (3×3) -Patch



Pavia HSI: Mathematical Morphology [Jouni et al. 2020]