

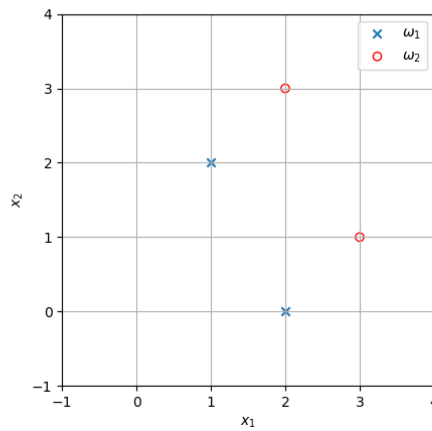
Machine Learning - Theoretical exercise 4

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Problem 1

- a) We have the same number of training samples for classes ω_1 and ω_2 , thus the prior probabilities are equal for both classes i.e. $P(\omega_1) = 0.5$ and $P(\omega_2) = 0.5$



- b) We compute θ according to the LS-method.

$$\theta = (X^T X)^{-1} X^T y \quad (1)$$

where

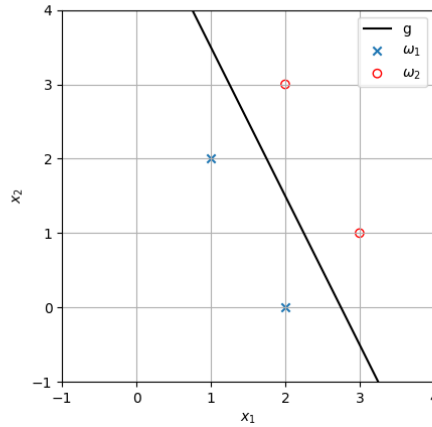
$$X = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 0 & 1 \\ 3 & 1 & 1 \\ 2 & 3 & 1 \end{bmatrix}^T \quad y = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$

The steps to solve this equation are shown below.

$$\begin{aligned} X^T X &= \begin{bmatrix} 18 & 11 & 8 \\ 11 & 14 & 6 \\ 8 & 6 & 4 \end{bmatrix} \\ (X^T X)^{-1} &= \begin{bmatrix} 18 & 11 & 8 \\ 11 & 14 & 6 \\ 8 & 6 & 4 \end{bmatrix} \\ (X^T X)^{-1} X^T &= \begin{bmatrix} -\frac{1}{2} & -\frac{1}{6} & \frac{1}{2} & \frac{1}{6} \\ 0 & -\frac{1}{3} & 0 & \frac{1}{3} \\ \frac{5}{4} & -\frac{13}{12} & -\frac{3}{4} & -\frac{7}{12} \end{bmatrix} \\ \theta &= \begin{bmatrix} -\frac{4}{3} \\ \frac{2}{3} \\ \frac{11}{3} \end{bmatrix} \end{aligned}$$

To determine the decision boundary, we find the root of the discriminant function.

$$\begin{aligned}
 g(x) &= 0 \\
 -\frac{4}{3}x_1 - \frac{2}{3}x_2 + \frac{11}{3} &= 0 \\
 x_2 &= -2x_1 + \frac{11}{2}
 \end{aligned}$$

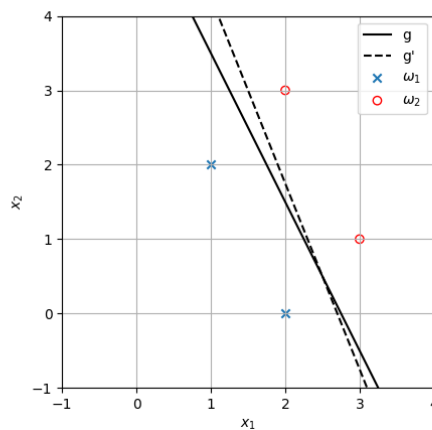


c) If we set $y_4 = -0.5$, we reduce the weight of the fourth training sample, which modifies θ .

$$\theta' = \begin{bmatrix} -\frac{5}{4} \\ -\frac{1}{2} \\ \frac{27}{8} \end{bmatrix}$$

Because $\theta' \neq \theta$, the decision boundary also changes.

$$\begin{aligned}
 g'(x) &= 0 \\
 -\frac{5}{4}x_1 - \frac{1}{2}x_2 + \frac{27}{8} &= 0 \\
 x_2 &= -\frac{5}{2}x_1 + \frac{27}{4}
 \end{aligned}$$



We can see that decreasing the weight of a training sample moves the decision boundary closer to it.

d) We now compute θ with the LMS-method. We use μ to denote the learning rate. The descent vector at each iteration is denoted ∇ .

Initialization

$$\mu^{(0)} = 0.5 \qquad \boldsymbol{\theta}^{(0)} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \qquad \theta = 1$$

Iteration 1

$$\begin{aligned} \nabla &= \mu^{(1)}(y_1 - \boldsymbol{\theta}^{(0)T} y_1 x_1) y_1 x_1 \\ &= \frac{0.5}{1} \left([-1] - [1 \quad 1 \quad 1] [-1] \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right) [-1] \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \\ &= -\frac{3}{2} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \end{aligned}$$

$$|\nabla| = \frac{3\sqrt{6}}{2} \approx 3.7 > \theta$$

$|\nabla|$ is greater than the threshold, so $\boldsymbol{\theta}$ is updated.

$$\begin{aligned} \boldsymbol{\theta}^{(1)} &= \boldsymbol{\theta}^{(0)} + \nabla \\ &= -\frac{1}{2} \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} \end{aligned}$$

Iteration 2

$$\begin{aligned} \nabla &= \mu^{(2)}(y_2 - \boldsymbol{\theta}^{(1)T} y_2 x_2) y_2 x_2 \\ &= \frac{0.5}{2} \left([-1] - [-\frac{1}{2} \quad -2 \quad -\frac{1}{2}] [-1] \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \right) [-1] \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} \frac{5}{4} \\ 0 \\ \frac{5}{8} \end{bmatrix} \end{aligned}$$

$$|\nabla| = \frac{5\sqrt{5}}{8} \approx 1.4 > \theta$$

$|\nabla|$ is greater than the threshold, so $\boldsymbol{\theta}$ is updated.

$$\begin{aligned} \boldsymbol{\theta}^{(2)} &= \boldsymbol{\theta}^{(1)} + \nabla \\ &= \begin{bmatrix} \frac{3}{4} \\ -2 \\ \frac{1}{8} \end{bmatrix} \end{aligned}$$

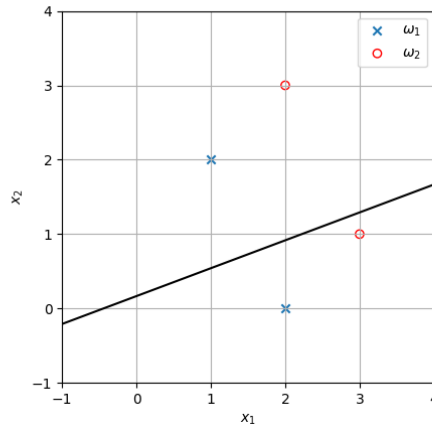
Iteration 3

$$\begin{aligned}
\nabla &= \mu^{(3)}(y_3 - \boldsymbol{\theta}^{(2)T} y_3 x_3) y_3 x_3 \\
&= \frac{0.5}{3} \left([1] - \begin{bmatrix} \frac{3}{4} & -2 & \frac{1}{8} \end{bmatrix} [1] \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} \right) [1] \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} \\
&= \begin{bmatrix} \frac{5}{16} \\ \frac{5}{48} \\ \frac{5}{48} \end{bmatrix}
\end{aligned}$$

$$|\nabla| = \frac{5\sqrt{11}}{48} \approx 0.3 < \theta$$

$|\nabla|$ is smaller than the threshold, so $\boldsymbol{\theta}$ is not updated and the algorithm terminates with $\boldsymbol{\theta}^{(2)} = \begin{bmatrix} \frac{3}{4} \\ -2 \\ \frac{1}{8} \end{bmatrix}$.

If we plot the resulting decision boundary, we observe that the converged value of $\boldsymbol{\theta}$ does not discriminate between the classes.



Problem 2

- An analytical solution to the equation $\mathbf{X}\boldsymbol{\theta} = \mathbf{y}$ would be to find the inverse of \mathbf{X} and compute $\boldsymbol{\theta} = \mathbf{X}^{-1}\mathbf{y}$ directly. However, this solution assumes that \mathbf{X} is invertible. In practice \mathbf{X} is often rectangular, with more rows (samples) than columns (features). Trying to find an exact solution would lead to have more equations than unknowns which is not solvable in general.
- In order to find $\boldsymbol{\theta}$ minimizing the function $\|\mathbf{X}\boldsymbol{\theta} - \mathbf{y}\|^2$, we can differentiate this function with respect to $\boldsymbol{\theta}$ and find its root.

$$\frac{\partial \|\mathbf{X}\boldsymbol{\theta} - \mathbf{y}\|^2}{\partial \boldsymbol{\theta}} = 2\mathbf{X}^T(\mathbf{X}\boldsymbol{\theta} - \mathbf{y})$$

We now set the derivative to zero.

$$\begin{aligned}
2\mathbf{X}^T(\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) &= 0 \\
\mathbf{X}^T\mathbf{X}\boldsymbol{\theta} &= \mathbf{X}^T\mathbf{y} \\
\boldsymbol{\theta} &= (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}
\end{aligned}$$

In this case, $\mathbf{X}^T\mathbf{X}$ is guaranteed to be invertible because it is a square symmetric matrix.

c) Let $\boldsymbol{\theta}_*$ be the value of $\boldsymbol{\theta}$ minimizing the squared error. We can rewrite the distance function as such.

$$\|\mathbf{X}\boldsymbol{\theta}_* - \mathbf{y}\|^2 = \|\mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} - \mathbf{y}\|^2$$

d) For the problem to be linearly separable, the distance function should be equal to zero.

$$\|\mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} - \mathbf{y}\|^2 = 0 \implies \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} = \mathbf{y} \implies \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T = \mathbf{I}$$

Problem 3

a) labels