

Formal verification of infinite state systems with unbounded agents

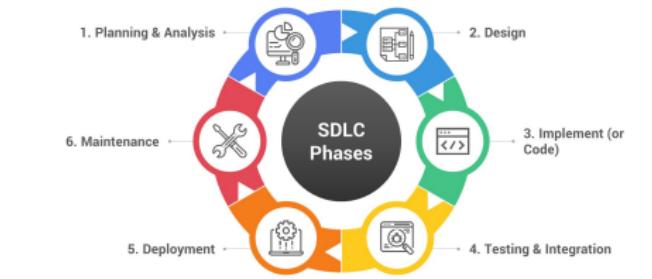
Tephilla Prince
Indian Institute of Technology Dharwad

Supervisors:
Prof. Ramchandra Phawade
Prof. S. Sheerazuddin

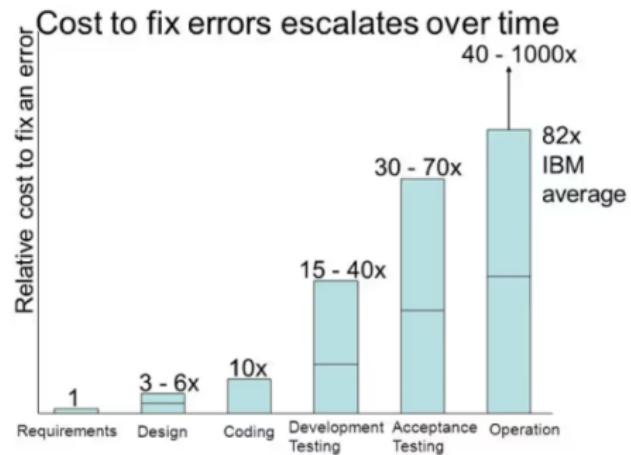
27/06/2025

Software Development Life Cycle (SDLC) Phases

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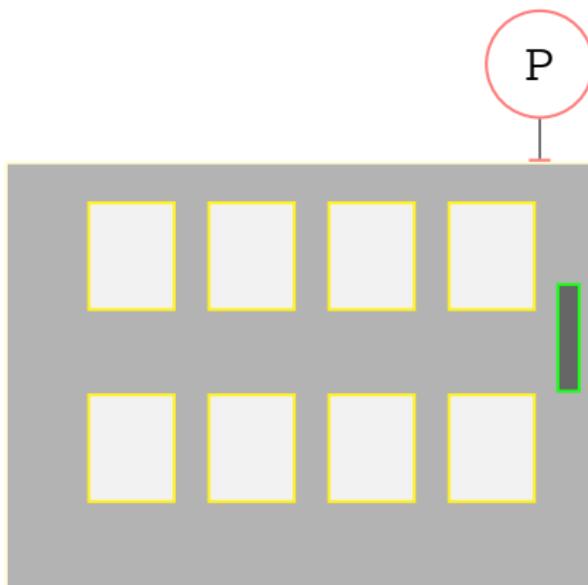
Error Costs



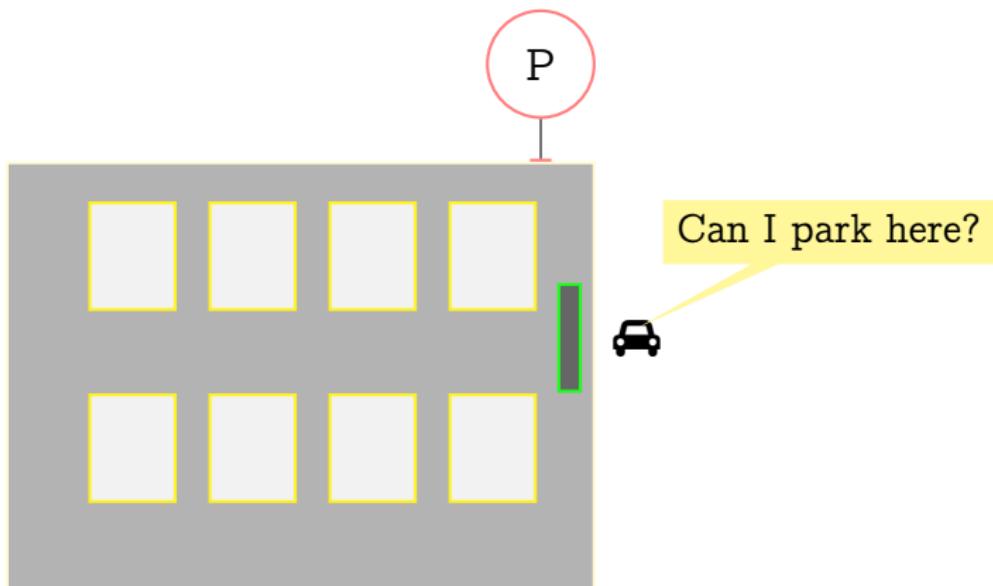
J. Stecklein, "Error cost escalation through the project life cycle, 2010

Running example

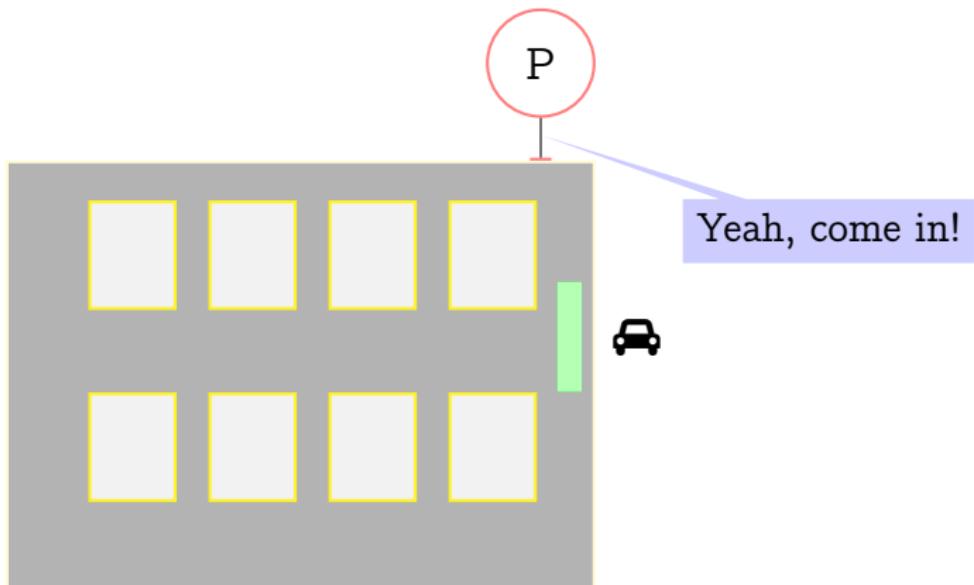
An empty Parking Lot waits
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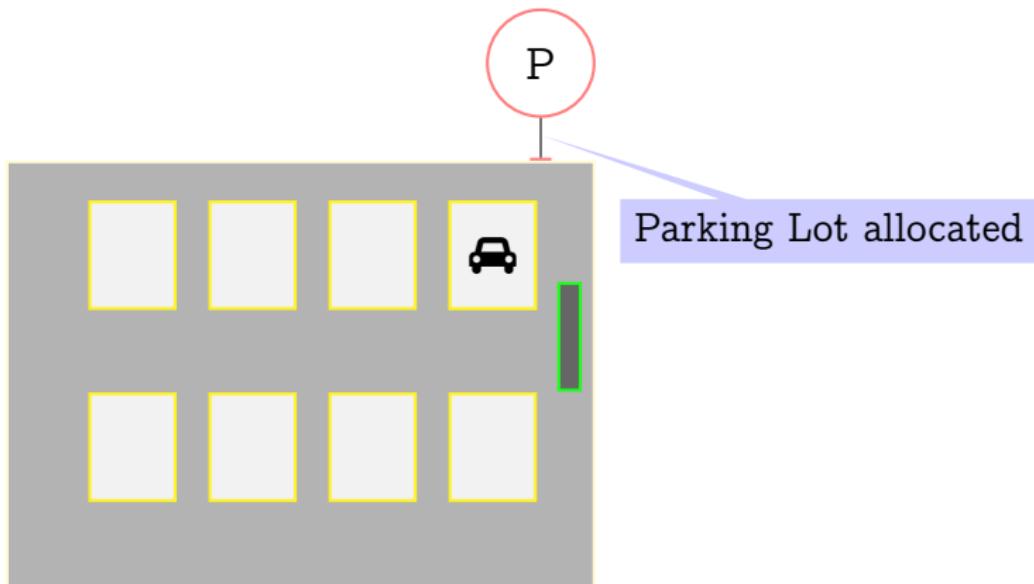
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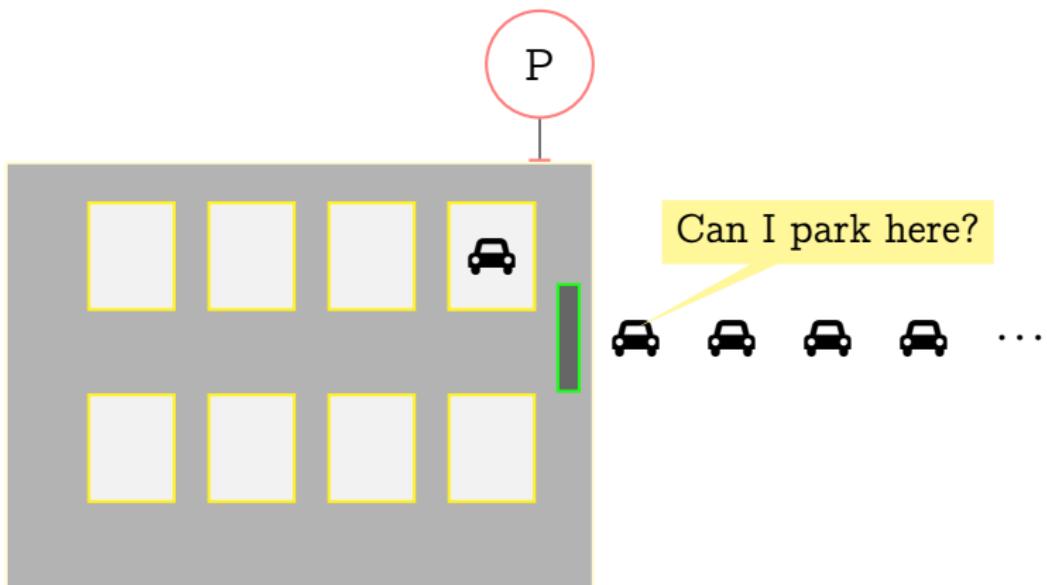


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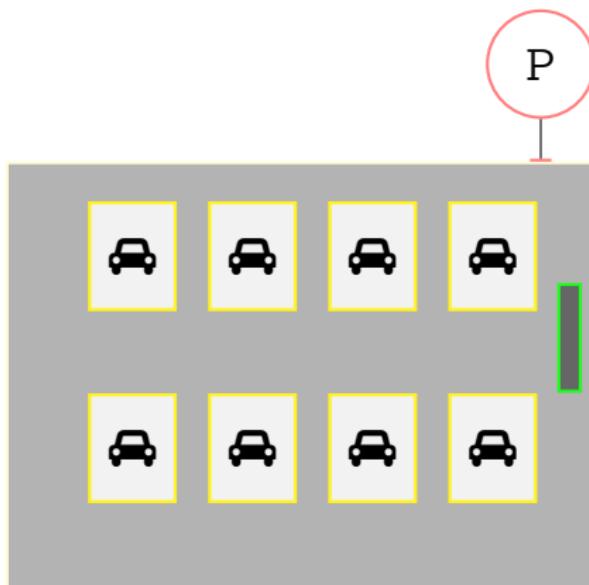
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Unbounded number of parking requests

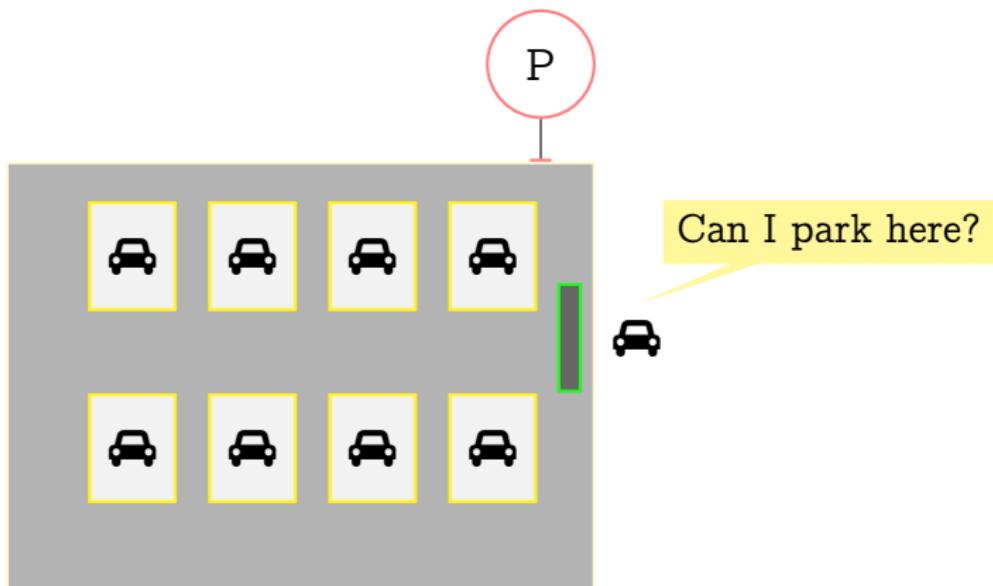


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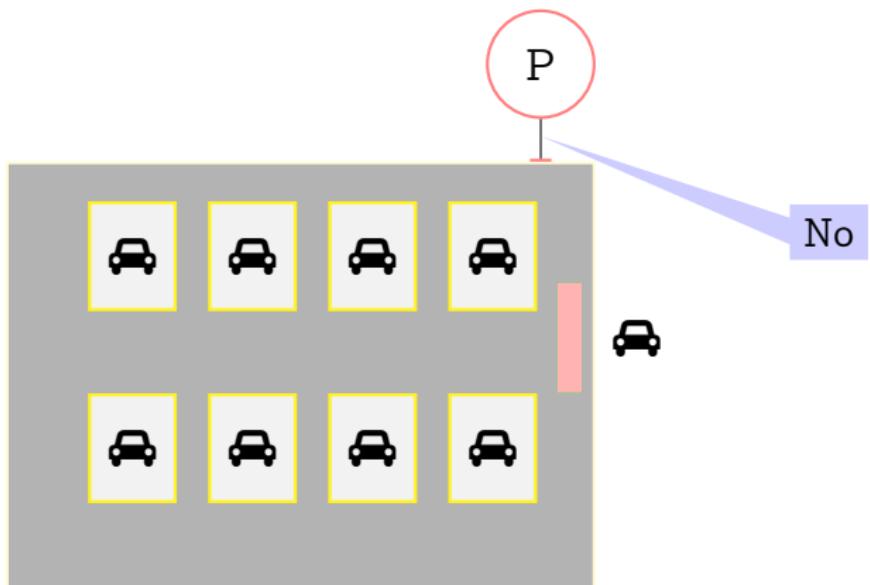
No parking space



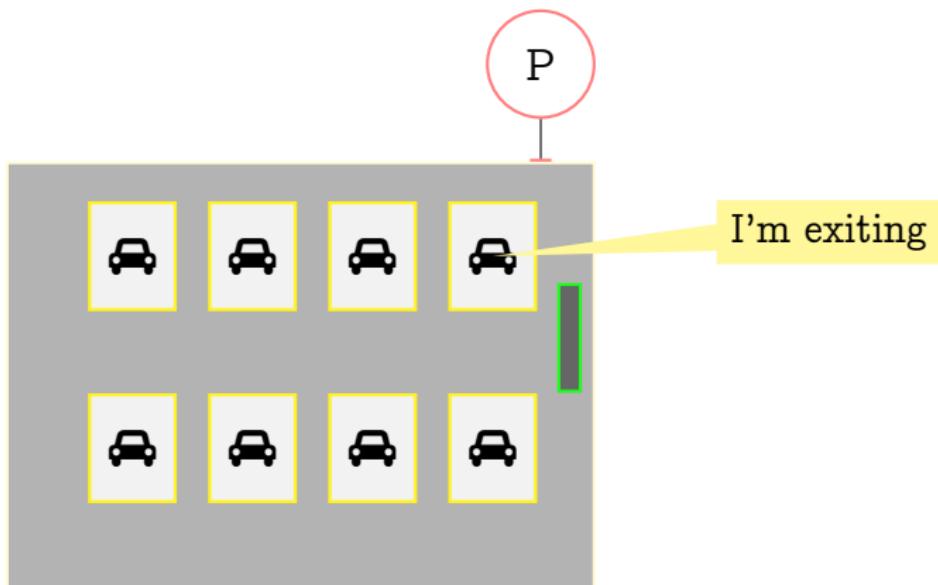
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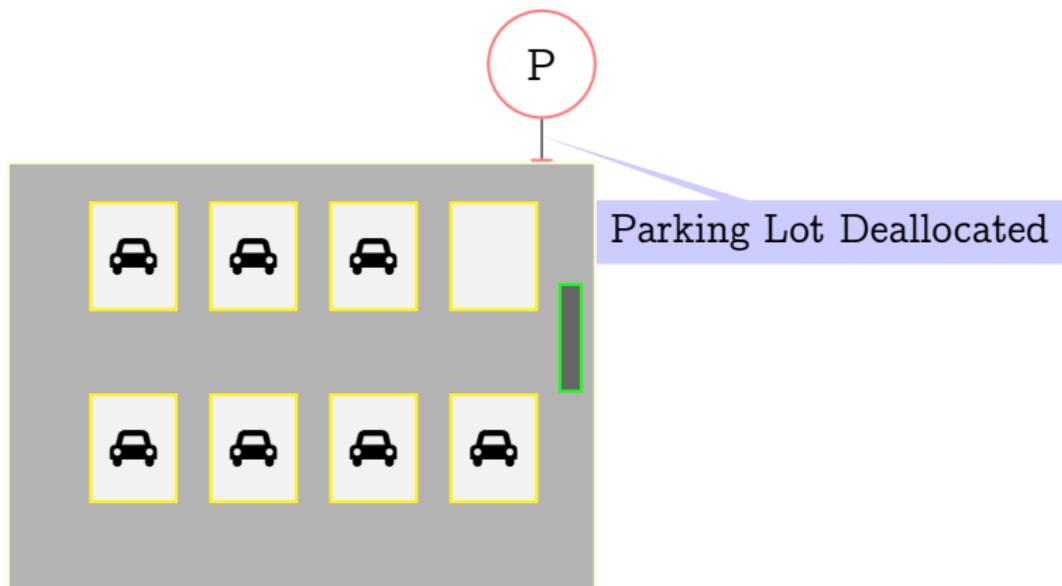
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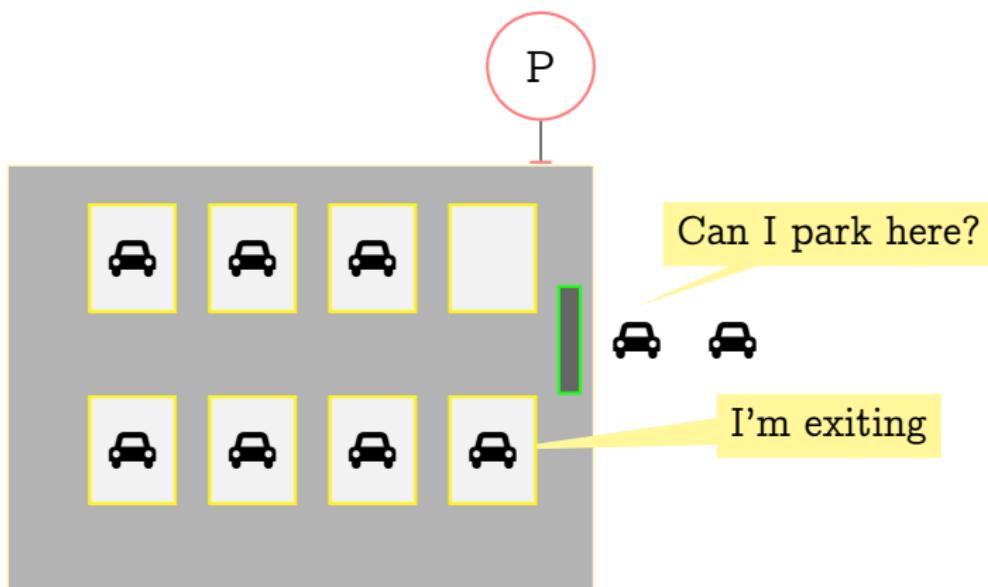


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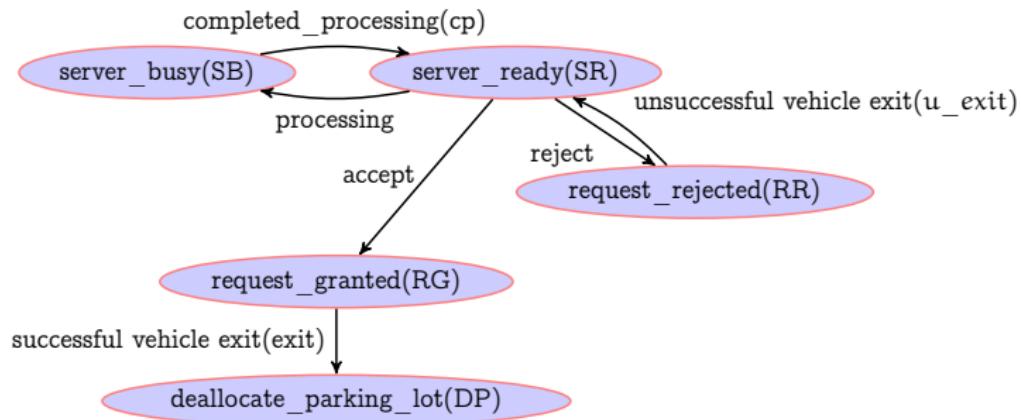


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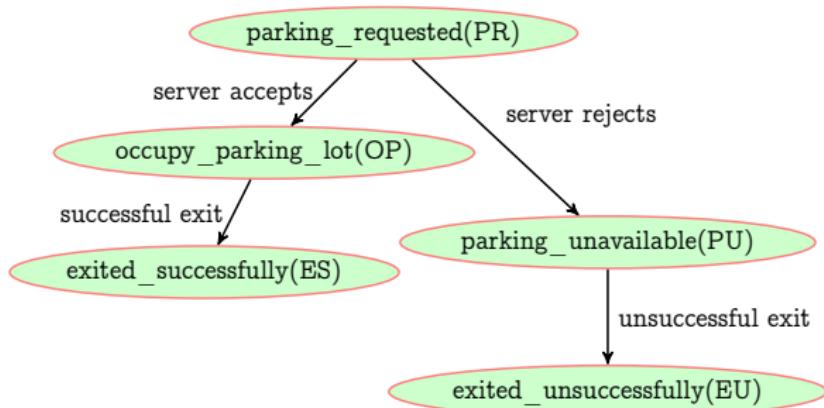
- single server-multiple client system
- unbounded clients of the same type



Case Study Parking System: Server behaviour



Case Study Parking System: Client behaviour



Research Questions

- 1 How do we formally verify UCS?
 - 1 How do we formally model UCS?

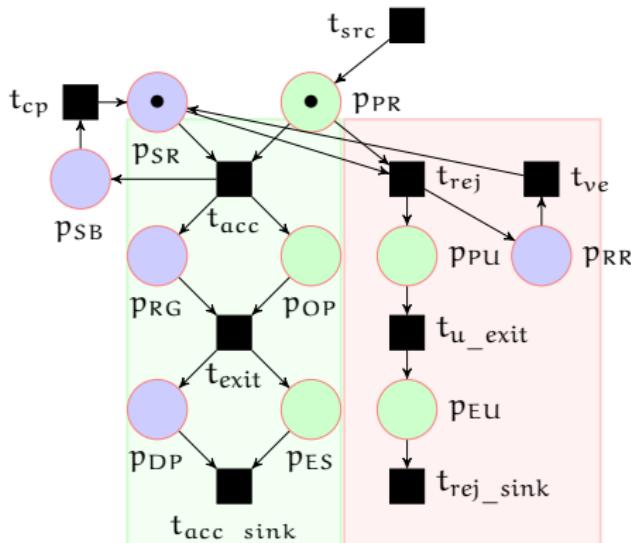
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 - 1 Do existing logics suffice?
 - 2 What additional properties are interesting in the context of unbounded client-server systems?

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 - 1 How do we formally model UCS?
- 2 How do we express properties of client-server systems naturally?
 - 1 Do existing logics suffice?
 - 2 What additional properties are interesting in the context of unbounded client-server systems?
- 3 Are there formal verification tools for UCS? Can we add to the repertoire?
 - 1 How are existing tools different, unique? Is another tool necessary?

Part 1: Modelling an Unbounded Client-Server (UCS) using Petri Nets



Finite sets of atomic client propositions P_c and server propositions P_s :

$P_c = \{\text{parking_requested(PR)}, \text{occupy_parking_lot(OP)}, \text{parking_unavailable(PU)}, \text{exit_successfully(ES)}, \text{exited_unsuccessfully(EU)}\}$

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- 3 Is the number of rejected requests greater than the number of accepted requests at some point?

$$F(\#p_{EU} > \#p_{ES}).$$

2D-BMC Algorithm

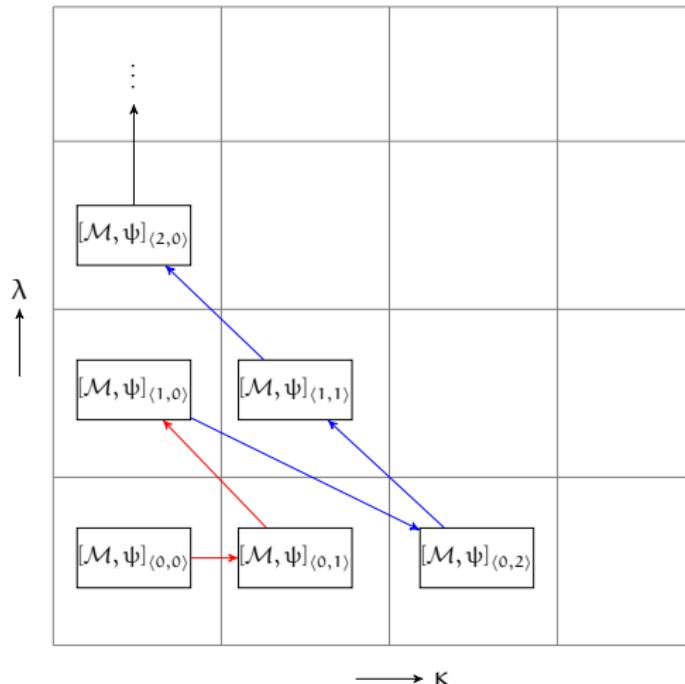


Figure: Unfolding of the encoded formula $[\mathcal{M}, \psi]_{(\lambda, \kappa)}$ with respect to λ (execution steps) and κ (number of tokens)

Tool Architecture

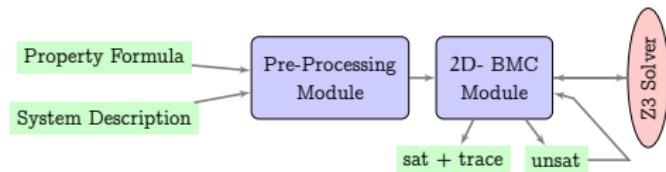


Figure: DCModelChecker architecture

Experimental Results

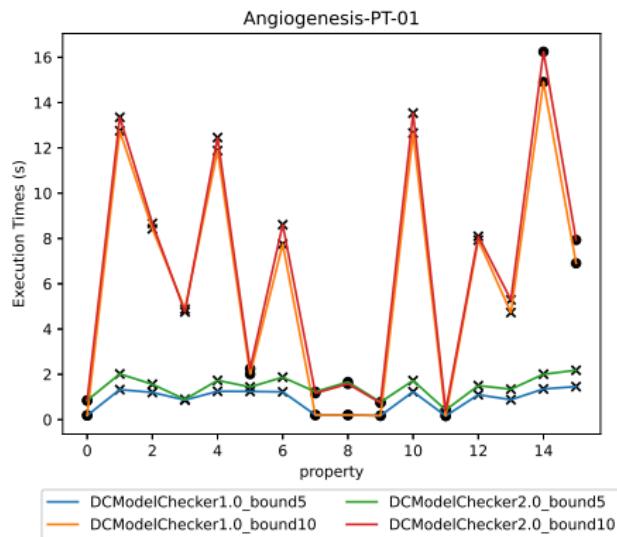


Figure: Verification of FireabilityCardinality Properties with bound 5 and 10

Verified against 16 Benchmarks from Model Checking Contest 2025

Experimental Results

Model	Execution Times(ms)			
	DCModelChecker 1.0	DCModelChecker 2.0	ITS-Tools	Tapaal
Parity	0.010	0.40	0.933	0.02
PGCD	0.019	0.98	1.487	0.07
Process	0.033	0.85	1.201	1e-05
CryptoMiner	0.036	0.64	0.957	7e-06
Murphy	0.031	0.83	1.161	8e-06

Table: Results of Comparative Experiments on Unbounded PNs

Contributions

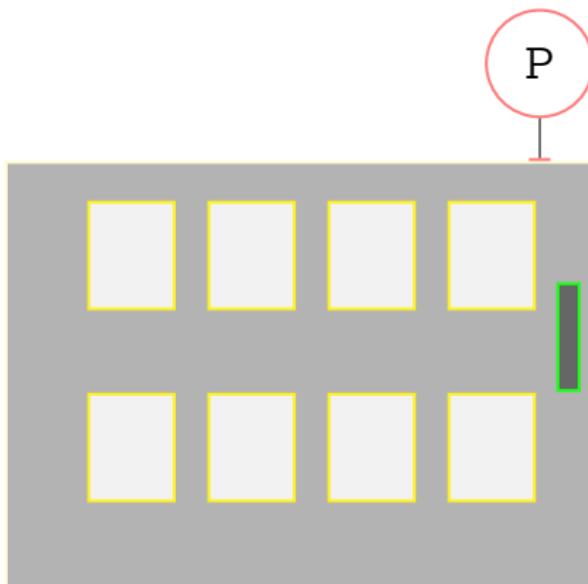
- Part 1: Verification of Unbounded Client-Server (UCS) using Petri Nets and Linear Temporal Logic with integer arithmetic using 2D-BMC

Modelling an Unbounded Client-Server (UCS)

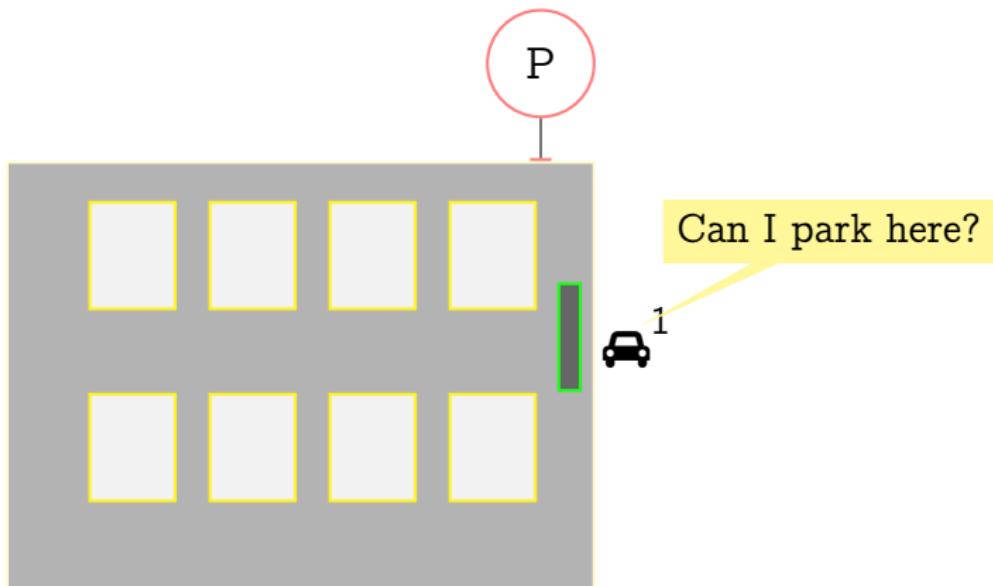
What if clients needed to be distinguished?

Running example

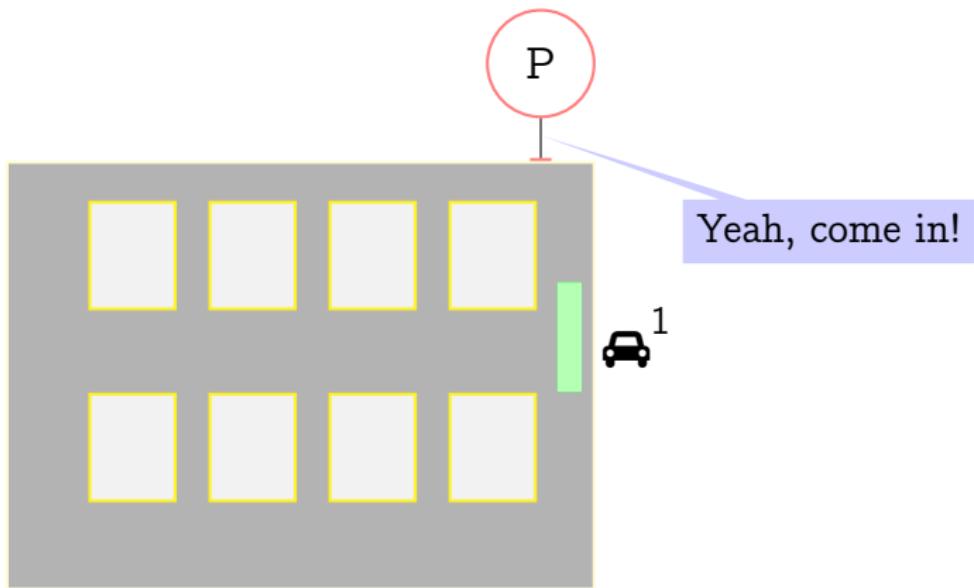
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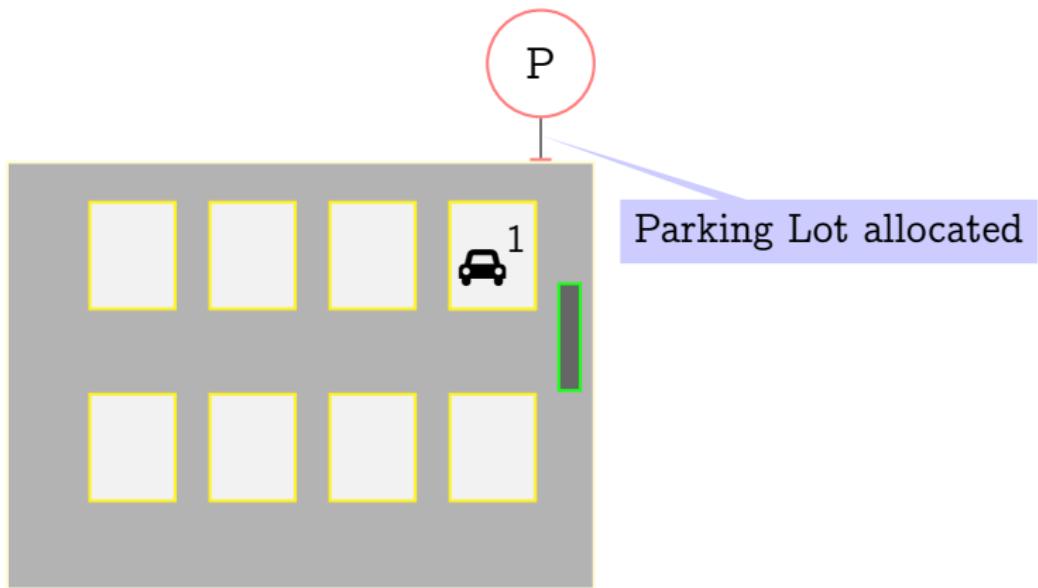
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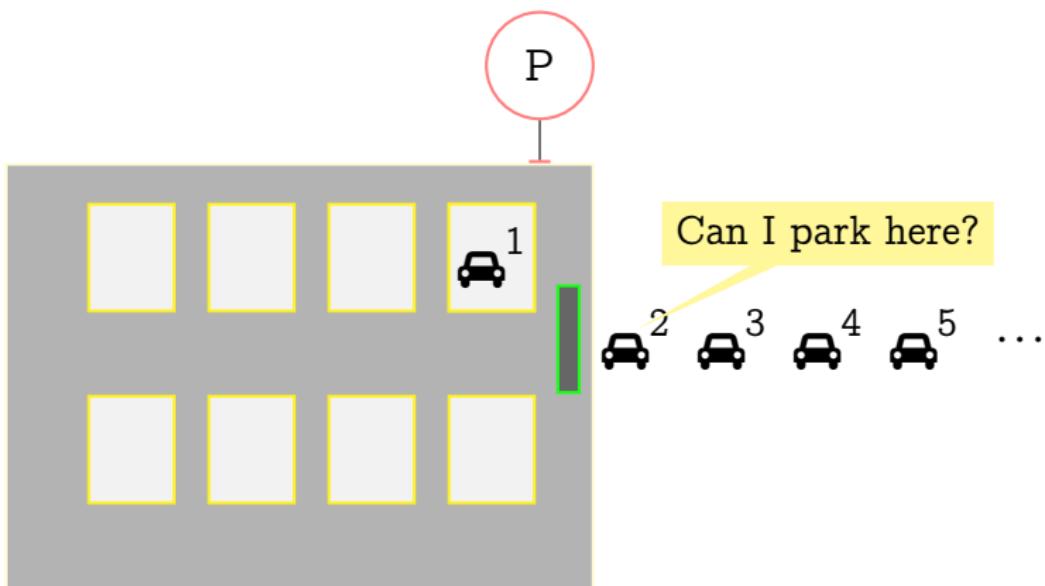


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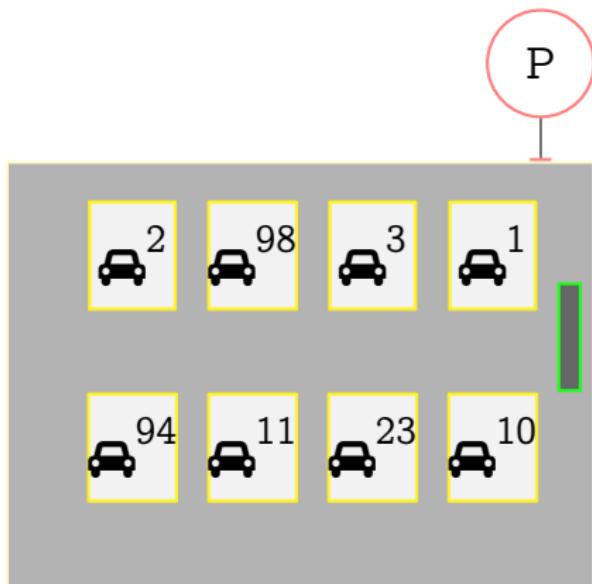
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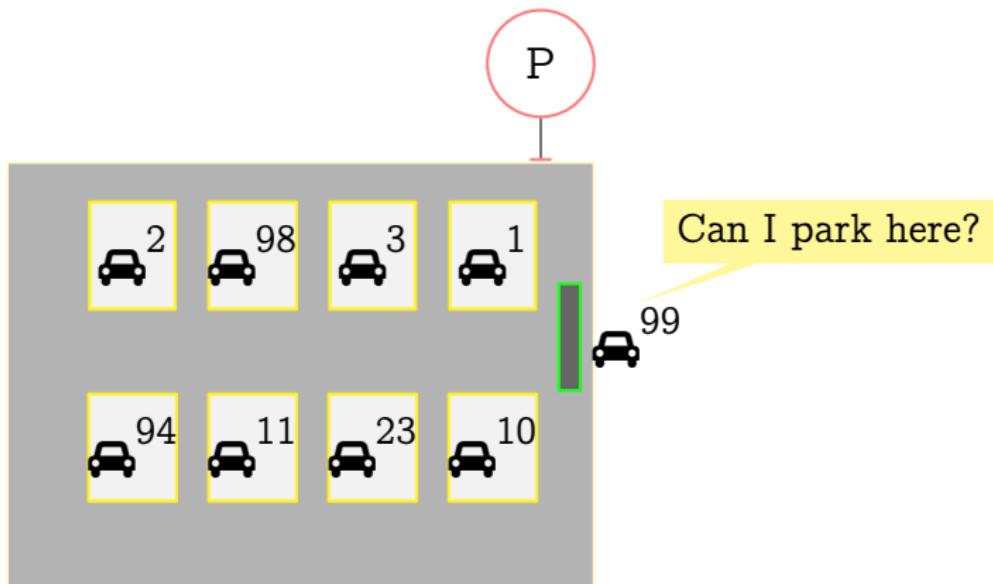


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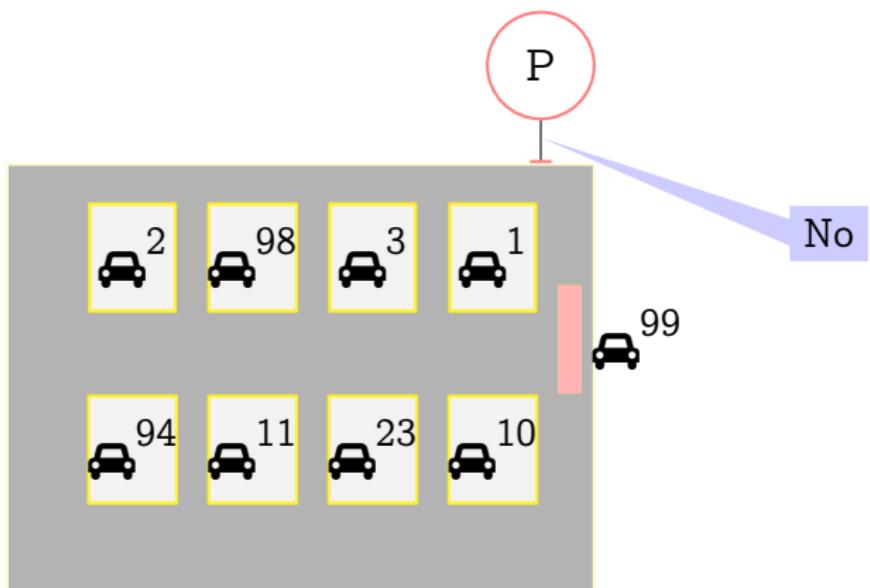
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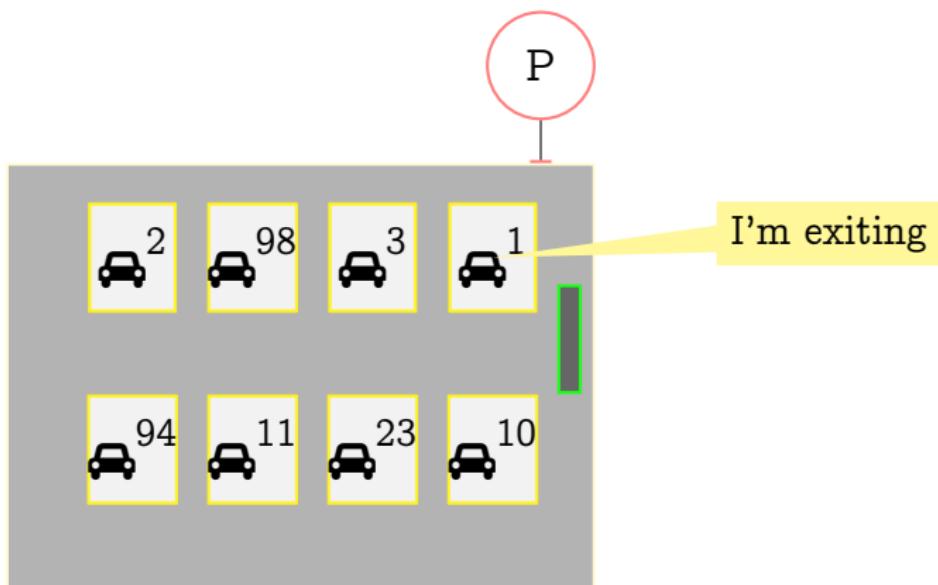
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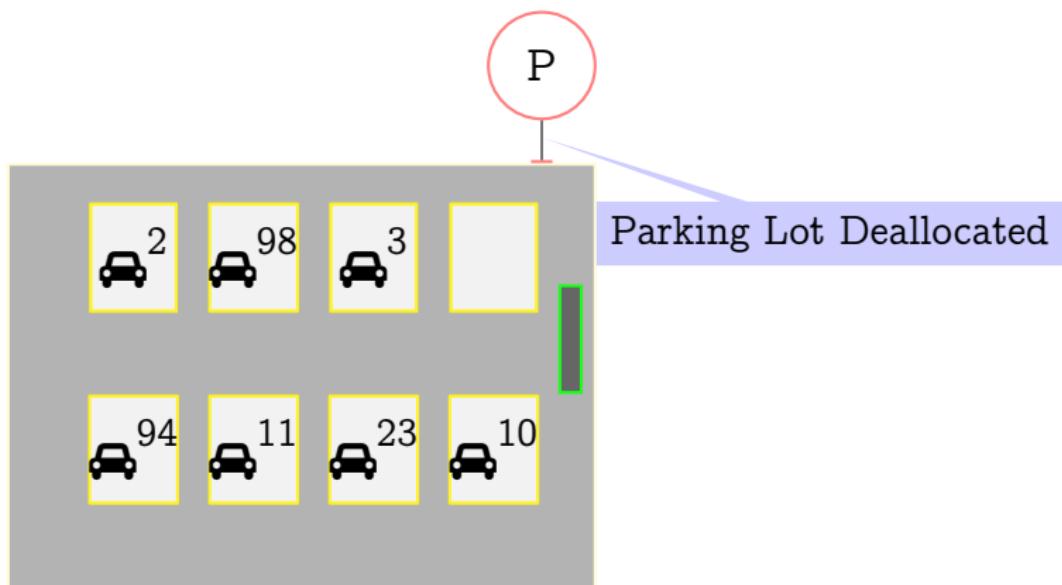
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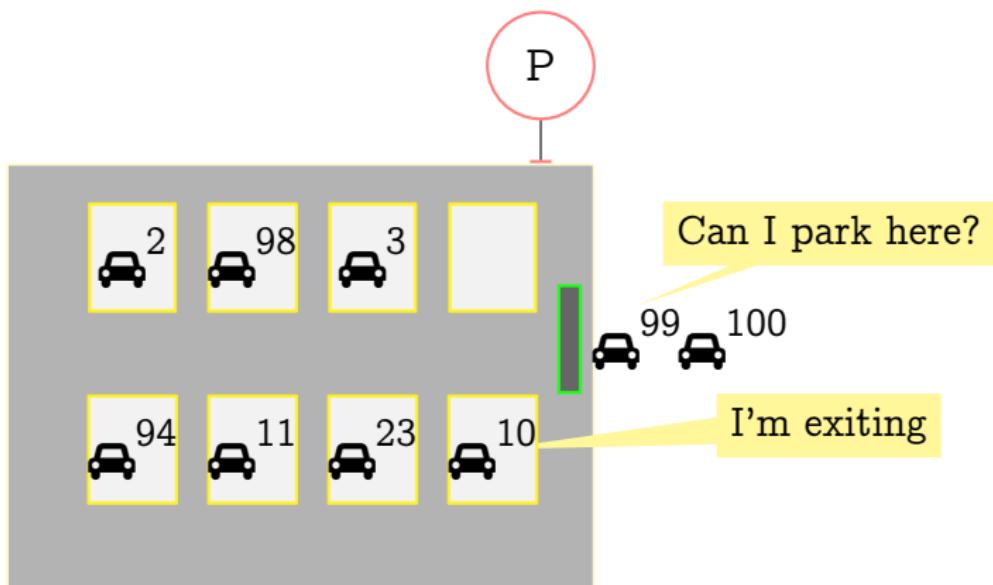


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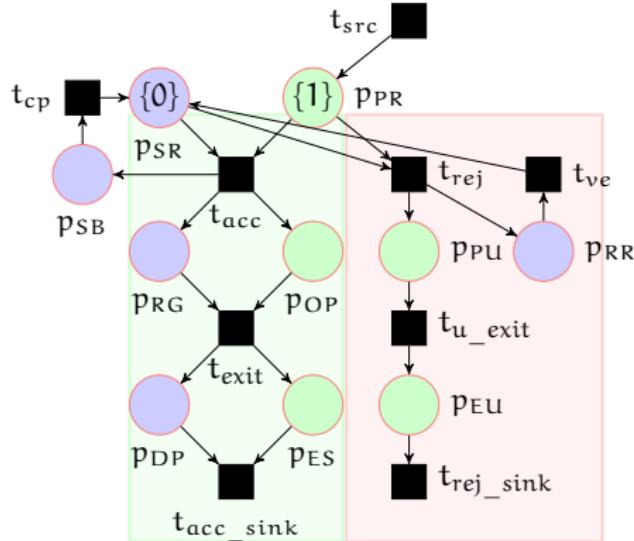


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$$G_s(\forall x) \left(\text{occupy_parking_lot}(x) \Rightarrow F_c(\text{exit_successfully}(x)) \right)$$

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The proposed logic: The Monodic* Logic $\mathcal{L}_{\text{ucs}}^1$

The set of client formulae Δ :

$$\Delta ::= p(x) \mid \neg \alpha \mid \alpha \vee \beta \mid \alpha \wedge \beta \mid X_c \alpha \mid F_c \alpha \mid G_c \alpha \mid \alpha \cup_c \beta$$

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The set of **server formulae** Ψ :

$$\begin{aligned}\Psi ::= & q \mid \neg\psi \mid (\exists x)\alpha \mid (\forall x)\alpha \mid \psi_1 \vee \psi_2 \mid \psi_1 \wedge \psi_2 \mid \\ & X_s \psi \mid F_s \psi \mid G_s \psi \mid \psi_1 U_s \psi_2\end{aligned}$$

where $\psi, \psi_1, \psi_2 \in \Psi$ and $q \in P_s$, the set of atomic server propositions, $\alpha \in \Delta$.

The Monodic Logic $\mathcal{L}_{\text{ucs}}^1$ (contd)

$$\psi = (\exists x)(\exists y) \left((\text{PR}(x) \wedge \text{PR}(y)) \wedge F_c(\text{ES}(x) \wedge \text{ES}(y)) \right)$$

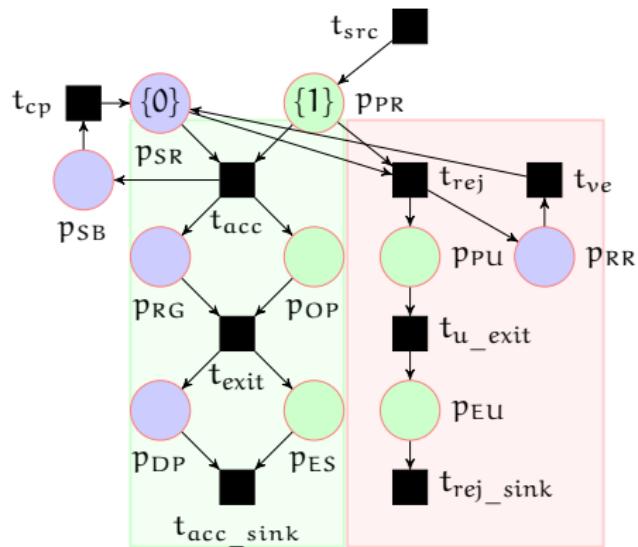
- Is $\psi \in \mathcal{L}_{\text{ucs}}^1$?

The Monodic Logic $\mathcal{L}_{\text{UCS}}^1$ (contd)

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- Is $\psi \in \mathcal{L}_{\text{UCS}}^1$?
- Answer: No. **not a well formed formula** in $\mathcal{L}_{\text{UCS}}^1$

Recall: our model

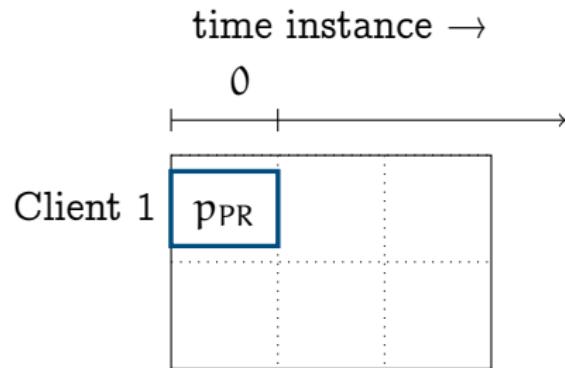


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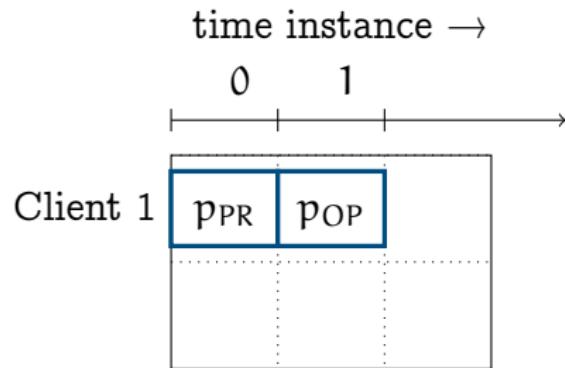
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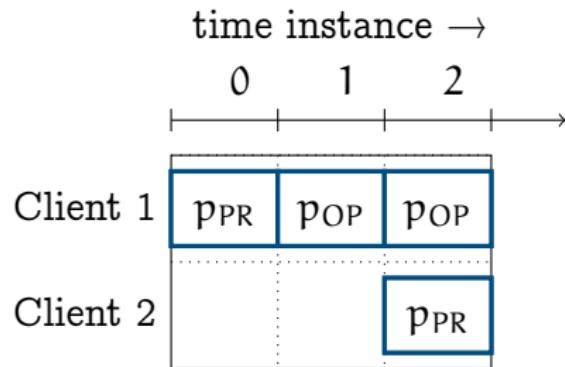
Snapshots of the system + live windows



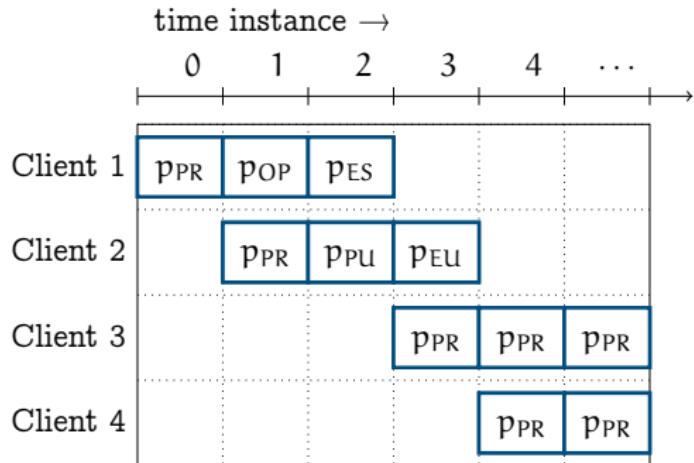
Snapshots of the system + live windows



Snapshots of the system + live windows



Snapshots of the system + live windows (contd)



- 4 distinguishable clients, with overlapping *live windows*, with the bound 5.
- client 1 is at p_{PR} at instance 0. i.e, $PR(x)$ is satisfied in client 1 at instance 0.
- For client 1, the *left boundary* is at instance 0 and its *right boundary* is at instance 2.

Formally speaking...

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- Let $\mathfrak{Z} : CN \times \mathbb{N}_0 \rightarrow Q$ be a partial mapping describing the local state of each client $a \in CN$ at an instance $i \in \mathbb{N}_0$.
 - For instance, $\mathfrak{Z}(a, i) \in q$, means that the local state of each client a at instance i is state q , where $q \in Q$.

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A model is a triple $M = (\nu, V, \xi)$ where

- ν gives the local behaviour of the server as follows:

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$V = V_0 V_1 V_2 \dots$, where for all $0 \leq i$, V_i is a finite subset of CN, gives the set of live agents at the i th instance.

For every $0 \leq i$, V_i and V_{i+1} satisfy the following properties:

- 1 if $V_i \subseteq V_{i+1}$ then for every $a \in V_{i+1} - V_i$ such that $\mathfrak{Z}(a, i+1) \in I$.
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- $\xi = \xi_0 \xi_1 \xi_2 \dots$, where for all $0 \leq i$, $\xi_i : V_i \rightarrow 2^{P_c}$ gives the properties satisfied by each live agent at i th instance.

Also, $L(\mathcal{Z}(a, i)) = \xi_i(a)$.

Semantics

$M, i \models (\exists x)\alpha$ iff $\exists a \in CN, a \in V_i$ and $M, [x \mapsto a], i \models_x \alpha$.

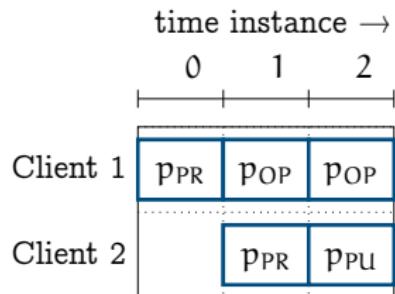
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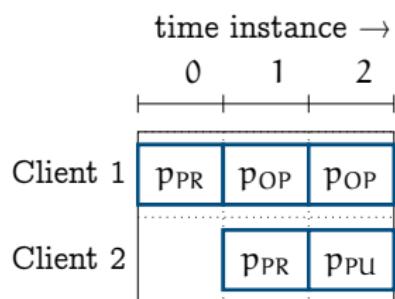
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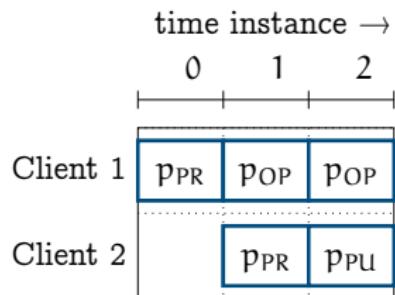
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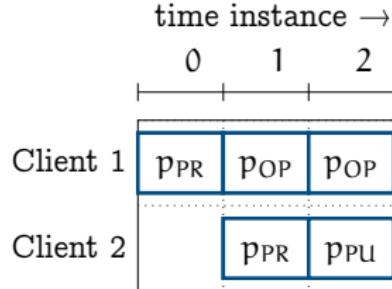


Given $\alpha = OP(x) \vee PR(x)$ and $CN = \{1, 2\}$.

- $M, 0 \models^k (\exists x)(OP(x) \vee PR(x))$.
- $M, 1 \models^k (\exists x)(OP(x) \vee PR(x))$.
- $M, 2 \models^k (\exists x)(OP(x) \vee PR(x))$.

Bounded Semantics

$M, i \models^k (\forall x)\alpha$ iff $\forall a \in CN$, if $a \in V_i$ then $M, [x \mapsto a], i \models_x^k \alpha$



Given $\alpha = ES(x)$ and $CN = \{1, 2\}$.

- $M, 0 \not\models^k (\exists x)(ES(x))$.
- $M, 1 \not\models^k (\exists x)(ES(x))$.
- $M, 2 \not\models^k (\exists x)(ES(x))$.

Bounded Semantics

$M, i \models^k F_s \psi$ iff $\exists j : i \leq j \leq k , M, j \models^k \psi$.

Given $\psi = (\exists x) E S(x)$.

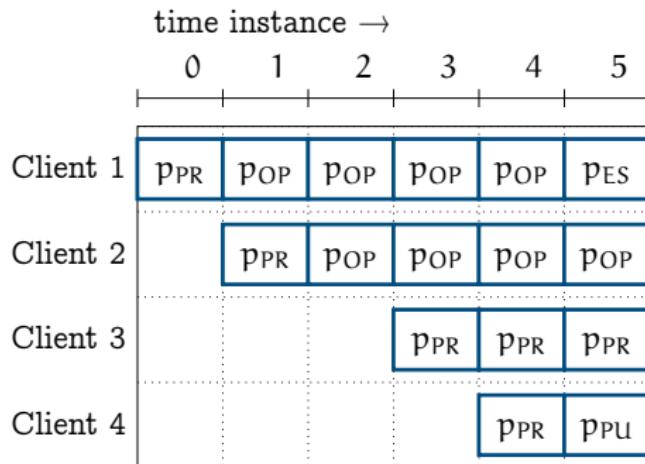


Figure: Snapshot with 4 clients

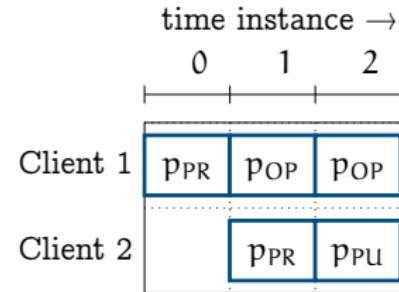


Figure: Snapshot with 2 clients

Bounded Semantics

$M, i \models^k F_s \psi$ iff $\exists j : i \leq j \leq k , M, j \models^k \psi$.

Given $\psi = (\exists x) E S(x)$.

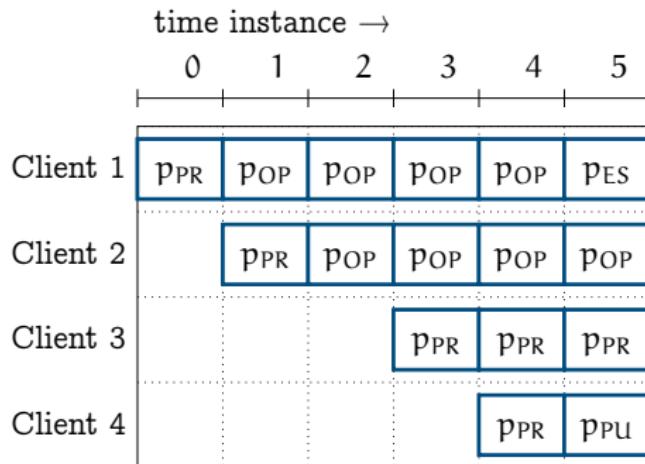


Figure: Snapshot with 4 clients

As shown above $M, 5 \models^k F_s (\exists x) E S(x)$.

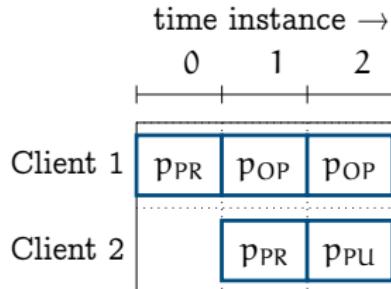


Figure: Snapshot with 2 clients

Implementation

Verifying $G_s \exists x(F_c(p_0(x)))$

```
evname: cToken_4_1
evname: cToken_4_2
evname: cToken_4_3
evname: cToken_4_4
evname: cToken_4_5
evname: sToken_4_1
LOG: done with initializing empty token variables
LOG: sysObj.MAX_TOKENS_LIMIT before initial marking: 1
LOG: constructed initial Marking
LOG: constructed the complete Transition Function
LOG: nochange constraint added
LOG: UNSAT
LOG: UNSAT
LOG: UNSAT
LOG: UNSAT
LOG: -----
evname: cToken_5_0
evname: cToken_5_1
evname: cToken_5_2
evname: cToken_5_3
evname: cToken_5_4
evname: cToken_5_5
evname: sToken_5_1
LOG: done with initializing empty token variables
LOG: sysObj.MAX_TOKENS_LIMIT before initial marking: 1
LOG: constructed initial Marking
LOG: constructed the complete Transition Function
LOG: nochange constraint added
LOG: UNSAT
LOG: UNSAT
LOG: UNSAT
LOG: UNSAT
LOG: UNSAT
```

Contributions

- Part 1: Verification of Unbounded Client-Server (UCS) using Petri Nets and Linear Temporal Logic with integer arithmetic
- Part 2: Verification of UCS with distinguishable clients using ν -nets and properties specified in monodic First Order Logic

Modelling an Unbounded Client-Server (UCS)

What if clients had an internal structure?

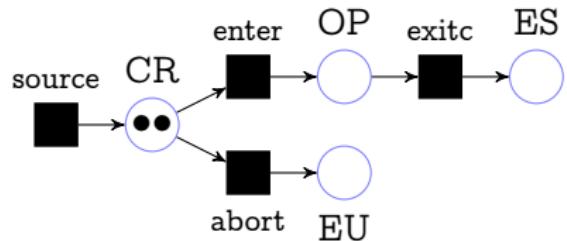


Figure: Petri net N_3 depicting client behaviour

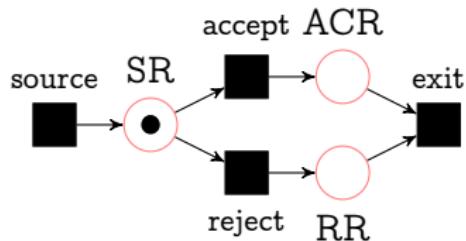


Figure: Petri net N_3 depicting server behaviour

Question: What properties of the system are we interested in?

- **Reachability:** Is $\mu_1 = \langle SR, \{\{client1CR, client2CR\}\} \rangle$ a reachable marking?
- **Coverability:** Given $\mu_1 = \langle SR, \{\{client1CR, client2OP\}\} \rangle$ and $\mu_2 = \langle SR, \{\{client1OP, client2CR, client3OP\}\} \rangle$.
Then, is $\mu_1 \preceq \mu_2$?

Modelling UCS via Elementary Object Systems

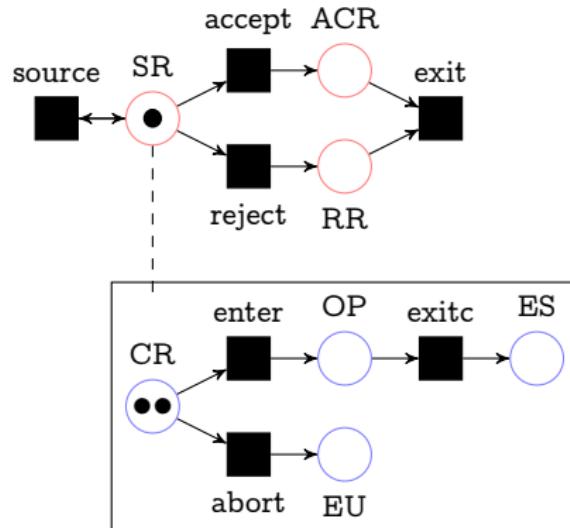
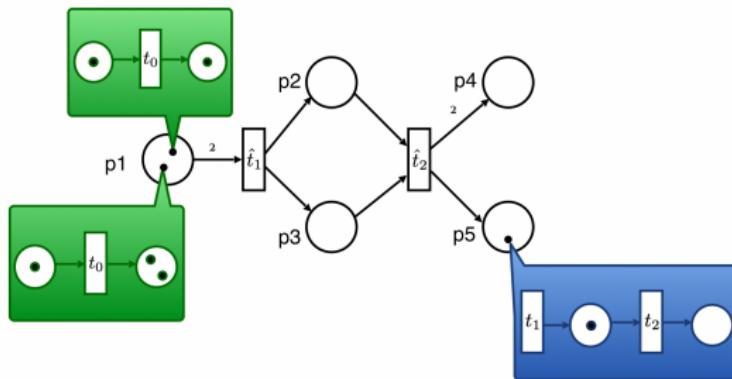


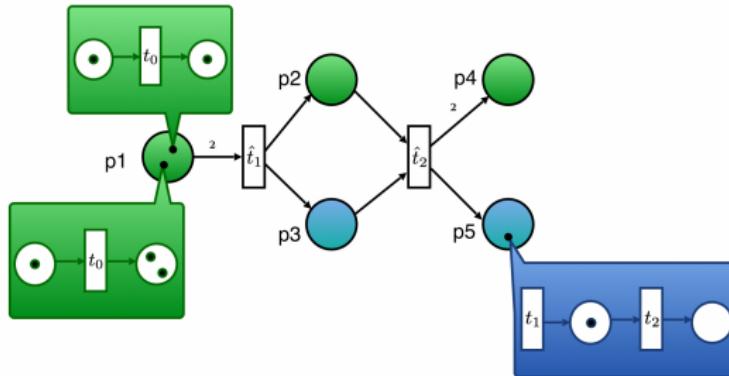
Figure: EOS modeling the single server (unbounded) multiple client system

What are EOSs?

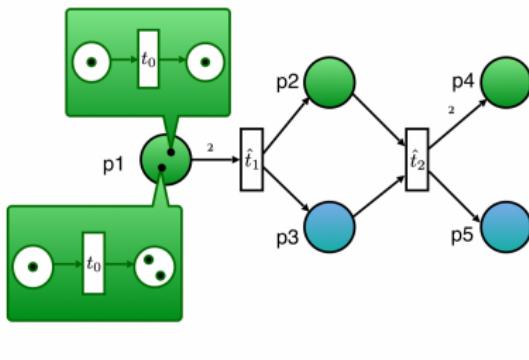
EOS – nested markings



EOS – typed places



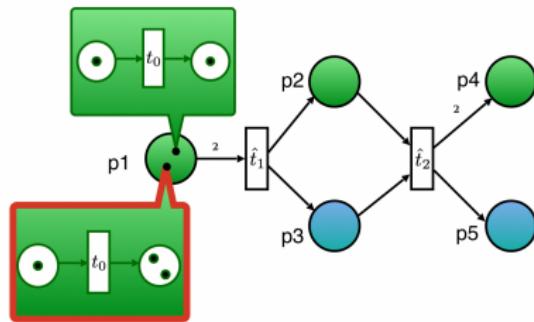
EOS – object autonomous events



EVENTS

$$e_1 = \left(id_{p_1}, t_0 \right)$$
$$e_2 = \left(\hat{t}_1, \emptyset \right)$$
$$e_3 = \left(\hat{t}_2, t_0 t_1 t_1 \right)$$

EOS – object autonomous events



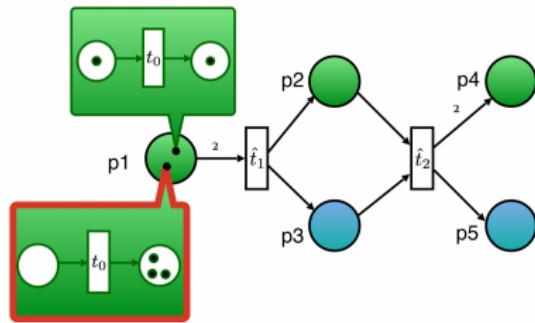
EVENTS

$$e_1 = (id_{p_1}, t_0)$$

$$e_2 = (\hat{t}_1, \emptyset)$$

$$e_3 = (\hat{t}_2, t_0 t_1 t_1)$$

EOS – object autonomous events



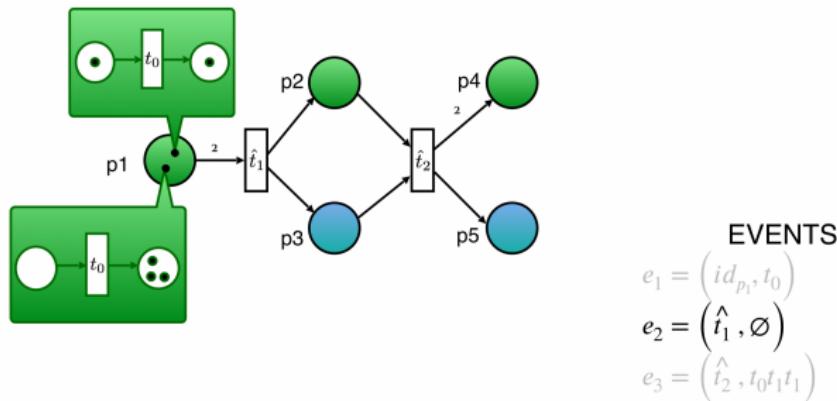
EVENTS

$$e_1 = \left(id_{p_1}, t_0 \right)$$

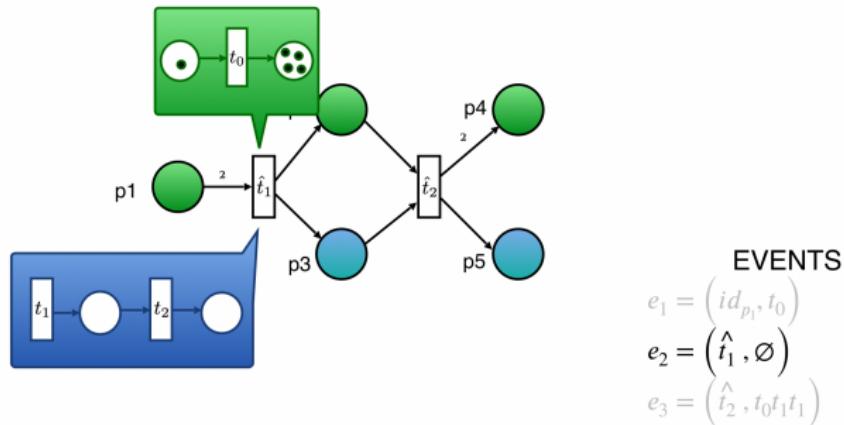
$$e_2 = \left(\hat{t}_1, \emptyset \right)$$

$$e_3 = \left(\hat{t}_2, t_0 t_1 t_1 \right)$$

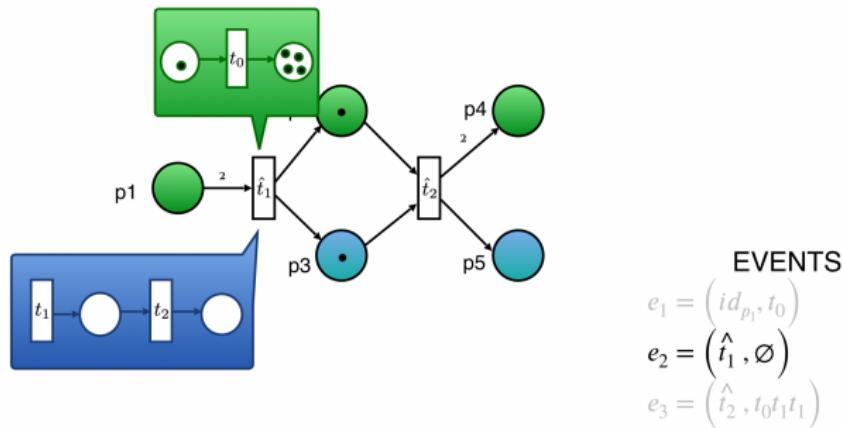
EOS – system autonomous events



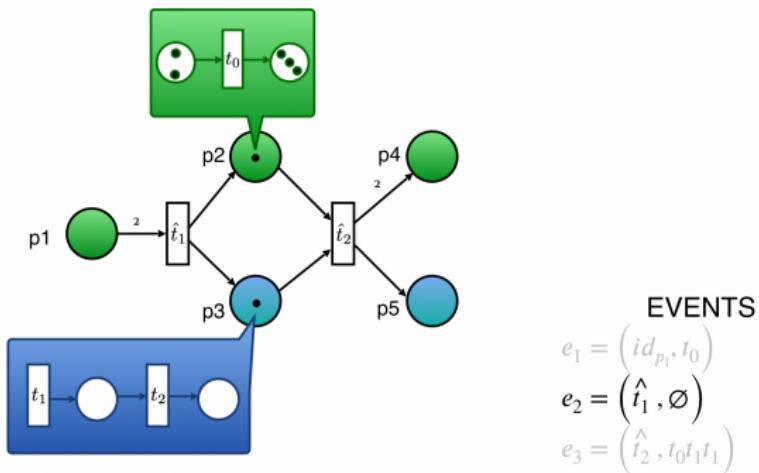
EOS – system autonomous events



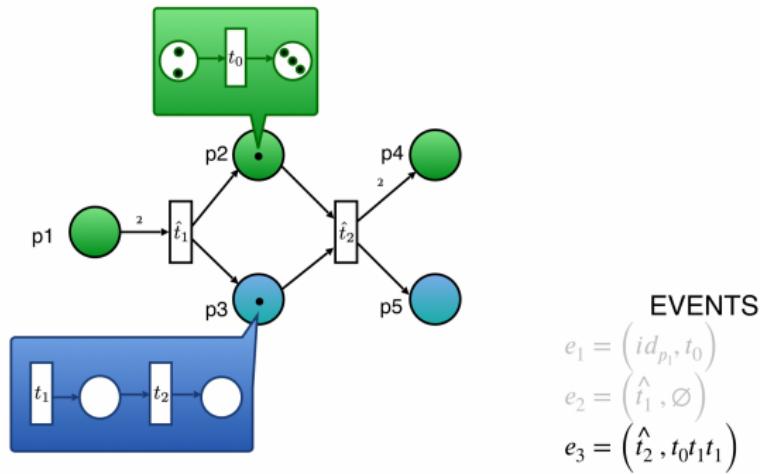
EOS – system autonomous events



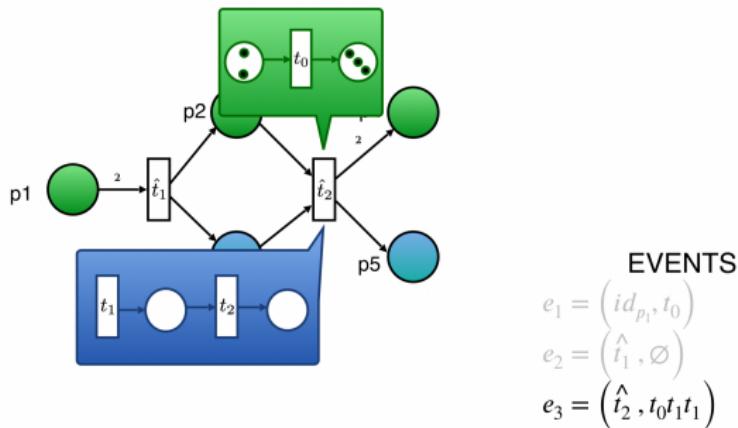
EOS – system autonomous events



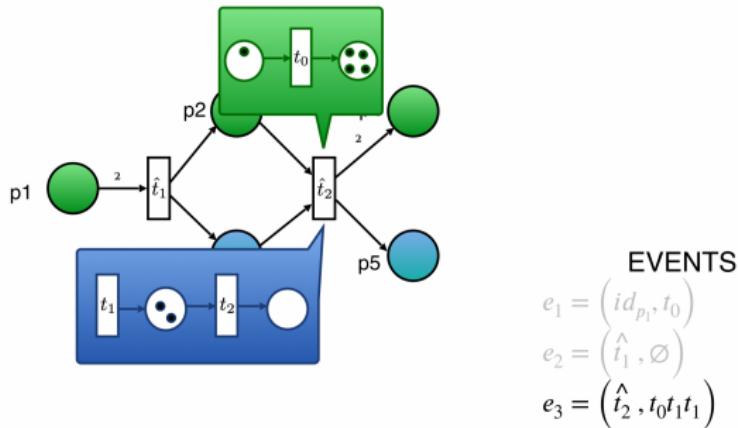
EOS – synchronization events



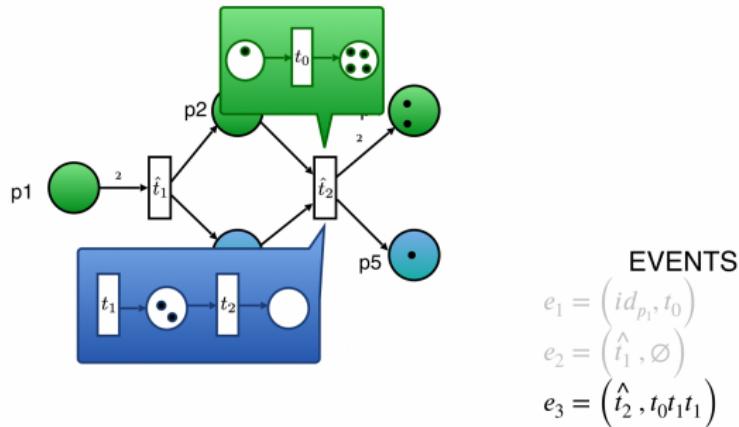
EOS – synchronization events



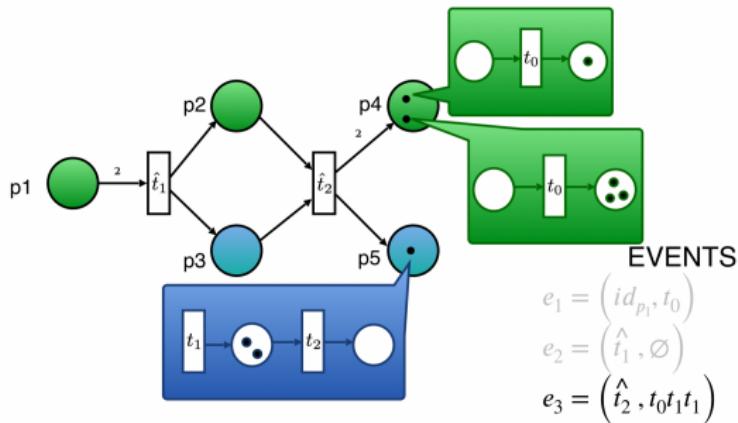
EOS – synchronization events



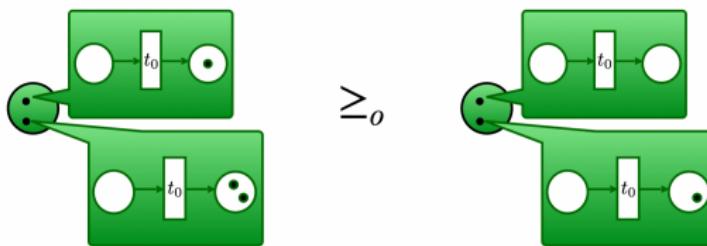
EOS – synchronization events



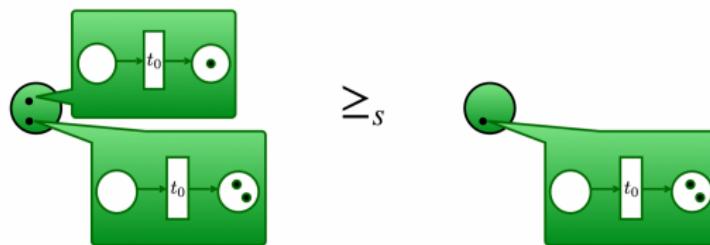
EOS – synchronization events



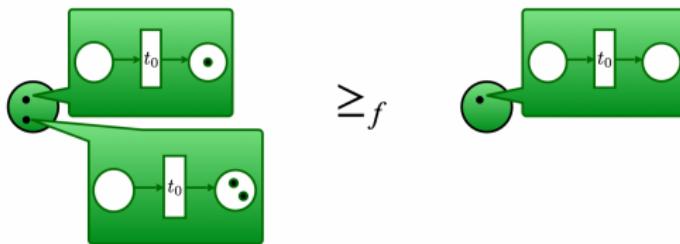
Object lossiness



System lossiness



Full lossiness

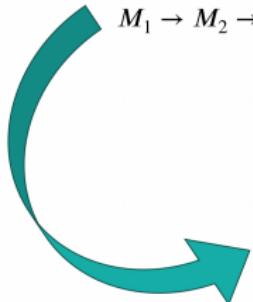
 \geq_f



(\preccurlyeq, ℓ) -lossy runs

Perfect runs: only standard steps

$$M_1 \rightarrow M_2 \rightarrow M_3 \rightarrow \dots$$



(\preccurlyeq, ℓ) -runs: at most $\ell \leq |\mathbb{N}|$ steps of type \preccurlyeq

$$M_1 \rightarrow M_2 \geqslant M'_3 \rightarrow M'_4 \geqslant M'_5 \geqslant M'_6 \rightarrow M_7 \rightarrow \dots$$



(\leq, ℓ) -lossy problems

Is the system **robust** up to ℓ occurrences of \leq ?



(\leq, ℓ) -lossy problems

Is the system **robust** up to ℓ occurrences of \leq ?

(\leq, ℓ) -deadlock freeness

Input

An EOS E and an initial marking M.

Output

Is there a (\leq, ℓ) -run from M to a marking where no event is enabled?

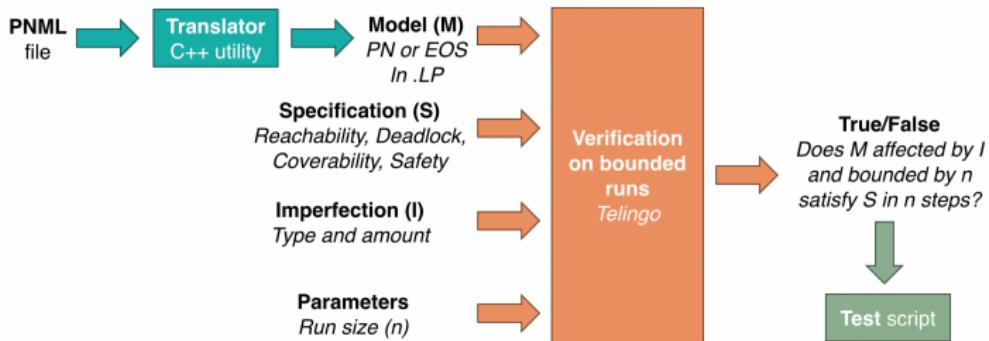
Decidability Results (PNSE'24)

	Problems	\leq_f	\leq_o	\leq_s
Conservative EOS	0-reach	Undec [Buß14]	Undec [Buß14]	Undec [Buß14]
	cover	Dec [Buß14]	Undec (2CM)	Undec (2CM)
	f-reach/cover	Dec (Comp.)	Undec (Comp.)	Undec (Comp.)
	ω -reach/cover	Dec (Comp.)	Undec (Comp.)	Undec (Comp.)
EOS	0-reach	Undec [Buß14]	Undec [Buß14]	Undec [Buß14]
	cover	Undec [Buß14]	Undec (cEOS)	Undec (cEOS)
	f-reach/cover	Undec (Gadget)	Undec (cEOS)	Undec (Comp.)
	ω -reach/cover	Dec (WSTS)	Undec (cEOS)	Undec (Comp.)

[Buß14] Köhler-Bußmeier, Michael. 'A Survey of Decidability Results for Elementary Object Systems'. 1 Jan. 2014 : 99 – 123.



Prototype (CILC'24)



Why bounded verification?



Problems on general EOS	\leq_f	\leq_o	\leq_s
0-reach	U	U	U
0-cover	U	U	U
ℓ -reach/cover	U	U	U
ω -reach/cover	D	U	U

F. Di Cosmo, S. Mal, T. Prince, *Deciding Reachability and Coverability in Lossy EOS*, PNSE'24

Why Telingo?



Telingo is **declarative** and supports **temporal constraints**

- E.g., `:- &tel(>? (lossy >(>? lossy))` allows at most one lossy step
- The meaning of lossy is declared orthogonally to EOS specification

Telingo returns **finite runs**

- Perfectly matches bounded verification

Encoding of PNs and EOSs is **elegant in ASP**

- E.g., when compared to SMT – R. Phawade, T. Prince, S. Sheerazuddin et al., *Bounded Model Checking for Unbounded Client Server Systems*, Arxiv (2022)



Correctness and performances

Correct answers

- Checked on MCC benchmarks

Slow on PNs

- Compared with Tapaal

Prohibitively slow
on EOSS

- Nesting exacerbates grounding

problem	lossiness	-imax = 5 (s)	-imax = 10 (s)	-imax = 20 (s)	TAPAAL (s)
deadlock	none	UNSAT in 0.052	SAT in 0.622	SAT in 82.754	SAT in 5e - 6
deadlock	any	SAT in 0.009	SAT in 0.010	SAT in 0.009	NA
1-safeness	none	UNSAT in 0.010	UNSAT in 0.014	UNSAT in 0.027	UNSAT in 0
1-safeness	any	UNSAT in 0.013	UNSAT in 0.018	UNSAT in 0.032	NA

Table 1

Comparative Results with TAPAAL for the Eratosthenes-PT-010 PN from the MCC benchmarks [12].

Contributions

- Part 1: Verification of Unbounded Client-Server (UCS) using Petri Nets and Linear Temporal Logic with integer arithmetic
- Part 2: Verification of UCS with distinguishable clients using ν -nets and properties specified in monodic First Order Logic
- Part 3: Verification of UCS where the clients have internal structure using Elementary Object Systems and properties specified in Linear Temporal Logic

List of publications:

- 1 Ramchandra Phawade, Tephilla Prince, S. Sheerazuddin: Bounded Model Checking for Unbounded Client Server Systems. Arxiv (2022)
- 2 Tephilla Prince: On Verifying Unbounded Client-Server Systems. Springer EUMAS 2023: 465-471
- 3 Francesco Di Cosmo, Tephilla Prince: Bounded Verification of Petri Nets and EOSs using Telingo: An Experience Report. CILC 2024
- 4 Francesco Di Cosmo, Soumodev Mal, Tephilla Prince: Deciding Reachability and Coverability in Lossy EOS. PNSE@Petri Nets 2024: 74-95

List of publications (ongoing):

- 5 Francesco Di Cosmo, Soumodev Mal, Tephilla Prince: Decidability and Complexity of Reachability and Coverability in Lossy EOS (Under review at TopNOC)
- 6 Ramchandra Phawade, Tephilla Prince, S. Sheerazuddin: Bounded Model Checking for Unbounded Client Server Systems. (Yet to be submitted to TopNOC)
- 7 Ramchandra Phawade, Tephilla Prince, S. Sheerazuddin: A Monodic Logic for Verifying Unbounded Client-Server Systems (yet to be submitted)

Appendix

Bounded Semantics

$M, [x \mapsto a], i \models_x^k F_c \alpha$ iff

$\exists j : i \leq j \leq k, a \in V_j$ and $M, [x \mapsto a], j \models_x^k \alpha$.

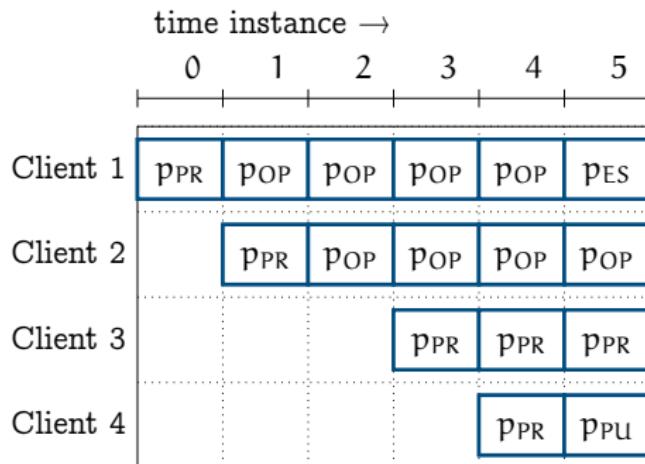


Figure: Snapshot with 4 clients

Given $\alpha = PR(x)$. The above formula is satisfiable for all clients in both figures.

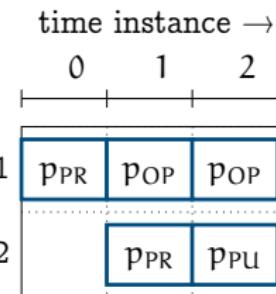


Figure: Snapshot with 2 clients