# Yujin Chen

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#### **EDUCATION**

• Wuhan University, State Key Lab of LIESMARS

M.E. in Cartography and Geographic Information Engineering

Wuhan, China

Sep. 2018 - Jun. 2021

• Wuhan University, School of Geodesy and Geomatics

B.E. in Geomatics Engineering; GPA: 3.71/4.0 (Top 5% in 310 students)

Wuhan, China Sep. 2014 – Jun. 2018

• Israel Institute of Technology (Technion), Faculty of Electrical Engineering

Haifa, Israel

Exchange Student; Summer School of Engineering and Science; Specialize in Machine Learning Jul. 2018 – Aug. 2018

#### RESEARCH EXPERIENCE

## • Visual Computing Lab, University at Buffalo

Research Assistant, Advisor: Prof. Junsong Yuan

Buffalo, NY, U.S.

Jul. 2019 - Nov. 2019

• Hand-Centric Parsing: Hand Pose and Shape Estimation; 3D pose and shape prediction from hand-object interaction image.

## • LIESMARS Vision Lab, Wuhan University

Wuhan, China

Research Assistant, Advisor: Prof. Zhiqang Tu

Sep. 2018 - Present

• **Depth-based 3D Hand Pose Estimation**: Proposed SO-HandNet aims at making use of the unannotated data to obtain accurate 3D hand pose estimation in a semi-supervised manner.

Accept by International Conference on Computer Vision (ICCV'19).

## • Ubiquitous Navigation Lab, Wuhan University

Wuhan, China

Research Assistant, Advisor: Prof. Ruizhi Chen

Jan. 2017 - Jul. 2018

• Image Geo-localization based on Image Retrieval: Developed a novel method for indoor visual positioning aided by CNN-based image retrieval.

\*Accepted by Sensors (SCI journal, 2018 Impact Factor:3.031).

• Scene Constrained Method for Indoor Localization: Developed a multi-sensor fusion method which is

implemented on a smartphone including cameras, Wi-Fi and inertial sensors.

Co-author paper accreet by Sensors.

### • National Undergraduate Research Project, Wuhan University

Wuhan, China

Research Team Leader, Advisor: Prof. Yingbing Li

Mar. 2016 - Sep. 2017

• Modeling, Evaluation and Analysis of Real Estate Data in Wuhan: Built real estate appraisal model using Neural Network.

Led a team of 5 members and the project which was evaluated as **Excellent**; Accept by a Chinese journal.

#### Publications

• Human-Centric Parsing:

SO-HandNet: Self-Organizing Network for 3D Hand Pose Estimation with Semi-supervised Learning.

Yujin Chen, Zhigang Tu, Liuhao Ge, Dejun Zhang, Ruizhi Chen, Junsong Yuan.

Proc. International Conference on Computer Vision (ICCV'19).

• Image Geo-localization & Indoor Scene Understanding:

Indoor Visual Positioning Aided by CNN-Based Image Retrieval: Training-Free, 3D Modeling Free.

Yujin Chen, Ruizhi Chen, Mengyun Liu, Aoran Xiao, Dewen Wu, Shuheng Zhao.

Sensors, 2018.

Scene recognition for indoor localization using a multi-sensor fusion approach.

Mengyun Liu, Ruizhi Chen, Deren Li, **Yujin Chen**, Guangyi Guo, Zhipeng Cao, Yuanjing Pan. Sensors, 2017.

An indoor positioning system based on static objects in large indoor scenes by using smartphone cameras. Aoran Xiao, Ruizhi Chen, Deren Li, Yujin Chen, Dewen Wu.

Sensors, 2018.

# AWARDS AND HONORS

Research Abroad Scholarship (top 1%), State key Lab of LIESMARS	2019
LIESMARS Freshman Scholarship (top 3%), State key Lab of LIESMARS	2018
National Endeavor Scholarship (top 3%), Ministry of Education of China	2015, 2016, 2017
Outstanding Bachelor Thesis award, Wuhan University	2018
Outstanding Graduate (top 5%), Wuhan University	2018
Postgraduate Freshman Scholarship(top 10%), Wuhan University	2018
Merit Student Honor (top 10%), Wuhan University	2016, 2017

# Programming Skills

Pytorch, Tensorflow, Python, C++/C, Matlab, C#, Android/Java, R, Latex

# ACADEMIC SERVICES

Teaching Assistant

Coursera: Computer Vision Specialization

 $Summer\ 2019$