Homework set 3

Please submit this Jupyter notebook through Canvas no later than Mon Nov. 20, 9:00. Submit the notebook file with your answers (as .ipynb file) and a pdf printout. The pdf version can be used by the teachers to provide feedback. A pdf version can be made using the save and export option in the Jupyter Lab file menu.

Homework is in **groups of two**, and you are expected to hand in original work. Work that is copied from another group will not be accepted.

Exercise 0

Write down the names + student ID of the people in your group.

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Run the following cell to import NumPy and Pyplot.

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
```

Exercise 1

In this exercise you will study the accuracy of several methods for computing the QR decomposition. You are asked to implement these methods yourself. (However, when testing your implementation you may compare with an external implementation.)

(a)

Implement the classical and modified Gram-Schmidt procedures for computing the QR decomposition.

Include a short documentation using triple quotes: describe at least the input and the output, and whether the code modifies the input matrix.

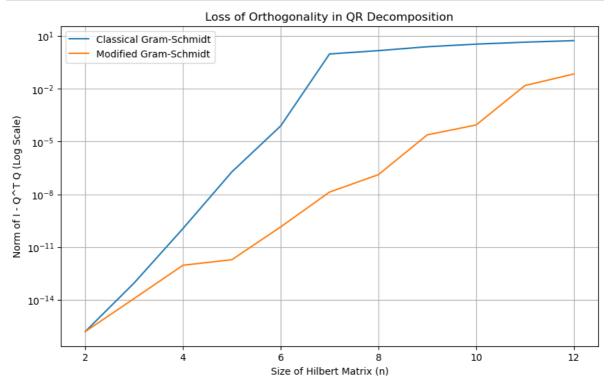
```
m, n = A.shape
    Q = np.zeros((m, n))
    R = np.zeros((n, n))
    for i in range(n):
        Q[:, i] = A[:, i]
        for j in range(i):
            R[j, i] = np.dot(Q[:, j], A[:, i])
            Q[:, i] = R[j, i] * Q[:, j]
        R[i, i] = np.linalg.norm(Q[:, i])
        Q[:, i] /= R[i, i]
    return Q, R
def modified_gram_schmidt(A):
    Modified Gram-Schmidt procedure for QR decomposition.
    Parameters:
    A (numpy.ndarray): The input matrix to be decomposed. It should be a 2D
    Returns:
    Q (numpy.ndarray): Orthogonal matrix.
   R (numpy.ndarray): Upper triangular matrix.
   Note:
    This function does not modify the input matrix A.
    m, n = A.shape
    Q = np.zeros((m, n))
   R = np.zeros((n, n))
    for k in range(n):
        R[k, k] = np.linalg.norm(A[:, k])
        Q[:, k] = A[:, k] / R[k, k]
        for i in range(k + 1, n):
            R[k, i] = np.dot(Q[:, k], A[:, i])
            A[:, i] = R[k, i] * Q[:, k]
    return Q, R
```

(b) (a+b 3.5 pts)

Let H be a Hilbert matrix of size n (see Computer Problem 2.6). Study the quality of the QR decompositions obtained using the two methods of part (a), specifically the loss of orthogonality. In order to do so, plot the quantity $\|I-Q^TQ\|$ as a function of n on a log scale. Vary n from 2 to 12.

```
In [3]: def hilbert_matrix(n):
    """Generate an n x n Hilbert matrix."""
    return np.array([[1 / (i + j - 1) for j in range(1, n + 1)] for i in range(1, n + 1)] for
```

```
norms_modified = []
# Vary n from 2 to 12
for n in range(2, 13):
   H = hilbert_matrix(n)
    # Classical Gram-Schmidt
    Q_classical, _ = classical_gram_schmidt(H)
    norms_classical.append(norm_diff(Q_classical))
    # Modified Gram-Schmidt
    Q_modified, _ = modified_gram_schmidt(H)
    norms_modified.append(norm_diff(Q_modified))
# Plotting the results
plt.figure(figsize=(10, 6))
plt.semilogy(range(2, 13), norms_classical, label='Classical Gram-Schmidt')
plt.semilogy(range(2, 13), norms_modified, label='Modified Gram-Schmidt')
plt.xlabel('Size of Hilbert Matrix (n)')
plt.ylabel('Norm of I - Q^T Q (Log Scale)')
plt.title('Loss of Orthogonality in QR Decomposition')
plt.legend()
plt.grid(True)
plt.show()
```



We generally expect to see an increasing trend in the loss of orthogonality as the size of the Hilbert matrix increases. This is because Hilbert matrices are known to be ill-conditioned, and their condition worsens with increasing size, leading to more significant numerical errors in the QR decomposition.

The Modified Gram-Schmidt method is typically more numerically stable than the Classical method. Therefore, the plot might show a lower loss of orthogonality for the Modified method compared to the Classical method, especially as the matrix size increases.

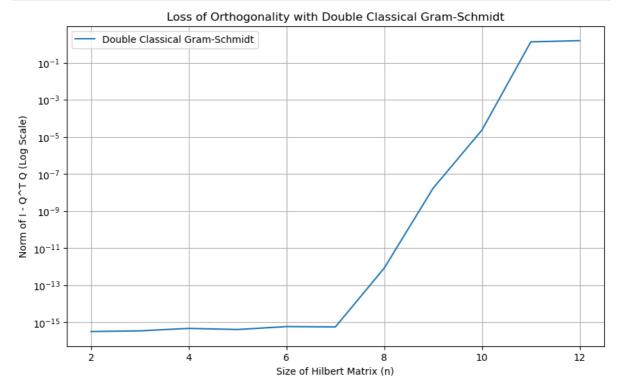
A higher value of $\|I - Q^T Q\|$ indicates a greater deviation of Q from perfect orthogonality. In numerical methods, maintaining orthogonality is crucial for the

accuracy of subsequent computations, such as solving linear systems or eigenvalue problems.

(c) (1.5 pts)

Try applying the classical procedure twice. Plot again the loss of orthogonality when computing the QR decomposition of the Hilbert matrix of size n as in (b).

```
In [4]:
        # Initialize list to store the norms for double classical Gram-Schmidt
        norms_double_classical = []
        # Vary n from 2 to 12
        for n in range(2, 13):
            H = hilbert_matrix(n)
            # Double Classical Gram-Schmidt
            Q1, _ = classical_gram_schmidt(H)
            Q2, _ = classical_gram_schmidt(Q1)
            norms_double_classical.append(norm_diff(Q2))
        # Plotting the results
        plt.figure(figsize=(10, 6))
        plt.semilogy(range(2, 13), norms_double_classical, label='Double Classical (
        plt.xlabel('Size of Hilbert Matrix (n)')
        plt.ylabel('Norm of I - Q^T Q (Log Scale)')
        plt.title('Loss of Orthogonality with Double Classical Gram-Schmidt')
        plt.legend()
        plt.grid(True)
        plt.show()
```



A lower loss of orthogonality in the double application would suggest that reorthogonalization helps in mitigating the issues of loss of orthogonality. This would be particularly evident for larger matrix sizes where the single application might show significant orthogonality loss. Since Hilbert matrices are known for their poor conditioning and tendency to induce numerical instability, they serve as a stringent test case. Improvement in orthogonality for these matrices would indicate a robust benefit of the re-orthogonalization approach.

If double application significantly improves orthogonality, it suggests that the classical method, while not inherently stable, can be enhanced for better performance in certain situations.

(d) (2 pts)

Implement the Householder method for computing the QR decomposition. Remember to include a short documentation.

```
def householder_qr(A):
In [5]:
            Compute the QR decomposition of a matrix using the Householder method.
            Parameters:
            A (numpy.ndarray): The input matrix to be decomposed. It should be a 2D
            Returns:
            Q (numpy.ndarray): Orthogonal matrix.
            R (numpy.ndarray): Upper triangular matrix.
            Note:
            This function does not modify the input matrix A.
            A = A.astype(np.float64) # Ensure A is of floating-point type
            m, n = A. shape
            R = A.copy()
            Q = np.eye(m)
            for k in range(n - (m == n)):
                # Create the Householder vector
                x = R[k:, k]
                e1 = np.zeros_like(x)
                e1[0] = np.linalg.norm(x) * np.sign(x[0])
                u = x - e1
                v = u / np.linalg.norm(u)
                # Update R and Q
                R[k:, k:] = 2 * np.outer(v, np.dot(v, R[k:, k:]))
                Q_k = np.eye(m)
                Q_k[k:, k:] = 2 * np.outer(v, v)
                Q = np.dot(Q, Q_k)
             return Q, R
        # Test
        A = np.array([[1, 2, 3], [4, 5, 6], [7, 8, 9]])
        Q, R = householder_qr(A)
```

This function computes the QR decomposition of a matrix using the Householder method by taking a single parameter A, which is a 2D NumPy array representing the matrix to be decomposed. It returns two matrices, Q and R. Q is an orthogonal matrix, and R is an upper triangular matrix such that A=QR.

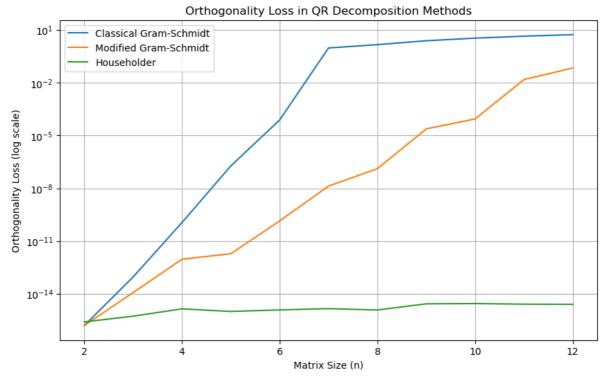
The Householder method is more numerically stable than the classical Gram-Schmidt process, especially for matrices with close-to-linearly dependent columns.

(e) (2 pts)

Perform the analysis of (b) for the Householder method. Discuss the differences between all the methods you have tested so far. Look online and/or in books for information about the accuracy of the different methods and include this in your explanations (with reference).

```
In [6]:
        def hilbert_matrix(n):
             """Create an n x n Hilbert matrix."""
             return np.array([[1 / (i + j - 1) \text{ for } j \text{ in } range(1, n + 1)] \text{ for } i \text{ in } range(1, n + 1)
         def classical_gram_schmidt(A):
             """Classical Gram-Schmidt QR decomposition."""
             m, n = A.shape
             Q = np.zeros((m, n))
             R = np.zeros((n, n))
             for k in range(n):
                 Q[:, k] = A[:, k]
                 for i in range(k):
                     R[i, k] = np.dot(Q[:, i], A[:, k])
                     Q[:, k] = R[i, k] * Q[:, i]
                 R[k, k] = np.linalg.norm(Q[:, k])
                 Q[:, k] /= R[k, k]
             return Q, R
         def modified_gram_schmidt(A):
             """Modified Gram-Schmidt QR decomposition."""
             m, n = A.shape
             Q = np.zeros((m, n))
             R = np.zeros((n, n))
             for k in range(n):
                 R[k, k] = np.linalg.norm(A[:, k])
                 Q[:, k] = A[:, k] / R[k, k]
                 for i in range(k + 1, n):
                     R[k, i] = np.dot(Q[:, k], A[:, i])
                     A[:, i] = R[k, i] * Q[:, k]
             return Q, R
         def householder(A):
             """Householder QR decomposition."""
             m, n = A.shape
             Q = np.eye(m)
             R = A.copy()
             for k in range(n - 1):
                 x = R[k:, k]
                 e = np.zeros_like(x)
                 e[0] = np.linalg.norm(x)
                 u = x + np.sign(x[0]) * e
                 u = u / np.linalg.norm(u)
                 R[k:, k:] = 2 * np.outer(u, np.dot(u, R[k:, k:]))
                 Q[k:] = 2 * np.outer(u, np.dot(u, Q[k:]))
```

```
return Q.T, R
def orthogonality_loss(Q):
    """Compute the orthogonality loss."""
    return np.linalg.norm(np.eye(Q.shape[1]) - np.dot(Q.T, Q))
# Range of n
n_{values} = range(2, 13)
# Store orthogonality losses
losses_classical = []
losses_modified = []
losses_householder = []
for n in n values:
    H = hilbert_matrix(n)
    Q_classical, _ = classical_gram_schmidt(H)
    Q_modified, _ = modified_gram_schmidt(H)
    Q_householder, _ = householder(H)
    losses_classical.append(orthogonality_loss(Q_classical))
    losses_modified.append(orthogonality_loss(Q_modified))
    losses_householder.append(orthogonality_loss(Q_householder))
# Plotting
plt.figure(figsize=(10, 6))
plt.semilogy(n_values, losses_classical, label='Classical Gram-Schmidt')
plt.semilogy(n_values, losses_modified, label='Modified Gram-Schmidt')
plt.semilogy(n_values, losses_householder, label='Householder')
plt.xlabel('Matrix Size (n)')
plt.ylabel('Orthogonality Loss (log scale)')
plt.title('Orthogonality Loss in QR Decomposition Methods')
plt.legend()
plt.grid(True)
plt.show()
```



Classical Gram-Schmidt: It orthogonalizes a set of vectors by iteratively subtracting the projection of each vector onto the previously orthogonalized vectors. Known for its

simplicity but can be numerically unstable, especially with ill-conditioned matrices like Hilbert matrices. This method is prone to loss of orthogonality due to round-off errors. It have a computational complexity of $O(n^3)$ for an $n \times n$ matrix.

Modified Gram-Schmidt: It orthogonalizes each vector against all previously orthogonalized vectors, one at a time. An improvement over the classical method in terms of numerical stability. This is because it reduces the accumulation of rounding errors during the orthogonalization process. It explicitly reorthogonalizes the vectors, which helps maintain orthogonality but still can suffer from numerical issues with very ill-conditioned matrices. It have a computational complexity of $O(n^3)$ for an $n \times n$ matrix, but it has a slightly higher constant factor due to its improved stability.

Householder Method: The Householder method uses Householder reflections to transform a matrix into an upper triangular form. It's a more involved process compared to Gram-Schmidt methods. Generally more stable than both Gram-Schmidt variants. The method is less sensitive to rounding errors and can handle ill-conditioned matrices more effectively. It's particularly effective for ill-conditioned matrices. The Householder method tends to maintain orthogonality better, leading to a smaller $|I-Q^TQ||$ value. It also have a computational complexity of $O(n^3)$ for an $n\times n$ matrix, but the constant factors are typically higher than last two methods. However, this trade-off is often worth it for the increased accuracy and stability.

Reference:

Trefethen, Lloyd N., and David Bau III. Numerical Linear Algebra. Philadelphia: SIAM, 1997. Print.

Golub, Gene H., and Charles F. Van Loan. Matrix Computations. 4th ed., Baltimore: Johns Hopkins University Press, 2013. Print.

Stewart, Gilbert W. Introduction to Matrix Computations. New York: Academic Press, 1973. Print.

Higham, Nicholas J. Accuracy and Stability of Numerical Algorithms. 2nd ed., Philadelphia: SIAM, 2002. Print.