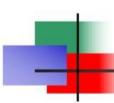


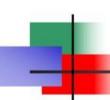
## Chapter 5

# Digital transmission through the AWGN channel

— by Prof. XIAOFENG LI SICE, UESTC



- Introduction
- Geometric rep. of the sig waveforms
- Pulse amplitude modulation
- 2-d signal waveforms
- M-d signal waveforms
- Opt. reception for the sig. in AWGN
- Optimal receivers and probs of err

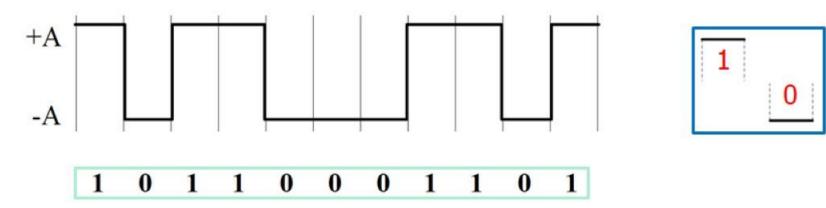


5.2.1. PAM: Binary= info bits are 1 and 0

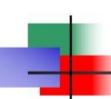


**5.2.1. PAM:** Binary= info bits are 1 and 0

Pulses of amp A and -A is used, called antipodal (or polar) signaling.



If one bit takes an interval of  $T_b$  seconds, the rate of signaling is  $R_b = 1 / T_b$  bps (bit-per-sec).



Alternately, A

and 0 may be

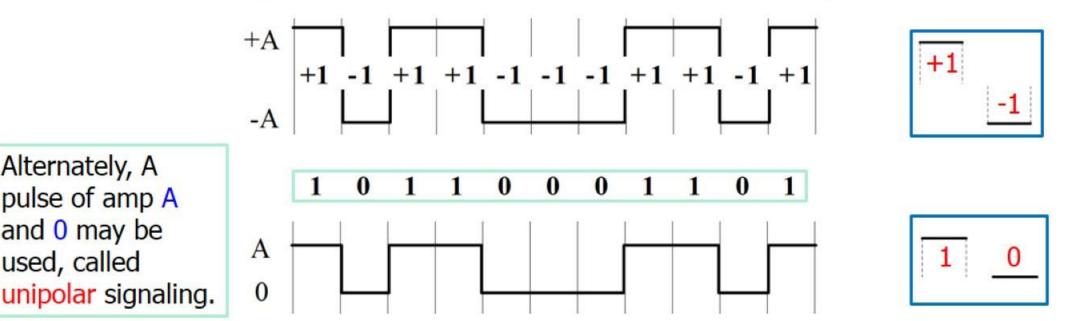
used, called

pulse of amp A

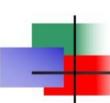
#### 5.2 Pulse amplitude modulation

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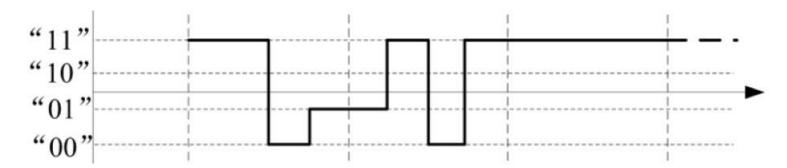


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A str of k bits is regarded as a symbol, and we have  $M=2^k$  different symbols.

- Take k=2, then M=4, and there are 4 symbols: 00, 01, 10, 11.
- We need 4 signals, pulses of 4 different amps, to send them.



If one symbol takes an interval of  $T_s$  seconds, the rate of signaling is  $R_s = 1/T_s$  symbols/s (also called Bauds).

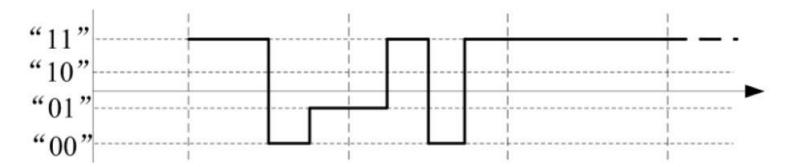
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#### 5.2 Pulse amplitude modulation

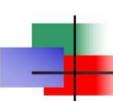
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- More, 1)  $R_s$  is called the symbol rate, or baud rate.
  - 2) The bit rate is  $R_b = kR_s$  bps. Equivalently, the bit interval is  $T_b = T_s / k$ .



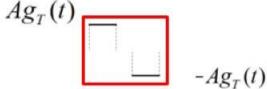
5.2.1. PAM: signal expression.

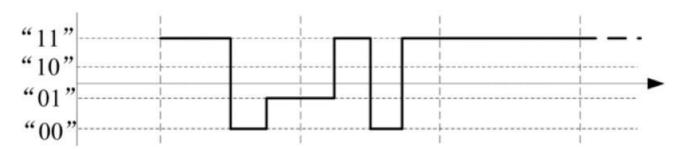
#### 5.2.1. PAM: signal expression.

$$S_m(t) = A_m g_T(t)$$

The signal 'element' is a rect pulse, and generally, can be of other shapes.







#### Pulse Amp Modulation

- For polar 2-PAM, A<sub>m</sub> are A and –A.
- For polar 4-PAM, A<sub>m</sub> are 3A, A, –A and –3A.

Generally, let  $g_T(t)$  be the pulse, the signals for M symbols is,

$$s_m(t) = A_m g_T(t)$$
  $m = 1, 2, ..., M$ 

where  $A_m$  are amps.



**5.2.1. PAM**: geometric representation

$$S_m(t) = A_m g_T(t)$$



#### **5.2.1. PAM**: geometric representation

$$S_m(t) = A_m g_T(t)$$

1) Basis function:  $\psi(t) = k_0 g_T(t)$ 

where 
$$k_0 = 1/\sqrt{E_g}$$
,  $E_g = \int_{-\infty}^{\infty} g_T^2(t) dt$  = the energy of the  $g_T(t)$ .

The space is of 1-d and N=1.

2) The signal vectors (points):  $\mathbf{s}_m = (a_m)$  m = 1, 2, ..., M

$$\mathbf{s}_m = (a_m)$$

$$m = 1, 2, ..., M$$

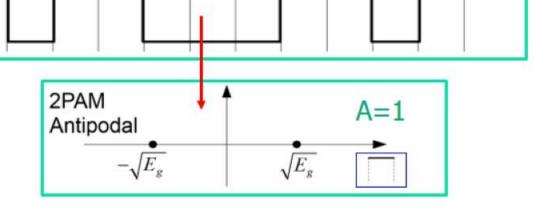
where, 
$$a_m = \mathbf{s}_m \cdot \mathbf{\psi_i} = \int_{-\infty}^{\infty} A_m g_T(t) \frac{g_T(t)}{\sqrt{E_g}} dt$$
  
=  $A_m \sqrt{E_g}$ 

#### 5.2.1. PAM: geometric representation

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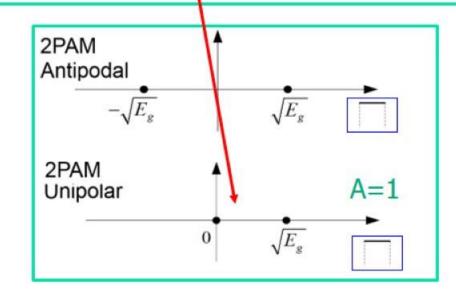
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$$=A_{m}\sqrt{E_{g}}$$



The energy of signals

$$E_m = \|\mathbf{s}_m\|^2 = \left(A_m \sqrt{E_g}\right)^2 = A_m^2 E_g$$

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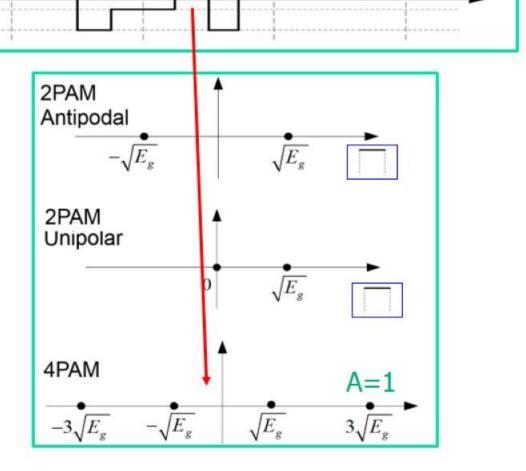
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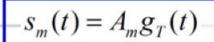
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"01"

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#### 5.2.1. PAM: geometric representation

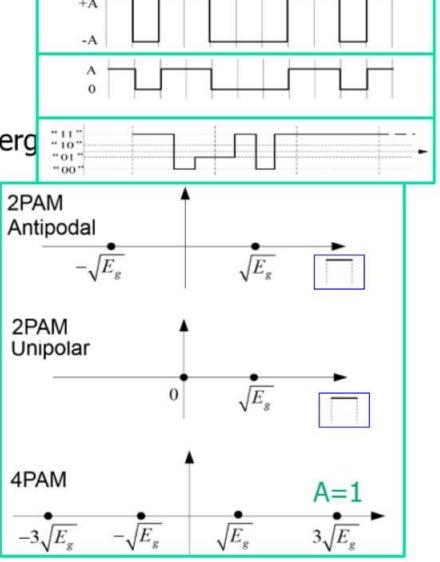
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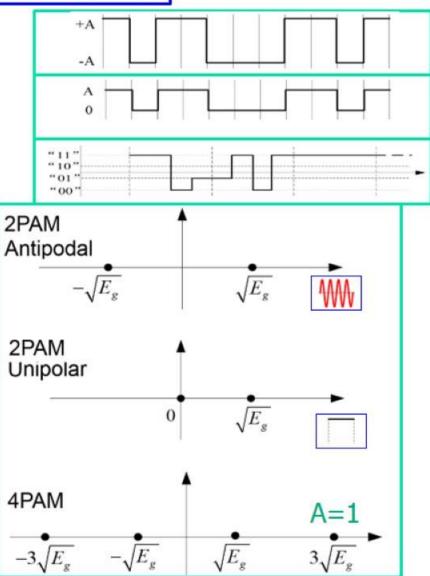
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$$-s_m(t) = A_m g_T(t)$$

**5.2.1. PAM:** passband signals

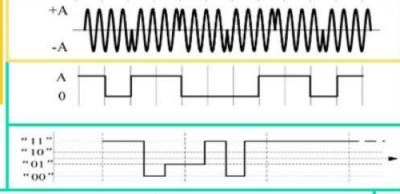
- Baseband signal: its freq band is close to zero, often used in wire-line transmission.
- Passband signal: its freq band is away from zero, a cos-like waveform, and widely used in wireless transmission.



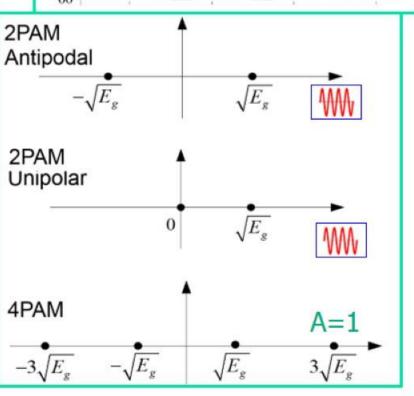
$$S_m(t) = A_m g_T(t) \cos 2\pi f_c t$$

5.2.1. PAM: passband signals

BPSK=Binary Phase-Shift-Keying



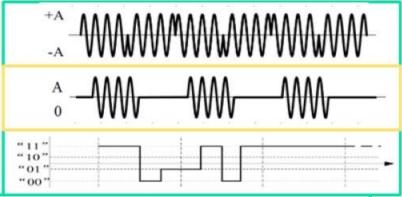
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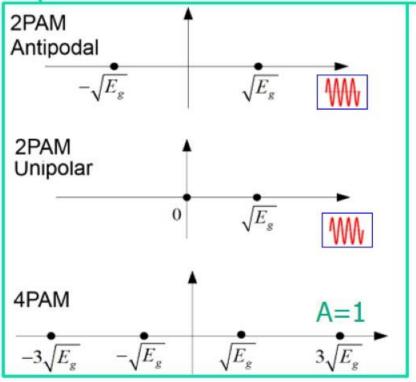
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5.2.1. PAM: passband signals

BASK=Binary Amp-Shift-Keying OOK=On-Off-Keying



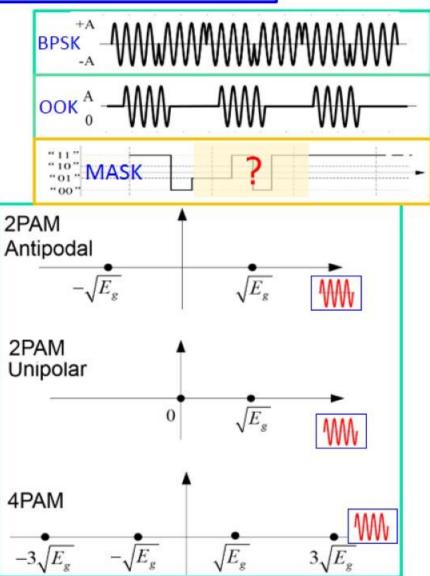
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4PAM

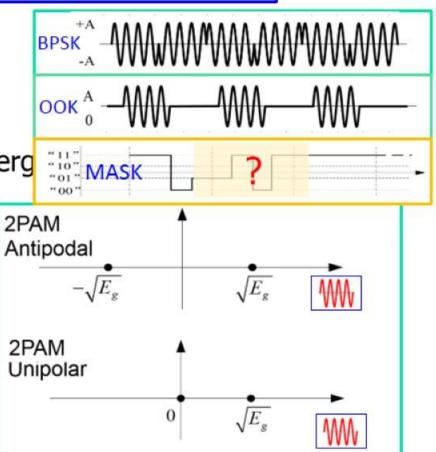
 $-3\sqrt{E_g}$ 

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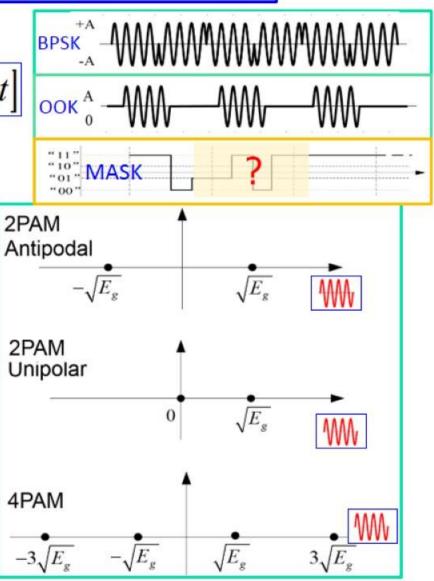
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$$\psi(t) = k_0 g_c(t) = k_0 [g_T(t) \cos 2\pi f_c t]$$
 where  $k_0 = 1/\sqrt{E_{gc}}$ 

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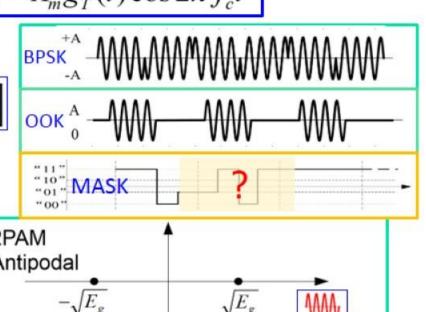
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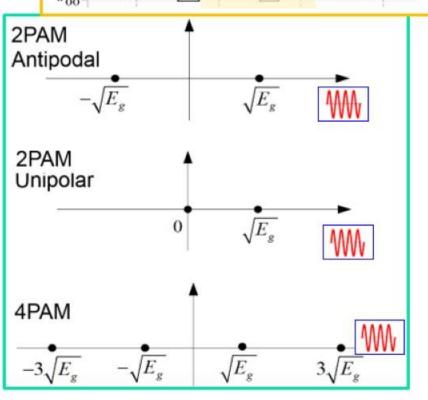
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Note that 
$$\begin{split} E_{gc} &= \int_{-\infty}^{\infty} g_T^2(t) \cos^2(2\pi f_c t) dt \\ &= \int_{-\infty}^{\infty} \frac{g_T^2(t) (1 - \cos 4\pi f_c t)}{2} dt = \frac{E_g}{2} \end{split}$$





$$S_m(t) = A_m g_T(t) \cos 2\pi f_c t$$

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The graph is called the constellation

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