



Chapter 6

Digital transmission through band-limited AWGN channels

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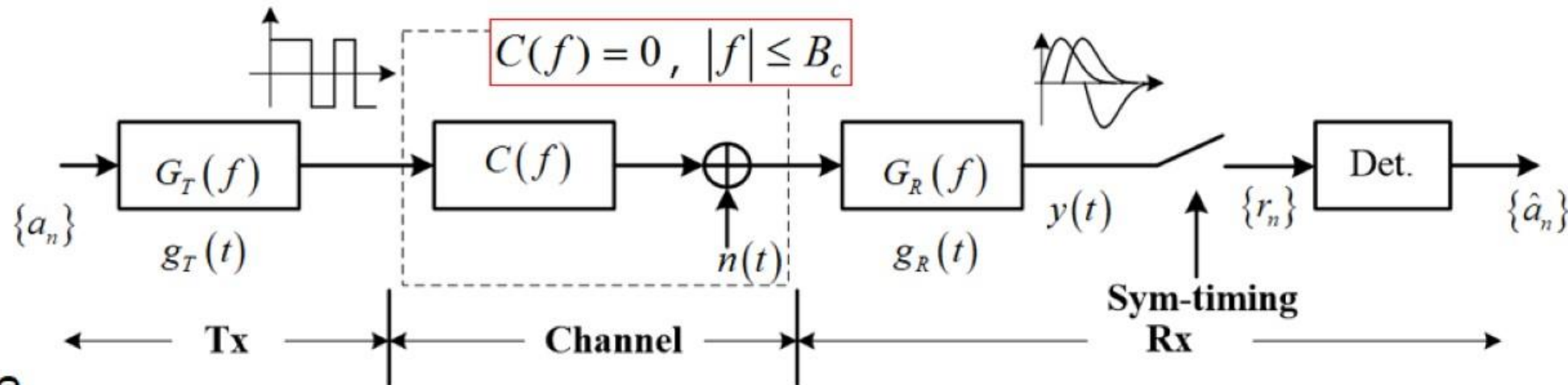
Problems

6-16, 6-14, 6-22

- ISI and zero-ISI condition
(Ref p380-381, p393-394)
- Design of BL signals for zero-ISI
(Ref p396-399)
- OFDM

6.1 ISI and zero-ISI condition

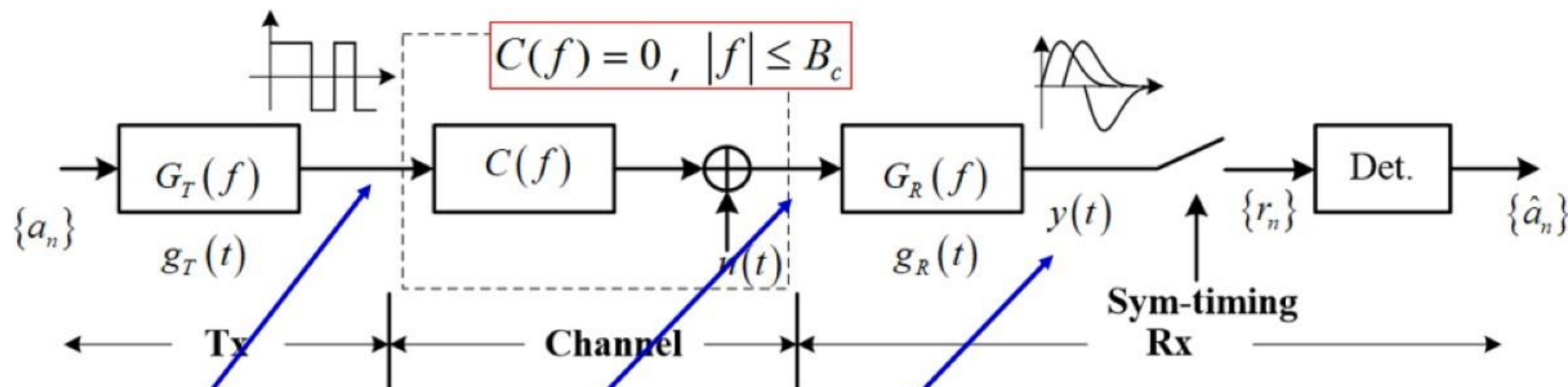
Consider the **general block diagram** as follows. Without loss of generality, we consider baseband (BB) case.



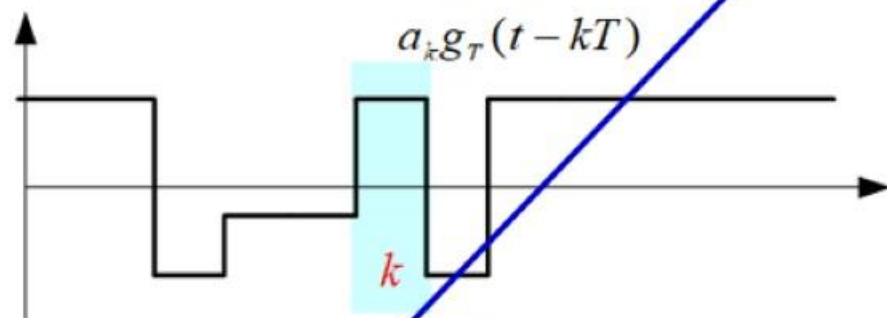
where,

- $G_T(f)$ represents the freq-characteristic of the transmission signal, which is determined by the **pulse shape**.
- $C(f)$ the freq-response of the **channel**.
- $G_R(f)$ the freq-response of the **receiving filter**. (eg. the MF)
- The corresponding **time representations** are $g_T(t)$, $c(t)$ and $g_R(t)$ respectively.

6.1 ISI and zero-ISI condition



Trans. Signal: $s(t) = \sum_{k=-\infty}^{\infty} a_k g_T(t - kT)$



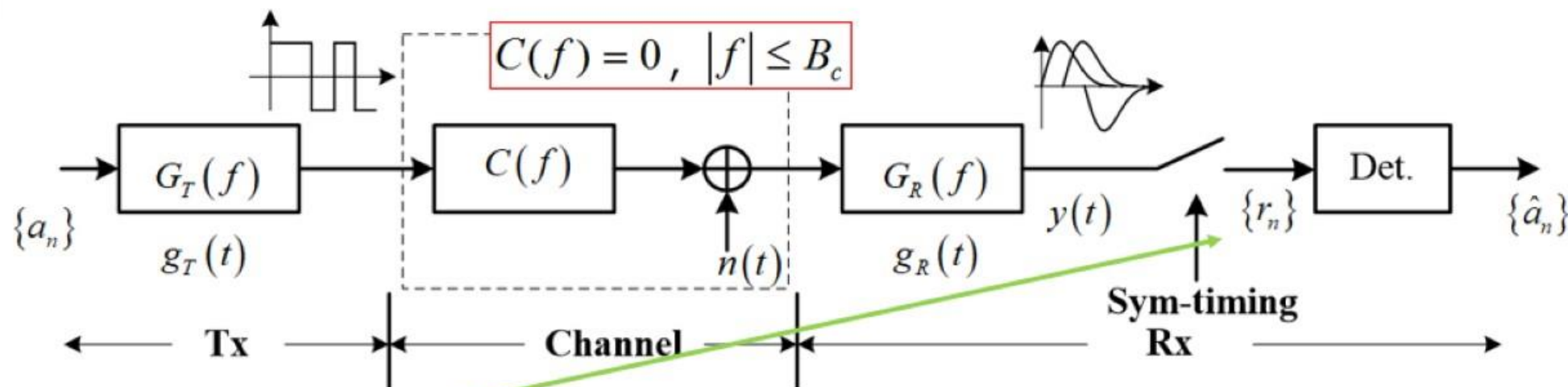
Received sig: $r(t) = \sum_{k=-\infty}^{\infty} a_k g_T(t - kT) * c(t) + n(t)$

Filtered sig:

$$\begin{aligned}
 y(t) &= r(t) * g_R(t) \\
 &= \sum_{k=-\infty}^{\infty} a_k g_T(t - kT) * c(t) * g_R(t) + n(t) * g_R(t) \\
 &= \sum_{k=-\infty}^{\infty} a_k h(t - kT) + v(t)
 \end{aligned}$$

where, $h(t) = g_T(t) * c(t) * g_R(t)$ is the overall resp.

6.1 ISI and zero-ISI condition

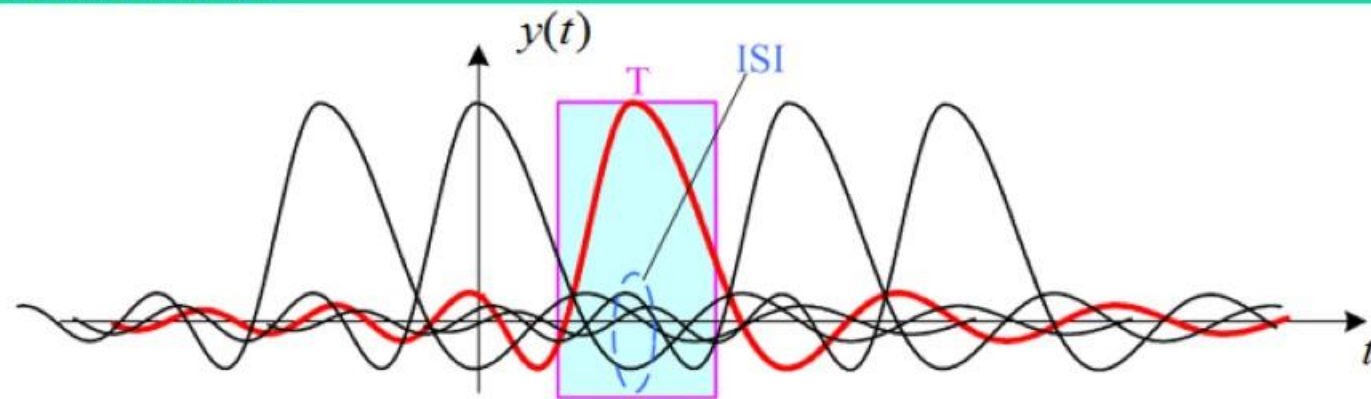
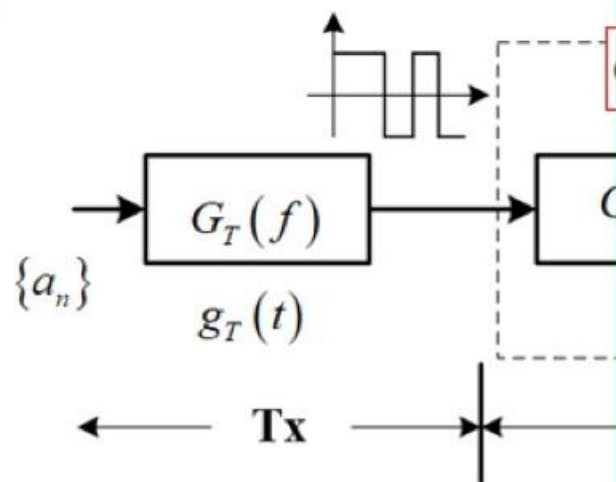


Observation:

$$\begin{aligned}
 r_n = y(nT) &= \sum_{k=-\infty}^{\infty} a_k h(nT - kT) + v(nT) \\
 &= \cdots + a_{n-2} h(2T_s) + a_{n-1} h(T_s) + \boxed{a_n h(0)} \\
 &\quad + \boxed{a_{n+1} h(-T_s) + a_{n+2} h(-2T_s)} + \cdots + \boxed{v(nT)} \\
 &= a_n h(0) + \text{ISI} + v(nT)
 \end{aligned}$$

The 1st term on RHS provides the nth symbol a_n .
 The 3rd term represents additive noise.
 The 2nd term provides no info on a_n , and is an harmful interference, called **Inter-Symbol Interference (ISI)**

6.1 ISI and zero-ISI condition



The **tails** on both sides of $h(t)$ **out of the symbol interval** cause the ISI.

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6.1 ISI and zero-ISI condition

Let $H(f)$ be the Fourier transform of $h(t)$ and $R_s = 1/T$ be the symbol rate.

Nyquist zero-ISI theorem:

$$x_n = c\delta[n] \Leftrightarrow \sum_{k=-\infty}^{+\infty} H(f - kR_s) = \text{const.}$$

Observation:

$$\begin{aligned} r_n = y(nT) &= \sum_{k=-\infty}^{\infty} a_k h(nT - kT) + v(nT) \\ &= \cdots + \underbrace{a_{n-2}h(2T_s) + a_{n-1}h(T_s)}_{0} + \underbrace{a_n h(0)}_c \\ &\quad + \underbrace{a_{n+1}h(-T_s) + a_{n+2}h(-2T_s)}_{0} + \cdots + \underbrace{v(nT)}_c \\ &= a_n h(0) + \cancel{\text{ISI}} + v(nT) \end{aligned}$$

Zero-ISI condition: the overall communication system has to be designed such that $h(t)$ satisfies the following.

$$x_n = h(nT) = c\delta[n] = \begin{cases} c & n = 0 \\ 0 & n \neq 0 \end{cases}$$

where c is an arbitrary non-zero constant.

6.1 ISI and zero-ISI condition

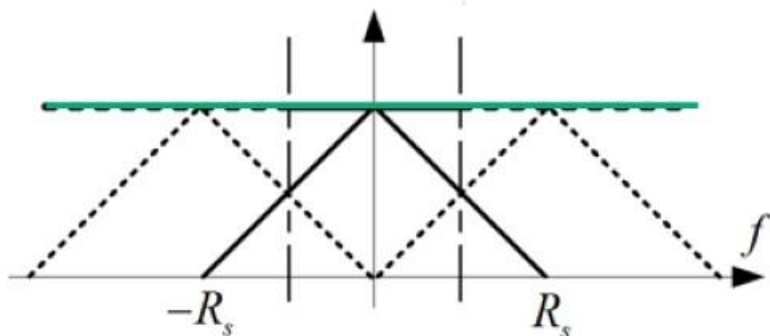
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As shown in fig, the condition requires the summation yields a flat spectrum.

For $\sum_{k=-\infty}^{+\infty} H(f - kR_s)$ is periodic with R_s , we pay attention to the interval of $(-R_s/2, +R_s/2)$.



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