

# Polygons & Transformations Cheatsheet

3.AB PreIB Math

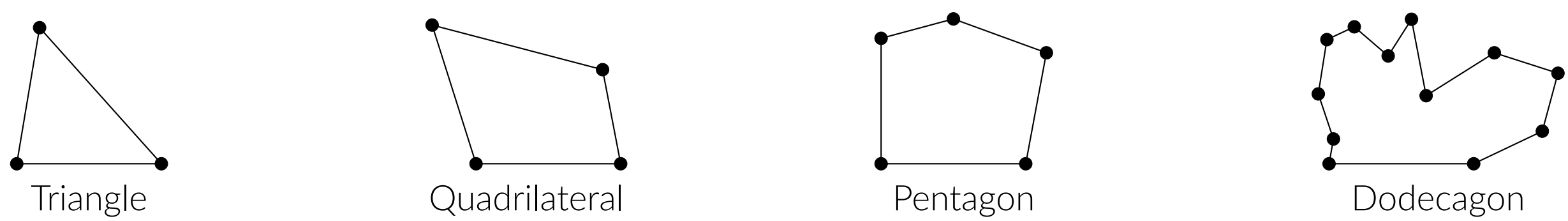
Adam Klepáč



## Polygons

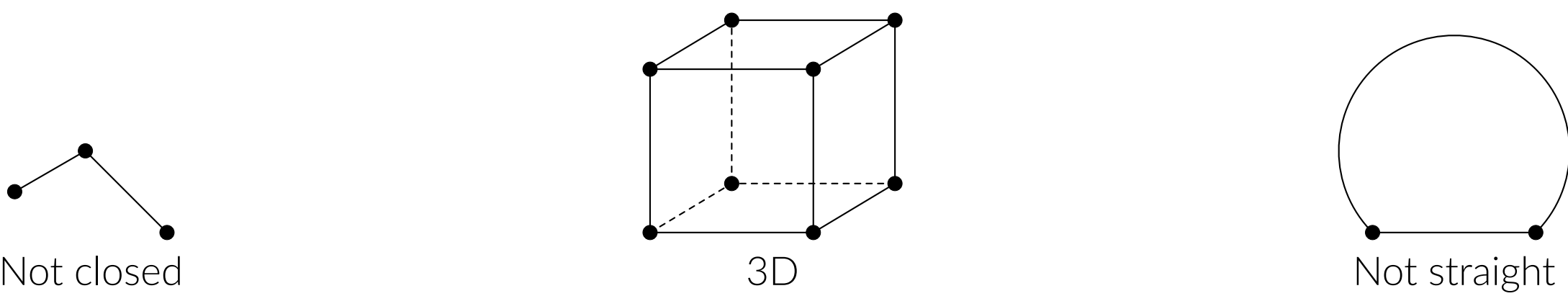
Polygon is a **closed** 2D shape **made only of segments**. We call the endpoints of those segments, **vertices**, and the segments themselves, **edges**.

Examples



Polygons with  $n$  sides are called  **$n$ -gons**.

Counterexamples

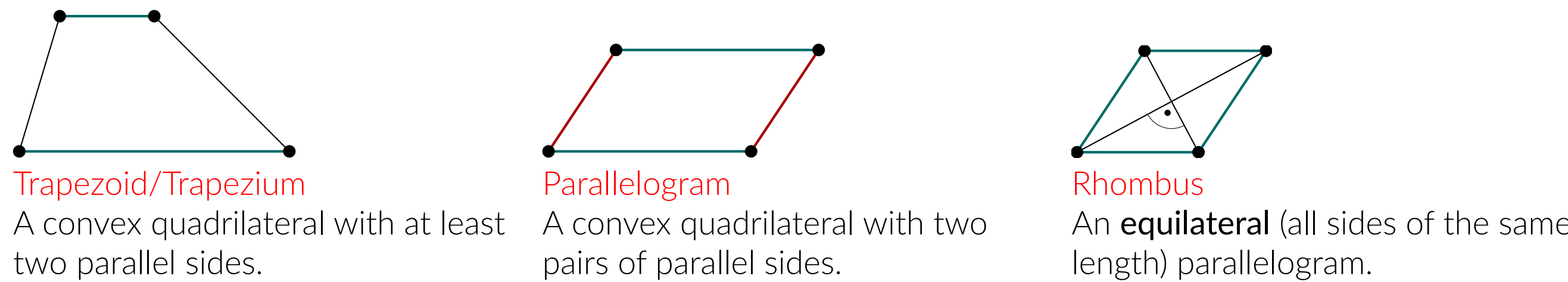


## Convex Polygons

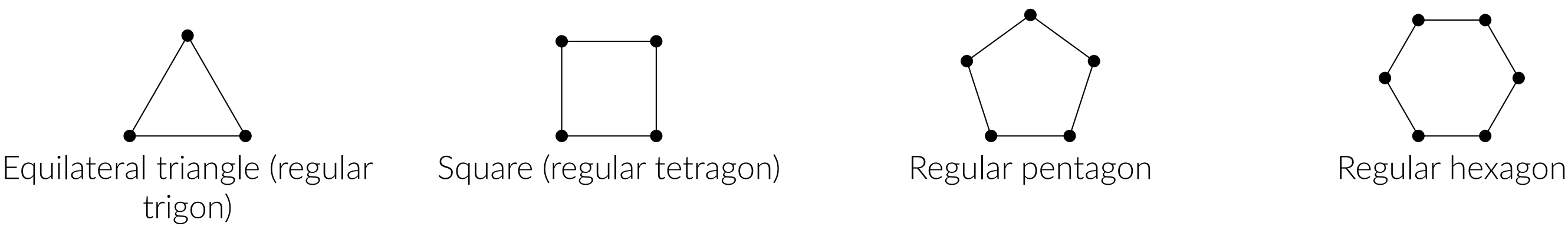
A polygon is called **convex** if it has no internal angle greater than  $180^\circ$ .



Special types of convex polygons

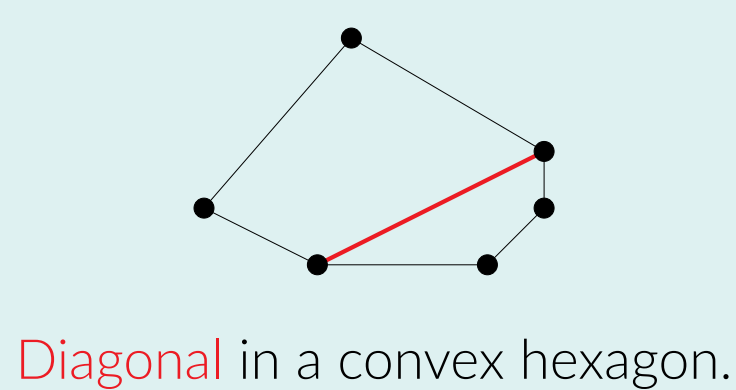


In addition, if a **convex** polygon has **all sides of the same length** and **all angles of the same size**, it is called **regular**.

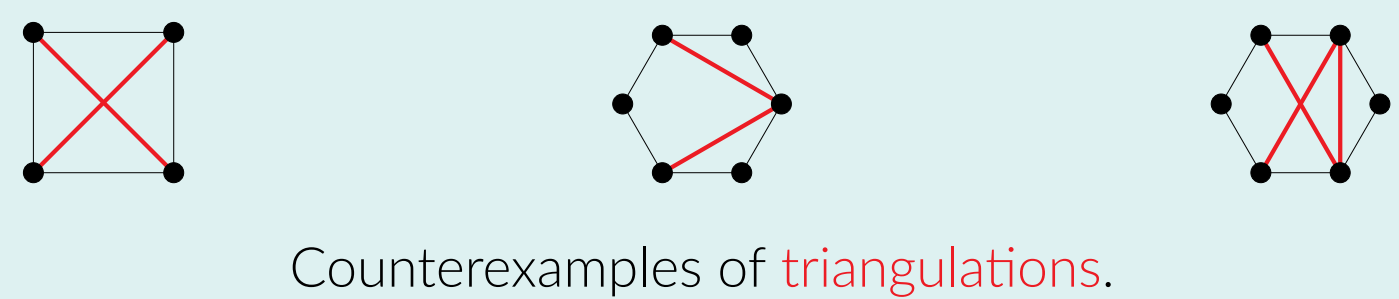
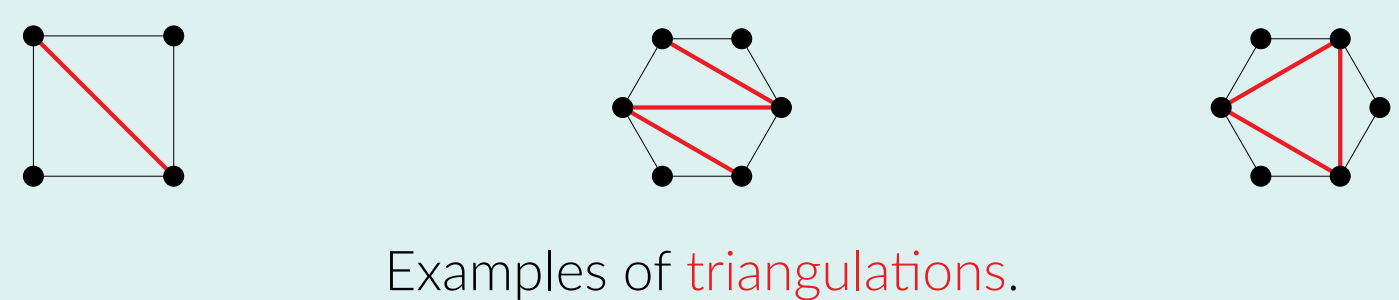


## Diagonals & Triangulations

A **diagonal** in a **convex** polygon is a segment connecting two of its **non-adjacent** vertices.



A **triangulation** of a **convex** polygon is its division into triangles by **non-intersecting** diagonals.

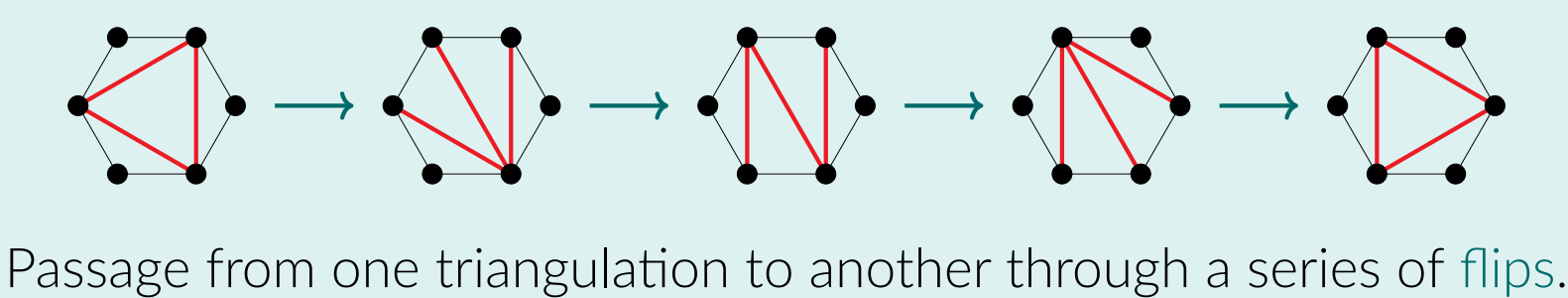
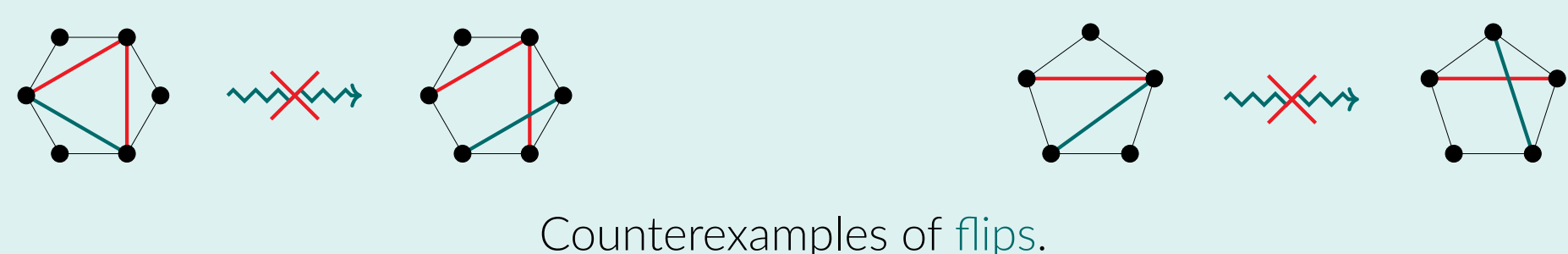


The total number of different triangulations of a convex  $n$ -gon is

$$\frac{n \cdot (n-1) \cdot \dots \cdot (n-2)}{(n-2)!}$$

which you **of course don't have to remember**. Interestingly enough, every triangulation can be transformed into any other by a series of **flips**.

A **flip** is a swap of one diagonal for the other in a chosen quadrilateral so that the **result is again a triangulation**.

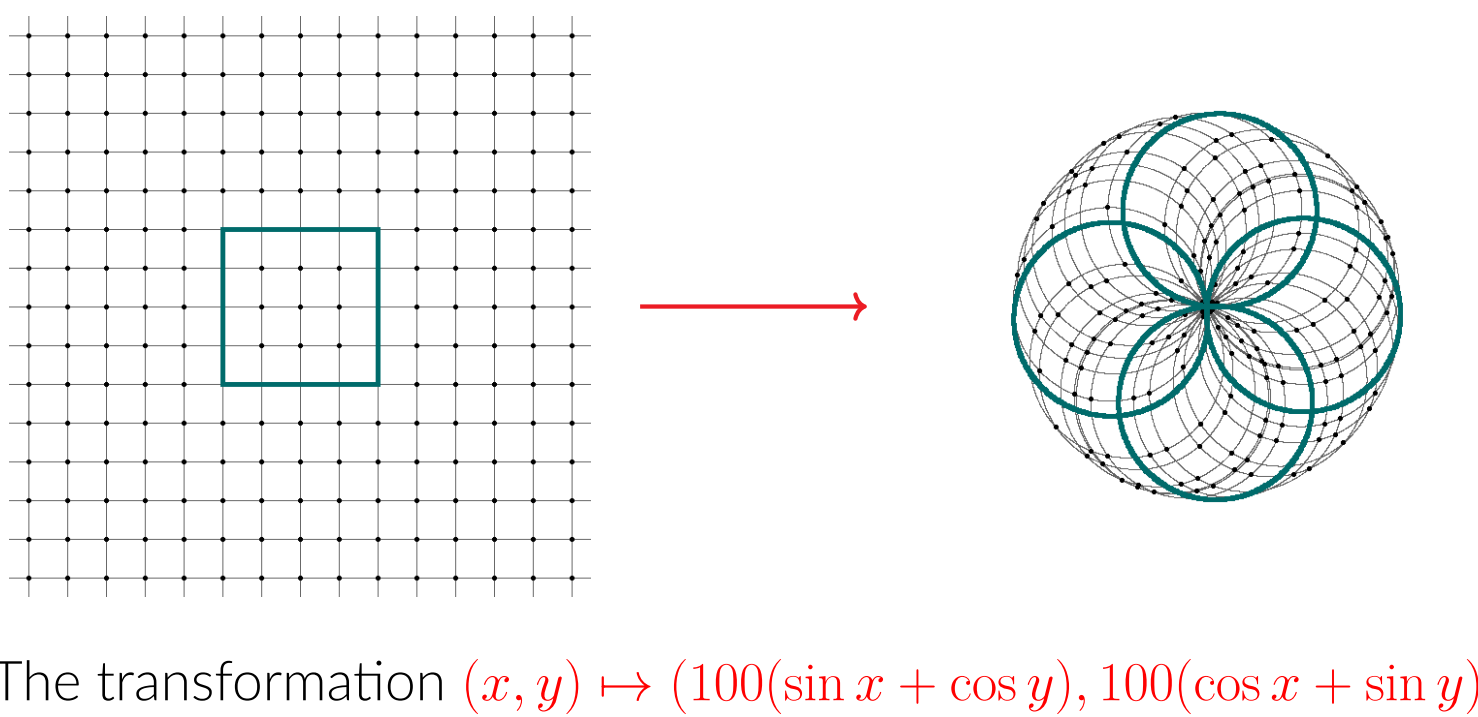
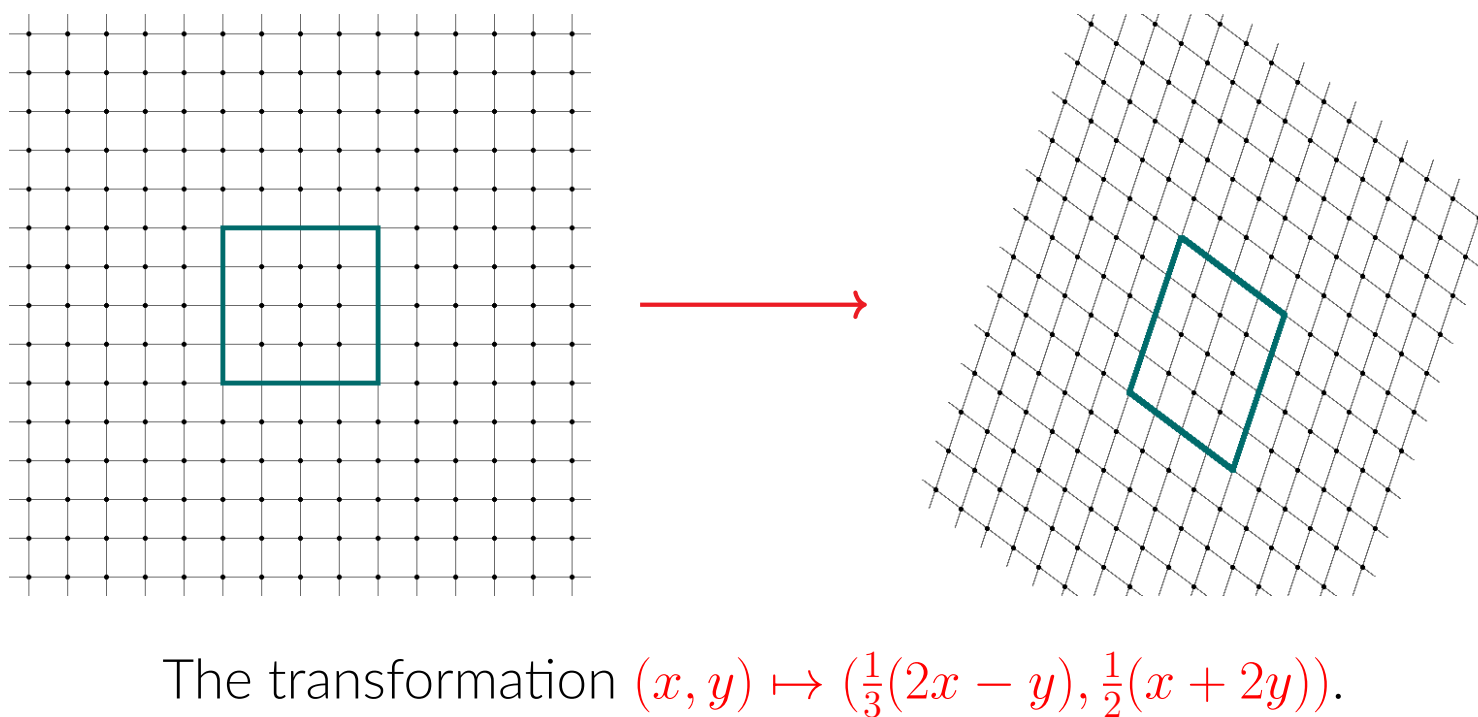


I encourage you to think about how to determine the number of flips necessary to pass from one triangulation to another. Can I have made the passage above in fewer flips?

## Plane Transformations

The **plane** is basically just the set  $\mathbb{R}^2$  of all **pairs of real numbers**. A pair  $(x, y) \in \mathbb{R}^2$  is typically called a **point**. Then, a plane **transformation** is a **function** which maps points to points. In symbols, it's a function  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ .

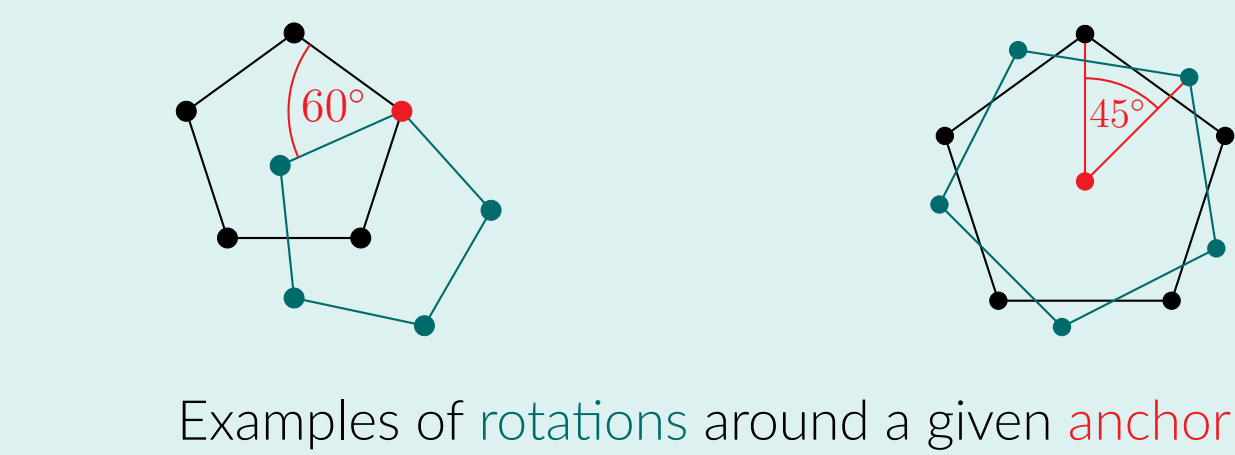
We can visualise what a transformation does for example by look at the image of a square (or an entire grid).



## Rotations & Reflections

We shall be interested in two specific plane transformations – **rotations** and **reflections**.

**Rotations** are plane transformations that, well ..., rotates the entire plane around a fixed point called **anchor**. Applied to polygons, rotations may look like this:



**Reflections** are basically 'mirrors'. They mirror each point in the plane through a given line called **axis** (of reflection).



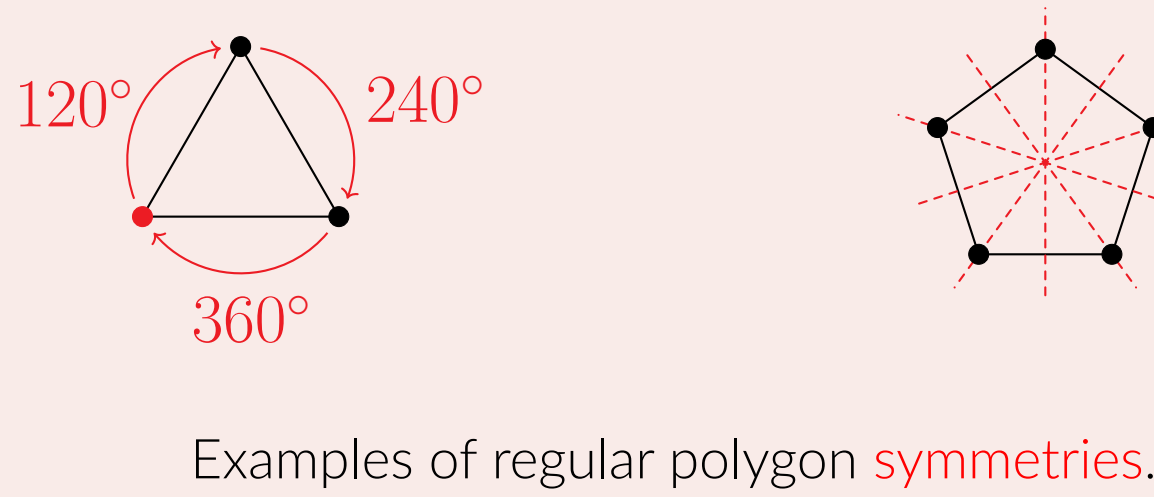
## Symmetries of Regular Polygons

Some **rotations** and **reflections** get along nicely with **regular polygons**. By this, we mean that they **keep them intact**. We call them the **symmetries** of the polygon.

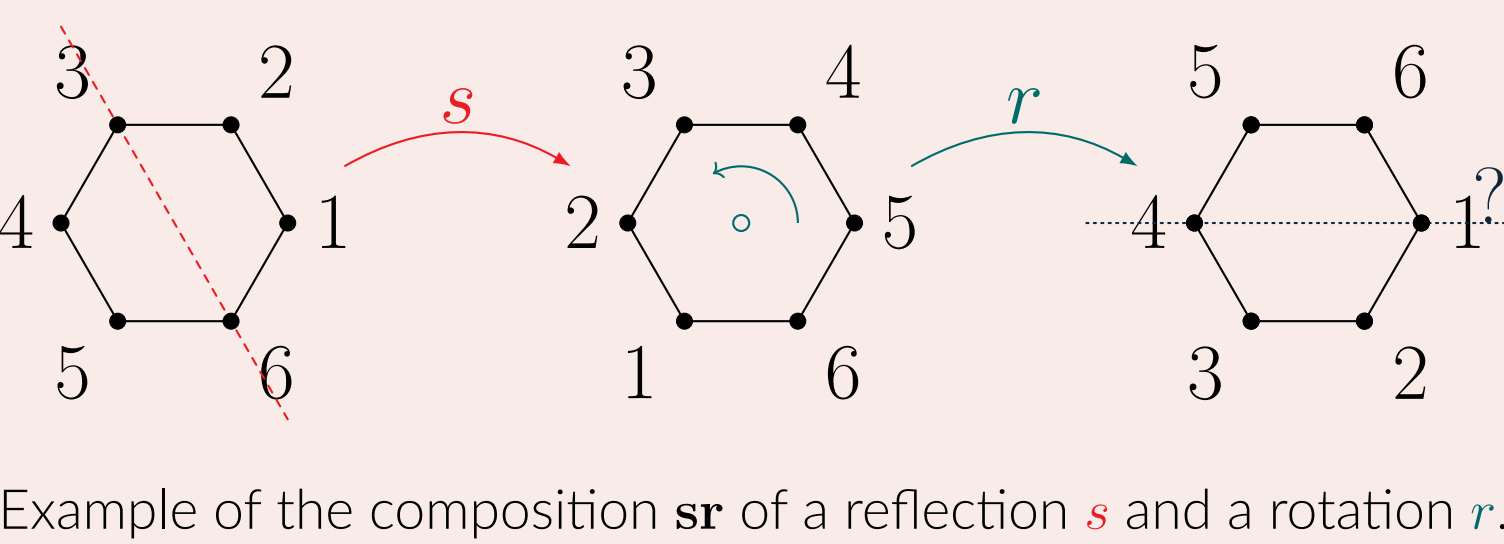
Each regular  $n$ -gon has multiple symmetries:

- (r) **rotation** by  $k \cdot 360^\circ / n$  for any  $k$  between 1 and  $n$ .
- (s) **reflection**
  - over lines passing through centres of opposite sides or through opposite vertices if  $n$  is **even**;
  - over lines passing through a centre of a side and the opposite vertex if  $n$  is **odd**.

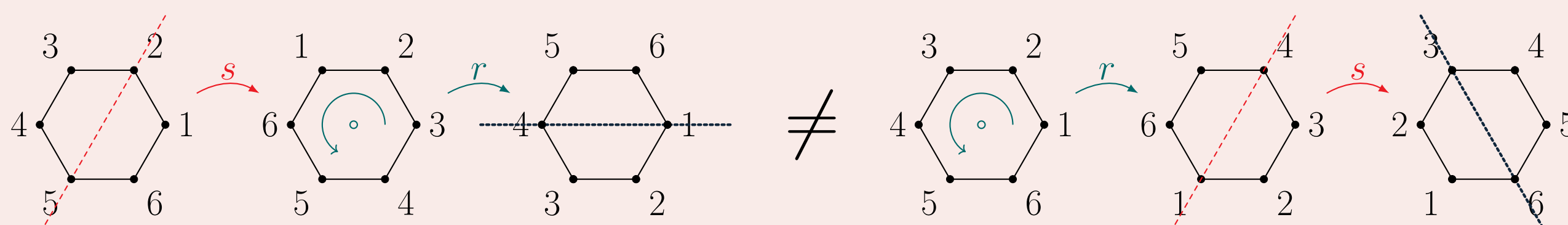
Therefore, an  $n$ -gon has  $n$  rotational and  $n$  reflectional symmetries.



Moreover, symmetries (being functions) can be **chained** or **composed**, creating new symmetries. We'll label rotations by the letter  $r$  and reflections by  $s$ . A **chain** or **composition** is read left-to-right, that is,  $sr$  means 'apply  $s$  first, then  $r$ '.



The order of composition matters!



In general, a composition of

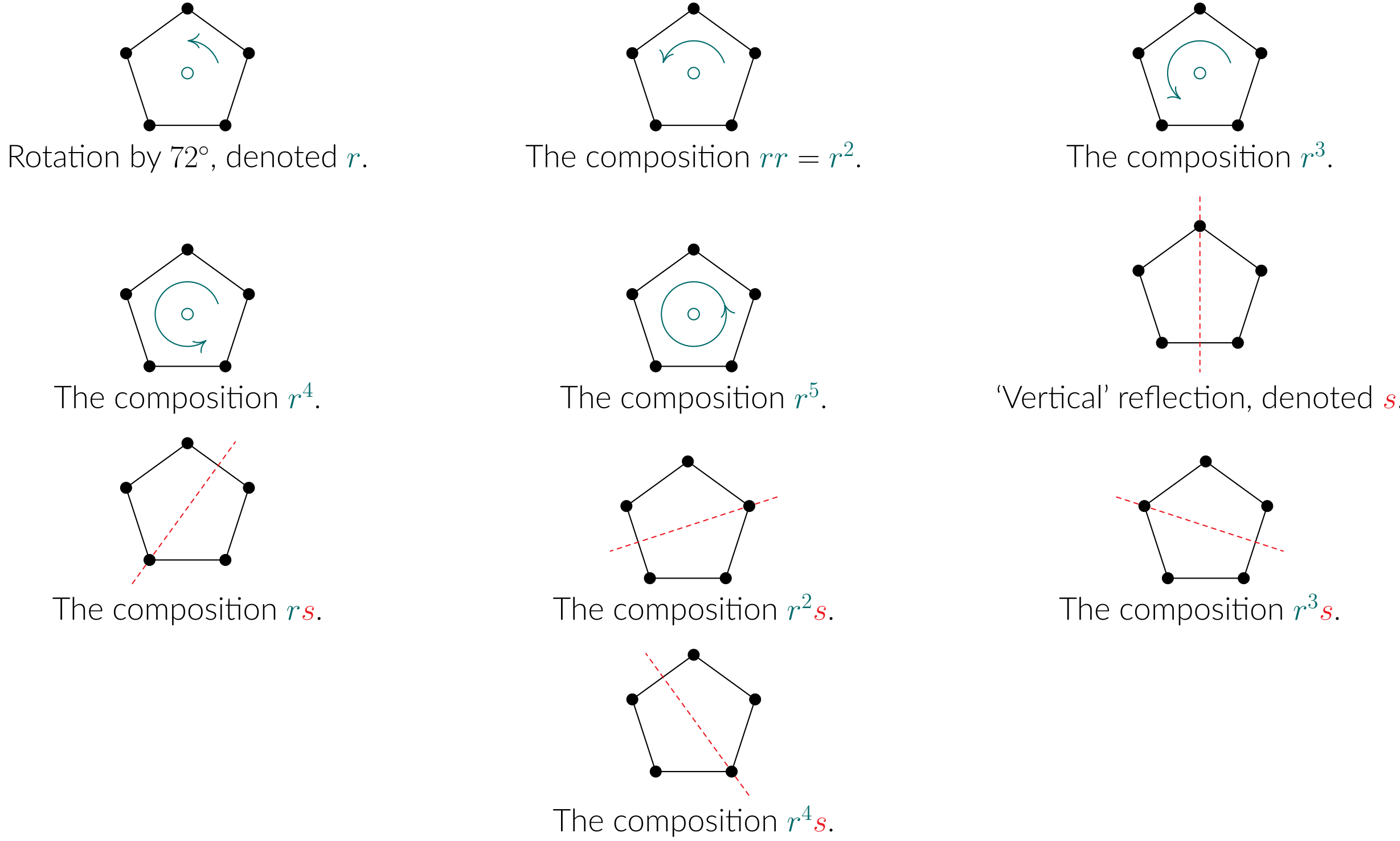
- a **rotation** and a **rotation** is again a **rotation**,
- a **rotation** and a **reflection** (in any order) is a **reflection**,
- a **reflection** and a **reflection** is a **rotation**.

## Generating Symmetries

**Question:** If I can compose symmetries, how many (and which) symmetries are enough to generate (create by composition) all the others?

**Answer:** Just two are enough. Basically, I need to be able to generate the smallest rotation (that is, rotation by  $360^\circ / n$ ) and any reflection. Composing these two gives me all the other rotations and reflections.

Let's see this on a regular pentagon. Here,  $r$  denotes the rotation by  $360^\circ / 5 = 72^\circ$  and  $s$  denotes the 'vertical' reflection.



All symmetries of the regular pentagon written as compositions of  $r$  and  $s$ .

**Question:** Given two symmetries, how do I know I can generate the rest using only these two?

**Answer:** It of course depends on their type.

- If I'm given 2 rotations, I can never generate all symmetries because composing rotations doesn't yield a reflection.
- If I'm given a rotation and a reflection, then the rotation must be by  $k \cdot 360^\circ / n$  with  $k$  **coprime to  $n$** . Otherwise I can never generate the rotation by  $360^\circ / n$ . The reflection can be of any kind.
- If I'm given two reflections, their composition must be a rotation by  $k \cdot 360^\circ / n$  with  $k$  **coprime to  $n$**  for the same reason as above.

## Vocabulary

English	Czech	Definition
Segment	Úsečka	Straight finite line connecting two points.
Polygon	Mnohoúhelník	Closed 2D shape made of segments.
Vertex	Vrchol	Any of the endpoints of the segments forming a polygon.
Edge	Hrana	Any of the segments forming a polygon.
Triangle	Trojúhelník	A polygon with 3 vertices.
Quadrilateral	Čtýřúhelník	A polygon with 4 vertices.
Internal/External angle	Vnitřní/Vnější úhel	The angle on the inside/outside of a polygon formed by its edges.
Convex	Konvexní	A polygon whose internal angles don't exceed $180^\circ$ .
Equilateral	Rovnostranný	Describes a polygon with all sides of equal length.
Trapezoid	Lichoběžník	A quadrilateral with a pair of parallel sides.
Parallelogram	Rovnoběžník	A quadrilateral with two pairs of parallel sides.
Rhombus	Kosočtverec	An equilateral parallelogram.
Regular	Pravidelný	Describes an equilateral polygon with all angles of the same size.
Square	Čtverec	A regular quadrilateral.