Low Level Design Document

for

AGORA

Version 2.0

A Versatile Environment for the Development of IntelliDrive Applications

(Visual ...Extensible ...Rule-Based)

Department of Computer Science, Western Michigan University



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Revision History

Name	Date	Reason For Changes	Version
Vinay B Gavirangaswamy	02/14/2010	Initial Draft	1.0
Vinay B Gavirangaswamy	02/16/2010	Changed project name from VII to AGORA, changed paragraph formatting, and reformatted cover page.	1.1
Vinay B Gavirangaswamy	06/23/2010	Documented TMC low level design	1.2
Jamie Lynn Groos	06/28/2010	Section 4 covering security included	1.3
Vinay B Gavirangaswamy	07/06/2010	New version release	2.0

1. Introduction

1.1 Purpose

AGORA refers to a set of application and infrastructure which constitutes intellidrive environment that is being developed at Computer Science Department, Western Michigan University. This infrastructure consists of On-Board Equipment (OBE), Road Side Equipment (RSE), and Traffic Management Centers (TMC), which work together to increase the safety and efficiency of the transportation network. Current system that is deployed across the university consists of initial versions RSE's, OBE's and VIS. And Current scope of work involves enhancement of VIS to include more features and functionality through incorporating different capability/applications. And it will also include development of TMC (Traffic Management Center). However the goal of this program is to facilitate MDOT in enforcing a safe and an efficient transportation system.

This document details different components that each system is composed of and their technical design, implementation strategies.

1.2 Document Conventions

TBD

1.3 Intended Audience and Reading Suggestions

Document is primarily intended for members of MDOT team which consists of graduate students working under the guidance of Dr. Ala Al-Fuqaha and Dr. Dionysios Kountanis.

1.4 References

- Project Proposal Document
- System Specification for AGORA
- System Architecture and High Level Design for AGORA

2. System Use Cases

Name:	SuperNode
Number:	1.0
Author:	Mrinal Khanvilkar Date: July 14, 2009
Description:	 For other super nodes: It checks whether the centroid set requested by another supernode is already blocked by itself or by another supernode. If it is not blocked, it means the centroid set can be allocated. For regional managers: It checks with itself and other super nodes whether the centroid set is blocked. If it is not blocked then return the centroid set to the regional manager after blocking it. For vehicles: It returns the regional manager associated with the closest centroid to the vehicles location.
Actors:	SuperNode, Regional Manager, Car
Pre-conditions:	None
Course of Events:	1. Load up neighboring supernodes from a file (which are static). Upon receiving a request from another supernode. a) Parse the requested centroid set and course of action from the request. i) If action == "lock" then check whether the centroid set is free 1) If it is free return a positive answer. 2) if it is locked already then return a negative answer. ii) If action == "unlock" then unlock the centroid set which was previously locked. iii) if action == "delete" then delete the associated regional manager (from the request) from the regional manager database. iv) if action == "update" then update the associated regional manager's time (from the request) in the regional manager database. Upon receiving a request from a regional manager. a) Check if regional manger already has a centroid. If yes then update its time in the regional manager table and send "update" to other supernodes with the regional manager's information (IP and portNO), else continue with b). b) Check if any free centroids. v) Pick a free centroid. vi) Contact other supernodes about this centroid set and ask them to lock it if it is free. vii) If the response from any of the supernodes is positive then grant the centroid set to the requesting regional manager. viii) If response from any of the supernodes if negative, contact the rest to unlock the centroid set and start with a). c) If no free centroids left, ignore the requesting regional manager.
	c) If no free centroids left, ignore the requesting regional manager.Upon receiving a request from a vehicle.

	 a) Parse the vehicles location from the request. b) Get the closest centroid set to the vehicles location. c) Lookup the centroid set and the corresponding regional manager and return to the vehicle. 		
	arbage Collection: a) Remove the regional managers from the regional manager database whose update hasn't occurred from a given time interval, and forward the request to delete the same to the other supernodes.		
Post- conditions:	•		
Alternatives/ Exceptions:			
Notes:			

Name:	Regional Manager		
Number:	1.0		
Author:	Mrinal Khanvilkar Date: July 14, 2009		
 For super nodes: It keeps on requesting a centroid set from randomly selected supernode. The requesting takes place even has a centroid set associated with it. This enables the update of regional managers. For vehicles: It returns the other vehicles currently registered this regional manager. This information includes (VIN, IP, por latitude, longitude, passkey (for encryption)). 			
Actors:	SuperNode, Regional Manager, Car		
Pre-conditions:	None		
Course of Events:	ourse of 1. Load up supernodes from a file (which are static).		
	Garbage Collection: b) Remove the vehicles from the vehicles database whose update hasn't occurred from a given time interval.		
Post- conditions:			
Alternatives/ Exceptions:			
Notes:			

Name:	VIS		
Number:	1.0		
Author:	Mrinal Khanvilkar, Jamie Groos Date: May 14, 2009		
Description:	 For super nodes: It keeps on requesting a regional manager from a randomly selected supernode. The requesting takes place even if it has an associated regional manager. This enables the vehicle to get regional managers according to its current location. For vehicles: It keeps on forwarding its own information to the vehicles returned by the associated regional manager. Rules are setup beforehand, and the fire according to the context of the this vehicle (i.e. the vehicle itself and the other vehicles in its neighborhood database). 		
Actors:	SuperNode, Regional Manager, Car		
Pre-conditions:	None		
Course of Events:	None		
conditions:			
Alternatives/ Exceptions:			
Notes:			

Name:	TMC		
Number:	1.0		
Author:	Vinay B Gavirangaswamy Date: Feb 14, 2010		
Description:	TMC's are designed to serve number of purposes while integrating with other architecture building block and system building blocks. One of the functionality that TMC does is CRUD operation on hazard data. This is exposed as web services.		
Actors:	TMC, VIS, A3		
Pre-conditions:	Client web service request to getAllHazard()		
Course of	 Receive client request to list all hazards around given centroid 		
Events:	 TMCServiceSEI handles the request and fetches all hazards that are within 2 mile radius of given location. Fetch all hazards within 2 mile radius of given location and populate the response. 		
Post-	None		
conditions:			
Alternatives/	Exception is thrown if no hazard is available around given location		
Exceptions:			
Notes:			

	THO		
Name:	TMC		
Number:	1.0		
Author:	Vinay B Gavirangaswamy Date: Feb 14, 2010		
Description:	TMC's are designed to serve number of purposes while integrating with other architecture building block and system building blocks. One of the functionality that TMC does is CRUD operation on hazard data. This is exposed as web services.		
Actors:	TMC, VIS, Gov 2.0		
Pre-conditions:	ditions: Client web service request to postHazard()		
Course of	 Receive client request to store hazard around at centroid 		
Events:	 TMCServiceSEI handles the request and store hazard with its corresponding hazard code. Return success if hazard was stored successfully or false otherwise. 		
Post-	None		
conditions:			
Alternatives/ Exception is thrown in case of error.			
Exceptions:			
Notes:			

3. Detailed System Design

3.1 Super Nodes

3.1.1 Design Description

This service keeps an inventory of the set of centroids which are used in the system. The centroids are locations with co-ordinates. There might be more than one centroid in a set. A centroid set is typically allocated to a region. The set with more than two centroids can be locked for regions with high traffic density. These centroid sets have to allocate to the regional managers for them to be active. The supernodes all maintain the same inventory of centroid sets (global view). i.e. at any given point of time they have the same inventory throughout. The global view of the used centroids is maintained as follows:

- 1. The regional manager pings any supernode which is randomly selected.
- 2. Now the supernode checks whether the regional manager already has the centroid set allocated to it. If not, the supernode contacts the other supernodes with the regional manager ID and the any unused centroid ID. The exact message is given as:
 - "{CentroidSetID}&{RegionalManagerHostName}&{RegionalManagerPortNo}&{RegionalManagerIPAddress}&{SuperNodeHostName}"
 - If the regional manager already has the centroid set allocated to it, the given supernode updates its used centroid set list to reflect the time of update. This is crucial since if there is no update from the regional manager, then its means that the regional manager has failed. The supernode uses the same message to communicate with its peers so that they too can update their used centroid lists with the time update from the regional manager thereby updating the entire global view.
- 3. Upon receiving the request from the original supernode, it's peer checks if that particular centroid set ({CentroidSetID}) is still in its unused list. If it is, it is marked as taken by the given regional manager({RegionalManagerIPAddress}). If it is used, then it checks if it was used by the same regional manager, upon which it simply updates the update time of the regional manager thereby updating the global view. But if the used centroid is taken by some different regional manager then it contacts the originating regional manager with the current Regional managers information and basically says,"hey, this centroid is already taken". The exact return message is given by "yes" (which means centroid taken).

The originating supernode upon receiving this return message, contacts the rest of its peers with the following message:

"{CentroidSetID}&{RegionalManagerHostName}&{SuperNodeHostName}"

If you notice the message in point 2, has more than 3 fields and that is the distinguishing factor. The peers upon receiving this message know that they have to remove the regional manager allotment from their used centroid list (if they have previously allotted to it).

4. To sum it up, when the supernode receives a ping from the regional manager, if there is an unused centroid with it, it allocates the centroid set to the regional manager and then contacts its peers to allocate the same to the same regional manager, unless one peer replies with "centroid taken {yes}" in which case the originating supernode has to roll back the allotment from itself and the rest of the peers used centroid list. Also when it receives a ping from a regional manager and a centroid set is already allocated to it, it updates its own

used centroid list with the "update time" and make sure that its peers too update the time in their used centroid list.

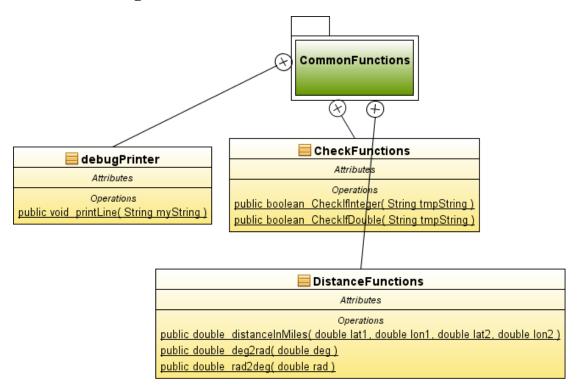
5. Consider a scenario if the regional manager doesn't ping a supernode for a long time. There is a garbage collection running on every supernode. Since a global view is maintained on all the suppernodes, it will remove the regional manager from its used centroid list and pass the same message i.e.:

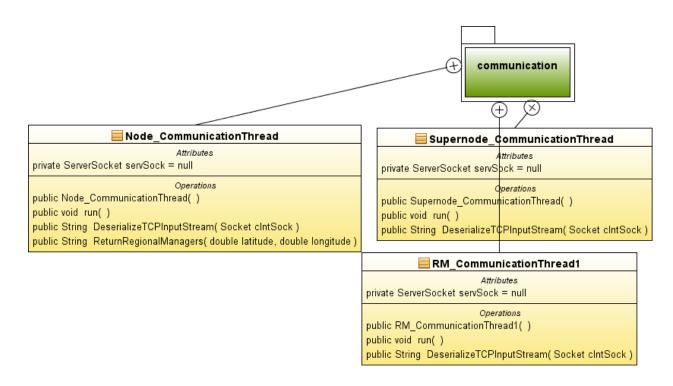
"{CentroidSetID}&{RegionalManagerHostName}&{SuperNodeHostName}"

to its peers in order to remove the particular supernode. So now the global view has been ridded of the regional manager who has not pinged for a long time (it may be because the regional manager has failed). In this case the used centroid allocated to that particular regional manager is returned back to the unused state and now it is free to be allocated to the next regional manager which doesn't yet have a centroid allocated to it. All this together maintain the same global list of used centroid list across all supernodes.

3.1.2 Design and Implementation Constraints

3.1.3 Class Diagram







🗏 debugger1

Attributes

private JLabel jLabel1

private JLabel jLabel2

private JLabel jLabel3

private JLabel jLabel4

private ozaber jzaber4

private JScrollPane jScrollPane1

private JScrollPane jScrollPane2

private JScrollPane jScrollPane3

private JScrollPane jScrollPane4

private JTextArea txtCentroids

private JTextArea txtNeighbors

private JTextArea txtRegisteredRM

private JTextArea txtUnusedCentroids

Operations

public debugger1()

private void initComponents()

private void formWindowClosing(WindowEvent evt)

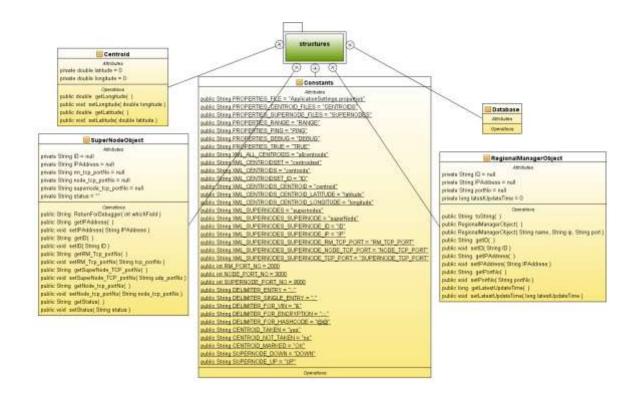
public void UpdateNeighborTable()

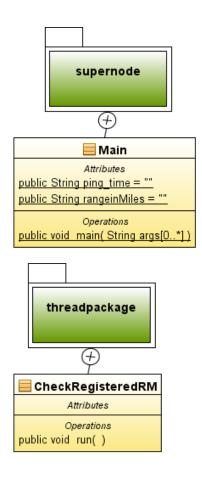
public void UpdateAllCentroids()

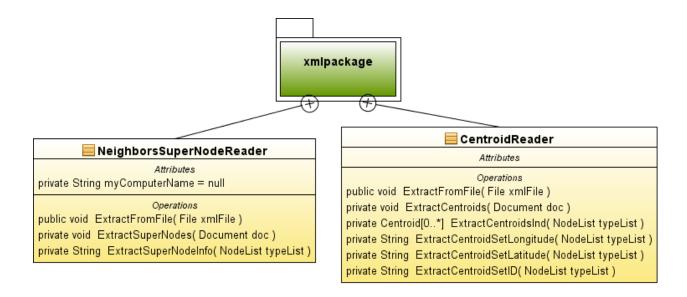
public void UpdateUnusedCentroids()

public void UpdateRegisteredRMs()

public void main(String args[0..*])







Component Name	Description

3.1.4 Sequence Diagram

TBD

3.1.5 Activity Diagram

TBD

3.1.6 External Interface Requirements

TBD

3.1.6.1 User Interfaces

TBD

3.1.6.2 Hardware Interfaces

TBD

3.1.6.3 Software Interfaces

TBD

3.1.6.4 Communications Interfaces

TBD

3.2 Regional Manager

3.2.1 Design Description

The Regional managers maintain the database of the vehicles, roadside, point of interest for a particular set of centroids. When the regional manager boots up, it requests a centroid set from a random supernode. As discussed before, since all the supernodes maintain the same inventory (global view), the random selection of the supernode doesn't create discrepancies. If all the centroids sets are taken, then the regional manager keeps on requesting a centroid set.

The message from the regional manager to the supernode is given as follows:

"{RegionalManagerHostName}&{RegionalManagerPortNo}"

If the reply from the supernode is "yes",it means that all the centroids are already taken. But if the message from the supernode is "{CentroidID}", which means that centroid set with that particular ID is now allocated to it. It is now that the regional manager will be accepting registration requests from cars in the centroid set region.

The regional manager gets registration requests from cars as follows:

 $\label{linear_continuous_equation} $$ (CAR_PortNO_Receive) & (CAR_Encryption_Password) & (CAR_Latitude) & (CAR_Longitude) & (CAR_Longitu$

Upon receiving this request, the regional manager has two options to deal with.

- The car is already registered with it. In this case, it just updates the "time update" of the car. This is necessary since if that car hasn't pinged the regional manager for a long time, it implies that it has moved into a different region. It has to be removed so that the other cars don't get outdated information.
- 2. The car is not registered with it. In this case we registered the car in the regional manager's database. The database of the regional manager consists of only the core data of the elements like IP, latitude, longitude and password for encryption.

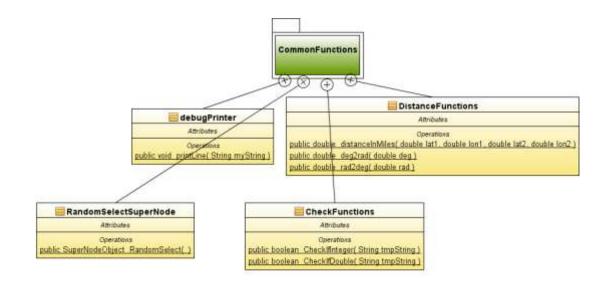
In both the cases, the return message from the regional manager to the car is given by:

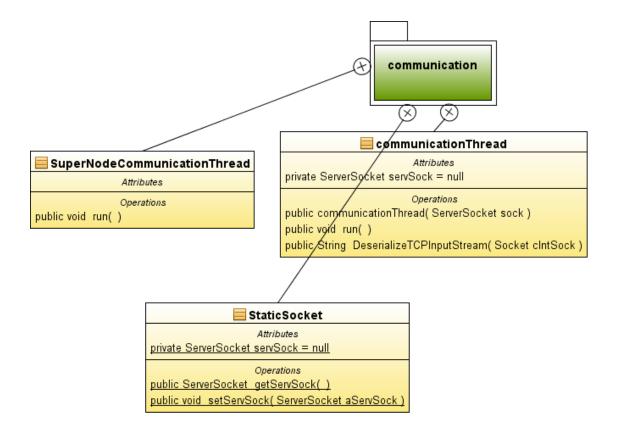
"{VIN_1}&{CAR_PortNO_IPAddress_1}&{CAR_PortNO_Receive_1}&{CAR_Encryption_Password _1}::{VIN_2}&{CAR_PortNO_IPAddress_2}&{CAR_PortNO_Receive_2}&{CAR_Encryption_Password 2}:...."

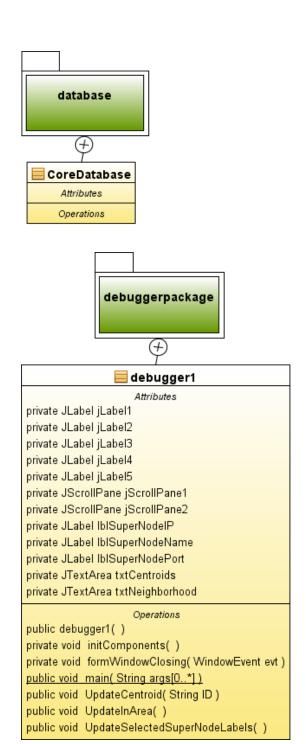
The return message contains the contact information about all the other cars in the regional manager's domain. In the above message example we have shown two vehicles, but in reality it can be more than that. Now the car has all the contact details of the other vehicles to which it contact and transfer information. Let's discuss that further in the next section.

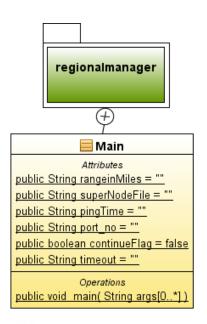
3.2.2 Design and Implementation Constraints

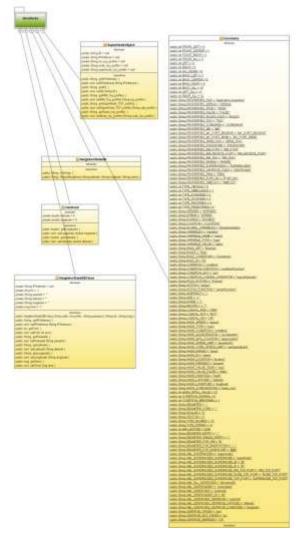
3.2.3 Class Diagram

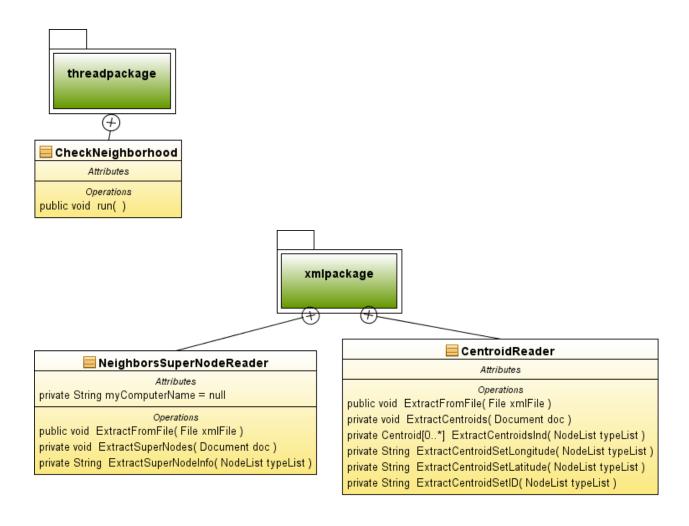






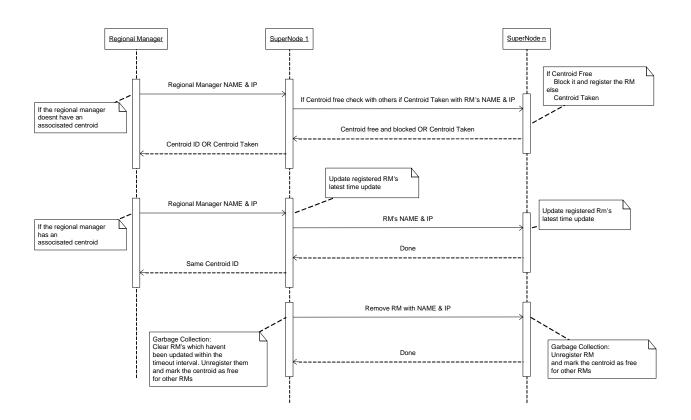






Component Name	Description

3.2.4 Sequence Diagram



3.2.5 Activity Diagram

TBD

3.2.6 External Interface Requirements

3.2.6.1 User Interfaces

TBD

3.2.6.2 Hardware Interfaces

TRE

3.2.6.3 Software Interfaces

TBD

3.2.6.4 Communications Interfaces

TBD

3.3 VIS

The cars application, while booting up, contacts a random supernode (to facilitate load balancing) with its current latitude and longitude. Since all the supernodes have the same global view of all the used centroid set list, there would be no discrepancies. The exact message is given by:

```
"{VIN}&{CAR Latitude}&{CAR Longitude}"
```

The supernode upon receiving this message looks up the centroid set and corresponding regional manager which is closest to this location and returns the regional managers contact details. The exact message is given by:

```
"{RegionalManagerHostName_1}&{RegionalManagerIPAddress_1}&{RegionalManagerPortNo_1}:: 
{RegionalManagerHostName_2}&{RegionalManagerIPAddress_2}&{RegionalManagerPortNo_2}:: ..."
```

The car application on receiving this information contacts the regional manager and registers itself in the manager's database (as discussed in the previous section of regional managers. While registering the car gets the information about the other vehicles in the manager's database and saves it for future reference. Now the car, having this information, contacts the other vehicles and transmits its information using encryption over UDP. The exact message is given by:

```
"{VIN}&{CAR_Encryption_Password}&{CAR_PortNO_Receive}&{Hash_field_1};{scalar/vector(s/v)}; {string/double(s/d)};{value}::{Hash_field_2};{scalar/vector(s/v)};{string/double(s/d)};{value}::..."
```

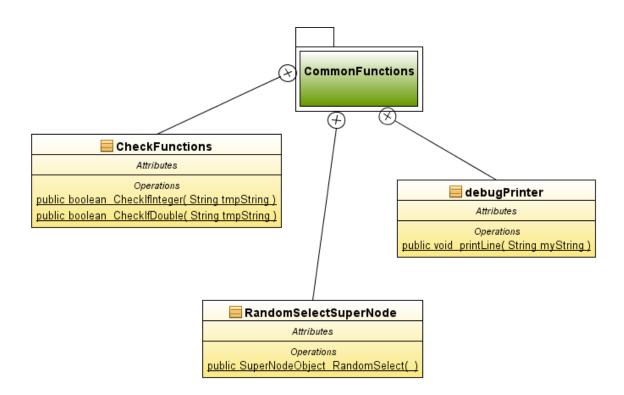
As we can see the first 3 fields are static in nature, whereas the rest of the fields depend upon the car context. The cars context is a hashtable with key/value pairs with keys being the fields and values being the objects/values (they can be scalar or vector of string and double).

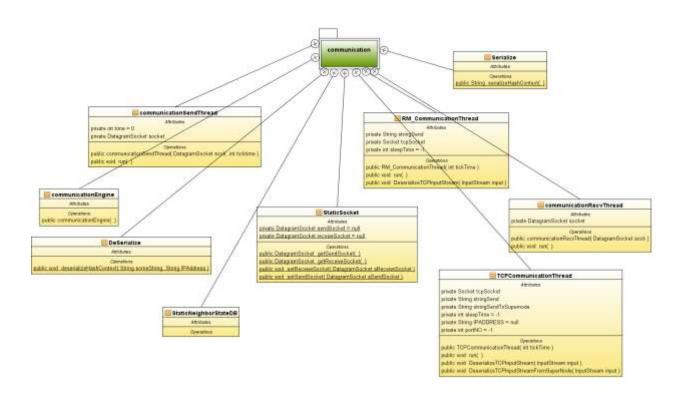
Since this communication is done through UDP, we don't wait for an acknowledgement from the other vehicles. The other vehicles upon receiving this message populate their own context with the details, thus enabling inter-vehicular communication.

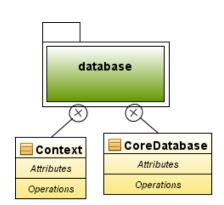
3.3.1 Design Description

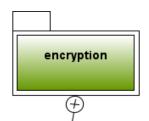
3.3.2 Design and Implementation Constraints

3.3.3 Class Diagram









pbeEncryption

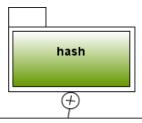
Attributes

private byte salt[0..*] = {(byte)0xA9, (byte)0x9B, (byte)0xC8, (byte)0x32, (byte)0x56, (byte)0x35, (byte)0xE3, (byte)0x03} private int iteration = 19

Operations

public byte[0..*] encrypt(String password, String input)

public byte[0..*] decrypt(byte input[0..*])



🗏 hashUtil

Attributes

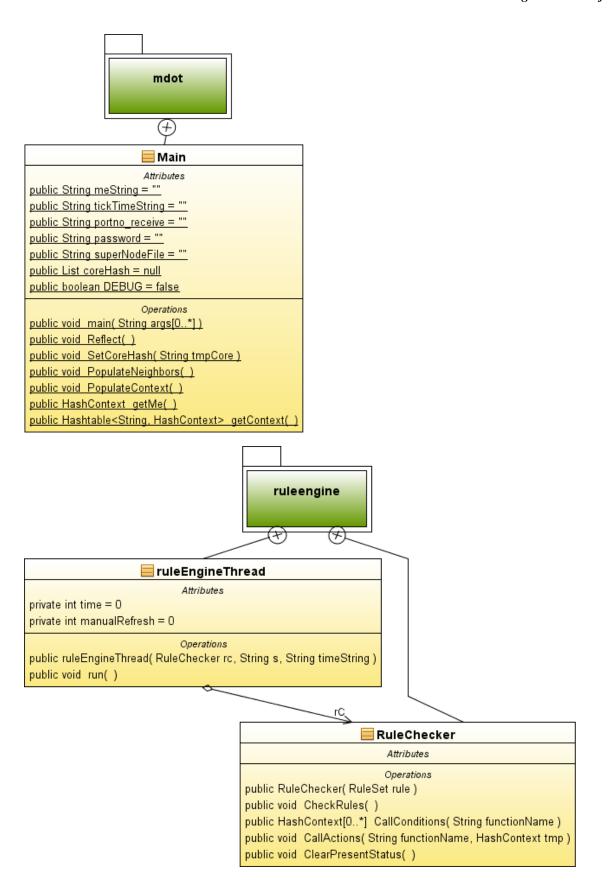
private int seed = 13

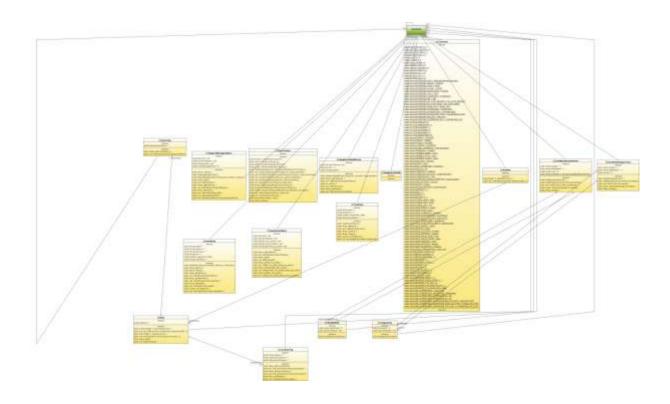
Operations

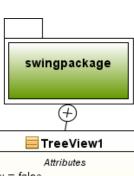
public double_getHash(double result, String hashValue)

public double_getHash(String hashValue)

public boolean_checkHashChanged(_)



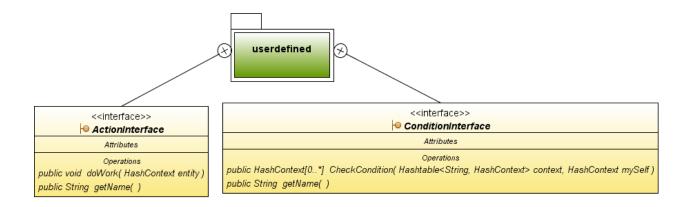


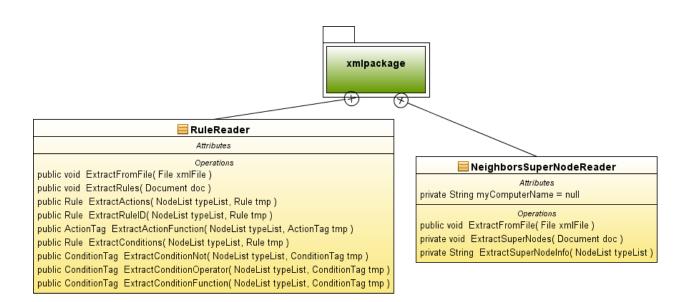


```
public boolean busy = false
private String scalarVectorSelected = ""
private String valueTypeSelected = ""
private String SCALAR_STRING = "Scalar"
private String VECTOR STRING = "Vector"
private String STRING_STRING = "String"
private String DOUBLE_STRING = "Double"
private JButton btnAdd
private JButton btnRemove
private JComboBox cboScalarVector
private JComboBox cboValueType
private JLabel jLabel1
private JLabel jLabel2
private JLabel jLabel3
private JLabel jLabel4
private JLabel jLabel5
private JLabel jLabel6
private JLabel jLabel7
private JScrollPane jScrollPane1
private JTextArea txtAreaContext
private JTextField txtKey
private JTextField txtRemoveKey
private JTextField txtValue
```

Operations

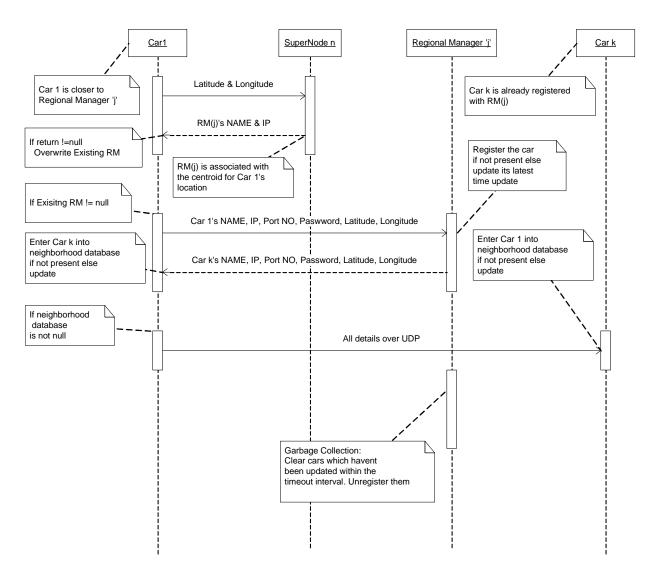
```
public TreeView1()
private void initComponents()
private void btnAddActionPerformed(ActionEvent evt)
private void btnRemoveActionPerformed(ActionEvent evt)
private void cboValueTypeActionPerformed(ActionEvent evt)
private void cboScalarVectorActionPerformed(ActionEvent evt)
private void formWindowClosing(WindowEvent evt)
public void main(String args[0..*])
private void InitializeComboBoxes()
public void UpdateTree()
private void createNodes()
```





Component Name	Description

3.3.4 Sequence Diagram



3.3.5 Activity Diagram

TBD

3.3.6 External Interface Requirements

3.3.6.1 User Interfaces

TBD

3.3.6.2 Hardware Interfaces

TRE

3.3.6.3 Software Interfaces

TBD

3.3.6.4 Communications Interfaces

3.4 TMC

3.4.1 Design Description

Traffic Management Centers are visualized to be central monitoring stations. This integrates with different systems; to serve multiple purposes (refer to section 3.2.1 in AGORA Architecture and High Level Design Document).

3.4.2 Design and Implementation Constraints

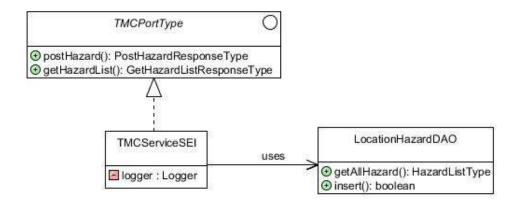
TMC integrates with multiples systems with resource constrained systems. One among them is

- VIS which integrates with every vehicle on the road
- MIS which is mobile version of VIS
- Regional Managers
- Super Nodes

Because of the number of systems that TMC integrates, services exposed by TMC has strict SLA requirement, it should be highly scalable, and fault tolerant.

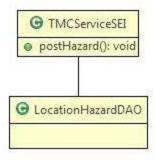
3.4.3 Class Diagram

3.4.3.1 getHazardList



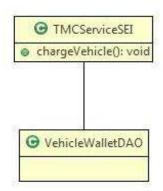
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
LocationHazardDAO	Data access object which help in crud operation on hazards

3.4.3.2 postHazard



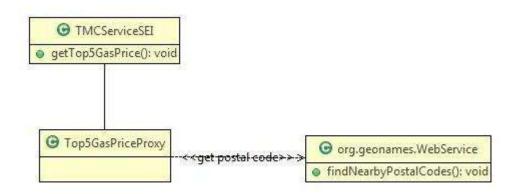
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
LocationHazardDAO	Data access object which help in crud operation on hazards

3.4.3.3 chargeVehicle



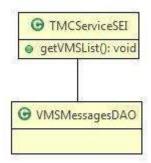
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
VehicleWalletDAO	Data access object which help in crud operation on wallet entries

3.4.3.4 getTop5GasPrice



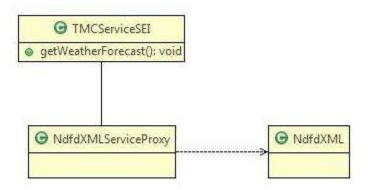
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract
	functions
Top5GasPriceProxy	Proxy component which is a wrapper for geonames web service and also other third party service to get top 5 gas price
WebService	Third party webservice used to translate latitude and longitude to zip code

3.4.3.5 getVMSList



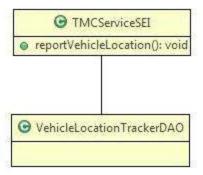
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
VMSMessagesDAO	Data access object which help in crud operation on VMS entries

3.4.3.6 getWeatherForecast



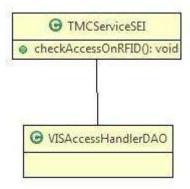
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
NdfdXMLServiceProxy	Proxy component which is a wrapper for geonames web service and also other third party service to get weatherforecast
NdfdXML	Third party webservice used get forecast from third party

3.4.3.7 reportVehicleLocation



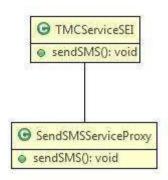
Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
VehicleLocationTrackerDAO	Data access object which help in crud operation on vehicle location tracking

3.4.3.8 checkAccessOnRFID



Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract functions
VISAccessHandlerDAO	Data access object which help in crud operation on VIS\MIS access restriction configuration

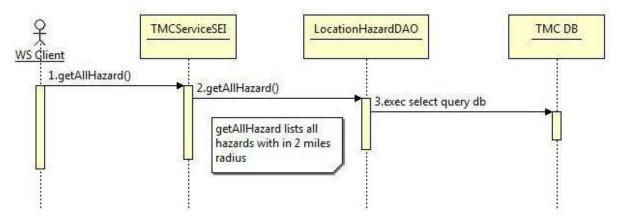
3.4.3.9 sendSMS



Component Name	Description
TMCPortType	Interface which is derived from wsdl contract
TMCServiceSEI	Concrete implementation of wsdl contract
	functions
SendSMSServiceProxy	Proxy component which is a wrapper against
	third party web service which is used to send
	sms

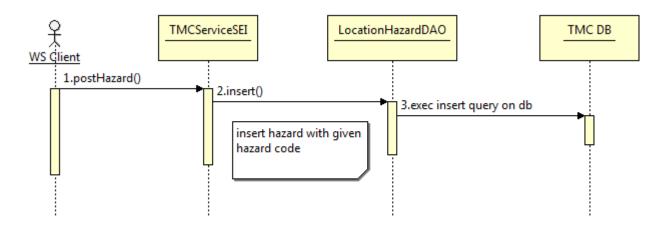
3.4.4 Sequence Diagram

3.4.4.1 getHazardList



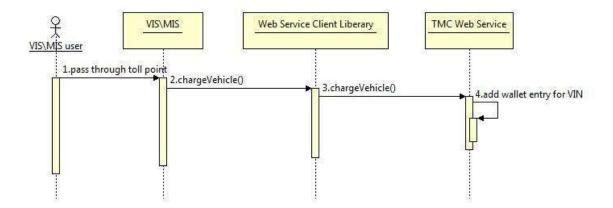
Sequence diagram to get all hazards

3.4.4.2 postHazard

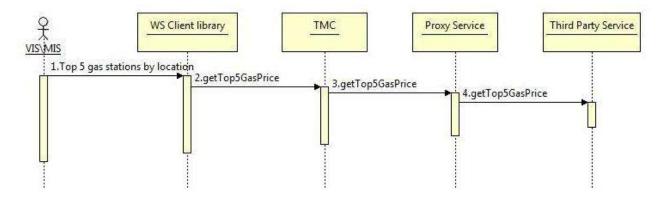


Sequence diagram to post hazard

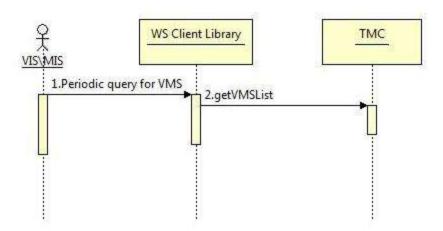
3.4.4.3 chargeVehicle



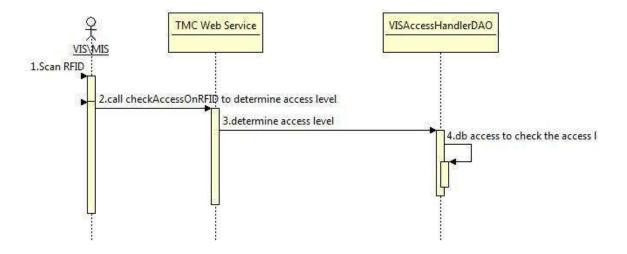
3.4.4.4 getTop5GasPrice



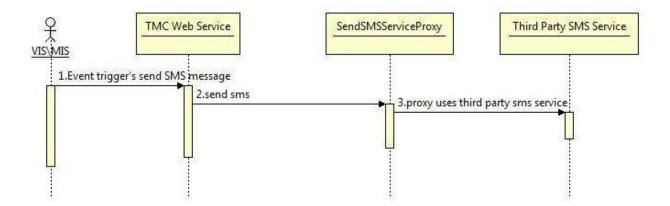
3.4.4.5 getVMSList



3.4.4.6 checkAccessOnRFID



3.4.4.7 sendSMS

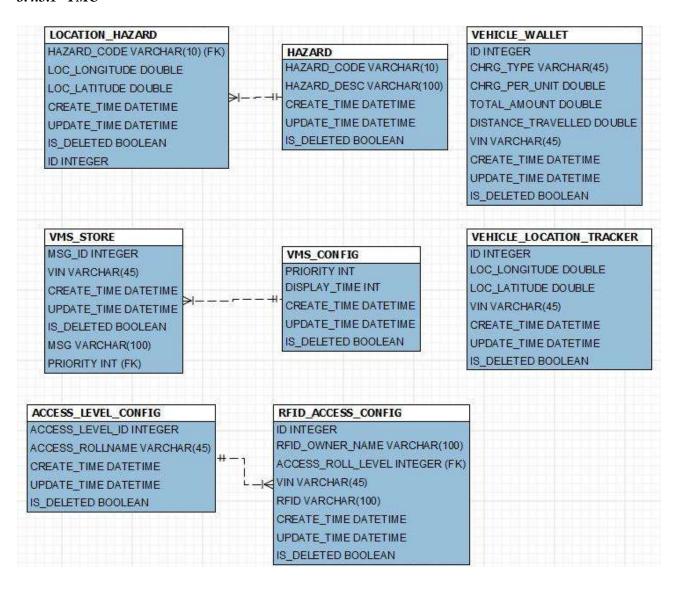


Description:

Above sequence diagram shows how different components interact with each other to serve web service client requests.

3.4.5 ER Diagram

3.4.5.1 TMC



3.4.6 Activity Diagram

TBD

3.4.7 External Interface Requirements

3.4.7.1 User Interfaces

TBD

3.4.7.2 Hardware Interfaces

TRE

3.4.7.3 Software Interfaces

TBD

3.4.7.4 Communications Interfaces

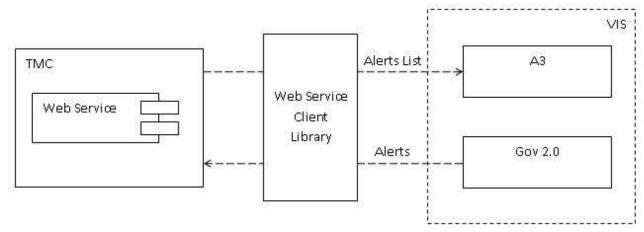
- WSDL
- SOAP
- XML

3.5 A3/Gov 2.0

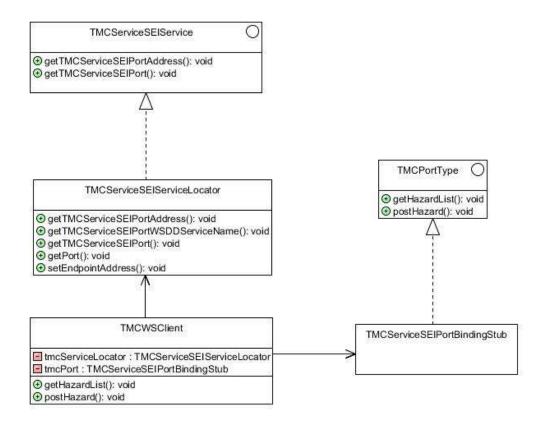
3.5.1 Design Description

A3 is advisory alert application that integrates with VIS so it uses the entire infrastructure that has been developed for VIS. A3 also integrates with TMC through web services.

3.5.1 Design and Implementation Constraints

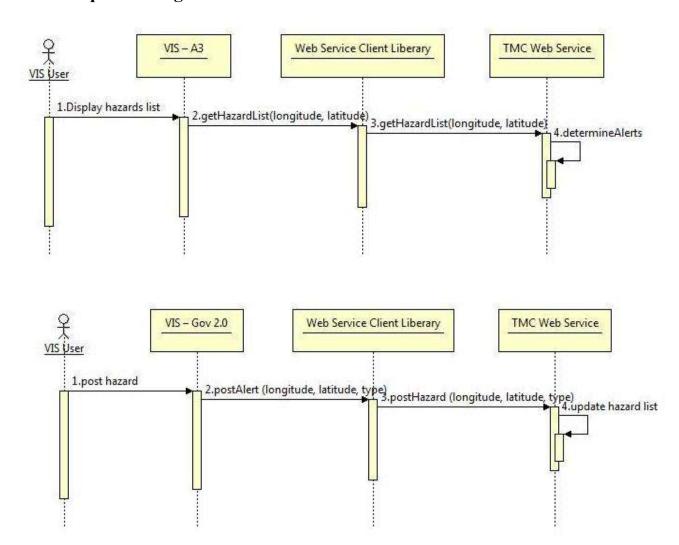


3.5.2 Class Diagram



Component Name	Description
TMCServiceSEIService	TMC web service client service interface
	contract
TMCServiceSEIServiceLocator	Concrete implementation of
	TMCServiceSEIService
TMCPortType	Stub used to make web service call
TMCServiceSEIPortBindingStub	Binding class
TMCWSClient	Client which makes actual web service call

3.5.3 Sequence Diagram



Description:

NONE

3.5.4 Activity Diagram

TBD

3.5.5 External Interface Requirements

3.5.5.1 User Interfaces

VIS – touch screen

3.5.5.2 Hardware Interfaces

None

3.5.5.3 Software Interfaces

VIS

3.5.5.4 Communications Interfaces

- WSDL
- SOAP
- XML

4. Security

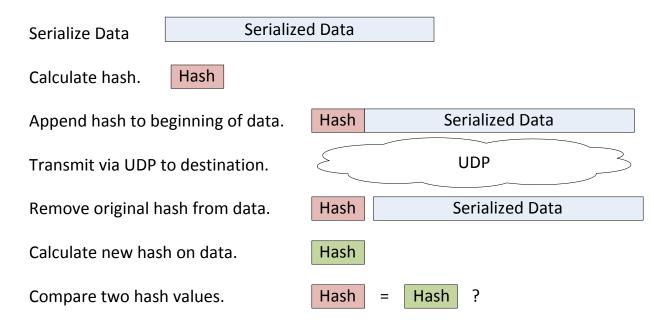
4.1 Vehicle to vehicle

Transport Layer Protocol: UDP

Vehicle to vehicle communication in the AGORA system uses the User Data gram Protocol (UDP). The simplicity of the protocol offers advantages in the following ways.

- No connection establishment/stateless
 In heavy traffic a vehicle may have many neighbors and establishing/maintaining connections with all of them would require substantial resources and introduce measurable delays. Using UDP keeps the communication quick and simple.
- 2. Flexibility

The flexibility of UDP allows AGORA to add a layer of reliability much like TCP, but without being hampered by TCP's transmission rate constraints. In order to detect errors in transmission, the VIS calculates the hash of the serialized data and appends the hash value to the beginning of the data string. When the data arrives at the receiver, the hash value is removed and the receiver calculates the hash of the data. If the two hash values are equal there was no tampering or errors in transmission. If the hash values are not equal, the data is corrupt and discarded.



Security: Password Based Encryption (PBE)

In order to protect transmitted data, the vehicle to vehicle communication in AGORA uses password based encryption (PBE). PBE works by taking a plain text password (usually something that can be remembered as opposed to random characters) and adding some random characters to it called a "Salt". The salted password is then used to generate the key which encrypts the data. The encrypted data is transmitted via UDP to the receiver and the reverse process is used to decrypt the data to display the plain text.

4.2 Vehicle-to-SuperNode, Supernode-to-RegionalManager, Vehicle-to-RegionalManager

Transport Layer Protocol: TCP

For communication from Vehicle-to-SuperNode, Vehicle-to-RegionalManager, RegionalManager-to-SuperNode and vice versa, the TCP protocol is used for reliable data transportation. Communication between each of these entities is extremely important and UDP is not suitable for the implementation. Vehicles contact SuperNodes in order to learn about Regional Managers in the area. Vehicles contact RegionalManagers to learn about neighboring vehicles. RegionalManagers and SuperNodes communicate to verify activity and monitor centroids.

Appendix A: Glossary

MDOT – Michigan Department of Transportation

OBE - On-Board Equipment

RSE – Road-Side Equipment

TMC – Traffic Management Centers A3– Advisory Alert Application

LSA – Life Safety Application

VIS - Vehicle Integrated Software