

Quentin Brateau

ROBOTICS ENGINEER · EMBEDDED SYSTEMS

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TAMPERE UNIVERSITY

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KALEVANTIE 4, 33100 TAMPERE

Ph.D. Letter of Intent : Safe and resilient control of autonomous surface vessels in dynamic environments

Dear Madam/Sir,

I am Quentin Brateau, a French engineer in robotics. I was graduated in 2021 ENSTA Bretagne, in Brest, a prominent French graduate, post-graduate school, Research Institute, and doctoral college, which trains engineers in various fields of engineering such as Robotics, which is my specialty. I also was graduated the same year with a master of science in dynamical systems and signals from the University of Angers in France.

My academic training has a strong emphasis on Science because I have completed a two-year intensive post-secondary school preparation for the competitive entrance examination for the French Graduate Engineering Schools. During my internships, I had the opportunity to discover various fields of mobile robotics such as agriculture robotics with Tecnoma, vineyard robotics with Exact Robotics, and underwater robotics with Forssea Robotics. I am then very familiar with the industrial application of robotics.

During my studies, I learned the basics of robotics such as robot mechanical conception, hardware design, simulation, and low-level control. I was also able to build a solid foundation in information technology through courses on applied mathematics, image and signal processing, machine learning, embedded operating systems. Additionally, I was able to reinforce my knowledge in robotics by learning control theory, probabilistic and set methods for state estimation, navigation, and path planning.

Thanks for your time and consideration. I genuinely believe that my experience and education would make me a valuable asset to the mechatronics research group. I believe my skills and motivation make me a great potential asset. I can be reached by phone and email if you need any further information.

Introduction

I would consider pursuing my studies by doing a Ph.D. at Tampere University mechatronics research group to be a privilege. I have already met Pr. Kari Koskinen and Dr. Jussi Aaltonen, and I had the opportunity to visit the laboratory and present some of my works. From what I was able to discover during my visit, my profile and my skills are perfectly suited to the expectations of the mechatronics research group, with projects that were presented to me such as PVT0, RoboMiners or the AutoFeeder project, which this thesis will be part of.

Problem Statement

The control of systems in a guaranteed and resilient way still has many shortcomings. This thesis will allow to remove scientific locks in the fields of control and command of systems in a safe and guaranteed way.

- How the guarantee provided by interval analysis can help us to realize a safe command-control loop?
- How to ensure collision-free control of a system in a dynamic environment?
- How can we ensure the security and resilient control of a system that operates in degraded mode?

Research Methods

Preliminary Schedule

After a state of the art review in the field of guaranteed and resilient control of systems, as well as in the classical control of surface vessels, I will alternate between phases of modeling and simulation and phases of real tests to validate the theoretical tools imple-

mented. The results of this theoretical work on the control of systems and their application to the control of autonomous surface vessels through trial results will be subject to publications.

As requested by the Ph.D. offer, at least four publications will be scheduled. The guaranteed control algorithms as well as those in degraded situations could be published in an international journal such as Oceanic Engineering or IEEE Transaction on Robotics. Two international conferences in robotics are also targeted ICRA and IROS for example.

Finally, the last year will be mainly devoted to the compilation of the results, the formalization of the implemented tools and the writing of my thesis as well as the preparation of my thesis defense.

	Preliminary Schedule															
	2022		2023				2024				2025				2026	
	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2
State of the Art																
Modelling and Simulation																
Laboratory and Field Experiments																
Article and Thesis																

Conclusion

Veuillez agréer, Messieurs, l'assurance de ma considération distinguée,

Quentin Brateau