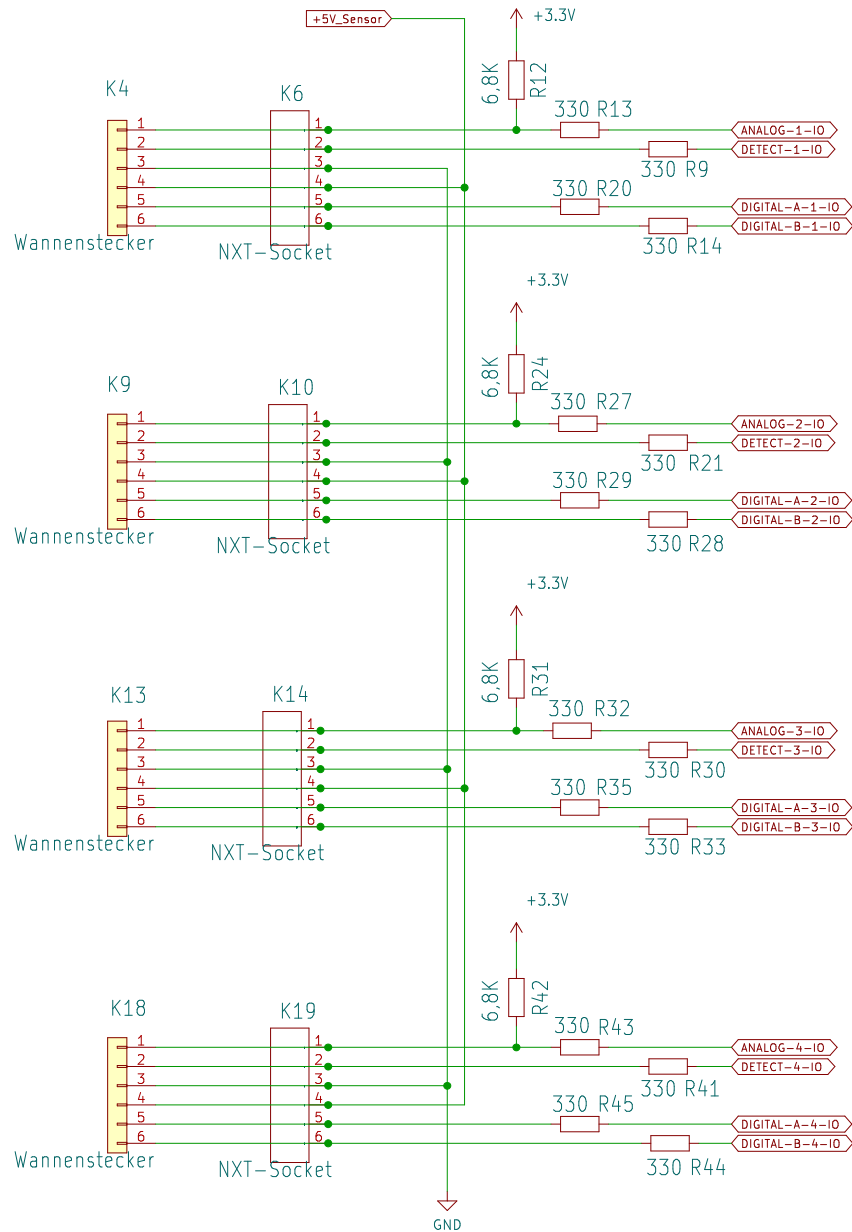
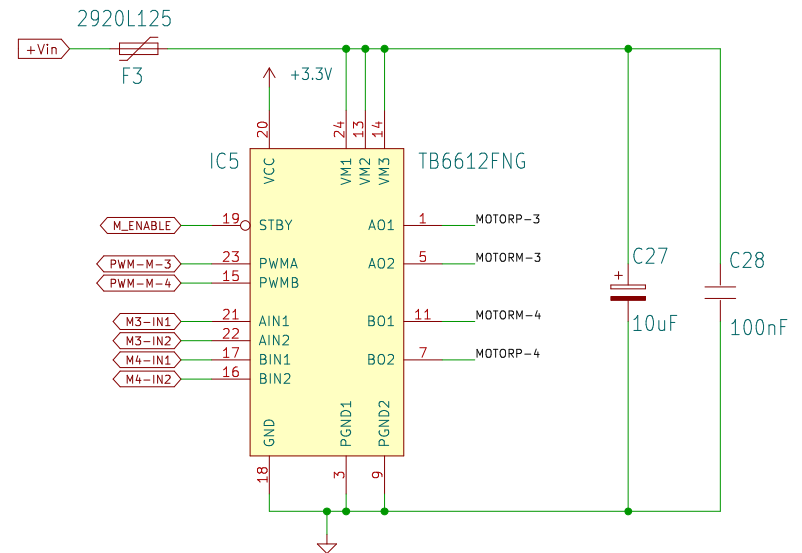
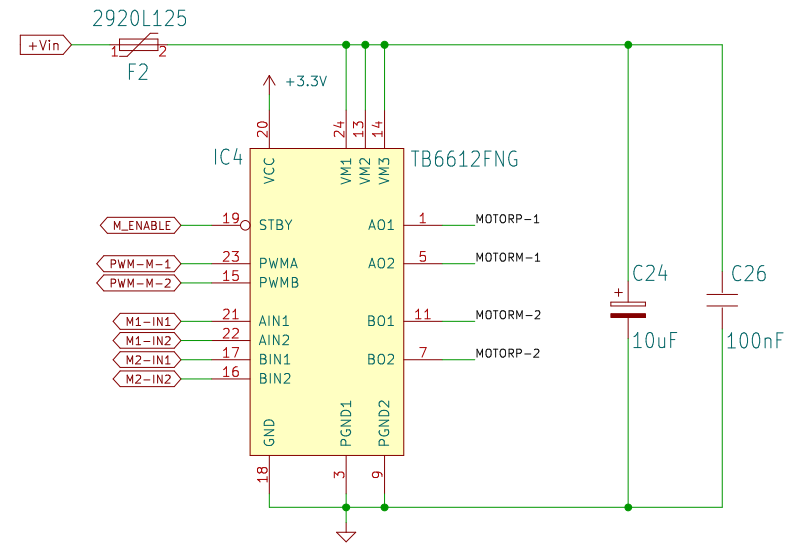
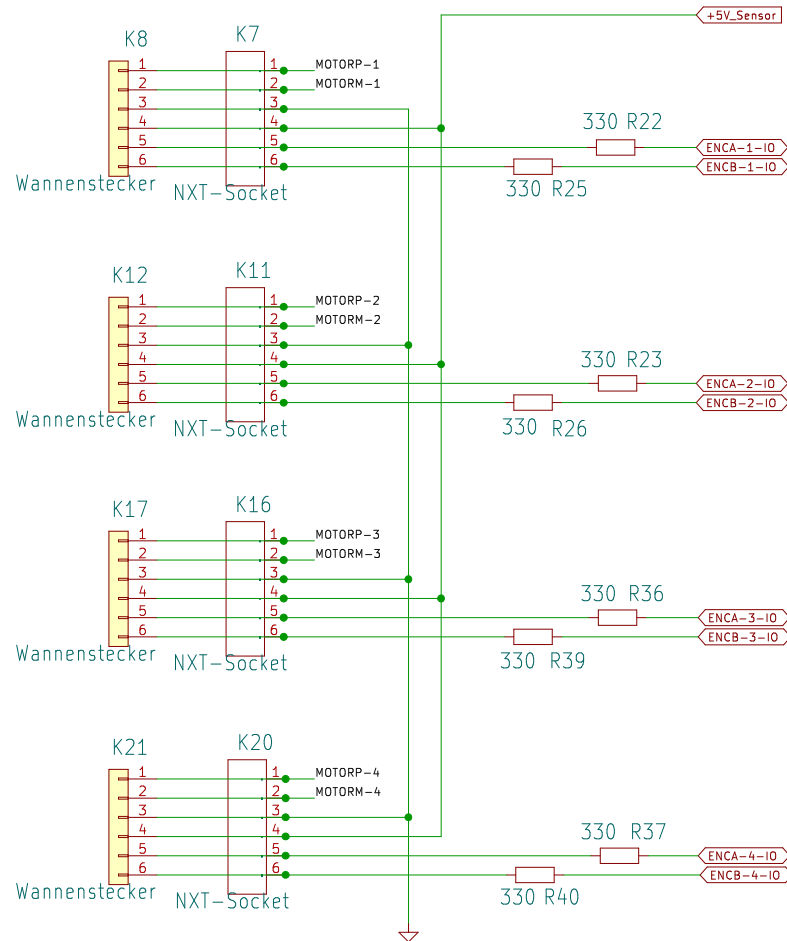


	1	2	3	4	5	6
A	<div>Controller, Bluetooth</div> <div></div> <div>Datei: Controller_Bluetooth.kicad_sch</div>	<div>Power, LED,Tasten, IO</div> <div></div> <div>Datei: Power_LED_Tasten_IO.kicad_sch</div>				
B						
C						
D					<div><div>Title: Open Robotic Board (ORB)</div><div>Rev: 01.00-99</div><div>Sheet: /</div><div>Id: 1/5</div><div>File: ORB.kicad_sch</div><div>Date: 2023-11-10</div><div>Overview</div><div></div><div>KiCad E.D.A. kicad (6.0.1)</div><div>Thomas Breuer (Hochschule Bonn-Rhein-Sieg)</div></div>	
	1	2	3	4	5	6

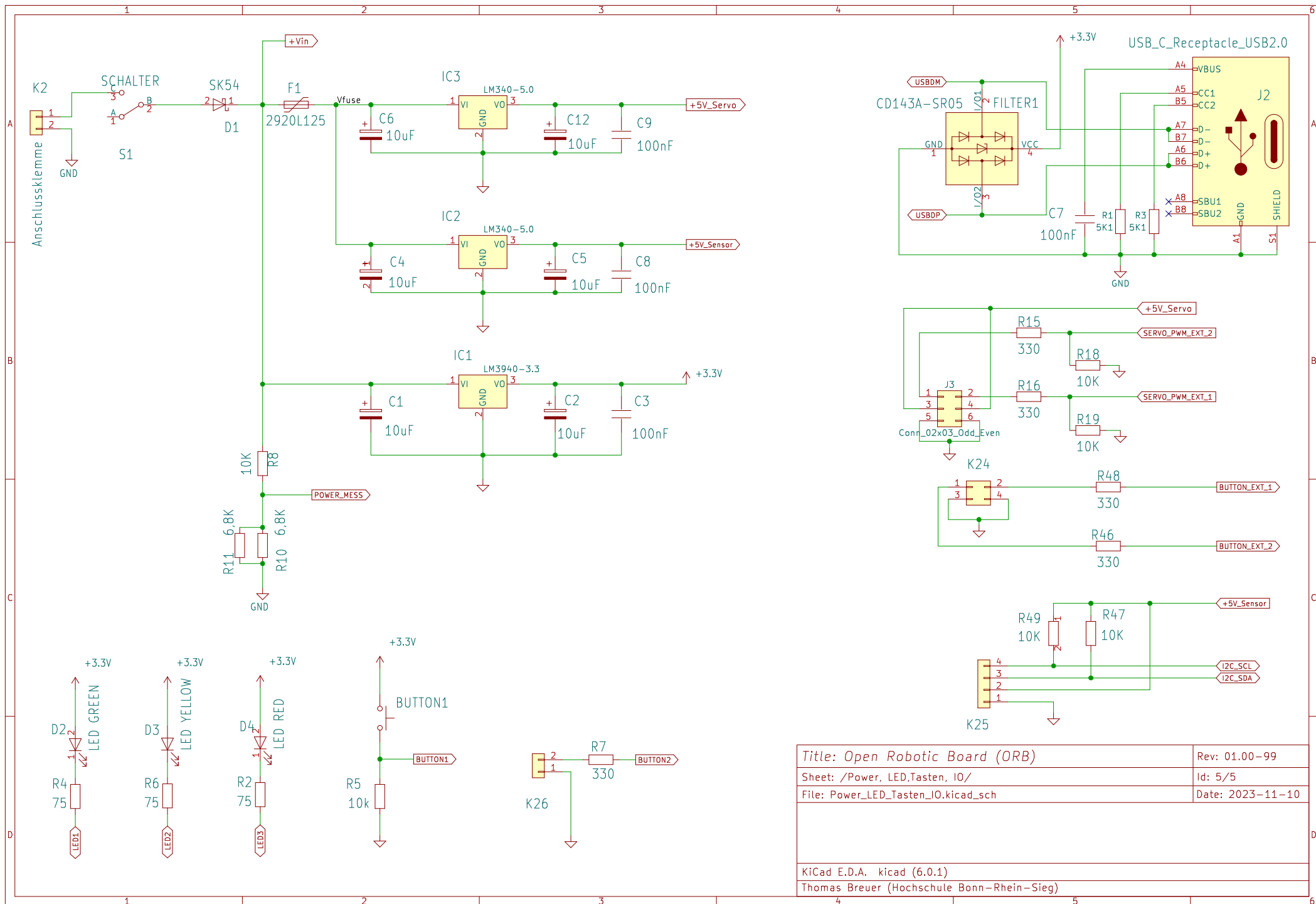




Title: Open Robotic Board (ORB)	Rev: 01.00-99
Sheet: /Sensor-Ports/	Id: 3/5
File: Sensor_Ports.kicad_sch	Date: 2023-11-10
<p>KiCad E.D.A. kicad (6.0.1)</p> <p>Thomas Breuer (Hochschule Bonn-Rhein-Sieg)</p>	



Title: Open Robotic Board (ORB)	Rev: 01.00-99
Sheet: /Motor-Ports/	Id: 4/5
File: Motor_Ports.kicad_sch	Date: 2023-11-10
KiCad E.D.A. kicad (6.0.1)	
Thomas Breuer (Hochschule Bonn-Rhein-Sieg)	



Title: Open Robotic Board (ORB)	Rev: 01.00-99
Sheet: /Power, LED,Tasten, IO/	Id: 5/5
File: Power_LED_Tasten_IO.kicad_sch	Date: 2023-11-10
<p>KiCad E.D.A. kicad (6.0.1)</p> <p>Thomas Breuer (Hochschule Bonn-Rhein-Sieg)</p>	