MECH 230 Dynamics Homework 2

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Due Wednesday September 18, 2024

1. Consider a particle tracing a circular helix. Its position vector is expressed in Cartesian coordinates as

```
\mathbf{r} = x\mathbf{E}_x + y\mathbf{E}_y + z\mathbf{E}_z = R\cos(\omega t)\mathbf{E}_x + R\sin(\omega t)\mathbf{E}_y + \alpha R\omega t\mathbf{E}_z.
```

(a) Create a Matlab script helix.m in which you write the following code to plot the helix for $R=1, \ \omega=2, \ \mathrm{and} \ \alpha=0.5$. Note that you can change your view angle manually or using the command view.

% Running this script builds an animation of a particle tracing a circular % helix

```
R = 1; % radius of helix
omega = 2; % angular velocity parameter
alpha = 0.5;
n = 30;
t = linspace(0,5,n);
                       % plotting trajectory for 0<t<5s with n time steps
x = R*cos(omega*t);
y = R*sin(omega*t);
z = R*alpha*omega*t;
figure()
hold on
plot3(0,0,0,'*','linewidth',2,'color','k') % plotting the orgin
plot3(x,y,z,'color','k','linewidth',2)
                                        % plotting the helix
quiver3(0,0,0,1,0,0,'linewidth',2,'color','b') % plot Ex
quiver3(0,0,0,0,1,0,'linewidth',2,'color','r') % plot Ey
quiver3(0,0,0,0,0,1,'linewidth',2,'color','g') % plot Ez
```

view(30,45) % set view angle, can be also changed manually axis equal

```
% plotting er in blue
er = [x./(x.^2+y.^2);
                            % the x-coordinate of er
    y./(x.^2+y.^2);
                            % the y-coordinate of er
    zeros(1,n)];
                            % the z-coordinate of er
quiver3(x,y,z,er(1,:),er(2,:),er(3,:),'color','b')
% plotting etheta in red
etheta = [-y./(x.^2+y.^2);
                            % the x-coordinate of etheta
    x./(x.^2+y.^2);
                            % the y-coordinate of etheta
                            \% the z-coordinate of etheta
    zeros(1,n)];
quiver3(x,y,z,etheta(1,:),etheta(2,:),etheta(3,:),'color','r')
```

(b) In cylindrical polar coordinates, the position vector can be expressed as

$$\mathbf{r} = r\mathbf{e}_r + z\mathbf{E}_z$$
.

Identify the expressions for r, θ , \mathbf{e}_r and \mathbf{e}_{θ} in terms of R and t.

- (c) Read the Matlab documentation on quiver3.
- (d) Copy the following code to the end of your script to plot the $\{\mathbf{e}_r, \mathbf{e}_{\theta}, \mathbf{E}_z\}$ basis on the helix.

- (e) Calculate $\mathbf{v} = \frac{d\mathbf{r}}{dt}$.
- (f) Knowing that $\mathbf{v}=||\mathbf{v}||\mathbf{e}_t$ and $\frac{ds}{dt}=v=||\mathbf{v}||,$ verify that

$$\begin{split} \mathbf{e}_t &= \frac{1}{\sqrt{1+\alpha^2}} \left(\mathbf{e}_\theta + \alpha \mathbf{E}_z \right), \\ \frac{ds}{dt} &= R \dot{\theta} \sqrt{1+\alpha^2}. \end{split}$$

(g) The chain rule implies that

$$\frac{d\mathbf{e}_t}{dt} = \frac{d\mathbf{e}_t}{ds} \frac{ds}{dt}.$$

Use this result to calculate $\frac{d\mathbf{e}_t}{ds}$.

(h) Recall that

$$\frac{d\mathbf{e}_t}{ds} = \kappa \mathbf{e}_n$$

where $\kappa \geq 0$ and $\mathbf{e}_n \cdot \mathbf{e}_n = 1$. Vertify that

$$\mathbf{e}_n = -\mathbf{e}_r$$

$$\kappa = \frac{1}{R(1+\alpha^2)}$$

- (i) Recall that $\mathbf{e}_b = \mathbf{e}_t \times \mathbf{e}_n$. Calculate \mathbf{e}_b .
- (j) Recall the Serret-Frenet relations and the definition of the torsion τ :

$$\frac{d\mathbf{e}_b}{ds} = -\tau \mathbf{e}_n.$$

Verify that

$$\tau = \frac{\alpha}{R(1 + \alpha^2)}.$$

(k) On a new figure, plot the helix, and the basis $\{\mathbf{e}_t, \mathbf{e}_n, \mathbf{e}_b\}$ along its length. Here's one way to plot \mathbf{e}_t :

```
figure() hold on
```

plot3(0,0,0,'*','linewidth',2,'color','k') % plotting the orgin

quiver3(0,0,0,1,0,0,'linewidth',2,'color','b') % plot Ex quiver3(0,0,0,0,1,0,'linewidth',2,'color','r') % plot Ey quiver3(0,0,0,0,0,1,'linewidth',2,'color','g') % plot Ez

 $\mbox{view(30,45)}$ % set view angle, can be also changed manually axis equal

```
Ez = [0;0;1];
% plotting et in blue
et = 1/sqrt(1+alpha^2)*(etheta+alpha*Ez);
quiver3(x,y,z,et(1,:),et(2,:),et(3,:),'color','b')
% plotting en in red
% ???
% ???
% plotting eb in green
% ???
% ???
```

(l) How do κ and τ change as you increase α ?

Deliverables: Your submission should include the following.

- \bullet A hard copy of your answers to parts b, e, g, i and l.
- A hard copy of the plot you obtained in part k.
- A hard copy of the code.