

Design aims of C++11



Bjarne Stroustrup:

" ... make C++
even better for
embedded system
programming ..."



Overview





- Key concerns
 - Safety critical
 - Limited resources
 - Long lifetime
 - Many cores
- Last thoughts
 - Myths
 - Facts







Preventing narrowing with {}-initialization

 $3.14159 \implies 3.14159$

```
double dou= 3.14159;
int a = dou; // ok
int b(dou); // ok
int c= {dou}; // error
int d{dou}; // error
int8_t f= {2011}; // error
int8 t g = \{14\}; // ok
```



narrowing conversion from double to int



Assertions with type traits and static_assert



- type traits performs at compile time
 - type information
 - type comparison
 - type modification
- static_assert
 - validate expressions at compile time



Assertions with type traits and static_assert

```
template <typename S, typename D>
void smallerAs(S s, D d) {
  static assert(sizeof(S) <= sizeof(D), "S is too big");</pre>
smallerAs(1.0,1.0L);
smallerAs(1.0L, 1.0);
                           // with S= long double; D= double
                           // S is too big
template <typename T>
T fac(T a) {
  static assert(std::is integral<T>::value, "T not integral");
fac(10);
fac(10.1);
                           // with T= double; T not integral
```

Respect the unit with user-defined literals

- Syntax: <built_in literal>+_ + <suffix>
 - integer literals: 101010_b
 - floating point literals: 123.45_km
 - string literals: "hello"_i18n
 - character literals: 'a'_Noldea



Respect the unit with user-defined literals

Respect the unit with user-defined literals

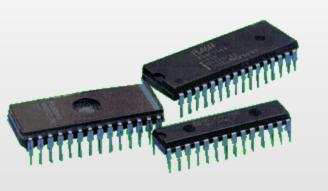
```
namespace Unit{
 MyDist operator "" km(long double k) {
    return MyDist(100000*k);
 MyDist operator "" m(long double m) {
    return MyDist(100*m);
 MyDist operator "" dm(long double d) {
    return MyDist(10*d);
 MyDist operator "" cm(long double c) {
    return MyDist(c);
```



Respect the unit with User-defined literals

```
class MyDist{
 private:
    long double cm;
  public:
    MyDist(long double i):cm(i){}
    friend MyDist operator + (const MyDist& a, const MyDist& b) {
      return MyDist(a.cm + b.cm);
    friend MyDist operator - (const MyDist& a, const MyDist& b) {
      return MyDist(a.cm - b.cm);
    friend std::ostream& operator<< (std::ostream &out, const MyDist&
   myDist) {
      out << myDist.cm << " cm";
      return out;
```

Evaluate at compile time with constexpr



- can be evaluated at compile timestored in ROM
- three forms
 - variables
 - functions
 - user-defined types



Evaluate at compile time with constexpr

```
constexpr int myConstExpr= 2;
constexpr int square(int i) { return i*i; }
struct MyInt{
  int myInt;
  constexpr MyInt(int i):myInt(i){}
  constexpr int multiplyBy(int i) { return i*myInt; }
};
constexpr MyInt myInt(5);
constexpr int res = myInt.multiplyBy(myConstExpr);
static assert(myInt.multiplyBy(2) == 10,"error");
static assert(res == 10, "error");
std::cout << myInt.multiplyBy(square(5)) << std::endl;</pre>
```



Be fast with generalized POD's



- has to be trivial
- has standard layout
- members and base classes must also be POD's



- fast manipulation like a C struct
 - arrays of POD's can be copied by block
 - static initialization



Be fast with generalized POD's

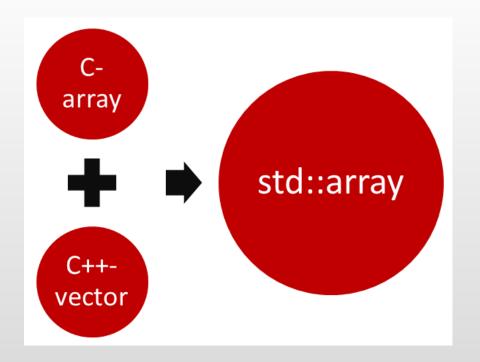
```
struct Base{};
struct Pod: Base {
  int a;
 Pod() = default;
  int getA() const { return a;}
};
std::cout << std::is pod<int>::value;
                                                // true
std::cout << std::is pod<std::string>::value; // false
                                                // true
std::cout << std::is pod<Pod>::value;
```



Be fast with generalized POD's

```
struct NotTrivial{
 NotTrivial() { }
class NotStandLay{
 int a;
public:
 int b;
};
                                // false
std::cout << std::is pod<NotTrivial>::value
std::cout << std::is standard layout<NotTrivial>::value; // true
std::cout << std::is trivial<NotStandLay>::value;  // true
std::cout << std::is standard layout<NotStandLay>::value;//false
```

Slim and fast with std::array



- homogeneous container of fixed length
- combines the performance of a C-Array with the interface of a C++-Vector
- no heap allocation



Slim and fast with std::array

Cheap moving with move semantic



- cheap moving instead of expensive copying
 - performance
 - no memory allocation and deallocation
 - predictability
- implementing save "moveonly" types
 - unique_ptr, files, locks and tasks



Cheap moving with move semantic

```
std::vector<int> a, b;
swap(a,b);
template <typename T>
void swap(T& a, T& b) {
  T tmp(a);
  a = b;
 b= tmp;
template <typename T>
void swap (T& a, T& b) {
  T tmp(std::move(a));
  a= std::move(b);
  b= std::move(tmp);
```

- T tmp(a);
 - allocate tmp and each element of tmp
 - copy each element of a to tmp
 - deallocate tmp and each element of tmp

- T tmp(std::move(a));
 - adjust a pointer of tmp to the data of a



Preserve the nature with perfect forwarding



- pass the arguments while preserving the lvlue/rvalue nature of the arguments
- use case
 - factory functions
 - constructors

chaining of move semantic forwarding of move-only types

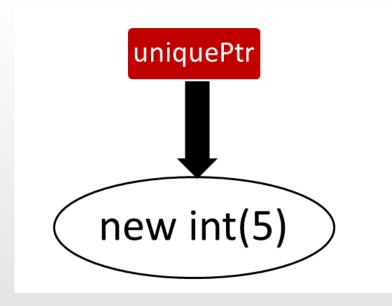


Preserve the nature with perfect forwarding

```
template <typename T, typename T1>
T createT(T1&& t1) {
  return T(std::forward<T1>(t1));
int lValue= createT<int>(2011);
int i= createT<int>(lValue);
struct NeedOnlyMove{
  NeedOnlyMove(OnlyMove){};
};
struct OnlyMove{
  OnlyMove() = default;
  OnlyMove(const OnlyMove&) = delete;
  OnlyMove& operator= (const OnlyMove&) = delete;
  OnlyMove(OnlyMove&&) = default;
  OnlyMove& operator= (OnlyMove&&) = default;
};
NeedOnlyMove nOnlyMove2= createT<NeedOnlyMove>(OnlyMove());
```



Explicit ownership with std::unique_ptr



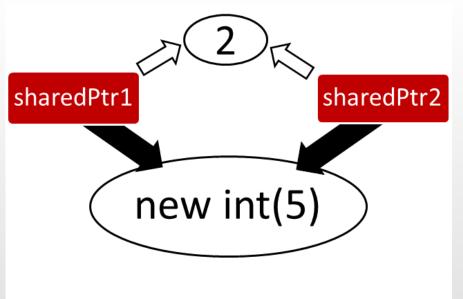
- explicit ownership
- only moveable
- support arrays



- create and forget
- minimal space and time overhead
- support special allocation strategies



Shared ownership with std::shared_ptr



- shared ownership
- has a reference counter and a handle to his resource
- manage the reference counter and the resource



- managing overhead in time and space
- saves memory
- have to deal with cycles



performance matters

```
auto st = std::chrono::system_clock::now();

for (long long i=0 ; i < 100000000; ++i) {
   int* tmp(new int(i));
   delete tmp;
   // std::unique_ptr<int> tmp(new int(i));
   // std::shared_ptr<int> tmp(new int(i));
   // std::shared_ptr<int> tmp= std::make_shared<int>(i);
}

std::chrono::duration<double> dur=std::chrono::system_clock::now() - st();
std::cout << dur.count();</pre>
```



pointer type	real hardware	virtualization
native	3.0 sec.	5.7 sec.
std::unique_ptr	2.9 sec.	5.7 sec.
std::shared_ptr	6.0 sec.	11.8 sec.
std::make_shared		6.5 sec.



Still missing ...

- Multiple cores
 - memory model, atomics, thread management
- Limited resource time
 - std::tuple and std::forward_list
 - unordered containers
- Limited resource memory
 - alignment support
- Safety critical
 - scoped enums and nullptr
 - auto_ptr deprecated
- . . .



Myths about C++





Myths about C++

- Templates causes code bloat.
- Objects have to be created on the heap.
- Exceptions are expensive.
- C++ is too slow and needs too much memory.
- C++ is too dangerous for safety critical systems.
- In C++ you have to program object oriented.
- You can use C++ only for applications.
- The iostream library is too big, the STL library too slow.



C++ is a nice toy. Be we are dealing with the serious problems.



Facts about C++





Facts about C++

- MISRA C++
 - Motor Industry Software Reliability Association
 - guidelines for C++ in critical(embedded) systems
- TR18015.pdf
 - Technical report on C++ performance
 - special focus on embedded systems
 - refute the myths
- both based on C++03, but C++11 is still better for the embedded programming





Thank you for your attention

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