```
So luong he truc toa do: 7
n =
    7
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0
C =
    0 1 0 1 0 1 0 0
Dich chuyen theo truc x: 11
dx =
11
Dich chuyen theo truc y : 12
dy =
12
Dich chuyen theo truc z: 0
dz =
    0
T =
[ 1, 0, 0, 11]
[ 0, 1, 0, 12]
[ 0, 0, 1, 0]
[ 0, 0, 0, 1]
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)1
C =
    0 1 0 1 0 1 0 0
Quay quanh tuc nao x/y/z: z
Q =
Z
```

```
Gia tri quay quanh truc: t1
t =
t1
T =
[\cos(t1), -\sin(t1), 0, 11]
[\sin(t1), \cos(t1), 0, 12]
[ 0, 0, 1, 0]
[ 0, 0, 0, 1]
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0
C =
    0 1 0 1 0 1 0 0
Dich chuyen theo truc x : 0
dx =
   0
Dich chuyen theo truc y : 0
dy =
    0
Dich chuyen theo truc z: 13
dz =
13
T =
[\cos(t1), -\sin(t1), 0, 11]
[\sin(t1), \cos(t1), 0, 12]
[ 0,
            0, 1, 13]
      0,
               0, 0, 1]
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)1
```

```
C =
    0 1 0 1 0 1 0 0
Quay quanh tuc nao x/y/z: y
Q =
У
Gia tri quay quanh truc: t2
t =
t2
T =
[\cos(t1) \cdot \cos(t2), -\sin(t1), \cos(t1) \cdot \sin(t2), 11]
[\cos(t2)*\sin(t1), \cos(t1), \sin(t1)*\sin(t2), 12]
       -\sin(t2),
                            cos(t2), 13
[
                    0,
                       Ο,
              Ο,
                                      0, 1]
[
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0
C =
    0 1 0 1 0 1 0 0
Dich chuyen theo truc x : 0
dx =
    0
Dich chuyen theo truc y : 0
dy =
  0
Dich chuyen theo truc z : -14-15
dz =
- 14 - 15
```

```
T =
[\cos(t1) \cdot \cos(t2), -\sin(t1), \cos(t1) \cdot \sin(t2), 11 - \cos(t1) \cdot \sin(t2) \cdot (14 + 15)]
[\cos(t2)*\sin(t1), \cos(t1), \sin(t1)*\sin(t2), 12 - \sin(t1)*\sin(t2)*(14 + 15)]
           -\sin(t2),
                                 0,
                                              cos(t2),
                                                             13 - \cos(t2) * (14 + 15)
Γ
[
                                 0,
                                                                                                 1]
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)1
C =
              1 0 1 0 1 0 0
Quay quanh tuc nao x/y/z: y
Q =
У
Gia tri quay quanh truc: t4
t =
t4
T =
[\cos(t1) \cdot \cos(t2) \cdot \cos(t4) - \cos(t1) \cdot \sin(t2) \cdot \sin(t4), -\sin(t1), \cos(t1) \cdot \cos(t2) \cdot \sin(t4)]
(t4) + \cos(t1) \cdot \cos(t4) \cdot \sin(t2), 11 - \cos(t1) \cdot \sin(t2) \cdot (14 + 15)
[\cos(t2) \cdot \cos(t4) \cdot \sin(t1) - \sin(t1) \cdot \sin(t2) \cdot \sin(t4), \cos(t1), \cos(t2) \cdot \sin(t1) \cdot \sin(t1) \cdot \sin(t4), \cos(t2) \cdot \sin(t1) \cdot \sin(t1) \cdot \sin(t1) \cdot \sin(t2) \cdot \sin(t3) \cdot \sin(t4)
(t4) + \cos(t4) \cdot \sin(t1) \cdot \sin(t2), 12 - \sin(t1) \cdot \sin(t2) \cdot (14 + 15)
                    -\cos(t2)*\sin(t4) - \cos(t4)*\sin(t2),
                                                                                                      COR
(t2)*\cos(t4) - \sin(t2)*\sin(t4),
                                              13 - \cos(t2) * (14 + 15)
[
                                                                Ο,
                                                                             0 🖊
Ο,
                                         1]
He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0
C =
           1 0 1 0 1 0 0
Dich chuyen theo truc x : 16
dx =
16
```

```
Dich chuyen theo truc y : 0
dy =
                                      0
Dich chuyen theo truc z : 0
dz =
T =
[\cos(t1) \cdot \cos(t2) \cdot \cos(t4) - \cos(t1) \cdot \sin(t2) \cdot \sin(t4), -\sin(t1), \cos(t1) \cdot \cos(t2) \cdot \sin(t4)]
 (t4) + \cos(t1) \cdot \cos(t4) \cdot \sin(t2), l1 - l6 \cdot (\cos(t1) \cdot \sin(t2) \cdot \sin(t4) - \cos(t1) \cdot \cos(t2)
(t4)) - cos(t1) * sin(t2) * (14 + 15)]
[\cos(t_2) \cdot \cos(t_4) \cdot \sin(t_1) - \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_4), \cos(t_1), \cos(t_2) \cdot \sin(t_1) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_1), \cos(t_1) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_2) \cdot \sin(t_1) \cdot \sin(t_2) \cdot \sin(t
 (t4) + \cos(t4) * \sin(t1) * \sin(t2), 12 - 16* (\sin(t1) * \sin(t2) * \sin(t4) - \cos(t2) * \cos(t4) * \cos(t4
*\sin(t1)) - \sin(t1)*\sin(t2)*(14 + 15)]
                                                                                                                        -\cos(t2)*\sin(t4) - \cos(t4)*\sin(t2),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          COR
                                                                                                                                                                                                                                                                                                                                                                                                                                                      13 - 16*(cos(t2)*sin(t4) ¥
 (t2)*\cos(t4) - \sin(t2)*\sin(t4),
cos(t4)*sin(t2)) - cos(t2)*(14 + 15)]
                                                                                                                                                                                                                                                                                                                                                                                                       Ο,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     0 K
[
0, 4
1]
ans =
[\cos(t2 + t4) \cos(t1), -\sin(t1), \sin(t2 + t4) \cos(t1), 11 + 16\cos(t2 + t4)\cos(t1)]
-\cos(t1)*\sin(t2)*(14 + 15)]
[\cos(t^2 + t^4) \cdot \sin(t^1), \cos(t^1), \sin(t^2 + t^4) \cdot \sin(t^1), 1^2 + 16 \cdot \cos(t^2 + t^4) \cdot \sin(t^1)]
-\sin(t1)*\sin(t2)*(14 + 15)]
                                                              -\sin(t2 + t4),
                                                                                                                                                                                                                                                                                                                         cos(t2 + t4),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 13 - cos(t2) ≰
                                                                                                                                                                                                                                                 Ο,
 (14 + 15) - 16*sin(t2 + t4)]
                                                                                                                                                                                                                                                                                                                                                                                                                              0 y
                                                                                                                                                                   Ο,
                                                                                                                                                                                                                                                   Ο,
[
1]
>>
```