

So luong he truc toa do: 9

n =

9

He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0

C =

0 1 0 1 0 0 0 0

Dich chuyen theo truc x : 0

dx =

0

Dich chuyen theo truc y : 0

dy =

0

Dich chuyen theo truc z : 11

dz =

11

T =

[1, 0, 0, 0]

[0, 1, 0, 0]

[0, 0, 1, 11]

[0, 0, 0, 1]

He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)1

C =

0 1 0 1 0 0 0 0

Quay quanh tuc nao x/y/z: z

Q =

z

Gia tri quay quanh trục: t1

t =

t1

T =

```
[ cos(t1), -sin(t1), 0, 0]
[ sin(t1),  cos(t1), 0, 0]
[      0,      0, 1, 11]
[      0,      0, 0,  1]
```

He trục so Chuyen vi của he trục, 0/1 (0:Tĩnh tiến, 1:Quay)0

C =

```
0      1      0      1      0      0      0      0
```

Dich chuyen theo trục x : 0

dx =

0

Dich chuyen theo trục y : 0

dy =

0

Dich chuyen theo trục z : 13

dz =

13

T =

```
[ cos(t1), -sin(t1), 0,      0]
[ sin(t1),  cos(t1), 0,      0]
[      0,      0, 1, 11 + 13]
[      0,      0, 0,      1]
```

He trục so Chuyen vi của he trục, 0/1 (0:Tĩnh tiến, 1:Quay)1

C =

```
0    1    0    1    0    0    0    0
```

Quay quanh trục nào x/y/z: x

Q =

x

Gia trị quay quanh trục: t2

t =

t2

T =

```
[ cos(t1), -cos(t2)*sin(t1), sin(t1)*sin(t2), 0]
[ sin(t1), cos(t1)*cos(t2), -cos(t1)*sin(t2), 0]
[      0,      sin(t2),      cos(t2), l1 + l3]
[      0,      0,      0,      1]
```

Hệ trục số Chuyển vị của hệ trục, 0/1 (0:Tĩnh tiến, 1:Quay)0

C =

```
0    1    0    1    0    0    0    0
```

Địch chuyển theo trục x : 0

dx =

0

Địch chuyển theo trục y : l4

dy =

l4

Địch chuyển theo trục z : 0

dz =

0

T =

```
[ cos(t1), -cos(t2)*sin(t1), sin(t1)*sin(t2), -l4*cos(t2)*sin(t1)]
[ sin(t1), cos(t1)*cos(t2), -cos(t1)*sin(t2), l4*cos(t1)*cos(t2)]
[      0,      sin(t2),      cos(t2), l1 + l3 + l4*sin(t2)]
[      0,      0,      0,      1]
```

He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)1

C =

```
0      1      0      1      0      1      0      0
```

Quay quanh tuc nao x/y/z: x

Q =

x

Gia tri quay quanh truc: t3

t =

t3

T =

```
[ cos(t1), sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1), cos(t2)*sin(t1)*sin(t3) + cos(t3)*sin(t1)*sin(t2), -l4*cos(t2)*sin(t1)]
[ sin(t1), cos(t1)*cos(t2)*cos(t3) - cos(t1)*sin(t2)*sin(t3), - cos(t1)*cos(t2)*sin(t3) - cos(t1)*cos(t3)*sin(t2), l4*cos(t1)*cos(t2)]
[      0,      cos(t2)*sin(t3) + cos(t3)*sin(t2),      cos(t2)*cos(t3) - sin(t2)*sin(t3), l1 + l3 + l4*sin(t2)]
[      0,      0,      0,      0]
0,      1]
```

He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0

C =

```
0      1      0      1      0      1      0      0
```

Dich chuyen theo truc x : 0

dx =

0

Dich chuyen theo truc y : 15

dy =

15

Dich chuyen theo truc z : 0

dz =

0

T =

```
[ cos(t1), sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1), cos(t2)*sin(t1)*sin(t3) + cos(t3)*sin(t1)*sin(t2), 15*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1)) - 14*cos(t2)*sin(t1)]
[ sin(t1), cos(t1)*cos(t2)*cos(t3) - cos(t1)*sin(t2)*sin(t3), - cos(t1)*cos(t2)*sin(t3) - cos(t1)*cos(t3)*sin(t2), 14*cos(t1)*cos(t2) - 15*(cos(t1)*sin(t2)*sin(t3) - cos(t1)*cos(t2)*cos(t3))]
[ 0, cos(t2)*sin(t3) + cos(t3)*sin(t2), cos(t2)*cos(t3) - sin(t2)*sin(t3), 11 + 13 + 15*(cos(t2)*sin(t3) + cos(t3)*sin(t2)) + 14*sin(t2)]
[ 0, 0, 0, 1]
```

He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)1

C =

0 1 0 1 0 1 0 1

Quay quanh tuc nao x/y/z: x

Q =

x

Gia tri quay quanh truc: t4

t =

t4

T =

```
[ cos(t1), cos(t4)*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1)) + sin(t4)*sin(t1),
```

```

(cos(t2)*sin(t1)*sin(t3) + cos(t3)*sin(t1)*sin(t2)), cos(t4)*(cos(t2)*sin(t1)*sin(t3)
+ cos(t3)*sin(t1)*sin(t2)) - sin(t4)*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin
(t1)), 15*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1)) - 14*cos(t2)*sin(t1)]
[ sin(t1), - cos(t4)*(cos(t1)*sin(t2)*sin(t3) - cos(t1)*cos(t2)*cos(t3)) - sin(t4)
(cos(t1)*cos(t2)*sin(t3) + cos(t1)*cos(t3)*sin(t2)), sin(t4)*(cos(t1)*sin(t2)*sin(t3)
- cos(t1)*cos(t2)*cos(t3)) - cos(t4)*(cos(t1)*cos(t2)*sin(t3) + cos(t1)*cos(t3)*sin
(t2)), 14*cos(t1)*cos(t2) - 15*(cos(t1)*sin(t2)*sin(t3) - cos(t1)*cos(t2)*cos(t3))]
[      0,                                cos(t4)*(cos(t2)*sin(t3) + cos(t3)*sin
(t2)) + sin(t4)*(cos(t2)*cos(t3) - sin(t2)*sin(t3))
cos(t4)*(cos(t2)*cos(t3) - sin(t2)*sin(t3)) - sin(t4)*(cos(t2)*sin(t3) + cos(t3)*sin
(t2)),                                11 + 13 + 15*(cos(t2)*sin(t3) + cos(t3)*sin(t2)) + 14*sin(t2)]
[      0,
0,
0,
0,
1]

```

He truc so Chuyen vi cua he truc, 0/1 (0:Tinh tien, 1:Quay)0

C =

```

0      1      0      1      0      1      0      1      0

```

Dich chuyen theo truc x : 0

dx =

```

0

```

Dich chuyen theo truc y : 16

dy =

```

16

```

Dich chuyen theo truc z : 0

dz =

```

0

```

T =

```

[ cos(t1), cos(t4)*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1)) + sin(t4)
(cos(t2)*sin(t1)*sin(t3) + cos(t3)*sin(t1)*sin(t2)), cos(t4)*(cos(t2)*sin(t1)*sin(t3)
+ cos(t3)*sin(t1)*sin(t2)) - sin(t4)*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin
(t1)), 15*(sin(t1)*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1)) + 16*(cos(t4)*(sin(t1)
*sin(t2)*sin(t3) - cos(t2)*cos(t3)*sin(t1)) + sin(t4)*(cos(t2)*sin(t1)*sin(t3) + co
(t3)*sin(t1)*sin(t2))) - 14*cos(t2)*sin(t1)]
[ sin(t1), - cos(t4)*(cos(t1)*sin(t2)*sin(t3) - cos(t1)*cos(t2)*cos(t3)) - sin(t4)

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```

(cos(t1)*cos(t2)*sin(t3) + cos(t1)*cos(t3)*sin(t2)), sin(t4)*(cos(t1)*sin(t2)*sin(t3)
- cos(t1)*cos(t2)*cos(t3)) - cos(t4)*(cos(t1)*cos(t2)*sin(t3) + cos(t1)*cos(t3)*sin
(t2)), 14*cos(t1)*cos(t2) - 16*(cos(t4)*(cos(t1)*sin(t2)*sin(t3) - cos(t1)*cos(t2)*
*cos(t3)) + sin(t4)*(cos(t1)*cos(t2)*sin(t3) + cos(t1)*cos(t3)*sin(t2))) - 15*(cos
(t1)*sin(t2)*sin(t3) - cos(t1)*cos(t2)*cos(t3))]
[      0,      cos(t4)*(cos(t2)*sin(t3) + cos(t3)*sin
(t2)) + sin(t4)*(cos(t2)*cos(t3) - sin(t2)*sin(t3))
cos(t4)*(cos(t2)*cos(t3) - sin(t2)*sin(t3)) - sin(t4)*(cos(t2)*sin(t3) + cos(t3)*sin
(t2)),      11 + 13 + 15*(cos(t2)*sin(t3) +
cos(t3)*sin(t2)) + 14*sin(t2) + 16*(cos(t4)*(cos(t2)*sin(t3) + cos(t3)*sin(t2)) + sin
(t4)*(cos(t2)*cos(t3) - sin(t2)*sin(t3)))]
[      0,
0,
0,
1]

```

ans =

```

[ cos(t1), -cos(t2 + t3 + t4)*sin(t1), sin(t2 + t3 + t4)*sin(t1), -sin(t1)*(15*cos
(t2 + t3) + 14*cos(t2) + 16*cos(t2 + t3 + t4))]
[ sin(t1), cos(t2 + t3 + t4)*cos(t1), -sin(t2 + t3 + t4)*cos(t1), cos(t1)*(15*cos
(t2 + t3) + 14*cos(t2) + 16*cos(t2 + t3 + t4))]
[      0,      sin(t2 + t3 + t4),      cos(t2 + t3 + t4),      11 + 13 + 15*sin
(t2 + t3) + 14*sin(t2) + 16*sin(t2 + t3 + t4)]
[      0,      0,      0]
1]

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