


Conventions:

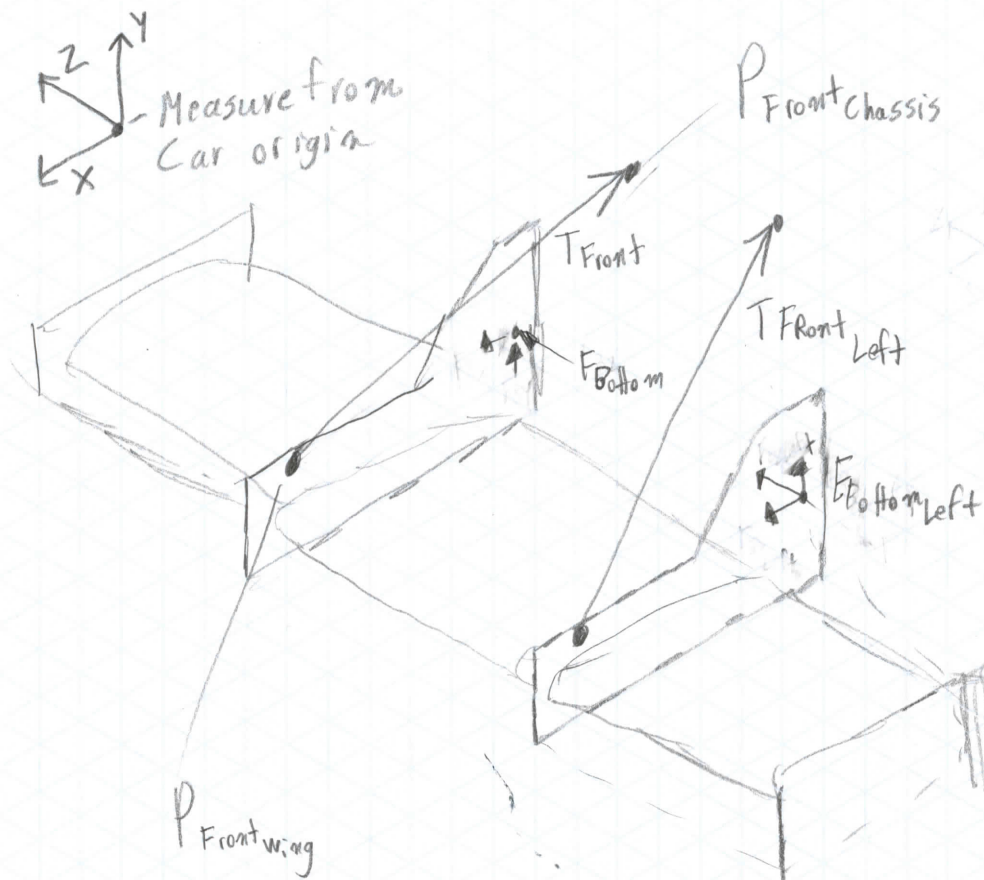
- Naming:

- P : a point, measured from origin. Vector.
- L : a line of action, but NOT a unit vector. Vector.
- T : a tension force which acts along a line of action. Scalar
- F : a vector force.

- FBD odds

 : a 3D vector force

Front Aero Mount Analysis



System: Front Wing

Time: Rate

Property: Lin. Momentum

$$\frac{d}{dt} \vec{p}_{sys} = \sum \vec{F} + \sum \dot{m} \vec{v} \rightarrow 0$$

$$\downarrow$$

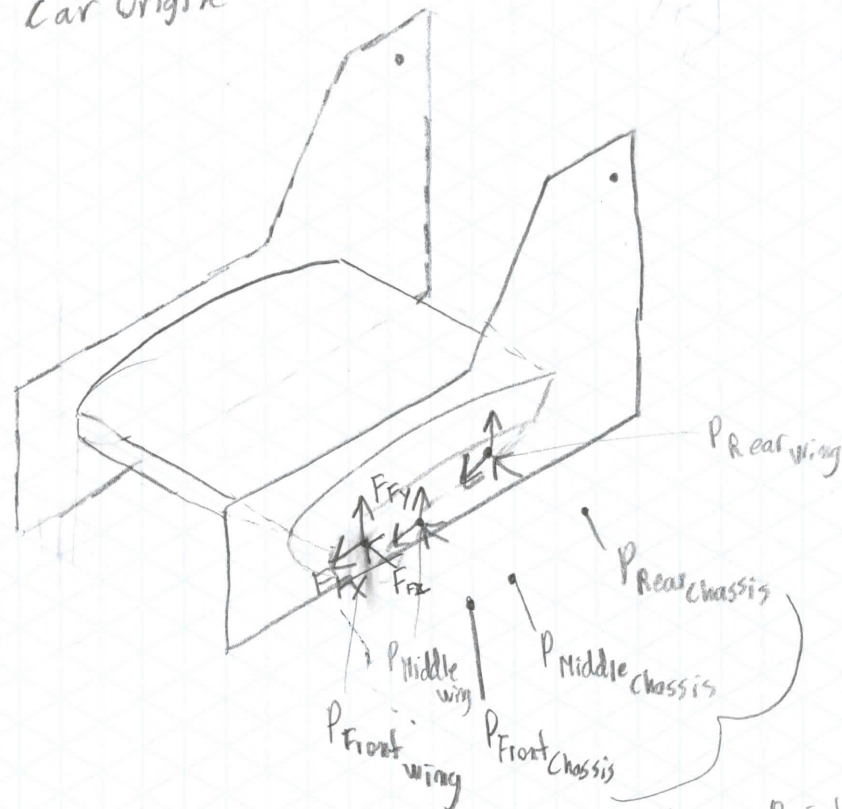
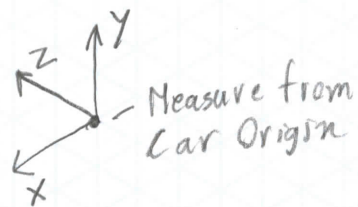
$$m \vec{a} = \sum \vec{F}$$

Property: Ang. Momentum About Car origin

$$\frac{d}{dt} \vec{L}_{sys} = \sum \vec{M} + \sum \dot{m} (\vec{r} \times \vec{v}) \rightarrow 0$$

$$\underline{m(\vec{\omega} \times \vec{a}) = \sum \vec{r} \times \vec{F}}$$

Side Aero Mount Analysis



System: Side Wing

Time: Rate

Property: Lin. Momentum

$$\frac{d}{dt} \vec{P}_{sys} = \sum \vec{F} + \sum m \vec{v}$$

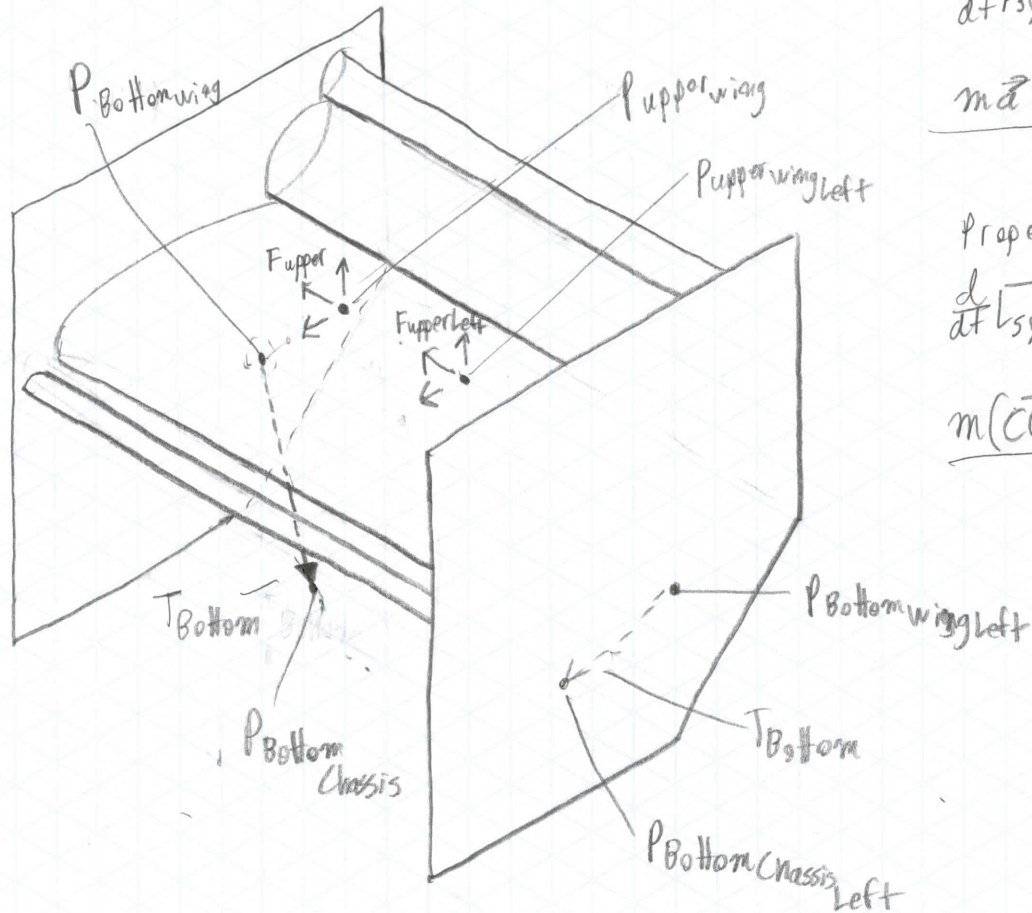
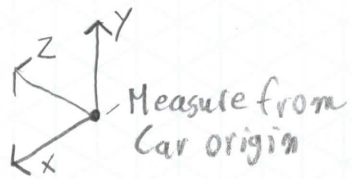
$$m \vec{a} = \sum \vec{F}$$

Property: Ang. Momentum About Car origin

$$\frac{d}{dt} \vec{L}_{sys} = \sum \vec{M} + \sum m (\vec{r} \times \vec{v})$$

$$m(\vec{COM} \times \vec{a}) = \sum \vec{r} \times \vec{F}$$

Rear Aero Mount Analysis



System: Rear Wing

Time: Rate

Property: Lin. Momentum

$$\frac{d}{dt} \vec{p}_{sys} = \sum \vec{F} + \sum \dot{m} \vec{v}$$

$$\downarrow$$

$$m \vec{a} = \sum \vec{F}$$

Property: Ang. Momentum About Car Origin

$$\frac{d}{dt} \vec{L}_{sys} = \sum \vec{\tau} + \sum \dot{m} (\vec{r} \times \vec{v})$$

$$m(\vec{COM} \times \vec{a}) = \sum \vec{r} \times \vec{F}$$