



Numerical  
Analysis

by Csaba  
Gáspár

Interpolation

Bivariate,  
scattered data  
interpolation

Shepard's  
method

The method of  
radial basis  
functions

# Numerical Analysis

## Scattered data interpolation problems

by Csaba Gáspár

Széchenyi István University

2020, autumn semester



# The problem of scattered data interpolation

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Let  $x_1, x_2, \dots, x_N \in \mathbf{R}^2$  be given locations on the plane (**interpolation points**), and let  $f_1, f_2, \dots, f_N \in \mathbf{R}$  be some predefined values associated to the interpolation points.

## The basic problem of interpolation

Find a function  $f : \mathbf{R}^2 \rightarrow \mathbf{R}$  (*as smooth as possible*) **interpolation function**, which satisfies the **interpolation conditions**:

$$f(x_k) = f_k \quad (k = 1, 2, \dots, N)$$

No special structure (grid of mesh) of the interpolation points is assumed.



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# The Shepard method

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## Shepard's method

If  $x$  is not an interpolation point, then:

$$f(x) := \frac{\sum_{j=1}^N f_j \cdot \frac{1}{\|x - x_j\|^p}}{\sum_{j=1}^N \frac{1}{\|x - x_j\|^p}} \quad (p > 0; \text{ usually } p = 2 \text{ or } p = 4)$$

For arbitrary interpolation point  $x_k$ :  $f(x) \rightarrow f_k$  whenever  $x \rightarrow x_k$ ; moreover, the partial derivatives tend to zero:  $\partial_1 f(x), \partial_2 f(x) \rightarrow 0$ .



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## ■ Low accuracy

- The computational cost is moderate: at each point of evaluation,  $\mathcal{O}(N)$  arithmetic operations are necessary
- Numerically stable

- If  $\|x\| \rightarrow +\infty$ , then  $f(x) \rightarrow \frac{1}{N} \cdot \sum_{j=1}^N f_j$



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# The Shepard method, example

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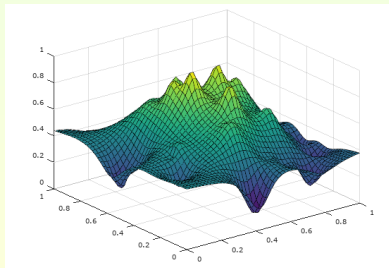
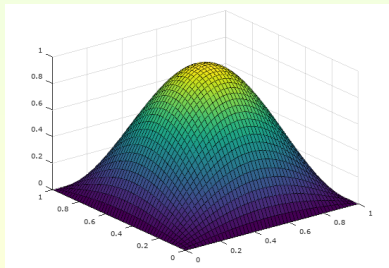
Shepard's  
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The method of  
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Test function:

$$f(x, y) := \sin \pi x \cdot \sin \pi y$$

defined on the unit square  $\Omega := \{(x, y) \in \mathbf{R}^2 : 0 \leq x, y \leq 1\}$ .  
30 interpolation points has been defined in the unit square in a random way.



Test function and Shepard interpolant (with  $p = 2$ ).



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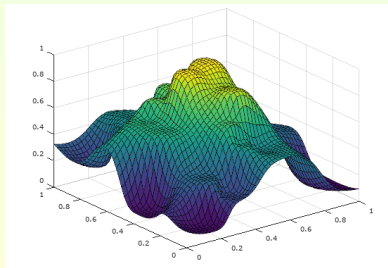
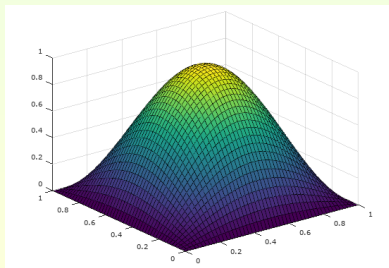
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Test function and Shepard interpolant (with  $p = 4$ ).



# The method of radial basis functions

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## The method of radial basis functions

Seek the interpolation function is the following form:

$$f(x) := \sum_{j=1}^N \alpha_j \cdot \Phi(x - x_j)$$

The a priori unknown coefficients  $\alpha_j$  can be computed by solving the system of interpolation equations:

$$\sum_{j=1}^N \alpha_j \cdot \Phi(x_k - x_j) = f_k \quad (k = 1, 2, \dots, N)$$



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Some usual choices of  $\Phi$ :

- $\Phi(x) := \sqrt{\|x\|^2 + c^2}$  (Method of multiquadrics, MQ)
- $\Phi(x) := \frac{1}{\sqrt{\|x\|^2 + c^2}}$  (Inverse multiquadrics, iMQ)
- $\Phi(x) := \|x\|^2 \cdot \log \|x\|$  (Thin plate splines, TPS)
- $\Phi(x) := e^{-c^2\|x\|^2}$  (Gauss functions)



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- Very good accuracy
  - At each point of evaluation, the number of necessary arithmetic operations is  $\mathcal{O}(N)$ , but the computational cost of the calculation of the coefficients is  $\mathcal{O}(N^3)$
  - In general, the calculation of the coefficients lead to a system of equations with fully populated and extremely ill-conditioned matrix.



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# The MQ-method, example

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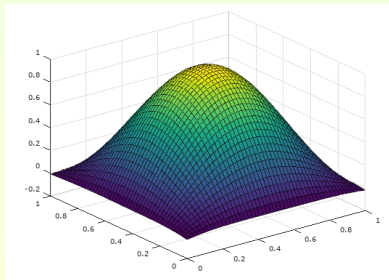
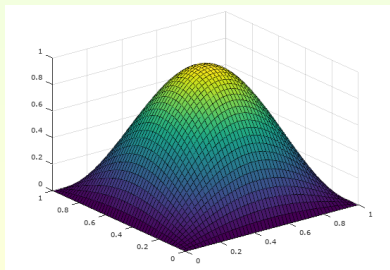
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30 interpolation points has been defined in the unit square in a random way.



Test function and MQ-interpolant (with parameter  $c = 1$ ).