Data structure and Algorithms Graph

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Outline

Shortest paths

- Introduction
- Applications
- Dijkstra's algorithm

Minimum spanning trees

- ◆ Introduction
- Applications
- Kruskal algorithm



Weighted graphs

- Let G be a weighted path, the length of a path is the sum of the weighted of the edges of P.
- If a path $P = ((v_0, v_1), (v_1, v_2), \dots, (v_{k-1}, v_k))$

$$w(P) = \sum_{i=0}^{k-1} w((v_i, v_{i+1}))$$

 A distance from a vertex v to a vertex u in G d(v,u) is the length of the minimum length path (shortest path) from v to u if the path exists

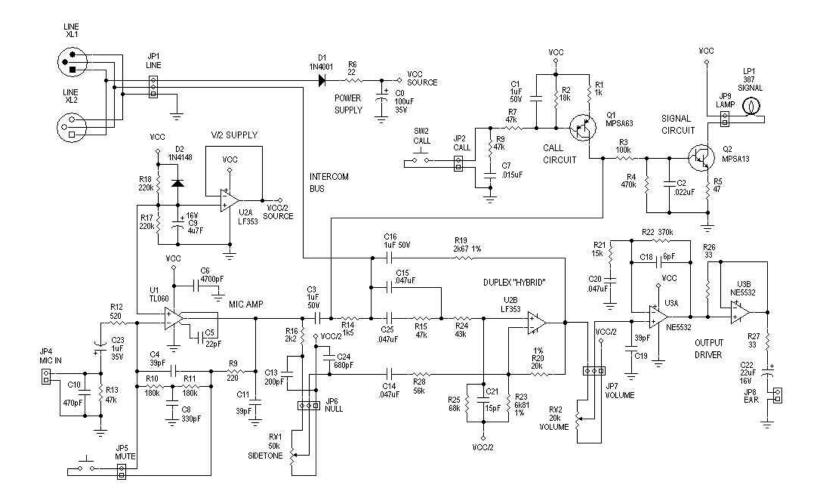


Shortest Path

- Given a weighted directed graph, one common problem is finding the shortest path between two given vertices
- Recall that in a weighted graph, the *length* of a path is the sum of the weights of each of the edges in that path
- Applications:
 - One application is circuit design: the time it takes for a change in input to affect an output depends on the shortest path

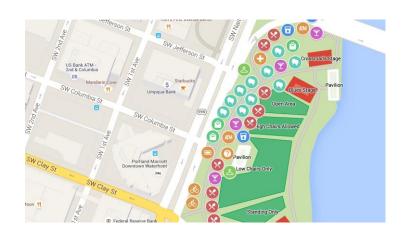


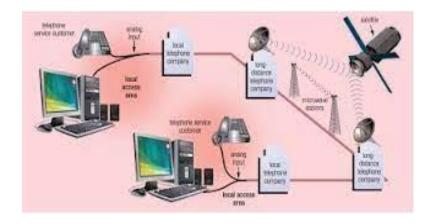
Applications





Applications







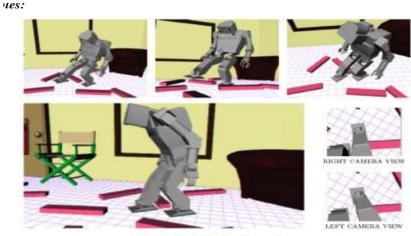


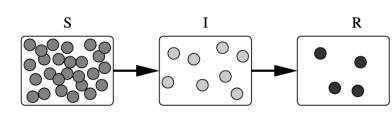
Fig. 1: Path Finding Examples

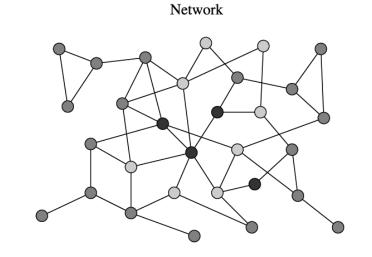


Applications of Dijkstra's Algorithm

Epidemiology:

- networks to model the spread of infectious diseases and design prevention and response strategies.
- Vertices represent individuals, and edges their possible contacts. It is useful to calculate how a particular individual is connected to others.
- Knowing the shortest path lengths to other individuals can be a relevant indicator of the potential of a particular individual to infect others.







Shortest paths

- BFS (breadth-first search) can be used to find a shortest path from some starting vertex to every other vertex in a connected graph
- This approach makes sense in cases where each edge is as good as any other,
- But there are many situations where this approach is not appropriate

Examples:

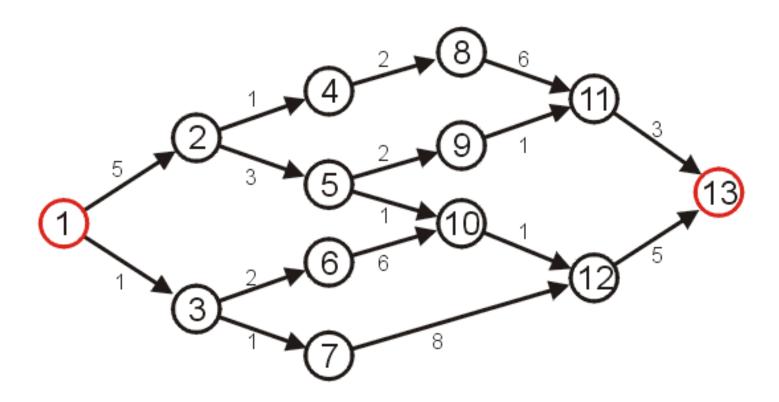
- Computer network: edges can be slow phone-line connections, high-speed, fiber-optic connections
- Intercity road network: inter-city distances are different
- They are connected, weighted graphs



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Shortest Path

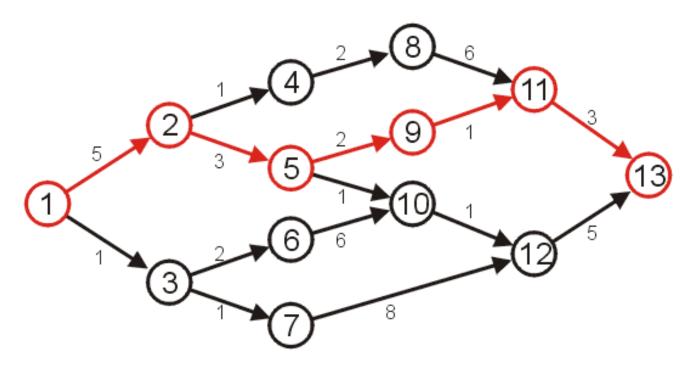
 Given the graph below, suppose we wish to find the shortest path from vertex 1 to vertex 13





Shortest Path

 After some consideration, we may determine that the shortest path is as follows, with length 14

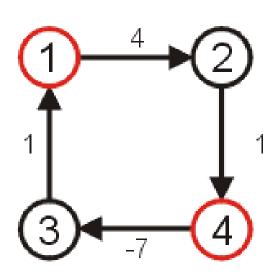


Other paths exists, but they are longer



Negative Cycles

- Clearly, if we have negative edges, it may be possible to end up in a cycle whereby each pass through the cycle decreases the total *length*
- Thus, a shortest length would be undefined for such a graph
- Consider the shortest path from vertex 1 to 4...
- We will only consider nonnegative weights.

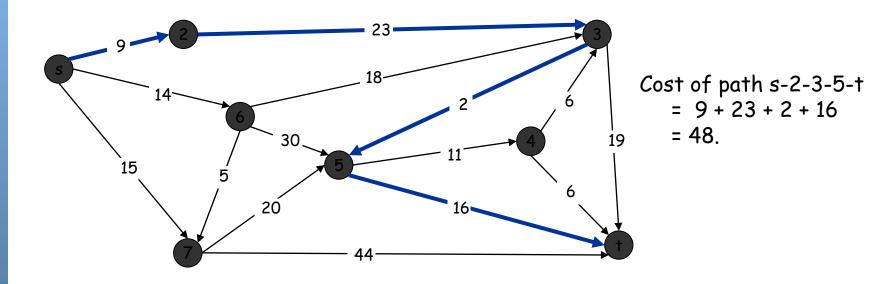




Shortest Path Example

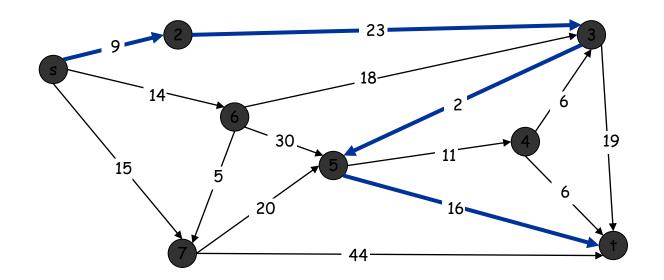
Given:

- Weighted Directed graph G = (V, E).
- Source s, destination t.
- Find shortest directed path from s to t.



Discussion Items

- How many possible paths are there from s to t?
- Can we safely ignore cycles? If so, how?
- Any suggestions on how to reduce the set of possibilities?
- Can we determine a lower bound on the complexity like we did for comparison sorting?





Key Observation

- A key observation is that if the shortest path contains the node v, then:
 - It will only contain v once, as any cycles will only add to the length => NO CYCLE
 - The path from s to v must be the shortest path to v from s.
 - The path from v to t must be the shortest path to t from v.
- Thus, if we can determine the shortest path to all other vertices that are incident to the target vertex we can easily compute the shortest path.
 - Implies a set of sub-problems on the graph with the target vertex removed.



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Edsger Wybe Dijkstra

- May 11, 1930 August 6, 2002
- Received the 1972 A. M. Turing Award, widely considered the most prestigious award in computer science
- The Schlumberger Centennial Chair of Computer Sciences at The University of Texas at Austin from 1984 until 2000
- Made a strong case against use of the GOTO statement in programming languages and helped lead to its deprecation
- Known for his many essays on programming

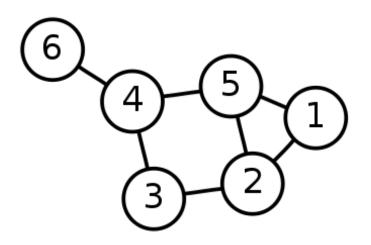


Edsger Wybe Dijkstra



Single-Source Shortest Path Problem

Single-Source Shortest Path Problem: The problem of finding shortest paths from a source vertex v to all other vertices in the graph.





Dijkstra's algorithm

<u>Dijkstra's algorithm</u> - is a solution to the single-source shortest path problem in graph theory.

Works on both directed and undirected graphs. However, all edges must have nonnegative weights.

Approach: Greedy

Input: Weighted graph G={E,V} and source vertex *v*∈V, such that all edge weights are nonnegative

Output: Lengths of shortest paths (or the shortest paths themselves) from a given source vertex *v*∈V to all other vertices



Dijkstra's algorithm

```
d[s] \leftarrow 0
for each v \in V - \{s\}
    do d[v] \leftarrow \infty
S \leftarrow \emptyset
Q \leftarrow V \triangleright Q is a priority queue maintaining V - S
while Q \neq \emptyset
    do u \leftarrow \text{Extract-Min}(Q)
         S \leftarrow S \cup \{u\}
         for each v \in Adj[u]
              do if d[v] > d[u] + w(u, v)
                       then d[v] \leftarrow d[u] + w(u, v)
                       p[v] \leftarrow u
```

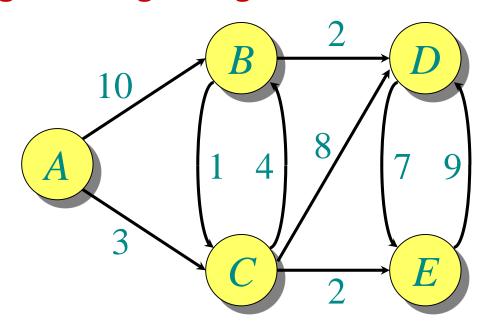


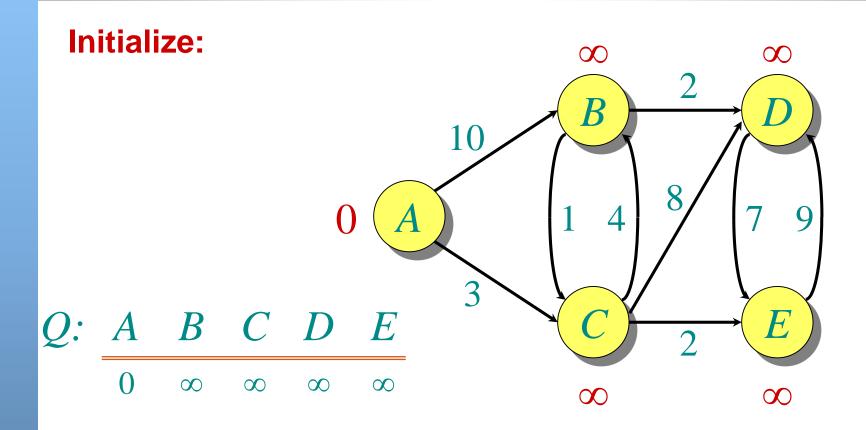
Dijkstra's algorithm

```
d[s] \leftarrow 0
for each v \in V - \{s\}
    do d[v] \leftarrow \infty
S \leftarrow \varnothing
Q \leftarrow V \triangleright Q is a priority queue maintaining V - S
while Q \neq \emptyset
    do u \leftarrow \text{Extract-Min}(Q)
         S \leftarrow S \cup \{u\}
         for each v \in Adj[u]
                                                         relaxation
              do if d[v] > d[u] + w(u, v)
                       then d[v] \leftarrow d[u] + w(u, v) step
                      p[v] \leftarrow u
```



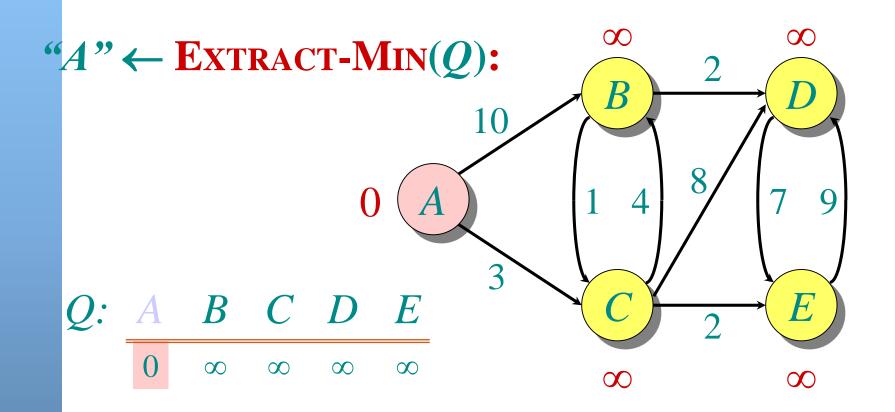
Graph with nonnegative edge weights:





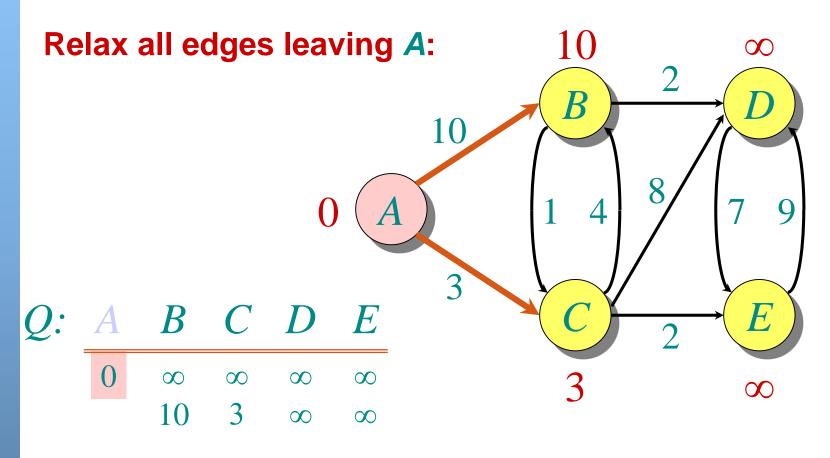






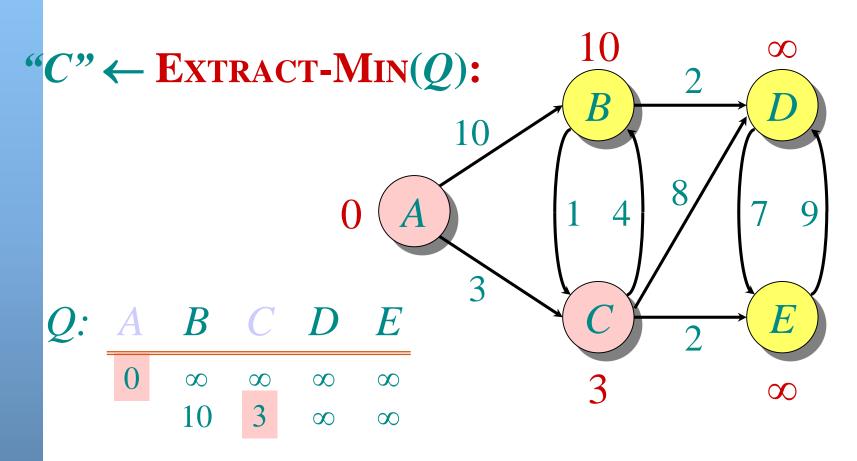
S: { A }



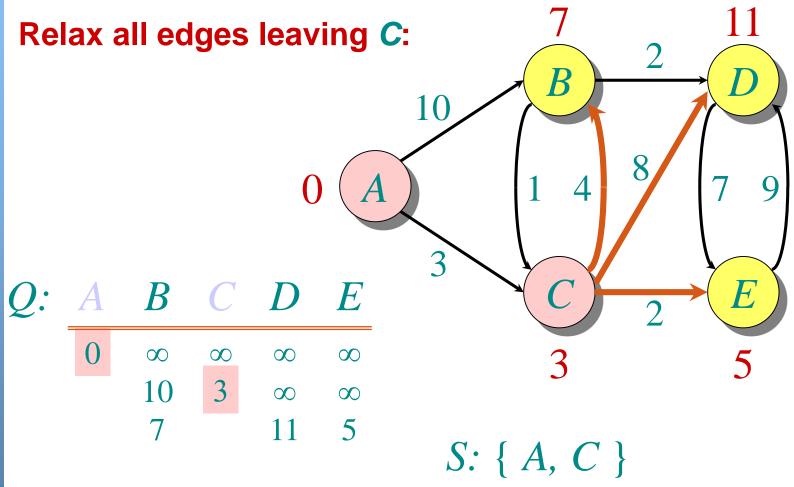




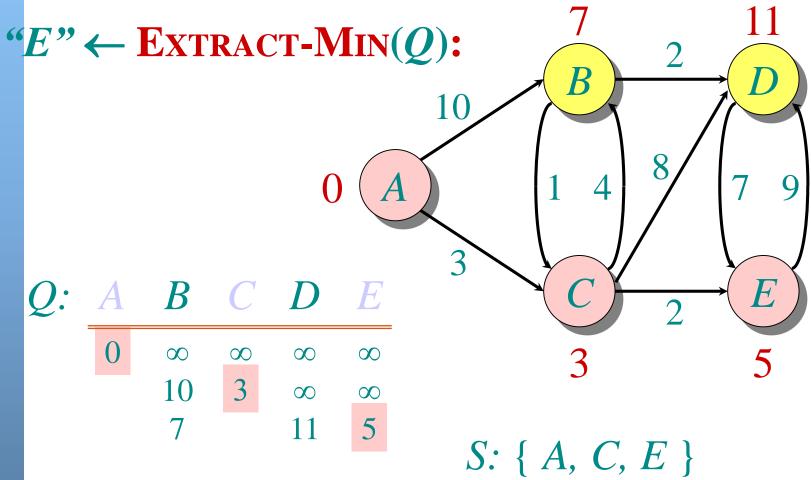




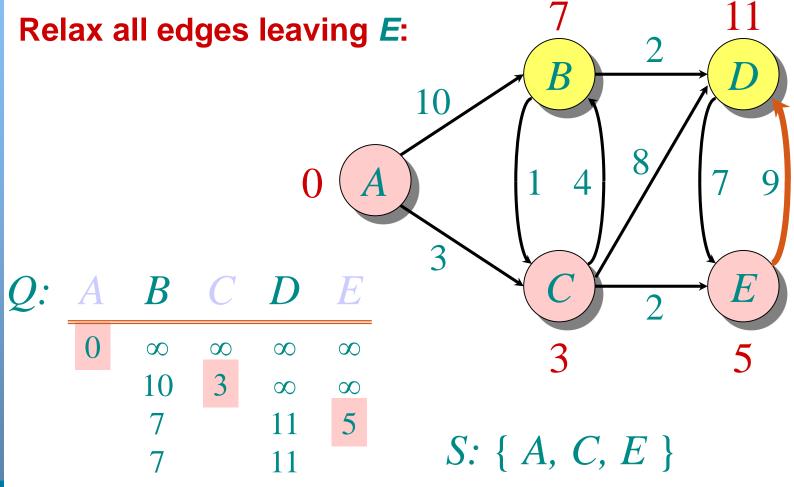




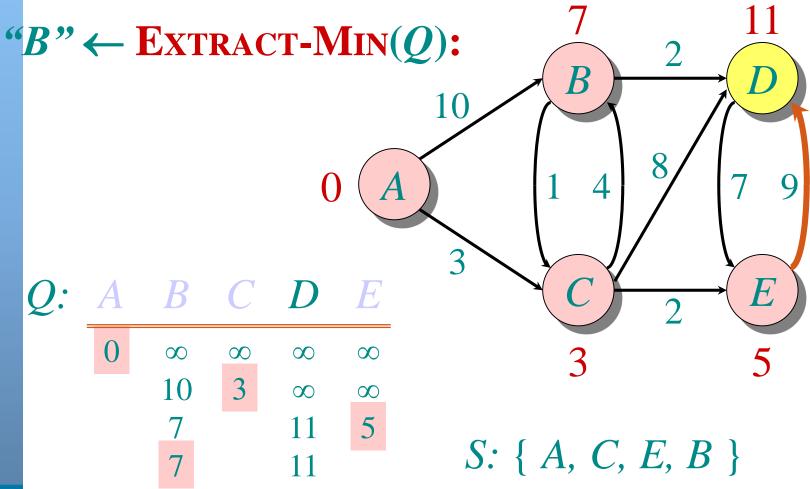




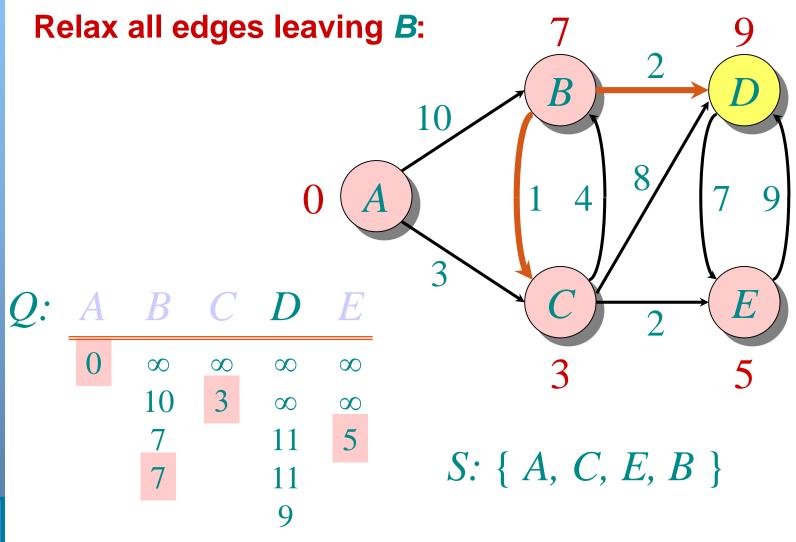




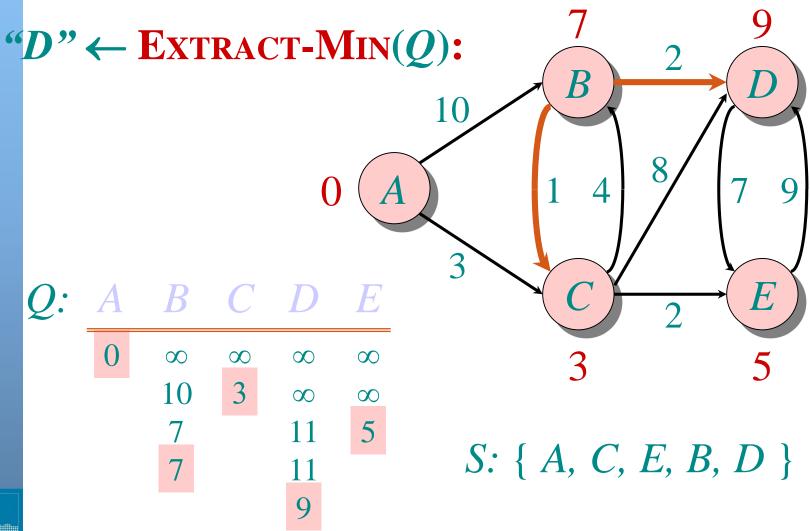




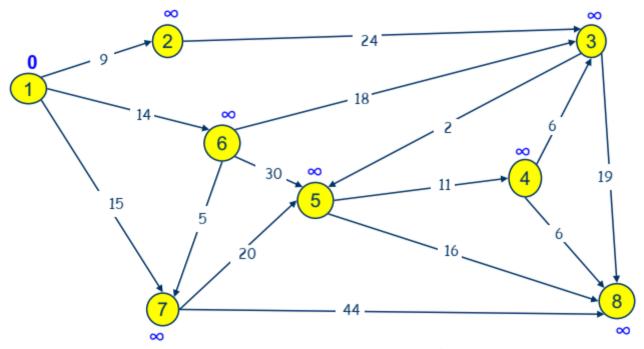




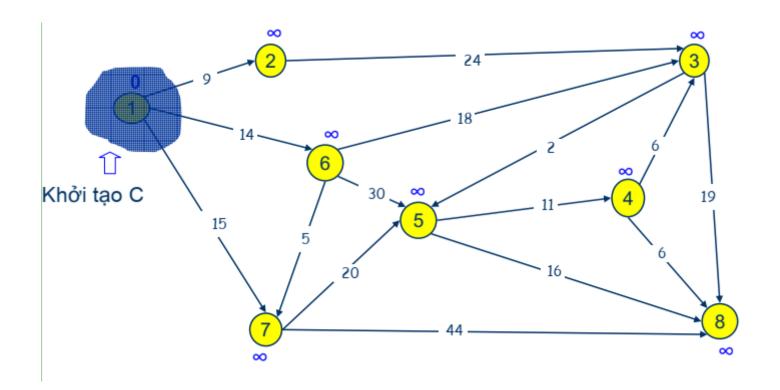


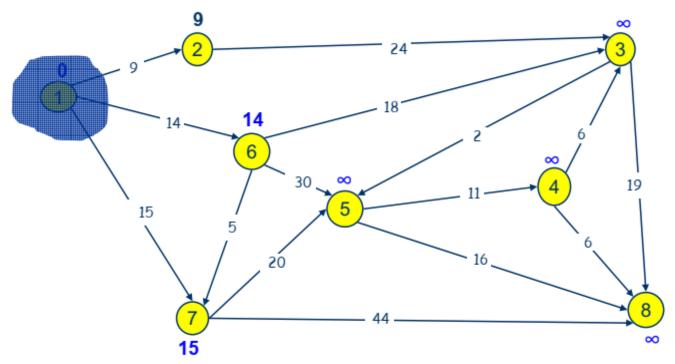




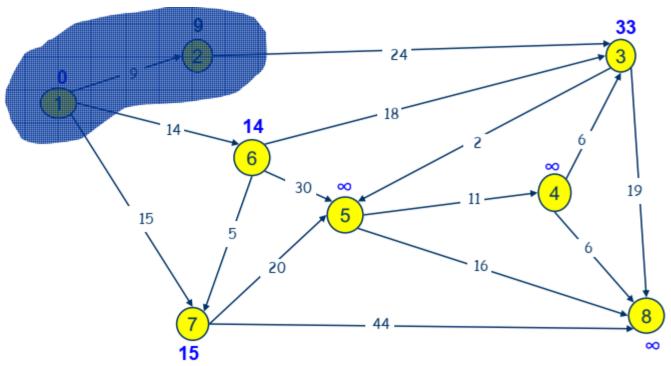


Khởi tạo các giá trị d cho tất cả các đỉnh



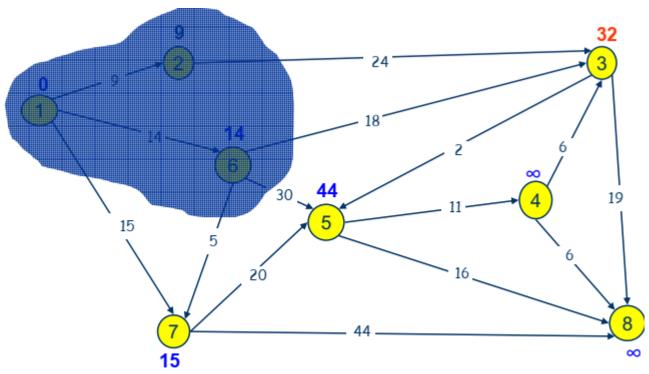


Cập nhật các giá trị d[2] = 9, d[6] = 14, d[7] = 15



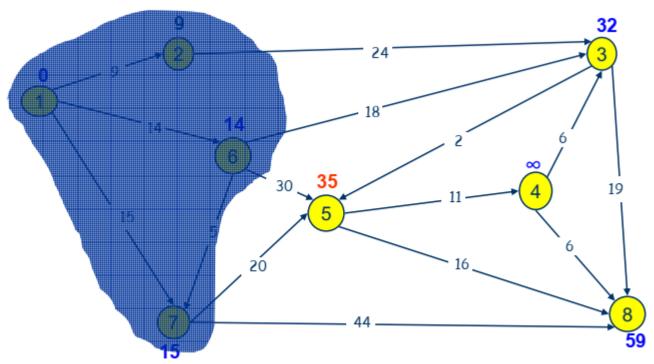
Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 2 có độ dài 9 Cập nhật giá trị d của các đỉnh lân cận của 2





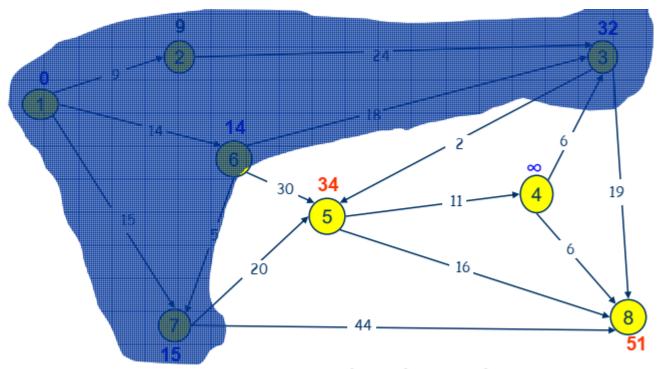
Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 6 có độ dài 14 Cập nhật giá trị d của các đỉnh lân cận với 6





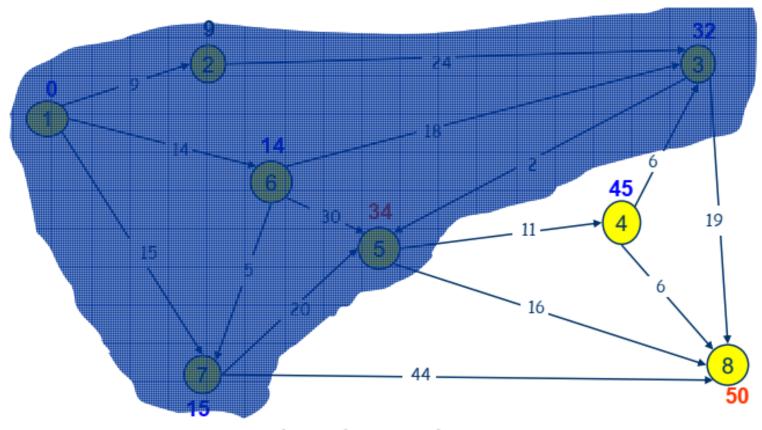
Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 7 có độ dài 15 Cập nhật giá trị d của các đỉnh lân cận với 7





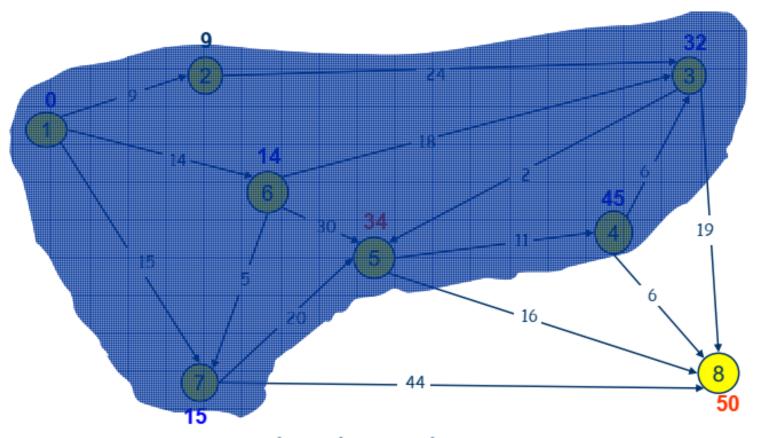
Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 3 có độ dài 32, đi qua 6 Cập nhật giá trị d của các đỉnh lân cận với 3





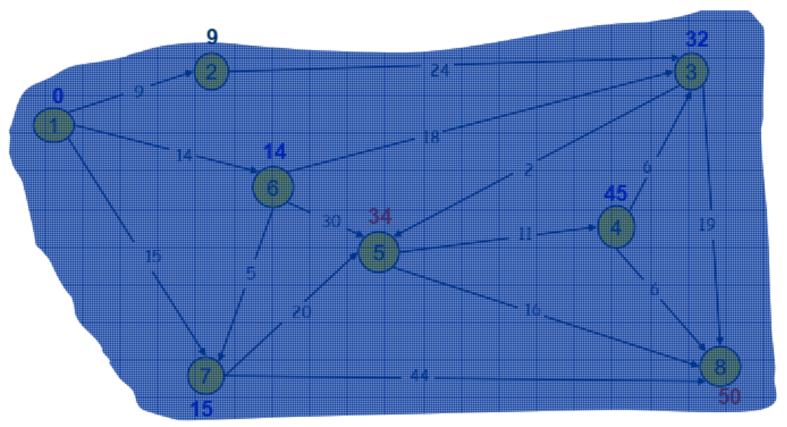
Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 5 có độ dài 34, đi qua 6,3 Cập nhật giá trị d của các đỉnh lân cận với 5





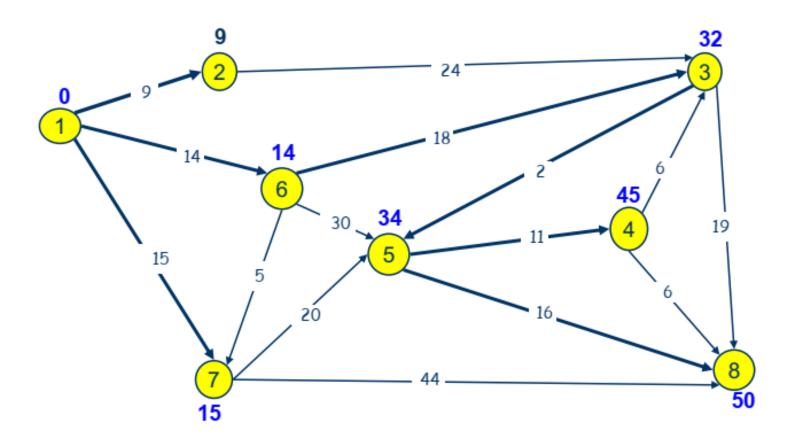
Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 4 có độ dài 45, đi qua 6,3,5 Cập nhật giá trị d của các đỉnh lân cận với 4





Mở rộng cụm C, đường đi ngắn nhất từ 1 đến 8 có độ dài 50, đi qua 1,6,3,5







Outline

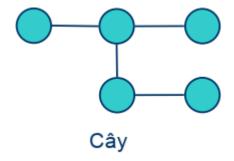
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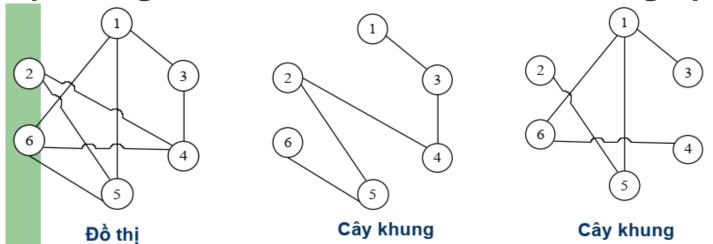
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Spanning tree

Tree: undirected graph, no cycle



In an undirected and connected graph: a spanning tree contains all vertices of the graph



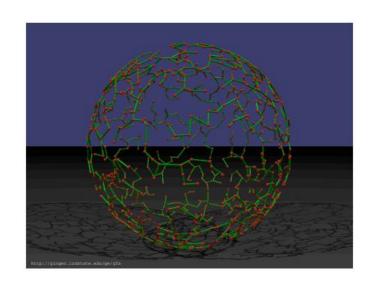
Minimum Spanning Tree

- A minimum spanning tree (MST) is defined as a spanning tree with weight less than or equal to the weight of every other spanning tree.
- A minimum spanning tree is a spanning tree that has weights associated with its edges, and the total weight of the tree (the sum of the weights of its edges) is at a minimum



MST applications

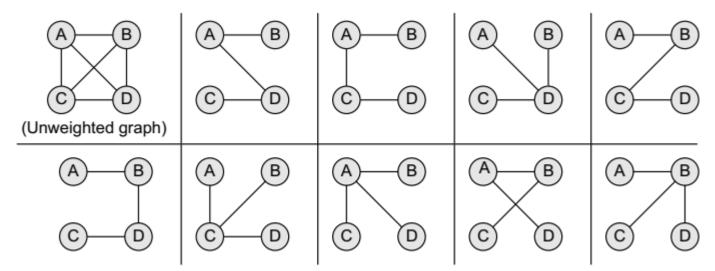
- MSTs are widely used for designing networks
- MSTs are used to find airline routes
- MSTs are used to find airline routes
- MSTs are applied in routing algorithms for finding the most efficient path





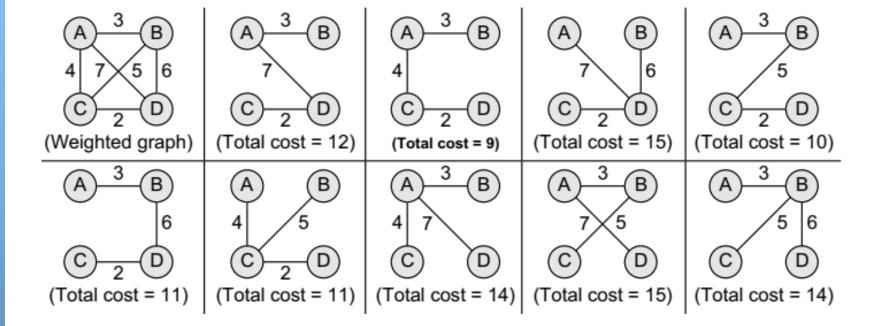
Properties

- Possible multiplicity
- Uniqueness
- Minimum-cost subgraph
- Cycle property
- Usefulness
- Simplicity





Properties



Kruskal's algorithm

```
Step 1: Create a forest in such a way that each graph is a separate tree.

Step 2: Create a priority queue Q that contains all the edges of the graph.

Step 3: Repeat Steps 4 and 5 while Q is NOT EMPTY

Step 4: Remove an edge from Q

Step 5: IF the edge obtained in Step 4 connects two different trees, then Add it to the forest (for combining two trees into one tree).

ELSE

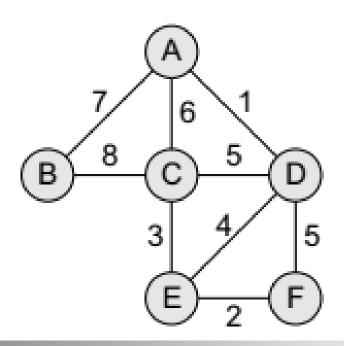
Discard the edge

Step 6: END
```



Kruskal's algorithm

- Init:
 - ◆ F = {{A}, {B}, {C}, {D}, {E}, {F}}
 - ◆ MST = {}
 - Q = {(A, D), (E, F), (C, E), (E, D), (C, D), (D, F), (A, C), (A, B), (B, C)}

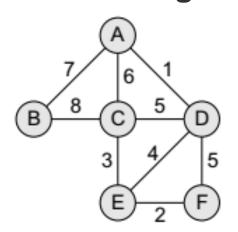




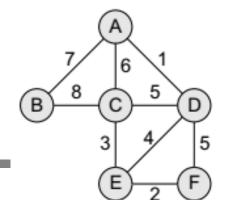
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Kruskal's algorithm

Step 1: remove edge (A,D) from Q and make following changes:

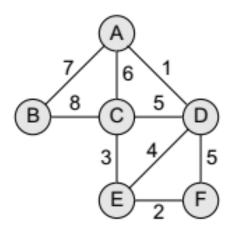


Step 2: Remove (E, F) from Q and make following changes



Giải thuật Kruskal

Step 4: Remove (E,D) from Q and make changes:



Step 5: Remove (C,D) from Q and do:

$$F = \{\{A, C, D, E, F\}, \{B\}\}\}$$

$$MST = \{(A, D), (C, E), (E, F), (E, D)\}$$

$$Q = \{(D, F), (A, C), (A, B), (B, C)\}$$



Giải thuật Kruskal

Step 6: Remove (D,F)

$$F = \{\{A, C, D, E, F\}, \{B\}\}\}$$

$$MST = \{(A, D), (C, E), (E, F), (E, D)\}$$

$$Q = \{(A, C), (A, B), (B, C)\}$$

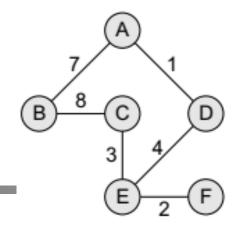
Step 7: Remove (A,C)

$$F = \{\{A, C, D, E, F\}, \{B\}\}\}$$

$$MST = \{(A, D), (C, E), (E, F), (E, D)\}$$

$$Q = \{(A, B), (B, C)\}$$

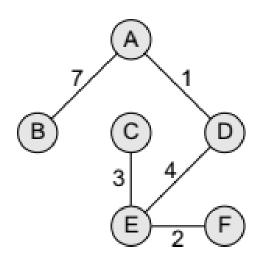
Step 8: Remove (A,B)





Giải thuật Kruskal

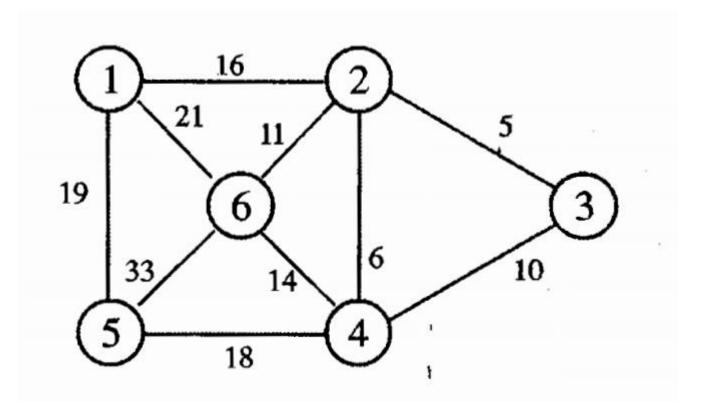
Step 9: Continue until Q = empty





Exercise

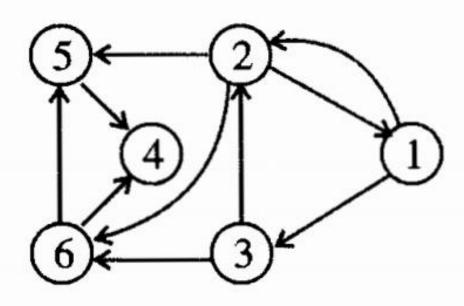
Find MST





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Exercise



Find Shortest Paths using Dijkstra's algorithm



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Assignment

- WAP to
 - Initialize a undirected weighted graph G(V,E)
 - BSF algo
 - DSF algo
 - Find the MST using Kruskal's algo
 - Find shortest paths from a source vertex to a destination vertex using Dijkstra's algo



References

- Slide– Nguyễn Thanh Bình ĐTVT
- Slide Đỗ Bích Diệp
- Chapter 13 Graph Data structure in C Rema Thareja – 2014
- Slide: CSE 680 Prof. Roger Crawfis

