

Optimization over Orbit Closures of Real Reductive Lie Group Actions

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1 Introduction

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Matrix Scaling [Sinkhorn 1964]

Given $A = (a_{ij}) \in M_n(\mathbb{R})$ with $a_{ij} \geq 0$,

- A is *almost doubly stochastic scalable* if $\forall \varepsilon > 0, \exists$ positive diagonal X, Y s.t. $B = XAY$ satisfies

$$\|B\mathbf{1} - \mathbf{1}\|_2 < \varepsilon, \quad \|B^T\mathbf{1} - \mathbf{1}\|_2 < \varepsilon$$

where $\mathbf{1} = (1, \dots, 1)^T \in \mathbb{R}^n$.

Remark: In short, we say A is almost scalable.

Theorem (Rothblum and Schneider 1989)

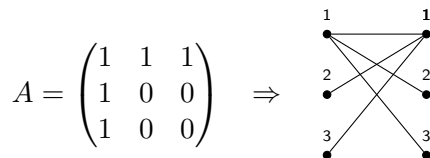
A is almost scalable if and only if for every zero minor $I \times J$ of A ,

$$|I| + |J| \leq n$$

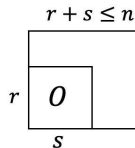
Connection with Graph Theory

Given $A = (a_{ij}) \in M_n(\mathbb{R})$:

- Bipartite graph $G_A = ([n] \cup [n], E)$: $(i, j) \in E \Leftrightarrow a_{ij} \neq 0$;



- Hall's theorem: G_A has a perfect matching \Leftrightarrow



- [RS89]: G_A has a perfect matching $\Leftrightarrow A$ is almost scalable

From Invariant Theory

Let $G = ST(n) \times ST(n)$ act on $V = M(n, \mathbb{R})$, that is

$$\pi: G \longrightarrow GL(V)$$

where $ST(n) = \left\{ \text{diag}(t_1, \dots, t_n) : t_j \in \mathbb{R} \setminus \{0\}, \prod_{j=1}^n t_j = 1 \right\}$.

$$\pi(X, Y)A := XAY, \forall (X, Y) \in G$$

Problem: Null Cone Membership

$$0 \in \overline{\pi(G)A}?$$

By Hilbert-Mumford Criterion [[Hil93](#); [MFK94](#)] and [[RS89](#)],

Invariant Theoretic View

$$A \text{ is almost scalable} \Leftrightarrow 0 \notin \overline{\pi(G)A}.$$

Optimization over Orbit Closure

The *Kempf-Ness function* of $A = (a_{ij}) \in M_n(\mathbb{R})$,

$$f_A(x, y) = \log \left(\frac{(x^T A y)^n}{\prod_{i=1}^n x_i \prod_{j=1}^n y_j} \right) : (\mathbb{R}^+)^n \times (\mathbb{R}^+)^n \rightarrow \mathbb{R}$$

- $0 \notin \overline{\pi(G)A} \Leftrightarrow \inf f_A > -\infty$
- $x_i = e^{s_i}, y_j = e^{t_j},$

$$\nabla f_A(s, t) \sim \text{const} \times (\text{Row sums} - \mathbf{1}, \text{Column sums} - \mathbf{1})$$

Observation

$$A \text{ is almost scalable} \Leftrightarrow \inf f_A > -\infty \Leftrightarrow 0 \in \overline{\nabla f(\mathbb{R}^n \times \mathbb{R}^n)}$$

Operator Scaling [Gurvits 2004]

Let $G = SL(n, \mathbb{C}) \times SL(n, \mathbb{C})$ act $V = M(n, \mathbb{C})^{\oplus m}$ by

$$\pi(g, h)(A_1, \dots, A_m) := (gA_1h^\dagger, \dots, gA_mh^\dagger)$$

$A = (A_1, \dots, A_m)$ is *almost scalable* for if $\forall \varepsilon > 0, \exists g, h$ s.t.

$$\left\| \sum_{i=1}^m gA_ih^\dagger hA_i^\dagger g^\dagger - I_n \right\|_F < \varepsilon, \quad \left\| \sum_{i=1}^m hA_i^\dagger g^\dagger gX_ih^\dagger - I_n \right\|_F < \varepsilon$$

Also by Hilbert-Mumford Criterion,

Theorem (Garg et al. 2020)

$$A \text{ is almost scalable} \Leftrightarrow 0 \notin \overline{\pi(G)A}.$$

Optimization: Given $A = (A_1, \dots, A_m)$,

$$f_A(g, h) = \log \|\pi(g, h)A\|, \quad g, h \in SL(n, \mathbb{C})$$

where $\|A\|^2 = \sum_i \|A_i\|_F^2$.

Theorem ([GGOW20])

$$A \text{ is almost scalable} \Leftrightarrow 0 \in \overline{\nabla f_A(G)} \Leftrightarrow \inf f_A > -\infty$$

Applications:

- Noncommutative PIT [GGOW20]:

$$p(x_1, \dots, x_n) : x_i x_j \neq x_j x_i \Rightarrow p(x_1, \dots, x_n) = 0?$$

- Brascamp–Lieb inequalities [GGOW18]:

$$\int_{\mathbb{R}^n} \prod_{i=1}^m f_i(B_i(x)) \, dx \leq C \prod_{i=1}^m \|f_i\|_{1/p_i}$$

Generalization [Bürgisser,Franks,Garg,Oliveira,Walter and Wigderson 2019]

- $G \subset GL(n, \mathbb{C})$: complex reductive group
- $V \simeq \mathbb{C}^m$ and $\pi: V \rightarrow GL(V)$: Given $0 \neq v \in V$

Problems

- **Null cone membership:** determine if $0 \in \overline{\pi(G)v}$
- **Norm minimization:** find g s.t. $\|\pi(g)v\| \rightarrow \inf \|\pi(g)v\|$
- **Scaling problem:** Kempf-Ness function $f_v \rightsquigarrow$ gradient ∇f_v
find g s.t. $\nabla f_v(g) \rightarrow 0$

Applications

- Horn's problem: A, B Hermitians \Rightarrow eigenvalues of $A + B$
- Quantum marginal, Orbit problems, invariant theory, $\dots\dots$

Previous Research [Bür+19]

Optimizing the Kempf-Ness function $f_v(g) := \log \|\pi(g)v\|$,

$$\inf_{g \in G} f_v(g)$$

- Smoothness of f_v : first order algorithm $\rightsquigarrow \nabla f_v(g_s) \rightarrow 0$
- Convexity of f_v : second order algorithm
- Norm minimization: quantizing the relationship

$$\nabla f_v(g) \rightarrow 0 \Leftrightarrow f_v(g) \rightarrow \inf_{g \in G} f_v(g)$$

- Nullcone membership, analyzing parameters,

This Thesis

Problem Settings

$G \subset GL(n, \mathbb{R}) \curvearrowright V \simeq \mathbb{R}^m$: real reductive Lie group actions

- Without considering the complex structure
- More general geometric structure of $P \simeq G/K$

Contributions: Extending some of results in [Bür+19] to G

- $f_v: P \rightarrow \mathbb{R}$ on a Riemannian manifold P .
- Smoothness and convexity of f_v .
- Riemannian optimization on f_v : RGD algorithm.
- Quantizing $\nabla f_v(g) \rightarrow 0 \Leftrightarrow f_v(g) \rightarrow \inf f_v(g)$ for real case.
- Analyzing a general scaling problem on P .

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Real Reductive Lie Group

Definition (Real Reductive Lie Group)

$G \subset GL(n, \mathbb{R})$ subgroup satisfies:

- $\exists f_1, \dots, f_l$ polynomials on $GL(n, \mathbb{R})$ s.t.

$$G = \{g \in GL(n, \mathbb{R}) : f_i(g) = 0, \forall i = 1, \dots, l\}$$

- $g \in G \Rightarrow g^T \in G$

Examples:

- 1 $GL(n, \mathbb{R}), O(n), SL(n, \mathbb{R}), SO(n, \mathbb{R}), ST(n), \dots$
- 2 $GL(n, \mathbb{C}), U(n), SL(n, \mathbb{C}), SU(n, \mathbb{C}), \dots$

Norm Minimization

Rational representation: (π, V)

- V : finite-dimesional \mathbb{R} -vector space with $\langle \cdot, \cdot \rangle$
- $\pi: G \rightarrow GL(V)$: group homomorphism

$$\pi(g)v = (\pi(g)_{ij}) v$$

s.t. $\pi(g)_{ij}$ is a polynomial in g and $\det g^{-1}$.

Norm Minization Problem

Given $\varepsilon > 0$, (π, V) of G , $v \in V$ with $0 \notin \overline{\pi(G)v}$, minimizing

$$\|\pi(g)v\|, \quad g \in G$$

Optimization

For $v \in V \setminus \{0\}$, define $\tilde{f}_v: G \rightarrow \mathbb{R}$

$$\tilde{f}_v(g) := \log \|\pi(g)v\|^2, \quad \forall g \in G$$

- Norm minimization \rightsquigarrow If $\tilde{f}_{v,\inf} := \inf_{g \in G} \tilde{f}_v(g) > -\infty$,

$$g \in G \Rightarrow \tilde{f}_v(g) - \tilde{f}_{v,\inf} < \varepsilon$$

- $K = G \cap O(n)$: maximal compact subgroup

$$\exists \langle \cdot, \cdot \rangle \text{ on } V \text{ s.t. } \langle \pi(k)v, \pi(k)w \rangle = \langle v, w \rangle, \quad \forall k \in K$$

$$\Rightarrow \tilde{f}_v: G/K \rightarrow \mathbb{R}$$

- Optimizing \tilde{f}_v on G/K : Riemannian optimization

Structure of G/K

G : real reductive Lie group with Lie algebra

$$\mathfrak{g} = \text{Lie}(G) := \{X \in M_n(\mathbb{R}) : e^{tX} \in G, \forall t \in \mathbb{R}\}$$

- $\mathfrak{p} := \mathfrak{g} \cap S_n = \{X \in \mathfrak{g} : X = X^T\}$: Cartan Decomposition

$$G \ni g = ke^X \quad (\exists k \in K, X \in \mathfrak{p})$$

$$\Rightarrow \mathfrak{g} = \mathfrak{k} + \mathfrak{p}, \quad \mathfrak{k} = \text{Lie}(K)$$

- $P := G \cap P(n) = \{g \in P(n) : g \in G\}$:

$$G/K \simeq P \quad ([ke^X] \mapsto e^X)$$

Settings in [Bür+19]: $G \subset GL(n, \mathbb{C})$, then $K = G \cap U(n)$, $\mathfrak{p} := i\mathfrak{k}$

Kempf-Ness Function

For any $v \in V \setminus \{0\}$, the Kempf-Ness Function f_v

$$\begin{aligned} f_v: P &\longrightarrow \mathbb{R} \cup \{\infty\} \\ x &\longmapsto \log \langle v, \pi(x)v \rangle \end{aligned}$$

- [RS90] $\exists \langle \cdot, \cdot \rangle$ on V s.t. $\pi(g)^T = \pi(g^T)$, $\forall g \in G$

$$f_v(g^T g) = \log \|\pi(g)v\|^2 = \tilde{f}_v(g)$$

- $\forall x \in P \subset G$, $x^{\frac{1}{2}} \in G$,

$$f_v(x) = \log \left\| \pi(x^{\frac{1}{2}})v \right\|^2 = \tilde{f}_v(x^{\frac{1}{2}})$$

Optimization

$$0 \notin \overline{\pi(G)v} \Leftrightarrow \inf_{x \in P} f_v(x) > -\infty$$

Riemannian Structure on P

$P = G \cap P(n) \simeq G/K$: Riemannian manifold

- $\langle \cdot, \cdot \rangle_{\mathfrak{p}}$ on \mathfrak{p} : $\langle X, Y \rangle_{\mathfrak{p}} = \text{tr}(XY) \rightsquigarrow \|\cdot\|_{\mathfrak{p}}$
- For $x \in P$, the tangent space at x is

$$T_x P := \left\{ x^{\frac{1}{2}} X x^{\frac{1}{2}} : X \in \mathfrak{p} \right\} \Rightarrow T_I P = \mathfrak{p}$$

- $\langle \cdot, \cdot \rangle_x$ on $T_x P$: $\rightsquigarrow \|\cdot\|_x$

$$\langle H_1, H_2 \rangle_x = \text{tr}(x^{-1} H_1 x^{-1} H_2), \quad \forall H_1, H_2 \in T_x P$$

Geodesic: starting at $x \in P$ with the direction $x^{\frac{1}{2}} X x^{\frac{1}{2}} \in T_x P$

$$\gamma_X(t) = x^{\frac{1}{2}} e^{tX} x^{\frac{1}{2}}, \quad t \in \mathbb{R}$$

Scaling Problem

For $x \in P$, the gradient $\nabla f_v(x) \in T_x P$ is

$$\left\langle \nabla f_v(x), x^{\frac{1}{2}} X x^{\frac{1}{2}} \right\rangle_x = \frac{d}{dt} \Big|_{t=0} f_v(x^{\frac{1}{2}} e^{tX} x^{\frac{1}{2}})$$

Theorem (Kempf-Ness Theorem)

$$f_{v,\inf} := \inf_{x \in P} f_v(x) > -\infty \Leftrightarrow \inf_{x \in P} \|\nabla f_v(x)\|_x = 0$$

Scaling Problem

Given $\varepsilon > 0$, (π, V) of G , $v \in V$ with $0 \in \overline{\nabla f_v(P)}$,

$$\text{find } x \in P \text{ s.t. } \|\nabla f_v(x)\|_x < \varepsilon$$

Norm Minimization and Scaling Problem

Given (π, V) of G and $\varepsilon > 0$, $v \in V$ s.t. $f_{v,\text{inf}} > -\infty$

- **Scaling Problem:** find $x \in P$ s.t.

$$\|\nabla f_v(x)\|_x < \varepsilon$$

- **Norm Minimization Problem:** find $x \in P$ s.t.

$$f_v(x) - f_{v,\text{inf}} < \varepsilon$$

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RGD Algorithm

Algorithm 1: Riemannian Gradient Descent

Input: Target function: $f: P \rightarrow \mathbb{R} \cup \{\infty\}$;

Step size: η ;

Number of iterations: T

Output: $x \in P$

```

1  $x_0 = I$ 
2 for  $t = 1$  to  $T$  do
3    $x_{t+1} = x_t^{\frac{1}{2}} e^{-\eta x_t^{-\frac{1}{2}} \nabla f(x_t) x_t^{-\frac{1}{2}}} x_t^{\frac{1}{2}}$ 
4 end
5  $x = \operatorname{argmin} \{x_t: \|\nabla f(x_t)\|_{x_t}\}$ 
6 return  $x_s$ 
```

c.f. N. Boumal, *An Introduction to Optimization on Smooth Manifolds*, 2022

Validity of RGD

Theorem ([Bou22] Corollary 4.9)

If $f_{\inf} := \inf_x f(x) > -\infty$ and f is L -smooth, then $\forall \varepsilon > 0$, by setting

$$\eta = \frac{1}{L}, \quad T > \frac{2L}{\varepsilon^2} (f(I) - f_{\inf})$$

in RGD, it can get

$$\|\nabla f(x)\|_x < \varepsilon$$

Remark: $f: P \rightarrow \mathbb{R} \cup \{\infty\}$ is called L -smooth if for any $x \in P$,

$$\left| \frac{d^2}{dt^2} f(x^{\frac{1}{2}} e^{tX} x^{\frac{1}{2}}) \right| \leq L \|X\|_{\mathfrak{p}}^2, \quad \forall X \in \mathfrak{p}$$

Smoothness and Convexity

Theorem (This Thesis)

- f_v is $N(\pi)^2$ -smooth;
- f_v is geodesically convex, that is $g(t) = f_v(\gamma_X(t))$ is convex for any geodesic $\gamma_X(t)$.

Remark: The weight norm [Bür+19] $N(\pi)$ is

$$N(\pi) = \max_{X \in \mathfrak{p}} \frac{\|\Pi(X)\|_{\text{op}}}{\|X\|_{\mathfrak{p}}}$$

where $\|\Pi(X)\|_{\text{op}}$ is the operator norm of $\Pi(X) := \left. \frac{d}{dt} \right|_{t=0} \pi(e^{tX})$.

RGD for Scaling Problem

Theorem (This Thesis)

If $f_{v,\text{inf}} > -\infty$, then for any $\varepsilon > 0$, by setting

$$\eta = \frac{1}{N(\pi)^2}, \quad T > \frac{2N(\pi)^2}{\varepsilon^2} \left(\log \|v\|^2 - f_{v,\text{inf}} \right)$$

in RGD, it returns $x \in P$ s.t. $\|\nabla f_v(x)\|_x < \varepsilon$.

Strengthening Kempf-Ness Theorem

Quantizing the relation: $\nabla f_v(g) \rightarrow 0 \Leftrightarrow f_v(g) \rightarrow \inf f_v(g)$

Theorem (This Thesis)

Given a real reductive Lie group G and a rational representation (π, V) of G , for any $v \in V \setminus \{0\}$ then

$$\log \left(1 - \frac{\|\nabla f_v(x)\|_x}{\gamma(\pi)} \right) \leq f_{v,\inf} - f_v(x) \leq \log \left(1 - \frac{\|\nabla f_v(x)\|_x^2}{4N(\pi)^2} \right)$$

Remark:

- $\gamma(\pi)$ is the weight margin [Bür+19], characterized by π ;
- Complex case $\mathfrak{g} = \mathfrak{k} + i\mathfrak{k} \Rightarrow$ Real case $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$.

RGD for Norm Minimization Problem

For any $0 < \varepsilon < \log 2$,

$$\|\nabla f_v(x)\|_x < \frac{1}{2}\gamma(\pi)\varepsilon \Rightarrow f_v(x) - f_{v,\inf} < \varepsilon$$

Theorem (This Thesis)

For $v \in V$ with $f_{v,\inf} > -\infty$ and $\varepsilon > 0$, by setting

$$\eta = \frac{1}{N(\pi)^2}, \quad T > \frac{8N(\pi)^2}{\gamma(\pi)^2\varepsilon^2} \left(\log \|v\|^2 - f_{v,\inf} \right)$$

in RGD, it returns $x \in P$ s.t. $f_v(x) - f_{v,\inf} < \varepsilon$.

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Conclusions

- Optimization over an orbit of real reductive Lie group
 \rightsquigarrow Optimization on $P \subset P(n)$, Riemannian submanifold
- Null cone, scaling and norm minimization problem
 \rightsquigarrow Optimizing the Kempf-Ness function f_v on P
- Smoothness of the Kempf-Ness function f_v
 \rightsquigarrow Applying RGD method to f_v
 \rightsquigarrow Solving the scaling problem
- Strengthening the Kempf-Ness theorem
 \rightsquigarrow RGD method applied for the norm minimization problem

Future work:

- Boundedness of $N(\pi)$ and $\gamma(\pi)$ for some cases;
- Second order algorithm for these problems.



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Moment Polytope

- Given (π, V) of $G \subset GL(n, \mathbb{R})$ and $v \in V \setminus \{0\}$
- $K \curvearrowright \mathfrak{p}$: $k \cdot X := kXk^T \rightsquigarrow \mathfrak{p}/K$
- Moment map $\mu: V \setminus \{0\} \rightarrow \mathfrak{p}$: $\mu(v) := \nabla f_v(I)$

Definition (Moment Polytope)

The moment polytope is defined as

$$\Delta(v) := \left\{ s(\mu(w)) : w \in \overline{\pi(G) \cdot v} \right\} \subset \mathfrak{p}/K$$

where $s(\mu(w)) = \text{diag}(\lambda_1, \dots, \lambda_n)$ with $\lambda_1 \geq \dots \geq \lambda_n$ and all λ_i are eigenvalues of $\mu(w)$.

Remark

$\Delta(v)$ is a convex polytope in \mathfrak{p}/K by [Par20; Uza92].

p-Scaling Problem

Matrix Scaling: positive vectors \mathbf{r}, \mathbf{c} with $\sum_{i=1}^n r_i = \sum_{j=1}^n c_j = R$

- A almost (\mathbf{r}, \mathbf{c}) -scalable: $\forall \varepsilon > 0, \exists$ positive diagonal X, Y s.t. $B = XAY$ satisfies

$$\|B\mathbf{1} - \mathbf{r}\|_2 < \varepsilon, \quad \|B^T\mathbf{1} - \mathbf{c}\|_2 < \varepsilon$$

- A almost (\mathbf{r}, \mathbf{c}) -scalable $\Leftrightarrow (\mathbf{r}, \mathbf{c}) - R/n(\mathbf{1}, \mathbf{1}) \in \Delta(A)$

p-Scaling Problem

Given $\varepsilon > 0$ and (π, V) of G and $v \in V$ such that $p \in \Delta(v)$, find a $g \in G$ s.t.

$$\|s(\mu(\pi(g)v)) - p\|_F < \varepsilon$$

Busemann Function

For any $p \in \Delta(v)$, the Busemann function b_p corresponding to p

$$\begin{aligned} b_p: \quad P &\longrightarrow \mathbb{R} \\ x &\longmapsto \lim_{t \rightarrow \infty} d(x, e^{tp}) - t \end{aligned}$$

where $d(x, e^{tp})$ is the geodesic distance from x to e^{tp} .

Theorem ([Hir22] Theorem 2.27)

① Consider the Kempf-Ness function f_v on P and $p \in \Delta(v)$,

$$\exists \{x_i\} \subset P \text{ s.t. } \lim_{i \rightarrow \infty} \|\nabla(f_v + b_p)(x_i)\|_{x_i} = 0$$

$$\Leftrightarrow \inf_{x \in P} (f_v + b_p) > -\infty$$

② If $p \in \Delta(v)$, then $\inf_{x \in P} (f_v + b_p)(x) > -\infty$.

Application to p -scaling Problem

Proposition ([Hir22] Proposition 2.35)

For any $p \in \Delta(v)$,

$$\|\nabla(f_v + b_p)(x)\|_x = \left\| \mu(\pi(x^{\frac{1}{2}})v) - ks(X)k^T \right\|_F$$

where $x^{\frac{1}{2}} = bk$ for upper triangular matrix b , orthogonal matrix k .

Problem

Whether is the Busemann function b_p L -smooth? i.e.

$$\left| \frac{d^2}{dt^2} b_p \left(x^{\frac{1}{2}} e^{tY} x^{\frac{1}{2}} \right) \right| \leq L \|Y\|_{\mathfrak{p}}^2, \quad \forall Y \in \mathfrak{p}$$

\rightsquigarrow RGD algorithm for p -scaling