

## Article


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# Diverse behaviors in non-uniform chiral and non-chiral swarmalators

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We study the emergent behaviors of a population of swarming coupled oscillators, dubbed swarmalators. Previous work considered the simplest, idealized case: identical swarmalators with global coupling. Here we expand this work by adding more realistic features: local coupling, non-identical natural frequencies, and chirality. This more realistic model generates a variety of new behaviors including lattices of vortices, beating clusters, and interacting phase waves. Similar behaviors are found across natural and artificial micro-scale collective systems, including social slime mold, spermatozoa vortex arrays, and Quincke rollers. Our results indicate a wide range of future use cases, both to aid characterization and understanding of natural swarms, and to design complex interactions in collective systems from soft and active matter to micro-robotics.

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In the original model:

$$|\mathbf{v}_i| = v_0 = 0$$

In this paper:

$$\mathbf{v}_i = c_i \mathbf{n}_i$$

$$\mathbf{n}_i = \begin{bmatrix} c_i = \omega_i R_i \\ \cos\left(\theta_i + \frac{\pi}{2}\right) \\ \sin\left(\theta_i + \frac{\pi}{2}\right) \end{bmatrix}$$

New phase offset terms,  $Q_{\dot{x}}, Q_{\dot{\theta}}$ , which enable ‘frequency coupling’.

$$Q_{\dot{x}} = \frac{\pi}{2} \left| \frac{\omega_j}{|\omega_j|} - \frac{\omega_i}{|\omega_i|} \right|$$

$$Q_{\dot{\theta}} = \frac{\pi}{4} \left| \frac{\omega_j}{|\omega_j|} - \frac{\omega_i}{|\omega_i|} \right|$$

My understanding:

$$Q_{\dot{x}} = \frac{\pi}{2} |\text{sgn } \omega_j - \text{sgn } \omega_i| = \begin{cases} \pi, & \text{sgn } \omega_j \neq \text{sgn } \omega_i \\ 0, & \text{sgn } \omega_j = \text{sgn } \omega_i \end{cases}$$

$$J \cos(\theta_j - \theta_i - Q_{\dot{x}}) = \begin{cases} -J \cos(\theta_j - \theta_i), & Q_{\dot{x}} = \pi \\ J \cos(\theta_j - \theta_i), & Q_{\dot{x}} = 0 \end{cases}$$

$$\dot{\mathbf{x}}_i = \mathbf{v}_i + \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (A + J \cos(\theta_j - \theta_i - Q_{\dot{x}})) - B \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^2} \right]$$

$$J \cos(\theta_j - \theta_i - Q_{\dot{x}}) = \begin{cases} -J \cos(\theta_j - \theta_i), & \text{sgn } \omega_j \neq \text{sgn } \omega_i \\ J \cos(\theta_j - \theta_i), & \text{sgn } \omega_j = \text{sgn } \omega_i \end{cases}$$

How can I ensure that  $J \cos(\theta_j - \theta_i) > 0$ , which means  $\theta_j - \theta_i > \pi$  when  $\text{sgn } \omega_j \neq \text{sgn } \omega_i$ ?

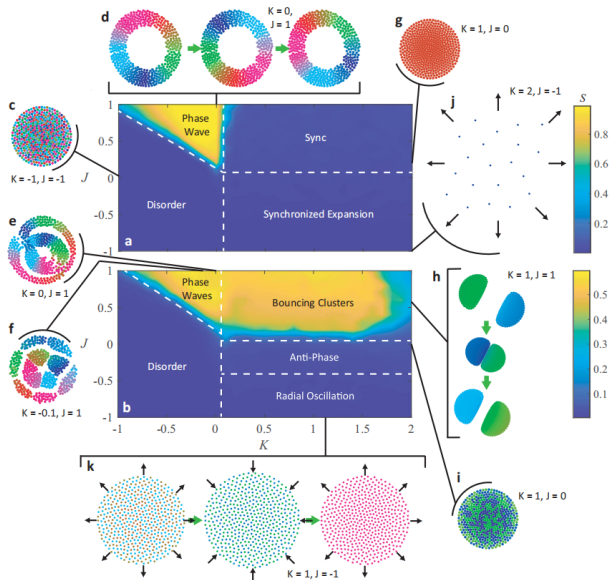
## Model equations:

$$\dot{\mathbf{x}}_i = \mathbf{v}_i + \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (A + J \cos(\theta_j - \theta_i - Q_{\dot{x}})) - B \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^2} \right]$$

$$\dot{\theta}_i = \omega_i + \frac{K}{N} \sum_{j \neq i}^N \frac{\sin(\theta_j - \theta_i - Q_{\dot{\theta}})}{|\mathbf{x}_j - \mathbf{x}_i|}$$

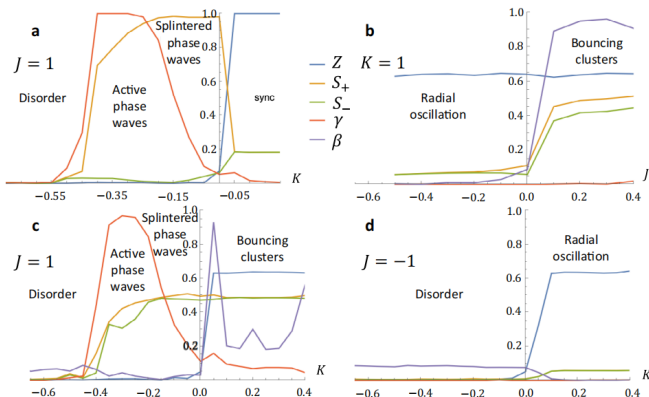
Several different cases of natural frequencies  $\omega$  in this paper:

1. Single frequency (F1):  $\omega_i = 1$  for all swarmalators.
2. Two frequencies (F2): Exactly half of the swarmalators have  $\omega_i = 1$  and the other half have  $\omega_i = -1$ .
3. Single uniform distribution (F3): All swarmalators have their natural frequency randomly selected from a single uniform distribution, such that  $\omega_i \sim U(1, \Omega)$ .
4. Double uniform distribution (F4): Exactly half of the swarmalators have their natural frequency randomly selected from one uniform distribution ( $\omega_i \sim U(1, \Omega)$ ) and the second half have their natural frequency selected from another uniform distribution ( $\omega_i \sim U(-\Omega, -1)$ ).





$$Z = \frac{1}{N} \sum_{j=1}^N e^{i(\theta_j)}, \quad \beta = \left| \frac{1}{n_{\omega > 0}} \sum_{j=1}^{n_{\omega > 0}} \mathbf{x}_{\omega > 0} - \frac{1}{n_{\omega < 0}} \sum_{j=1}^{n_{\omega < 0}} \mathbf{x}_{\omega < 0} \right|$$



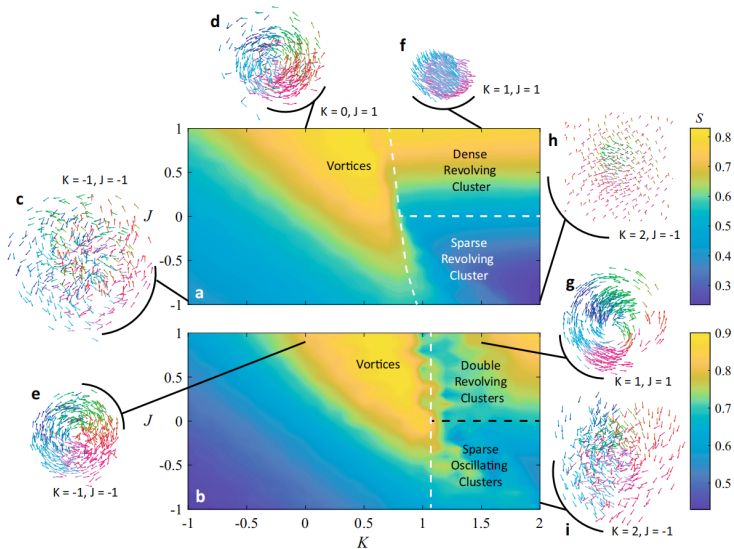
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# Revolving swarmalators

Revolving swarmalators' motion and phase coupling behavior is defined when  $c_i \neq 0$  for all agents and  $Q_{\dot{x}}, Q_{\dot{\theta}} = 0$

$$\begin{cases} \dot{\mathbf{x}}_i = \mathbf{v}_i + \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (A + J \cos(\theta_j - \theta_i)) - B \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^2} \right] \\ \dot{\theta}_i = \omega_i + \frac{K}{N} \sum_{j \neq i}^N \frac{\sin(\theta_j - \theta_i)}{|\mathbf{x}_j - \mathbf{x}_i|} \\ \mathbf{v}_i = \omega_i \begin{bmatrix} \cos(\theta_i + \frac{\pi}{2}) \\ \sin(\theta_i + \frac{\pi}{2}) \end{bmatrix} \end{cases}$$



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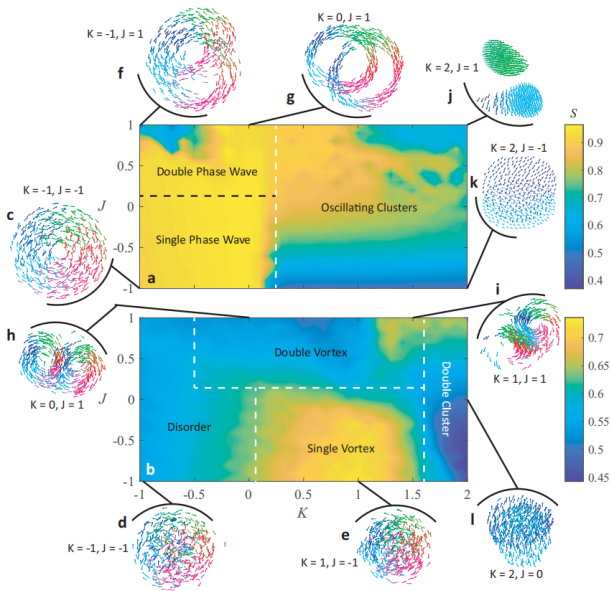
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# Frequency-coupled chiral swarmalators

$$\begin{cases} \dot{\mathbf{x}}_i = \mathbf{v}_i + \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (A + J \cos(\theta_j - \theta_i - Q_{\dot{x}})) - B \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^2} \right] \\ \dot{\theta}_i = \omega_i + \frac{K}{N} \sum_{j \neq i}^N \frac{\sin(\theta_j - \theta_i - Q_{\dot{\theta}})}{|\mathbf{x}_j - \mathbf{x}_i|} \\ \mathbf{v}_i = \omega_i \begin{bmatrix} \cos(\theta_i + \frac{\pi}{2}) \\ \sin(\theta_i + \frac{\pi}{2}) \end{bmatrix} \end{cases}$$

$$Q_{\dot{x}} = \frac{\pi}{2} \left| \frac{\omega_j}{|\omega_j|} - \frac{\omega_i}{|\omega_i|} \right|$$

$$Q_{\dot{\theta}} = \frac{\pi}{4} \left| \frac{\omega_j}{|\omega_j|} - \frac{\omega_i}{|\omega_i|} \right|$$



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# 3D Revolving swarmalators

$$\begin{cases} \dot{\mathbf{x}}_i = \mathbf{v}_i + \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (A + J \cos(\theta_j - \theta_i)) - B \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^2} \right] \\ \dot{\theta}_i = \omega_i + \frac{K}{N} \sum_{j \neq i}^N \frac{\sin(\theta_j - \theta_i)}{|\mathbf{x}_j - \mathbf{x}_i|} \\ \mathbf{v}_i = \omega_i \begin{bmatrix} \cos(\theta_i + \frac{\pi}{2}) \\ \sin(\theta_i + \frac{\pi}{2}) \\ z_i \end{bmatrix} \end{cases}$$

$$z_i = \begin{cases} \cos \theta_i, & \omega_i > 0 \\ \sin \theta_i, & \omega_i < 0 \end{cases}$$

$$z_i \sim U(0, 1)$$

$$\dot{\mathbf{x}}_i = \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (1 + J \cos(\theta_j - \theta_i)) - \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^3} \right], \quad (21)$$

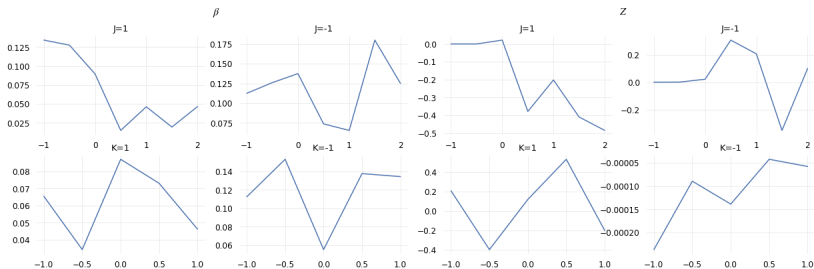
$$\dot{\theta}_i = \frac{K}{N} \sum_{j \neq i}^N \frac{\sin(\theta_j - \theta_i)}{|\mathbf{x}_j - \mathbf{x}_i|}, \quad (22)$$

where  $\mathbf{x}_i = (x_i, y_i, z_i)$ . These are the same as Eqs. (3) and (4), except the exponent of the hard shell repulsion is now 3 (we choose this because it yields simple formulas for the radii of certain states).

# Order parameter

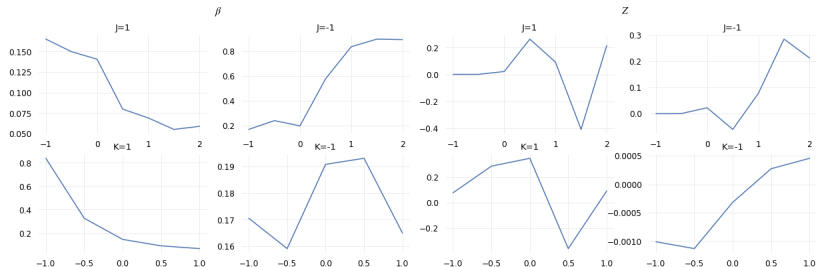
$$z_i = \begin{cases} \cos \theta_i, & \omega_i > 0 \\ \sin \theta_i, & \omega_i < 0 \end{cases}$$

$$Z = \frac{1}{N} \sum_{j=1}^N e^{i(\theta_j)}, \beta = \left| \frac{1}{n_{\omega>0}} \sum_{j=1}^{n_{\omega>0}} x_{\omega>0} - \frac{1}{n_{\omega<0}} \sum_{j=1}^{n_{\omega<0}} x_{\omega<0} \right|$$



# Order parameter

$$Z = \frac{1}{N} \sum_{j=1}^N e^{i(\theta_j)}, \beta = \left| \frac{1}{n_{\omega>0}} \sum_{j=1}^{n_{\omega>0}} \mathbf{x}_{\omega>0} - \frac{1}{n_{\omega<0}} \sum_{j=1}^{n_{\omega<0}} \mathbf{x}_{\omega<0} \right|$$



# 3D Frequency-coupled chiral swarmalators

$$\begin{cases} \dot{\mathbf{x}}_i = \mathbf{v}_i + \frac{1}{N} \sum_{j \neq i}^N \left[ \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|} (A + J \cos(\theta_j - \theta_i - Q_{\dot{x}})) - B \frac{\mathbf{x}_j - \mathbf{x}_i}{|\mathbf{x}_j - \mathbf{x}_i|^2} \right] \\ \dot{\theta}_i = \omega_i + \frac{K}{N} \sum_{j \neq i}^N \frac{\sin(\theta_j - \theta_i - Q_{\dot{\theta}})}{|\mathbf{x}_j - \mathbf{x}_i|} \\ \mathbf{v}_i = \omega_i \begin{bmatrix} \cos(\theta_i + \frac{\pi}{2}) \\ \sin(\theta_i + \frac{\pi}{2}) \\ z_i \end{bmatrix} \end{cases}$$

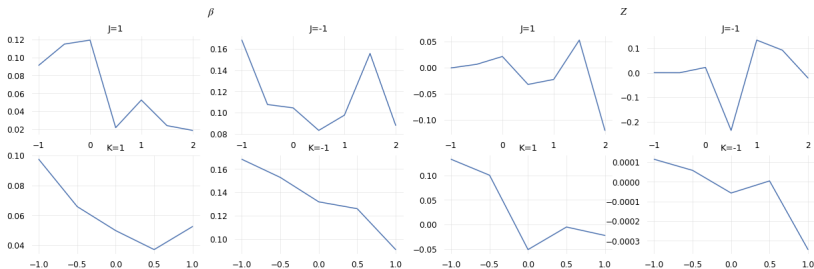
$$Q_{\dot{x}} = \frac{\pi}{2} \left| \frac{\omega_j}{|\omega_j|} - \frac{\omega_i}{|\omega_i|} \right|$$

$$Q_{\dot{\theta}} = \frac{\pi}{4} \left| \frac{\omega_j}{|\omega_j|} - \frac{\omega_i}{|\omega_i|} \right|$$

# Order parameter

$$z_i = \begin{cases} \cos \theta_i, & \omega_i > 0 \\ \sin \theta_i, & \omega_i < 0 \end{cases}$$

$$Z = \frac{1}{N} \sum_{j=1}^N e^{i(\theta_j)}, \quad \beta = \left| \frac{1}{n_{\omega>0}} \sum_{j=1}^{n_{\omega>0}} x_{\omega>0} - \frac{1}{n_{\omega<0}} \sum_{j=1}^{n_{\omega<0}} x_{\omega<0} \right|$$



# Order parameter

$$Z = \frac{1}{N} \sum_{j=1}^N e^{i(\theta_j)}, \beta = \left| \frac{1}{n_{\omega>0}} \sum_{j=1}^{n_{\omega>0}} \mathbf{x}_{\omega>0} - \frac{1}{n_{\omega<0}} \sum_{j=1}^{n_{\omega<0}} \mathbf{x}_{\omega<0} \right|$$

$z_i \sim U(0, 1)$

