Radii of Emergent Patterns in Swarmalator Systems

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Abstract	Abstract: For a system of swarmalators converging to different types of circular patterns, we provide expressions for the outer and inner radii of these patterns and examine their dependence on the model parameters. Derivations are made for three static patterns with an infinite number of entities and a generalized swarmalator model with parameterized	
Document Sections		
1. Introduction		
2. System Model	attraction and repulsion kernels. Simulations of finite systems show good agreement with the asymptotic expressions.	
3. Derivation of Radii		
4. Numerical Evaluation	Published in: 2023 IEEE International Conference on Autonomic Computing and Self-Organizing Systems (ACSOS)	
5 Conclusions and Outlook	Date of Conference: 25-29 September 2023	DOI: 10.1109/ACSOS58161.2023.00034

Full Text Views Model equations:

$$\begin{split} \dot{x}_i &= \frac{1}{N} \sum_{j \neq i}^N e_{ij} d_{ij}^\alpha \left(1 + J \cos \theta_{ij} \right) - e_{ij} d_{ij}^\beta \\ \dot{\theta}_i &= \frac{K}{N} \sum_{i \neq i}^N d_{ij}^\gamma \sin \theta_{ij} \end{split}$$

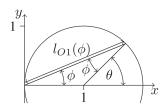
where
$$d_{ij} = ||x_j - x_i||$$
, $\theta_{ij} = \theta_i - \theta_j$, $e_{ij} = \frac{1}{d_{ij}}(x_j - x_i)$.

Choosing $\alpha = 0$ and $\beta = \gamma = -1$ gives the original model.

In the converged state of the static patterns, the entities no longer move, so we have $\dot{x}_i = 0$, which yields:

$$r_{\text{out}}^{\alpha}\underbrace{\sum_{j\neq i}^{N}e_{ij}g_{ij}^{\alpha}\left(1+J\cos\theta_{ij}\right)}_{\text{Attraction}A} = r_{\text{out}}^{\beta}\underbrace{\sum_{j\neq i}^{N}e_{ij}g_{ij}^{\alpha}}_{\text{Repulsion}R}$$

where
$$r_{\text{out}} = \max_{1 \leq i \leq N} \|x_i - \bar{x}\|, \, g_{ij} = \frac{d_{ij}}{r_{\text{out}}}.$$



(a) Calculating the length $l_{O1}(\phi)$.

- Pattern center \bar{x} is positioned at (1,0) and a swarmalator is present at the origin.
- using polar coordinates (r, ϕ) , hence $e_{ij} = (\cos \phi, \sin \phi)$ and $g_{ij} = r$.
- $\blacksquare \ l_{O1}\left(\phi\right)=2\cos\phi=\frac{2\sin\phi\cos\phi}{\sin\phi}=\frac{\sin2\phi}{\sin\phi}$

Due to symmetry, $\sum_{j\neq i}^{N} e_{ij,y} g_{ij}^{\alpha} = 0$, $\sum_{j\neq i}^{N} e_{ij,y} g_{ij}^{\beta} = 0$, which yields

$$r_{\text{out}}^{\alpha} \sum\nolimits_{j \neq i}^{N} e_{ij,x} g_{ij}^{\alpha} \left(1 + J \cos \theta_{ij}\right) = r_{\text{out}}^{\beta} \sum\nolimits_{j \neq i}^{N} e_{ij,x} g_{ij}^{\alpha}$$

Next, the authors consider the limiting case $N \to \infty$ and rewrite the sums as integrals $(\mathrm{d}x\mathrm{d}y = r\mathrm{d}r\mathrm{d}\phi)$

$$r_{\mathrm{out}}^{\alpha-\beta} = \frac{\mathrm{Repulsion}}{\mathrm{Attraction}} = \frac{\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \phi \int_{0}^{l_{O1}(\phi)} r^{1+\beta} \mathrm{d}r \mathrm{d}\phi}{\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \phi \int_{0}^{l_{O1}(\phi)} \left(1 + J \cos \theta_{ij}\right) r^{1+\alpha} \mathrm{d}r \mathrm{d}\phi}$$

The solution in the first integration:

$$\int_{0}^{l_{O1}(\phi)} r^{1+m} dr = \frac{1}{2+m} l_{O1}^{2+m}\left(\phi\right) = \frac{\left(2\cos\phi\right)^{2+m}}{2+m}$$

Supposed θ_{ij} is a constant, we have

$$\begin{split} r_{\mathrm{out}}^{\alpha-\beta} &= \frac{\frac{2^{2+\beta}}{2+\beta} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^{3+\beta} \phi \mathrm{d}\phi}{\frac{(1+J\cos\theta_{ij})2^{2+\alpha}}{2+\alpha} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^{3+\alpha} \phi \mathrm{d}\phi} \\ &= \frac{2^{\beta-\alpha} \left(2+\alpha\right) \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^{3+\beta} \phi \mathrm{d}\phi}{\left(1+J\cos\theta_{ij}\right) \left(2+\beta\right) \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos^{3+\alpha} \phi \mathrm{d}\phi} \end{split}$$

■ Static Sync. In Static Sync State, $J\cos\theta_{ij} = J \ \forall (i,j)$, For $\alpha = 0$ and $\beta = -1$, we have

$$r_{\rm out} = \frac{\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \phi \frac{\sin(2\phi)}{\sin \phi} \mathrm{d}\phi}{(1+J)\frac{1}{2}\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \phi \frac{\sin^2(2\phi)}{\sin^2 \phi} \mathrm{d}\phi} = \frac{3\pi}{8(1+J)}$$

■ Static Async. In Static Async State, $J\cos\theta_{ij}=0\ \forall\ (i,j),$ For $\alpha=0$ and $\beta=-1,$ we have

$$r_{\rm out} = \frac{\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \phi \frac{\sin(2\phi)}{\sin \phi} d\phi}{\frac{1}{2} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos \phi \frac{\sin^2(2\phi)}{\sin^2 \phi} d\phi} = \frac{3\pi}{8} \approx 1.178$$