

Enhancement of Demixing in Swarmalators with Inter-chiral Frustration

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* All red parts are the methods that were tried but did not work.

1 The Model

Swarmalators have a spatial position $\mathbf{r}_i = (x_i, y_i)$ and an internal phase θ_i which evolve according to equations:

$$\dot{\mathbf{r}}_i = v\mathbf{p}(\theta_i) , \quad (1a)$$

$$\dot{\theta}_i = \omega_i + \frac{K}{|A_i|} \sum_{j \in A_i} [\sin(\theta_j - \theta_i + \alpha_{ij}) - \sin \alpha_{ij}] , \quad (1b)$$

for $i = 1, 2, \dots, N$. Here in Eq. (1a), $\mathbf{p}(\theta) = (\cos \theta, \sin \theta)$, which means each swarmalator rotates with a constant speed v in the direction of its instantaneous phase $\theta_i(t)$. As per Eq. (1b), the sum runs over neighbors within a coupling radius d_0 around swarmalator i :

$$A_i(t) = \{j \mid |\mathbf{r}_i(t) - \mathbf{r}_j(t)| \leq d_0\} , \quad (2)$$

K is the coupling strength, and ω_i is the natural frequency of the i -th swarmalator. This means that a swarmalator will rotate with the angular velocity $|\omega_i|$ in the absence of mutual coupling ($K = 0$), and the sign of ω_i represents the direction of rotation, namely, the tribute of the chirality of the i -th swarmalator. A positive (negative) chirality (ω) describes the counterclockwise (clockwise) rotations of the swarmalator in space. We will study swarmalators including two types of chiralities with both positive and negative natural frequencies uniformly distributed in two symmetric regimes as

$$g_U^D(\omega; \mu, \sigma) = \frac{1}{2} [g_U(\omega; -\mu, \sigma) + g_U(\omega; \mu, \sigma)] . \quad (3)$$

where $g_U(\omega; \mu, \sigma)$ is the uniform distribution:

$$g_U(\omega; \mu, \sigma) = \begin{cases} \frac{1}{\sigma}, & \omega_{\min} \leq \omega \leq \omega_{\max} \\ 0, & \text{otherwise} \end{cases} . \quad (4)$$

Here $\sigma = \omega_{\max} - \omega_{\min}$ is the natural-frequency span, and $\mu = (\omega_{\max} + \omega_{\min})/2$ is the average.

Additionally, α_{ij} is the phase frustration between two neighboring swarmalators, which is defined as:

$$\alpha_{ij} = \begin{cases} \alpha_0, & \omega_i \omega_j < 0 \\ 0, & \omega_i \omega_j \geq 0 \end{cases} \quad (5)$$

When $\alpha_0 = 0$, the dynamics reduces to the normal chiral model [2]. The counter term $\sin \alpha_{ij}$ is introduced to ensure that frustration only interferes with the inter-chiral coupling without changing the symbol of natural frequency.

Some order parameters can be introduced to measure the level of spatiotemporal coordination among swarmalators and distinguish the different collective states of the system. Firstly, an order parameter to measure the chiral demixing among swarmalators can be defined as:

$$S(t) = \frac{1}{N} \sum_{i=1}^N \frac{\sum_{j \in A_i} H(\omega_i \omega_j)}{|A_i(t)|}, \quad (6)$$

where $H(x) = (x > 0)$ is the Heaviside step function. $S(t)$ is the fraction of the pairs of neighboring swarmalators with the same chirality. When $S(t) = 1$, all the neighboring pairs of swarmalators have the same chirality, and the system is in a completely phase-separated state. When $S(t) < 1$, the system is in a mixed state.

Except for measuring the demixing degree, an order parameter to measure the degree of the complete demixing can be defined as:

$$M(t) = \frac{1}{N} \sum_{i=1}^N H \left[\sum_{j \in A_i} H(-\omega_i \omega_j) \right]. \quad (7)$$

$M(t)$ is the fraction of swarmalators that have neighbors with different chirality. When $M(t) = 0$, all the swarmalators are in a completely phase-separated state. When $M(t) > 0$, the system is in a mixed state. Obviously, M describes the qualitative nature of the mixing, while S describes the quantitative nature.

The above order parameters measure the chiral demixing from the perspective of the spatial distribution of the swarmalators. The coordination of the internal phases can also be quantified to describe the demixing of the system. Firstly, a usual order parameter to measure the phase synchronization of the system can be defined as:

$$Z(t) = R(t) e^{i\psi(t)} = \frac{1}{N} \sum_{j=1}^N e^{i\theta_j(t)}, \quad (8)$$

where $i = \sqrt{-1}$. The degree modulus $R(t) = |Z(t)|$ is the absolute value of the mean of the complex numbers $e^{i\theta_i}$, which can be interpreted as the absolute value of the mean normalized velocity of all swarmalators. When $R \approx 1$, swarmalators are fully phase synchronized, and when $R \approx 0$, swarmalators are phase incoherent. When the system is in a mixed state, the order parameter R remains constant in the long run, while for the phase-separated state, R will fluctuate over time. These behaviors can be quantified by the maximum and minimum values of R in a certain time window:

$$R_{\max} = \max_{t \in W} \{R(t)\} \quad (9a)$$

$$R_{\min} = \min_{t \in W} \{R(t)\} \quad (9b)$$

where $W = [T - h, T + h]$ is a time window that is long enough to cover the transient and steady states of the system. When $R_{\max} = R_{\min} \approx 1$, the system is in a mixed state, and when $R_{\max} \neq R_{\min}$, the system is phase-separated.

We conducted numerical simulations to investigate the performance and characteristics of our system under various conditions. For simplicity, we assume that swarmalators are initially distributed uniformly in a two-dimensional $L \times L$ square with periodic boundary conditions. All the numerical simulations of the model Eq. (1) were run on Python using Euler integration with box size of $L = 7$, population sizes of $N = 1000$, natural-frequency span $\sigma = 1$, minimal absolute value of frequencies ω_{\min} in $[10^{-3}, 3]$, and coupling radius of $d_0 = 1$. Unless otherwise stated, each data point of order parameters was collected by averaging last 1000 time steps of the simulation to discard the transients.

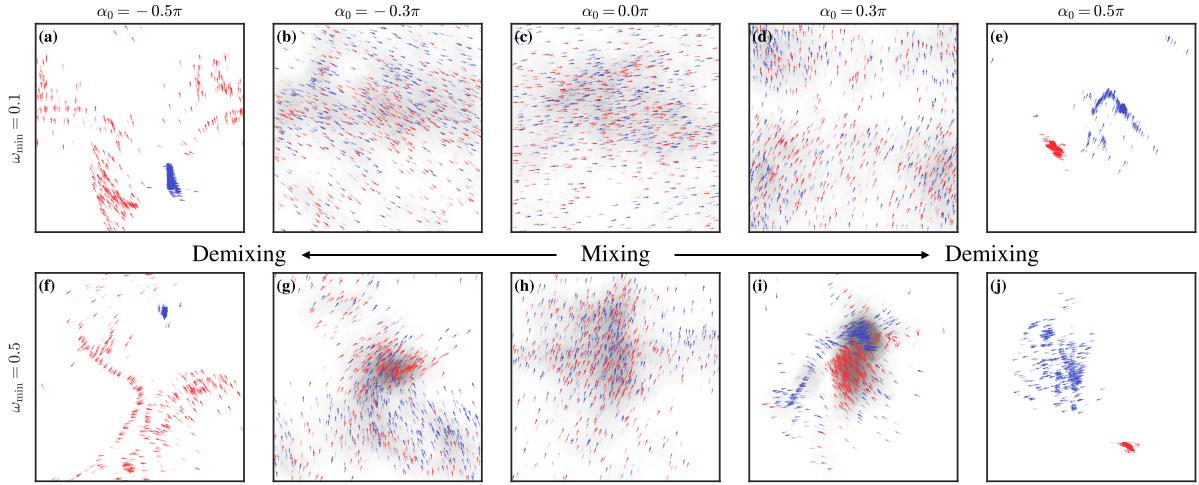


Figure 1: Snapshots of the spatial distribution for different minimal frequency ω_{\min} and phase frustration α_0 . Two types of chiral swarmalators are represented by red ($\omega_i > 0$) and blue ($\omega_i < 0$) arrows, respectively. The position and direction of the arrows represent the spatial position and phase of the swarmalators, respectively.

2 Frustration-enhanced demixing

Swarmalators with inter-chiral frustration can significantly enhance the chiral demixing of the system, both during the transient and in the steady state. The spatial distribution of the swarmalators is shown in Fig. 1 by modulating the minimal frequencies ω_{\min} and phase frustrations α_0 .

To further investigate the chiral demixing of the system, we calculated the instantaneous rotational centers $\mathbf{c}_i(t) = (X_i(t), Y_i(t))$, which is given by

$$\begin{aligned} X_i(t) &= x_i(t) - \frac{v}{\dot{\theta}_i(t)} \sin \theta_i(t), \\ Y_i(t) &= y_i(t) + \frac{v}{\dot{\theta}_i(t)} \cos \theta_i(t). \end{aligned} \quad (10)$$

By starting from uniform initial conditions, the instantaneous rotational centers of the swarmalators are shown in Fig. 2(a, b) for the minimal frequency $\omega_{\min} = 1.1$ and phase frustrations $\alpha_0 = 0, -0.5\pi$, respectively.

To quantify the level of chiral demixing, we introduce the order parameters S and M to measure the fraction of neighboring pairs of swarmalators with the same chirality and the fraction of swarmalators that have neighbors with different chirality, respectively.

3 Phase diagrams and theoretical approximation

The dynamics of the system (1) in the ISS can be abstracted as a synchronization problem in double layer networks. This problem can be described by the following equations:

$$\begin{aligned} \dot{\theta}_i^\pm &= \omega_i^\pm + \frac{K}{N} \sum_{j=1}^{N^\pm} \sin(\theta_j^\pm - \theta_i^\pm) \\ &\quad + \frac{K}{N} \sum_{j=1}^{N^\mp} [\sin(\theta_j^\mp - \theta_i^\pm + \alpha_0) - \sin \alpha_0], \end{aligned} \quad (11)$$

where $N^\pm = N/2$ is the numbers of swarmalators with positive and negative chirality, respectively. Each layer \pm represents the swarmalators with the same chirality, and the second, third terms in Eq. (11) describe the intralayer and interlayer interactions, respectively.

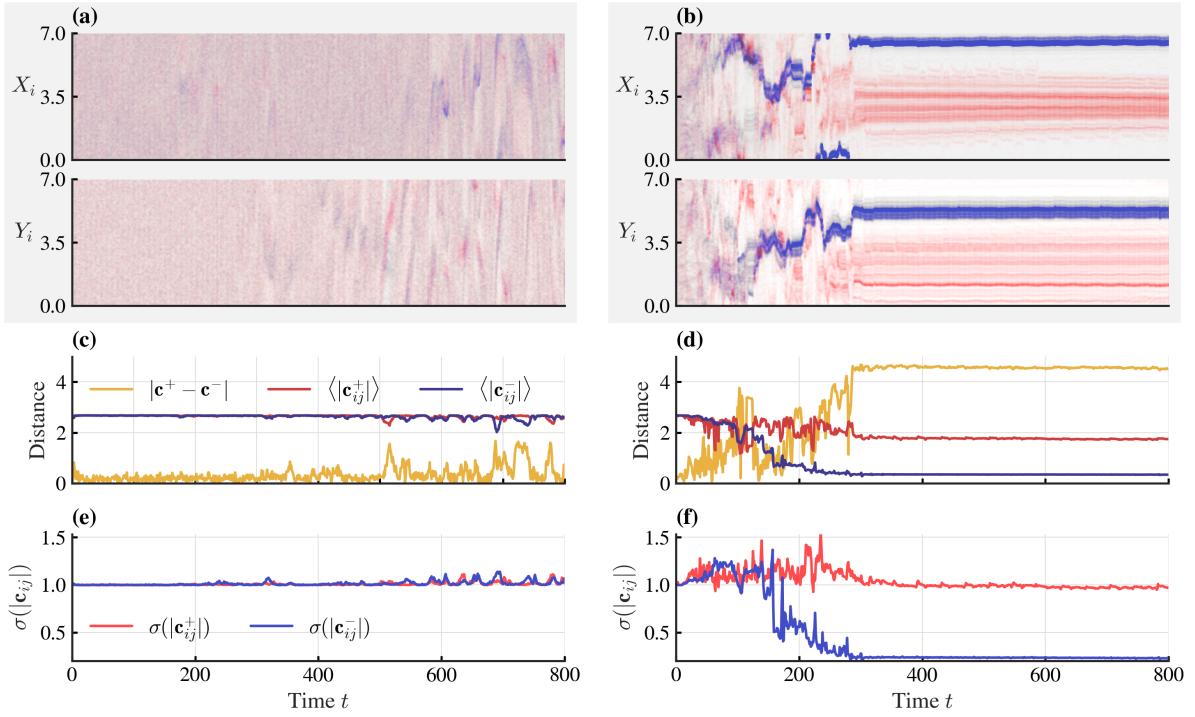


Figure 2: Scatter plot of the instantaneous rotational centers of swarmalators for $\omega_{\min} = 1.1$ and different α_0 : (a), $\alpha_0 = 0$; (b), $\alpha_0 = -0.5\pi$. The color of the dots denotes the corresponding natural frequency.

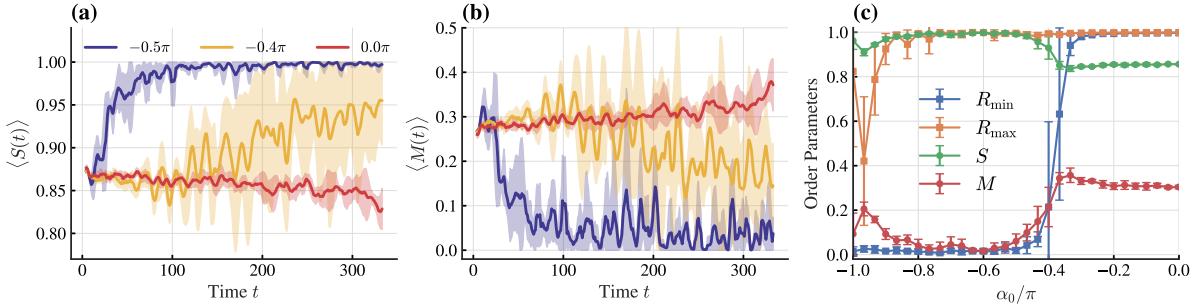


Figure 3: (a-b), time evolution of the order parameters S and M for different phase frustration α_0 , where “ $\langle \cdot \rangle$ ” denotes the average over the minimal frequency $\omega_{\min} \in [0.1, 0.5]$. (c), order parameters S , M , R_{\max} and R_{\min} versus α_0 averaged over different initial conditions for $\omega_{\min} = 10^{-3}$. (translucent bond and error-bars representing the standard deviation).

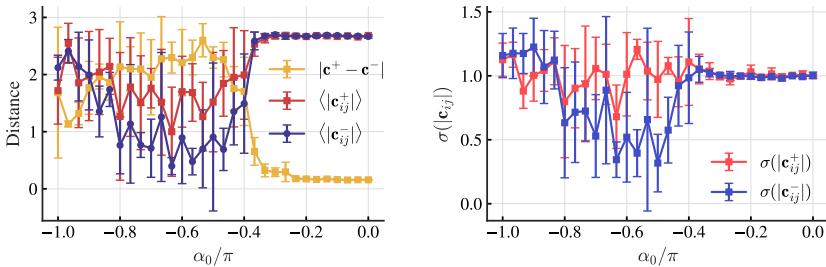


Figure 4: (a), the distance between centers of neighboring swarmalators versus α_0 . (b), the standard deviation of distance between centers of neighboring swarmalators versus α_0 . All data points are averaged over different initial conditions for $\omega_{\min} = 10^{-3}$.

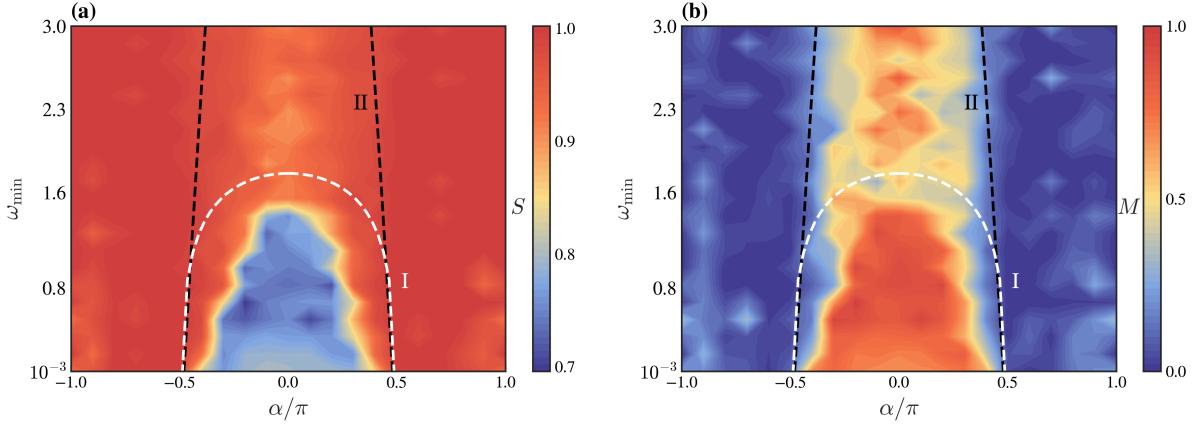


Figure 5: Heatmaps for order parameters S , M across the phase diagram of $(\alpha_0, \omega_{\min})$ with the critical demixing frustration α_c (black dashed line) and the critical swarming frustration α_s (white dashed line). Different colors describe the amplitudes of different order parameters.

Let $\theta_i^\pm(t) = \theta^\pm$ and introduce $\Delta\theta = \theta^+ - \theta^-$, $\Delta\omega = \mu^+ - \mu^-$, the phase locking dynamics of two layers can be described by the following equations:

$$\Delta\dot{\theta} = \Delta\omega - K \sin(\theta^+ - \theta^-) \cos \alpha_0 . \quad (12)$$

When $K^{-1}\Delta\omega \leq 1$, Eq. (12) has fixed points solutions $\Delta\theta = \arcsin(K \sin \alpha_0 \Delta\omega)$, which means the two layers are phase-locked. When $K^{-1}\Delta\omega > 1$, the two layers are not phase-locked, and the phase difference $\Delta\theta$ will drift with time. Therefore, the critical frustration α_0 can be driven by the natural frequency difference $\Delta\omega$ and coupling strength K as

$$\alpha_c = \arccos \frac{|\Delta\omega|}{K} . \quad (13)$$

The critical line of the demixing is shown in Fig. 5. The critical frustration α_0 descends with the minimal natural frequency $\Delta\omega$ increasing until the fixed point solution of Eq. (12) is absent.

Ref. [2] gives another critical frustration α_s for the swarming transition, which is the critical frustration for the swarming transition:

$$\alpha_s = \arccos \frac{2\pi d_0 |\Delta\omega|}{K \left(2\beta d_0 - 2r_d \sin \frac{\beta}{2} \right)} , \quad (14)$$

with the terms being

$$\begin{aligned} r_d &= \frac{L}{\sqrt{2}} - d_0 - 2r_o , \\ \beta &= 2\arccos \frac{r_d^2}{2d_0 r_d} , \\ r_o &= \frac{v}{\mu^+} = -\frac{v}{\mu^-} , \end{aligned} \quad (15)$$

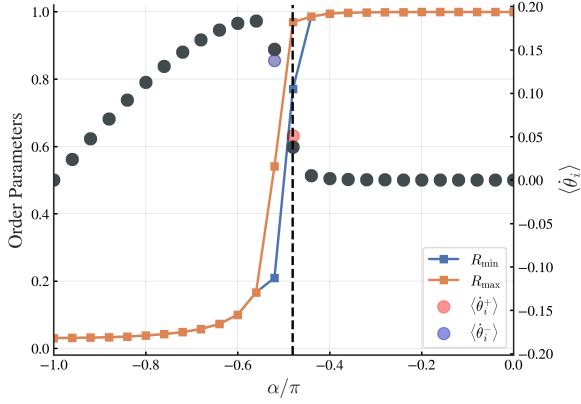


Figure 6: Order parameters R_{\max} and R_{\min} versus α_0 for abstracted synchronization model Eq. (11) with $\omega_{\min} = 10^{-3}$.

3.1 OA Reduction

To quantify the inter-layer coherence of the system, it is convenient to define the generalized complex-valued order parameters, i.e.,

$$Z^{\pm}(t) = R^{\pm}(t) e^{i\psi^{\pm}(t)} = \frac{1}{N} \sum_{j=1}^N e^{i\theta_j^{\pm}(t)}, \quad (16)$$

where $n = 1, 2, \dots, N$, and $r^{\pm}(t)$, $\psi^{\pm}(t)$ are the amplitudes and arguments of the n -order parameter. Our starting point is to analyze the critical point for the pulsation of the order parameter. In the thermodynamic limit $N \rightarrow \infty$, where $N^{\pm} \rightarrow \infty$. Then Eq. (11) gives rise to the continuity equations

$$\frac{\partial \rho^{\pm}}{\partial t} + \frac{\partial}{\partial \theta} (\rho^{\pm} v^{\pm}) = 0 \quad (17)$$

where $\rho^{\pm}(\theta, \omega, t)$ is the probability density of oscillators in layer \pm with phase θ at fixed frequency ω and t , it satisfies the normalization condition

$$\int_0^{2\pi} \rho^{\pm}(\theta, \omega, t) d\theta = 1. \quad (18)$$

Here, $v^{\pm}(\theta, \omega, t)$ is the velocity field, given by

$$\begin{aligned} v^{\pm}(\theta, \omega, t) &= \omega - \frac{K}{2} \sin \alpha_0 \\ &+ \frac{K}{2} \int \sin(\theta' - \theta) \rho^{\pm}(\theta', \omega', t) d\theta' d\omega' \\ &+ \frac{K}{2} \int \sin(\theta' - \theta + \alpha_0) \rho^{\mp}(\theta', \omega', t) d\theta' d\omega'. \end{aligned} \quad (19)$$

Correspondingly, the 1-order parameter defined in Eq. (16) in the thermodynamic limit reads

$$z^{\pm}(t) = \int_{-\infty}^{+\infty} g^{\pm}(\omega) \int_0^{2\pi} e^{i\theta} \rho^{\pm}(\theta, \omega, t) d\theta d\omega, \quad (20)$$

then $v^{\pm}(\theta, \omega, t)$ simplifies to

$$v^{\pm} = \omega - \frac{K}{2} \sin \alpha_0 + \frac{K}{2} \text{Im} [Z^{\pm}(t) e^{-i\theta}] \quad (21)$$

with the mean-field being

$$Z^{\pm}(t) = z^{\pm}(t) + z^{\mp}(t) e^{i\alpha_0} \quad (22)$$

To proceed, the probability $\rho^\pm(\theta, \omega, t)$ can be expressed as a Fourier series of the following form

$$\rho^\pm(\theta, \omega, t) = \frac{1}{2\pi} \sum_{-\infty}^{+\infty} a_n^\pm(\omega, t) e^{in\theta}, \quad (23)$$

where $a_n^\pm(\omega, t)$ is the n -th Fourier coefficient.

According to Ott and Antonsen ansatz [3, 4], the dynamics of the system can be reduced to a set of ordinary differential equations for the 1st Fourier coefficients $a^\pm(\omega, t)$:

$$\rho^\pm = \frac{1}{2\pi} \left\{ 1 + \sum_{n=1}^{\infty} [a^\pm(\omega, t) e^{-i\theta}]^n + \text{c.c.} \right\}. \quad (24)$$

To streamline the analysis, we express Eq. (17) in its complex form by multiplying both sides by $e^{i\theta}$ and then integrating with respect to θ :

$$\begin{aligned} \dot{a}^\pm(\omega, t) = & i a^\pm(\omega, t) \left(\omega - \frac{K}{2} \sin \alpha_0 \right) \\ & + \frac{K}{4} [Z^\pm(t) - \bar{Z}^\pm(a^\pm(\omega, t))^2(t)]. \end{aligned} \quad (25)$$

Herein, “ $\bar{\cdot}$ ” denotes the complex conjugate. It is closed by the order parameter,

$$z^\pm(t) = \int_{-\infty}^{+\infty} a^\pm(\omega, t) g^\pm(\omega) d\omega = \hat{g} a^\pm(\omega, t), \quad (26)$$

where the integral operator \hat{g} is introduced to ease notation.

To close the system, we express the complex order parameter $z^\pm(t)$ in Eq. (20) by using Cauchy’s residue theorem with analytical continuation of $a^\pm(\omega, t)$ into the right/left half complex plane for $g^+(\omega)$ and $g^-(\omega)$, respectively. Then we have $z^\pm = \bar{a}^\pm(\pm\omega_0 + i\Delta, t)$.

As a result, the low-dimensional evolution of the order parameter can be obtained by letting $\omega = i\Delta$ and substituting Eq. (26) into Eq. (25), which yields

$$\begin{aligned} \dot{z}^\pm = & z^\pm \left(\pm\omega_0 - \frac{iK}{2} \sin \alpha_0 - \Delta \right) + \frac{K}{4} (z^\pm + z^\mp e^{-i\alpha_0}) \\ & - \frac{K}{4} (z^\pm)^2 (\bar{z}^\pm + \bar{z}^\mp e^{i\alpha_0}). \end{aligned} \quad (27)$$

Then we rewrite the above equation using polar coordinates $z^\pm = r^\pm e^{-i\phi^\pm}$. (The negative sign in the exponent is chosen to ensure that ρ^\pm converges to $\delta(\theta - \phi^\pm)$, not $\delta(\theta + \phi^\pm)$ as $t \rightarrow \infty$.) Thus, ϕ^\pm can be interpreted as the phase of the chirality \pm , and r^\pm measures the degree of synchronization of the chirality \pm . Then Eq. (27) becomes

$$\dot{r}^\pm = -r^\pm \Delta + K \frac{1 - (r^\pm)^2}{4} [r^\pm + r^\mp \cos(\phi^\pm - \phi^\mp - \alpha_0)], \quad (28a)$$

$$\dot{\phi}^\pm = \pm\omega_0 + \frac{K}{2} \sin \alpha_0 - Kr^\mp \frac{1 + (r^\pm)^2}{4r^\pm} \sin(\phi^\pm - \phi^\mp - \alpha_0). \quad (28b)$$

Introducing $\varphi = \phi^+ - \phi^-$, the dynamics of the system can be further simplified to

$$\dot{r}^+ = -r^+ \Delta + K \frac{1 - (r^+)^2}{4} [r^+ + r^- \cos(\varphi - \alpha_0)], \quad (29a)$$

$$\dot{r}^- = -r^- \Delta + K \frac{1 - (r^-)^2}{4} [r^- + r^+ \cos(\varphi + \alpha_0)], \quad (29b)$$

$$\begin{aligned} \dot{\varphi} = & 2\omega_0 - Kr^- \frac{1 + (r^+)^2}{4r^+} \sin(\varphi - \alpha_0) \\ & - Kr^+ \frac{1 + (r^-)^2}{4r^-} \sin(\varphi + \alpha_0) \end{aligned} \quad (29c)$$

3.2 Linear Stability Analysis

We aim to obtain the steady solutions to Eq. (25), specifically where $\dot{a}^\pm(\omega, t) = 0$ and $z^\pm(t) = r^\pm$. Some calculations give

$$a_0^\pm(\omega) = \begin{cases} \frac{i\Omega + \sqrt{(R^\pm)^2 - \Omega^2}}{R^\pm}, & |\Omega| \leq R^\pm, \\ i\frac{\Omega - \text{sgn}(\Omega)\sqrt{\Omega^2 - (R^\pm)^2}}{R^\pm}, & |\Omega| > R^\pm, \end{cases} \quad (30)$$

where $R^\pm = K(r^\pm + r^\mp e^{i\alpha_0})$ and $\Omega = \omega - \frac{1}{2}K \sin \alpha_0$. In fact, the first part of the resulting expression corresponds to the locked oscillators, and the second one accounts for drafting populations.

We next explore the stability of $a_0^\pm(\omega)$ by linearizing Eq. (25). To this end, we introduce the perturbation $a^\pm(\omega, t) = a_0^\pm(\omega) + \varepsilon \eta^\pm(\omega, t)$, where $0 < \varepsilon \ll 1$ denotes the magnitude of the weak perturbation, and $\eta^\pm(\omega, t)$ is the perturbed function. As a result, the order parameter under the perturbation now becomes

$$z^\pm(t) = r^\pm + \varepsilon \hat{g} \eta^\pm(\omega, t). \quad (31)$$

Substituting all these terms into Eq. (25) and neglecting higher-order terms of ε , we obtain

$$\frac{\partial \eta^\pm}{\partial t} = \nu^\pm(\omega) \eta^\pm + \frac{K}{4} [\hat{g} \eta^\pm - (a_0^\pm(\omega))^2 \hat{g} \bar{\eta}^\pm], \quad (32)$$

where the coefficient $\nu(\omega)$ is

$$\nu^\pm(\omega) = i \left(\omega + \frac{K}{2} \sin \alpha_0 \right) - \frac{1}{2} K R^\pm a_0^\pm(\omega). \quad (33)$$

To ensure clarity and thoroughness, we define the vector $\mathbf{v} = (\eta^+, \bar{\eta}^+, \eta^-, \bar{\eta}^-)^\top$. We can then express Eq. (32) in a compact matrix form.

$$\frac{\partial \mathbf{v}}{\partial t} = \mathbf{M} \mathbf{v} + \frac{K}{4} \mathbf{P} \hat{g} \mathbf{v}, \quad (34)$$

where the multiplication matrix is

$$\mathbf{M} = \begin{bmatrix} \nu^+(\omega) & 0 & 0 & 0 \\ 0 & \bar{\nu}^+(\omega) & 0 & 0 \\ 0 & 0 & \nu^-(\omega) & 0 \\ 0 & 0 & 0 & \bar{\nu}^-(\omega) \end{bmatrix}, \quad (35)$$

and the coefficient matrix is

$$\mathbf{P} = \begin{bmatrix} 1 & -(a_0^+)^2 & 0 & 0 \\ (a_0^+)^2 & 1 & 0 & 0 \\ 0 & 0 & 1 & -(a_0^-)^2 \\ 0 & 0 & (a_0^-)^2 & 1 \end{bmatrix}. \quad (36)$$

To determine the stability of the fixed point, we let $\frac{\partial \mathbf{v}}{\partial t} = \lambda \mathbf{v}$ and analyze the eigenvectors of the matrix, which are given by

$$\mathbf{v} = \frac{K}{4} (\lambda \mathbf{I} - \mathbf{M})^{-1} \mathbf{P} \hat{g} \mathbf{v}. \quad (37)$$

Applying the operator \hat{g} to both sides of the equation, we have

$$(\mathbf{I} - K \mathbf{J}) \hat{g} \mathbf{v} = 0, \quad (38)$$

where the matrix \mathbf{J} is defined as

$$\mathbf{J} = \frac{1}{4} \hat{g} [(\lambda \mathbf{I} - \mathbf{M})^{-1} \mathbf{P}]. \quad (39)$$

A nontrivial solution to Eq. (38) is equivalent to the condition $\det(\mathbf{I} - K\mathbf{J}) = 0$. Straightforward calculations yield a group of eigenvalue equations, which are

$$\frac{1}{K} = h_c^\pm(\lambda) = \frac{1}{2}\hat{g}\frac{1 - (\alpha_0^\pm)^2}{\lambda - \eta(\omega)}, \quad (40a)$$

$$\frac{1}{K} = h_s^\pm(\lambda) = \frac{1}{2}\hat{g}\frac{1 + (\alpha_0^\pm)^2}{\lambda - \eta(\omega)}. \quad (40b)$$

The sign of eigenvalue $(\lambda + i\eta)$ symbols the stability property of partial locking. In other words, it is stable for $\lambda < 0$; otherwise, it is unstable. Determining the exact solution of the eigenvalue equation is challenging, nevertheless, some qualitative features of λ with respect to R^\pm can be inferred from Eqs. (40). The first observation is that $h_c^\pm(\lambda) > 0$ for $\lambda > 0$ and $\lim_{\lambda \rightarrow +\infty} h_c^\pm(\lambda) = 0$. Second, it follows from Eq. (30) that

$$\frac{da_0^\pm}{dR^\pm} = \begin{cases} \frac{1}{\sqrt{(R^\pm)^2 - \omega^2}} - \frac{i\Omega + \sqrt{(R^\pm)^2 - \Omega^2}}{(R^\pm)^2}, & |\Omega| < R^\pm, \\ \frac{i\text{sgn}(\Omega)}{\sqrt{\Omega^2 - (R^\pm)^2}} - i\frac{(\Omega + \text{sgn}(\Omega)\sqrt{\Omega^2 - (R^\pm)^2})}{(R^\pm)^2}, & |\Omega| > R^\pm. \end{cases} \quad (41)$$

It can be verified that

$$\lim_{\lambda \rightarrow 0^+} h_c^\pm(\lambda) = \hat{g} \left(\frac{da_0^\pm}{dR^\pm} \right) = \frac{d}{dR^\pm} (\hat{g}a_0^\pm). \quad (42)$$

Therefore, we have the identity

$$h_c^\pm(0^+) - \frac{1}{K} = R^\pm \frac{dQ(R^\pm)}{dR^\pm}, \quad (43)$$

where $Q(R^\pm)$ given by the self-consistent equation

$$\frac{1}{K} = Q(R^\pm) = \frac{1}{R^\pm} \int_{|\Omega| < R^\pm} \sqrt{1 - \frac{\Omega^2}{(R^\pm)^2}} g(\omega) d\omega. \quad (44)$$

3.3 Coarse graining

We begin with Eq. (1), replacing the finite coupling distance alignment interaction with a pseudopotential (the ' δ '-interaction). This substitution is justified when the interaction is sufficiently short-ranged, making the specific shape of the associated interaction potential irrelevant to the dynamics of many swarmalators. The pseudopotential is defined as:

$$\dot{\mathbf{r}}_i^\pm = v\mathbf{p}(\theta_i^c), \quad (45a)$$

$$\begin{aligned} \dot{\theta}_i^\pm &= \omega_i^\pm + K \sum_{j=1} \{ \delta(\mathbf{r}_j^\pm - \mathbf{r}_i^\pm) \sin(\theta_j^\pm - \theta_i^\pm) \\ &\quad + \delta(\mathbf{r}_j^\mp - \mathbf{r}_i^\pm) [\sin(\theta_j^\mp - \theta_i^\pm + \alpha_0) - \sin \alpha_0] \}, \end{aligned} \quad (45b)$$

where $c \in \{+, -\}$ is the chirality of the swarmalator i and $b = +$ if $c = -$ and vice versa. Then following [1] we derive a continuum equation of motion for the combined N -swarmalator probability density

$$\rho^\pm(\mathbf{r}, \theta, t) = \sum_{i=1} \rho_i^\pm(\mathbf{r}, \theta, t), \quad (46)$$

where $\rho_i^\pm(\mathbf{r}, \theta, t) = \delta(\mathbf{r}_i^\pm(t) - \mathbf{r}) \delta(\theta_i^\pm(t) - \theta)$ is the probability density of finding i -th swarmalator at position \mathbf{r} with phase θ and chirality $+$ or $-$ at time t . Since the deterministic dynamical equation Eq. (1) conserves the number of oscillators with a given natural frequency over time, the distribution function evolves according to a continuity equation of the following form:

$$\frac{\partial \rho_i^\pm}{\partial t} = -\nabla \cdot (\rho_i^\pm v_\mathbf{r}) - \frac{\partial}{\partial \theta} (\rho_i^\pm v_\theta^{\pm, i}). \quad (47)$$

Here, the velocity fields read

$$v_{\mathbf{r}}(\mathbf{r}, \theta, t) = v \mathbf{p}(\theta) , \quad (48a)$$

$$\begin{aligned} v_{\theta}^{\pm, i}(\mathbf{r}, \theta, t) &= \omega_i^{\pm} + K \int_{-\pi}^{\pi} d\phi \left\{ \rho^{\pm}(\mathbf{r}, \phi, t) \sin(\phi - \theta) \right. \\ &\quad \left. + \rho^{\mp}(\mathbf{r}, \phi, t) [\sin(\phi - \theta + \alpha_0) - \sin \alpha_0] \right\} . \end{aligned} \quad (48b)$$

Summing Eq. (47) over the i and \pm indices, and using the definition of the density ρ^{\pm} in Eq. (46), we obtain

$$\begin{aligned} \frac{\partial}{\partial t} \rho^{\pm}(\mathbf{r}, \theta, t) &= -v \mathbf{p}(\theta) \cdot \nabla \rho^{\pm}(\mathbf{r}, \theta, t) - \frac{\partial}{\partial \theta} \Omega^{\pm} \\ &\quad - K \frac{\partial}{\partial \theta} \rho^{\pm}(\mathbf{r}, \theta, t) \int_{-\pi}^{\pi} d\phi \left\{ \rho^{\pm}(\mathbf{r}, \phi, t) \sin(\phi - \theta) \right. \\ &\quad \left. + \rho^{\mp}(\mathbf{r}, \phi, t) [\sin(\phi - \theta + \alpha_0) - \sin \alpha_0] \right\} , \end{aligned} \quad (49)$$

where $\Omega^{\pm}(\mathbf{r}, \theta, t) = \sum_{i=1} \rho_i^{\pm}(\mathbf{r}, \theta, t) \omega_i^{\pm}$. Spatial homogeneity and phase synchronization of the ISS indicates $\forall i, \rho_i^{\pm}(\mathbf{r}, \theta, t) \equiv \rho_{\text{ISS}}(\mathbf{r}, \theta, t)$, which yields

$$\Omega^{\pm}(\mathbf{r}, \theta, t) = \rho^{\pm}(\mathbf{r}, \theta, t) \bar{\omega}^{\pm} , \quad (50)$$

where $\bar{\omega}^{\pm} = \langle \omega_i^{\pm} \rangle$.

Transforming ρ^{\pm} in a Fourier series in θ , we have

$$\rho^{\pm}(\mathbf{r}, \theta, t) = \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} \varrho_k^{\pm}(\mathbf{r}, t) e^{-ik\theta} , \quad (51)$$

where ϱ_k^{\pm} is the k -th Fourier coefficient of ρ^{\pm} , defined as

$$\varrho_k^{\pm}(\mathbf{r}, t) = \int_{-\pi}^{\pi} \rho^{\pm}(\mathbf{r}, \theta, t) e^{ik\theta} d\theta . \quad (52)$$

To streamline the analysis, we express Eq. (49) in its complex form by multiplying both sides by $e^{ik\theta}$ and then integrating with respect to θ :

$$\begin{aligned} \dot{\varrho}_k^{\pm} &= -\frac{v}{2} [\partial_x (\varrho_{k+1}^{\pm} + \varrho_{k-1}^{\pm}) - i \partial_y (\varrho_{k+1}^{\pm} - \varrho_{k-1}^{\pm})] \\ &\quad + ik \bar{\omega}^{\pm} \varrho_k^{\pm} \\ &\quad + \frac{ikK}{2\pi} \sum_{m=-\infty}^{\infty} \varrho_{k-m}^{\pm} F_{-m} \varrho_m^{\pm} \\ &\quad + \frac{ikK}{2\pi} \sum_{m=-\infty}^{\infty} e^{im\alpha_0} \varrho_{k-m}^{\pm} F_{-m} \varrho_m^{\mp} \\ &\quad - ikK \varrho_0^{\mp} \varrho_k^{\pm} \sin \alpha_0 , \end{aligned} \quad (53)$$

where F_m is the m -th Fourier coefficient of $\sin \theta$. Evaluating Eq. (53) for $k = 0, 1, \dots$ leads to a hierarchy of equations for $\{\varrho_k^{\pm}\}$ with

$$\rho^{\pm}(\mathbf{r}, t) = \varrho_0^{\pm}(\mathbf{r}, t) = \int_{-\pi}^{\pi} \rho^{\pm}(\mathbf{r}, \theta, t) d\theta \quad (54)$$

being the probability density of finding a swarmalator at position \mathbf{r} at time t and

$$\mathbf{w}^{\pm}(\mathbf{r}, t) = (\text{Re} \varrho_1^{\pm}, \text{Im} \varrho_1^{\pm}) = \int_{-\pi}^{\pi} \mathbf{p}(\theta) \rho^{\pm}(\mathbf{r}, \theta, t) d\theta \quad (55)$$

being the momentum field at position \mathbf{r} at time t . The degree modulus $R^{\pm}(\mathbf{r}, t) = |\mathbf{w}^{\pm}(\mathbf{r}, t)|$ is the absolute value of the mean normalized velocity of local swarmalators, which can be used as a measure of the local degree of synchronization.

To close the hierarchy of equations Eq. (53), we truncate the series at a finite order K and neglect the higher-order terms. This truncation is justified when the interaction is sufficiently short-ranged, making the specific shape of the associated interaction potential irrelevant to the dynamics of many swarmalators. Specifically, we assume that $\varrho_2^\pm(\mathbf{r}, t)$ follows changes in $\varrho_0^\pm(\mathbf{r}, t)$ and $\varrho_1^\pm(\mathbf{r}, t)$ adiabatically ($\dot{\varrho}_2^\pm(\mathbf{r}, t) \approx 0$) and neglect the higher-order terms ($\varrho_{k \geq 3}^\pm(\mathbf{r}, t) \approx 0$). Truncating at order 3, we are left with

$$\dot{\varrho}_0^\pm = -\text{Re}\bar{\nabla}\varrho_1^\pm \quad (56a)$$

$$\begin{aligned} \dot{\varrho}_1^\pm &= -\frac{v}{2}(\nabla\varrho_0^\pm + \bar{\nabla}\varrho_2^\pm) + i\varrho_1^\pm(\bar{\omega}^\pm - K\varrho_0^\mp \sin\alpha_0) \\ &\quad + \frac{K}{2}\varrho_0^\pm(\varrho_1^\pm + e^{i\alpha_0}\varrho_1^\mp), \end{aligned} \quad (56b)$$

$$\begin{aligned} \dot{\varrho}_2^\pm &= -\frac{v}{2}\nabla\varrho_1^\pm + i2\varrho_k^\pm(\bar{\omega}^\pm - K\varrho_0^\mp \sin\alpha_0) \\ &\quad + K\varrho_1^\pm(\varrho_1^\pm + e^{i\alpha_0}\varrho_1^\mp), \end{aligned} \quad (56c)$$

where $\nabla = \partial_x + i\partial_y$ denotes the gradient operator in the complex plane, and $\bar{\nabla} = \partial_x - i\partial_y$ is the complex conjugate of ∇ . Let $\dot{\varrho}_2^\pm = 0$, then ϱ_2^\pm can be solved as

$$\varrho_2^\pm = -\frac{iK\varrho_1^\pm}{a^\pm}(\varrho_1^\pm + e^{-i\alpha_0}\varrho_1^\mp) + \frac{i\nabla\varrho_1^\pm v}{2a^\pm} \quad (57)$$

where $a^\pm = 2(K\rho^\mp \sin\alpha_0 - \bar{\omega}^\pm)$. Substituting ϱ_2^\pm into Eq. (56b), we have

$$\begin{aligned} \dot{\varrho}_1^\pm &= -\frac{v}{2}\nabla\varrho_0^\pm + \frac{ivK\bar{\nabla}\varrho_1^\pm}{2a^\pm}(\varrho_1^\pm + e^{-i\alpha_0}\varrho_1^\mp) \\ &\quad + \frac{ivK\varrho_1^\pm}{2a^\pm}(\bar{\nabla}\varrho_1^\pm + e^{-i\alpha_0}\bar{\nabla}\varrho_1^\mp) - \frac{iv^2\Delta\varrho_1^\pm}{4a^\pm} \\ &\quad + i\varrho_1^\pm(\bar{\omega}^\pm - K\varrho_0^\mp \sin\alpha_0) + \\ &\quad \frac{K}{2}\varrho_0^\pm(\varrho_1^\pm + e^{i\alpha_0}\varrho_1^\mp) \end{aligned} \quad (58)$$

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