

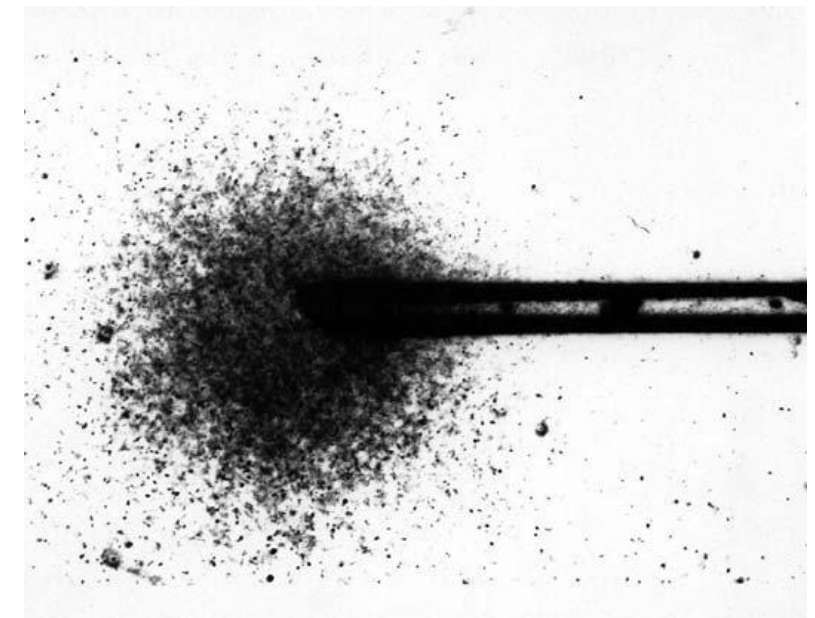
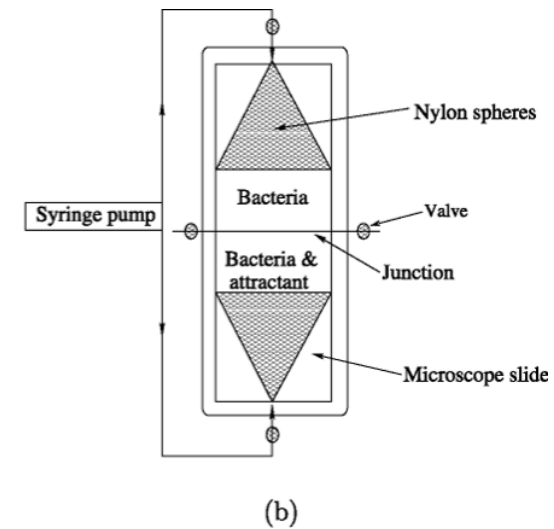
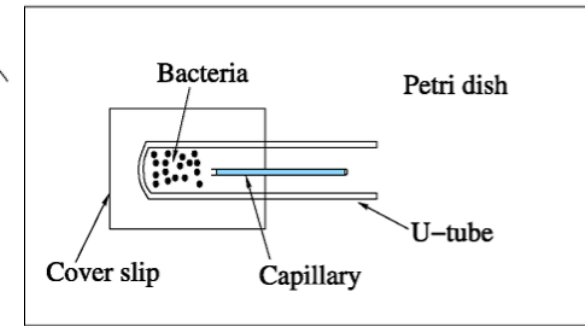
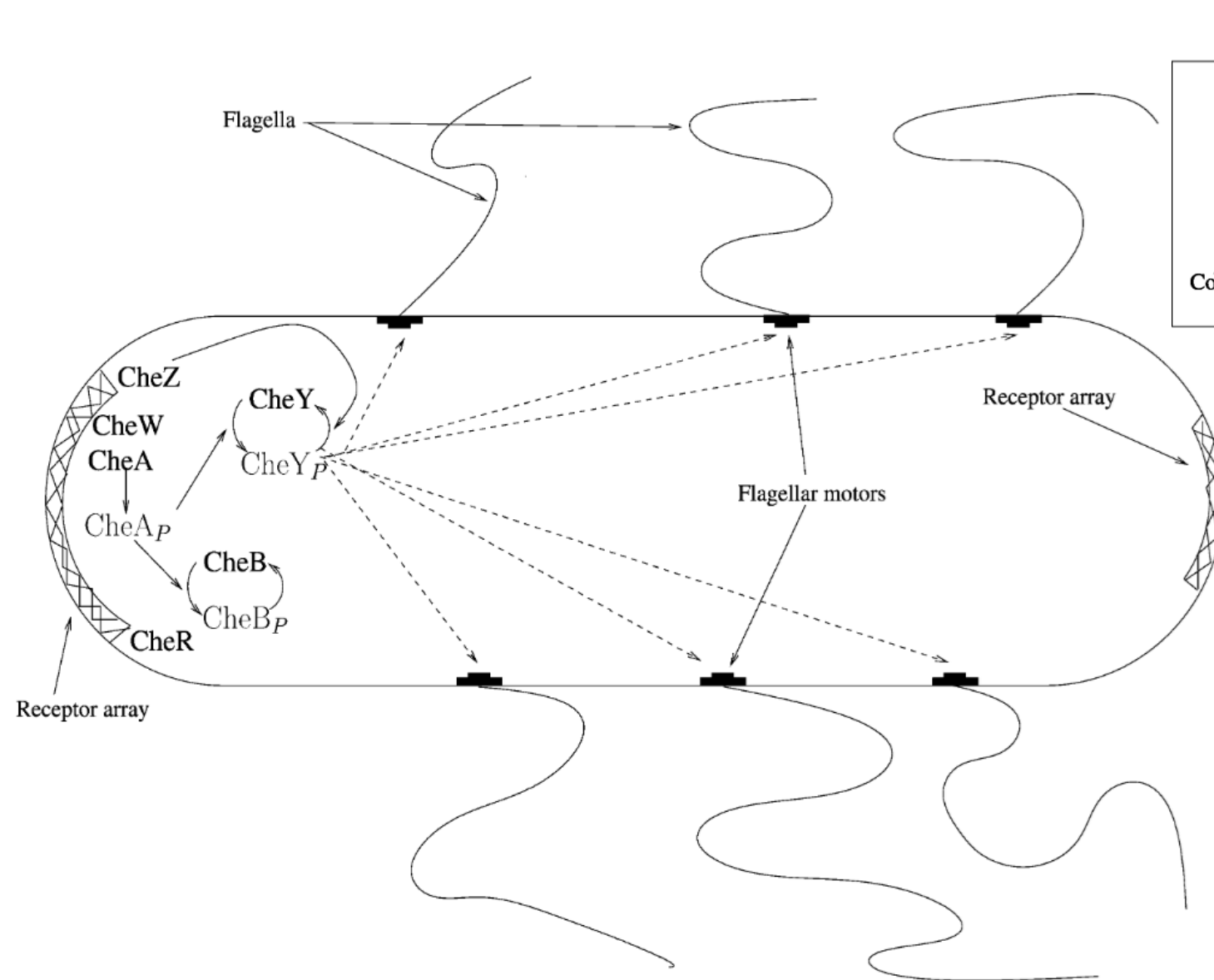
Active Matter



Flocking, Self-propelled, Chiral & Chemotactic



Chemotaxis Bacteria



Agent-based Chemotaxis Model to Smoluchowski Equation

Single Agent

$$\begin{aligned}\dot{\mathbf{r}}_1(t) &= \beta_D \nabla_c (\mathbf{r}_1(t), t) + \sqrt{2D} \boldsymbol{\xi}(t) \\ \dot{c}(\mathbf{r}, t) &= D_c \nabla^2 c(\mathbf{r}, t) + k_0 \delta(\mathbf{r} - \mathbf{r}_1) - k_d c(\mathbf{r}, t)\end{aligned}$$

Multi Agents

$$\begin{aligned}\dot{\mathbf{r}}_i(t) &= \beta_D \nabla_c (\mathbf{r}_i(t), t) + \sqrt{2D} \boldsymbol{\xi}(t) \\ \dot{c}(\mathbf{r}, t) &= D_c \nabla^2 c(\mathbf{r}, t) + k_0 \sum_{i=1}^N \delta(\mathbf{r} - \mathbf{r}_i) - k_d c(\mathbf{r}, t)\end{aligned}$$

Smoluchowski Equation

$$\begin{aligned}\dot{\rho} &= -\nabla \cdot (\beta_D \rho \nabla c) + D \nabla^2 \rho \\ \dot{c} &= D_c \nabla^2 c + k_0 \rho - k_d c\end{aligned}$$

Generalized Keller–Segel (K–S) model

$$\begin{aligned}\frac{\partial b}{\partial t} &= \nabla \cdot (\mu(s) \nabla b) - \nabla \cdot (\chi(s) b \nabla s) + g(b, s) - h(b, s), \\ \frac{\partial s}{\partial t} &= D \nabla^2 s - f(b, s),\end{aligned}$$

[1] Keller, E., Segel, L., 1970. Initiation of slime mold aggregation viewed as an instability. J. Theor. Biol. 26, 399–415.

[2] Keller, E., Segel, L., 1971a. Model for chemotaxis. J. Theor. Biol. 30(2), 225–234.

A trivial solution:

Uniform disordered phase / Equilibrium state

$$\rho(\mathbf{r}, t) \equiv \rho_0$$

$$c(\mathbf{r}, t) \equiv \frac{k_0 \rho_0}{k_d}$$

Keller–Segel instability

Smoluchowski Equation

$$\dot{\rho} = -\nabla \cdot (\beta_D \rho \nabla c) + D \nabla^2 \rho$$

$$\dot{c} = D_c \nabla^2 c + k_0 \rho - k_d c$$

Linear stability
analysis



$$(\rho, c) = (\rho_0, k_0 \rho_0 / k_d)$$

$$\rho = \rho_0 + \delta \rho, \quad c = c_0 + \delta c \quad (|\delta \rho| \ll \rho_0, |\delta c| \ll c_0)$$

$$\begin{aligned} \dot{\delta \rho} &= -\beta_D \nabla \cdot (\rho \nabla \delta c) + D \nabla^2 \delta \rho \\ &= -\beta_D \nabla \cdot [(\rho_0 + \delta \rho) \nabla (c_0 + \delta c)] + D \nabla^2 (\rho_0 + \delta \rho) \\ &= D \nabla^2 \delta \rho - \beta_D \rho_0 \nabla^2 \delta c - \beta_D \nabla \cdot \underbrace{(\delta \rho \nabla \delta c)}_{\approx 0} \end{aligned}$$

$$= D \nabla^2 \delta \rho - \beta_D \rho_0 \nabla^2 \delta c$$

$$\begin{aligned} \dot{\delta c} &= D_c \nabla^2 \delta c + k_0 \delta \rho - k_d \delta c + \underbrace{k_0 \delta_0 - k_d c_0}_{=0} \\ &= D_c \nabla^2 \delta c + k_0 \delta \rho - k_d \delta c \end{aligned}$$

Take the form of a plane wave:

$$\delta \rho = \delta \rho_0 e^{\sigma t + \mathbf{i} \mathbf{k} \cdot \mathbf{r}}, \quad \delta c = \delta c_0 e^{\sigma t + \mathbf{i} \mathbf{k} \cdot \mathbf{r}}$$

Symbol	Means
σ	growth rate
\mathbf{k}	wave vector (representing the oscillation mode in space)
$k = \mathbf{k} $	wave numbers (LSA usually focuses on the σ corresponding to different wave numbers)

For $\delta \rho = \delta \rho_0 e^{\sigma t + \mathbf{i} \mathbf{k} \cdot \mathbf{r}}$

left = $\dot{\delta \rho} = \sigma \delta \rho_0 e^{\sigma t + \mathbf{i} \mathbf{k} \cdot \mathbf{r}}$

right = $D(-k^2) \delta \rho_0 e^{\sigma t + \mathbf{i} \mathbf{k} \cdot \mathbf{r}} - \beta_D \rho_0 (-k^2) \delta c_0 e^{\sigma t + \mathbf{i} \mathbf{k} \cdot \mathbf{r}}$

$$\sigma \delta \rho_0 = -D k^2 \delta \rho_0 + \beta_D \rho_0 k^2 \delta c_0$$

$$\begin{cases} \sigma \delta \rho_0 = -D k^2 \delta \rho_0 + \beta_D \rho_0 k^2 \delta c_0 \\ \sigma \delta c_0 = -D_c k^2 \delta c_0 + k_0 \delta \rho_0 - k_d \delta c_0 \end{cases}$$

Keller–Segel instability

$$\begin{cases} \sigma \delta \rho_0 = -Dk^2 \delta \rho_0 + \beta_D \rho_0 k^2 \delta c_0 \\ \sigma \delta c_0 = -D_c k^2 \delta c_0 + k_0 \delta \rho_0 - k_d \delta c_0 \end{cases}$$

This can be written in matrix form

$$\begin{pmatrix} \sigma + Dk^2 & -\beta_D \rho_0 k^2 \\ -k_0 & \sigma + D_c k^2 + k_d \end{pmatrix} \begin{pmatrix} \delta \rho_0 \\ \delta c_0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

In order to have non-zero solutions, the det of the coefficient matrix must be 0:

$$\det \begin{pmatrix} \sigma + Dk^2 & -\beta_D \rho_0 k^2 \\ -k_0 & \sigma + D_c k^2 + k_d \end{pmatrix} = 0$$



$$\sigma^2 + [(D + D_c)k^2 + k_d]\sigma + DD_c k^4 + (Dk_d - \beta_D \rho_0 k_0)k^2 = 0$$

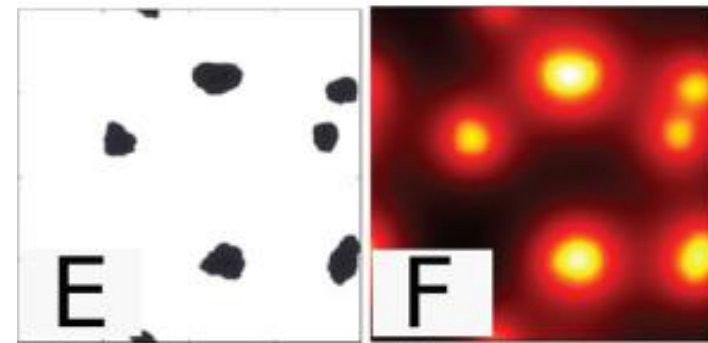
$$\forall k, \sigma < 0 \Rightarrow \forall k, \begin{cases} (D + D_c)k^2 + k_d > 0 \\ DD_c k^4 + (Dk_d - \beta_D \rho_0 k_0)k^2 > 0 \end{cases}$$

$$\Rightarrow Dk_d > \beta_D \rho_0 k_0$$

Keller–Segel instability:

$$\beta_D \rho_0 k_0 > Dk_d$$

The Keller–Segel instability leads to clusters of active particles and colocated clusters of the self-produced chemical that grow in the course of the time due to coarsening and cluster coalescence:



Chemotaxis Self-propelled Particles

$$\dot{\mathbf{r}}(t) = \nu_0 \mathbf{p} + \beta_d \nabla c(\mathbf{r}(t), t) + \sqrt{2D} \boldsymbol{\xi}(t)$$

$$\dot{\theta}(t) = \beta \mathbf{p} \times \nabla c(\mathbf{r}(t), t) + \sqrt{2D_r} \eta(t)$$

$$\dot{c}(\mathbf{r}, t) = D_c \nabla^2 c(\mathbf{r}, t) + k_0 \sum_{i=1}^N \delta(\mathbf{r} - \mathbf{r}_i) - k_d c(\mathbf{r}, t)$$

$$\mathbf{p} = (\cos \theta, \sin \theta)$$

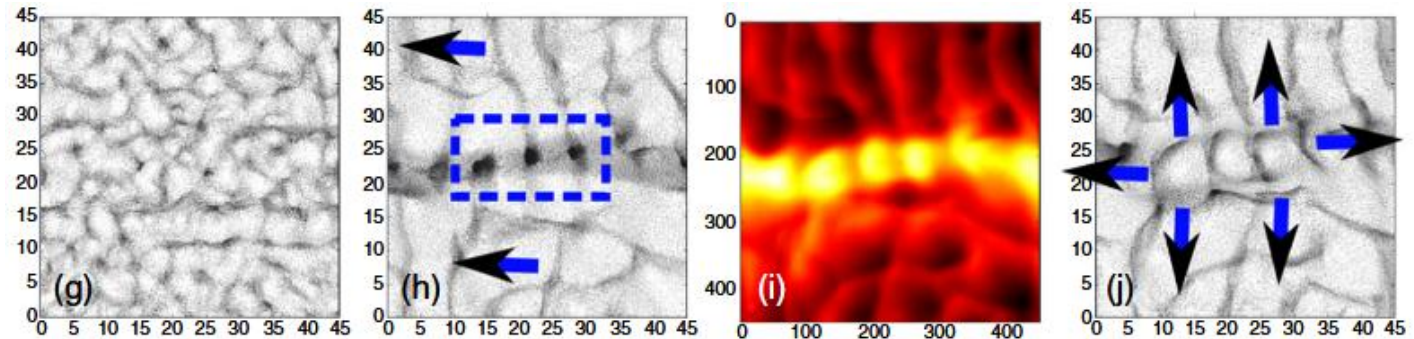
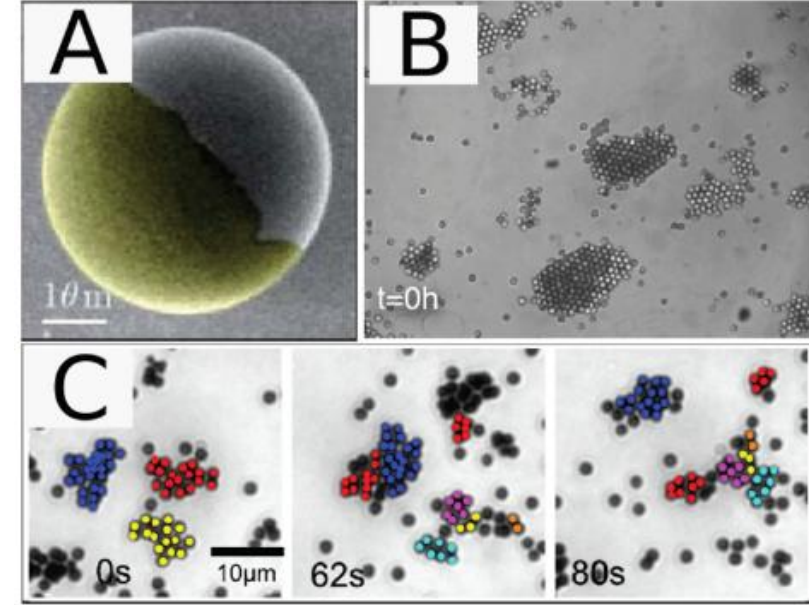
Phoretic Interactions Generically Induce Dynamic Clusters and Wave Patterns in Active Colloids:

$$\dot{\mathbf{r}}_i(t) = v \mathbf{p}_i, \quad (1)$$

$$\dot{\theta}_i(t) = \beta \mathbf{p}_i \times \nabla c + \sqrt{2D_r} \eta_i(t). \quad (2)$$

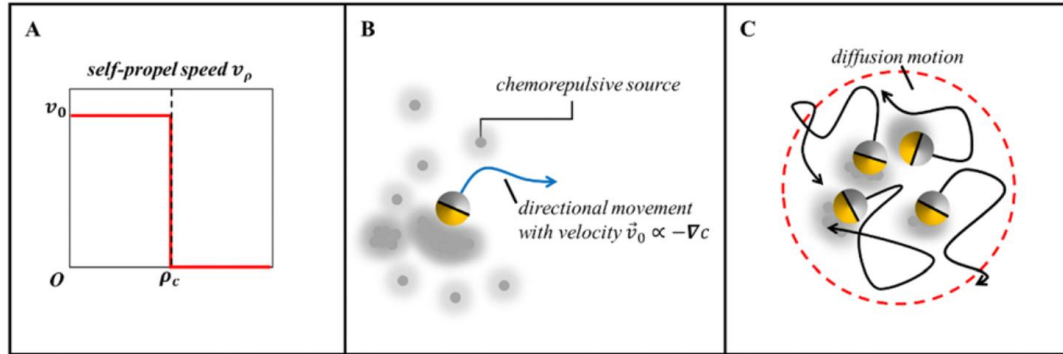
$$\dot{c}(\mathbf{r}, t) = D_c \nabla^2 c - k_d c + \sum_{i=1}^N \oint d\mathbf{x}_i \delta(\mathbf{r} - \mathbf{r}_i(t) - R_0 \mathbf{x}_i) \sigma(\mathbf{x}_i). \quad (3)$$

Janus colloid



A Variety of Chemotaxis Particles

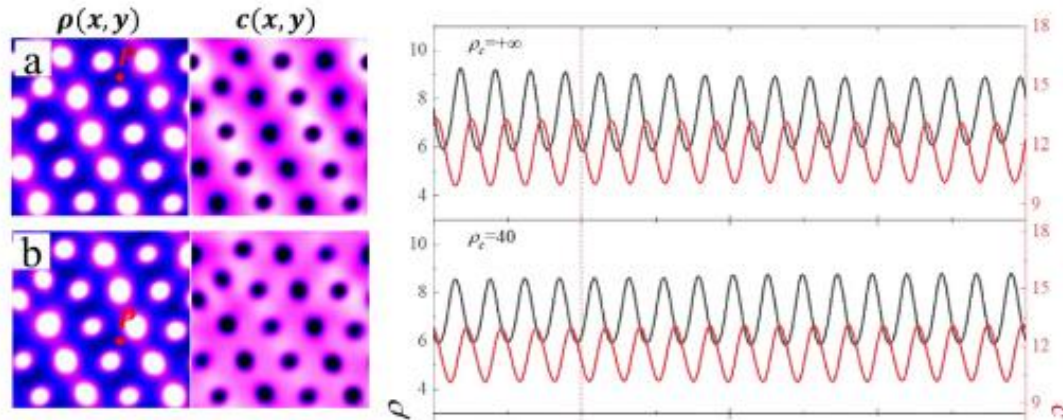
Quorum sensing-induced transition



$$\dot{\rho} = -\nabla \cdot (\rho v_{\rho} \mathbf{P}) + D_{\rho} \nabla^2 \rho$$

$$\dot{\mathbf{P}} = -\gamma \mathbf{P} + D_{\mathbf{P}} \nabla^2 \mathbf{P} + \beta \nabla c - \gamma_2 |\mathbf{p}^2| \mathbf{P}$$

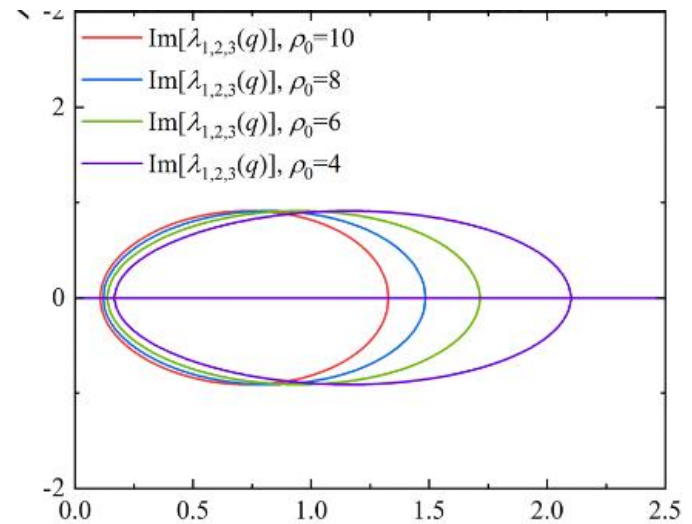
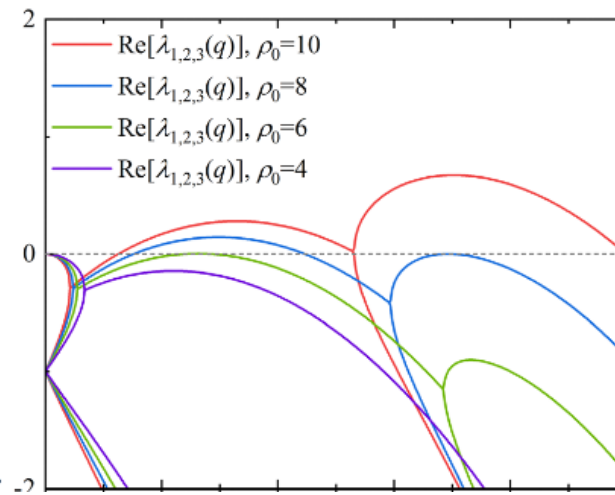
$$\dot{c} = D_c \nabla^2 c + k_0 \rho - k_d c + k_a \nabla \cdot (\rho \mathbf{P})$$



$$\begin{pmatrix} \dot{\delta \rho} \\ \dot{\delta \mathbf{P}} \\ \dot{\delta c} \end{pmatrix} = M \begin{pmatrix} \delta \rho \\ \delta \mathbf{P} \\ \delta c \end{pmatrix}; \quad M = \begin{pmatrix} \partial_x^2 & -\rho_0 \partial_x & 0 \\ 0 & -\Gamma + \mathcal{D}_{\mathbf{P}} \partial_x^2 & s \partial_x \\ 1 & \kappa \rho_0 \partial_x & \mathcal{D}_c \partial_x^2 - 1 \end{pmatrix}$$

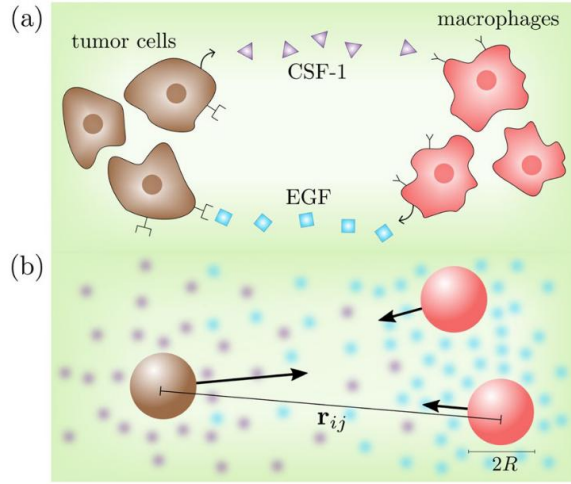
$$P(\lambda) = \det(M - \lambda I)$$

$$= (z^2 - \lambda)(z^2 \mathcal{D}_c - \lambda - 1)(-\Gamma + z^2 \mathcal{D}_{\mathbf{P}} - \lambda) - \rho_0 s z^2 (-\kappa \lambda + \kappa z^2 + 1)$$



A Variety of Chemotaxis Particles

Swarm Hunting in chemically communicating Active Mixtures



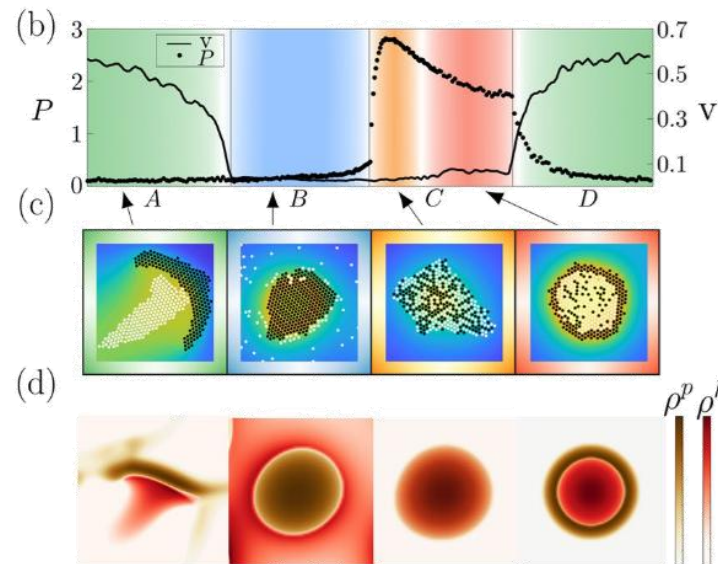
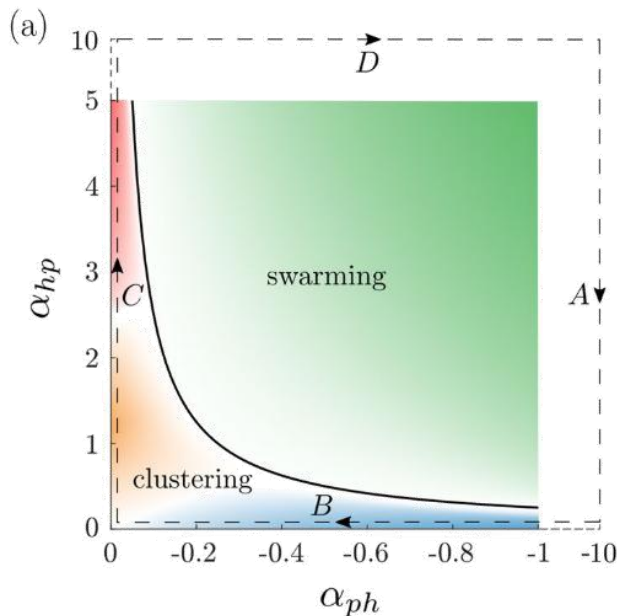
$$\partial_t \mathbf{r}_i^s(t) = \sum_{s' \in \{p, h\}} \alpha_{ss'} \nabla c^{s'} - \nabla_{\mathbf{r}_i} V + \sqrt{2D} \boldsymbol{\eta}_i^s$$

$$\partial_t c^s(\mathbf{r}, t) = (D_c \Delta - \mu) c^s + \sum_{i=1}^N \delta(\mathbf{r} - \mathbf{r}_i^s)$$

$$\begin{aligned} \partial_t \delta \rho^p &= D \Delta \delta \rho^p - \alpha_{pp} \rho_0^p \Delta \delta c^p - \alpha_{ph} \rho_0^p \Delta \delta c^h \\ \partial_t \delta \rho^h &= D \Delta \delta \rho^h - \alpha_{hh} \rho_0^h \Delta \delta c^h - \alpha_{hp} \rho_0^h \Delta \delta c^p, \end{aligned}$$

$$\partial_t \delta c^s = D_c \Delta \delta c^s + \delta \rho^s - \mu \delta c^s.$$

$$\lambda \begin{pmatrix} \delta \hat{\rho}^p \\ \delta \hat{c}^p \\ \delta \hat{\rho}^h \\ \delta \hat{c}^h \end{pmatrix} = \begin{pmatrix} -D \mathbf{q}^2 & \alpha_{pp} \rho_0^p \mathbf{q}^2 & 0 & \alpha_{ph} \rho_0^p \mathbf{q}^2 \\ 1 & -D_c \mathbf{q}^2 - \mu & 0 & 0 \\ 0 & \alpha_{hp} \rho_0^h \mathbf{q}^2 & -D \mathbf{q}^2 & 0 \\ 0 & 0 & 1 & -D_c \mathbf{q}^2 - \mu \end{pmatrix} \begin{pmatrix} \delta \hat{\rho}^p \\ \delta \hat{c}^p \\ \delta \hat{\rho}^h \\ \delta \hat{c}^h \end{pmatrix}$$



- (a) The steady state is stable, if the eigenvalues of the matrix all have real parts strictly less than zero.
- (b) The steady state is unstable, if at least one of the eigenvalues of the matrix has a positive real part.
- (c) Otherwise in the marginal case higher order terms determine the stability of the problem.

Application of Chemotaxis Particles

Collective chemotactic search strategies

$$\dot{\mathbf{r}}_i(t) = v_0 \mathbf{e}_i(t) + \sum_{j=1}^N \frac{\mathbf{f}(r_{ij})}{\gamma_t},$$

$$\dot{\varphi}_i(t) = \frac{\kappa}{\gamma_r} [\nabla c(\mathbf{r}_i(t), t) \times \mathbf{e}_i(t)]_z + \sqrt{2D_r} \eta_i(t),$$

$$\dot{c}(\mathbf{r}, t) = D_c \nabla^2 c(\mathbf{r}, t) - k_c c(\mathbf{r}, t) + h_c \sum_{i=1}^N \delta(\mathbf{r} - \mathbf{r}_i(t)).$$

$$\mathbf{e}_i(t) = (\cos \varphi_i(t), \sin \varphi_i(t))^\top$$

$$l_p = v_0 / (a D_r), \quad \Lambda = \kappa h_c a / \gamma_r D_c^2$$

$\sigma_{\mathcal{A}}^{\text{ind}} / \sigma_{\mathcal{A}} > 0$, more uniform

$\bar{T}_N^{\text{ind}} / \bar{T}_N$, collective more advantageous

