

# Chemotactic Network Designing

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# 1 Models

## 1.1 Thinking Process

$$\dot{\mathbf{r}}_i(t) = \alpha_c \nabla c - \nabla_{\mathbf{r}_i} V + \sqrt{2D_p} \boldsymbol{\eta}_i \quad (1a)$$

$$\dot{c}(\mathbf{r}, t) = D_c \nabla^2 c - k_c c + \beta_c \sum_j \delta(\mathbf{r} - \mathbf{r}_j^*) \quad (1b)$$

for  $i = 1, 2, \dots, N$  and  $j = 1, 2, \dots, M$ . Here,  $\mathbf{r}_i, \mathbf{r}_j^*$  is the position of the  $i$ -th particle,  $j$ -th target node, respectively,  $c$  is the concentration of the signal chemical released by the node,  $\alpha_c < 0$  is the chemotactic sensitivity,  $V$  is the potential field of short-range repulsion,  $D_p$  is the intensity of thermal noise,  $s_i$  is the internal state of the  $i$ -th particle,  $D_c$  is the diffusion coefficient,  $k_c$  is the decay rate of the chemical, and  $\beta_c$  is the production rate of the target nodes.

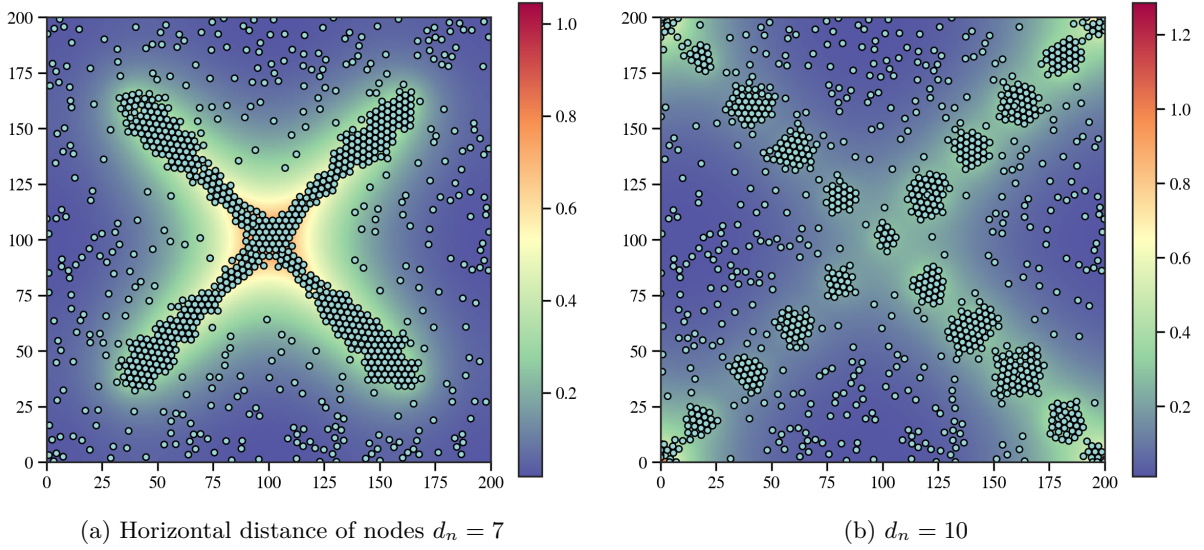


Figure 1: The simulation of the above model with  $\alpha_c = -5$ ,  $D_c = 2$ ,  $k_c = 0.001$  and  $\beta_c = 0.3$ . When the horizontal distance of nodes  $d_n$  is small, the nodes are connected by the particles. While, when  $d_n$  is large, the particles are not connected.

The above model have initially realized the network formation, but it does not solve the problem when the distance between nodes is large. To address this, we introduce a convection term  $\mathbf{v} \cdot \nabla c$  in the chemical equation, which represents the influence of the particles' active transport on the chemical field. The updated model is as follows:

$$\dot{\mathbf{r}}_i(t) = \alpha_c \nabla c - \nabla_{\mathbf{r}_i} V + \sqrt{2D_p} \boldsymbol{\eta}_i, \quad (2a)$$

$$\dot{c}(\mathbf{r}, t) = D_c \nabla^2 c - \mathbf{v} \cdot \nabla c - k_c c + \beta_c \sum_j \delta(\mathbf{r} - \mathbf{r}_j^*), \quad (2b)$$

where  $\mathbf{v} = v_c \sum_{i=1}^N \delta(\mathbf{r} - \mathbf{r}_i) (\cos \phi_{\mathbf{r}}, \sin \phi_{\mathbf{r}})^\top$  is the convection velocity of the chemical field,  $v_c$  is the convection speed, and

$$\phi_{\mathbf{r}} = \tan^{-1} \left( \frac{y_{\text{cm}} - y_i}{x_{\text{cm}} - x_i} \right) \quad (3)$$

is the angle toward the particle's center of mass at position  $\mathbf{r}$ , where  $(x_{\text{cm}}, y_{\text{cm}})^\top = N^{-1} \sum_i \mathbf{r}_i$ .

$$\dot{\mathbf{r}}_i(t) = \alpha_c \nabla c - \nabla_{\mathbf{r}_i} V + \sqrt{2D_p} \boldsymbol{\eta}_i, \quad (4a)$$

$$\dot{c}(\mathbf{r}, t) = D_c \nabla^2 c - k_c c + \sum_j s_j \delta(\mathbf{r} - \mathbf{r}_j^*), \quad (4b)$$

$$\dot{s}_j(t) = (1 + s_j)(1 - s_j) \left( s_{\text{th}} - \sum_i \delta(\mathbf{r}_i - \mathbf{r}_j^*) \right) \quad (4c)$$

## **2 Behaviors**

## **3 Continuum model**