

# Project Report

An Implementation Of:  
A Simple Randomized  $O(n \log n)$ –Time Closest-Pair  
Algorithm in Doubling Metrics

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## 1 Introduction

Implementation of an algorithm helps us observe its efficiency and behavior in practice. In this report, I will briefly explain each part of the closest-pair doubling algorithm [1], show the program’s implementation along with practical running time analysis, and some implementation techniques I used. The theoretical information in this report fully refers to the work of A. Maheshwari, W. Mulzer and M. Smid, see [1].

The closest-pair algorithm consists of three smaller parts:

1. Computing a separating annulus, denoted  $\text{SEPANN}(S, n, d, \mu, c)$
2. The refinement of  $\text{SEPANN}(S, n, d, \mu, c)$ , denoted  $\text{SPARSESEPANN}(S, n, d, t)$
3. The main recursive closest-pair algorithm, denoted  $\text{CLOSESTPAIR}(S, n, d)$

Throughout the paper, let:

- $(P, \text{dist})$  be a finite metric space in which  $P$  is the set of all points, and  $\text{dist}$  is the function that calculate the distance between any two points
- $d$  be the space’s doubling dimension
- $S$  be a non-empty subset of  $P$

**Note:** I will only mention about 2D points because of the extremely high running time of the algorithm in the space more than 3D (in which the doubling dimension is approximately at least  $\log_2 21$  that gives us the base case with more than 3,000,000 points).

## 2 Algorithm 1: Computing a separating annulus

An important part of the main closest-pair algorithm is finding a separating annulus in the subset  $S$ . I will briefly describe this algorithm in the next subsection, due to A. Maheshwari, W. Mulzer and M. Smid [1, Section 3.1].

### 2.1 The $\text{SEPANN}(S, n, d, \mu, c)$ algorithm

In this section,  $\mu \geq 1$  is a real constant number,  $c$  is calculated based on  $\mu$  (I would say that  $c = 2(4\mu)^d$  [1, Remark 1] since  $\mu$  is not an integer in this case [1, Section 3.2]).

This algorithm picks a uniformly random point  $p$  from the subset  $S$  then finds the smallest ball centered at  $p$ , denoted  $\text{ball}_S(p, R_p)$ , that contains at least  $n/c$  point. If the outer ball  $\text{ball}_S(p, \mu R_p)$  contains at most  $n/2$  points, it returns  $p$  and  $R_p$ . If not, this procedure is repeated until the condition is satisfied. This algorithm's pseudocode is given below.

<p><b>Algorithm 1:</b> <math>\text{SPARSESEPANN}(S, n, d, t)</math></p> <p><b>Input:</b> Let <math>S</math> be a subset of <math>P</math>, of size <math>n</math>, <math>d</math> be the metric space's doubling dimension, <math>\mu \geq 1</math> and <math>c &gt; 1</math> be large enough real numbers.</p> <p><b>repeat</b></p> <p>    <math>p =</math> a uniformly random point in <math>S</math>;</p> <p>    <math>R_p = \min\{r &gt; 0 :  \text{ball}_S(p, r)  \geq n/c\}</math>;</p> <p><b>until</b> <math> \text{ball}_S(p, \mu R_p)  \leq n/2</math></p> <p>return <math>p</math> and <math>R_p</math></p>
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*This pseudocode is from [1, Section 3.1]*

### 2.2 Finding the $K^{\text{th}}$ smallest element

One step in  $\text{SEPANN}(S, n, d, \mu, c)$  algorithm is to find the smallest ball which contains at least  $n/c$  points. This ball is easy to find using the  $k^{\text{th}}$  smallest element algorithm. Particularly, in a list of distances between  $p$  and all other points in  $S$ , we pick the  $\lceil n/c \rceil$ -th smallest element and let it be the radius of the ball we need to find. Thus, all points closer to  $p$  are inside this ball.

A very easy approach to find the  $k^{\text{th}}$  smallest element in a list is to sort it in ascending order, and then simply return the element at the  $k^{\text{th}}$  place. This sorting algorithm takes  $O(n \log n)$  time complexity in the worst case. Fortunately, we can improve the running time to  $O(n)$  using a common recursive technique called Quickselect, which is similar to Quicksort.

Given an unordered list  $D$  which contains  $n$  numbers, and a positive integer  $k$  satisfies  $1 \leq k \leq n$ . Each element in  $D$  has an index from 0 to  $n-1$ . Consider a sublist of  $D$ , denoted  $D[a : b]$ , which starts from index  $a$  and ends at  $b$ , inclusively. The base case is when  $a = b$ , the algorithm returns the only element in that sublist. If it is not the case, the algorithm will choose a random *pivot* in the list. The algorithm then rearranges the list so that all elements smaller and larger than the pivot are to the left and right of it, respectively. Now, the pivot has a new index, says  $c$ . If  $k = c - a + 1$ , the chosen pivot is the  $k^{\text{th}}$  smallest element of  $D$ , the algorithm returns  $D[c]$ . If  $k < c - a + 1$ , the algorithm recurses on the

sublist to the left of the pivot,  $D[a : c - 1]$ . If  $k > c - a + 1$ , the algorithm recurses on the sublist to the right of the pivot,  $D[c + 1 : b]$ . This algorithm's pseudocode is given below.

<p><b>Algorithm:</b> KTHSMALLEST(<math>D, a, b, k</math>)</p> <p><b>Input:</b> Let <math>D</math> be a list of double numbers, the integers <math>a</math> and <math>b</math> respectively be the starting and ending indices of a sublist and <math>k</math> be an integer refers to the <math>k^{th}</math> smallest element.</p> <pre> <b>if</b> <math>a == b</math> <b>then</b>     return <math>D[i]</math> <b>else</b>     <math>p</math> = a random element in <math>D</math>;     <b>rearranging:</b>         all elements smaller than <math>p</math> to the left of <math>p</math>;         all elements larger than <math>p</math> to the right of <math>p</math>;     <b>end;</b>     <math>c</math> = the current index of <math>p</math> in <math>D</math>;     <b>if</b> <math>k == c - a + 1</math> <b>then</b>         return <math>p</math>     <b>else if</b> <math>k &lt; c - a + 1</math> <b>then</b>         return KTHSMALLEST(<math>D, a, c - 1, k</math>)     <b>else</b>         return KTHSMALLEST(<math>D, c + 1, b, k</math>)     <b>endif;</b> <b>endif;</b> </pre>
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Unlike the original Quicksort algorithm, the Quickselect recurses only once and on one side after rearranging. This helps the algorithm remain  $O(n)$  time complexity. By using the random selection, the pivot on average is close to the middle of the list. Therefore, with the input is an  $n$ -sized list  $D$ , the recursive call is on a sublist whose size is a half. Because the rearrangement takes  $O(n)$  time, this algorithm takes at most  $2n$  time which is  $O(n)$ . The running time is shown below:

$$O(n) + O(n/2) + O(n/4) + \dots \leq O(2n) = O(n)$$

The following image is one of many outputs using different number of elements and  $k$  value. I generated 100,000,000 numbers uniformly random in the range  $[-100000, 100000]$  with  $k = 76,543,210$ .

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Number of elements: 100,000,000
k: 76,543,210
Value range: -100,000 to 100,000
- O(nlogn) Result Using Sort: 53086.024078
  Time taken: 59.389754s
- O(n) Result Using QuickSort Technique: 53086.024078
  Time taken: 3.889757s

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Figure 1: The outputs of the  $O(N\log N)$  algorithm using regular sorting and the  $O(n)$  Quickselect algorithm that recurses only once.

With the given number of elements,  $k$  and value range, both of the algorithms produced the same result, which is 53086.024078, but the running times of them have a significant difference (For the output capture, see Figure 1).

Since the Quickselect takes at most  $2n$  running time, the regular sorting takes at least  $\log(n)/2$  times more than it, and the  $\log$  is in base 2. In this case, there are 100,000,000 numbers, so:

$$\frac{\log(n)}{2} = \frac{\log(100,000,000)}{2} \approx 13.2877 \text{ times} \leq \frac{59.389754}{3.889757} \approx 15.268 \text{ times}$$

Since 15.268 is quite close to 13.2877, the running time of this Quickselect algorithm in practice is reasonable compared to the theory.

## 2.3 Probability to select a “good” point

Again, the goal of algorithm  $\text{SEPANN}(S, n, d, \mu, c)$  is to find a “good” point  $p$  in  $S$ . A “good” point  $p$  implies that with  $R_p$  (the radius of the smallest  $\text{ball}_S(p, R_p)$  that contains at least  $n/c$  points), the  $\text{ball}_S(p, \mu R_p)$  contains at most  $n/2$  points. Due to A. Maheshwari, W. Mulzer and M. Smid [1, Lemma 3], the algorithm has probability at least  $1/c$  (about  $1/1623.4$  in 2D space) to select a good point uniformly random from  $S$ .

The number of times the algorithm  $\text{SEPANN}(S, n, d, \mu, c)$  repeats until it gets a good point depends on the way how the input points are generated. I will show you some ways I use to generate the points based on some patterns which produced different number of times the algorithm repeats.

- The first way is **generating uniformly random** points spread throughout the space. This way of generating point produces a surprising behavior of this algorithm. Every time  $\text{SEPANN}(S, n, d, \mu, c)$  is called, it only repeats *once* until it gets to the base case, that means the probability to get a good point is 100%, see algorithm’s data on *GitHub repository*<sup>1</sup>. Since the points are generated randomly, so they change every time, there

<sup>1</sup>Random points SepAnn data. [https://github.com/ThangMinhCao/closestpairstdoubling/blob/master/report/images%26\\_data/closest\\_pair/random\\_generation/random\\_sep\\_ann\\_data.txt](https://github.com/ThangMinhCao/closestpairstdoubling/blob/master/report/images%26_data/closest_pair/random_generation/random_sep_ann_data.txt)

are no explanations about specific properties of the points in this case. However, since 100% satisfied the probability at least  $1/c$ , this result is reasonable.

- Another way is **generating points evenly in a grid**. Let  $n$  be the number of points,  $a$  and  $b$  be any two factors of  $n$  that satisfies  $a \times b = n$ ,  $d$  be the distances between any two points which are close together. The points are set into the  $a \times b$  grid which means each point is on a corner of a  $d$ -sided square, see Figure 2. When using this way to generate points, the algorithm  $\text{SEPANN}(S, n, d, \mu, c)$  now repeats multiple times which is its expected behavior, see. Again, the lowest probability in most of trials in this case is about  $1/20$  which satisfies probability at least  $1/c$ . See the algorithm grid data on *GitHub repository*<sup>2</sup>.

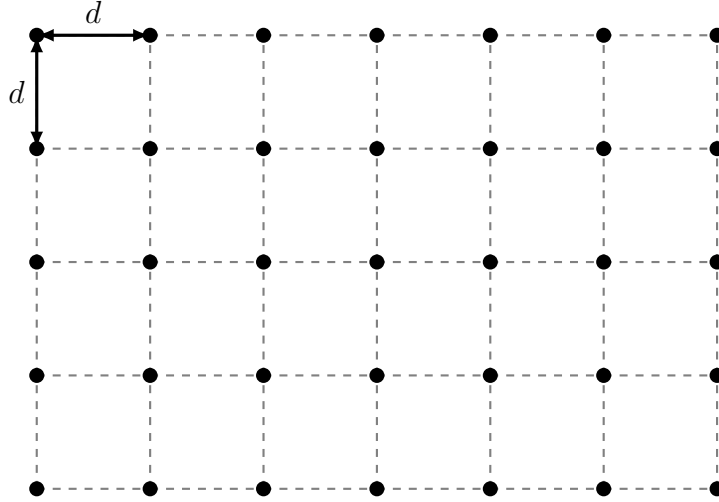


Figure 2: An example of generating points in grid. A set of 35 points that gives us a  $5 \times 7$  grid. Points are placed at corners of the squares with side is  $d$  which could be any number.

### 3 Algorithm 2: The refinement of $\text{SEPANN}(S, n, d, \mu, c)$

With the use of the algorithm  $\text{SEPANN}(S, n, d, \mu, c)$ 's output, this refinement algorithm continues to find an annulus that separates the points in  $S$  into different smaller sets of points.

Let  $\mu = e$  and  $c = 2(4e)^d$ , see [1, Remark 1]. The algorithm  $\text{SEPANN}(S, n, d, e, c)$  returns an annulus's center  $p \in S$  and its radius,  $R' > 0$ . An input of this refined algorithm is  $t > 0$ , a large enough constant calculated based on  $n$ . Let  $R_i = (1 + 1/t)^i \cdot R'$ , in which  $i$  is a uniformly random element inclusively from 1 to  $t$ . The algorithm then finds an annulus centered at  $p$  with the inner radius  $R_{i-1}$  and outer radius  $R_i$ , denoted  $A_i = \text{annulus}_S(p, R_{i-1}, R_i)$ . If the annulus contains at most  $n/t$  points then we are done. The algorithm returns  $p$  and  $R_{i-1}$ . If

<sup>2</sup>Grid points SepAnn data. [https://github.com/ThangMinhCao/closestpairstdoubling/blob/master/report/images%26\\_data/closest\\_pair/grid\\_generation/grid\\_sepenn\\_data.txt](https://github.com/ThangMinhCao/closestpairstdoubling/blob/master/report/images%26_data/closest_pair/grid_generation/grid_sepenn_data.txt)

this is not the case, the previous procedure is repeated until the condition is satisfied. The pseudocode of this refined algorithm is given below.

<b>Algorithm 2:</b> SPARSESEPANN( $S, n, d, t$ )
<p><b>Input:</b> Let <math>S</math> be a subset of <math>P</math>, of size <math>n \geq 2(4e)^d + 1</math>, <math>d</math> be the space's doubling dimension, <math>t \geq 1</math> be an integer.</p> <p><math>c = 2(4e)^d</math>;</p> <p>let <math>p \in S</math> and <math>R' &gt; 0</math> be the output of algorithm SEPANN(<math>S, n, d, e, c</math>);</p> <p><b>repeat</b></p> <p>    <math>i =</math> a uniformly random element in <math>\{1, 2, \dots, t\}</math>;</p> <p>    <math>R_i = (1 + 1/t)^i \cdot R'</math>;</p> <p>    <math>R_{i-1} = (1 + 1/t)^{i-1} \cdot R'</math>;</p> <p>    <math>A_i = \text{annulus}_S(p, R_{i-1}, R_i)</math>;</p> <p>    <math>s =  A_i </math>;</p> <p><b>until</b> <math>s \leq n/t</math>;</p> <p><math>R = R_{i-1}</math>;</p> <p>return <math>p</math> and <math>R</math></p>

*This pseudocode is from [1, Section 3.2]*

## 4 Algorithm 3: The main closest-pair algorithm

## 5 Implementation

This implementation of the closest-pair doubling algorithm of A. Maheshwari, W. Mulzer and M. Smid [1] is written in C++ since it is a very common and fast programming language with high-level supports of object-oriented programming that can help us organize the program efficiently (see the implementation's *GitHub repository*<sup>3</sup> for the source code).

## References

- [1] A. Maheshwari, W. Mulzer and M. Smid. *A Simple Randomized  $O(n \log n)$ -Time Closest-Pair Algorithm in Doubling Metrics*, 2020. <https://arxiv.org/abs/2004.05883>

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<sup>3</sup>GitHub repository of the implementation. <https://github.com/ThangMinhCao/closestpairstdoubling>