view frames Result

Recorded at time: 1614349122.7804172

map Broadcaster: /slam gmapping Average rate: 20.2 Buffer length: 5.0 Most recent transform: 1614349122.821 Oldest transform: 1614349117.821 odom Broadcaster: /robotino odometry node Average rate: 20.27 Buffer length: 4.933 Most recent transform: 1614349122.724 Oldest transform: 1614349117.791 base link Broadcaster: /tf base2laser Average rate: 10.189 Buffer length: 4.907 Most recent transform: 1614349122.84 Oldest transform: 1614349117.933 laser link