# Memory management

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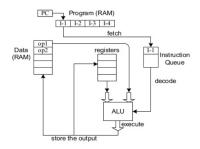
### Outline

- 1 Background
- 2 Swapping
- 3 Contiguous memory allocation
- 4 Segmentation
- 5 Paging
  - Structure of page table

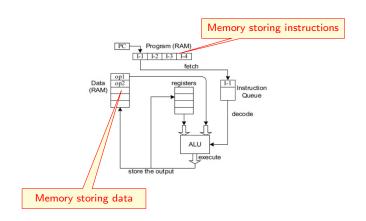
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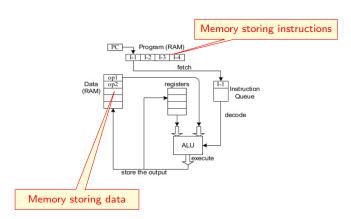
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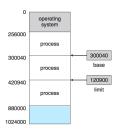
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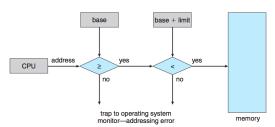


- Instructions of programs are only executed when they are in memory
- Memory management requires some hardware support

# Hardware support

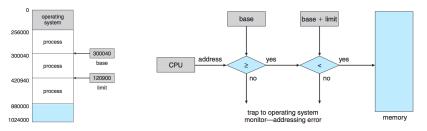
- Each user process has a separate memory space
- Base and limit registers give a range of the memory space





# Hardware support

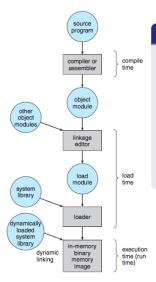
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Memory protection mechanism is not applied for operating system executing in kernel mode

## Address binding

User program to execution



#### Address binding

A process to convert one kind of high abstract memory address to low abstract memory address

- a symbolic address to a relocatable address
- a relocatable address to a absolute address

#### Example:

- a variable "count" → a relocatable address "14 bytes from the beginning of this module"
- "14 bytes from the beginning of this module"  $\rightarrow$  an absolute address "74014"

# Address binding

When it happens?

#### Binding is performed in any of following 3 steps

- Compile time: if starting location changes, absolute address must be regenerated (by compile)
- Load time: with relocatable code, only reloading is needed when starting address changes
- Execution time: if a process moved in memory, binding is delayed until its run time. Most general-purpose OSs use this method

# Logical address vs. physical address

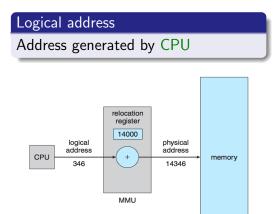
### Logical address

Address generated by CPU

### Physical address

Address seen by memory management unit (MMU)

## Logical address vs. physical address



### Physical address

Address seen by memory management unit (MMU)

- Compile/load-time binding: logical address = physical address
- Execution-time binding: logical address  $\neq$  physical address User program thinks logical (virtual) address range is [0, max], but physical address range is [R + 0, R + max].

# Dynamic loading

#### Dynamic loading

A routine is not loaded until it is called

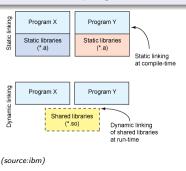
- Routine must be in relocatable load format
- Relocatable linking loader is responsible to load dynamic loading routing when a caller has not loaded yet
- Better memory=space utilization, useful to handle infrequently occurring cases
- Dynamic loading does not require support from OS

If multiple programs use a same routine, dynamic loading requires duplication of the routine in memory

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#### Dynamic linking

A routine is linked to user programs when the programs are run

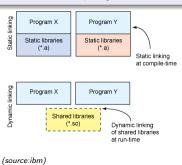


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#### Dynamic linking

A routine is linked to user programs when the programs are run

- A stub is put in the image of each reference
- The stub is replaced with the address of the needed routine, and then can be referred to by other references without loading

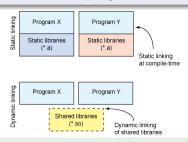


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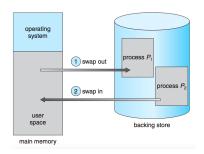
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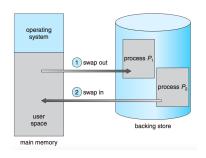
# Standard swapping

- Backing store must be large enough to accommodate copies of all memory images of all users
- Images of processes in ready queue are in backing store



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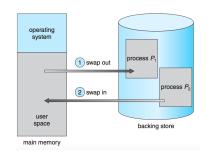


### Swapping is influenced by factors

- Transfer time between fast disk and memory
- Informing mechanism to activate swapping
- I/O waiting processes should be swapped out carefully

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Standard swapping is not used in modern OSs

# Swapping on mobile systems

#### Flash drives have finite number of write/erase cycles

- Mobile OSs do not support swapping
- OSs may terminate processes if memory is not sufficient
- Developers for mobile systems must carefully allocate and release memory

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Each process is contained in a single section of memory that is contiguous to the section of the next process

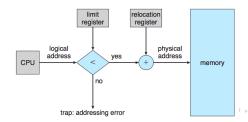
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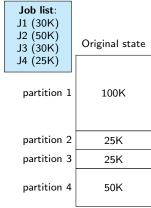
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OSs use relocation register for memory protection

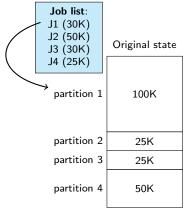


- Fixed-partition: memory is divided into several fixed-size partitions. A process is in a single partition
- Variable-partition: only assign enough memory for processes and OS keeps a table storing status of memory

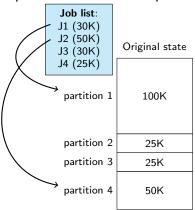
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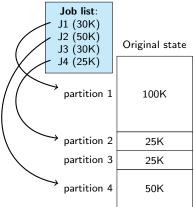
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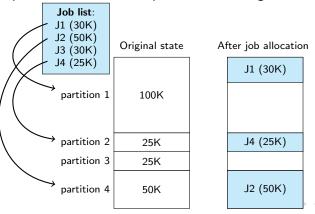
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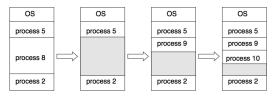


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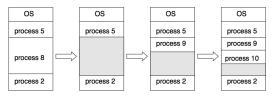
## Variable partition

- Fixed-partition scheme limits the level of multiprogramming
- Variable-partition scheme needs a mechanism to deal efficiently with set of holes



### Variable partition

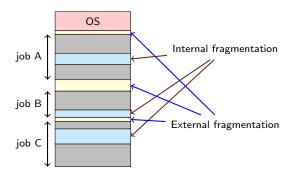
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- Variable-partition scheme needs a mechanism to deal efficiently with set of holes



- State: list of available (free) block sizes, input queue
- Dynamic storage-allocation problem: how to satisfy a request of size n from a list of free holes
- Strategies: first-fit, best-fit, worst-fit

## Fragmentation

Internal vs external



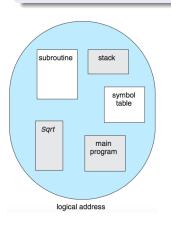
- External fragmentation: small holes which cannot satisfy large request
- Internal fragmentation: unused memory which has been allocated for process

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### What is segmentation?

Memory management should be convenient to both OS and programmers

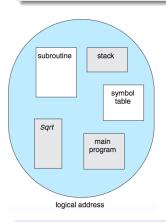


Programmers think of programs as set of data structures and methods. With memory, they need

- Collection of variable-sized memory blocks (segments)
- No neccessary ordering among segments

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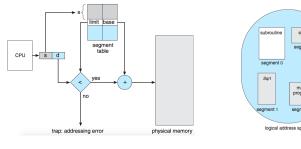
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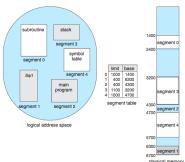
- Collection of variable-sized memory blocks (segments)
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Segment = <segment-number, offset>

### Segmentation hardware

Segment address is 2-dimensional, but physical memory address is 1-dimensional





Segment table is an array of base-limit register pairs

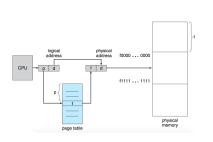
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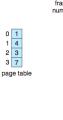
## What is paging?

Segmentation still has external fragmentation, requiring compaction

- Physical memory is divided into fixed-sized blocks (frame)
- Logical memory is divided into same-sized blocks (page)









physical memory

Page address = <page number, page offset>

Logical address space =  $2^m$ Page size =  $2^n$ 

page number	page offset	
р	d	
m-n	n	

Logical address space =  $2^m$ Page size =  $2^n$ 

page number	page offset	
p	d	
m-n	n	

0	a	
1 2 3 4 5 6 7	a b c d	
2	С	
3	d	
4	е	
5	f	
6		
7	g h	
8		
9	j k	
10	k	
11		
12	m	
13	n	
14	0	
15	р	
logical	memo	ory

0	5	1
1	6	1
2	1	
3	2	
page	tal	ole

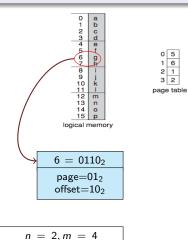


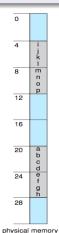
n = 2, m = 4



Logical address space =  $2^m$ Page size =  $2^n$ 

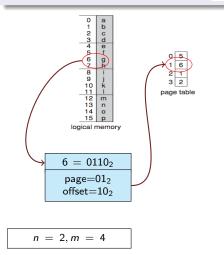
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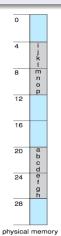


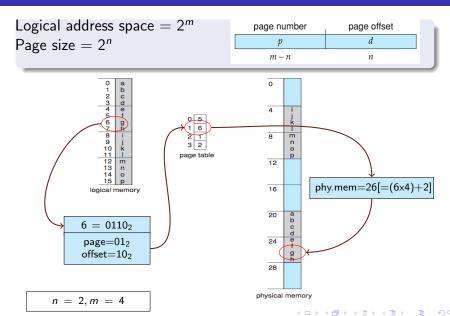


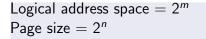
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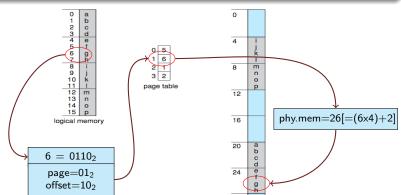






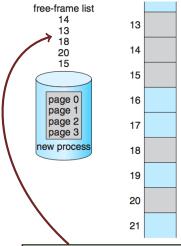




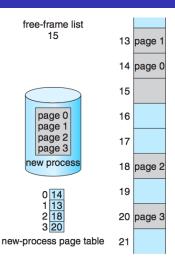


Paging has no external fragmentation, but has internal fragmentation.

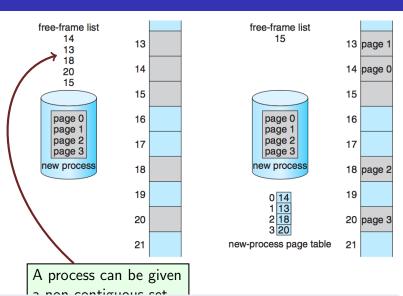
#### Frame allocation



A process can be given a non-contiguous set of frames



#### Frame allocation



A data structure (frame-table) is needed to manage frames.

### Hardware support

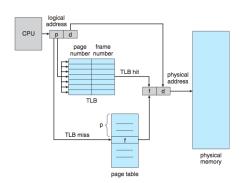
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  - A page table for each process, pointer to it in PCB
  - Few page tables for all processes

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- Page table stored in main memory,
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  - Few page tables for all processes
- Page-address translation overhead ⇒ hardware support
  - Page-table base register (PTBR): point to page table
  - Translation look-aside buffer (TLB): associative, high-speed memory (<key,value>)

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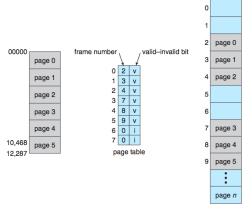


#### hit ratio

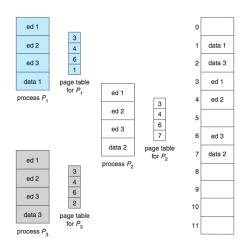
- 80% effective access time =  $80\% \times 100(ns) + 20\% \times 200(ns) = 120(ns)$
- 99% effective access time =  $99\% \times 100(ns) + 1\% \times 200(ns) = 101(ns)$

#### Protection

- From access permission: read-write/read-only bit
- From out-of-range access: valid-invalid bit
  - Just keep a small range of pages ⇒ page-table length register (PTLR)



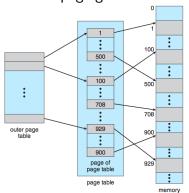
### Shared pages

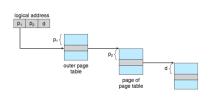


An advantage of paging is possibility of sharing common code

# Hierarchical paging

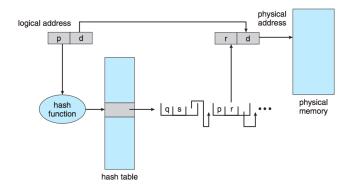
2-level paging scheme





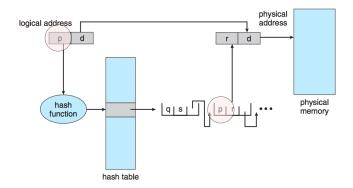
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# Hashed paging



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### Inverted paging

Just keep a page table for all processes. PID is needed to search for an address-space identifier

