Sierpinksi Triangle - Tarea 1

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Este código genera y visualiza el triángulo de Sierpinski utilizando una subdivisión recursiva, mientras que también calcula y analiza diferentes métricas de distancia entre los puntos del fractal.

1) Construcción del Triángulo de Sierpinski y Cálculo de Distancias

El triángulo de Sierpinski se genera dividiendo repetidamente un triángulo equilátero en sub-triángulos más pequeños. La función clave para esto es subdivide_triangle(), que toma un triángulo y genera tres sub-triángulos nuevos al calcular los puntos medios de sus lados.

Métricas de Distancia

Una vez que el triángulo es construido, el código analiza las distancias entre sus puntos utilizando cuatro métricas distintas:

1. Distancia Euclidiana (distance euclid(p1, p2))

• Es la distancia en línea recta entre dos puntos ((x_1, y_1)) y ((x_2, y_2)), calculada como:

$$[d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}]$$

• Es la distancia geométrica más intuitiva y se usa en muchas aplicaciones espaciales.

2. Distancia Manhattan (distance_manhattan(p1, p2))

• Se define como la suma de las diferencias absolutas en las coordenadas (x) e (y):

$$[d = |x_2 - x_1| + |y_2 - y_1|]$$

 Representa un movimiento restringido a una cuadrícula, donde no se permite el movimiento en diagonal.

3. Distancia Minkowski (distance_minkowski(p1, p2, p=3))

• Es una generalización de las distancias Euclidiana y Manhattan, definida como:

$$[d = \left(\frac{x_2 - x_1}{p} + \frac{y_2 - y_1}{p} \right)^{1/p}$$

• Para (p = 2), es equivalente a la distancia Euclidiana. Para (p = 1), se convierte en la distancia Manhattan. En el código se usa (p = 3) como ejemplo.

4. Distancia de Aparición (distance aparicion(p1, p2))

• No es una distancia geométrica, sino que mide cuántas iteraciones separan la aparición de dos puntos en la construcción del fractal:

```
[d = | \text{text{iteración}}(p_2) - \text{text{iteración}}(p_1) | ]
```

• Útil para analizar cómo emergen los puntos a lo largo del proceso recursivo.

2) Cálculo de Estadísticas de Distancia

La función compute_distance_data() calcula las distancias entre todos los puntos usando las métricas anteriores y almacena estadísticas resumidas:

- Distancias mínima, máxima, media y mediana para cada métrica.
- Una métrica "iteracion", que simplemente registra la iteración en la que apareció el punto.

Estos datos permiten analizar cómo se distribuyen las distancias dentro de la estructura fractal.

3) Visualización de Distancias

El código ofrece dos enfoques principales de visualización:

Colorear Puntos Según Métricas de Distancia

```
Función: plot_filled_new_triangles()
```

- Cada punto es coloreado según una estadística de distancia (por ejemplo, la distancia Euclidiana media).
- Los triángulos se rellenan según el nivel de iteración en el que fueron introducidos.
- Se usa una escala de colores para representar visualmente la variación de distancias.

Resaltar Distancias desde un Punto Específico

Función: plot_filled_triangles_and_point_metric()

- Se elige un punto de referencia y se colorean todos los demás puntos según su distancia a este.
- Permite visualizar cómo crecen las distancias dentro de la estructura fractal.
- El punto de referencia se resalta con un marcador especial.
- Permite obtener las distancias exactas de un punto a todos los demas mediante show_metrics_for_point()

```
In [2]: import numpy as np
        import matplotlib.pyplot as plt
        import matplotlib.patches as mpatches
        import matplotlib.colors as mcolors
        # 1) BUILD THE SIERPINSKI DATA
        def midpoint(A, B):
            return ((A[0] + B[0]) / 2.0, (A[1] + B[1]) / 2.0)
        def subdivide triangle(tri):
            Given tri = (A,B,C),
            return the 3 corner sub-triangles
            formed by connecting midpoints.
            A, B, C = tri
            AB_mid = midpoint(A, B)
            BC mid = midpoint(B, C)
            CA_mid = midpoint(C, A)
            return [
                (A, AB_mid, CA_mid), # corner that includes A
                (B, BC_mid, AB_mid), # corner that includes B
                (C, CA_mid, BC_mid) # corner that includes C
            ]
        def sierpinski_triangles_and_points(k):
            Returns:
              triangles by iter[i] = list of sub-triangles introduced at iteration i
              points_list = [(x, y, iterationOfAppearance), ...]
            triangles_by_iter = {}
            point_appearance = {}
            # Iteration 1: one big triangle
            t0 = ((0,0), (1,0), (0.5, np.sqrt(3)/2))
            triangles_by_iter[1] = [t0]
            # Mark these 3 corners as "first appeared in iter=1"
            for corner in t0:
                point appearance[corner] = 1
            # For each iteration > 1, subdivide the previous iteration's triangles
            for i in range(2, k+1):
                new_tris = []
                for tri in triangles_by_iter[i-1]:
                    subs = subdivide_triangle(tri)
                    new tris.extend(subs)
                    # Mark new midpoints as iteration i (if not seen before)
                    for sub t in subs:
                         for corner in sub_t:
                            if corner not in point_appearance:
                                 point_appearance[corner] = i
                triangles_by_iter[i] = new_tris
            # Build the full list of points
            points_list = [(p[0], p[1], it) for (p,it) in point_appearance.items()]
```

```
return triangles_by_iter, points_list
# -----
# 2) DISTANCES AND STATISTICS
def distance euclid(p1, p2):
   """distance between two points in 2D"""
   return np.sqrt((p1[0]-p2[0])**2 + (p1[1]-p2[1])**2)
def distance manhattan(p1, p2):
   """distance defined by sum of absolute differences in each dimension"""
   return abs(p1[0] - p2[0]) + abs(p1[1] - p2[1])
def distance_minkowski(p1, p2, p=3):
   """distance defined by the Minkowski metric"""
   return (abs(p1[0]-p2[0])**p + abs(p1[1]-p2[1])**p)**(1.0/p)
def distance_aparicion(p1, p2):
   """Difference in iteration of appearance - not a real distance"""
   return abs(p1[2] - p2[2])
def compute_distance_data(points):
   For each point i, compute distances to all others
   in these metrics: Euclid, Manhattan, Minkowski(p=3), Aparicion.
   Then store min, max, mean, median.
   Also define a 'iteracion' "metric" => the point's own iteration,
   so we can color by iteration directly.
   dist_data = {}
   n = len(points)
   def stats(arr):
       arr_np = np.array(arr)
       return {
            'values': arr,
            'min': float(np.min(arr_np)) if len(arr_np)>0 else 0.0,
           'max': float(np.max(arr_np)) if len(arr_np)>0 else 0.0,
           'mean': float(np.mean(arr np)) if len(arr np)>0 else 0.0,
            'median': float(np.median(arr_np)) if len(arr_np)>0 else 0.0,
       }
   for i in range(n):
       p_i = points[i]
       dist_eu, dist_man, dist_mink, dist_ap = [], [], [], []
       for j in range(n):
           if i == j:
               continue
           p_j = points[j]
           dist_eu.append(distance_euclid(p_i, p_j))
           dist man.append(distance manhattan(p i, p j))
           dist_mink.append(distance_minkowski(p_i, p_j, p=3))
           dist_ap.append(distance_aparicion(p_i, p_j))
       # iteration metric => the point's own iteration
       iteration_value = p_i[2]
       iteration_stats = {
            'values': [iteration_value],
```

```
'min': iteration_value,
            'max': iteration_value,
            'mean': iteration_value,
           'median': iteration_value,
       }
       dist_data[i] = {
            'point': p_i,
            'euclid': stats(dist_eu),
            'manhattan': stats(dist_man),
           'minkowski': stats(dist_mink),
            'aparicion': stats(dist_ap),
            'iteracion': iteration_stats
       }
   return dist_data
# 3) SHOW METRICS FOR A SPECIFIC POINT
def show_metrics_for_point(dist_data, i):
   Prints the stored distance stats for the point with index i.
   (Indices match the order in 'points_list'.)
   if i not in dist_data:
       print(f"No data for point index {i}!")
       return
   p = dist_data[i]['point'] # (x, y, iteration)
   print(f"\nMetrics for point index={i} => coords=({p[0]:.3f}, {p[1]:.3f}), it
   for m in ['euclid', 'manhattan', 'minkowski', 'aparicion', 'iteracion']:
       s = dist data[i][m]
       print(f" Metric: {m}")
       print(f" min={s['min']:.3f}, max={s['max']:.3f}, mean={s['mean']:.3f}
   print("-----")
# 4) PLOT: FILL NEW TRIANGLES EACH ITERATION,
  COLOR POINTS BY A METRIC
def plot filled new triangles(
   triangles_by_iter,
   points_list,
   dist_data,
   metric="euclid",
   stat="mean",
   title=None
):
   - For each iteration i=1..k, fill in (with color_i)
    the sub-triangles introduced at iteration i.
   - The points are colored by 'metric'('stat') in a scatter with a colorbar.
   - We add a legend showing which color belongs to iteration i.
   if title is None:
       title = f"Sierpinski new triangles + Points color={metric}({stat})"
   fig, ax = plt.subplots(figsize=(18,18))
   ax.set_aspect("equal")
```

```
ax.set_axis_off()
ax.set_title(title)
max_iter = max(triangles_by_iter.keys())
# Discrete colormap for the triangles & possibly for points if metric="itera
cmap_iter = plt.cm.get_cmap('tab10', max_iter+1)
# Fill the triangles iteration by iteration
legend_handles = []
for i in range(1, max_iter+1):
   tri_list = triangles_by_iter[i]
    if not tri list:
        continue
    color_i = cmap_iter(i-1) # -1
    for tri in tri_list:
        A, B, C = tri
        polygon = mpatches.Polygon(
            [A, B, C],
            closed=True,
            facecolor=color_i,
                                # fill color
            edgecolor='black', # outline
            linewidth=1.0,
            alpha=0.8
        ax.add_patch(polygon)
    # We'll add a patch to the legend
    patch_for_legend = mpatches.Patch(facecolor=color_i, edgecolor='black',
                                      label=f"Iteration {i}")
    legend_handles.append(patch_for_legend)
# Show a legend that maps iteration -> color
ax.legend(handles=legend_handles, loc='upper right',
          title="Triangles by iteration")
# 2) Plot the points
arr_p = np.array(points_list)
x, y = arr p[:,0], arr p[:,1]
n_points = len(points_list)
# If the metric is 'iteracion', use the iteration values
# and the SAME colormap as the triangles, with discrete steps for 1..max ite
if metric == "iteracion":
    iteration_vals = np.array([p[2] for p in points_list], dtype=float)
    # We'll set up a discrete normalization so each iteration i uses exactly
    # Boundaries are at 0.5, 1.5, 2.5, ... up to max_iter+0.5
    boundaries = np.arange(0.5, max_iter+1.5, 1.0)
    norm = mcolors.BoundaryNorm(boundaries, max iter)
    sc = ax.scatter(
       х, у,
        c=iteration_vals,
        cmap=cmap_iter,
        norm=norm,
        edgecolors='k',
        s=40,
        zorder=5
    # Build colorbar (discrete steps from 1..max_iter)
```

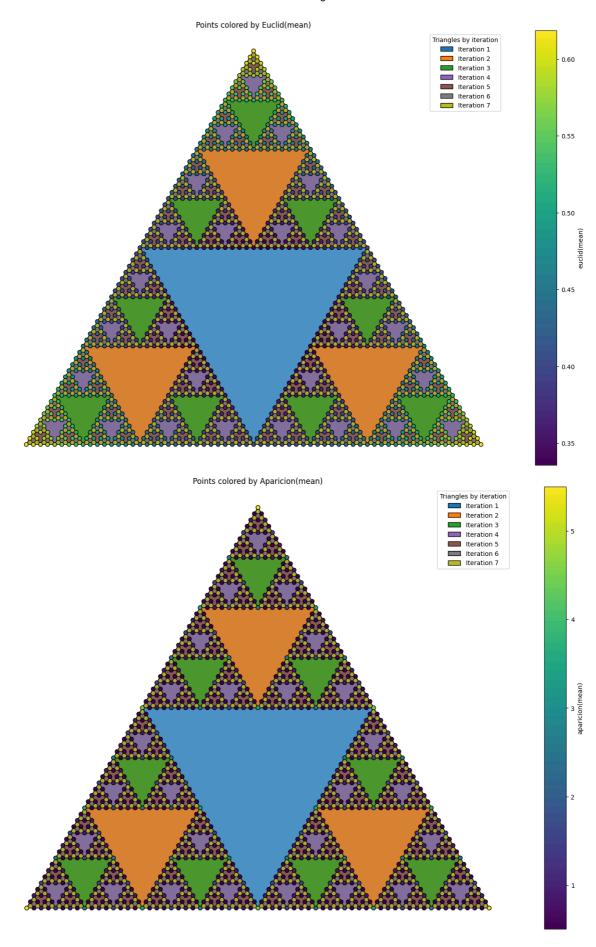
```
cb = fig.colorbar(sc, ax=ax, boundaries=boundaries, spacing='proportiona
        cb.set_ticks(np.arange(1, max_iter+1))
        cb.set_ticklabels([str(i) for i in range(1, max_iter+1)])
        cb.set_label("iteracion (discrete)")
    else:
        # Otherwise, we color by the usual metric stats
        values = np.zeros(n_points)
        for idx in range(n_points):
            values[idx] = dist_data[idx][metric][stat]
        sc = ax.scatter(x, y, c=values, cmap='viridis',
                        edgecolors='k', s=40, zorder=5)
        cb = fig.colorbar(sc, ax=ax, shrink=0.7)
        cb.set_label(f"{metric}({stat})")
    plt.show()
def plot_filled_triangles_and_point_metric(
   triangles_by_iter,
   points_list,
   point_index=0,
   metric="euclid",
                   # only relevant if metric="minkowski"
    p_mink=3,
    title=None
):
    Similar to 'plot_filled_new_triangles', except:
    - We STILL fill Sierpinski triangles by iteration.
     - We color each point by *its distance to the point with index=point index*
       (under the chosen metric).
     - We highlight the reference point (point_index) with a special marker.
    import matplotlib.patches as mpatches
    if title is None:
        title = f"Sierpinski + Distances from point #{point_index} in metric='{m
   fig, ax = plt.subplots(figsize=(18,18))
    ax.set aspect("equal")
   ax.set_axis_off()
   ax.set_title(title)
   # 1) Fill the triangles by iteration (same discrete colormap approach)
    max_iter = max(triangles_by_iter.keys())
    cmap_iter = plt.cm.get_cmap('tab10', max_iter+1)
    legend_handles = []
    for i in range(1, max_iter+1):
        tri_list = triangles_by_iter[i]
        if not tri list:
            continue
        color_i = cmap_iter(i)
        for tri in tri list:
            A, B, C = tri
            polygon = mpatches.Polygon(
                [A, B, C],
                closed=True,
                facecolor=color_i,
```

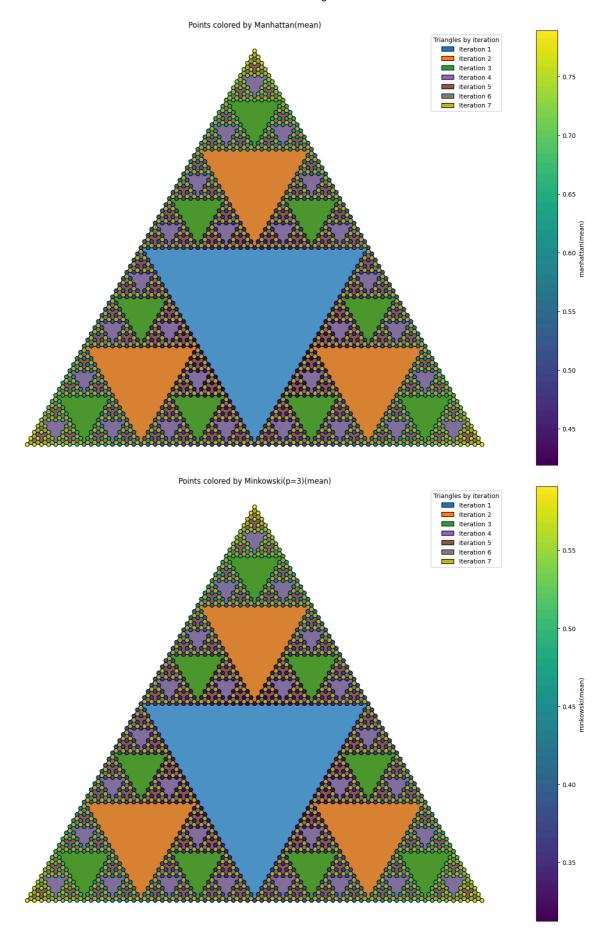
```
edgecolor='black',
            linewidth=1.0,
            alpha=0.6
        )
        ax.add_patch(polygon)
    patch for legend = mpatches.Patch(facecolor=color i, edgecolor='black',
                                      label=f"Iteration {i}")
    legend_handles.append(patch_for_legend)
ax.legend(handles=legend_handles, loc='upper right',
          title="Triangles by iteration")
# 2) Color each point by the distance to the reference point
def get_distance(pA, pB, metric, p=3):
    if metric == "euclid":
        return np.sqrt((pA[0]-pB[0])**2 + (pA[1]-pB[1])**2)
    elif metric == "manhattan":
        return abs(pA[0]-pB[0]) + abs(pA[1]-pB[1])
    elif metric == "minkowski":
        return ((abs(pA[0]-pB[0]))**p + (abs(pA[1]-pB[1]))**p)**(1.0/p)
    elif metric == "aparicion":
        # difference in iteration
        return abs(pA[2] - pB[2])
    else:
        # default to euclid
        return np.sqrt((pA[0]-pB[0])**2 + (pA[1]-pB[1])**2)
arr_p = np.array(points_list)
n_points = len(points_list)
if point_index < 0 or point_index >= n_points:
    print(f"Invalid point_index={point_index}, must be in [0..{n_points-1}]"
# The reference point
p_ref = points_list[point_index] # (x, y, iteration)
# Build a color array with distances from p ref
dist_vals = np.zeros(n_points, dtype=float)
for i in range(n points):
    if i == point index:
        dist vals[i] = 0.0
    else:
        dist_vals[i] = get_distance(p_ref, points_list[i], metric, p_mink)
# We'll do a normal continuous scale for these distances
x coords = arr p[:,0]
y_coords = arr_p[:,1]
sc = ax.scatter(x_coords, y_coords, c=dist_vals, cmap='viridis',
                edgecolors='k', s=40, zorder=5)
# highlight the reference point with a star
ax.scatter(
    [p_ref[0]], [p_ref[1]],
    color='red', marker='*', s=200, edgecolors='yellow', linewidths=1.5, zor
cb = fig.colorbar(sc, ax=ax, shrink=0.7)
```

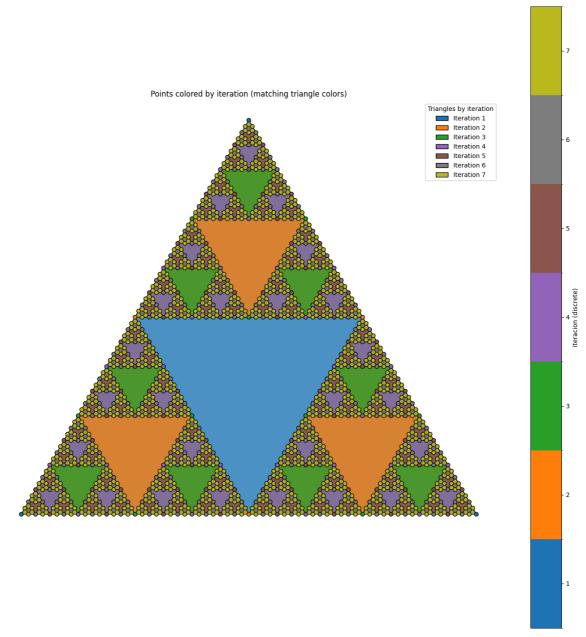
```
cb.set_label(f"Distance to point #{point_index} (metric={metric})")
    plt.show()
# GENERATION OF TRAINGLES
if __name__=="__main__":
   # Generate triangles
   K = 7 # set iterations
    triangles_by_iter, points_list = sierpinski_triangles_and_points(K)
    # Compute distances & stats
    dist_data = compute_distance_data(points_list)
    # Plot triangles + color points by euclid
    plot_filled_new_triangles(
        triangles_by_iter,
        points_list,
        dist_data,
        metric="euclid",
        stat="mean",
        title="Points colored by Euclid(mean)"
    )
    # Plot traingles + color points by aparicion
    plot_filled_new_triangles(
        triangles_by_iter,
        points_list,
        dist_data,
        metric="aparicion",
        stat="mean",
        title="Points colored by Aparicion(mean)"
    )
    # Plot triangles + color points by manhattan
    plot_filled_new_triangles(
        triangles_by_iter,
        points list,
        dist data,
        metric="manhattan",
        stat="mean",
        title="Points colored by Manhattan(mean)"
    )
    # Plot triangles + color points by minkowski
    plot_filled_new_triangles(
        triangles_by_iter,
        points_list,
        dist_data,
        metric="minkowski",
        stat="mean",
        title="Points colored by Minkowski(p=3)(mean)"
    )
    # Plot triangles (filled) + color points by 'iteracion' so they match the tr
    plot_filled_new_triangles(
        triangles_by_iter,
```

```
points_list,
    dist_data,
    metric="iteracion",
    stat="mean", # 'min', 'max', 'median' are identical for 'iteracion'
    title="Points colored by iteration (matching triangle colors)"
# Plot for individual points (distances to a reference point)
show_metrics_for_point(dist_data, i=0)
plot_filled_triangles_and_point_metric(
    triangles_by_iter, points_list, point_index=0,
    metric="euclid",
    title="Distances from point #0 in 'euclid'"
)
show_metrics_for_point(dist_data, i=1)
plot_filled_triangles_and_point_metric(
    triangles_by_iter, points_list, point_index=1,
    metric="manhattan",
    title="Distances from point #1 in 'manhattan'"
)
show_metrics_for_point(dist_data, i=2)
plot_filled_triangles_and_point_metric(
    triangles_by_iter, points_list, point_index=2,
    metric="minkowski",
    title="Distances from point #2 in 'minkowski(p=3)'"
)
```

C:\Users\thano\AppData\Local\Temp\ipykernel_25884\3315475924.py:185: MatplotlibDe
precationWarning: The get_cmap function was deprecated in Matplotlib 3.7 and will
be removed two minor releases later. Use ``matplotlib.colormaps[name]`` or ``matp
lotlib.colormaps.get_cmap(obj)`` instead.
 cmap_iter = plt.cm.get_cmap('tab10', max_iter+1)







Metrics for point index=0 => coords=(0.000, 0.000), iteration=1

Metric: euclid

min=0.016, max=1.000, mean=0.619, median=0.676

Metric: manhattan

min=0.016, max=1.366, mean=0.789, median=0.847

Metric: minkowski

min=0.014, max=1.000, mean=0.582, median=0.637

Metric: aparicion

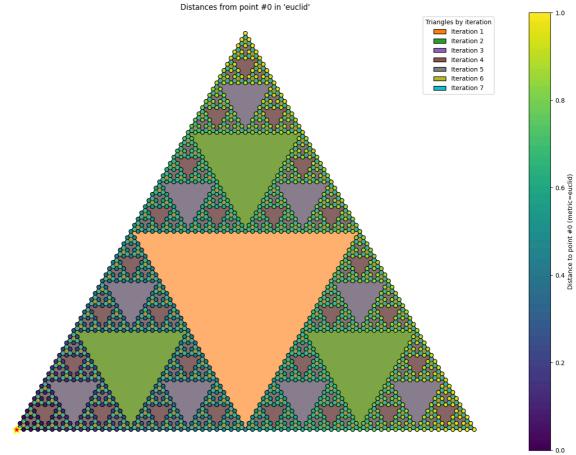
min=0.000, max=6.000, mean=5.498, median=6.000

Metric: iteracion

 $\label{eq:min=1.000} \mbox{min=1.000, mean=1.000, median=1.000}$

C:\Users\thano\AppData\Local\Temp\ipykernel_25884\3315475924.py:286: MatplotlibDe precationWarning: The get_cmap function was deprecated in Matplotlib 3.7 and will be removed two minor releases later. Use ``matplotlib.colormaps[name]`` or ``matplotlib.colormaps.get_cmap(obj)`` instead.

cmap_iter = plt.cm.get_cmap('tab10', max_iter+1)

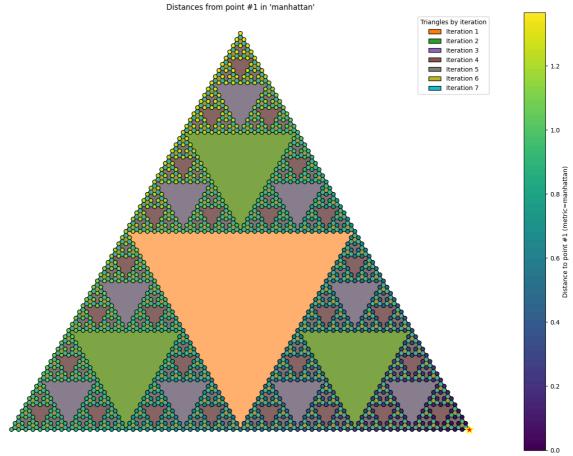


Metrics for point index=1 => coords=(1.000, 0.000), iteration=1
 Metric: euclid
 min=0.016, max=1.000, mean=0.619, median=0.676
 Metric: manhattan
 min=0.016, max=1.366, mean=0.789, median=0.847
 Metric: minkowski
 min=0.014, max=1.000, mean=0.582, median=0.637
 Metric: aparicion

Metric: iteracion

min=1.000, max=1.000, mean=1.000, median=1.000

min=0.000, max=6.000, mean=5.498, median=6.000



Metrics for point index=2 => coords=(0.500, 0.866), iteration=1 Metric: euclid min=0.016, max=1.000, mean=0.619, median=0.676 Metric: manhattan min=0.021, max=1.366, mean=0.778, median=0.836 Metric: minkowski min=0.014, max=0.918, mean=0.591, median=0.645

min=0.000, max=6.000, mean=5.498, median=6.000

Metric: iteracion

Metric: aparicion

min=1.000, max=1.000, mean=1.000, median=1.000

