

## ACKNOWLEDGEMENT

This satisfaction and euphoria that accompany the successful completion of any task would be but complete without the mention of the people who made it possible with constant guidance and encouragement and crowned our efforts with success.

We thank our Honorable **Chancellor, Dr. P. Shyamaraaju** for his support and encouragement and wonderful infrastructure/resources.

We express our thanks to **Dr. M Dhanamjaya**, Vice Chancellor, REVA University, Bangalore, for extending his support.

We are grateful to **Dr. K.M. Sudarshan**, Director, School of Electronics and Communication Engineering, REVA University, Bangalore, for his valuable support and encouragement.

A hearty thanks to our Project Guide **Dr. Prasad M**, Assistant Professor, School of ECE, for his guidance and support throughout the course.

We also thank year wise coordinator, all the staff members of School of Electronics and Communication Engineering and all those who have directly or indirectly helped us with their valuable suggestions in the successful completion of this project.

Last but not the least we would like to thank our beloved parents for their blessings, love and encouragement to successfully complete the task by meeting all the requirements.

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# ABSTRACT

Gesture Controlled Car is a robot which can be controlled by simple human gestures. The user just needs to wear a gesture device in which a sensor is included. The sensor will record the movement of hand in a specific direction which will result in the motion of the robot in the respective directions. The robot and the Gesture instrument are connected wirelessly through radio waves. User can interact with the robot in a more friendly way due to the wireless communication. We can control the car using a gyroscope sensors connected to a hand glove. The sensors are intended to replace the remote control that is generally used to run the car. It will allow user to control the forward, backward, leftward and rightward movements, while using the same sensor to control the directions of the car. Movement of car is controlled by the differential mechanism. The mechanism involves the rotation of both forth & rear wheels of left or right side to move in the anticlockwise direction and the other pair to rotate in the clockwise direction which makes the car to rotate about its own axis without any kind of forward or backward motion. The main advantage of this mechanism is the car with this mechanism can take sharp turn without any difficulty. The robotic arm is made to imitate the human hand movements using a hand glove. The main objective of the project work is to control car with gestures using hand. There are two main components of the system: The accelerometer depends upon the gestures of the hand. Now it's time to break the task in different modules to make the task easy and simple any project become easy or error free if it is done in different modules.