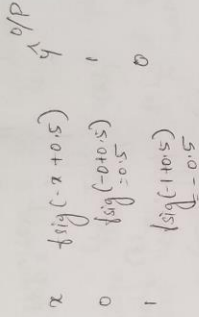


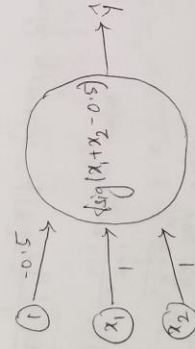
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Khaeewannan

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1. NOT gate

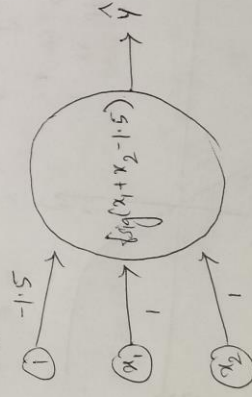


OR gate



x_1	x_2	$\text{sig}(x_1+x_2-0.5)$	y
0	0	$\text{sig}(0+0-0.5) = \text{sig}(-0.5)$	0
0	1	$\text{sig}(0+1-0.5) = \text{sig}(+0.5)$	1
1	0	$\text{sig}(1+0-0.5) = \text{sig}(+0.5)$	1
1	1	$\text{sig}(1+1-0.5) = \text{sig}(+1.5)$	1

AND gate



x_1	x_2	$\text{sig}(x_1+x_2-1.5)$	y
0	0	$\text{sig}(0+0-1.5) = \text{sig}(-1.5)$	0
0	1	$\text{sig}(0+1-1.5) = \text{sig}(-0.5)$	0
1	0	$\text{sig}(1+0-1.5) = \text{sig}(-0.5)$	0
1	1	$\text{sig}(1+1-1.5) = \text{sig}(+0.5)$	1

(1)

2. Vector equation in the forward propagation

$$z^{(1)} = x$$

$$T^{(2)} = \beta^{(1)T} z^{(1)}$$

$$z^{(2)} = \text{sig} \cdot T^{(2)} \text{ \& add } z_0^{(2)}$$

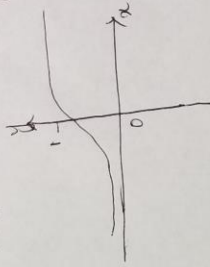
$$T^{(3)} = \beta^{(2)T} z^{(2)}$$

$$z^{(3)} = \text{sig} \cdot T^{(3)} \text{ \& add } z_0^{(3)}$$

$$T^{(4)} = \beta^{(3)T} z^{(3)}$$

$$z^{(4)} = \hat{y} = \text{sig} \cdot T^{(4)}$$

3. (a) characteristic curve for sigmoid function $f(x) = \frac{1}{1 + e^{-x}}$



$$\text{when } x \rightarrow \infty \Rightarrow \frac{1}{1 + e^{-x}} = 1$$

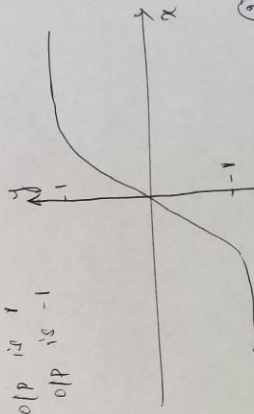
$$x = 0 \Rightarrow \frac{1}{1 + e^0} = 0.5$$

when x is +ve $f(x)$ is 1

when x is -ve $f(x)$ is 0

characteristic curve for hyperbolic tangent function $f(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$

when x is +ve $f(x)$ is 1
when x is -ve $f(x)$ is -1



(3)

(b) When the starting values of weight are very small nears the operating function part of sigmoid function will be linear & the model will collapse.

When the starting values are zero, it produces zero derivative & make perfect symmetry & the algorithm do not move further.

When the weights are large it will produce poor solution.

When the starting values are near zero it will be linear.

& when the weight increases it will become non-linear.

For standardized slips, the starting values can be in the range $[-0.7, 0.7]$.

$$J_p(p, \beta, \alpha_i) = \frac{1}{2} \|p\|^2 - \sum_{i=1}^N \alpha_i \int y_i (\alpha_i^T p + p_0 - 1)$$

$$J_p(p, \beta, \alpha_i) = \frac{1}{2} \|p\|^2 - \sum_{i=1}^N \alpha_i y_i \alpha_i^T p - \sum_{i=1}^N \alpha_i y_i p_0 + \sum_{i=1}^N \alpha_i$$

$$J_p(p, \beta, \alpha_i) = \frac{1}{2} \|p\|^2 - \sum_{i=1}^N \alpha_i y_i \alpha_i^T p - \sum_{i=1}^N \alpha_i y_i p_0 + \sum_{i=1}^N \alpha_i$$

Differentiating J_p with respect to p & equating to 0.

$$\frac{\partial J_p}{\partial p} = \frac{1}{2} \times 2 p - \sum_{i=1}^N \alpha_i y_i \alpha_i^T = 0$$

$$p = \sum_{i=1}^N \alpha_i y_i \alpha_i^T$$

Differentiating J_p with respect to p_0

$$\frac{\partial J_p}{\partial p_0} = \sum_{i=1}^N \alpha_i y_i = 0$$

$$\therefore p = \sum_{i=1}^N \alpha_i y_i \alpha_i^T, \sum_{i=1}^N \alpha_i y_i = 0$$

$$(\alpha_i^T p = \alpha_i^T \beta)$$

$$\begin{pmatrix} \alpha^T p \\ \alpha^T \beta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Substituting P_{dual} into the Wolfe-Dual

$$L_D(P, P_0, \alpha_i) = \frac{1}{2} \sum_{i=1}^N \alpha_i \alpha_k y_i y_k x_i^T x_k - \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k x_i^T x_k + \sum_{i=1}^N \alpha_i$$

$$= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k x_i^T x_k$$

Now L_D can be represented in terms of α ,

$$L_D(\alpha_i) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{k=1}^N \alpha_i \alpha_k y_i y_k x_i^T x_k$$

Steps followed for prediction using SVM.

1. Transform data into the format of SVM package.
2. Conduct simple scaling on the data.
3. Consider the RBF kernel, $K(x, x') = \exp(-\gamma \|x - x'\|^2)$
4. Use cross-validation to find the best parameters of C & γ to train the whole
5. Use the best parameters C & γ to train the whole training set.

6. Test

$$6. \quad k(x, x') = (1 + x_1 x'_1)^2 = (1 + x^T x')^2$$

$$\bar{x}^T = [x_1 \quad x_2], \quad x' = \begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix}$$

$$\bar{x}^T x' = x_1 x'_1 + x_2 x'_2$$

$$k(x, x') = (1 + x_1 x'_1 + x_2 x'_2)^2$$

$$(a + b + c)^2 = a^2 + b^2 + c^2 + 2ab + 2ac + 2bc$$

$$\text{where } a=1, b=x_1 x'_1, c=x_2 x'_2$$

$$k(x, x') = (1 + 2x_1 x'_1 + 2x_2 x'_2 + (x_1 x'_1)^2 + 2x_1 x'_1 x_2 x'_2 + (x_2 x'_2)^2)$$

$$= \begin{bmatrix} 1 & \sqrt{2}x_1 & \sqrt{2}x_2 & x_1^2 & \sqrt{2}x_1 x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} 1 \\ \sqrt{2}x'_1 \\ \sqrt{2}x'_2 \\ \cancel{\text{feature}} x'^2_1 \\ \sqrt{2}x'_1 x'_2 \\ x'^2_2 \end{bmatrix}$$

$$= h(x^T) h(x')$$

The kernel function can be expressed as an inner product in a feature space mapping from 2 dimension to 6 dimension is by the mapping of input vector function $h(x)$

(5)

The components of $h(x)$ are $h(x_1) = 1$, $h(x_2) = \sqrt{2}x_1$, $h(x_3) = \sqrt{2}x_2$, $h(x_4) = x_1^2$, $h(x_5) = \sqrt{2}x_1x_2$ and $h(x_6) = x_2^2$