

# Assignment Web Similarity Analysis

Generated on 2025-03-22 00:43:54

## Executive Summary

**Overall Web Similarity Score:** 30%

**Assessment:** The assignment shows some similarity to online resources related to step response analysis and control systems, but the majority of the content appears to be derived from the student's own calculations and MATLAB code. The similarity is primarily focused on general concepts and terminology related to step response analysis, which are common in control systems education.

**Conclusion:** While the assignment uses common terminology related to step response and control systems, and even has an exact match to a YouTube video title, the core content, such as the derivations, calculations, MATLAB code, and specific parameter values related to the DC motor model, appears original. The matches are generally related to common phrases used in control systems engineering or generic titles of educational resources. Thus, the assignment is unlikely to be considered plagiarized. However, it would be beneficial for the student to explicitly cite any resources they consulted for background information or conceptual understanding, even if they didn't directly copy text.

## Web Sources Analyzed

Source URL	Similarity Score
https://www.chegg.com/homework-help/questions-and-answers/following-figures-show-block-diagram-step-response-system-r-s-y-s-10k-figure-3-step-respon-q51329205	<font color='green'>52.48%</font>
https://www.youtube.com/watch?v=virn3Nnwb3A	<font color='green'>5.38%</font>
https://www.chegg.com/homework-help/questions-and-answers/2-figure-3-shows-step-response-curve-system-1-system-curve-represents-plcase-explain-2-als-q127731696	<font color='green'>16.68%</font>
https://www.youtube.com/watch?v=_g-lzZ5e0h0	<font color='green'>6.52%</font>

## Detailed Content Matches

### Match 1 - Similar Content (70%)

**Assignment:** Step Response of the system  
**Source:** https://www.chegg.com/homework-help/questions-and-answers/following-figures-show-block-diagram-step-response-system-r-s-y-s-10k-figure-3-step-respon-q51329205  
**Source Text:** Step Response

### Match 2 - Similar Content (70%)

**Assignment:** Step Response of the system  
**Source:** https://www.chegg.com/homework-help/questions-and-answers/2-figure-3-shows-step-response-curve-system-1-system-curve-represents-plcase-explain-2-als-q127731696  
**Source Text:** step response curve of a system

### Match 3 - Similar Content (90%)

**Assignment:** Step Response of the system  
**Source:** https://www.youtube.com/watch?v=virn3Nnwb3A  
**Source Text:** Step Response of a System

#### **Match 4 - Exact Match (100%)**

**Assignment:** Step Response of a transfer function

**Source:** [https://www.youtube.com/watch?v=\\_g-lzZ5e0h0](https://www.youtube.com/watch?v=_g-lzZ5e0h0)

**Source Text:** Step Response of a transfer function

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#### **Match 5 - Common Knowledge (100%)**

**Assignment:** steady-state value

**Source:** <https://www.chegg.com/homework-help/questions-and-answers/2-figure-3-shows-step-response-curve-system-1-s-system-curve-represents-plcase-explain-2-als-q127731696>

**Source Text:** steady state value

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#### **Match 6 - Similar Content (50%)**

**Assignment:** The steady-state value of the step response :

**Source:** <https://www.chegg.com/homework-help/questions-and-answers/following-figures-show-block-diagram-step-response-system-r-s-y-s-10k-figure-3-step-response-q51329205>

**Source Text:** Figure 3 Step Response

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# Full Assignment with Highlighted Plagiarism

*Sections highlighted in yellow with red text indicate potential plagiarism.*

EE5351:CONTROL SYSTEM DESIGN

ASSIGNMENT 03

NAME

:

BANDARA LRTD

REG.NO

:

EG/2021/4433

SEMESTER:

05

DATE

04/11/2024

:

Tables of Figures

Figure 1: Sample DCMotor

Figure 2:Pole zero plot of Splane

Figure 3: **Step Response of the system**

Source: <https://www.youtube.com/watch?v=virn3Nnwb3A>

Figure 4:Figure of the Simulink system

Figure 5:Final Output

3

5

6

9

10

Q1)

Figure 1: Sample DCMotor

Sample Data Set

Voltage constant of the motor (kb)

-

0.85V/rads-1

Torque constant of the motor (km)

-

0.9 Nm/A

Tachometer constant (kt)

-

0.15 V/rads-1

Inertia of the rotating parts of the motor (J)

-

0.85kgm<sup>2</sup>

Input DC voltage (V<sub>i</sub>(t))

-

10.0V

Voltage gain of the amplifier (A)

-

100

Armature resistance and inductance

-1.3 Ω, 0.5 H respectively

1. Assume that G<sub>m</sub> as the transfer function of DC motor. Then assume the armature current as I<sub>a</sub>

■ ■

V<sub>a</sub> (t) = I<sub>a</sub>R<sub>a</sub>+L■ ■+V<sub>0</sub>

V<sub>0</sub>

T<sub>m</sub>

= k<sub>b</sub>■m

= k<sub>m</sub>I<sub>a</sub>

Now convert the time equations into the laplace domain

V<sub>a</sub> (s) = I<sub>a</sub>R<sub>a</sub>+LSI+ V<sub>0</sub>

V<sub>0</sub>

= k<sub>b</sub>■m

T<sub>m</sub>

= k<sub>m</sub>I<sub>a</sub>

T<sub>m</sub>

= J■m

G<sub>m</sub>

■ ■

2+■ ■ ■ ■+■ ■

■ ■

■ ■ ■

=

Assume the overall transfer function as G<sub>s</sub>

G<sub>s</sub>

■ ■

■

=1+■ ■ ■

$$\begin{aligned}
 &= 0.85s^2 + 1.3s + 0.9(0.85 + 100 \times 0.015) \\
 &= 0.85s^2 + 1.3s + 13.35 \\
 &= 0.425s^2 + 1.1s + 2.11
 \end{aligned}$$

By substituting values

Gs

$$100 \times 0.9$$

$$= 0.85s^2 + 1.3s + 0.9(0.85 + 100 \times 0.015)$$

$$90$$

$$= 0.425s^2 + 1.1s + 2.11$$

## 2. Sample code

% Define the transfer function numerator and denominator

numerator = 90;

denominator = [0.425, 1.105, 2.115];

% Create transfer function

G = tf(numerator, denominator);

poles = pole(G); %Find poles

zeros = zero(G); %Find zeros

%Display poles and zeros

disp('Poles:');

disp(poles);

disp('Zeros:');

disp(zeros);

% Plot the poles and zeros in the s-plane

pzmap(G);

title('Pole-Zero Plot');

grid on;

output

>> Q1\_2

Poles:

-1.3000 + 1.8129i

-1.3000 - 1.8129i

Zeros:

>>

Figure 2:Pole zero plot of Splane

## 3. Sample code

% Define the transfer function numerator and denominator

```

numerator = 900;
denominator = [0.425, 1.105, 2.115];
% Create the transfer function
G = tf(numerator, denominator);
% Define the time vector
t = 0:0.01:10; % time vector from 0 to 10 seconds with a step of 0.01
% step response
[y, t] = step(G, t);
% Plot the step response
step(G, t);
grid on;
title('Step Response of the System');
% Calculate and display the steady-state value

```

Source: <https://www.chegg.com/homework-help/questions-and-answers/2-figure-3-shows-step-response-curve-system-1-system-curve-represent-plcase-explain-2-als-q127731696>

```

steady_state_value = y(end);
disp(['The steady-state value of the step response : ', num2str(steady_state_value)]);

```

Source: <https://www.chegg.com/homework-help/questions-and-answers/2-figure-3-shows-step-response-curve-system-1-system-curve-represent-plcase-explain-2-als-q127731696>

output

```
>> Q1_3
```

The steady-state value of the step response : 425.5316

Source: <https://www.chegg.com/homework-help/questions-and-answers/2-figure-3-shows-step-response-curve-system-1-system-curve-represent-plcase-explain-2-als-q127731696>

Figure 3: Step Response of the system

Source: <https://www.youtube.com/watch?v=virn3Nnwb3A>

4. Considering the transfer function we can simplify it as follows.

211.756

Gs

= 2 + 2.6s + 4.976

So it shows that the characteristic equation as :

2 + 2.6s + 4.976 = 0

2 = 4.976

= 2.23

2 = 2.6

= 0.583

-

Mp =  $\sqrt{1 - \zeta^2}$

= 0.105

So it can be taken the o/p as follows

(s)

= G(s) × V(s)

90

10

$$= 0.425s^2 + 1.1s + 2.11 \times 10^2$$

900

$$= (0.425s^2 + 1.1s + 2.11 \times 10^2)$$

For that the sample matlab code

% Define the transfer function numerator and denominator

numerator = 900;

denominator = [0.425 1.105 2.115 0]; % Multiply by s

% Using residue to find the partial fraction expansion

[residues, poles, direct\_terms] = residue(numerator, denominator);

% Display the results

disp('Residues:');

disp(residues);

disp('Poles:');

disp(poles);

disp('Direct Terms:');

disp(direct\_terms);

from that it given the o/p as

>> Q1\_4

Residues:

1.0e+02 \*

-2.1277 + 1.5257i

-2.1277 - 1.5257i

4.2553 + 0.0000i

Poles:

-1.3000 + 1.8129i

-1.3000 - 1.8129i

0.0000 + 0.0000i

•

$s$

= [

= [

4.2553

$s$

4.2553

$s$

$-2.1277 + 1.5257s$

$-2.1277 - 1.5257s$

$+ (s + 1.3 - 1.8129s) + (s + 1.3 + 1.8129s) \times 10^2$

$4.26s + 11.034$

$- (s^2 + 2.6s + 4.976) \times 10^2$

From inverse laplace domain

•

$\frac{1}{s}$

$$= [4.2553 \frac{1}{s} - 4.26 - 1.3 \cos(1.813s) - 3.03 - 1.3 \sin(1.813s)] \times 102$$

to find the  $\lim_{s \rightarrow \infty}$  it can be used final value theorem because all the poles are located in the left half of the s plane.

$\lim_{s \rightarrow \infty}$

$$= \lim_{s \rightarrow \infty} [4.2553 \frac{1}{s} - 4.26 - 1.3 \cos(1.813s) - 3.03 - 1.3 \sin(1.813s)] \times 102$$

$\lim_{s \rightarrow \infty}$

$$= 425.53 \text{ rad}^{-1}$$

So the overshoot equation is given as

$M_p$

$\frac{1}{s}$

$\frac{1}{s}$

$-\frac{1}{s}$

$-\frac{1}{s}$

$= \frac{1}{s}$

$\frac{1}{s}$

$$; M_p = \frac{1}{\sqrt{1-\zeta^2}} = 0.105$$

$\frac{1}{s}$

$$-4.2553 \times 102$$

$$0.105 = \frac{1}{4.2553 \times 102}$$

$$4.2553 \times 102$$

$\frac{1}{s}$

5. TP

$$= 4.702 \times 102 \text{ rad}^{-1}$$

$\frac{1}{s}$

$\frac{1}{s}$

$$\frac{1}{s} \times \sqrt{1-\zeta^2}$$

$\frac{1}{s}$

$\frac{1}{s}$

$$2.23 \times \sqrt{1-0.5832}$$

$$= 1.73 \text{ s}$$

6.

Figure 4: Figure of the Simulink system

7.

Figure 5: Final Output



8. By looking at the figure2 it is clear that all the poles are located in the left hand side. Thus it is clear that the system is stable.

# Analysis Methodology

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**Web Similarity Analysis Method:** This report analyzes the similarity between a student assignment and web content using multiple approaches:

1. **Basic similarity analysis** using TF-IDF vectorization and cosine similarity metrics to calculate statistical similarity between texts.
2. **Advanced semantic analysis** using Google's Gemini AI to identify conceptual similarities, common phrases, and potential plagiarism patterns.
3. **Source verification** by analyzing multiple sources to distinguish between common knowledge and unique content.

## Interpretation Guide:

- 0-15%: Very low similarity - Likely original content
- 16-30%: Low similarity - Contains common phrases but largely original
- 31-50%: Moderate similarity - May contain some paraphrased content
- 51-70%: High similarity - Contains substantial similar content
- 71-100%: Very high similarity - Significant portions may be unoriginal

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*Disclaimer: This automated similarity analysis provides an approximation of content similarity against web sources. Results should be interpreted by a human reviewer for context-appropriate assessment. Common knowledge, standard phrases, and coincidental matches may be flagged and require human judgment.*