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Body.hpp
    1: //Authors: Joseph Calles and Tharith Sovann
    3: #ifndef BODY_HPP
    4: #define BODY_HPP
    6: // include SFML libraries
    7: #include <SFML/Graphics.hpp>
   8: #include <SFML/Window.hpp>
   9: #include <SFML/System.hpp>
   10: #include <SFML/Audio.hpp>
   11:
   12: // include directives
  13: #include <iostream>
  14: #include <string>
  15: #include <memory>
   16: #include <vector>
  17: #include <cmath>
  18:
  19: using namespace std;
   20:
   21: class Body : public sf::Drawable {
   22: public:
   23:
       Body(): x_position(0), y_position(0),
   24:
               _x_velocity(0), _y_velocity(0), _mass(0) {}
   25:
        Body (double x, double y, double xv,
   26:
   27:
             double yv, double m, string filename): _x_position(x), _y_position(y)
   28:
                                                  _x_velocity(xv), _y_velocity(y
v),
   29:
                                                  _mass(m), _filename(filename)
{ }
   30:
   31:
        friend istream& operator>>(istream& input, Body& x);
   32:
        friend ostream& operator << (ostream& out, Body& body);
   33:
              34:
double>(radius); }
   35:
              s; }
   36:
   37:
              void set_big_G(double G) { _big_G = make_shared<double>(G); }
   38:
  39:
              void set_window_scale(sf::Vector2u window_size) { _window_size = wind
ow_size; }
   40:
              sf::Vector2u get_window_size(void) { return _window_size; }
   41:
   42:
              void set_x_vel(double xvel) { _x_position = xvel; }
   43:
              void set_y_vel(double yvel) { _y_position = yvel; }
   44:
   45:
              double calc_y_force(Body& other_planet);
   46:
              double calc_x_force(Body& other_planet);
   47:
   48:
              void set_x_force(double xforce) { _x_force = xforce; }
              void set_y_force(double yforce) { _y_force = yforce; }
   49:
  50:
```

shared_ptr<double> get_radius(void) { return _universe_radius; }

shared_ptr<double> get_G(void) { return _big_G; }

double get_mass(void) { return _mass; }

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   56:
               void step(double delta_seconds);
   57:
               void set_new_position(void);
   58: private:
   59:
   60:
               void draw(sf::RenderTarget& target, sf::RenderStates state) const
               { target.draw(_sprite, state); } // draw function overrider
   61:
   62:
               double _x_position;
   63:
   64:
               double _y_position;
   65:
   66:
               double _x_velocity;
   67:
               double _y_velocity;
   68:
   69:
               double _x_accel;
   70:
               double _y_accel;
   71:
   72:
               double _x_force;
   73:
               double _y_force;
   74:
   75:
               double _mass;
   76:
               string _filename;
   77:
   78:
               shared_ptr<double> _universe_radius;
   79:
               shared_ptr<double> _big_G;
   80:
   81:
   82:
               sf::Vector2u _window_size;
   83:
               sf::Texture _texture;
               sf::Image _image;
   84:
   85:
               sf::Sprite _sprite;
   86: };
   87:
   88: #endif /* BODY_HPP */
```