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import cv2
import matplotlib.pyplot as plt
import numpy as np

# Define the paths to the YOLOv3 configuration, weights, and class names files
cfg_file = '/content/yolov3.cfg'
weight_file = '/content/yolov3.weights'
namesfile = '/content/coco.names'

# Load the YOLOv3 model
net = cv2.dnn.readNet(weight_file, cfg_file)

# Load class names
with open(namesfile, 'r') as f:
    classes = f.read().strip().split('\n')

# Load an image for object detection
image_path = '/content/hit.jpg'
image = cv2.imread(image_path)

# Get the height and width of the image
height, width = image.shape[:2]

# Create a blob from the image
blob = cv2.dnn.blobFromImage(image, 1/255.0, (416, 416), swapRB=True, crop=False)
net.setInput(blob)

# Get the names of the output layers
layer_names = net.getUnconnectedOutLayersNames()

# Run forward pass
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outs = net.forward(layer_names)

# Initialize lists to store detected objects' information
class_ids = []
confidences = []
boxes = []

# Define a confidence threshold for object detection
conf_threshold = 0.5

# Loop over the detections
for out in outs:
    for detection in out:
        scores = detection[5:]
        class_id = np.argmax(scores)
        confidence = scores[class_id]
        if confidence > conf_threshold:
            # Object detected
            center_x = int(detection[0] * width)
            center_y = int(detection[1] * height)
            w = int(detection[2] * width)
            h = int(detection[3] * height)

            # Rectangle coordinates
            x = int(center_x - w / 2)
            y = int(center_y - h / 2)

            class_ids.append(class_id)
            confidences.append(float(confidence))
            boxes.append([x, y, w, h])
```

```
# Apply non-maximum suppression to eliminate overlapping boxes
nms_threshold = 0.4
indices = cv2.dnn.NMSBoxes(boxes, confidences, conf_threshold, nms_threshold)

# Draw bounding boxes and labels on the image
for i in indices.flatten():  # flatten for compatibility
    x, y, w, h = boxes[i]
    label = str(classes[class_ids[i]])
    confidence = confidences[i]

    cv2.rectangle(image, (x, y), (x + w, y + h), (0, 255, 0), 2)
    cv2.putText(image, f'{label} {confidence:.2f}', (x, y - 10),
                cv2.FONT_HERSHEY_SIMPLEX, 0.8, (0, 255, 0), 2)

# Display the result in Jupyter Notebook
plt.figure(figsize=(10, 8))
plt.imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB))
plt.axis('off')
plt.show()
```