

ランダム行列・無限次元近似・自由確率論

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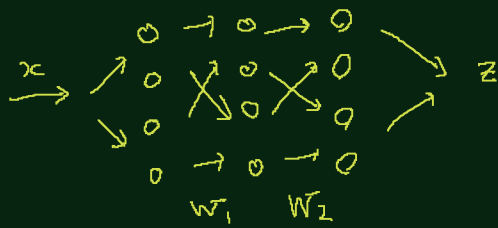
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SI Overview

Deep Neural Networks

Rosenblatt '57~62 Multilayer perceptron



(x, y) : given data.

$$z = f_{w_1, w_2}(x)$$

$$L(f_{w_1, w_2}) = |y - \underbrace{f_{w_1, w_2}(x)}_{\text{parameter}}|^2$$

Stochastic gradient descent

Error Back Propagation

Amari, Tsypkin '66~67

'76

51 Overview

A standard setting

1. Multilayer Perceptron is a parametric family $(f_\theta)_{\theta \in \Theta}$

$$v / f_\theta : \mathbb{R}^M \rightarrow \mathbb{R}^M \quad (M \in \mathbb{N})$$

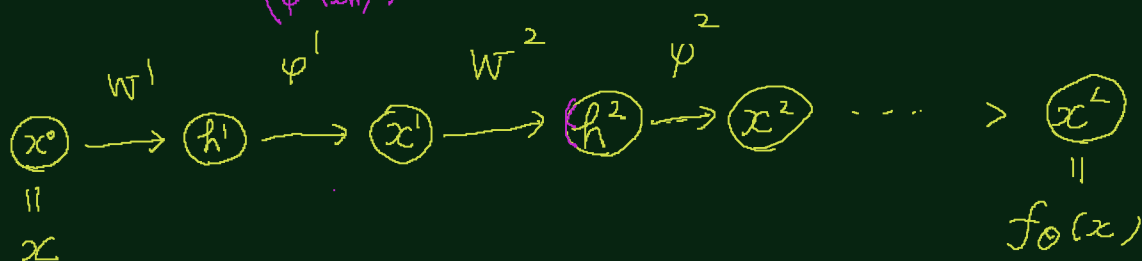
$$\hookrightarrow \varphi^L \circ g_{\theta^L}^L \dots \circ \varphi^1 \circ g_{\theta^1}^1$$

$$g_{\theta^l}^l(x) = \underbrace{W^l}_{M \times M} x + \underbrace{b^l}_{\in \mathbb{R}^M} \quad (\theta^l = (w^l, b^l))$$

activation $\varphi^l \in C(\mathbb{R})$:

differentiable, except for
finite number of points

$$\varphi^l(x) = \begin{pmatrix} \varphi^l(x_1) \\ \vdots \\ \varphi^l(x_n) \end{pmatrix}$$



Examples of Activation

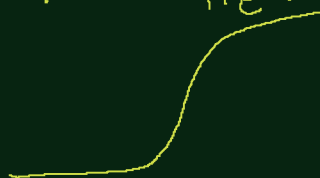
ReLU '15

$$\varphi(x) = \max(0, x)$$

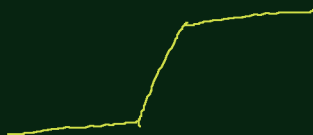


Sigmoid

$$\varphi(x) = \frac{1}{1+e^{-x}}$$

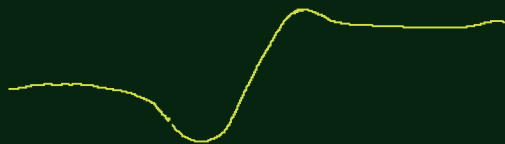


Hard tanh



SiLU (Sigmoid Linear Unit) '17

$$\text{(or swish)} \quad \varphi(x) = \frac{x}{1+e^{-x}}$$



testing dataset: training dataset
 (= 学習したモデルが
 ある程度近い dataset.)

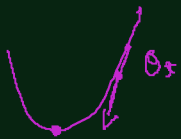
2. A training dataset is a set of pairs $(x_n, y_n)_{n=1}^N$

3. Gradient Descent

(MSE)

$$L(f_\theta) = \frac{1}{2N} \sum_{n=1}^N \|f_\theta(x_n) - y_n\|_2^2$$

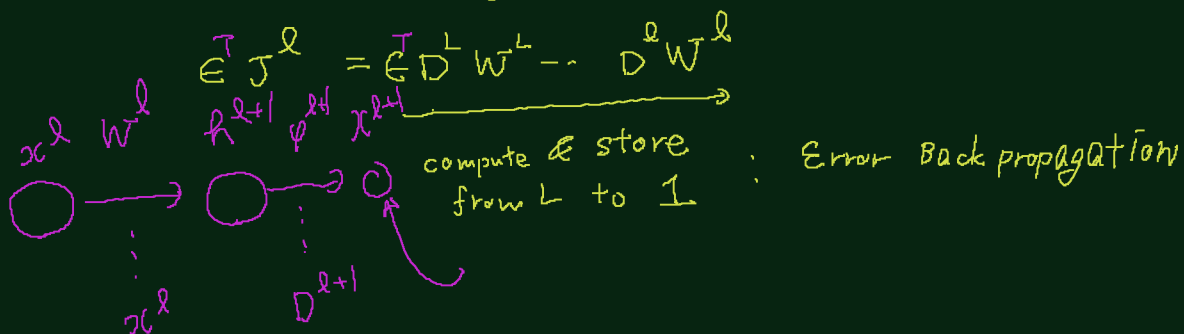
$t=0, 1, 2, \dots$ $\theta_{t+1} = \theta_t - \eta_t \frac{d}{d\theta} L(f_\theta) \Big|_{\theta=\theta_t} \quad (\eta_t > 0)$



* In practice, (x_n, y_n) are picked randomly from the training dataset.

4. Error Back-Propagation

$$\frac{\partial L}{\partial W^l} = \underbrace{(f(W^l) - y)^T}_{e^T} \underbrace{\frac{\partial f}{\partial x^{l+1}}}_{J^{l+1}} D^{l+1} x^l$$



Deep

ILSVRC 2012

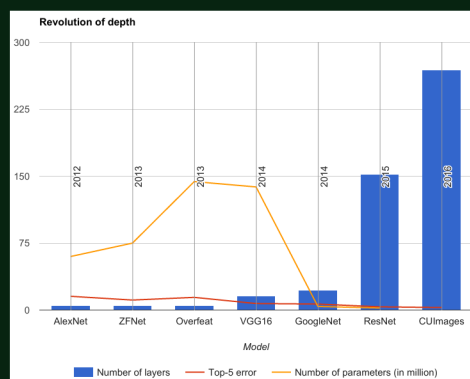
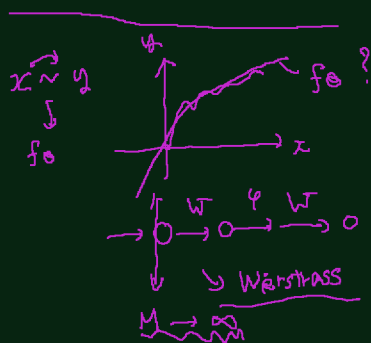
(ImageNet Large Scale Visual Recognition Challenge)

: AlexNet (Hinton et al.)

ImageNet Classification with Deep Convolutional Neural Networks
(NIPS 2012)

Deep である必要

- 表現能力の指數的向上
- 性能は上昇する(?)



S2. Dynamical Isometry

Fix L (= the number of Layers)

$$J = D^L W^L \dots D^1 W^1$$

D^l : activation @ Jacobian.

W^1, \dots, W^L : initial state

Error back propagation $\|J^T\|_2$ can

explode / vanish as $L \rightarrow \infty$

Uniform.

"Exploding / Vanishing Gradient Problem"

Gaussian

Haar orthogonal

(uniformly picking up)

Pennington, Schoenholz, Ganguli [NIPS '17, AISTATS '18] from OCM

Ensuring J 's singular values $\sim O(1)$ as $L \rightarrow \infty$. (Dynamical Isometry)
is essential for avoiding the exploding / vanishing of gradients.

Gaussian Initialization X

Orthogonal Initialization + normalization of $\rho \Rightarrow$ DI.

$$S_{\lim_{M \rightarrow \infty} \mu_{JJ^T}}(z) \xrightarrow{L \rightarrow \infty} \exp\left(-\frac{z \sigma_0^2}{1+z}\right) \text{ (Voiculescu)}$$

Free Infinite Multiplicative Infinite Divisible

free prob.



limit spectral distribution

Sketch

Assume that $(W_1, W_1^*), \dots, (W_L, W_L^*), (\underline{D}_1, \dots, \underline{D}_L)$ are asymptotic free as $M \rightarrow \infty$.

Let $(u_1, u_1^*), \dots, (u_L, u_L^*), (d_1, \dots, d_L)$

be free family in a C^* -prob. sp. (\mathcal{A}, τ) .

$$J := \underline{d}_L u_L \dots d_1 u_1$$

$$J J^* = d_L u_L (\underline{d_{L-1} u_{L-1} \dots d_1 \dots u_{L-1} d_{L-1}}) u_L^* d_L^*$$

$$S_{JJ^*}(z) = S_{d_L^2}(z) S_{\tilde{J}_{L-1} \tilde{J}_{L-1}^*}(z), \quad \tilde{J}_{L-1} \tilde{J}_{L-1}^*$$

$$= S_{d_1^2}(z) \dots S_{d_L^2}(z)$$

unitary だけ消えた

free probability

SS. Fisher Information Matrix & Neural Tangent Kernel

$$I(\theta) = \frac{1}{N} \sum_{n=1}^N \frac{\partial f_{\theta}(x_n)}{\partial \theta} \frac{\partial f_{\theta}(x_n)}{\partial \theta}^T$$
 (Empirical) Fisher Information Matrix
 : $M^2 \times M^2$ 行列

$$D_{KL}(P_{\theta} || P_{\theta+d\theta}) \approx \frac{1}{2} d\theta^T I(\theta) d\theta$$
 (Information Geometry (Amari))

$$P_{\theta} = \exp(-L f_{\theta}) / Z$$
 : $M \times M$ 行列
 $C \times C$ ($C \leq M$) : 出力次元

$b^{\theta} = 0$ と $L = \frac{1}{N} \sum_{n=1}^N \frac{\partial f_{\theta}(x_n)}{\partial \theta} \frac{\partial f_{\theta}(x_n)}{\partial \theta}^T$

Neural Tangent Kernel

$$K(x, x') = \frac{\partial f_{\theta}(x)}{\partial \theta} \frac{\partial f_{\theta}(x')}{\partial \theta}^T$$
 : $M \times M$ 行列
 $C \times C$ ($C \leq M$) : 出力次元

NTK describes learning dynamics

Learning dynamics of parameters is given by:

$$\frac{d\theta_t}{dt} = \eta (\nabla_{\theta} f_{\theta_t})^T (y - f_{\theta_t})$$

Learning dynamics of DNN is given by:

$$\frac{df_{\theta_t}}{dt} = \eta \Theta_t (y - f_{\theta_t})$$

$$\Theta_t = \nabla_{\theta} f_{\theta_t} (\nabla_{\theta} f_{\theta_t})^T$$

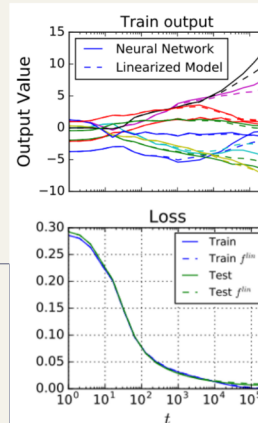
where

Informal [Jacot+NeurIPS2018, Lee+NeurIPS2019]: Under the wide limit $M \rightarrow \infty$, the learning of the DNN is approximated by

where

$$\frac{df_{\theta_t}}{dt} = \eta \Theta (y - f_{\theta_t})$$

$$\Theta = \nabla_{\theta} f_{\theta} (\nabla_{\theta} f_{\theta})^T \quad (\text{Neural Tangent Kernel})$$



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θ : 初期値

✓ Gaussian

✓ $C = O(1)$ as $M \rightarrow \infty$

↑ M ?

✓ D.I. (?)

(?) orthogonal

per sample.
Spectrum of $\frac{\partial f_0}{\partial \theta} (= D^L \frac{\partial \chi^L}{\partial \theta})$ arXiv: 2006.07814

T.H. & Ryo Karakida [AISTATS '21]

$H_L := \frac{1}{M} \frac{\partial \chi^L}{\partial \theta} \frac{\partial \chi^L}{\partial \theta}^*$ A dual of Fisher Information Matrix
NTK per sample

Then limit spectral distribution of H_L

concentrates on the point $\underline{q^L}$ as $M \rightarrow \infty$

$$w/q = \lim_{M \rightarrow \infty} \frac{1}{M} \|\chi^0\|_2^2$$

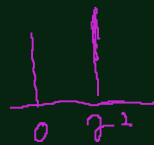
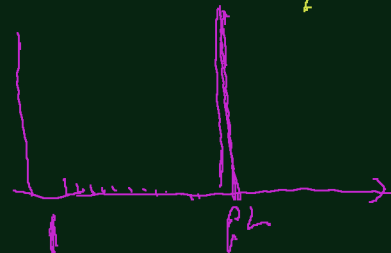
under some assumptions to achieve dynamical isometry.

Sketch

$$H_{L+1} = \hat{\beta}_L + W_{L+1} D_L H_L D_L^* W_{L+1}^*$$

asymptotic freeness

$$\Rightarrow \underbrace{\mu_{L+1}}_{H_{L+1}} = (\underbrace{q}_{\hat{\beta}_L} + \underbrace{\cdot}_{D_L^2} \underbrace{\mu_L}_{\mu_L})$$

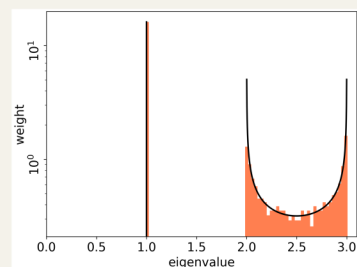
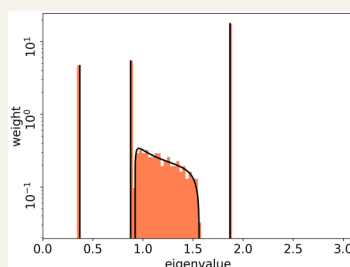
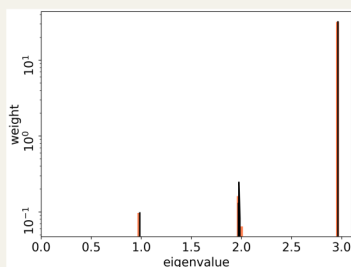


Point: If activation function is ReLU-like ftn,

μ_L has an atom as a maximal point spectrum,

$$\nu \boxtimes \mu(\{ab\}) = \nu(\{a\}) \mu(\{b\}) + \mu(\{bb\}) - 1.$$

Limit spectral distributions : $L = 3$



$D \rightarrow P$ PR p.c. free
0 or 1

Training Dynamics

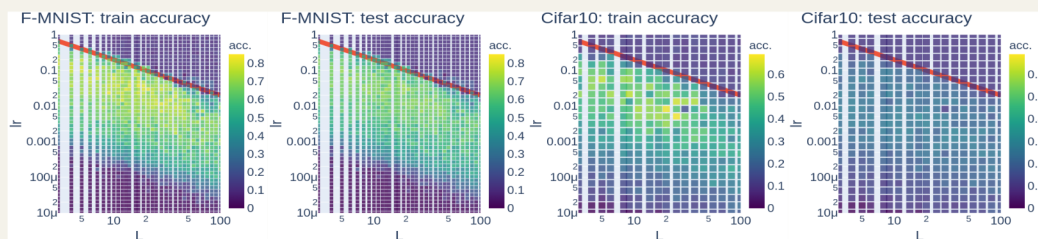
- $\eta > \frac{1}{\lambda_{\max}(H_L)} \Rightarrow$ The training dynamics may not converge

Training under D. Isometry

Red line (the boarder line of the exploding gradients) :

$$\eta = 2/L$$

This line is expected by our theory !



Conclusion

- Random Matrices appear in the theory of deep neural networks (e.g. dynamical isometry, Fisher Information, NTK)
- Since Jacobian (input or parameter) are (noncommutative) polynomials of Random Matrices,

Free Probability Theory provides tools for handling them!

To use this, we have to prove asymptotic freeness $\left\{ \begin{array}{l} \text{a.s.} \\ \text{expected} \\ \text{strong (operator norm)} \end{array} \right.$

Gaussian $\left\{ \begin{array}{l} \text{Havin-Naim 19} \\ \text{Yang 19, '20} \\ \text{Pastur '20} \end{array} \right.$

Orthogonal \rightarrow H. '67 (under preparation)

gradient independence

$\left\{ \begin{array}{l} w^1, \dots, w^L \\ D^1, \dots, D^L \end{array} \right. \leftarrow \begin{array}{l} \text{independent} \\ \in \mathbb{R}^{n \times n} \end{array}$

freeness $\rightarrow \text{tr}(\mathbb{Q}(w^1, \dots, w^L, D^1, \dots, D^L))$
: ok (?)