Tensor Products of Pointed Sets

The Clowder Project Authors

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In this chapter we introduce, construct, and study tensor products of pointed sets. The most well-known among these is the *smash product of pointed sets*

$$\wedge : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

introduced in Section 7.5.1, defined via a universal property as inducing a bijection between the following data:

- Pointed maps $f: X \wedge Y \to Z$.
- Maps of sets $f: X \times Y \to Z$ satisfying

$$f(x_0, y) = z_0,$$

$$f(x, y_0) = z_0$$

for each $x \in X$ and each $y \in Y$.

As it turns out, however, dropping either of the bilinearity conditions

$$f(x_0,y)=z_0,$$

$$f(x, y_0) = z_0$$

while retaining the other leads to two other tensor products of pointed sets,

$$\triangleleft \colon \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*,$$

$$\triangleright$$
: Sets_{*} × Sets_{*} \rightarrow Sets_{*},

called the *left* and *right tensor products of pointed sets*. In contrast to \land , which turns out to endow Sets* with a monoidal category structure (Proposition 7.5.9.1.1), these do not admit invertible associators and unitors, but do endow Sets* with the structure of a skew monoidal category, however (Propositions 7.3.8.1.1 and 7.4.8.1.1).

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Finally, in addition to the tensor products \triangleleft , \triangleright , and \wedge , we also have a "tensor product" of the form

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\odot: Sets \times Sets_* \rightarrow Sets_*,
```

called the *tensor* of sets with pointed sets. All in all, these tensor products assemble into a family of functors of the form

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\begin{split} & \otimes_{k,\ell} \colon \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}) \times \mathsf{Mon}_{\mathbb{B}_\ell}(\mathsf{Sets}) \to \mathsf{Mon}_{\mathbb{B}_{k+\ell}}(\mathsf{Sets}), \\ & \lhd_{i,k} \colon \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}) \times \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}) \to \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}), \\ & \rhd_{i,k} \colon \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}) \times \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}) \to \mathsf{Mon}_{\mathbb{B}_k}(\mathsf{Sets}), \end{split}
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where $k, \ell, i \in \mathbb{N}$ with $i \le k - 1$. Together with the Cartesian product \times of Sets, the tensor products studied in this chapter form the cases:

- $(k, \ell) = (-1, -1)$ for the Cartesian product of Sets;
- $(k, \ell) = (0, -1)$ and (-1, 0) for the tensor of sets with pointed sets of Definition 7.2.1.1.1;
- (i, k) = (−1, 0) for the left and right tensor products of pointed sets of Sections 7.3 and 7.4;
- $(k, \ell) = (-1, -1)$ for the smash product of pointed sets of Section 7.5.

In this chapter, we will carefully define and study bilinearity for pointed sets, as well as all the tensor products described above. Then, in $\ref{eq:condition}$, we will extend these to tensor products involving also monoids and commutative monoids, which will end up covering all cases up to $k, \ell \leq 2$, and hence *all* cases since \mathbb{E}_k -monoids on Sets are the same as \mathbb{E}_2 -monoids on Sets when $k \geq 2$.

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00C4 7.1 Bilinear Morphisms of Pointed Sets

00C5 7.1.1 Left Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

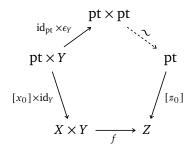
00C6 DEFINITION 7.1.1.1.1 ► LEFT BILINEAR MORPHISMS OF POINTED SETS

A left bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: X \times Y \to Z$$

satisfying the following condition:^{1,2}

(★) Left Unital Bilinearity. The diagram



commutes, i.e. for each $y \in Y$, we have

$$f(x_0, y) = z_0.$$

$$f(x_0, y) = z_0$$

for each $y \in Y$.

 $^{^1}Slogan$: The map f is left bilinear if it preserves basepoints in its first argument.

²Succinctly, f is bilinear if we have

00C7 DEFINITION 7.1.1.1.2 ➤ THE SET OF LEFT BILINEAR MORPHISMS OF POINTED SETS

The set of left bilinear morphisms of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is the set $\mathrm{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{L}}(X \times Y, Z)$ defined by

 $\operatorname{Hom}_{\mathsf{Sets}_*}^{\otimes,\mathsf{L}}(X\times Y,Z)\stackrel{\mathrm{def}}{=}\{f\in\operatorname{Hom}_{\mathsf{Sets}}(X\times Y,Z)\mid f\text{ is left bilinear}\}.$

00C8 7.1.2 Right Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

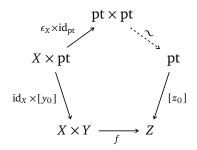
00C9 DEFINITION 7.1.2.1.1 ➤ RIGHT BILINEAR MORPHISMS OF POINTED SETS

A right bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: X \times Y \to Z$$

satisfying the following condition:^{1,2}

(★) Right Unital Bilinearity. The diagram



commutes, i.e. for each $x \in X$, we have

$$f(x, y_0) = z_0.$$

$$f(x, y_0) = z_0$$

for each $x \in X$.

¹Slogan: The map f is right bilinear if it preserves basepoints in its second argument.

²Succinctly, f is bilinear if we have

00CA

DEFINITION 7.1.2.1.2 ► THE SET OF RIGHT BILINEAR MORPHISMS OF POINTED SETS

The set of right bilinear morphisms of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is the set $\operatorname{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{R}}(X \times Y, Z)$ defined by

 $\operatorname{Hom}_{\mathsf{Sets}_*}^{\otimes,\mathsf{R}}(X\times Y,Z)\stackrel{\operatorname{def}}{=}\{f\in\operatorname{Hom}_{\mathsf{Sets}}(X\times Y,Z)\mid f\text{ is right bilinear}\}.$

00CB 7.1.3 Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

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DEFINITION 7.1.3.1.1 ► BILINEAR MORPHISMS OF POINTED SETS

A bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: X \times Y \to Z$$

that is both left bilinear and right bilinear.

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REMARK 7.1.3.1.2 ► Unwinding Definition 7.1.3.1.1

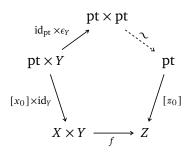
In detail, a bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: (X \times Y, (x_0, y_0)) \rightarrow (Z, z_0)$$

satisfying the following conditions: 1,2

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1. Left Unital Bilinearity. The diagram

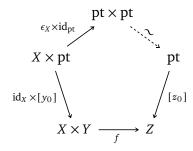


commutes, i.e. for each $y \in Y$, we have

$$f(x_0, y) = z_0.$$

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2. Right Unital Bilinearity. The diagram



commutes, i.e. for each $x \in X$, we have

$$f(x, y_0) = z_0.$$

$$f(x_0,y)=z_0,$$

$$f(x,y_0)=z_0$$

for each $x \in X$ and each $y \in Y$.

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DEFINITION 7.1.3.1.3 ► THE SET OF BILINEAR MORPHISMS OF POINTED SETS

The set of bilinear morphisms of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is the set $\mathrm{Hom}_{\mathsf{Sets.}}^{\otimes}(X \times Y, Z)$ defined by

$$\operatorname{Hom}_{\mathsf{Sets}_*}^{\otimes}(X \times Y, Z) \stackrel{\text{def}}{=} \{ f \in \operatorname{Hom}_{\mathsf{Sets}}(X \times Y, Z) \mid f \text{ is bilinear} \}.$$

OOCF 7.2 Tensors and Cotensors of Pointed Sets by Sets

OOCG 7.2.1 Tensors of Pointed Sets by Sets

Let (X, x_0) be a pointed set and let A be a set.

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DEFINITION 7.2.1.1.1 ► TENSORS OF POINTED SETS BY SETS

The **tensor of** (X, x_0) **by** A^1 is the tensor $A \odot (X, x_0)^2$ of (X, x_0) by A as in Limits and Colimits, ??.

¹*Slogan:* The map f is bilinear if it preserves basepoints in each argument.

²Succinctly, f is bilinear if we have

¹Further Terminology: Also called the **copower of** (X, x_0) **by** A.

²Further Notation: Often written $A \odot X$ for simplicity.

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In detail, the **tensor of** (X, x_0) **by** A is the pointed set $A \odot (X, x_0)$ satisfying the following universal property:

 (\star) We have a bijection

$$\mathsf{Sets}_*(A \odot X, K) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(X, K)),$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$.

This universal property is in turn equivalent to the following one:

(★) We have a bijection

$$\mathsf{Sets}_*(A \odot X, K) \cong \mathsf{Sets}^{\otimes}_{\mathbb{E}_0}(A \times X, K),$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$, where $\mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K)$ is the set defined by

$$\mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K) \stackrel{\mathsf{def}}{=} \left\{ f \in \mathsf{Sets}(A \times X, K) \, \middle| \, \begin{array}{l} \mathsf{for \ each} \ a \in A, \ \mathsf{we} \\ \mathsf{have} \ f(a, x_0) = k_0 \end{array} \right\}.$$

PROOF 7.2.1.1.3 ► PROOF OF THE EQUIVALENCE IN REMARK 7.2.1.1.2

We claim that we have a bijection

$$\mathsf{Sets}(A,\mathsf{Sets}_*(X,K))\cong\mathsf{Sets}_{\mathbb{E}_0}^\otimes(A\times X,K)$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$. Indeed, this bijection is a restriction of the bijection

$$Sets(A, Sets(X, K)) \cong Sets(A \times X, K)$$

of Constructions With Sets, Item 2 of Proposition 4.1.3.1.4:

A map

$$\xi \colon A \longrightarrow \mathsf{Sets}_*(X, K),$$

 $a \mapsto (\xi_a \colon X \to K),$

in $Sets(A, Sets_*(X, K))$ gets sent to the map

$$\xi^{\dagger}: A \times X \to K$$

defined by

$$\xi^{\dagger}(a,x) \stackrel{\text{def}}{=} \xi_a(x)$$

for each $(a, x) \in A \times X$, which indeed lies in $\mathsf{Sets}^{\otimes}_{\mathbb{E}_0}(A \times X, K)$, as we have

$$\xi^{\dagger}(a, x_0) \stackrel{\text{def}}{=} \xi_a(x_0)$$

$$\stackrel{\text{def}}{=} k_0$$

for each $a \in A$, where we have used that $\xi_a \in \mathsf{Sets}_*(X,K)$ is a morphism of pointed sets.

· Conversely, a map

$$\xi: A \times X \to K$$

in $\mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K)$ gets sent to the map

$$\xi^{\dagger} \colon A \longrightarrow \mathsf{Sets}_*(X,K),$$

$$a \mapsto (\xi_a^{\dagger} \colon X \to K),$$

where

$$\xi_a^{\dagger} \colon X \to K$$

is the map defined by

$$\xi_a^{\dagger}(x) \stackrel{\text{def}}{=} \xi(a, x)$$

for each $x \in X$, and indeed lies in Sets_{*}(X, K), as we have

$$\xi_a^{\dagger}(x_0) \stackrel{\text{def}}{=} \xi(a, x_0)$$

$$\stackrel{\text{def}}{=} k_0.$$

This finishes the proof.

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CONSTRUCTION 7.2.1.1.4 ➤ CONSTRUCTION OF TENSORS OF POINTED SETS BY SETS

Concretely, the **tensor of** (X, x_0) **by** A is the pointed set $A \odot (X, x_0)$ consisting of:

• *The Underlying Set.* The set $A \odot X$ given by

$$A\odot X\cong\bigvee_{a\in A}(X,x_0),$$

where $\bigvee_{a \in A} (X, x_0)$ is the wedge product of the *A*-indexed family $((X, x_0))_{a \in A}$ of Pointed Sets, Definition 6.3.2.1.1.

• *The Basepoint.* The point $[(a,x_0)] = [(a',x_0)]$ of $\bigvee_{a \in A} (X,x_0)$.

PROOF 7.2.1.1.5 ► PROOF OF CONSTRUCTION 7.2.1.1.4

(Proven below in a bit.)

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NOTATION 7.2.1.1.6 ► ELEMENTS OF TENSORS OF POINTED SETS BY SETS

We write $a \odot x$ for the element [(a, x)] of

$$A \odot X \cong \bigvee_{\alpha \in A} (X, x_0)$$

$$\stackrel{\text{def}}{=} (\coprod_{i \in I} X_i) / \sim.$$

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REMARK 7.2.1.1.7 ▶ BASEPOINTS OF TENSORS OF POINTED SETS BY SETS

Taking the tensor of any element of A with the basepoint x_0 of X leads to the same element in $A \odot X$, i.e. we have

$$a\odot x_0=a'\odot x_0,$$

for each $a, a' \in A$. This is due to the equivalence relation \sim on

$$\bigvee_{a \in A} (X, x_0) \stackrel{\text{def}}{=} \coprod_{a \in A} X / \sim$$

identifying (a, x_0) with (a', x_0) , so that the equivalence class $a \odot x_0$ is independent from the choice of $a \in A$.

PROOF 7.2.1.1.8 ► PROOF OF CONSTRUCTION 7.2.1.1.4

We claim we have a bijection

$$\mathsf{Sets}_*(A \odot X, K) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(X, K))$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$.

1. Map I. We define a map

$$\Phi_K : \mathsf{Sets}_*(A \odot X, K) \to \mathsf{Sets}(A, \mathsf{Sets}_*(X, K))$$

by sending a morphism of pointed sets

$$\xi \colon (A \odot X, a \odot x_0) \to (K, k_0)$$

to the map of sets

$$\xi^{\dagger} : A \longrightarrow \mathsf{Sets}_*(X, K),$$

 $a \mapsto (\xi_a : X \to K),$

where

$$\xi_a \colon (X, x_0) \to (K, k_0)$$

is the morphism of pointed sets defined by

$$\xi_a(x) \stackrel{\text{def}}{=} \xi(a \odot x)$$

for each $x \in X$. Note that we have

$$\xi_a(x_0) \stackrel{\text{def}}{=} \xi(a \odot x_0)$$
$$= k_0,$$

so that ξ_a is indeed a morphism of pointed sets, where we have used that ξ is a morphism of pointed sets.

2. Map II. We define a map

$$\Psi_K : \mathsf{Sets}(A, \mathsf{Sets}_*(X, K)) \to \mathsf{Sets}_*(A \odot X, K)$$

given by sending a map

$$\xi \colon A \longrightarrow \mathsf{Sets}_*(X, K),$$

 $a \mapsto (\xi_a \colon X \to K),$

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to the morphism of pointed sets

$$\xi^{\dagger} : (A \odot X, a \odot x_0) \rightarrow (K, k_0)$$

defined by

$$\xi^{\dagger}(a\odot x)\stackrel{\mathrm{def}}{=}\xi_a(x)$$

for each $a \odot x \in A \odot X$. Note that ξ^{\dagger} is indeed a morphism of pointed sets, as we have

$$\xi^{\dagger}(a \odot x_0) \stackrel{\text{def}}{=} \xi_a(x_0)$$
$$= k_0.$$

where we have used that $\xi(a) \in \mathsf{Sets}_*(X, K)$ is a morphism of pointed sets.

3. Invertibility I. We claim that

$$\Psi_K \circ \Phi_K = \mathrm{id}_{\mathsf{Sets}_*(A \odot X, K)}$$
.

Indeed, given a morphism of pointed sets

$$\xi \colon (A \odot X, a \odot x_0) \to (K, k_0),$$

we have

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$$\begin{split} [\Psi_K \circ \Phi_K](\xi) &= \Psi_K(\Phi_K(\xi)) \\ &= \Psi_K(\llbracket a \mapsto \llbracket x \mapsto \xi(a \odot x) \rrbracket \rrbracket)) \\ &= \Psi_K(\llbracket a' \mapsto \llbracket x' \mapsto \xi(a' \odot x') \rrbracket \rrbracket)) \\ &= \llbracket a \odot x \mapsto \operatorname{ev}_x(\operatorname{ev}_a(\llbracket a' \mapsto \llbracket x' \mapsto \xi(a' \odot x') \rrbracket \rrbracket)) \rrbracket \\ &= \llbracket a \odot x \mapsto \operatorname{ev}_x(\llbracket x' \mapsto \xi(a \odot x') \rrbracket) \rrbracket \\ &= \llbracket a \odot x \mapsto \xi(a \odot x) \rrbracket \\ &= \xi. \end{split}$$

4. Invertibility II. We claim that

$$\Phi_K \circ \Psi_K = \mathrm{id}_{\mathsf{Sets}(A,\mathsf{Sets}_*(X,K))}.$$

Indeed, given a morphism $\xi: A \to \mathsf{Sets}_*(X, K)$, we have

$$[\Phi_K \circ \Psi_K](\xi) = \Phi_K(\Psi_K(\xi))$$

$$= \Phi_K(\llbracket a \odot x \mapsto \xi_a(x) \rrbracket)$$

$$= \llbracket a \mapsto \llbracket x \mapsto \xi_a(x) \rrbracket \rrbracket$$

$$= \llbracket a \mapsto \xi(a) \rrbracket$$

$$= \xi.$$

5. *Naturality of* Φ . We need to show that, given a morphism of pointed sets

$$\phi \colon (K, k_0) \to (K', k'_0),$$

the diagram

$$\begin{array}{ccc} \mathsf{Sets}_*(A \odot X, K) & \stackrel{\Phi_K}{\longrightarrow} & \mathsf{Sets}(A, \mathsf{Sets}_*(X, K)) \\ & & & \downarrow^{(\phi_*)_*} \\ \\ \mathsf{Sets}_*(A \odot X, K') & \stackrel{\Phi_{K'}}{\longrightarrow} & \mathsf{Sets}(A, \mathsf{Sets}_*(X, K')) \end{array}$$

commutes. Indeed, given a morphism of pointed sets

$$\xi \colon (A \odot X, a \odot x_0) \to (K, k_0),$$

we have

$$\begin{split} [\Phi_{K'} \circ \phi_*](\xi) &= \Phi_{K'}(\phi_*(\xi)) \\ &= \Phi_{K'}(\phi \circ \xi) \\ &= (\phi \circ \xi)^{\dagger} \\ &= [\![a \mapsto \phi \circ \xi (a \odot -)]\!] \\ &= [\![a \mapsto \phi_*(\xi (a \odot -))]\!] \\ &= (\phi_*)_*([\![a \mapsto \xi (a \odot -]]\!])) \\ &= (\phi_*)_*(\Phi_K(\xi)) \\ &= [(\phi_*)_* \circ \Phi_K](\xi). \end{split}$$

6. Naturality of Ψ . Since Φ is natural and Φ is a componentwise inverse to Ψ , it follows from Categories, Item 2 of Proposition 11.9.7.1.2 that Ψ is also natural.

This finishes the proof.

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00CN PROPOSITION 7.2.1.1.9 ▶ PROPERTIES OF TENSORS OF POINTED SETS BY SETS

Let (X, x_0) be a pointed set and let A be a set.

1. Functoriality. The assignments A, (X, x_0) , $(A, (X, x_0))$ define functors

$$A \odot -:$$
 Sets_{*} \rightarrow Sets_{*},
 $- \odot X:$ Sets \rightarrow Sets_{*},
 $-_1 \odot -_2:$ Sets \times Sets_{*} \rightarrow Sets_{*}.

In particular, given:

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- A map of sets $f: A \rightarrow B$;
- A pointed map $\phi: (X, x_0) \to (Y, y_0)$;

the induced map

$$f \odot \phi : A \odot X \rightarrow B \odot Y$$

is given by

$$[f \odot \phi](a \odot x) \stackrel{\text{def}}{=} f(a) \odot \phi(x)$$

for each $a \odot x \in A \odot X$.

2. Adjointness I. We have an adjunction

$$(-\odot X \dashv \mathsf{Sets}_*(X,-))$$
: $\mathsf{Sets}_*(X,-)$

witnessed by a bijection

$$\mathsf{Sets}_*(A \odot X, K) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(X, K)),$$

natural in $A \in \text{Obj}(\mathsf{Sets})$ and $X, Y \in \text{Obj}(\mathsf{Sets}_*)$.

3. Adjointness II. We have an adjunctions

$$(A \odot - \dashv A \pitchfork -)$$
: Sets_{*} $\underbrace{\stackrel{A \odot -}{\bot}}_{A \pitchfork -}$ Sets_{*},

witnessed by a bijection

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}(A\odot X,Y)\cong \operatorname{\mathsf{Hom}}_{\operatorname{\mathsf{Sets}}_*}(X,A\pitchfork Y),$$

natural in $A \in Obj(Sets)$ and $X, Y \in Obj(Sets_*)$.

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4. As a Weighted Colimit. We have

$$A \odot X \cong \operatorname{colim}^{[A]}(X),$$

where in the right hand side we write:

- A for the functor A: pt \rightarrow Sets picking $A \in Obj(Sets)$;
- *X* for the functor *X*: pt \rightarrow Sets_{*} picking $(X, x_0) \in Obj(Sets_*)$.

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5. Iterated Tensors. We have an isomorphism of pointed sets

$$A \odot (B \odot X) \cong (A \times B) \odot X$$

natural in $A, B \in \text{Obj}(\mathsf{Sets})$ and $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$.

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6. Interaction With Homs. We have a natural isomorphism

$$\mathsf{Sets}_*(A \odot X, -) \cong A \pitchfork \mathsf{Sets}_*(X, -).$$

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7. The Tensor Evaluation Map. For each $X, Y \in Obj(Sets_*)$, we have a map

$$\operatorname{ev}_{X,Y}^{\odot} \colon \operatorname{\mathsf{Sets}}_*(X,Y) \odot X \to Y,$$

natural in $X, Y \in Obj(Sets_*)$, and given by

$$\operatorname{ev}_{X,Y}^{\odot}(f\odot x)\stackrel{\mathrm{def}}{=} f(x)$$

for each $f \odot x \in \mathsf{Sets}_*(X,Y) \odot X$.

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8. The Tensor Coevaluation Map. For each $A \in Obj(Sets)$ and each $X \in Obj(Sets_*)$, we have a map

$$\operatorname{coev}_{A,X}^{\odot} \colon A \to \operatorname{\mathsf{Sets}}_*(X, A \odot X),$$

natural in $A \in \text{Obj}(\mathsf{Sets})$ and $X \in \text{Obj}(\mathsf{Sets}_*)$, and given by

$$\mathsf{coev}_{A,X}^{\odot}(a) \stackrel{\scriptscriptstyle\mathsf{def}}{=} \llbracket x \mapsto a \odot x \rrbracket$$

for each $a \in A$.

PROOF 7.2.1.1.10 ► PROOF OF PROPOSITION 7.2.1.1.9

Item 1: Functoriality

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 2: Adjointness I

This is simply a rephrasing of Definition 7.2.1.1.1.

Item 3: : Adjointness II

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 4: As a Weighted Colimit

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 5: Iterated Tensors

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 6: Interaction With Homs

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 7: The Tensor Evaluation Map

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 8: The Tensor Coevaluation Map

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

00CX 7.2.2 Cotensors of Pointed Sets by Sets

Let (X, x_0) be a pointed set and let A be a set.

00CY DEFINITION 7.2.2.1.1 ► COTENSORS OF POINTED SETS BY SETS

The **cotensor of** (X, x_0) **by** A^1 is the cotensor $A \pitchfork (X, x_0)^2$ of (X, x_0) by A as in Limits and Colimits, ??.

REMARK 7.2.2.1.2 ► UNWINDING DEFINITION 7.2.2.1.1

In detail, the **cotensor of** (X, x_0) **by** A is the pointed set $A \pitchfork (X, x_0)$ satisfying the following universal property:

(★) We have a bijection

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$$\mathsf{Sets}_*(K, A \pitchfork X) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(K, X)),$$

¹Further Terminology: Also called the **power of** (X, x_0) **by** A.

²Further Notation: Often written $A \cap X$ for simplicity.

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$.

This universal property is in turn equivalent to the following one:

(★) We have a bijection

$$\mathsf{Sets}_*(K, A \pitchfork X) \cong \mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X),$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$, where $\mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X)$ is the set defined by

$$\mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X) \stackrel{\text{def}}{=} \left\{ f \in \mathsf{Sets}(A \times K, X) \, \middle| \, \begin{array}{l} \text{for each } a \in A, \text{ we} \\ \text{have } f(a, k_0) = x_0 \end{array} \right\}.$$

PROOF 7.2.2.1.3 ► PROOF OF THE EQUIVALENCE IN REMARK 7.2.2.1.2

This follows from the bijection

$$\mathsf{Sets}(A,\mathsf{Sets}_*(K,X)) \cong \mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K,X),$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$ constructed in the proof of Remark 7.2.1.1.2.

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CONSTRUCTION 7.2.2.1.4 ➤ CONSTRUCTION OF COTENSORS OF POINTED SETS BY SETS

Concretely, the **cotensor of** (X, x_0) **by** A is the pointed set $A \pitchfork (X, x_0)$ consisting of:

• The Underlying Set. The set $A \cap X$ given by

$$A \pitchfork X \cong \bigwedge_{a \in A} (X, x_0),$$

where $\bigwedge_{a \in A}(X, x_0)$ is the smash product of the *A*-indexed family $((X, x_0))_{a \in A}$ of Definition 7.6.1.1.1.

• The Basepoint. The point $[(x_0)_{a\in A}] = [(x_0, x_0, x_0, \dots)]$ of $\bigwedge_{a\in A}(X, x_0)$.

PROOF 7.2.2.1.5 ► PROOF OF CONSTRUCTION 7.2.2.1.4

We claim we have a bijection

$$\mathsf{Sets}_*(K, A \pitchfork X) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(K, X)),$$

natural in $(K, k_0) \in \text{Obj}(\mathsf{Sets}_*)$.

1. Map I. We define a map

$$\Phi_K \colon \mathsf{Sets}_*(K, A \pitchfork X) \to \mathsf{Sets}(A, \mathsf{Sets}_*(K, X)),$$

by sending a morphism of pointed sets

$$\xi \colon (K, k_0) \to (A \pitchfork X, [(x_0)_{a \in A}])$$

to the map of sets

$$\xi^{\dagger}: A \longrightarrow \mathsf{Sets}_{*}(K, X),$$

$$a \mapsto (\xi_a \colon K \to X),$$

where

$$\xi_a \colon (K, k_0) \to (X, x_0)$$

is the morphism of pointed sets defined by

$$\xi_a(k) = \begin{cases} x_a^k & \text{if } \xi(k) \neq [(x_0)_{a \in A}], \\ x_0 & \text{if } \xi(k) = [(x_0)_{a \in A}] \end{cases}$$

for each $k \in K$, where x_a^k is the ath component of $\xi(k) = [(x_a^k)_{a \in A}]$. Note that:

(a) The definition of $\xi_a(k)$ is independent of the choice of equivalence class. Indeed, suppose we have

$$\xi(k) = [(x_a^k)_{a \in A}]$$
$$= [(y_a^k)_{a \in A}]$$

with $x_a^k \neq y_a^k$ for some $a \in A$. Then there exist $a_x, a_y \in A$ such that $x_{a_x}^k = y_{a_y}^k = x_0$. The equivalence relation \sim on $\prod_{a \in A} X$ then forces

$$[(x_a^k)_{a \in A}] = [(x_0)_{a \in A}],$$
$$[(y_a^k)_{a \in A}] = [(x_0)_{a \in A}],$$

however, and $\xi_a(k)$ is defined to be x_0 in this case.

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(b) The map ξ_a is indeed a morphism of pointed sets, as we have

$$\xi_a(k_0) = x_0$$

since $\xi(k_0) = [(x_0)_{a \in A}]$ as ξ is a morphism of pointed sets and $\xi_a(k_0)$, defined to be the *a*th component of $[(x_0)_{a \in A}]$, is equal to x_0 .

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2. Map II. We define a map

$$\Psi_K$$
: Sets $(A, Sets_*(K, X)) \rightarrow Sets_*(K, A \cap X)$,

given by sending a map

$$\xi: A \longrightarrow \mathsf{Sets}_*(K, X),$$

 $a \mapsto (\xi_a: K \to X),$

to the morphism of pointed sets

$$\xi^{\dagger} \colon (K, k_0) \to (A \pitchfork X, [(x_0)_{a \in A}])$$

defined by

$$\xi^{\dagger}(k) \stackrel{\text{def}}{=} [(\xi_a(k))_{a \in A}]$$

for each $k \in K$. Note that ξ^{\dagger} is indeed a morphism of pointed sets, as we have

$$\xi^{\dagger}(k_0) \stackrel{\text{def}}{=} [(\xi_a(k_0))_{a \in A}]$$
$$= x_0,$$

where we have used that $\xi_a \in \mathsf{Sets}_*(K, X)$ is a morphism of pointed sets for each $a \in A$.

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3. Invertibility I. We claim that

$$\Psi_K \circ \Phi_K = \mathrm{id}_{\mathsf{Sets}_*(K,A \cap X)}$$
.

Indeed, given a morphism of pointed sets

$$\xi \colon (K, k_0) \to (A \pitchfork X, [(x_0)_{a \in A}])$$

we have

$$\begin{split} \big[\Psi_K \circ \Phi_K \big] (\xi) &= \Psi_K (\Phi_K (\xi)) \\ &= \Psi_K (\big[a \mapsto \xi_a \big] \big) \\ &= \Psi_K (\big[a' \mapsto \xi_{a'} \big] \big) \\ &= \big[k \mapsto \big[(\operatorname{ev}_a (\big[a' \mapsto \xi_{a'} (k) \big] \big])_{a \in A} \big] \big] \big] \\ &= \big[k \mapsto \big[(\xi_a (k))_{a \in A} \big] \big]. \end{split}$$

Now, we have two cases:

(a) If $\xi(k) = [(x_0)_{a \in A}]$, we have

$$\begin{split} [\Psi_K \circ \Phi_K](\xi) &= \llbracket k \mapsto [(\xi_a(k))_{a \in A}] \rrbracket \\ &= \llbracket k \mapsto [(x_0)_{a \in A}] \rrbracket \\ &= \llbracket k \mapsto \xi(k) \rrbracket \\ &= \xi. \end{split}$$

(b) If $\xi(k) \neq [(x_0)_{a \in A}]$ and $\xi(k) = [(x_a^k)_{a \in A}]$ instead, we have

$$\begin{aligned} [\Psi_K \circ \Phi_K](\xi) &= \llbracket k \mapsto [(\xi_a(k))_{a \in A}] \rrbracket \\ &= \llbracket k \mapsto [(x_a^k)_{a \in A}] \rrbracket \\ &= \llbracket k \mapsto \xi(k) \rrbracket \\ &= \xi. \end{aligned}$$

In both cases, we have $[\Psi_K \circ \Phi_K](\xi) = \xi$, and thus we are done.

4. Invertibility II. We claim that

$$\Phi_K \circ \Psi_K = \mathrm{id}_{\mathsf{Sets}(A,\mathsf{Sets}_*(K,X))} \; .$$

Indeed, given a morphism $\xi: A \to \mathsf{Sets}_*(K, X)$, we have

$$\begin{split} [\Phi_K \circ \Psi_K](\xi) &= \Phi_K(\Psi_K(\xi)) \\ &= \Phi_K(\llbracket k \mapsto \llbracket (\xi_a(k))_{a \in A} \rrbracket \rrbracket) \\ &= \llbracket a \mapsto \llbracket k \mapsto \xi_a(k) \rrbracket \rrbracket \rrbracket \\ &= \xi \end{split}$$

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5. Naturality of Ψ . We need to show that, given a morphism of pointed sets

$$\phi: (K, k_0) \to (K', k'_0),$$

the diagram

$$\mathsf{Sets}(A,\mathsf{Sets}_*(K',X)) \xrightarrow{\Psi_{K'}} \mathsf{Sets}_*(K',A \pitchfork X)$$

$$(\phi^*)_* \downarrow \qquad \qquad \qquad \downarrow \phi^*$$

$$\mathsf{Sets}(A,\mathsf{Sets}_*(K,X)) \xrightarrow{\Psi_{K'}} \mathsf{Sets}_*(K,A \pitchfork X)$$

commutes. Indeed, given a map of sets

$$\xi: A \longrightarrow \mathsf{Sets}_*(K', X),$$

 $a \mapsto (\xi_a: K' \to X),$

we have

$$\begin{split} \big[\Psi_{K} \circ (\phi^{*})_{*} \big] (\xi) &= \Psi_{K} ((\phi^{*})_{*}(\xi)) \\ &= \Psi_{K} ((\phi^{*})_{*} (\llbracket a \mapsto \xi_{a} \rrbracket)) \\ &= \Psi_{K} ((\llbracket a \mapsto \phi^{*}(\xi_{a}) \rrbracket)) \\ &= \Psi_{K} ((\llbracket a \mapsto \llbracket k \mapsto \xi_{a}(\phi(k)) \rrbracket \rrbracket)) \\ &= \llbracket k \mapsto [(\xi_{a}(\phi(k)))_{a \in A}] \rrbracket \\ &= \phi^{*} (\llbracket k' \mapsto [(\xi_{a}(k'))_{a \in A}] \rrbracket) \\ &= \phi^{*} (\Psi_{K'}(\xi)) \\ &= [\phi^{*} \circ \Psi_{K'}] (\xi). \end{split}$$

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6. Naturality of Φ . Since Ψ is natural and Ψ is a componentwise inverse to Φ , it follows from Categories, Item 2 of Proposition 11.9.7.1.2 that Φ is also natural.

This finishes the proof.

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PROPOSITION 7.2.2.1.6 ► PROPERTIES OF COTENSORS OF POINTED SETS BY SETS

Let (X, x_0) be a pointed set and let A be a set.

00D2 1. Functoriality. The assignments $A, (X, x_0), (A, (X, x_0))$ define functors

$$\begin{array}{cccc} A \pitchfork -\colon & \mathsf{Sets}_* & \to \mathsf{Sets}_*, \\ - \pitchfork X \colon & \mathsf{Sets}^\mathsf{op} & \to \mathsf{Sets}_*, \\ -_1 \pitchfork -_2 \colon \mathsf{Sets}^\mathsf{op} \times \mathsf{Sets}_* \to \mathsf{Sets}_*. \end{array}$$

In particular, given:

- A map of sets $f: A \rightarrow B$;
- A pointed map $\phi: (X, x_0) \to (Y, y_0)$;

the induced map

$$f \odot \phi \colon A \pitchfork X \to B \pitchfork Y$$

is given by

$$[f \odot \phi]([(x_a)_{a \in A}]) \stackrel{\text{def}}{=} [(\phi(x_{f(a)}))_{a \in A}]$$

for each $[(x_a)_{a \in A}] \in A \cap X$.

2. Adjointness I. We have an adjunction

$$(- \pitchfork X \dashv \mathsf{Sets}_*(-,X))$$
: $\mathsf{Sets}^{\mathsf{op}} \underbrace{\bot}_{\mathsf{Sets}_*(-,X)} \mathsf{Sets}_*,$

witnessed by a bijection

$$\mathsf{Sets}^{\mathsf{op}}_*(A \pitchfork X, K) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(K, X)),$$

i.e. by a bijection

$$\mathsf{Sets}_*(K, A \pitchfork X) \cong \mathsf{Sets}(A, \mathsf{Sets}_*(K, X)),$$

natural in $A \in \text{Obj}(\mathsf{Sets})$ and $X, Y \in \text{Obj}(\mathsf{Sets}_*)$.

3. Adjointness II. We have an adjunctions

$$(A \odot - \dashv A \pitchfork -)$$
: Sets_{*} $\xrightarrow{A \odot -}$ Sets_{*},

witnessed by a bijection

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}(A\odot X,Y)\cong \operatorname{\mathsf{Hom}}_{\operatorname{\mathsf{Sets}}_*}(X,A\pitchfork Y),$$

natural in $A \in Obj(Sets)$ and $X, Y \in Obj(Sets_*)$.

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4. As a Weighted Limit. We have

$$A \cap X \cong \lim^{[A]}(X),$$

where in the right hand side we write:

- A for the functor A: pt \rightarrow Sets picking $A \in Obj(Sets)$;
- *X* for the functor *X*: pt \rightarrow Sets_{*} picking $(X, x_0) \in Obj(Sets_*)$.

00D6

5. Iterated Cotensors. We have an isomorphism of pointed sets

$$A \pitchfork (B \pitchfork X) \cong (A \times B) \pitchfork X$$
,

natural in $A, B \in Obj(Sets)$ and $(X, x_0) \in Obj(Sets_*)$.

00D7

6. Commutativity With Homs. We have natural isomorphisms

$$A \pitchfork \mathsf{Sets}_*(X, -) \cong \mathsf{Sets}_*(A \odot X, -),$$

 $A \pitchfork \mathsf{Sets}_*(-, Y) \cong \mathsf{Sets}_*(-, A \pitchfork Y).$

00D8

7. *The Cotensor Evaluation Map.* For each $X, Y \in Obj(Sets_*)$, we have a map

$$\operatorname{ev}_{X,Y}^{\pitchfork} \colon X \to \operatorname{\mathsf{Sets}}_*(X,Y) \pitchfork Y,$$

natural in $X, Y \in Obj(Sets_*)$, and given by

$$\operatorname{ev}_{XY}^{\uparrow}(x) \stackrel{\text{def}}{=} [(f(x))_{f \in \operatorname{Sets}_*(X,Y)}]$$

for each $x \in X$.

00D9

8. *The Cotensor Coevaluation Map.* For each $X \in \text{Obj}(\mathsf{Sets}_*)$ and each $A \in \text{Obj}(\mathsf{Sets})$, we have a map

$$coev_{A,X}^{\uparrow} : A \to Sets_*(A \uparrow X, X),$$

natural in $X \in \text{Obj}(\mathsf{Sets}_*)$ and $A \in \text{Obj}(\mathsf{Sets})$, and given by

$$\operatorname{coev}_{A,X}^{\uparrow}(a) \stackrel{\text{def}}{=} \llbracket [(x_b)_{b \in A}] \mapsto x_a \rrbracket$$

for each $a \in A$.

PROOF 7.2.2.1.7 ► PROOF OF PROPOSITION 7.2.2.1.6

Item 1: Functoriality

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 2: Adjointness I

This is simply a rephrasing of Definition 7.2.2.1.1.

Item 3: : Adjointness II

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 4: As a Weighted Limit

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 5: Iterated Cotensors

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 6: Commutativity With Homs

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 7: The Cotensor Evaluation Map

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

Item 8: The Cotensor Coevaluation Map

This is the special case of Limits and Colimits, ?? of ?? for $C = Sets_*$.

7.3 The Left Tensor Product of Pointed Sets

00DB 7.3.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

00DC DEFINITION 7.3.1.1.1 ► THE LEFT TENSOR PRODUCT OF POINTED SETS

The **left tensor product of pointed sets** is the functor¹

$$\triangleleft$$
: Sets, \times Sets, \rightarrow Sets,

defined as the composition

$$\mathsf{Sets}_* \times \mathsf{Sets}_* \xrightarrow{\mathsf{id} \times \overline{\bowtie}} \mathsf{Sets}_* \times \mathsf{Sets} \xrightarrow{\boldsymbol{\beta}^{\mathsf{Cats}_2}_{\mathsf{Sets}_*,\mathsf{Sets}}} \mathsf{Sets} \times \mathsf{Sets}_* \xrightarrow{\odot} \mathsf{Sets}_*,$$

where:

• \overline{a} : Sets_{*} → Sets is the forgetful functor from pointed sets to sets.

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β^{Cats₂}_{Sets_{*},Sets}: Sets_{*} × Sets → Sets × Sets_{*} is the braiding of Cats₂, i.e. the functor witnessing the isomorphism

$$\mathsf{Sets}_* \times \mathsf{Sets} \cong \mathsf{Sets} \times \mathsf{Sets}_*.$$

• ⊙: Sets × Sets_{*} → Sets_{*} is the tensor functor of Item 1 of Proposition 7.2.1.1.9.

00DD REMARK 7.3.1.1.2 ➤ UNWINDING DEFINITION 7.3.1.1.1: UNIVERSAL PROPERTY I

The left tensor product of pointed sets satisfies the following natural bijection:

$$\mathsf{Sets}_*(X \triangleleft Y, Z) \cong \mathsf{Hom}^{\otimes, \mathsf{L}}_{\mathsf{Sets}_*}(X \times Y, Z).$$

That is to say, the following data are in natural bijection:

026B 1. Pointed maps $f: X \triangleleft Y \rightarrow Z$.

026C

2. Maps of sets $f: X \times Y \to Z$ satisfying $f(x_0, y) = z_0$ for each $y \in Y$.

00DE REMARK 7.3.1.1.3 ► UNWINDING DEFINITION 7.3.1.1.1: UNIVERSAL PROPERTY II

The left tensor product of pointed sets may be described as follows:

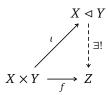
- The left tensor product of (X, x_0) and (Y, y_0) is the pair $((X \triangleleft Y, x_0 \triangleleft y_0), \iota)$ consisting of
 - A pointed set $(X \triangleleft Y, x_0 \triangleleft y_0)$;
 - A left bilinear morphism of pointed sets ι : ($X \times Y$, (x_0 , y_0)) → $X \triangleleft Y$;

satisfying the following universal property:

- (\star) Given another such pair $((Z, z_0), f)$ consisting of
 - * A pointed set (Z, z_0) ;
 - * A left bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \rightarrow X \triangleleft Y$;

¹Further Notation: Also written ⊲_{Sets}.

there exists a unique morphism of pointed sets $X \triangleleft Y \xrightarrow{\exists !} Z$ making the diagram



commute.

00DF CONSTRUCTION 7.3.1.1.4 ► THE LEFT TENSOR PRODUCT OF POINTED SETS

In detail, the **left tensor product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \triangleleft Y, [x_0])$ consisting of:

• *The Underlying Set.* The set $X \triangleleft Y$ defined by

$$X \triangleleft Y \stackrel{\text{def}}{=} |Y| \odot X$$
$$\cong \bigvee_{\gamma \in Y} (X, x_0),$$

where |Y| denotes the underlying set of (Y, y_0) .

• *The Underlying Basepoint.* The point $[(y_0, x_0)]$ of $\bigvee_{y \in Y} (X, x_0)$, which is equal to $[(y, x_0)]$ for any $y \in Y$.

PROOF 7.3.1.1.5 ► PROOF OF CONSTRUCTION 7.3.1.1.4

Since $\bigvee_{y \in Y} (X, x_0)$ is defined as the quotient of $\coprod_{y \in Y} X$ by the equivalence relation R generated by declaring $(y, x) \sim (y', x')$ if $x = x' = x_0$, we have, by Conditions on Relations, ??, a natural bijection

$$\mathsf{Sets}_*(X \triangleleft Y, Z) \cong \mathsf{Hom}^R_{\mathsf{Sets}}(\bigsqcup_{Y \in Y} X, Z),$$

where $\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z)$ is the set

$$\operatorname{Hom}_{\mathsf{Sets}}^R(\coprod_{y\in Y}X,Z)\stackrel{\mathrm{def}}{=} \left\{f\in \operatorname{Hom}_{\mathsf{Sets}}(\coprod_{y\in Y}X,Z) \middle| \begin{array}{l} \text{for each } x,y\in X, \text{ if} \\ (y,x)\sim_R (y',x'), \text{ then} \\ f(y,x)=f(y',x') \end{array} \right\}.$$

However, the condition $(y,x) \sim_R (y',x')$ only holds when:

026D 1. We have x = x' and y = y'.

026E

2. We have $x = x' = x_0$.

So, given $f \in \operatorname{Hom}_{\mathsf{Sets}}(\coprod_{y \in Y} X, Z)$ with a corresponding $\overline{f} \colon X \triangleleft Y \to Z$, the latter case above implies

$$f([(y,x_0)]) = f([(y',x_0)])$$
$$= f([(y_0,x_0)]),$$

and since $\overline{f}: X \triangleleft Y \rightarrow Z$ is a pointed map, we have

$$f([(y_0, x_0)]) = \overline{f}([(y_0, x_0)])$$

= z_0 .

Thus the elements f in $\mathrm{Hom}_{\mathsf{Sets}}^R(X\times Y,Z)$ are precisely those functions $f\colon X\times Y\to Z$ satisfying the equality

$$f(x_0, y) = z_0$$

for each $y \in Y$, giving an equality

$$\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z) = \operatorname{Hom}_{\mathsf{Sets}_*}^{\otimes, L}(X \times Y, Z)$$

of sets, which when composed with our earlier isomorphism

$$\mathsf{Sets}_*(X \triangleleft Y, Z) \cong \mathsf{Hom}^R_{\mathsf{Sets}}(X \times Y, Z),$$

gives our desired natural bijection, finishing the proof.

00DG

NOTATION 7.3.1.1.6 ► ELEMENTS OF LEFT TENSOR PRODUCTS OF POINTED SETS

We write $x \triangleleft y$ for the element [(y, x)] of

$$X \triangleleft Y \cong |Y| \odot X$$
.

¹*Further Notation:* Also written $x \triangleleft_{\mathsf{Sets}_*} y$.

00DH

REMARK 7.3.1.1.7 ► BASEPOINTS OF LEFT TENSOR PRODUCTS OF POINTED SETS

Employing the notation introduced in Notation 7.3.1.1.6, we have

$$x_0 \triangleleft y_0 = x_0 \triangleleft y$$

for each $y \in Y$, and

$$x_0 \triangleleft y = x_0 \triangleleft y'$$

for each $y, y' \in Y$.

00DJ

PROPOSITION 7.3.1.1.8 ➤ PROPERTIES OF LEFT TENSOR PRODUCTS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

00DK

1. Functoriality. The assignments $X, Y, (X, Y) \mapsto X \triangleleft Y$ define functors

$$X \triangleleft -:$$
 Sets_{*} \rightarrow Sets_{*},
 $- \triangleleft Y:$ Sets_{*} \rightarrow Sets_{*},
 $-_1 \triangleleft -_2:$ Sets_{*} \times Sets_{*} \rightarrow Sets_{*}.

In particular, given pointed maps

$$f\colon (X,x_0)\to (A,a_0),$$

$$g: (Y, y_0) \to (B, b_0),$$

the induced map

$$f \triangleleft g: X \triangleleft Y \rightarrow A \triangleleft B$$

is given by

$$[f \triangleleft g](x \triangleleft y) \stackrel{\text{def}}{=} f(x) \triangleleft g(y)$$

for each $x \triangleleft y \in X \triangleleft Y$.

00DL

2. Adjointness I. We have an adjunction

$$\left(- \triangleleft Y \dashv [Y, -]_{\mathsf{Sets}_*}^{\triangleleft}\right) : \quad \mathsf{Sets}_* \underbrace{\bot}_{[Y, -]_{\mathsf{Sets}_*}^{\triangleleft}} \mathsf{Sets}_*,$$

witnessed by a bijection of sets

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \triangleleft Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(X, [Y, Z]_{\mathsf{Sets}_*}^{\triangleleft})$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in \text{Obj}(\mathsf{Sets}_*)$, where $[X, Y]^{\triangleleft}_{\mathsf{Sets}_*}$ is the pointed set of Definition 7.3.2.1.1.

00DM

3. Adjointness II. The functor

$$X \triangleleft -: \mathsf{Sets}_* \to \mathsf{Sets}_*$$

does not admit a right adjoint.

00DN

4. Adjointness III. We have a 忘-relative adjunction

$$(X \triangleleft - \dashv \mathsf{Sets}_*(X, -)): \mathsf{Sets}_* \underbrace{\overset{X \triangleleft -}{\downarrow_{\overline{\mathbb{K}}}}} \mathsf{Sets}_*,$$

witnessed by a bijection of sets

$$\operatorname{Hom}_{\operatorname{Sets}_*}(X \triangleleft Y, Z) \cong \operatorname{Hom}_{\operatorname{Sets}}(|Y|, \operatorname{Sets}_*(X, Z))$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in Obj(Sets_*).$

PROOF 7.3.1.1.9 ► PROOF OF PROPOSITION 7.3.1.1.8

Item 1: Functoriality

This follows from the definition of \triangleleft as a composition of functors (Definition 7.3.1.1.1).

Item 2: Adjointness I

This follows from Item 3 of Proposition 7.2.1.1.9.

Item 3: Adjointness II

For $X \triangleleft -$ to admit a right adjoint would require it to preserve colimits by ??, ?? of ??. However, we have

$$X \triangleleft \operatorname{pt} \stackrel{\operatorname{def}}{=} |\operatorname{pt}| \odot X$$

 $\cong X$
 $\ncong \operatorname{pt},$

and thus we see that $X \triangleleft -$ does not have a right adjoint.

Item 4: Adjointness III

This follows from Item 2 of Proposition 7.2.1.1.9.

00DP

REMARK 7.3.1.1.10 \blacktriangleright On the Failure of $X \triangleleft -$ To Be a Left Adjoint

Here is some intuition on why $X \triangleleft -$ fails to be a left adjoint. Item 4 of Proposition 7.3.1.1.8 states that we have a natural bijection

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \triangleleft Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}}(|Y|, \mathsf{Sets}_*(X, Z)),$$

so it would be reasonable to wonder whether a natural bijection of the form

$$\operatorname{Hom}_{\operatorname{Sets}_*}(X \triangleleft Y, Z) \cong \operatorname{Hom}_{\operatorname{Sets}_*}(Y, \operatorname{\mathbf{Sets}}_*(X, Z)),$$

also holds, which would give $X \triangleleft \neg \neg \mathbf{Sets}_*(X, \neg)$. However, such a bijection would require every map

$$f: X \triangleleft Y \rightarrow Z$$

to satisfy

$$f(x \triangleleft y_0) = z_0$$

for each $x \in X$, whereas we are imposing such a basepoint preservation condition only for elements of the form $x_0 \triangleleft y$. Thus **Sets**_{*}(X, -) can't be a right adjoint for $X \triangleleft -$, and as shown by Item 3 of Proposition 7.3.1.1.8, no functor can.¹

00D0 7.3.2 The Left Internal Hom of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

¹The functor **Sets**_{*}(X, -) is instead right adjoint to X \wedge -, the smash product of pointed sets of Definition 7.5.1.1.1. See Item 2 of Proposition 7.5.1.1.12.

00DR

DEFINITION 7.3.2.1.1 ► THE LEFT INTERNAL HOM OF POINTED SETS

The **left internal Hom**¹ **of pointed sets** is the functor

$$[-,-]_{\mathsf{Sets}_*}^{\triangleleft} : \mathsf{Sets}_*^{\mathsf{op}} \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

defined as the composition

$$\mathsf{Sets}^{\mathsf{op}}_* \times \mathsf{Sets}_* \xrightarrow{\ \, \, \, \, \, \, \, \, } \mathsf{Sets}^{\mathsf{op}} \times \mathsf{Sets}_* \xrightarrow{\ \, \, \, \, \, \, \, \, \, \, } \mathsf{Sets}_*,$$

where:

- \overline{a} : Sets_{*} → Sets is the forgetful functor from pointed sets to sets.
- \pitchfork : Sets^{op} × Sets_{*} \rightarrow Sets_{*} is the cotensor functor of Item 1 of Proposition 7.2.2.1.6.

 1 For a proof that $[-,-]_{\mathsf{Sets}_*}^{\triangleleft}$ is indeed the left internal Hom of Sets $_*$ with respect to the left tensor product of pointed sets, see Item 2 of Proposition 7.3.1.1.8.

00DS

REMARK 7.3.2.1.2 ➤ UNWINDING DEFINITION 7.3.2.1.1, I: UNIVERSAL PROPERTY

The left internal Hom of pointed sets satisfies the following universal property:

$$\mathsf{Sets}_*(X \triangleleft Y, Z) \cong \mathsf{Sets}_*(X, [Y, Z]_{\mathsf{Sets}_*}^{\triangleleft})$$

That is to say, the following data are in bijection:

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- 1. Pointed maps $f: X \triangleleft Y \rightarrow Z$.
- 026G
- 2. Pointed maps $f: X \to [Y, Z]^{\triangleleft}_{\mathsf{Sets}_*}$.

00DT

REMARK 7.3.2.1.3 ► UNWINDING DEFINITION 7.3.2.1.1, II: EXPLICIT DESCRIPTION

In detail, the **left internal Hom of** (X, x_0) **and** (Y, y_0) is the pointed set $([X, Y]_{\mathsf{Sets}_*}^{\triangleleft}, [(y_0)_{x \in X}])$ consisting of:

• The Underlying Set. The set $[X,Y]_{Sets}^{\triangleleft}$ defined by

$$\begin{split} [X,Y]^{\lhd}_{\mathsf{Sets}_*} &\stackrel{\text{def}}{=} |X| \pitchfork Y \\ &\cong \bigwedge_{x \in X} (Y,y_0), \end{split}$$

where |X| denotes the underlying set of (X, x_0) .

• *The Underlying Basepoint.* The point $[(y_0)_{x \in X}]$ of $\bigwedge_{x \in X} (Y, y_0)$.

00DU PROPOSITION 7.3.2.1.4 ► PROPERTIES OF LEFT INTERNAL HOMS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. Functoriality. The assignments $X, Y, (X, Y) \mapsto [X, Y]_{\mathsf{Sets}_*}^{\triangleleft}$ define functors

$$\begin{split} [X,-]_{\mathsf{Sets}_*}^{\triangleleft} : & \mathsf{Sets}_* & \to \mathsf{Sets}_*, \\ [-,Y]_{\mathsf{Sets}_*}^{\triangleleft} : & \mathsf{Sets}_*^{\mathsf{op}} & \to \mathsf{Sets}_*, \\ [-_1,-_2]_{\mathsf{Sets}_*}^{\triangleleft} : & \mathsf{Sets}_*^{\mathsf{op}} \times \mathsf{Sets}_* & \to \mathsf{Sets}_*. \end{split}$$

In particular, given pointed maps

$$f: (X, x_0) \to (A, a_0),$$

 $g: (Y, y_0) \to (B, b_0),$

the induced map

$$[f,g]_{\mathsf{Sets}_*}^{\triangleleft} \colon [A,Y]_{\mathsf{Sets}_*}^{\triangleleft} \to [X,B]_{\mathsf{Sets}_*}^{\triangleleft}$$

is given by

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$$[f,g]_{\mathsf{Sets}_*}^{\triangleleft}([(y_a)_{a\in A}]) \stackrel{\mathrm{def}}{=} [(g(y_{f(x)}))_{x\in X}]$$

for each $[(y_a)_{a \in A}] \in [A, Y]^{\triangleleft}_{\mathsf{Sets}_*}$.

2. Adjointness I. We have an adjunction

$$\left(- \lhd Y \dashv [Y, -]_{\mathsf{Sets}_*}^{\lhd}\right) : \quad \mathsf{Sets}_* \underbrace{\bot}_{[Y, -]_{\mathsf{Sets}_*}^{\lhd}} \mathsf{Sets}_*,$$

witnessed by a bijection of sets

$$\mathsf{Hom}_{\mathsf{Sets}_*}(X \lhd Y, Z) \cong \mathsf{Hom}_{\mathsf{Sets}_*}(X, [Y, Z]^{\lhd}_{\mathsf{Sets}_*})$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in Obj(Sets_*)$

3. *Adjointness II*. The functor

$$X \triangleleft -: \mathsf{Sets}_* \to \mathsf{Sets}_*$$

does not admit a right adjoint.

Item 1: Functoriality

This follows from the definition of $[-,-]_{Sets_*}^{\triangleleft}$ as a composition of functors (Definition 7.3.2.1.1).

Item 2: Adjointness I

This is a repetition of Item 2 of Proposition 7.3.1.1.8, and is proved there.

Item 3: Adjointness II

This is a repetition of Item 3 of Proposition 7.3.1.1.8, and is proved there.

00DY 7.3.3 The Left Skew Unit

00DZ DEFINITION 7.3.3.1.1 ► THE LEFT SKEW UNIT OF <

The **left skew unit of the left tensor product of pointed sets** is the functor

$$\mathbb{1}^{\mathsf{Sets}_*, \triangleleft} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

defined by

$$\mathbb{1}_{\mathsf{Sets}_*}^{\triangleleft} \stackrel{\mathrm{def}}{=} S^0.$$

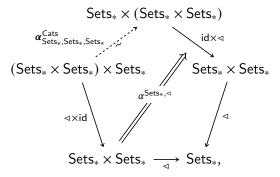
00E0 7.3.4 The Left Skew Associator

00E1 DEFINITION 7.3.4.1.1 ► THE LEFT SKEW ASSOCIATOR OF <

The **skew associator of the left tensor product of pointed sets** is the natural transformation

$$\alpha^{\mathsf{Sets}_*, \lhd} \colon \lhd \circ (\lhd \times \mathsf{id}_{\mathsf{Sets}_*}) \Longrightarrow \lhd \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \lhd) \circ \pmb{\alpha}^{\mathsf{Cats}}_{\mathsf{Sets}_*, \mathsf{Sets}_*, \mathsf{Sets}_*}$$

as in the diagram



whose component

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\lhd} \colon (X \lhd Y) \lhd Z \to X \lhd (Y \lhd Z)$$

at (X, x_0) , (Y, y_0) , $(Z, z_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by

$$(X \triangleleft Y) \triangleleft Z \stackrel{\text{def}}{=} |Z| \odot (X \triangleleft Y)$$

$$\stackrel{\text{def}}{=} |Z| \odot (|Y| \odot X)$$

$$\cong \bigvee_{z \in Z} |Y| \odot X$$

$$\cong \bigvee_{z \in Z} (\bigvee_{y \in Y} X)$$

$$\longrightarrow \bigvee_{z \in Z} X$$

$$[(z,y)] \in \bigvee_{z \in Z} Y$$

$$\cong \bigvee_{z \in Z} X$$

$$[(z,y)] \in |Z| \odot Y$$

$$\cong ||Z| \odot Y| \odot X$$

$$\stackrel{\text{def}}{=} |Y \triangleleft Z| \odot X$$

$$\stackrel{\text{def}}{=} X \triangleleft (Y \triangleleft Z),$$

where the map

$$\bigvee_{z \in Z} (\bigvee_{y \in Y} X) \to \bigvee_{(z,y) \in \bigvee_{z \in Z} Y} X$$

is given by $[(z, [(y, x)])] \mapsto [([(z, y)], x)].$

PROOF 7.3.4.1.2 ▶ PROOF OF DEFINITION 7.3.4.1.1

(Proven below in a bit.)

00E2 REMARK 7.3.4.1.3 ➤ UNWINDING DEFINITION 7.3.4.1.1

Unwinding the notation for elements, we have

$$[(z, [(y, x)])] \stackrel{\text{def}}{=} [(z, x \triangleleft y)]$$
$$\stackrel{\text{def}}{=} (x \triangleleft y) \triangleleft z$$

and

$$[([(z,y)],x)] \stackrel{\text{def}}{=} [(y \triangleleft z,x)]$$
$$\stackrel{\text{def}}{=} x \triangleleft (y \triangleleft z).$$

So, in other words, $\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \triangleleft}$ acts on elements via

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\lhd}((x \lhd y) \lhd z) \stackrel{\mathrm{def}}{=} x \lhd (y \lhd z)$$

for each $(x \triangleleft y) \triangleleft z \in (X \triangleleft Y) \triangleleft Z$.

00E3 REMARK 7.3.4.1.4 ► Non-Invertibility of the Skew Associator of <

Taking $y = y_0$, we see that the morphism $\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \triangleleft}$ acts on elements as

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \lhd}((x \lhd y_0) \lhd z) \stackrel{\text{def}}{=} x \lhd (y_0 \lhd z).$$

However, by the definition of \triangleleft , we have $y_0 \triangleleft z = y_0 \triangleleft z'$ for all $z, z' \in Z$, preventing $\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \triangleleft}$ from being non-invertible.

PROOF 7.3.4.1.5 ► PROOF OF DEFINITION 7.3.4.1.1

Firstly, note that, given (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$, the map

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\lhd} \colon (X \lhd Y) \lhd Z \to X \lhd (Y \lhd Z)$$

is indeed a morphism of pointed sets, as we have

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \lhd}((x_0 \lhd y_0) \lhd z_0) = x_0 \lhd (y_0 \lhd z_0).$$

Next, we claim that $\alpha^{Sets_*, \triangleleft}$ is a natural transformation. We need to show that, given morphisms of pointed sets

$$f\colon (X,x_0)\to (X',x_0'),$$

$$g: (Y, y_0) \to (Y', y_0'),$$

$$h: (Z, z_0) \to (Z', z'_0)$$

the diagram

commutes. Indeed, this diagram acts on elements as

$$(x \triangleleft y) \triangleleft z \longmapsto (f(x) \triangleleft g(y)) \triangleleft h(z)$$

$$\downarrow \qquad \qquad \downarrow$$

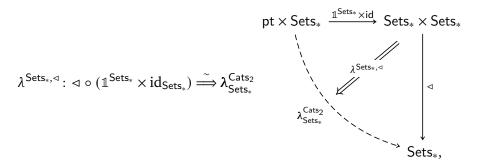
$$x \triangleleft (y \triangleleft z) \longmapsto f(x) \triangleleft (g(y) \triangleleft h(z))$$

and hence indeed commutes, showing $\alpha^{\mathsf{Sets}_*, \triangleleft}$ to be a natural transformation. This finishes the proof.

00E4 7.3.5 The Left Skew Left Unitor

00E5 DEFINITION 7.3.5.1.1 ➤ THE LEFT SKEW LEFT UNITOR OF <

The **skew left unitor of the left tensor product of pointed sets** is the natural transformation



whose component

$$\lambda_X^{\mathsf{Sets}_*, \triangleleft} \colon S^0 \triangleleft X \to X$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by the composition

$$S^{0} \triangleleft X \cong |X| \odot S^{0}$$
$$\cong \bigvee_{x \in X} S^{0}$$
$$\rightarrow X,$$

where $\bigvee_{x \in X} S^0 \to X$ is the map given by

$$[(x,0)] \mapsto x_0,$$
$$[(x,1)] \mapsto x$$

for each $x \in X$.

PROOF 7.3.5.1.2 ► PROOF OF DEFINITION 7.3.5.1.1

(Proven below in a bit.)

00E6 REMARK 7.3.5.1.3 ➤ UNWINDING DEFINITION 7.3.5.1.1

In other words, $\lambda_X^{\mathsf{Sets}_*, \triangleleft}$ acts on elements as

$$\lambda_X^{\mathsf{Sets}_*, \triangleleft}(0 \triangleleft x) \stackrel{\text{def}}{=} x_0,$$
$$\lambda_X^{\mathsf{Sets}_*, \triangleleft}(1 \triangleleft x) \stackrel{\text{def}}{=} x$$

for each $1 \triangleleft x \in S^0 \triangleleft X$.

00E7

The morphism $\lambda_X^{\mathsf{Sets}_*, \lhd}$ is almost invertible, with its would-be-inverse

$$\phi_X \colon X \to S^0 \lhd X$$

given by

$$\phi_X(x) \stackrel{\text{def}}{=} 1 \triangleleft x$$

for each $x \in X$. Indeed, we have

$$\begin{split} [\lambda_X^{\mathsf{Sets}_*, \lhd} \circ \phi](x) &= \lambda_X^{\mathsf{Sets}_*, \lhd}(\phi(x)) \\ &= \lambda_X^{\mathsf{Sets}_*, \lhd}(1 \lhd x) \\ &= x \\ &= [\mathrm{id}_X](x) \end{split}$$

so that

$$\lambda_X^{\mathsf{Sets}_*, \lhd} \circ \phi = \mathrm{id}_X$$

and

$$\begin{split} [\phi \circ \lambda_X^{\mathsf{Sets}_*, \triangleleft}](1 \triangleleft x) &= \phi(\lambda_X^{\mathsf{Sets}_*, \triangleleft}(1 \triangleleft x)) \\ &= \phi(x) \\ &= 1 \triangleleft x \\ &= [\mathrm{id}_{S^0 \triangleleft X}](1 \triangleleft x), \end{split}$$

but

$$\begin{aligned} [\phi \circ \lambda_X^{\mathsf{Sets}_*, \lhd}](0 \lhd x) &= \phi(\lambda_X^{\mathsf{Sets}_*, \lhd}(0 \lhd x)) \\ &= \phi(x_0) \\ &= 1 \lhd x_0, \end{aligned}$$

where $0 \triangleleft x \neq 1 \triangleleft x_0$. Thus

$$\phi \circ \lambda_X^{\mathsf{Sets}_*, \lhd} \stackrel{?}{=} \mathrm{id}_{S^0 \lhd X}$$

holds for all elements in $S^0 \triangleleft X$ except one.

PROOF 7.3.5.1.5 ► PROOF OF DEFINITION 7.3.5.1.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$, the map

$$\lambda_X^{\mathsf{Sets}_*, \triangleleft} \colon S^0 \triangleleft X \to X$$

is indeed a morphism of pointed sets, as we have

$$\lambda_X^{\mathsf{Sets}_*,\triangleleft}(0 \triangleleft x_0) = x_0.$$

Next, we claim that $\lambda^{\mathsf{Sets}_*, \triangleleft}$ is a natural transformation. We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

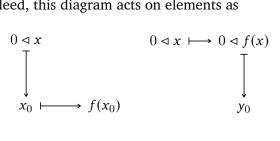
the diagram

$$S^{0} \triangleleft X \xrightarrow{\mathrm{id}_{S^{0}} \triangleleft f} S^{0} \triangleleft Y$$

$$\lambda_{X}^{\mathsf{Sets}_{*}, \triangleleft} \downarrow \qquad \qquad \downarrow \lambda_{Y}^{\mathsf{Sets}_{*}, \triangleleft}$$

$$X \xrightarrow{f} Y$$

commutes. Indeed, this diagram acts on elements as



and

$$\begin{array}{ccc}
1 \triangleleft x & \longmapsto & 1 \triangleleft f(x) \\
\downarrow & & \downarrow \\
x & \longmapsto & f(x)
\end{array}$$

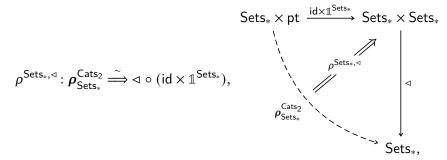
and hence indeed commutes, showing $\lambda^{\mathsf{Sets}_*, \triangleleft}$ to be a natural transformation. This finishes the proof.

00E8 7.3.6 The Left Skew Right Unitor

00E9 DEFI

DEFINITION 7.3.6.1.1 ► THE LEFT SKEW RIGHT UNITOR OF <

The **skew right unitor of the left tensor product of pointed sets** is the natural transformation



whose component

$$\rho_X^{\mathsf{Sets}_*, \lhd} \colon X \to X \lhd S^0$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by the composition

$$X \to X \lor X$$
$$\cong |S^0| \odot X$$
$$\cong X \lhd S^0,$$

where $X \to X \vee X$ is the map sending X to the second factor of X in $X \vee X$.

PROOF 7.3.6.1.2 ► PROOF OF DEFINITION 7.3.6.1.1

(Proven below in a bit.)

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REMARK 7.3.6.1.3 ► UNWINDING DEFINITION 7.3.6.1.1

In other words, $\rho_X^{\mathsf{Sets}_*, \lhd}$ acts on elements as

$$\rho_X^{\mathsf{Sets}_*, \triangleleft}(x) \stackrel{\mathrm{def}}{=} [(1, x)]$$

i.e. by

$$\rho_X^{\mathsf{Sets}_*, \triangleleft}(x) \stackrel{\mathrm{def}}{=} x \triangleleft 1$$

for each $x \in X$.

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REMARK 7.3.6.1.4 ► Non-Invertibility of the Skew Right Unitor of <

The morphism $\rho_X^{\mathsf{Sets}_*, \lhd}$ is non-invertible, as it is non-surjective when viewed as a map of sets, since the elements $x \lhd 0$ of $X \lhd S^0$ with $x \ne x_0$ are outside the image of $\rho_X^{\mathsf{Sets}_*, \lhd}$, which sends x to $x \lhd 1$.

PROOF 7.3.6.1.5 ▶ PROOF OF DEFINITION 7.3.6.1.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$, the map

$$\rho_X^{\mathsf{Sets}_*, \triangleleft} \colon X \to X \triangleleft S^0$$

is indeed a morphism of pointed sets as we have

$$\rho_X^{\mathsf{Sets}_*, \triangleleft}(x_0) = x_0 \triangleleft 1$$
$$= x_0 \triangleleft 0$$

Next, we claim that $\rho^{\mathsf{Sets}_*, \triangleleft}$ is a natural transformation. We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \to (Y, y_0),$$

the diagram

$$\begin{array}{c|c} X & \xrightarrow{f} & Y \\ \rho_X^{\mathsf{Sets}_*, \triangleleft} & & & \Big| \rho_Y^{\mathsf{Sets}_*, \triangleleft} \\ X \lhd S^0 & \xrightarrow{f \lhd \mathrm{id}_{S^0}} & Y \lhd S^0 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
x & \longmapsto & f(x) \\
\downarrow & & \downarrow \\
x < 0 & \longmapsto & f(x) < 0
\end{array}$$

and hence indeed commutes, showing $\rho^{\mathsf{Sets}_*, \triangleleft}$ to be a natural transformation. This finishes the proof.

00EC 7.3.7 The Diagonal

00ED DEFINITION 7.3.7.1.1 ► THE DIAGONAL OF <

The **diagonal of the left tensor product of pointed sets** is the natural transformation

$$\Delta^{\triangleleft} \colon \operatorname{id}_{\mathsf{Sets}_*} \Longrightarrow \triangleleft \circ \Delta^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}, \qquad \underbrace{\Delta^{\triangleleft}_{\mathsf{Sets}_*}}^{\operatorname{id}_{\mathsf{Sets}_*}} \to \mathsf{Sets}_*$$

$$\mathsf{Sets}_* \times \mathsf{Sets}_*,$$

$$\mathsf{Sets}_* \times \mathsf{Sets}_*,$$

whose component

$$\Delta_X^{\triangleleft} \colon (X, x_0) \to (X \triangleleft X, x_0 \triangleleft x_0)$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by

$$\Delta_X^{\triangleleft}(x) \stackrel{\mathrm{def}}{=} x \triangleleft x$$

for each $x \in X$.

PROOF 7.3.7.1.2 ► PROOF OF DEFINITION 7.3.7.1.1

Being a Morphism of Pointed Sets

We have

$$\Delta_X^{\triangleleft}(x_0) \stackrel{\mathrm{def}}{=} x_0 \triangleleft x_0,$$

and thus Δ_X^{\lhd} is a morphism of pointed sets.

Naturality

We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

00EF

$$X \xrightarrow{f} Y$$

$$\downarrow^{\Delta_X^{\triangleleft}} \qquad \qquad \downarrow^{\Delta_Y^{\triangleleft}}$$

$$X \triangleleft X \xrightarrow{f \triangleleft f} Y \triangleleft Y$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
x & \longmapsto & f(x) \\
\downarrow & & \downarrow \\
x \triangleleft x & \longmapsto & f(x) \triangleleft f(x)
\end{array}$$

and hence indeed commutes, showing Δ^{\triangleleft} to be natural.

00EE 7.3.8 The Left Skew Monoidal Structure on Pointed Sets Associated to ⊲

Proposition 7.3.8.1.1 \blacktriangleright The Left Skew Monoidal Structure on Pointed Sets Associated to \lhd

The category Sets_{*} admits a left-closed left skew monoidal category structure consisting of:

- The Underlying Category. The category Sets* of pointed sets.
- The Left Skew Monoidal Product. The left tensor product functor

$$\triangleleft$$
: Sets_{*} × Sets_{*} \rightarrow Sets_{*}

of Definition 7.3.1.1.1.

• The Left Internal Skew Hom. The left internal Hom functor

$$[-,-]_{\mathsf{Sets}}^{\lhd} : \mathsf{Sets}_{*}^{\mathsf{op}} \times \mathsf{Sets}_{*} \to \mathsf{Sets}_{*}$$

of Definition 7.3.2.1.1.

• The Left Skew Monoidal Unit. The functor

$$\mathbb{1}^{\mathsf{Sets}_*, \triangleleft} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

of Definition 7.3.3.1.1.

• The Left Skew Associators. The natural transformation

$$\alpha^{\mathsf{Sets}_*, \triangleleft} : \triangleleft \circ (\triangleleft \times \mathsf{id}_{\mathsf{Sets}_*}) \Longrightarrow \triangleleft \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \triangleleft) \circ \alpha^{\mathsf{Cats}}_{\mathsf{Sets}_*, \mathsf{Sets}_*, \mathsf{Sets}_*}$$
 of Definition 7.3.4.1.1.

• The Left Skew Left Unitors. The natural transformation

$$\lambda^{\mathsf{Sets}_*, \triangleleft} \colon \triangleleft \circ (\mathbb{1}^{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*}) \stackrel{\widetilde{\longrightarrow}}{\Longrightarrow} \lambda^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}$$

of Definition 7.3.5.1.1.

• The Left Skew Right Unitors. The natural transformation

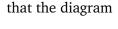
$$\rho^{\mathsf{Sets}_*, \triangleleft} \colon \rho_{\mathsf{Sets}_*}^{\mathsf{Cats}_2} \stackrel{\widetilde{-}}{\Longrightarrow} \triangleleft \circ (\mathsf{id} \times \mathbb{1}^{\mathsf{Sets}_*})$$

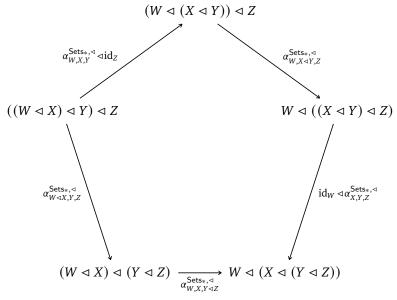
of Definition 7.3.6.1.1.

PROOF 7.3.8.1.2 ► PROOF OF PROPOSITION 7.3.8.1.1

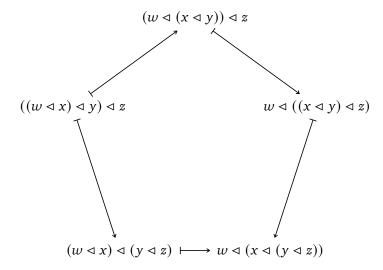
The Pentagon Identity

Let (W, w_0) , (X, x_0) , (Y, y_0) and (Z, z_0) be pointed sets. We have to show





commutes. Indeed, this diagram acts on elements as



and thus we see that the pentagon identity is satisfied.

The Left Skew Left Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$(S^0 \triangleleft X) \triangleleft Y \xrightarrow{\alpha_{S^0, X, Y}^{\mathsf{Sets}_*, \triangleleft}} S^0 \triangleleft (X \triangleleft Y)$$

$$\lambda_X^{\mathsf{Sets}_*, \triangleleft} \triangleleft \mathrm{id}_Y \qquad \lambda_X^{\mathsf{Sets}_*, \triangleleft}$$

$$X \triangleleft Y$$

commutes. Indeed, this diagram acts on elements as

$$(0 \triangleleft x) \triangleleft y \longmapsto 0 \triangleleft (x \triangleleft y)$$

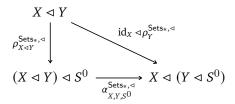
$$\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \qquad \qquad \downarrow \qquad \qquad$$

and

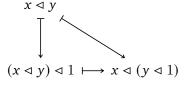
and hence indeed commutes. Thus the left skew triangle identity is satisfied.

The Left Skew Right Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram



commutes. Indeed, this diagram acts on elements as



and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Left Skew Middle Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$X \triangleleft Y = X \triangleleft Y$$

$$\rho_X^{\mathsf{Sets}_*, \triangleleft} \triangleleft \mathrm{id}_Y \downarrow \qquad \qquad \qquad \uparrow \mathrm{id}_A \triangleleft \lambda_Y^{\mathsf{Sets}_*, \triangleleft}$$

$$(X \triangleleft S^0) \triangleleft Y \xrightarrow[\alpha_{X, S^0, Y}]{} X \triangleleft (S^0 \triangleleft Y)$$

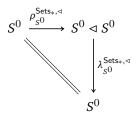
commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
x \triangleleft y & \longmapsto & x \triangleleft y \\
\downarrow & & \downarrow \\
(x \triangleleft 1) \triangleleft y & \longmapsto & x \triangleleft (1 \triangleleft y)
\end{array}$$

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Zig-Zag Identity

We have to show that the diagram



commutes. Indeed, this diagram acts on elements as



and

$$1 \mapsto 1 \triangleleft$$

$$\downarrow$$

$$\downarrow$$

$$\downarrow$$

$$\downarrow$$

and hence indeed commutes. Thus the zig-zag identity is satisfied.

Left Skew Monoidal Left-Closedness

This follows from Item 2 of Proposition 7.3.1.1.8.

OOEG 7.3.9 Monoids With Respect to the Left Tensor Product of Pointed Sets

00EH PROPOSITION 7.3.9.1.1 ► MONOIDS WITH RESPECT TO <

The category of monoids on $(\mathsf{Sets}_*, \lhd, S^0)$ is isomorphic to the category of "monoids with left zero" and morphisms between them.

 1 A monoid with left zero is defined similarly as the monoids with zero of **??**. Succinctly, they are monoids (A, μ_A, η_A) with a special element 0_A satisfying

$$0_A a = 0_A$$

for each $a \in A$.

PROOF 7.3.9.1.2 ▶ PROOF OF PROPOSITION 7.3.9.1.1

Monoids on (Sets_{*}, \triangleleft , S^0)

A monoid on (Sets_{*}, \triangleleft , S^0) consists of:

- *The Underlying Object.* A pointed set $(A, 0_A)$.
- The Multiplication Morphism. A morphism of pointed sets

$$\mu_A: A \triangleleft A \rightarrow A$$
,

determining a left bilinear morphism of pointed sets

$$A \times A \longrightarrow A$$

$$(a,b) \longmapsto ab.$$

• The Unit Morphism. A morphism of pointed sets

$$\eta_A \colon S^0 \to A$$

picking an element 1_A of A.

satisfying the following conditions:

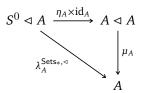
1. Associativity. The diagram

026H

026J

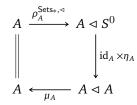
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2. Left Unitality. The diagram



commutes.

3. Right Unitality. The diagram



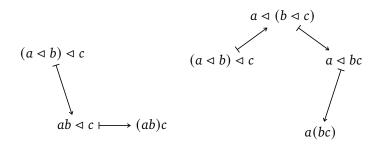
commutes.

Being a left-bilinear morphism of pointed sets, the multiplication map satisfies

$$0_A a = 0_A$$

for each $a \in A$. Now, the associativity, left unitality, and right unitality conditions act on elements as follows:

1. Associativity. The associativity condition acts as



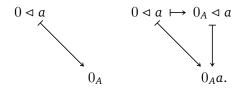
This gives

$$(ab)c = a(bc)$$

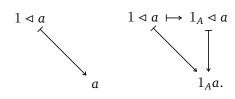
for each $a, b, c \in A$.

2. Left Unitality. The left unitality condition acts:

(a) On $0 \triangleleft a$ as



026P (b) On 1 \triangleleft a as



026L

026M

026N

This gives

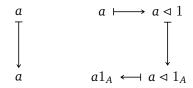
$$1_A a = a,$$
$$0_A a = 0_A$$

for each $a \in A$.

026Q

026R

3. Right Unitality. The right unitality condition acts as



This gives

$$a1_A = a$$

for each $a \in A$.

Thus we see that monoids with respect to \triangleleft are exactly monoids with left zero.

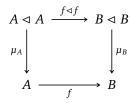
Morphisms of Monoids on (Sets_{*}, \triangleleft , S^0)

A morphism of monoids on (Sets_{*}, \triangleleft , S^0) from $(A, \mu_A, \eta_A, 0_A)$ to $(B, \mu_B, \eta_B, 0_B)$ is a morphism of pointed sets

$$f: (A, 0_A) \rightarrow (B, 0_B)$$

satisfying the following conditions:

1. Compatibility With the Multiplication Morphisms. The diagram



commutes.

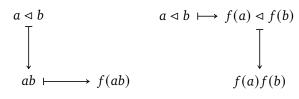
026S

2. Compatibility With the Unit Morphisms. The diagram

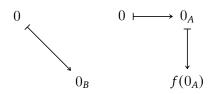


commutes.

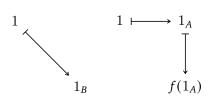
These act on elements as



and



and



giving

$$f(ab) = f(a)f(b),$$

$$f(0_A) = 0_B,$$

$$f(1_A) = 1_B,$$

for each $a, b \in A$, which is exactly a morphism of monoids with left zero.

Identities and Composition

Similarly, the identities and composition of $\mathsf{Mon}(\mathsf{Sets}_*, \lhd, S^0)$ can be easily seen to agree with those of monoids with left zero, which finishes the proof.

7.4 The Right Tensor Product of Pointed Sets

00EK 7.4.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

00EL

DEFINITION 7.4.1.1.1 ► THE RIGHT TENSOR PRODUCT OF POINTED SETS

The **right tensor product of pointed sets** is the functor¹

$$\triangleright$$
: Sets_{*} × Sets_{*} \rightarrow Sets_{*}

defined as the composition

$$\mathsf{Sets}_* \times \mathsf{Sets}_* \xrightarrow{\overline{\bowtie} \times \mathsf{id}} \mathsf{Sets} \times \mathsf{Sets}_* \xrightarrow{\circ} \mathsf{Sets}_*,$$

where:

- \overline{a} : Sets* \rightarrow Sets is the forgetful functor from pointed sets to sets.
- ⊙: Sets × Sets_{*} → Sets_{*} is the tensor functor of Item 1 of Proposition 7.2.1.1.9.

00EM

REMARK 7.4.1.1.2 ► UNWINDING DEFINITION 7.4.1.1.1: UNIVERSAL PROPERTY I

The right tensor product of pointed sets satisfies the following natural bijection:

$$\mathsf{Sets}_*(X \rhd Y, Z) \cong \mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{R}}(X \times Y, Z).$$

That is to say, the following data are in natural bijection:

- 026T
- 1. Pointed maps $f: X \triangleright Y \rightarrow Z$.
- 026U
- 2. Maps of sets $f: X \times Y \to Z$ satisfying $f(x, y_0) = z_0$ for each $x \in X$.

00EN

REMARK 7.4.1.1.3 ► UNWINDING DEFINITION 7.4.1.1.1: UNIVERSAL PROPERTY II

The right tensor product of pointed sets may be described as follows:

- The right tensor product of (X, x_0) and (Y, y_0) is the pair $((X \triangleright Y, x_0 \triangleright y_0), \iota)$ consisting of
 - A pointed set $(X \triangleright Y, x_0 \triangleright y_0)$;

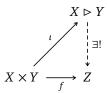
¹Further Notation: Also written ⊳_{Sets*}.

- A right bilinear morphism of pointed sets ι : ($X \times Y$, (x_0, y_0)) → $X \triangleright Y$;

satisfying the following universal property:

- (\star) Given another such pair $((Z, z_0), f)$ consisting of
 - * A pointed set (Z, z_0) ;
 - * A right bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \to X \triangleright Y;$

there exists a unique morphism of pointed sets $X \triangleright Y \xrightarrow{\exists !} Z$ making the diagram



commute.

00EP

CONSTRUCTION 7.4.1.1.4 ► THE RIGHT TENSOR PRODUCT OF POINTED SETS

In detail, the **right tensor product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \triangleright Y, [y_0])$ consisting of:

• *The Underlying Set.* The set $X \triangleright Y$ defined by

$$\begin{split} X \rhd Y &\stackrel{\mathrm{def}}{=} |X| \odot Y \\ &\cong \bigvee_{x \in X} (Y, y_0), \end{split}$$

where |X| denotes the underlying set of (X, x_0) .

• *The Underlying Basepoint.* The point $[(x_0, y_0)]$ of $\bigvee_{x \in X} (Y, y_0)$, which is equal to $[(x, y_0)]$ for any $x \in X$.

PROOF 7.4.1.1.5 ► PROOF OF CONSTRUCTION 7.4.1.1.4

Since $\bigvee_{y \in Y} (X, x_0)$ is defined as the quotient of $\coprod_{x \in X} Y$ by the equivalence relation R generated by declaring $(x, y) \sim (x', y')$ if $y = y' = y_0$, we have, by Conditions on Relations, ??, a natural bijection

$$\mathsf{Sets}_*(X \rhd Y, Z) \cong \mathsf{Hom}^R_{\mathsf{Sets}}(\coprod_{X \in X} Y, Z),$$

where $\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z)$ is the set

$$\operatorname{Hom}_{\mathsf{Sets}}^R(\coprod_{x\in X}Y,Z)\stackrel{\mathrm{def}}{=} \left\{ f\in \operatorname{Hom}_{\mathsf{Sets}}(\coprod_{x\in X}Y,Z) \middle| \begin{array}{l} \text{for each } x,y\in X, \text{ if} \\ (x,y)\sim_R(x',y'), \text{ then} \\ f(x,y)=f(x',y') \end{array} \right\}.$$

However, the condition $(x, y) \sim_R (x', y')$ only holds when:

- 1. We have x = x' and y = y'.
- 2. We have $y = y' = y_0$.

026V

026W

So, given $f \in \operatorname{Hom}_{\mathsf{Sets}}(\coprod_{X \in X} Y, Z)$ with a corresponding $\overline{f} \colon X \rhd Y \to Z$, the latter case above implies

$$f([(x, y_0)]) = f([(x', y_0)])$$

= $f([(x_0, y_0)]),$

and since $\bar{f}: X \triangleright Y \rightarrow Z$ is a pointed map, we have

$$f([(x_0, y_0)]) = \overline{f}([(x_0, y_0)])$$

= z_0 .

Thus the elements f in $\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z)$ are precisely those functions $f: X \times Y \to Z$ satisfying the equality

$$f(x, y_0) = z_0$$

for each $y \in Y$, giving an equality

$$\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z) = \operatorname{Hom}_{\mathsf{Sets}_*}^{\otimes, R}(X \times Y, Z)$$

of sets, which when composed with our earlier isomorphism

$$\mathsf{Sets}_*(X \rhd Y, Z) \cong \mathsf{Hom}^R_{\mathsf{Sets}}(X \times Y, Z),$$

gives our desired natural bijection, finishing the proof.

59

00EQ

NOTATION 7.4.1.1.6 ► ELEMENTS OF RIGHT TENSOR PRODUCTS OF POINTED SETS

We write x > y for the element (x, y) of

$$X \triangleright Y \cong |X| \odot Y$$
.

¹Further Notation: Also written $x \triangleright_{\mathsf{Sets}_*} y$.

00ER

REMARK 7.4.1.1.7 ► BASEPOINTS OF RIGHT TENSOR PRODUCTS OF POINTED SETS

Employing the notation introduced in Notation 7.4.1.1.6, we have

$$x_0 \triangleright y_0 = x \triangleright y_0$$

for each $x \in X$, and

$$x \triangleright y_0 = x' \triangleright y_0$$

for each $x, x' \in X$.

00ES

PROPOSITION 7.4.1.1.8 ➤ PROPERTIES OF RIGHT TENSOR PRODUCTS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

00ET

1. Functoriality. The assignments $X, Y, (X, Y) \mapsto X \triangleright Y$ define functors

$$X
ightharpoonup -:$$
 Sets_{*} \rightarrow Sets_{*},
 $-
ightharpoonup Y:$ Sets_{*} \rightarrow Sets_{*},
 $-_1
ightharpoonup -_2:$ Sets_{*} \times Sets_{*} \rightarrow Sets_{*}.

In particular, given pointed maps

$$f\colon (X,x_0)\to (A,a_0),$$

$$g: (Y, y_0) \to (B, b_0),$$

the induced map

$$f \rhd g : X \rhd Y \to A \rhd B$$

is given by

$$[f \triangleright g](x \triangleright y) \stackrel{\text{def}}{=} f(x) \triangleright g(y)$$

for each $x \triangleright y \in X \triangleright Y$.

00EU

2. Adjointness I. We have an adjunction

$$(X \rhd - \dashv [X, -]_{\mathsf{Sets}_*}^{\rhd}) : \mathsf{Sets}_* \underbrace{\overset{X \rhd -}{\bot}}_{[X, -]_{\mathsf{Sets}_*}^{\varsigma}} \mathsf{Sets}_*,$$

witnessed by a bijection of sets

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \triangleright Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(Y, [X, Z]^{\triangleright}_{\mathsf{Sets}_*})$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in \text{Obj}(\mathsf{Sets}_*)$, where $[X, Y]^{\triangleright}_{\mathsf{Sets}_*}$ is the pointed set of Definition 7.4.2.1.1.

00EV

3. Adjointness II. The functor

$$- \triangleright Y : \mathsf{Sets}_* \to \mathsf{Sets}_*$$

does not admit a right adjoint.

00EW

4. Adjointness III. We have a 忘-relative adjunction

$$(- \triangleright Y \dashv \mathsf{Sets}_*(Y, -)): \mathsf{Sets}_* \underbrace{\downarrow_{\Xi}}_{\mathsf{Sets}_*(Y, -)} \mathsf{Sets}_*,$$

witnessed by a bijection of sets

$$\operatorname{Hom}_{\operatorname{Sets}_*}(X \triangleright Y, Z) \cong \operatorname{Hom}_{\operatorname{Sets}}(|X|, \operatorname{Sets}_*(Y, Z))$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in Obj(Sets_*).$

PROOF 7.4.1.1.9 ► PROOF OF PROPOSITION 7.4.1.1.8

Item 1: Functoriality

This follows from the definition of \triangleright as a composition of functors (Definition 7.4.1.1.1).

Item 2: Adjointness I

This follows from Item 3 of Proposition 7.2.1.1.9.

Item 3: Adjointness II

For $- \triangleright Y$ to admit a right adjoint would require it to preserve colimits by ??, ?? of ??. However, we have

$$pt \rhd X \stackrel{\text{def}}{=} |pt| \odot X$$

$$\cong X$$

$$\ncong pt,$$

and thus we see that $- \triangleright Y$ does not have a right adjoint.

Item 4: Adjointness III

This follows from Item 2 of Proposition 7.2.1.1.9.

00EX REMARK 7.4.1.1.10 ► ON THE FAILURE OF -> Y TO BE A LEFT ADJOINT

Here is some intuition on why $- \triangleright Y$ fails to be a left adjoint. Item 4 of Proposition 7.3.1.1.8 states that we have a natural bijection

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \triangleright Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}}(|X|, \mathsf{Sets}_*(Y, Z)),$$

so it would be reasonable to wonder whether a natural bijection of the form

$$\operatorname{Hom}_{\operatorname{Sets}_*}(X \triangleright Y, Z) \cong \operatorname{Hom}_{\operatorname{Sets}_*}(X, \operatorname{\mathbf{Sets}}_*(Y, Z)),$$

also holds, which would give $- \triangleright Y \dashv \mathbf{Sets}_*(Y, -)$. However, such a bijection would require every map

$$f: X \triangleright Y \rightarrow Z$$

to satisfy

$$f(x_0 \triangleright y) = z_0$$

for each $x \in X$, whereas we are imposing such a basepoint preservation condition only for elements of the form $x \triangleright y_0$. Thus **Sets**_{*}(Y, -) can't be a right adjoint for $-\triangleright Y$, and as shown by Item 3 of Proposition 7.4.1.1.8, no functor can.¹

OOEY 7.4.2 The Right Internal Hom of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

¹The functor **Sets**_{*}(Y, -) is instead right adjoint to $- \land Y$, the smash product of pointed sets of Definition 7.5.1.1.1. See Item 2 of Proposition 7.5.1.1.12.

00EZ

DEFINITION 7.4.2.1.1 ► THE RIGHT INTERNAL HOM OF POINTED SETS

The **right internal Hom**¹ **of pointed sets** is the functor

$$[-,-]_{\mathsf{Sets}}^{\triangleright} : \mathsf{Sets}_{*}^{\mathsf{op}} \times \mathsf{Sets}_{*} \to \mathsf{Sets}_{*}$$

defined as the composition

$$\mathsf{Sets}^{\mathsf{op}}_* \times \mathsf{Sets}_* \xrightarrow{\overline{\Sigma} \times \mathsf{id}} \mathsf{Sets}^{\mathsf{op}} \times \mathsf{Sets}_* \xrightarrow{\mathsf{h}} \mathsf{Sets}_*,$$

where:

- \overline{a} : Sets_{*} → Sets is the forgetful functor from pointed sets to sets.
- \pitchfork : Sets^{op} × Sets_{*} \rightarrow Sets_{*} is the cotensor functor of Item 1 of Proposition 7.2.2.1.6.

 1 For a proof that $[-,-]^{\triangleright}_{\mathsf{Sets}_*}$ is indeed the right internal Hom of Sets_* with respect to the right tensor product of pointed sets, see Item 2 of Proposition 7.4.1.1.8.

00F0

REMARK 7.4.2.1.2 \blacktriangleright Unwinding Definition 7.4.2.1.1, I: Comparison With $[-,-]_{S_{etc}}^{\triangleleft}$

We have

$$[-,-]_{\mathsf{Sets}_*}^{\triangleleft} = [-,-]_{\mathsf{Sets}_*}^{\triangleright}.$$

00F1

REMARK 7.4.2.1.3 ► UNWINDING DEFINITION 7.4.2.1.1, II: UNIVERSAL PROPERTY

The right internal Hom of pointed sets satisfies the following universal property:

$$\mathsf{Sets}_*(X \rhd Y, Z) \cong \mathsf{Sets}_*(Y, [X, Z]^{\triangleright}_{\mathsf{Sets}_*})$$

That is to say, the following data are in bijection:

- 026X
- 1. Pointed maps $f: X \triangleright Y \rightarrow Z$.
- 026Y
- 2. Pointed maps $f: Y \to [X, Z]^{\triangleright}_{\mathsf{Sets}_*}$.

00F2

REMARK 7.4.2.1.4 ► UNWINDING DEFINITION 7.4.2.1.1, III: EXPLICIT DESCRIPTION

In detail, the **right internal Hom of** (X, x_0) **and** (Y, y_0) is the pointed set $([X, Y]_{Sets_*}^{\triangleright}, [(y_0)_{x \in X}])$ consisting of:

• The Underlying Set. The set $[X,Y]^{\triangleright}_{Sets_*}$ defined by

$$[X,Y]^{\triangleright}_{\mathsf{Sets}_*} \stackrel{\text{def}}{=} |X| \pitchfork Y$$

$$\cong \bigwedge_{Y \in X} (Y, y_0),$$

where |X| denotes the underlying set of (X, x_0) .

• The Underlying Basepoint. The point $[(y_0)_{x \in X}]$ of $\bigwedge_{x \in X} (Y, y_0)$.

PROPOSITION 7.4.2.1.5 ➤ PROPERTIES OF RIGHT INTERNAL HOMS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

00F4 1. Functoriality. The assignments $X, Y, (X, Y) \mapsto [X, Y]_{\mathsf{Sets}_*}^{\triangleright}$ define functors

$$\begin{split} [X,-]^{\triangleright}_{\mathsf{Sets}_*} \colon & \mathsf{Sets}_* & \to \mathsf{Sets}_*, \\ [-,Y]^{\triangleright}_{\mathsf{Sets}_*} \colon & \mathsf{Sets}^{\mathsf{op}}_* & \to \mathsf{Sets}_*, \\ [-_1,-_2]^{\triangleright}_{\mathsf{Sets}_*} \colon & \mathsf{Sets}^{\mathsf{op}}_* \times \mathsf{Sets}_* & \to \mathsf{Sets}_*. \end{split}$$

In particular, given pointed maps

$$f: (X, x_0) \to (A, a_0),$$

 $g: (Y, y_0) \to (B, b_0),$

the induced map

$$[f,g]^{\triangleright}_{\mathsf{Sets}_*} \colon [A,Y]^{\triangleright}_{\mathsf{Sets}_*} \to [X,B]^{\triangleright}_{\mathsf{Sets}_*}$$

is given by

00F5

$$[f,g]_{\mathsf{Sets}_*}^{\triangleright}([(y_a)_{a\in A}]) \stackrel{\text{def}}{=} [(g(y_{f(x)}))_{x\in X}]$$

for each $[(y_a)_{a \in A}] \in [A, Y]^{\triangleright}_{\mathsf{Sets}_*}$.

2. Adjointness I. We have an adjunction

$$(X \rhd - \dashv [X, -]_{\mathsf{Sets}_*}^{\triangleright}): \mathsf{Sets}_* \underbrace{\bot}_{[X, -]_{\mathsf{Sets}_*}^{\triangleright}} \mathsf{Sets}_*,$$

witnessed by a bijection of sets

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \triangleright Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(Y, [X, Z]^{\triangleright}_{\mathsf{Sets}_*})$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in \text{Obj}(\mathsf{Sets}_*)$, where $[X, Y]^{\triangleright}_{\mathsf{Sets}_*}$ is the pointed set of Definition 7.4.2.1.1.

00F6

3. Adjointness II. The functor

$$- \triangleright Y : \mathsf{Sets}_* \to \mathsf{Sets}_*$$

does not admit a right adjoint.

PROOF 7.4.2.1.6 ► PROOF OF PROPOSITION 7.4.2.1.5

Item 1: Functoriality

This follows from the definition of $[-,-]_{\mathsf{Sets}_*}^{\triangleright}$ as a composition of functors (Definition 7.4.2.1.1).

Item 2: Adjointness I

This is a repetition of Item 2 of Proposition 7.4.1.1.8, and is proved there.

Item 3: Adjointness II

This is a repetition of Item 3 of Proposition 7.4.1.1.8, and is proved there.

□

00F7 7.4.3 The Right Skew Unit

00F8

DEFINITION 7.4.3.1.1 ► THE RIGHT SKEW UNIT OF ▷

The **right skew unit of the right tensor product of pointed sets** is the functor

$$\mathbb{1}^{\mathsf{Sets}_*, \triangleright} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

defined by

$$\mathbb{1}^{\triangleright}_{\mathsf{Sets}_*} \stackrel{\text{def}}{=} S^0.$$

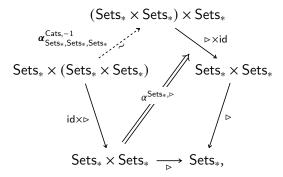
00F9 7.4.4 The Right Skew Associator

00FA DEFINITION 7.4.4.1.1 ► THE RIGHT SKEW ASSOCIATOR OF ▷

The **skew associator of the right tensor product of pointed sets** is the natural transformation

$$\alpha^{\mathsf{Sets}_*, \triangleright} \colon \rhd \circ (\mathrm{id}_{\mathsf{Sets}_*} \times \rhd) \Longrightarrow \rhd \circ (\rhd \times \mathrm{id}_{\mathsf{Sets}_*}) \circ \pmb{\alpha}^{\mathsf{Cats}, -1}_{\mathsf{Sets}_*, \mathsf{Sets}_*, \mathsf{Sets}_*}$$

as in the diagram



whose component

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\rhd} \colon X \rhd (Y \rhd Z) \to (X \rhd Y) \rhd Z$$

at (X, x_0) , (Y, y_0) , $(Z, z_0) \in \mathsf{Obj}(\mathsf{Sets}_*)$ is given by

$$X \rhd (Y \rhd Z) \stackrel{\text{def}}{=} |X| \odot (Y \rhd Z)$$

$$\stackrel{\text{def}}{=} |X| \odot (|Y| \odot Z)$$

$$\cong \bigvee_{x \in X} (|Y| \odot Z)$$

$$\cong \bigvee_{x \in X} (\bigvee_{y \in Y} Z)$$

$$\longrightarrow \bigvee_{x \in X} Z$$

$$[(x,y)] \in |X| \odot Y$$

$$\cong |X| \odot Y| \odot Z$$

$$\stackrel{\text{def}}{=} |X \rhd Y| \odot Z$$

$$\stackrel{\text{def}}{=} (X \rhd Y) \rhd Z,$$

where the map

$$\bigvee_{x \in X} (\bigvee_{y \in Y} Z) \to \bigvee_{[(x,y)] \in \bigvee_{x \in X} Y} Z$$

is given by $[(x, [(y, z)])] \mapsto [([(x, y)], z)].$

PROOF 7.4.4.1.2 ▶ PROOF OF DEFINITION 7.4.4.1.1

(Proven below in a bit.)

00FB REMARK 7.4.4.1.3 ➤ UNWINDING DEFINITION 7.4.4.1.1

Unwinding the notation for elements, we have

$$[(x, [(y, z)])] \stackrel{\text{def}}{=} [(x, y \triangleright z)]$$
$$\stackrel{\text{def}}{=} x \triangleright (y \triangleright z)$$

and

$$[([(x,y)],z)] \stackrel{\text{def}}{=} [(x \triangleright y,z)]$$
$$\stackrel{\text{def}}{=} (x \triangleright y) \triangleright z.$$

So, in other words, $\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \triangleright}$ acts on elements via

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\triangleright}(x \rhd (y \rhd z)) \stackrel{\mathrm{def}}{=} (x \rhd y) \rhd z$$

for each $x \triangleright (y \triangleright z) \in X \triangleright (Y \triangleright Z)$.

00FC REMARK 7.4.4.1.4 ► NON-INVERTIBILITY OF THE SKEW ASSOCIATOR OF ▷

Taking $y = y_0$, we see that the morphism $\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \triangleright}$ acts on elements as

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\triangleright}(x \rhd (y_0 \rhd z)) \stackrel{\mathrm{def}}{=} (x \rhd y_0) \rhd z.$$

However, by the definition of \triangleright , we have $x \triangleright y_0 = x' \triangleright y_0$ for all $x, x' \in X$, preventing $\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\triangleright}$ from being non-invertible.

PROOF 7.4.4.1.5 ► PROOF OF DEFINITION 7.4.4.1.1

Firstly, note that, given (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$, the map

$$\alpha^{\mathsf{Sets}_{*}, \triangleright}_{X,Y,Z} \colon X \rhd (Y \rhd Z) \to (X \rhd Y) \rhd Z$$

is indeed a morphism of pointed sets, as we have

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\triangleright}(x_0 \rhd (y_0 \rhd z_0)) = (x_0 \rhd y_0) \rhd z_0.$$

Next, we claim that $\alpha^{\mathsf{Sets}_*,\triangleright}$ is a natural transformation. We need to show that, given morphisms of pointed sets

$$f: (X, x_0) \to (X', x'_0),$$

 $g: (Y, y_0) \to (Y', y'_0),$

 $h: (Z, z_0) \to (Z', z'_0)$

the diagram

commutes. Indeed, this diagram acts on elements as

$$x \rhd (y \rhd z) \longmapsto f(x) \rhd (g(y) \rhd h(z))$$

$$\downarrow \qquad \qquad \downarrow$$

$$(x \rhd y) \rhd z \longmapsto (f(x) \rhd g(y)) \rhd h(z)$$

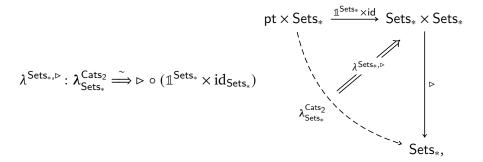
and hence indeed commutes, showing $\alpha^{\mathsf{Sets}_*, \triangleright}$ to be a natural transformation. This finishes the proof.

00FD 7.4.5 The Right Skew Left Unitor

00FE

DEFINITION 7.4.5.1.1 ► THE RIGHT SKEW LEFT UNITOR OF ▷

The **skew left unitor of the right tensor product of pointed sets** is the natural transformation



whose component

$$\lambda_X^{\mathsf{Sets}_*, \triangleright} : X \to S^0 \triangleright X$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by the composition

$$X \to X \lor X$$
$$\cong |S^0| \odot X$$
$$\cong S^0 \rhd X,$$

where $X \to X \vee X$ is the map sending X to the second factor of X in $X \vee X$.

PROOF 7.4.5.1.2 ► PROOF OF DEFINITION 7.4.5.1.1

(Proven below in a bit.)



00FF

REMARK 7.4.5.1.3 ► UNWINDING DEFINITION 7.4.5.1.1

In other words, $\lambda_X^{\mathsf{Sets}_*,\triangleright}$ acts on elements as

$$\lambda_X^{\mathsf{Sets}_*,\triangleright}(x) \stackrel{\mathrm{def}}{=} [(1,x)]$$

i.e. by

$$\lambda_X^{\mathsf{Sets}_*,\triangleright}(x) \stackrel{\mathrm{def}}{=} 1 \triangleright x$$

for each $x \in X$.

00FG

REMARK 7.4.5.1.4 ► Non-Invertibility of the Skew Left Unitor of ▷

The morphism $\lambda_X^{\mathsf{Sets}_*, \triangleright}$ is non-invertible, as it is non-surjective when viewed as a map of sets, since the elements $0 \triangleright x$ of $S^0 \triangleright X$ with $x \ne x_0$ are outside the image of $\lambda_X^{\mathsf{Sets}_*, \triangleright}$, which sends x to $1 \triangleright x$.

PROOF 7.4.5.1.5 ▶ PROOF OF DEFINITION 7.4.5.1.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$, the map

$$\lambda_X^{\mathsf{Sets}_*,\triangleright} : X \to S^0 \triangleright X$$

is indeed a morphism of pointed sets, as we have

$$\lambda_X^{\mathsf{Sets}_*,\triangleright}(x_0) = 1 \triangleright x_0$$
$$= 0 \triangleright x_0$$

Next, we claim that $\lambda^{Sets_*,\triangleright}$ is a natural transformation. We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \to (Y, y_0),$$

the diagram

$$\begin{array}{c|c} X & \xrightarrow{f} & Y \\ \lambda_X^{\mathsf{Sets}_*, \triangleright} & & & \downarrow \lambda_Y^{\mathsf{Sets}_*, \triangleright} \\ S^0 \rhd X & \xrightarrow{\mathrm{id}_{S^0} \, \rhd \, f} & S^0 \rhd Y \end{array}$$

commutes. Indeed, this diagram acts on elements as

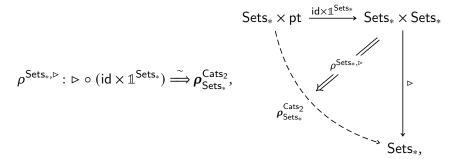
$$\begin{array}{ccc}
x & \longmapsto & f(x) \\
\downarrow & & \downarrow \\
1 \triangleright x & \longmapsto & 1 \triangleright f(x)
\end{array}$$

and hence indeed commutes, showing $\lambda^{\mathsf{Sets}_*, \triangleright}$ to be a natural transformation. This finishes the proof.

00FH 7.4.6 The Right Skew Right Unitor

00FJ DEFINITION 7.4.6.1.1 ► THE RIGHT SKEW RIGHT UNITOR OF ▷

The **skew right unitor of the right tensor product of pointed sets** is the natural transformation



whose component

$$\rho_X^{\mathsf{Sets}_*,\triangleright} \colon X \rhd S^0 \to X$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by the composition

$$X \rhd S^0 \cong |X| \odot S^0$$
$$\cong \bigvee_{x \in X} S^0$$
$$\to X,$$

where $\bigvee_{x \in X} S^0 \to X$ is the map given by

$$[(x,0)] \mapsto x_0,$$

$$[(x,1)] \mapsto x$$

for each $x \in X$.

PROOF 7.4.6.1.2 ▶ PROOF OF DEFINITION 7.4.6.1.1

(Proven below in a bit.)

00FK

REMARK 7.4.6.1.3 ► UNWINDING DEFINITION 7.4.6.1.1

In other words, $\rho_X^{\mathsf{Sets}_*, \rhd}$ acts on elements as

$$\rho_X^{\mathsf{Sets}_*,\triangleright}(x \triangleright 0) \stackrel{\text{def}}{=} x_0,$$

$$\rho_X^{\mathsf{Sets}_*,\triangleright}(x \triangleright 1) \stackrel{\text{def}}{=} x$$

for each $x \triangleright 1 \in X \triangleright S^0$.

00FL REMARK 7.4.6.1.4 ➤ Non-Invertibility of the Skew Right Unitor of ▷

The morphism $\rho_X^{\mathsf{Sets}_*, \triangleright}$ is almost invertible, with its would-be-inverse

$$\phi_X \colon X \to X \rhd S^0$$

given by

$$\phi_X(x) \stackrel{\text{def}}{=} x > 1$$

for each $x \in X$. Indeed, we have

$$\begin{split} [\rho_X^{\mathsf{Sets}_*, \triangleright} \circ \phi](x) &= \rho_X^{\mathsf{Sets}_*, \triangleright}(\phi(x)) \\ &= \rho_X^{\mathsf{Sets}_*, \triangleright}(x \triangleright 1) \\ &= x \\ &= [\mathrm{id}_X](x) \end{split}$$

so that

$$\rho_X^{\mathsf{Sets}_*,\triangleright} \circ \phi = \mathrm{id}_X$$

and

$$\begin{split} [\phi \circ \rho_X^{\mathsf{Sets}_*, \triangleright}](x \rhd 1) &= \phi(\rho_X^{\mathsf{Sets}_*, \triangleright}(x \rhd 1)) \\ &= \phi(x) \\ &= x \rhd 1 \\ &= [\mathrm{id}_{X \rhd S^0}](x \rhd 1), \end{split}$$

but

$$\begin{aligned} [\phi \circ \rho_X^{\mathsf{Sets}_*, \triangleright}](x \triangleright 0) &= \phi(\rho_X^{\mathsf{Sets}_*, \triangleright}(x \triangleright 0)) \\ &= \phi(x_0) \\ &= 1 \triangleright x_0, \end{aligned}$$

where $x \triangleright 0 \neq 1 \triangleright x_0$. Thus

$$\phi \circ \rho_X^{\mathsf{Sets}_*, \triangleright} \stackrel{?}{=} \mathrm{id}_{X \triangleright S^0}$$

holds for all elements in $X \triangleright S^0$ except one.

Firstly, note that, given $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$, the map

$$\rho_X^{\mathsf{Sets}_*,\triangleright} : X \triangleright S^0 \to X$$

is indeed a morphism of pointed sets as we have

$$\rho_X^{\mathsf{Sets}_*,\triangleright}(x_0 \triangleright 0) = x_0.$$

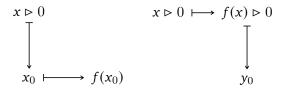
Next, we claim that $\rho^{\mathsf{Sets}_*, \triangleright}$ is a natural transformation. We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \to (Y, y_0),$$

the diagram

$$\begin{array}{c} X \rhd S^0 \xrightarrow{f \rhd \mathrm{id}_{S^0}} Y \rhd S^0 \\ \rho_X^{\mathsf{Sets}_*, \rhd} \bigvee \qquad \qquad \bigvee_{f} \rho_Y^{\mathsf{Sets}_*, \rhd} \end{array}$$

commutes. Indeed, this diagram acts on elements as



and

$$x \triangleright 1 \longmapsto f(x) \triangleright 1$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad$$

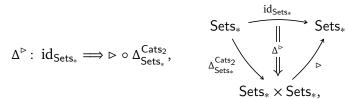
and hence indeed commutes, showing $\rho^{\mathsf{Sets}_*, \triangleright}$ to be a natural transformation. This finishes the proof.

00FM 7.4.7 The Diagonal

00FN

DEFINITION 7.4.7.1.1 ► THE DIAGONAL OF ▷

The **diagonal of the right tensor product of pointed sets** is the natural transformation



whose component

$$\Delta_X^{\triangleright} : (X, x_0) \to (X \triangleright X, x_0 \triangleright x_0)$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by

$$\Delta_X^{\triangleright}(x) \stackrel{\mathrm{def}}{=} x \triangleright x$$

for each $x \in X$.

PROOF 7.4.7.1.2 ▶ PROOF OF DEFINITION 7.4.7.1.1

Being a Morphism of Pointed Sets

We have

$$\Delta_X^{\triangleright}(x_0) \stackrel{\text{def}}{=} x_0 \triangleright x_0,$$

and thus Δ_X^{\rhd} is a morphism of pointed sets.

Naturality

We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

00FQ

$$X \xrightarrow{f} Y$$

$$\Delta_X^{\triangleright} \downarrow \qquad \qquad \downarrow \Delta_Y^{\triangleright}$$

$$X \triangleright X \xrightarrow{f \triangleright f} Y \triangleright Y$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
x & \longmapsto & f(x) \\
\downarrow & & \downarrow \\
x \triangleright x & \longmapsto & f(x) \triangleright f(x)
\end{array}$$

and hence indeed commutes, showing Δ^{\triangleright} to be natural.

00FP 7.4.8 The Right Skew Monoidal Structure on Pointed Sets Associated to ⊳

PROPOSITION 7.4.8.1.1 ► THE RIGHT SKEW MONOIDAL STRUCTURE ON POINTED SETS ASSOCI-

The category Sets* admits a right-closed right skew monoidal category structure consisting of:

- The Underlying Category. The category Sets* of pointed sets.
- The Right Skew Monoidal Product. The right tensor product functor

$$\triangleright$$
: Sets_{*} \times Sets_{*} \rightarrow Sets_{*}

of Definition 7.4.1.1.1.

• The Right Internal Skew Hom. The right internal Hom functor

$$[-,-]_{\mathsf{Sets}}^{\triangleright} : \mathsf{Sets}_{*}^{\mathsf{op}} \times \mathsf{Sets}_{*} \to \mathsf{Sets}_{*}$$

of Definition 7.4.2.1.1.

• The Right Skew Monoidal Unit. The functor

$$\mathbb{1}^{\mathsf{Sets}_*,\triangleright} : \mathsf{pt} \to \mathsf{Sets}_*$$

of Definition 7.4.3.1.1.

• The Right Skew Associators. The natural transformation

$$\alpha^{\mathsf{Sets}_*, \triangleright} : \triangleright \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \triangleright) \Longrightarrow \triangleright \circ (\triangleright \times \mathsf{id}_{\mathsf{Sets}_*}) \circ \pmb{\alpha}_{\mathsf{Sets}_*, \mathsf{Sets}_*, \mathsf{Sets}_*}^{\mathsf{Cats}, -1}$$
of Definition 7.4.4.1.1.

• The Right Skew Left Unitors. The natural transformation

$$\lambda^{\mathsf{Sets}_*, \triangleright} \colon \lambda^{\mathsf{Cats}_2}_{\mathsf{Sets}_*} \stackrel{^{\sim}}{\Longrightarrow} \rhd \circ (\mathbb{1}^{\mathsf{Sets}_*} \times id_{\mathsf{Sets}_*})$$

of Definition 7.4.5.1.1.

• The Right Skew Right Unitors. The natural transformation

$$\rho^{\mathsf{Sets}_*,\triangleright} : \triangleright \circ (\mathsf{id} \times \mathbb{1}^{\mathsf{Sets}_*}) \xrightarrow{\sim} \rho_{\mathsf{Sets}_*}^{\mathsf{Cats}_2}$$

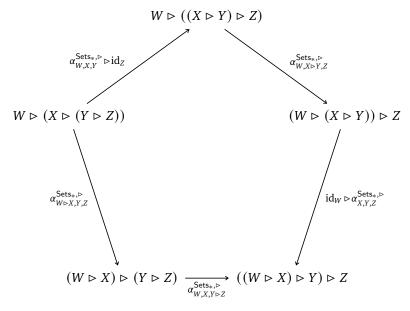
of Definition 7.4.6.1.1.

PROOF 7.4.8.1.2 ► PROOF OF PROPOSITION 7.4.8.1.1

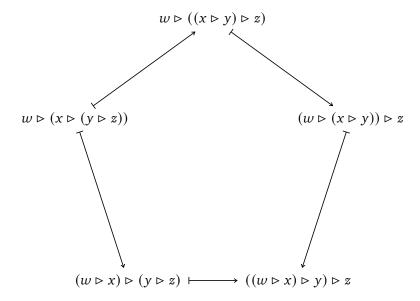
The Pentagon Identity

Let (W, w_0) , (X, x_0) , (Y, y_0) and (Z, z_0) be pointed sets. We have to show

that the diagram



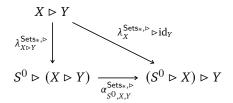
commutes. Indeed, this diagram acts on elements as



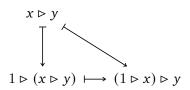
and thus we see that the pentagon identity is satisfied.

The Right Skew Left Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram



commutes. Indeed, this diagram acts on elements as



and hence indeed commutes. Thus the left skew triangle identity is satisfied.

The Right Skew Right Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

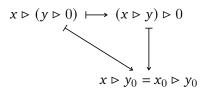
$$X \rhd (Y \rhd S^{0}) \xrightarrow{\operatorname{id}_{X} \rhd \rho_{Y}^{\mathsf{Sets}_{*}, \rhd}} (X \rhd Y) \rhd S^{0}$$

$$\downarrow \rho_{X \rhd Y}^{\mathsf{Sets}_{*}, \rhd}$$

$$\downarrow \rho_{X \rhd Y}^{\mathsf{Sets}_{*}, \rhd}$$

$$X \rhd Y$$

commutes. Indeed, this diagram acts on elements as



and

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Right Skew Middle Triangle Identity

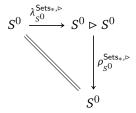
Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

commutes. Indeed, this diagram acts on elements as

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Zig-Zag Identity

We have to show that the diagram



commutes. Indeed, this diagram acts on elements as

$$0 \longmapsto 1 \triangleright 0$$

$$\downarrow \qquad \qquad \downarrow$$

$$0$$

and

$$1 \mapsto 1 \triangleright 1$$

$$\downarrow \qquad \qquad \downarrow$$

$$\downarrow \qquad \qquad \downarrow$$

$$\downarrow \qquad \qquad \downarrow$$

$$\downarrow \qquad \qquad \downarrow$$

and hence indeed commutes. Thus the zig-zag identity is satisfied.

Right Skew Monoidal Right-Closedness

This follows from Item 2 of Proposition 7.4.1.1.8.

OOFR 7.4.9 Monoids With Respect to the Right Tensor Product of Pointed Sets

00FS PROPOSITION 7.4.9.1.1 ► MONOIDS WITH RESPECT TO ▷

The category of monoids on $(\mathsf{Sets}_*, \triangleright, S^0)$ is isomorphic to the category of "monoids with right zero" and morphisms between them.

$$0_A a = 0_A$$

for each $a \in A$.

PROOF 7.4.9.1.2 ► PROOF OF PROPOSITION 7.4.9.1.1

Monoids on (Sets_{*}, \triangleright , S^0)

A monoid on (Sets_{*}, \triangleright , S^0) consists of:

• The Underlying Object. A pointed set $(A, 0_A)$.

 $^{^{1}}$ A monoid with right zero is defined similarly as the monoids with zero of ??. Succinctly, they are monoids (A, μ_A, η_A) with a special element 0_A satisfying

• The Multiplication Morphism. A morphism of pointed sets

$$\mu_A : A \triangleright A \rightarrow A$$
,

determining a right bilinear morphism of pointed sets

$$A \times A \longrightarrow A$$

 $(a,b) \longmapsto ab.$

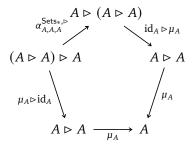
• The Unit Morphism. A morphism of pointed sets

$$\eta_A \colon S^0 \to A$$

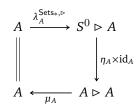
picking an element 1_A of A.

satisfying the following conditions:

1. Associativity. The diagram



2. Left Unitality. The diagram



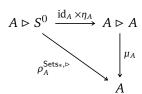
commutes.

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7.4.9 Monoids With Respect to the Right Tensor Product of Pointed Sets82

3. *Right Unitality*. The diagram



commutes.

0272

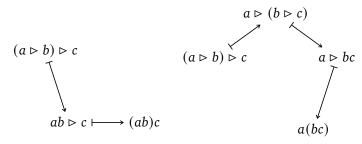
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Being a right-bilinear morphism of pointed sets, the multiplication map satisfies

$$0_A a = 0_A$$

for each $a \in A$. Now, the associativity, left unitality, and right unitality conditions act on elements as follows:

1. Associativity. The associativity condition acts as

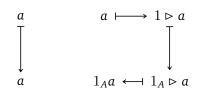


This gives

$$(ab)c = a(bc)$$

for each $a, b, c \in A$.

2. Left Unitality. The left unitality condition acts as



This gives

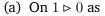
$$1_A a = a$$

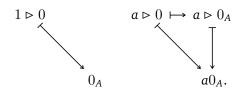
for each $a \in A$.

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3. Right Unitality. The right unitality condition acts:

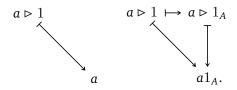
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0276

(b) On a > 1 as



This gives

$$a1_A = a,$$

$$a0_A = 0_A$$

for each $a \in A$.

Thus we see that monoids with respect to \triangleright are exactly monoids with right zero.

Morphisms of Monoids on $(Sets_*, \triangleright, S^0)$

A morphism of monoids on $(\mathsf{Sets}_*, \triangleright, S^0)$ from $(A, \mu_A, \eta_A, 0_A)$ to $(B, \mu_B, \eta_B, 0_B)$ is a morphism of pointed sets

$$f: (A, 0_A) \rightarrow (B, 0_B)$$

satisfying the following conditions:

0277

1. Compatibility With the Multiplication Morphisms. The diagram

$$\begin{array}{ccc} A \rhd A & \xrightarrow{f \rhd f} & B \rhd E \\ \downarrow^{\mu_A} & & \downarrow^{\mu_E} \\ A & \xrightarrow{f} & B \end{array}$$

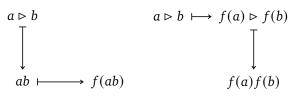
commutes.

2. Compatibility With the Unit Morphisms. The diagram



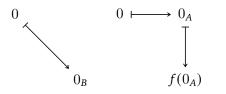
commutes.

These act on elements as

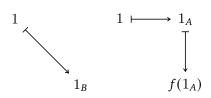


and

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and



giving

$$f(ab) = f(a)f(b),$$

$$f(0_A) = 0_B,$$

$$f(1_A) = 1_B,$$

for each $a, b \in A$, which is exactly a morphism of monoids with right zero.

Identities and Composition

Similarly, the identities and composition of $\mathsf{Mon}(\mathsf{Sets}_*, \triangleright, S^0)$ can be easily seen to agree with those of monoids with right zero, which finishes the proof.

OOFT 7.5 The Smash Product of Pointed Sets

00FU 7.5.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

00FV

DEFINITION 7.5.1.1.1 ► SMASH PRODUCTS OF POINTED SETS

The **smash product of** (X, x_0) **and** $(Y, y_0)^1$ is the pointed set $X \wedge Y^2$ satisfying the bijection

$$\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes}(X \times Y, Z),$$

naturally in (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$.

²Further Notation: In the context of monoids with zero as models for \mathbb{F}_1 -algebras, the smash product $X \wedge Y$ is also denoted $X \otimes_{\mathbb{F}_1} Y$.

00FW

REMARK 7.5.1.1.2 ► UNWINDING DEFINITION 7.5.1.1.1: THE UNIVERSAL PROPERTY I

That is to say, the smash product of pointed sets is defined so as to induce a bijection between the following data:

- Pointed maps $f: X \wedge Y \to Z$.
- Maps of sets $f: X \times Y \to Z$ satisfying

$$f(x_0, y) = z_0,$$

$$f(x, y_0) = z_0$$

for each $x \in X$ and each $y \in Y$.

00FX

REMARK 7.5.1.1.3 ► UNWINDING DEFINITION 7.5.1.1.1: THE UNIVERSAL PROPERTY II

The smash product of pointed sets may be described as follows:

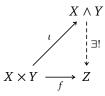
- The smash product of (X, x_0) and (Y, y_0) is the pair $((X \land Y, x_0 \land y_0), \iota)$ consisting of
 - A pointed set $(X \wedge Y, x_0 \wedge y_0)$;
 - A bilinear morphism of pointed sets $\iota: (X \times Y, (x_0, y_0)) \to X \wedge Y$;

satisfying the following universal property:

¹Further Terminology: In the context of monoids with zero as models for \mathbb{F}_1 -algebras, the smash product $X \wedge Y$ is also called the **tensor product of** \mathbb{F}_1 -**modules of** (X, x_0) **and** (Y, y_0) or the **tensor product of** (X, x_0) **and** (Y, y_0) **over** \mathbb{F}_1 .

- (\star) Given another such pair $((Z, z_0), f)$ consisting of
 - * A pointed set (Z, z_0) ;
 - * A bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \rightarrow X \wedge Y$;

there exists a unique morphism of pointed sets $X \wedge Y \xrightarrow{\exists !} Z$ making the diagram



commute.

00FY CONSTR

CONSTRUCTION 7.5.1.1.4 ► SMASH PRODUCTS OF POINTED SETS

Concretely, the smash product of (X, x_0) and (Y, y_0) is the pointed set $(X \land Y, x_0 \land y_0)$ consisting of:

• *The Underlying Set.* The set $X \wedge Y$ defined by

$$X \wedge Y \cong (X \times Y)/\sim_R$$

where \sim_R is the equivalence relation on $X \times Y$ obtained by declaring

$$(x_0, y) \sim_R (x_0, y'),$$

 $(x, y_0) \sim_R (x', y_0)$

for each $x, x' \in X$ and each $y, y' \in Y$.

• *The Basepoint*. The element $[(x_0, y_0)]$ of $X \wedge Y$ given by the equivalence class of (x_0, y_0) under the equivalence relation \sim on $X \times Y$.

PROOF 7.5.1.1.5 ► PROOF OF CONSTRUCTION 7.5.1.1.4

By Conditions on Relations, ??, we have a natural bijection

$$\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Hom}^R_{\mathsf{Sets}}(X \times Y, Z),$$

where $\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z)$ is the set

$$\operatorname{Hom}_{\mathsf{Sets}}^R(X\times Y,Z) \stackrel{\mathrm{def}}{=} \left\{ f \in \operatorname{Hom}_{\mathsf{Sets}}(X\times Y,Z) \middle| \begin{array}{l} \text{for each } x,y\in X, \text{ if} \\ (x,y)\sim_R (x',y'), \text{ then} \\ f(x,y) = f(x',y') \end{array} \right\}.$$

However, the condition $(x, y) \sim_R (x', y')$ only holds when:

0279 1. We have x = x' and y = y'.

027A

027B

027C

- 2. The following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$.
 - (b) We have $x' = x_0$ or $y' = y_0$.

So, given $f \in \text{Hom}_{\mathsf{Sets}}(X \times Y, Z)$ with a corresponding $\overline{f} \colon X \wedge Y \to Z$, the latter case above implies

$$f(x_0, y) = f(x, y_0)$$

= $f(x_0, y_0)$,

and since $\overline{f}: X \wedge Y \to Z$ is a pointed map, we have

$$f(x_0, y_0) = \overline{f}(x_0, y_0)$$

= z_0 .

Thus the elements f in $\operatorname{Hom}_{\mathsf{Sets}}^R(X \times Y, Z)$ are precisely those functions $f \colon X \times Y \to Z$ satisfying the equalities

$$f(x_0, y) = z_0,$$

$$f(x, y_0) = z_0$$

for each $x \in X$ and each $y \in Y$, giving an equality

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}}^R(X\times Y,Z)=\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}^\otimes(X\times Y,Z)$$

of sets, which when composed with our earlier isomorphism

$$\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Hom}^R_{\mathsf{Sets}}(X \times Y, Z),$$

gives our desired natural bijection, finishing the proof.

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REMARK 7.5.1.1.6 ► ON THE CONSTRUCTION OF THE SMASH PRODUCT OF POINTED SETS 00FZ

It is also somewhat common to write

$$X \wedge Y \stackrel{\text{def}}{=} \frac{X \times Y}{X \vee Y},$$

identifying $X \vee Y$ with the subspace $(\{x_0\} \times Y) \cup (X \times \{y_0\})$ of $X \times Y$, and having the quotient be defined by declaring $(x, y) \sim (x', y')$ iff we have $(x, y), (x', y') \in X \vee Y.$

CONSTRUCTION 7.5.1.1.7 ► A SECOND CONSTRUCTION OF THE SMASH PRODUCT OF POINTED 01VX **SETS**

> Alternatively, the smash product of (X, x_0) and (Y, y_0) may be constructed as the pointed set $X \wedge Y$ given by

$$X \wedge Y \cong \bigvee_{x \in X^{-}} Y$$
$$\cong \bigvee_{y \in Y^{-}} X.$$

PROOF 7.5.1.1.8 ► PROOF OF CONSTRUCTION 7.5.1.1.7

Indeed, since $X \cong \bigvee_{x \in X^-} S^0$, we have

$$X \wedge Y \cong (\bigvee_{x \in X^{-}} S^{0}) \wedge Y$$
$$\cong \bigvee_{x \in X^{-}} S^{0} \wedge Y$$
$$\cong \bigvee_{x \in X^{-}} Y,$$

where we have used that A preserves colimits in both variables via ?? for the second isomorphism above, since it has right adjoints in both variables by Item 2.

A similar proof applies to the isomorphism $X \wedge Y \cong \bigvee_{y \in Y^-} X$.

NOTATION 7.5.1.1.9 ► ELEMENTS OF SMASH PRODUCTS OF POINTED SETS 00G0

We write $x \wedge y$ for the element [(x, y)] of $X \wedge Y \cong X \times Y/\sim$.

00G1

REMARK 7.5.1.1.10 ► BASEPOINTS OF SMASH PRODUCTS OF POINTED SETS

Employing the notation introduced in Notation 7.5.1.1.9, we have

$$x_0 \wedge y_0 = x \wedge y_0,$$

= $x_0 \wedge y$

for each $x \in X$ and each $y \in Y$, and

$$x \wedge y_0 = x' \wedge y_0,$$

 $x_0 \wedge y = x_0 \wedge y'$

for each $x, x' \in X$ and each $y, y' \in Y$.

00G2

EXAMPLE 7.5.1.1.11 ► EXAMPLES OF SMASH PRODUCTS OF POINTED SETS

Here are some examples of smash products of pointed sets.

00G3

1. *Smashing With pt.* For any pointed set *X*, we have isomorphisms of pointed sets

$$\operatorname{pt} \wedge X \cong \operatorname{pt},$$

 $X \wedge \operatorname{pt} \cong \operatorname{pt}.$

00G4

2. *Smashing With* S^0 . For any pointed set X, we have isomorphisms of pointed sets

$$S^0 \wedge X \cong X$$
,
 $X \wedge S^0 \cong X$.

00G5

PROPOSITION 7.5.1.1.12 ► PROPERTIES OF SMASH PRODUCTS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

00G6

1. Functoriality. The assignments $X, Y, (X, Y) \mapsto X \wedge Y$ define functors

$$X \land -:$$
 Sets_{*} \rightarrow Sets_{*},
 $- \land Y:$ Sets_{*} \rightarrow Sets_{*},
 $-_1 \land -_2:$ Sets_{*} \times Sets_{*} \rightarrow Sets_{*}.

In particular, given pointed maps

$$f: (X, x_0) \to (A, a_0),$$

 $g: (Y, y_0) \to (B, b_0),$

the induced map

$$f \wedge g : X \wedge Y \rightarrow A \wedge B$$

is given by

$$[f \land g](x \land y) \stackrel{\text{def}}{=} f(x) \land g(y)$$

for each $x \land y \in X \land Y$.

2. Adjointness. We have adjunctions

$$(X \land \neg \dashv \mathbf{Sets}_*(X, \neg)):$$
 Sets, $X \land \neg$
Sets, $X \land \neg$
 $(\neg \land Y \dashv \mathbf{Sets}_*(Y, \neg)):$ Sets, $Y \land \neg \land Y$
 $Y \dashv \mathbf{Sets}_*(Y, \neg)$

witnessed by bijections

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \wedge Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z)),$$

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \wedge Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(X, \mathsf{Sets}_*(A, Z)),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in Obj(Sets_*)$.

3. Enriched Adjointness. We have Sets*-enriched adjunctions

$$(X \land - \dashv \mathbf{Sets}_*(X, -)) : \quad \mathbf{Sets}_* \underbrace{\bot}_{X \land -} \mathbf{Sets}_*,$$

$$(- \land Y \dashv \mathbf{Sets}_*(Y, -)) : \quad \mathbf{Sets}_* \underbrace{\bot}_{X \land -} \mathbf{Sets}_*,$$

$$(- \land Y \dashv \mathbf{Sets}_*(Y, -)) : \quad \mathbf{Sets}_* \underbrace{\bot}_{X \land -} \mathbf{Sets}_*,$$

$$(- \land Y \dashv \mathbf{Sets}_*(Y, -)): \mathbf{Sets}_* \underbrace{\downarrow}_{\mathbf{Sets}_*(Y, -)}^{- \land Y} \mathbf{Sets}_*$$

witnessed by isomorphisms of pointed sets

$$\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Sets}_*(X, \mathsf{Sets}_*(Y, Z)),$$

$$\mathsf{Sets}_*(X \land Y, Z) \cong \mathsf{Sets}_*(X, \mathsf{Sets}_*(A, Z)),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathbf{Sets}_*).$

00G7

00G8

00G9

4. As a Pushout. We have an isomorphism

$$X \wedge Y \cong \operatorname{pt} \coprod_{X \vee Y} (X \times Y),$$

$$X \wedge Y \longleftarrow X \times Y$$

$$\uparrow \qquad \qquad \qquad \uparrow \qquad \qquad \qquad \downarrow \iota$$

$$\operatorname{pt} \longleftarrow X \vee Y$$

natural in $X, Y \in \text{Obj}(\mathsf{Sets}_*)$, where the pushout is taken in Sets, and the embedding $\iota \colon X \vee Y \hookrightarrow X \times Y$ is defined following Remark 7.5.1.1.6.

00GA

5. *Distributivity Over Wedge Sums*. We have isomorphisms of pointed sets

$$X \wedge (Y \vee Z) \cong (X \wedge Y) \vee (X \wedge Z),$$

$$(X \vee Y) \wedge Z \cong (X \wedge Z) \vee (Y \wedge Z),$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$.

PROOF 7.5.1.1.13 ► PROOF OF PROPOSITION 7.5.1.1.12

Item 1: Functoriality

The map $f \land g$ comes from Conditions on Relations, Item 4 of Proposition 10.6.2.1.3 via the map

$$f \wedge g: X \times Y \rightarrow A \wedge B$$

sending (x, y) to $f(x) \land g(y)$, which we need to show satisfies

$$[f \land g](x, y) = [f \land g](x', y')$$

for each $(x, y), (x', y') \in X \times Y$ with $(x, y) \sim_R (x', y')$, where \sim_R is the relation constructing $X \wedge Y$ as

$$X \wedge Y \cong (X \times Y)/\sim_R$$

in Construction 7.5.1.1.4. The condition defining \sim is that at least one of the following conditions is satisfied:

027D

1. We have x = x' and y = y';

027E

2. Both of the following conditions are satisfied:

027F

(a) We have
$$x = x_0$$
 or $y = y_0$.

027G

(b) We have $x' = x_0$ or $y' = y_0$.

We have five cases:

027H

1. In the first case, we clearly have

$$[f \wedge g](x,y) = [f \wedge g](x',y')$$

since x = x' and y = y'.

027J

2. If $x = x_0$ and $x' = x_0$, we have

$$[f \land g](x_0, y) \stackrel{\text{def}}{=} f(x_0) \land g(y)$$

$$= a_0 \land g(y)$$

$$= a_0 \land g(y')$$

$$= f(x_0) \land g(y')$$

$$\stackrel{\text{def}}{=} [f \land g](x_0, y').$$

027K

3. If $x = x_0$ and $y' = y_0$, we have

$$[f \land g](x_0, y) \stackrel{\text{def}}{=} f(x_0) \land g(y)$$

$$= a_0 \land g(y)$$

$$= a_0 \land b_0$$

$$= f(x') \land b_0$$

$$= f(x') \land g(y_0)$$

$$\stackrel{\text{def}}{=} [f \land g](x', y_0).$$

027L

4. If $y = y_0$ and $x' = x_0$, we have

$$[f \land g](x, y_0) \stackrel{\text{def}}{=} f(x) \land g(y_0)$$

$$= f(x) \land b_0$$

$$= a_0 \land b_0$$

$$= a_0 \land g(y')$$

$$= f(x_0) \land g(y')$$

$$\stackrel{\text{def}}{=} [f \land g](x_0, y').$$

027M

5. If $y = y_0$ and $y' = y_0$, we have

$$[f \land g](x, y_0) \stackrel{\text{def}}{=} f(x) \land g(y_0)$$

$$= f(x) \land b_0$$

$$= f(x') \land b_0$$

$$= f(x) \land g(y_0)$$

$$\stackrel{\text{def}}{=} [f \land g](x', y_0).$$

Thus $f \wedge g$ is well-defined. Next, we claim that \wedge preserves identities and composition:

• Preservation of Identities. We have

$$[id_X \wedge id_Y](x \wedge y) \stackrel{\text{def}}{=} id_X(x) \wedge id_Y(y)$$
$$= x \wedge y$$
$$= [id_{X \wedge Y}](x \wedge y)$$

for each $x \land y \in X \land Y$, and thus

$$id_X \wedge id_Y = id_{X \wedge Y}$$
.

• Preservation of Composition. Given pointed maps

$$f: (X, x_0) \to (X', x'_0),$$

$$h: (X', x'_0) \to (X'', x''_0),$$

$$g: (Y, y_0) \to (Y', y'_0),$$

$$k: (Y', y'_0) \to (Y'', y''_0),$$

we have

$$[(h \circ f) \land (k \circ g)](x \land y) \stackrel{\text{def}}{=} h(f(x)) \land k(g(y))$$

$$\stackrel{\text{def}}{=} [h \land k](f(x) \land g(y))$$

$$\stackrel{\text{def}}{=} [h \land k]([f \land g](x \land y))$$

$$\stackrel{\text{def}}{=} [(h \land k) \circ (f \land g)](x \land y)$$

for each $x \land y \in X \land Y$, and thus

$$(h \circ f) \wedge (k \circ g) = (h \wedge k) \circ (f \wedge g).$$

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This finishes the proof.

Item 2: Adjointness

We prove only the adjunction $- \land Y \dashv \mathbf{Sets}_*(Y, -)$, witnessed by a natural bijection

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}(X \wedge Y, Z) \cong \operatorname{\mathsf{Hom}}_{\operatorname{\mathsf{Sets}}_*}(X, \operatorname{\mathsf{Sets}}_*(Y, Z)),$$

as the proof of the adjunction $X \land \neg \neg \mathbf{Sets}_*(X, \neg)$ is similar. We claim we have a bijection

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}^{\otimes}(X\times Y,Z)\cong \operatorname{\mathsf{Hom}}_{\operatorname{\mathsf{Sets}}_*}(X,\operatorname{\mathbf{Sets}}_*(Y,Z))$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$, impliying the desired adjunction. Indeed, this bijection is a restriction of the bijection

$$Sets(X \times Y, Z) \cong Sets(X, Sets(Y, Z))$$

of Constructions With Sets, Item 2 of Proposition 4.1.3.1.4:

A map

$$\xi: X \times Y \to Z$$

in $\operatorname{Hom}_{\operatorname{Sets}_n}^{\otimes}(X \times Y, Z)$ gets sent to the pointed map

$$\xi^{\dagger} : (X, x_0) \to (\mathbf{Sets}_*(Y, Z), \Delta_{z_0}),$$

$$x \longmapsto (\xi_x^{\dagger} : Y \to Z),$$

where $\xi_x^{\dagger} \colon Y \to Z$ is the map defined by

$$\xi_x^{\dagger}(y) \stackrel{\text{def}}{=} \xi(x,y)$$

for each $y \in Y$, where:

- The map ξ^{\dagger} is indeed pointed, as we have

$$\xi_{x_0}^{\dagger}(y) \stackrel{\text{def}}{=} \xi(x_0, y)$$

$$\stackrel{\text{def}}{=} z_0$$

for each $y \in Y$. Thus $\xi_{x_0}^{\dagger} = \Delta_{z_0}$ and ξ^{\dagger} is pointed.

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– The map ξ_x^{\dagger} indeed lies in **Sets**_{*}(Y,Z), as we have

$$\xi_x^{\dagger}(y_0) \stackrel{\text{def}}{=} \xi(x, y_0)$$

$$\stackrel{\text{def}}{=} z_0.$$

· Conversely, a map

$$\xi: (X, x_0) \to (\mathbf{Sets}_*(Y, Z), \Delta_{z_0}),$$

$$x \longmapsto (\xi_X: Y \to Z),$$

in $Hom_{Sets_*}(X, \mathbf{Sets}_*(Y, Z))$ gets sent to the map

$$\xi^{\dagger}: X \times Y \to Z$$

defined by

$$\xi^{\dagger}(x,y) \stackrel{\text{def}}{=} \xi_x(y)$$

for each $(x, y) \in X \times Y$, which indeed lies in $\text{Hom}_{\mathsf{Sets}_*}^{\otimes}(X \times Y, Z)$, as:

- Left Bilinearity. We have

$$\xi^{\dagger}(x_0, y) \stackrel{\text{def}}{=} \xi_{x_0}(y)$$

$$\stackrel{\text{def}}{=} \Delta_{z_0}(y)$$

$$\stackrel{\text{def}}{=} z_0$$

for each $y \in Y$, since $\xi_{x_0} = \Delta_{z_0}$ as ξ is assumed to be a pointed map.

- Right Bilinearity. We have

$$\xi^{\dagger}(x, y_0) \stackrel{\text{def}}{=} \xi_x(y_0)$$

$$\stackrel{\text{def}}{=} z_0$$

for each $x \in X$, since $\xi_x \in \mathbf{Sets}_*(Y, Z)$ is a morphism of pointed sets.

This finishes the proof.

Item 3: Enriched Adjointness

This follows from Item 2 and Monoidal Categories, ?? of ??.

Item 4: As a Pushout

Following the description of Constructions With Sets, Remark 4.2.4.1.4, we have

pt
$$\coprod_{X \vee Y} (X \times Y) \cong (\text{pt} \times (X \times Y))/\sim$$
,

where \sim identifies the element \star in pt with all elements of the form (x_0, y) and (x, y_0) in $X \times Y$. Thus Conditions on Relations, Item 4 of Proposition 10.6.2.1.3 coupled with Remark 7.5.1.1.10 then gives us a well-defined map

$$pt \coprod_{X \vee Y} (X \times Y) \to X \wedge Y$$

via $[(\star, (x, y))] \mapsto x \land y$, with inverse

$$X \wedge Y \rightarrow \mathsf{pt} \prod_{X \vee Y} (X \times Y)$$

given by $x \land y \mapsto [(\star, (x, y))].$

Item 5: Distributivity Over Wedge Sums

This follows from Proposition 7.5.9.1.1, Monoidal Categories, ?? of ??, and the fact that \lor is the coproduct in Sets $_*$ (Pointed Sets, Definition 6.3.3.1.1).

00GB 7.5.2 The Internal Hom of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

00GC DEFINITION 7.5.2.1.1 ► THE INTERNAL HOM OF POINTED SETS

The internal Hom¹ of pointed sets from (X, x_0) to (Y, y_0) is the pointed set **Sets**_{*} $((X, x_0), (Y, y_0))^2$ consisting of:

- *The Underlying Set.* The set $Sets_*((X, x_0), (Y, y_0))$ of morphisms of pointed sets from (X, x_0) to (Y, y_0) .
- The Basepoint. The element

$$\Delta_{y_0}: (X, x_0) \rightarrow (Y, y_0)$$

of $Sets_*((X, x_0), (Y, y_0))$ given by

$$\Delta_{y_0}(x) \stackrel{\text{def}}{=} y_0$$

for each $x \in X$.

¹For a proof that **Sets**_{*} is indeed the internal Hom of Sets_{*} with respect to the smash product of pointed sets, see <u>Item 2</u> of <u>Proposition 7.5.1.1.12</u>.

²Further Notation: Also written $\mathbf{Hom}_{\mathsf{Sets}_*}(X,Y)$.

PROPOSITION 7.5.2.1.2 ➤ PROPERTIES OF THE INTERNAL HOM OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. Functoriality. The assignments $X, Y, (X, Y) \mapsto \mathbf{Sets}_*(X, Y)$ define functors

$$\begin{array}{lll} \textbf{Sets}_*(X,-)\colon & \mathsf{Sets}_* & \to \mathsf{Sets}_*, \\ \textbf{Sets}_*(-,Y)\colon & \mathsf{Sets}_*^\mathsf{op} & \to \mathsf{Sets}_*, \\ \textbf{Sets}_*(-_1,-_2)\colon & \mathsf{Sets}_*^\mathsf{op} \times \mathsf{Sets}_* & \to \mathsf{Sets}_*. \end{array}$$

In particular, given pointed maps

$$f: (X, x_0) \to (A, a_0),$$

 $g: (Y, y_0) \to (B, b_0),$

the induced map

$$\mathsf{Sets}_*(f,g) \colon \mathsf{Sets}_*(A,Y) \to \mathsf{Sets}_*(X,B)$$

is given by

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$$[\mathbf{Sets}_*(f,g)](\phi) \stackrel{\text{def}}{=} g \circ \phi \circ f$$

for each $\phi \in \mathbf{Sets}_*(A, Y)$.

2. Adjointness. We have adjunctions

$$(X \land \neg \dashv \mathbf{Sets}_*(X, \neg)):$$
 Sets, $X \land \neg$
Sets, $X \land \neg$
 $Sets_*(X, \neg)$
 $(\neg \land Y \dashv \mathbf{Sets}_*(Y, \neg)):$ Sets, $X \land \neg$
Sets, $X \land \neg$
Sets, $X \land \neg$
Sets, $X \land \neg$
Sets, $X \land \neg$

witnessed by bijections

$$\operatorname{Hom}_{\mathsf{Sets}_*}(X \wedge Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z)),$$

 $\operatorname{Hom}_{\mathsf{Sets}_*}(X \wedge Y, Z) \cong \operatorname{Hom}_{\mathsf{Sets}_*}(X, \mathbf{Sets}_*(A, Z)),$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in Obj(Sets_*).$

00GG

3. Enriched Adjointness. We have Sets*-enriched adjunctions

$$(X \land \neg \dashv \mathbf{Sets}_*(X, \neg)) \colon \quad \mathbf{Sets}_* \underbrace{\bot}_{X \land \neg} \mathbf{Sets}_*,$$

$$(\neg \land Y \dashv \mathbf{Sets}_*(Y, \neg)) \colon \quad \mathbf{Sets}_* \underbrace{\bot}_{X \land \neg} \mathbf{Sets}_*,$$

$$\mathbf{Sets}_*(Y, \neg)$$

$$(- \land Y \dashv \mathbf{Sets}_*(Y, -)): \mathbf{Sets}_* \underbrace{\bot}_{\mathbf{Sets}_*(Y, -)} \mathbf{Sets}_*$$

witnessed by isomorphisms of pointed sets

$$\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Sets}_*(X, \mathsf{Sets}_*(Y, Z)),$$

 $\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Sets}_*(X, \mathsf{Sets}_*(A, Z)),$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathbf{Sets}_*)$.

PROOF 7.5.2.1.3 ► PROOF OF PROPOSITION 7.5.2.1.2

Item 1: Functoriality

This follows from Constructions With Sets, Item 1 of Proposition 4.3.5.1.2 and from the equalities

$$g \circ \Delta_{y_0} = \Delta_{z_0},$$

 $\Delta_{y_0} \circ f = \Delta_{y_0}$

for morphisms $f: (K, k_0) \to (X, x_0)$ and $g: (Y, y_0) \to (Z, z_0)$, which guarantee pre- and postcomposition by morphisms of pointed sets to also be morphisms of pointed sets.

Item 2: Adjointness

This is a repetition of Item 2 of Proposition 7.5.1.1.12, and is proved there.

Item 3: Enriched Adjointness

This is a repetition of Item 3 of Proposition 7.5.1.1.12, and is proved there.

00GH 7.5.3 The Monoidal Unit

00GJ DEFINITION 7.5.3.1.1 ► THE MONOIDAL UNIT OF ∧

The monoidal unit of the smash product of pointed sets is the functor

$$\mathbb{1}^{\mathsf{Sets}_*} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

defined by

$$\mathbb{1}_{\mathsf{Sets}_*} \stackrel{\text{def}}{=} S^0$$

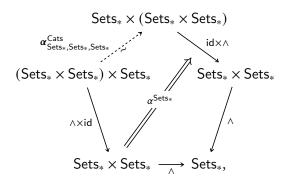
00GK 7.5.4 The Associator

00GL DEFINITION 7.5.4.1.1 ► THE ASSOCIATOR OF ∧

The **associator of the smash product of pointed sets** is the natural isomorphism

$$\alpha^{\mathsf{Sets}_*} : \wedge \circ (\wedge \times \mathsf{id}_{\mathsf{Sets}_*}) \stackrel{^{\sim}}{\Longrightarrow} \wedge \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \wedge) \circ \pmb{\alpha}^{\mathsf{Cats}}_{\mathsf{Sets}_*,\mathsf{Sets}_*,\mathsf{Sets}_*},$$

as in the diagram



whose component

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*} \colon (X \wedge Y) \wedge Z \xrightarrow{\sim} X \wedge (Y \wedge Z)$$

at (X, x_0) , (Y, y_0) , $(Z, z_0) \in \mathsf{Obj}(\mathsf{Sets}_*)$ is given by

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*}((x \wedge y) \wedge z) \stackrel{\mathrm{def}}{=} x \wedge (y \wedge z)$$

for each $(x \land y) \land z \in (X \land Y) \land Z$.

Well-Definedness

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Let [((x, y), z)] = [((x', y'), z')] be an element in $(X \wedge Y) \wedge Z$. Then either:

- 027N 1. We have x = x', y = y', and z = z'.
 - 2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$ or $z = z_0$.
 - (b) We have $x' = x_0$ or $y' = y_0$ or $z' = z_0$.

In the first case, $\alpha_{X,Y,Z}^{\mathsf{Sets}_*}$ clearly sends both elements to the same element in $X \wedge (Y \wedge Z)$. Meanwhile, in the latter case both elements are equal to the basepoint $(x_0 \wedge y_0) \wedge z_0$ of $(X \wedge Y) \wedge Z$, which gets sent to the basepoint $x_0 \wedge (y_0 \wedge z_0)$ of $X \wedge (Y \wedge Z)$.

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*}((x_0 \wedge y_0) \wedge z_0) \stackrel{\text{def}}{=} x_0 \wedge (y_0 \wedge z_0),$$

and thus $\alpha_{X,Y,Z}^{\mathsf{Sets}_*}$ is a morphism of pointed sets.

Invertibility

The inverse of $\alpha_{X,Y,Z}^{\mathsf{Sets}_*}$ is given by the morphism

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,-1} \colon X \wedge (Y \wedge Z) \xrightarrow{\sim} (X \wedge Y) \wedge Z$$

defined by

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,-1}(x \wedge (y \wedge z)) \stackrel{\mathrm{def}}{=} (x \wedge y) \wedge z$$

for each $x \land (y \land z) \in X \land (Y \land Z)$.

Naturality

We need to show that, given morphisms of pointed sets

$$f: (X, x_0) \to (X', x_0'),$$

$$g: (Y, y_0) \to (Y', y_0'),$$

$$h: (Z, z_0) \to (Z', z'_0)$$

the diagram

$$\begin{array}{c|c} (X \wedge Y) \wedge Z & \xrightarrow{(f \wedge g) \wedge h} & (X' \wedge Y') \wedge Z' \\ \\ \alpha^{\mathsf{Sets}_*}_{X,Y,Z} & & & & & & \\ X \wedge (Y \wedge Z) & \xrightarrow{f \wedge (g \wedge h)} & X' \wedge (Y' \wedge Z') \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$(x \wedge y) \wedge z \longmapsto (f(x) \wedge g(y)) \wedge h(z)$$

$$\downarrow \qquad \qquad \downarrow$$

$$x \wedge (y \wedge z) \longmapsto f(x) \wedge (g(y) \wedge h(z))$$

and hence indeed commutes, showing α^{Sets_*} to be a natural transformation.

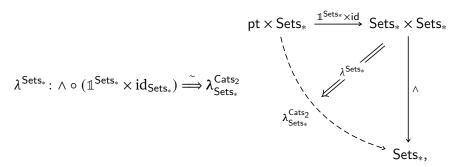
Being a Natural Isomorphism

Since α^{Sets_*} is natural and $\alpha^{\mathsf{Sets}_*,-1}$ is a componentwise inverse to α^{Sets_*} , it follows from Categories, Item 2 of Proposition 11.9.7.1.2 that $\alpha^{\mathsf{Sets}_*,-1}$ is also natural. Thus α^{Sets_*} is a natural isomorphism.

00GM 7.5.5 The Left Unitor

00GN DEFINITION 7.5.5.1.1 ► THE LEFT UNITOR OF ∧

The **left unitor of the smash product of pointed sets** is the natural isomorphism



whose component

$$\lambda_X^{\mathsf{Sets}_*} \colon S^0 \wedge X \xrightarrow{\sim} X$$

at $X \in \text{Obj}(\mathsf{Sets}_*)$ is given by

$$0 \land x \mapsto x_0,$$

$$1 \land x \mapsto x$$

for each $x \in X$.

PROOF 7.5.5.1.2 ► PROOF OF DEFINITION 7.5.5.1.1

Well-Definedness

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Let [(x, y)] = [(x', y')] be an element in $S^0 \wedge X$. Then either:

- 027S 1. We have x = x' and y = y'.
 - 2. Both of the following conditions are satisfied:
 - (a) We have x = 0 or $y = x_0$.
 - (b) We have x' = 0 or $y' = x_0$.

In the first case, $\lambda_X^{\mathsf{Sets}_*}$ clearly sends both elements to the same element in X. Meanwhile, in the latter case both elements are equal to the basepoint $0 \wedge x_0$ of $S^0 \wedge X$, which gets sent to the basepoint x_0 of X.

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\lambda_X^{\mathsf{Sets}_*}(0 \wedge x_0) \stackrel{\mathrm{def}}{=} x_0,$$

and thus $\lambda_X^{\mathsf{Sets}_*}$ is a morphism of pointed sets.

Invertibility

The inverse of $\lambda_X^{\mathsf{Sets}_*}$ is the morphism

$$\lambda_X^{\mathsf{Sets}_*,-1} \colon X \xrightarrow{\sim} S^0 \wedge X$$

defined by

$$\lambda_X^{\mathsf{Sets}_*,-1}(x) \stackrel{\mathsf{def}}{=} 1 \wedge x$$

for each $x \in X$. Indeed:

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1. Invertibility I. We have

$$\begin{split} [\lambda_X^{\mathsf{Sets}_*,-1} \circ \lambda_X^{\mathsf{Sets}_*}](0 \wedge x) &= \lambda_X^{\mathsf{Sets}_*,-1}(\lambda_X^{\mathsf{Sets}_*}(0 \wedge x)) \\ &= \lambda_X^{\mathsf{Sets}_*,-1}(x_0) \\ &= 1 \wedge x_0 \\ &= 0 \wedge x, \end{split}$$

and

$$\begin{split} \big[\lambda_X^{\mathsf{Sets}_*,-1} \circ \lambda_X^{\mathsf{Sets}_*}\big](1 \wedge x) &= \lambda_X^{\mathsf{Sets}_*,-1}(\lambda_X^{\mathsf{Sets}_*}(1 \wedge x)) \\ &= \lambda_X^{\mathsf{Sets}_*,-1}(x) \\ &= 1 \wedge x \end{split}$$

for each $x \in X$, and thus we have

$$\lambda_X^{\mathsf{Sets}_*,-1} \circ \lambda_X^{\mathsf{Sets}_*} = \mathrm{id}_{S^0 \wedge X} \,.$$

027X

2. Invertibility II. We have

$$\begin{split} [\lambda_X^{\mathsf{Sets}_*} \circ \lambda_X^{\mathsf{Sets}_*,-1}](x) &= \lambda_X^{\mathsf{Sets}_*} (\lambda_X^{\mathsf{Sets}_*,-1}(x)) \\ &= \lambda_X^{\mathsf{Sets}_*,-1} (1 \wedge x) \\ &= x \end{split}$$

for each $x \in X$, and thus we have

$$\lambda_X^{\mathsf{Sets}_*} \circ \lambda_X^{\mathsf{Sets}_*,-1} = \mathrm{id}_X \,.$$

This shows $\lambda_X^{\mathsf{Sets}_*}$ to be invertible.

Naturality

We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \to (Y, y_0),$$

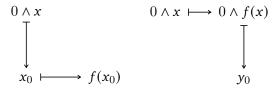
the diagram

$$S^{0} \wedge X \xrightarrow{\mathrm{id}_{S^{0}} \wedge f} S^{0} \wedge Y$$

$$\lambda_{X}^{\mathsf{Sets}_{*}} \downarrow \qquad \qquad \downarrow \lambda_{Y}^{\mathsf{Sets}_{*}}$$

$$X \xrightarrow{f} Y$$

commutes. Indeed, this diagram acts on elements as



and

$$\begin{array}{ccc}
1 \land x & \longmapsto & 1 \land f(x) \\
\downarrow & & \downarrow \\
x & \longmapsto & f(x)
\end{array}$$

and hence indeed commutes, showing $\lambda^{\mathsf{Sets}_*}$ to be a natural transformation.

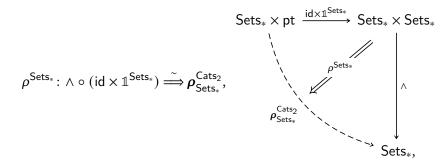
Being a Natural Isomorphism

Since $\lambda^{\mathsf{Sets}_*}$ is natural and $\lambda^{\mathsf{Sets}_*,-1}$ is a componentwise inverse to $\lambda^{\mathsf{Sets}_*}$, it follows from Categories, Item 2 of Proposition 11.9.7.1.2 that $\lambda^{\mathsf{Sets}_*,-1}$ is also natural. Thus $\lambda^{\mathsf{Sets}_*}$ is a natural isomorphism.

00GP 7.5.6 The Right Unitor

00GQ DEFINITION 7.5.6.1.1 ► THE RIGHT UNITOR OF ∧

The **right unitor of the smash product of pointed sets** is the natural isomorphism



whose component

$$\rho_X^{\mathsf{Sets}_*} : X \wedge S^0 \xrightarrow{\sim} X$$

at $X \in \text{Obj}(\mathsf{Sets}_*)$ is given by

$$x \wedge 0 \mapsto x_0,$$

 $x \wedge 1 \mapsto x$

for each $x \in X$.

PROOF 7.5.6.1.2 ► PROOF OF DEFINITION 7.5.6.1.1

Well-Definedness

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Let [(x, y)] = [(x', y')] be an element in $X \wedge S^0$. Then either:

- 027Y 1. We have x = x' and y = y'.
 - 2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or y = 0.
 - (b) We have $x' = x_0$ or y' = 0.

In the first case, $\rho_X^{\mathsf{Sets}_*}$ clearly sends both elements to the same element in X. Meanwhile, in the latter case both elements are equal to the basepoint $x_0 \wedge 0$ of $X \wedge S^0$, which gets sent to the basepoint x_0 of X.

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\rho_X^{\mathsf{Sets}_*}(x_0 \wedge 0) \stackrel{\mathrm{def}}{=} x_0,$$

and thus $\rho_{\rm X}^{{\sf Sets}_*}$ is a morphism of pointed sets.

Invertibility

The inverse of $\rho_{X}^{\mathsf{Sets}_*}$ is the morphism

$$\rho_X^{\mathsf{Sets}_*,-1} \colon X \xrightarrow{\sim} X \wedge S^0$$

defined by

$$\rho_X^{\mathsf{Sets}_*,-1}(x) \stackrel{\mathsf{def}}{=} x \wedge 1$$

for each $x \in X$. Indeed:

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1. Invertibility I. We have

$$\begin{split} [\rho_X^{\mathsf{Sets}_*,-1} \circ \rho_X^{\mathsf{Sets}_*}](x \wedge 0) &= \rho_X^{\mathsf{Sets}_*,-1}(\rho_X^{\mathsf{Sets}_*}(x \wedge 0)) \\ &= \rho_X^{\mathsf{Sets}_*,-1}(x_0) \\ &= x_0 \wedge 1 \\ &= x \wedge 0, \end{split}$$

and

$$\begin{split} [\rho_X^{\mathsf{Sets}_*,-1} \circ \rho_X^{\mathsf{Sets}_*}](x \wedge 1) &= \rho_X^{\mathsf{Sets}_*,-1}(\rho_X^{\mathsf{Sets}_*}(x \wedge 1)) \\ &= \rho_X^{\mathsf{Sets}_*,-1}(x) \\ &= x \wedge 1 \end{split}$$

for each $x \in X$, and thus we have

$$\rho_X^{\mathsf{Sets}_*,-1} \circ \rho_X^{\mathsf{Sets}_*} = \mathrm{id}_{X \wedge S^0}.$$

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2. Invertibility II. We have

$$\begin{split} [\rho_X^{\mathsf{Sets}_*} \circ \rho_X^{\mathsf{Sets}_*,-1}](x) &= \rho_X^{\mathsf{Sets}_*} (\rho_X^{\mathsf{Sets}_*,-1}(x)) \\ &= \rho_X^{\mathsf{Sets}_*,-1}(x \wedge 1) \\ &= x \end{split}$$

for each $x \in X$, and thus we have

$$\rho_{\scriptscriptstyle X}^{\mathsf{Sets}_*} \circ \rho_{\scriptscriptstyle X}^{\mathsf{Sets}_*,-1} = \mathrm{id}_{\scriptscriptstyle X}\,.$$

This shows $\rho_X^{\mathsf{Sets}_*}$ to be invertible.

Naturality

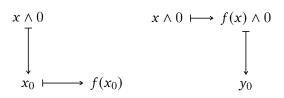
We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \to (Y, y_0),$$

the diagram

$$\begin{array}{ccc} X \wedge S^0 & \xrightarrow{f \wedge \mathrm{id}_{S^0}} & Y \wedge S^0 \\ \rho_X^{\mathsf{Sets}_*} & & & & \downarrow \rho_Y^{\mathsf{Sets}_*} \\ X & \xrightarrow{f} & & Y \end{array}$$

commutes. Indeed, this diagram acts on elements as



and

$$\begin{array}{ccc}
x \wedge 1 & \longmapsto f(x) \wedge 1 \\
\downarrow & & \downarrow \\
x & \longmapsto f(x)
\end{array}$$

and hence indeed commutes, showing ρ^{Sets_*} to be a natural transformation.

Being a Natural Isomorphism

Since ρ^{Sets_*} is natural and $\rho^{\mathsf{Sets}_*,-1}$ is a componentwise inverse to ρ^{Sets_*} , it follows from Categories, Item 2 of Proposition 11.9.7.1.2 that $\rho^{\mathsf{Sets}_*,-1}$ is also natural. Thus ρ^{Sets_*} is a natural isomorphism.

00GR 7.5.7 The Symmetry

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DEFINITION 7.5.7.1.1 ► THE SYMMETRY OF \land

The symmetry of the smash product of pointed sets is the natural isomorphism

$$\sigma^{\mathsf{Sets}_*} \colon \wedge \stackrel{\widetilde{\longrightarrow}}{\Longrightarrow} \wedge \circ \sigma^{\mathsf{Cats}_2}_{\mathsf{Sets}_*,\mathsf{Sets}_*},$$



whose component

$$\sigma_{X,Y}^{\mathsf{Sets}_*} \colon X \wedge Y \xrightarrow{\sim} Y \wedge X$$

at $X, Y \in Obj(Sets_*)$ is defined by

$$\sigma_{X,Y}^{\mathsf{Sets}_*}(x \wedge y) \stackrel{\mathrm{def}}{=} y \wedge x$$

for each $x \land y \in X \land Y$.

PROOF 7.5.7.1.2 ► PROOF OF DEFINITION 7.5.7.1.1

Well-Definedness

Let [(x, y)] = [(x', y')] be an element in $X \wedge Y$. Then either:

- 1. We have x = x' and y = y'.
- 2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$.
 - (b) We have $x' = x_0$ or $y' = y_0$.

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In the first case, $\sigma_X^{\mathsf{Sets}_*}$ clearly sends both elements to the same element in X. Meanwhile, in the latter case both elements are equal to the basepoint $x_0 \wedge y_0$ of $X \wedge Y$, which gets sent to the basepoint $y_0 \wedge x_0$ of $Y \wedge X$.

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\sigma_X^{\mathsf{Sets}_*}(x_0 \wedge y_0) \stackrel{\text{def}}{=} y_0 \wedge x_0,$$

and thus $\sigma_X^{\mathsf{Sets}_*}$ is a morphism of pointed sets.

Invertibility

The inverse of $\sigma_{X,Y}^{\mathsf{Sets}_*}$ is given by the morphism

$$\sigma_{X,Y}^{\mathsf{Sets}_*,-1} \colon Y \wedge X \xrightarrow{\sim} X \wedge Y$$

defined by

$$\sigma_{X,Y}^{\mathsf{Sets}_*,-1}(y \wedge x) \stackrel{\mathsf{def}}{=} x \wedge y$$

for each $y \land x \in Y \land X$.

Naturality

We need to show that, given morphisms of pointed sets

$$f: (X, x_0) \to (A, a_0),$$

 $g: (Y, y_0) \to (B, b_0)$

the diagram

$$\begin{array}{c|c} X \wedge Y & \xrightarrow{f \wedge g} & A \wedge B \\ \sigma_{X,Y}^{\mathsf{Sets}*} & & & \int_{\sigma_{A,B}}^{\mathsf{Sets}*} \\ Y \wedge X & \xrightarrow{g \wedge f} & B \wedge A \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$x \wedge y \longmapsto f(x) \wedge g(y)$$

$$\downarrow \qquad \qquad \downarrow$$

$$y \wedge x \longmapsto g(y) \wedge f(x)$$

and hence indeed commutes, showing σ^{Sets_*} to be a natural transformation.

Being a Natural Isomorphism

Since σ^{Sets_*} is natural and $\sigma^{\mathsf{Sets}_*,-1}$ is a componentwise inverse to σ^{Sets_*} , it follows from Categories, Item 2 of Proposition 11.9.7.1.2 that $\sigma^{\mathsf{Sets}_*,-1}$ is also natural. Thus σ^{Sets_*} is a natural isomorphism.

00GT 7.5.8 The Diagonal

00GU

DEFINITION 7.5.8.1.1 ► THE DIAGONAL OF ∧

The **diagonal of the smash product of pointed sets** is the natural transformation

$$\Delta^{\wedge} \colon \operatorname{id}_{\mathsf{Sets}_*} \Longrightarrow \wedge \circ \Delta^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}, \qquad \underbrace{\Delta^{\wedge}_{\mathsf{Sets}_*}}^{\operatorname{id}_{\mathsf{Sets}_*}} \to \mathsf{Sets}_*$$

$$\mathsf{Sets}_* \wedge \mathsf{Sets}_*, \qquad \mathsf{Sets}_* \wedge \mathsf{Sets}_*,$$

whose component

$$\Delta_X^{\wedge} : (X, x_0) \to (X \wedge X, x_0 \wedge x_0)$$

at $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$ is given by the composition

$$(X, x_0) \xrightarrow{\Delta_X^{\wedge}} (X \times X, (x_0, x_0))$$

$$\longrightarrow ((X \times X)/\sim, [(x_0, x_0)])$$

$$\stackrel{\text{def}}{=} (X \wedge X, x_0 \wedge x_0)$$

in Sets*, and thus by

$$\Delta_X^{\wedge}(x) \stackrel{\text{def}}{=} x \wedge x$$

for each $x \in X$.

PROOF 7.5.8.1.2 ▶ PROOF OF DEFINITION 7.5.8.1.1

Being a Morphism of Pointed Sets

We have

$$\Delta_X^{\wedge}(x_0) \stackrel{\text{def}}{=} x_0 \wedge x_0,$$

and thus Δ_X^{\wedge} is a morphism of pointed sets.

Naturality

We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$X \xrightarrow{f} Y$$

$$\downarrow^{\Delta_X^{\wedge}} \downarrow \qquad \downarrow^{\Delta_Y^{\wedge}}$$

$$X \wedge X \xrightarrow{f \wedge f} Y \wedge Y$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
x & \longmapsto & f(x) \\
\downarrow & & \downarrow \\
x \land x & \longmapsto & f(x) \land f(x)
\end{array}$$

and hence indeed commutes, showing Δ^{\wedge} to be natural.

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PROPOSITION 7.5.8.1.3 ► PROPERTIES OF THE DIAGONAL OF ∧

Let $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$.

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1. Monoidality. The diagonal

$$\Delta^{\wedge} \colon \operatorname{id}_{\mathsf{Sets}_*} \Longrightarrow \wedge \circ \Delta^{\mathsf{Cats}_2}_{\mathsf{Sets}_*},$$

of the smash product of pointed sets is a monoidal natural transformation:

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(a) Compatibility With Strong Monoidality Constraints. For each $(X, x_0), (Y, y_0) \in \mathsf{Obj}(\mathsf{Sets}_*)$, the diagram

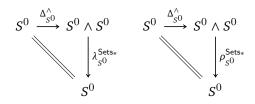
$$X \wedge Y \xrightarrow{\Delta_X^{\wedge} \wedge \Delta_Y^{\wedge}} (X \wedge X) \wedge (Y \wedge Y)$$

$$\downarrow \lambda \qquad \qquad \downarrow \lambda \qquad$$

commutes.

00GY

(b) Compatibility With Strong Unitality Constraints. The diagrams



commute, i.e. we have

$$\begin{split} \Delta_{S^0}^{\wedge} &= \lambda_{S^0}^{\mathsf{Sets}_*,-1} \\ &= \rho_{S^0}^{\mathsf{Sets}_*,-1}, \end{split}$$

where we recall that the equalities

$$\begin{split} \lambda_{\mathcal{S}^0}^{\mathsf{Sets}_*} &= \rho_{\mathcal{S}^0}^{\mathsf{Sets}_*}, \\ \lambda_{\mathcal{S}^0}^{\mathsf{Sets}_*, -1} &= \rho_{\mathcal{S}^0}^{\mathsf{Sets}_*, -1} \end{split}$$

are always true in any monoidal category by Monoidal Categories, ?? of ??.

00GZ

2. The Diagonal of the Unit. The component

$$\Delta_{S^0}^{\wedge} : S^0 \xrightarrow{\sim} S^0 \wedge S^0$$

of Δ^{\wedge} at S^0 is an isomorphism.

PROOF 7.5.8.1.4 ► PROOF OF PROPOSITION 7.5.8.1.3

Item 1: Monoidality

We claim that Δ^{\wedge} is indeed monoidal:

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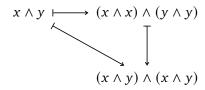
1. *Item 1a*: Compatibility With Strong Monoidality Constraints: We need to show that the diagram

$$X \wedge Y \xrightarrow{\Delta_X^{\wedge} \wedge \Delta_Y^{\wedge}} (X \wedge X) \wedge (Y \wedge Y)$$

$$\downarrow^{\lambda}$$

$$(X \wedge Y) \wedge (X \wedge Y)$$

commutes. Indeed, this diagram acts on elements as



and hence indeed commutes.

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2. *Item 1b*: *Compatibility With Strong Unitality Constraints*: As shown in the proof of Definition 7.5.5.1.1, the inverse of the left unitor of Sets* with respect to to the smash product of pointed sets at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by

$$\lambda_X^{\mathsf{Sets}_*,-1}(x) \stackrel{\mathrm{def}}{=} 1 \wedge x$$

for each $x \in X$, so when $X = S^0$, we have

$$\begin{split} &\lambda_{S^0}^{\mathsf{Sets}_*,-1}(0) \stackrel{\text{def}}{=} 1 \wedge 0, \\ &\lambda_{S^0}^{\mathsf{Sets}_*,-1}(1) \stackrel{\text{def}}{=} 1 \wedge 1. \end{split}$$

But since $1 \land 0 = 0 \land 0$ and

$$\Delta_{S^0}^{\wedge}(0) \stackrel{\text{def}}{=} 0 \wedge 0,$$

$$\Delta_{S^0}^{\wedge}(1) \stackrel{\text{def}}{=} 1 \wedge 1,$$

it follows that we indeed have $\Delta_{S^0}^{\wedge} = \lambda_{S^0}^{\mathsf{Sets}_*,-1}.$

This finishes the proof.

Item 2: The Diagonal of the Unit

This follows from Item 1 and the invertibility of the left/right unitor of Sets_∗ with respect to ∧, proved in the proof of Definition 7.5.5.1.1 for the left unitor or the proof of Definition 7.5.6.1.1 for the right unitor.

00H0 7.5.9 The Monoidal Structure on Pointed Sets Associated to ∧

00H1 PROPOSITION 7.5.9.1.1 ➤ THE MONOIDAL STRUCTURE ON POINTED SETS ASSOCIATED TO ∧

The category Sets_{*} admits a closed monoidal category with diagonals structure consisting of:

- *The Underlying Category*. The category Sets* of pointed sets.
- The Monoidal Product. The smash product functor

$$\land : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

of Item 1 of Proposition 7.5.1.1.12.

• The Internal Hom. The internal Hom functor

Sets_{*}:
$$Sets_*^{op} \times Sets_* \rightarrow Sets_*$$

of Item 1 of Proposition 7.5.2.1.2.

• The Monoidal Unit. The functor

$$\mathbb{1}^{\mathsf{Sets}_*} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

of Definition 7.5.3.1.1.

• The Associators. The natural isomorphism

$$\alpha^{\mathsf{Sets}_*} \colon \wedge \circ (\wedge \times \mathsf{id}_{\mathsf{Sets}_*}) \stackrel{^{\sim}}{\Longrightarrow} \wedge \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \wedge) \circ \pmb{\alpha}^{\mathsf{Cats}}_{\mathsf{Sets}_*,\mathsf{Sets}_*,\mathsf{Sets}_*}$$

of Definition 7.5.4.1.1.

• *The Left Unitors*. The natural isomorphism

$$\lambda^{\mathsf{Sets}_*} : \wedge \circ (\mathbb{1}^{\mathsf{Sets}_*} \times id_{\mathsf{Sets}_*}) \stackrel{\sim}{\Longrightarrow} \lambda^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}$$

of Definition 7.5.5.1.1.

• The Right Unitors. The natural isomorphism

$$\rho^{\mathsf{Sets}_*} \colon \wedge \circ (\mathsf{id} \times \mathbb{1}^{\mathsf{Sets}_*}) \stackrel{\widetilde{\longrightarrow}}{\Longrightarrow} \rho^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}$$

of Definition 7.5.6.1.1.

• The Symmetry. The natural isomorphism

$$\sigma^{\mathsf{Sets}_*} \colon \wedge \stackrel{\widetilde{\longrightarrow}}{\Longrightarrow} \wedge \circ \sigma^{\mathsf{Cats}_2}_{\mathsf{Sets}_*,\mathsf{Sets}_*}$$

of Definition 7.5.7.1.1.

• The Diagonals. The monoidal natural transformation

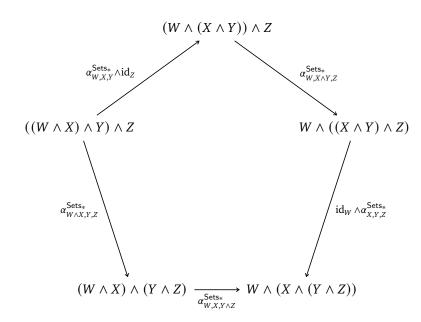
$$\Delta^{\wedge} \colon \operatorname{id}_{\mathsf{Sets}_*} \Longrightarrow \wedge \circ \Delta^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}$$

of Definition 7.5.8.1.1.

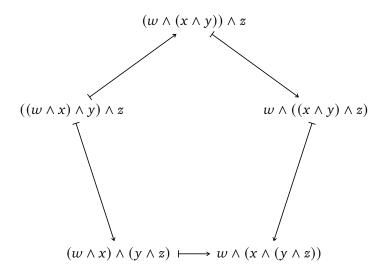
PROOF 7.5.9.1.2 ► PROOF OF PROPOSITION 7.5.9.1.1

The Pentagon Identity

Let (W, w_0) , (X, x_0) , (Y, y_0) and (Z, z_0) be pointed sets. We have to show that the diagram



commutes. Indeed, this diagram acts on elements as



and thus we see that the pentagon identity is satisfied.

The Triangle Identity

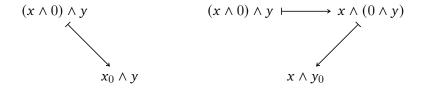
Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$(X \wedge S^{0}) \wedge Y \xrightarrow{\alpha_{X,S^{0},Y}^{\mathsf{Sets}_{*}}} X \wedge (S^{0} \wedge Y)$$

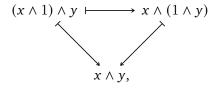
$$\rho_{X}^{\mathsf{Sets}_{*}} \wedge \mathrm{id}_{Y} \qquad \qquad \mathrm{id}_{X} \wedge \lambda_{Y}^{\mathsf{Sets}_{*}}$$

$$X \wedge Y$$

commutes. Indeed, this diagram acts on elements as



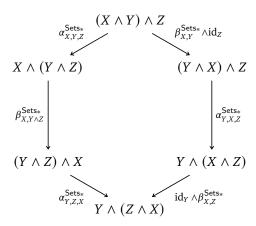
and



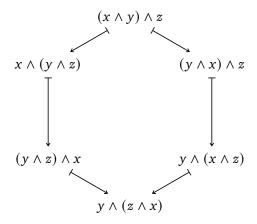
and thus we see that the triangle identity is satisfied.

The Left Hexagon Identity

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets. We have to show that the diagram



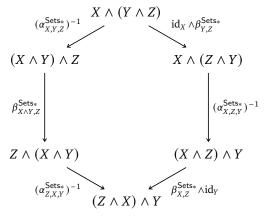
commutes. Indeed, this diagram acts on elements as



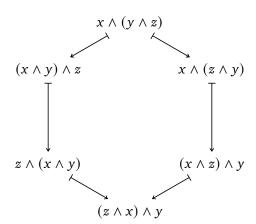
and thus we see that the left hexagon identity is satisfied.

The Right Hexagon Identity

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets. We have to show that the diagram



commutes. Indeed, this diagram acts on elements as



and thus we see that the right hexagon identity is satisfied.

Monoidal Closedness

This follows from Item 2 of Proposition 7.5.1.1.12.

Existence of Monoidal Diagonals

This follows from Items 1 and 2 of Proposition 7.5.8.1.3.

OLY 7.5.10 The Universal Property of $(Sets_*, \land, S^0)$

01 V7 THEOREM 7.5.10.1.1 ▶ THE UNIVERSAL PROPERTY OF (Sets_{*}, \wedge , S^0)

The symmetric monoidal structure on the category Sets_{*} of Proposition 7.5.9.1.1 is uniquely determined by the following requirements:

1. Existence of an Internal Hom. The tensor product

$$\otimes_{\mathsf{Sets}}: \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

of Sets_{*} admits an internal Hom $[-1, -2]_{Sets_*}$.

2. The Unit Object Is S^0 . We have $\mathbb{1}_{\mathsf{Sets}_*} \cong S^0$.

More precisely, the full subcategory of the category $\mathcal{M}^{cld}_{\mathbb{E}_{\infty}}(\mathsf{Sets}_*)$ of $\ref{eq:spanned}$ spanned by the closed symmetric monoidal categories (Sets_* , $\otimes_{\mathsf{Sets}_*}$, $[-_1, -_2]_{\mathsf{Sets}_*}$, $\mathbb{1}_{\mathsf{Sets}_*}$, $\lambda^{\mathsf{Sets}_*}$, ρ^{Sets_*} , σ^{Sets_*}) satisfying Items 1 and 2 is contractible (i.e. equivalent to the punctual category).

PROOF 7.5.10.1.2 ► PROOF OF THEOREM 7.5.10.1.1

Unwinding the Statement

01W0

01W1

Let $(Sets_*, \otimes_{Sets_*}, [-_1, -_2]_{Sets_*}, \mathbb{1}_{Sets_*}, \lambda', \rho', \sigma')$ be a closed symmetric monoidal category satisfying Items 1 and 2. We need to show that the identity functor

$$id_{\mathsf{Sets}_*} \colon \mathsf{Sets}_* \to \mathsf{Sets}_*$$

admits a unique closed symmetric monoidal functor structure

making it into a symmetric monoidal strongly closed isomorphism of categories from (Sets*, \otimes_{Sets_*} , $[-_1, -_2]_{Sets_*}$, $\mathbb{1}_{Sets_*}$, λ' , ρ' , σ') to the closed symmetric monoidal category (Sets*, \times , Sets*($-_1$, $-_2$), $\mathbb{1}_{Sets_*}$, λ^{Sets_*} , ρ^{Sets_*} , σ^{Sets_*}) of Proposition 7.5.9.1.1.

Constructing an Isomorphism $[-1, -2]_{Sets_*} \cong Sets_*(-1, -2)$

By ??, we have a natural isomorphism

$$\mathsf{Sets}_*(S^0, [-1, -2]_{\mathsf{Sets}_*}) \cong \mathsf{Sets}_*(-1, -2).$$

By Pointed Sets, Item 4 of Proposition 6.1.4.1.1, we also have a natural isomorphism

$$\mathsf{Sets}_*(S^0, [-1, -2]_{\mathsf{Sets}_*}) \cong [-1, -2]_{\mathsf{Sets}_*}.$$

Composing both natural isomorphisms, we obtain a natural isomorphism

$$\mathsf{Sets}_*(-1, -2) \cong [-1, -2]_{\mathsf{Sets}_*}.$$

Given $X, Y \in Obj(Sets_*)$, we will write

$$id_{X,Y}^{Hom}$$
: Sets_{*} $(X,Y) \xrightarrow{\sim} [X,Y]_{Sets_*}$

for the component of this isomorphism at (X, Y).

Constructing an Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

Since $\otimes_{\mathsf{Sets}_*}$ is adjoint in each variable to $[-_1, -_2]_{\mathsf{Sets}_*}$ by assumption and \wedge is adjoint in each variable to $\mathsf{Sets}_*(-_1, -_2)$ by Constructions With Sets, Item 2 of Proposition 4.3.5.1.2, uniqueness of adjoints (??) gives us natural isomorphisms

$$X \otimes_{\mathsf{Sets}_*} - \cong X \wedge -,$$

 $- \otimes_{\mathsf{Sets}_*} Y \cong Y \wedge -.$

By ??, we then have $\otimes_{\mathsf{Sets}_*} \cong \wedge$. We will write

$$\mathrm{id}_{\mathsf{Sets}_*|X,Y}^{\otimes} \colon X \otimes_{\mathsf{Sets}_*} Y \xrightarrow{\sim} X \wedge Y$$

for the component of this isomorphism at (X, Y).

Alternative Construction of an Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

Alternatively, we may construct a natural isomorphism $\otimes_{\mathsf{Sets}_*} \cong \wedge$ as follows:

1. Let $X \in Obi(Sets_*)$.

01W2

01W3

2. Since $\otimes_{\mathsf{Sets}_*}$ is part of a closed monoidal structure, it preserves colimits in each variable by $\ref{eq:sets}$.

01W4

3. Since $X \cong \bigvee_{x \in X^-} S^0$ and $\bigotimes_{\mathsf{Sets}_*}$ preserves colimits in each variable, we have

$$X \otimes_{\mathsf{Sets}_*} Y \cong (\bigvee_{x \in X^-} S^0) \otimes_{\mathsf{Sets}_*} Y$$

$$\cong \bigvee_{x \in X^-} (S^0 \otimes_{\mathsf{Sets}_*} Y)$$

$$\cong \bigvee_{x \in X^-} Y$$

$$\cong \bigvee_{x \in X^-} S^0 \wedge Y$$

$$\cong (\bigvee_{x \in X^-} S^0) \wedge Y$$

$$\cong X \wedge Y,$$

naturally in $Y \in \text{Obj}(\mathsf{Sets}_*)$, where we have used that S^0 is the monoidal unit for $\otimes_{\mathsf{Sets}_*}$. Thus $X \otimes_{\mathsf{Sets}_*} - \cong X \wedge -$ for each $X \in \mathsf{Obj}(\mathsf{Sets}_*)$.

01W5

- 4. Similarly, $\otimes_{\mathsf{Sets}_*} Y \cong \wedge Y$ for each $Y \in \mathsf{Obj}(\mathsf{Sets}_*)$.
- 01W6

Below, we'll show that if a natural isomorphism $\otimes_{\mathsf{Sets}_*} \cong \wedge$ exists, then it must be unique. This will show that the isomorphism constructed above is equal to the isomorphism $\mathrm{id}_{\mathsf{Sets}_*|X,Y}^\otimes: X \otimes_{\mathsf{Sets}_*} Y \to X \wedge Y$ from before.

Constructing an Isomorphism $id_1^{\otimes}: \mathbb{1}_{Sets_*} \to S^0$

5. By ??, we then have $\otimes_{\mathsf{Sets}_*} \cong \wedge$.

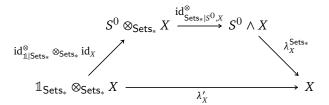
We define an isomorphism $\mathrm{id}_{\mathbb{1}}^{\otimes}:\mathbb{1}_{\mathsf{Sets}_*}\to S^0$ as the composition

$$\mathbb{1}_{\mathsf{Sets}_*} \overset{\rho_{\mathsf{1Sets}_*}^{\mathsf{Sets}_*,-1}}{\overset{\circ}{\to}} \mathbb{1}_{\mathsf{Sets}_*} \wedge S^0 \overset{\mathsf{id}_{\mathsf{Sets}_*}^{\otimes,-1}}{\overset{\circ}{\to}} \mathbb{1}_{\mathsf{Sets}_*} \otimes_{\mathsf{Sets}_*} S^0 \overset{\lambda_{\mathsf{S}^0}'}{\overset{\circ}{\to}} S^0$$

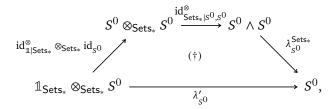
in Sets*.

Monoidal Left Unity of the Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

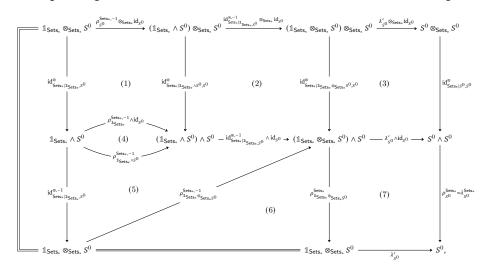
We have to show that the diagram



commutes. To this end, we will first show that the diagram



corresponding to the case $X = S^0$, commutes. Indeed, consider the diagram

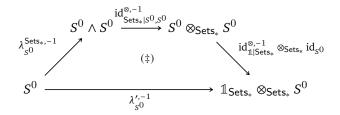


whose boundary diagram corresponds to the diagram (\dagger) above. In this diagram:

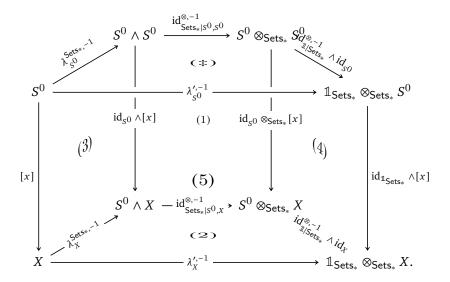
- Subdiagrams (1), (2), and (3) commute by the naturality of $\mathrm{id}_{\mathsf{Sets}_*}^\otimes$.
- Subdiagram (4) commutes by ??.

- Subdiagram (5) commutes by the naturality of $\rho^{\text{Sets}_*,-1}$.
- Subdiagram (6) commutes trivially.
- Subdiagram (7) commutes by the naturality of ρ^{Sets_*} , where the equality $\rho^{\mathsf{Sets}_*}_{S^0} = \lambda^{\mathsf{Sets}_*}_{S^0}$ comes from ??.

Since all subdiagrams commute, so does the boundary diagram, i.e. the diagram (\dagger) above. As a result, the diagram



also commutes. Now, let $X \in \text{Obj}(\mathsf{Sets}_*)$, let $x \in X$, and consider the diagram

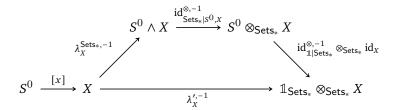


Since:

- Subdiagram (5) commutes by the naturality of λ'^{-1} .
- Subdiagram (‡) commutes, as proved above.

- Subdiagram (4) commutes by the naturality of $id_{1|Sets_*}^{\otimes,-1}$.
- Subdiagram (1) commutes by the naturality of $id_{Sets_*}^{\otimes,-1}$.
- Subdiagram (3) commutes by the naturality of $\lambda^{Sets_*,-1}$.

it follows that the diagram



Here's a step-by-step showcase of this argument: [Link]. We then have

$$\begin{split} \lambda_X^{\prime,-1}(x) &= [\lambda_X^{\prime,-1} \circ [x]](1) \\ &= [(\mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes,-1} \wedge \mathrm{id}_X) \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes,-1} \circ \lambda_X^{\mathsf{Sets}_*,-1} \circ [x]](1) \\ &= [(\mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes,-1} \wedge \mathrm{id}_X) \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes,-1} \circ \lambda_X^{\mathsf{Sets}_*,-1}](x) \end{split}$$

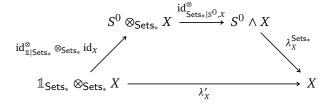
for each $x \in X$, and thus we have

$$\lambda_X^{\prime,-1} = (\mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes,-1} \wedge \mathrm{id}_X) \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes,-1} \circ \lambda_X^{\mathsf{Sets}_*,-1}.$$

Taking inverses then gives

$$\lambda_X' = \lambda_X^{\mathsf{Sets}_*} \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes} \circ (\mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes} \wedge \mathrm{id}_X),$$

showing that the diagram



indeed commutes.

Braidedness of the Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

We have to show that the diagram

$$\begin{array}{ccc} X \otimes_{\mathsf{Sets}_*} Y & \xrightarrow{\mathsf{id}_{\mathsf{Sets}_*|X,Y}^{\otimes}} & X \wedge Y \\ & \sigma'_{X,Y} & & & & \int \sigma^{\mathsf{Sets}_*}_{X,Y} \\ Y \otimes_{\mathsf{Sets}_*} X & \xrightarrow{\mathsf{id}_{\mathsf{Sets}_*|Y,X}^{\otimes}} & Y \wedge X \end{array}$$

commutes. To this end, we will first show that the diagram

$$S^{0} \otimes_{\mathsf{Sets}_{*}} S^{0} \xrightarrow{\mathsf{id}_{\mathsf{Sets}_{*}\mid S^{0},S^{0}}} S^{0} \wedge S^{0}$$

$$\sigma'_{S^{0},S^{0}} \downarrow \qquad (\dagger) \qquad \qquad \downarrow \sigma^{\mathsf{Sets}_{*}}_{S^{0},S^{0}}$$

$$S^{0} \otimes_{\mathsf{Sets}_{*}} S^{0} \xrightarrow{\mathsf{id}_{\mathsf{Sets}_{*}\mid S^{0},S^{0}}} S^{0} \wedge S^{0}$$

commutes. To that end, we will first show that the diagram

$$S^{0} \otimes_{\mathsf{Sets}_{*}} \mathbb{1}_{\mathsf{Sets}_{*}} \xrightarrow{\mathrm{id}_{\mathsf{Sets}_{*}\mid S^{0},\mathbb{1}_{\mathsf{Sets}_{*}}}^{\otimes}} S^{0} \wedge \mathbb{1}_{\mathsf{Sets}_{*}}$$

$$\sigma'_{S^{0},\mathbb{1}_{\mathsf{Sets}_{*}}} \downarrow \qquad \qquad (\ddagger) \qquad \qquad \downarrow \sigma^{\mathsf{Sets}_{*}}_{S^{0},\mathbb{1}_{\mathsf{Sets}_{*}}}$$

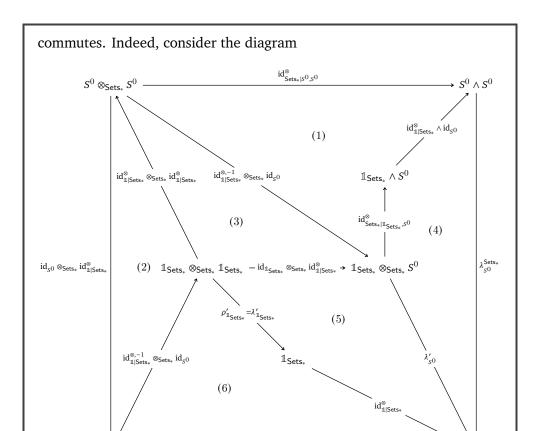
$$\mathbb{1}_{\mathsf{Sets}_{*}} \otimes_{\mathsf{Sets}_{*}} S^{0} \xrightarrow{\mathrm{id}_{\mathsf{Sets}_{*}\mid \mathbb{1}_{\mathsf{Sets}_{*}},S^{0}}^{\otimes}} \mathbb{1}_{\mathsf{Sets}_{*}} \wedge S^{0}$$

commutes, and, to this end, we will first show that the diagram

$$S^{0} \otimes_{\mathsf{Sets}_{*}} S^{0} \xrightarrow{\mathrm{id}_{\mathsf{Sets}_{*}\mid S^{0},S^{0}}} S^{0} \wedge S^{0}$$

$$\mathrm{id}_{S^{0}} \otimes_{\mathsf{Sets}_{*}} \mathrm{id}_{\mathsf{Sets}_{*}\mid 1}^{\otimes} \qquad (\S) \qquad \bigvee_{\lambda_{S^{0}}^{\mathsf{Sets}_{*}}} \lambda_{S^{0}}^{\mathsf{Sets}_{*}}$$

$$S^{0} \otimes_{\mathsf{Sets}_{*}} \mathbb{1}_{\mathsf{Sets}_{*}} \xrightarrow{\rho_{S^{0}}'} S^{0}$$



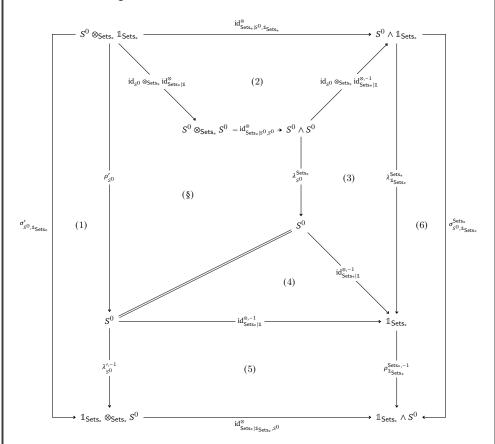
whose boundary diagram corresponds to diagram (§) above. Since:

• Subdiagram (1) commutes by the naturality of $id_{\mathsf{Sets}_*}^{\otimes}$;

 $S^0 \otimes_{\mathsf{Sets}_*} \mathbb{1}_{\mathsf{Sets}_*}$

- Subdiagrams (2) and (3) commute by the functoriality of \otimes ;
- Subdiagram (4) commutes by the left monoidal unity of $(id^{\otimes}, id^{\otimes}_{1})$, which we proved above;
- Subdiagram (5) commutes by the naturality of λ' ;
- Subdiagram (6) commutes by the naturality of ρ' , where the equality $\rho'_{\mathbb{1}_{\mathsf{Sets}_*}} = \lambda'_{\mathbb{1}_{\mathsf{Sets}_*}}$ comes from $\ref{eq:substant}$?

it follows that the boundary diagram, i.e. diagram (\S), also commutes. Next, consider the diagram

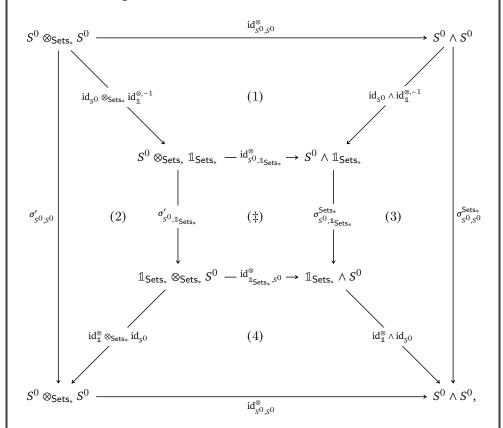


whose boundary diagram corresponds to the diagram (‡) above. Since:

- Subdiagrams (1) and (6) commute by ??;
- Subdiagram (2) commutes by the naturality of $\mathrm{id}_{\mathsf{Sets}_*}^\otimes;$
- Subdiagram (§) commutes, as was shown above;
- Subdiagram (3) commutes by the naturality of $\lambda^{\mathsf{Sets}_*}$;
- Subdiagram (4) commutes trivially;

Subdiagram (5) commutes by Constructions With Monoidal Categories, Item 2c of Item 2 of Proposition 13.1.1.1.4, whose proof uses only the left monoidal unity of (id[®], id[®]₁), which has been proven above;

it follows that the boundary diagram, i.e. diagram (\ddagger) , also commutes. Next, consider the diagram



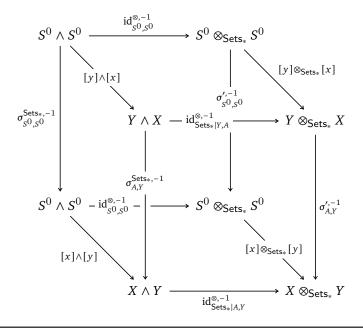
whose boundary diagram corresponds to the diagram (†). Since:

- Subdiagram (1) commutes by the naturality of $id_{\mathsf{Sets}_*}^{\otimes}$;
- Subdiagram (2) commutes by the naturality of σ' and the fact that id_1^{\otimes} is invertible;
- Subdiagram (‡) commutes as proved above;

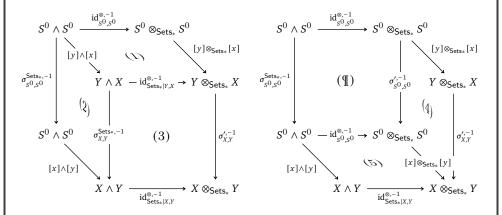
- Subdiagram (3) commutes by the naturality of σ^{Sets_*} and the fact that id_1^\otimes is invertible;
- Subdiagram (4) commutes by the naturality of id_{Sets},;

it follows that the boundary diagram, i.e. diagram (\dagger) also commutes. Taking inverses for the diagram (\dagger) , we see that the diagram

commutes as well. Now, let $X, Y \in \text{Obj}(\mathsf{Sets}_*)$, let $x \in X$, let $y \in Y$, and consider the diagram



which we partition into subdiagrams as follows:



Since:

- Subdiagram (2) commutes by the naturality of $\sigma^{Sets_*,-1}$.
- Subdiagram (5) commutes by the naturality of $id^{\otimes,-1}$.
- Subdiagram (¶) commutes, as proved above.
- Subdiagram (4) commutes by the naturality of σ'^{-1} .
- Subdiagram (1) commutes by the naturality of $id^{\otimes,-1}$.

it follows that the diagram

$$S^{0} \wedge S^{0}$$

$$Y \wedge X \xrightarrow{id_{\mathsf{Sets}_{*}|Y,X}^{\otimes}} Y \otimes_{\mathsf{Sets}_{*}} X$$

$$\sigma_{X,Y}^{\mathsf{Sets}_{*}} \downarrow \qquad \qquad \downarrow \sigma_{X,Y}'$$

$$X \wedge Y \xrightarrow{id_{\mathsf{Sets}_{*}|X,Y}^{\otimes}} X \otimes_{\mathsf{Sets}_{*}} Y$$
then have

commutes. We then have

$$[\operatorname{id}_{\mathsf{Sets}_*|X,Y}^{\otimes,-1} \circ \sigma_{X,Y}^{\mathsf{Sets}_*,-1}](y,x) = [\operatorname{id}_{\mathsf{Sets}_*|X,Y}^{\otimes,-1} \circ \sigma_{X,Y}^{\mathsf{Sets}_*,-1} \circ ([y] \wedge [x])](1,1)$$

$$\begin{split} &= [\sigma_{X,Y}^{\prime,-1} \circ \mathrm{id}_{\mathsf{Sets}_*|Y,X}^{\otimes,-1} \circ ([y] \wedge [x])](1,1) \\ &= [\sigma_{X,Y}^{\prime,-1} \circ \mathrm{id}_{\mathsf{Sets}_*|Y,X}^{\otimes,-1}](y,x) \end{split}$$

for each $(y, x) \in Y \land X$, and thus we have

$$id_{\mathsf{Sets}_*|X,Y}^{\otimes,-1} \circ \sigma_{X,Y}^{\mathsf{Sets}_*,-1} = \sigma_{X,Y}'^{,-1} \circ id_{\mathsf{Sets}_*|Y,X}^{\otimes,-1}.$$

Taking inverses then gives

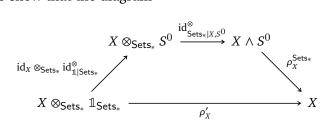
$$\sigma_{X,Y}^{\mathsf{Sets}_*} \circ \mathrm{id}_{\mathsf{Sets}_*|X,Y}^{\otimes} = \mathrm{id}_{\mathsf{Sets}_*|Y,X}^{\otimes} \circ \sigma_{X,Y}',$$

showing that the diagram

indeed commutes.

Monoidal Right Unity of the Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

We have to show that the diagram



commutes. To this end, we will first show that the diagram

$$S^{0} \otimes_{\mathsf{Sets}_{*}} S^{0} \xrightarrow{\mathsf{id}_{\mathsf{Sets}_{*}|S^{0},S^{0}}^{\mathsf{id}_{\mathsf{Sets}_{*}|S^{0},S^{0}}^{\otimes}}} S^{0} \wedge S^{0}$$

$$\downarrow^{\mathsf{id}_{\mathbb{1}|\mathsf{Sets}_{*}}^{\otimes} \otimes_{\mathsf{Sets}_{*}} \mathsf{id}_{S^{0}}} (\dagger)$$

$$S^{0} \otimes_{\mathsf{Sets}_{*}} \mathbb{1}_{\mathsf{Sets}_{*}} \xrightarrow{\rho'_{S^{0}}} S^{0} \wedge S^{0}$$

corresponding to the case $X = S^0$, commutes. First, notice that we may write

$$\sigma'_{S^0,\mathbb{1}_{\mathsf{Sets}_*}}\colon S^0\otimes_{\mathsf{Sets}_*}\mathbb{1}_{\mathsf{Sets}_*}\to\mathbb{1}_{\mathsf{Sets}_*}\otimes_{\mathsf{Sets}_*}S^0$$

as the composition

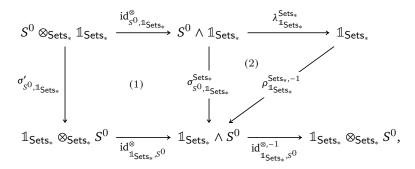
$$S^{0} \otimes_{\mathsf{Sets}_{*}} \mathbb{1}_{\mathsf{Sets}_{*}} \xrightarrow{\mathrm{id}_{\mathsf{S}^{0},\mathbb{1}_{\mathsf{Sets}_{*}}}^{\otimes}} S^{0} \wedge \mathbb{1}_{\mathsf{Sets}_{*}}$$

$$\xrightarrow{\lambda_{\mathsf{1}_{\mathsf{Sets}_{*}}}^{\mathsf{Sets}_{*}}} \mathbb{1}_{\mathsf{Sets}_{*}}$$

$$\xrightarrow{\rho_{\mathsf{1}_{\mathsf{Sets}_{*}}}^{\mathsf{Sets}_{*}}} \mathbb{1}_{\mathsf{Sets}_{*}} \wedge S^{0}$$

$$\xrightarrow{\mathrm{id}_{\mathsf{Sets}_{*}}^{\otimes,-1}} \mathbb{1}_{\mathsf{Sets}_{*}} \otimes_{\mathsf{Sets}_{*}} S^{0}.$$

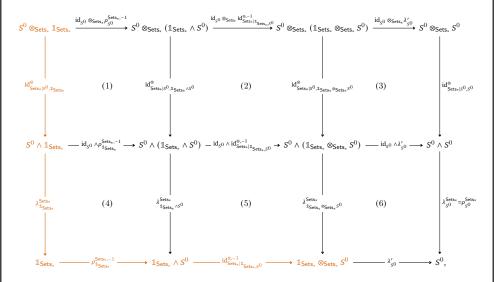
Indeed, we may write this composition as part of the diagram



which commutes since:

- Subdiagram (1) commutes by the braidedness of id^{\otimes} , as proved above.
- Subdiagram (2) commutes by ??.

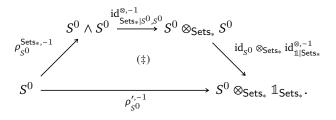
Next, consider the diagram

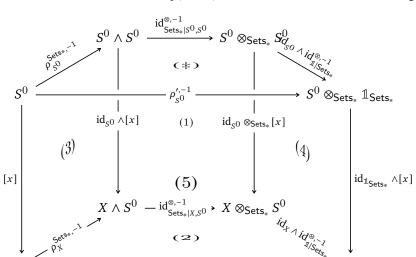


whose boundary diagram corresponds to the diagram (†) above, since the composition in red is equal to $\sigma'_{S^0,\mathbb{1}_{\mathsf{Sets}_*}}$ as proved above, and then the composition in red composed with λ'_{S^0} is equal to ρ'_{S^0} by ??. In this diagram:

- Subdiagrams (1), (2), and (3) commute by the naturality of $id_{\mathsf{Sets}_*}^{\otimes}$.
- Subdiagrams (4), (5), and (6) commute by the naturality of $\lambda^{\mathsf{Sets}_*}$, where the equality $\lambda_{S^0}^{\mathsf{Sets}_*} = \rho_{S^0}^{\mathsf{Sets}_*}$ comes from **??**.

Since all subdiagrams commute, so does the boundary diagram, i.e. the diagram (†) above. As a result, the diagram



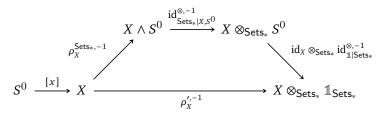


also commutes. Now, let $X \in \text{Obj}(\mathsf{Sets}_*)$, let $x \in X$, and consider the diagram

Since:

- Subdiagram (5) commutes by the naturality of ρ'^{-1} .
- Subdiagram (†) commutes, as proved above.
- Subdiagram (4) commutes by the naturality of $\mathrm{id}_{1|\mathsf{Sets}_*}^{\otimes,-1}$.
- Subdiagram (1) commutes by the naturality of $id_{Sets_*}^{\otimes,-1}$.
- Subdiagram (3) commutes by the naturality of $\rho^{\mathsf{Sets}_*,-1}$.

it follows that the diagram



Here's a step-by-step showcase of this argument: [Link]. We then have

$$\rho_X'^{,-1}(a) = [\rho_X'^{,-1} \circ [x]](1)$$

$$\begin{split} &= [(\mathrm{id}_X \wedge \mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes,-1}) \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes,-1} \circ \rho_X^{\mathsf{Sets}_*,-1} \circ [x]](1) \\ &= [(\mathrm{id}_X \wedge \mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes,-1}) \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes,-1} \circ \rho_X^{\mathsf{Sets}_*,-1}](a) \end{split}$$

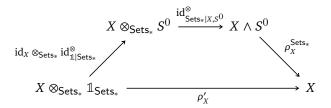
for each $a \in X$, and thus we have

$$\rho_X'^{,-1} = (\mathrm{id}_X \wedge \mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes,-1}) \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes,-1} \circ \rho_X^{\mathsf{Sets}_*,-1}.$$

Taking inverses then gives

$$\rho_X' = \rho_X^{\mathsf{Sets}_*} \circ \mathrm{id}_{\mathsf{Sets}_*|S^0,X}^{\otimes} \circ (\mathrm{id}_X \wedge \mathrm{id}_{\mathbb{1}|\mathsf{Sets}_*}^{\otimes}),$$

showing that the diagram



indeed commutes.

Monoidality of the Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

We have to show that the diagram

$$(X \otimes_{\mathsf{Sets}_*} Y) \otimes_{\mathsf{Sets}_*} Z$$

$$\mathsf{id}_{\mathsf{Sets}_*|X,Y}^{\otimes} \otimes_{\mathsf{Sets}_*} \mathsf{id}_Z \qquad \qquad \alpha'_{X,Y,Z}$$

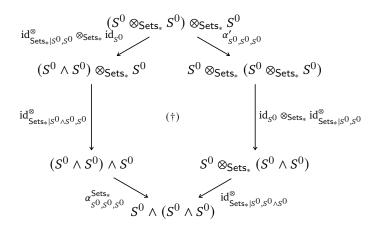
$$(X \wedge Y) \otimes_{\mathsf{Sets}_*} Z \qquad X \otimes_{\mathsf{Sets}_*} (Y \otimes_{\mathsf{Sets}_*} Z)$$

$$\mathsf{id}_{\mathsf{Sets}_*|X \wedge Y,Z}^{\otimes} \qquad \qquad \mathsf{id}_{\mathsf{X}} \otimes_{\mathsf{Sets}_*} \mathsf{id}_{\mathsf{Sets}_*|Y,Z}^{\otimes}$$

$$(X \wedge Y) \wedge Z \qquad X \otimes_{\mathsf{Sets}_*} (Y \wedge Z)$$

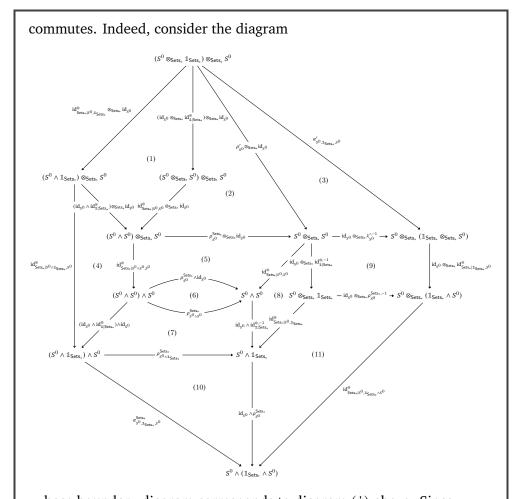
$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*} \qquad X \wedge (Y \wedge Z)$$

commutes. To this end, we will first prove that the diagram



commutes, and, to that end, we will first show that the diagram

$$\begin{array}{c} \operatorname{id}_{\mathsf{Sets}_*|S^0,\mathbb{1}_{\mathsf{Sets}_*}}^{\otimes} & (S^0 \otimes_{\mathsf{Sets}_*} \ \mathbb{1}_{\mathsf{Sets}_*}) \otimes_{\mathsf{Sets}_*} S^0 \\ & (S^0 \wedge \mathbb{1}_{\mathsf{Sets}_*}) \otimes_{\mathsf{Sets}_*} S^0 & S^0 \otimes_{\mathsf{Sets}_*} (\mathbb{1}_{\mathsf{Sets}_*} \otimes_{\mathsf{Sets}_*} S^0) \\ & \operatorname{id}_{\mathsf{Sets}_*|S^0 \wedge \mathbb{1}_{\mathsf{Sets}_*},S^0} & (\ddagger) & \operatorname{id}_{S^0 \otimes_{\mathsf{Sets}_*}} \operatorname{id}_{\mathsf{Sets}_*}^{\otimes} S^0) \\ & (S^0 \wedge \mathbb{1}_{\mathsf{Sets}_*}) \wedge S^0 & S^0 \otimes_{\mathsf{Sets}_*} (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (S^0 \wedge \mathbb{1}_{\mathsf{Sets}_*}) \wedge S^0 & S^0 \otimes_{\mathsf{Sets}_*} (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (S^0 \wedge \mathbb{1}_{\mathsf{Sets}_*}) \wedge S^0 & \operatorname{id}_{\mathsf{Sets}_*}^{\otimes} (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) & (\mathbb{1}_{\mathsf{Sets}_*} \wedge S^0) \\ & (\mathbb{1}_{\mathsf{Sets}_*}$$

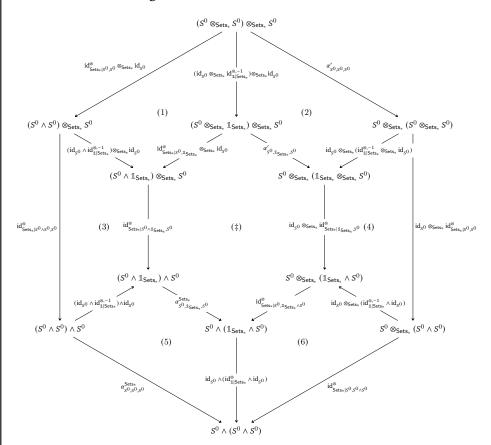


whose boundary diagram corresponds to diagram (‡) above. Since:

- Subdiagrams (1), (4), (5), (8), and (11) commute by the naturality of $id_{\mathsf{Sets}_*}^{\otimes}$;
- Subdiagram (2) commutes by the right monoidal unity of $(id_{\mathsf{Sets}_*}^\otimes, id_{\mathbb{1}|\mathsf{Sets}_*}^\otimes);$
- Subdiagram (3) commutes by the triangle identity for $(\alpha', \lambda', \rho')$;
- Subdiagram (6) commutes by ??;
- Subdiagram (7) commutes by the naturality of ρ^{Sets_*} ;

- Subdiagram (9) commutes by ??;
- Subdiagram (10) commutes by ??;

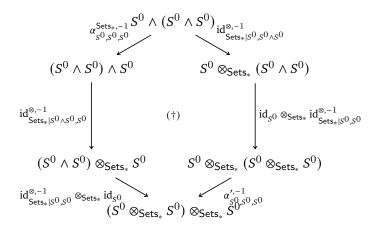
it follows that the boundary diagram, i.e. diagram (‡), also commutes. Consider now the diagram



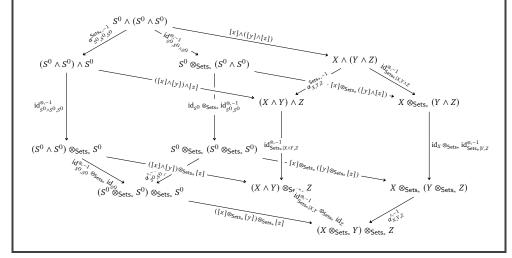
whose boundary corresponds to diagram (†) above. Since:

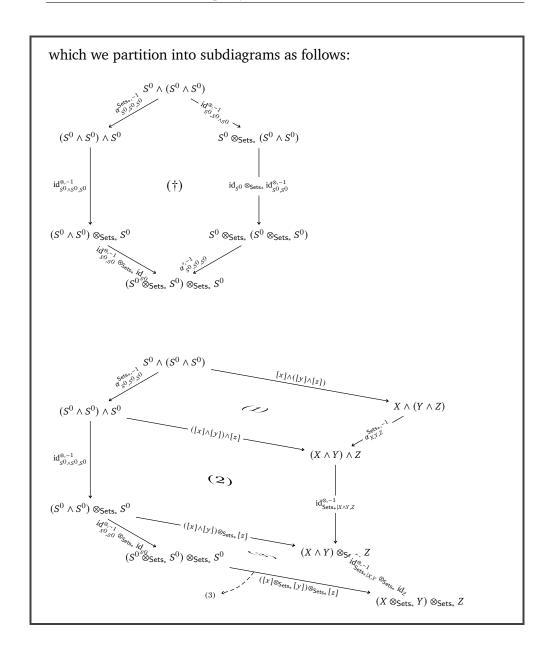
- Subdiagrams (1), (3), (4), and (6) commute by the naturality of $\mathrm{id}_{Sets_*}^{\otimes}$;
- Subdiagram (‡) commutes, as proved above;
- Subdiagram (2) commutes by the naturality of α' ;
- Subdiagram (5) commutes by the naturality of α^{Sets_*} ;

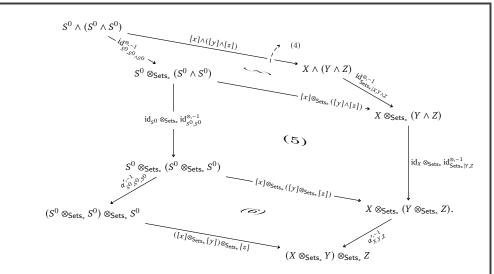
it follows that the boundary diagram, i.e. diagram (†), also commutes. Taking inverses on the diagram (†), we see that the diagram



commutes as well. Now, let $X,Y,Z\in \mathrm{Obj}(\mathsf{Sets}_*)$, let $x\in X$, let $y\in Y$, let $z\in Z$, and consider the diagram



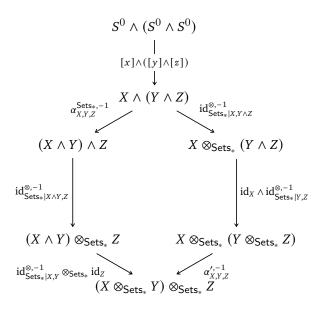




Since:

- Subdiagram (1) commutes by the naturality of $\alpha^{Sets_*,-1}$.
- Subdiagram (2) commutes by the naturality of $id_{Sets}^{\otimes,-1}$.
- Subdiagram (3) commutes by the naturality of $id_{Sets}^{\otimes,-1}$.
- Subdiagram (†) commutes, as proved above.
- Subdiagram (4) commutes by the naturality of $id_{\mathsf{Sets}_*}^{\otimes,-1}$.
- Subdiagram (5) commutes by the naturality of $\mathrm{id}_{\mathsf{Sets}_*}^{\otimes,-1}$
- Subdiagram (6) commutes by the naturality of α'^{-1} .

it follows that the diagram



also commutes. We then have

$$\begin{split} \left[(\mathrm{id}_{\mathsf{Sets}_*|X,Y}^{\otimes,-1} \otimes_{\mathsf{Sets}_*} \mathrm{id}_Z) \circ \mathrm{id}_{\mathsf{Sets}_*|X \wedge Y,Z}^{\otimes,-1} \\ & \circ \alpha_{X,Y,Z}^{\mathsf{Sets}_*,-1} \right] (x,(y,z)) = \left[(\mathrm{id}_{\mathsf{Sets}_*|X,Y}^{\otimes,-1} \otimes_{\mathsf{Sets}_*} \mathrm{id}_Z) \circ \mathrm{id}_{\mathsf{Sets}_*|X \wedge Y,Z}^{\otimes,-1} \\ & \circ \alpha_{X,Y,Z}^{\mathsf{Sets}_*,-1} \circ ([x] \wedge ([y] \wedge [z])) \right] (1,(1,1)) \\ & = \left[\alpha_{X,Y,Z}^{\prime,-1} \circ (\mathrm{id}_X \wedge \mathrm{id}_{\mathsf{Sets}_*|Y,Z}^{\otimes,-1}) \\ & \circ \mathrm{id}_{\mathsf{Sets}_*|X,Y \wedge Z}^{\otimes,-1} \circ ([x] \wedge ([y] \wedge [z])) \right] (1,(1,1)) \\ & = \left[\alpha_{X,Y,Z}^{\prime,-1} \circ (\mathrm{id}_X \wedge \mathrm{id}_{\mathsf{Sets}_*|Y,Z}^{\otimes,-1}) \circ \mathrm{id}_{\mathsf{Sets}_*|X,Y \wedge Z}^{\otimes,-1} \right] (x,(y,z)) \end{split}$$

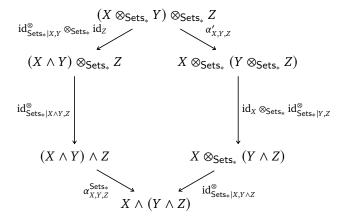
for each $(x, (y, z)) \in X \land (Y \land Z)$, and thus we have

$$(\mathrm{id}_{\mathsf{Sets}_*|X,Y}^{\otimes,-1} \otimes_{\mathsf{Sets}_*} \mathrm{id}_Z) \circ \mathrm{id}_{\mathsf{Sets}_*|X \wedge Y,Z}^{\otimes,-1} \circ \alpha_{X,Y,Z}^{\mathsf{Sets}_*,-1} = \alpha_{X,Y,Z}^{\prime,-1} \circ (\mathrm{id}_X \wedge \mathrm{id}_{\mathsf{Sets}_*|Y,Z}^{\otimes,-1}) \circ \mathrm{id}_{\mathsf{Sets}_*|X,Y \wedge Z}^{\otimes,-1}.$$

Taking inverses then gives

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*} \circ id^{\otimes}_{\mathsf{Sets}_*|X \wedge Y,Z} \circ (id^{\otimes}_{\mathsf{Sets}_*|X,Y} \otimes_{\mathsf{Sets}_*} id_Z) = id^{\otimes}_{\mathsf{Sets}_*|X,Y \wedge Z} \circ (id_X \wedge id^{\otimes}_{\mathsf{Sets}_*|Y,Z}) \circ \alpha_{X,Y,Z}',$$

showing that the diagram



indeed commutes.

Uniqueness of the Isomorphism $\otimes_{\mathsf{Sets}_*} \cong \land$

Let $\phi, \psi \colon \neg_1 \otimes_{\mathsf{Sets}_*} \neg_2 \Rightarrow \neg_1 \wedge \neg_2$ be natural isomorphisms. Since these isomorphisms are compatible with the unitors of Sets_* with respect to \wedge and \otimes (as shown above), we have

$$\lambda_Y' = \lambda_Y^{\mathsf{Sets}_*} \circ \phi_{S^0,Y} \circ (\mathrm{id}_{1|\mathsf{Sets}}^{\otimes} \otimes_{\mathsf{Sets}} \mathrm{id}_Y),$$

$$\lambda_Y' = \lambda_Y^{\mathsf{Sets}_*} \circ \psi_{S^0,Y} \circ (\mathrm{id}_{1|\mathsf{Sets}}^{\otimes} \otimes_{\mathsf{Sets}} \mathrm{id}_Y).$$

Postcomposing both sides with $\lambda_Y^{\mathsf{Sets}_*,-1}$ and then precomposing both sides with $\mathsf{id}_{1|\mathsf{Sets}}^{\otimes,-1} \otimes_{\mathsf{Sets}} \mathsf{id}_Y$ gives

$$\begin{split} \lambda_Y^{\mathsf{Sets}_*,-1} \circ \lambda_Y' \circ (\mathrm{id}_{\mathbb{1}|\mathsf{Sets}}^{\otimes,-1} \otimes_{\mathsf{Sets}} \mathrm{id}_Y) &= \phi_{S^0,Y}, \\ \lambda_Y^{\mathsf{Sets}_*,-1} \circ \lambda_Y' \circ (\mathrm{id}_{\mathbb{1}|\mathsf{Sets}}^{\otimes,-1} \otimes_{\mathsf{Sets}} \mathrm{id}_Y) &= \psi_{S^0,Y}, \end{split}$$

and thus we have

$$\phi_{S^0 Y} = \psi_{S^0 Y}$$

for each $Y \in \text{Obj}(\mathsf{Sets}_*)$. Now, let $x \in X$ and consider the naturality diagrams

for ϕ and ψ with respect to the morphisms [x] and id_Y . Having shown that $\phi_{S^0,Y} = \psi_{S^0,Y}$, we have

$$\begin{aligned} \phi_{X,Y}(x,y) &= [\phi_{X,Y} \circ ([x] \wedge id_Y)](1,y) \\ &= [([x] \otimes_{\mathsf{Sets}_*} id_Y) \circ \phi_{S^0,Y}](1,y) \\ &= [([x] \otimes_{\mathsf{Sets}_*} id_Y) \circ \psi_{S^0,Y}](1,y) \\ &= [\psi_{X,Y} \circ ([x] \wedge id_Y)](1,y) \\ &= \psi_{X,Y}(x,y) \end{aligned}$$

for each $(x, y) \in X \land Y$. Therefore we have

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$$\phi_{X,Y} = \psi_{X,Y}$$

for each $X, Y \in \text{Obj}(\mathsf{Sets}_*)$ and thus $\phi = \psi$, showing the isomorphism $\otimes_{\mathsf{Sets}_*} \cong \times$ to be unique.

COROLLARY 7.5.10.1.3 ► A SECOND UNIVERSAL PROPERTY FOR (Sets_{*}, \wedge , S^0)

The symmetric monoidal structure on the category Sets_{*} of Proposition 7.5.9.1.1 is uniquely determined by the following requirements:

1. Two-Sided Preservation of Colimits. The tensor product

$$\otimes_{\mathsf{Sets}_*} : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

of Sets, preserves colimits separately in each variable.

2. The Unit Object Is S^0 . We have $\mathbb{1}_{Sets_*} \cong S^0$.

More precisely, the full subcategory of the category $\mathcal{M}_{\mathbb{E}_{\infty}}(\mathsf{Sets}_*)$ of ?? spanned by the symmetric monoidal categories (Sets_* , $\otimes_{\mathsf{Sets}_*}$, $\mathbb{1}_{\mathsf{Sets}_*}$, $\lambda^{\mathsf{Sets}_*}$, ρ^{Sets_*} , σ^{Sets_*}) satisfying Items 1 and 2 is contractible.

Since Sets_{*} is locally presentable (??), it follows from ?? that Corollary 7.5.10.1.3 is equivalent to the existence of an internal Hom as in Item 1 of Theorem 7.5.10.1.1. The result then follows from Theorem 7.5.10.1.1.

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COROLLARY 7.5.10.1.5 ► A THIRD UNIVERSAL PROPERTY OF THE SMASH PRODUCT OF POINTED SETS

The symmetric monoidal structure on the category Sets, is the unique symmetric monoidal structure on Sets, such that the free pointed set functor

$$(-)^+$$
: Sets \rightarrow Sets_{*}

admits a symmetric monoidal structure, i.e. the full subcategory of the category $\mathcal{M}_{\mathbb{E}_{\infty}}(\mathsf{Sets}_*)$ of $\ref{eq:substructure}$ spanned by the symmetric monoidal categories $(\mathsf{Sets}_*, \otimes_{\mathsf{Sets}_*}, \mathbb{1}_{\mathsf{Sets}_*}, \lambda^{\mathsf{Sets}_*}, \rho^{\mathsf{Sets}_*}, \sigma^{\mathsf{Sets}_*})$ with respect to which $(-)^+$ admits a symmetric monoidal structure is contractible.

PROOF 7.5.10.1.6 ► PROOF OF COROLLARY 7.5.10.1.5

Let $(\otimes_{\mathsf{Sets}_*}, \mathbb{1}_{\mathsf{Sets}_*}, \lambda^{\mathsf{Sets}_*}, \rho^{\mathsf{Sets}_*}, \sigma^{\mathsf{Sets}_*})$ be a symmetric monoidal structure on Sets_* such that $(-)^+$ admits a symmetric monoidal structure with respect to $\otimes_{\mathsf{Sets}_*}$ and \wedge . We have isomorphisms

$$X \otimes_{\mathsf{Sets}_*} Y \cong (X^-)^+ \otimes_{\mathsf{Sets}_*} (Y^-)^+$$
$$\cong (X^- \times Y^-)^+$$
$$\cong (X^-)^+ \wedge (Y^-)^+$$
$$\cong X \wedge Y,$$

all natural in X and Y. Now, since \wedge preserves colimits in both variables and $\otimes_{\mathsf{Sets}_*} \cong \wedge$, it follows that $\otimes_{\mathsf{Sets}_*}$ also preserves colimits in both variables, so the result then follows from Corollary 7.5.10.1.3.

00H6 7.5.11 Monoids With Respect to the Smash Product of Pointed Sets

00H7 PROPOSITION 7.5.11.1.1 ► MONOIDS WITH RESPECT TO ∧

The category of monoids on (Sets_{*}, \wedge , S^0) is isomorphic to the category of monoids with zero and morphisms between them.

PROOF 7.5.11.1.2 ► PROOF OF PROPOSITION 7.5.11.1.1

See ??, in particular ??, ??, ??, and ??.

OOH8 7.5.12 Comonoids With Respect to the Smash Product of Pointed Sets

00H9 PROPOSITION 7.5.12.1.1 ► COMONOIDS WITH RESPECT TO ∧

The symmetric monoidal functor

$$((-)^+,(-)^{+,\times},(-)^{+,\times}_{\mathbb{1}})\colon (\mathsf{Sets},\mathsf{x},\mathsf{pt})\to (\mathsf{Sets}_*,\wedge,S^0),$$

of Pointed Sets, Item 4 of Proposition 6.4.1.1.2 lifts to an equivalence of categories

$$\mathsf{CoMon}(\mathsf{Sets}_*, \wedge, S^0) \stackrel{\mathsf{eq.}}{\cong} \mathsf{CoMon}(\mathsf{Sets}, \times, \mathsf{pt})$$

 $\cong \mathsf{Sets.}$

PROOF 7.5.12.1.2 ▶ PROOF OF PROPOSITION 7.5.12.1.1

We follow [PS19, Lemma 2.4].

Faithfulness

Given morphisms $f, g: X \to Y$, if $f^+ = g^+$, then we have

$$f(x) \stackrel{\text{def}}{=} f^{+}(x)$$
$$= g^{+}(x)$$
$$\stackrel{\text{def}}{=} g(x)$$

for each $x \in X^+$, and thus f = g, showing $(-)^+$ to be faithful.

Fullness

Let $f: X^+ \to Y^+$ be a morphism of comonoids in Sets*. By counitality, the diagram

$$X^{+} \xrightarrow{f} Y^{+}$$

$$\epsilon_{X}^{+} \swarrow \epsilon_{Y}^{+}$$

$$S^{0}$$

commutes. If $f(x) = \star_Y$ for $x \neq \star_X$, the commutativity of this diagram then gives

$$1 = \epsilon_X^+(x)$$

$$= \epsilon_Y^+(f(x))$$

$$= \epsilon_Y^+(\star_Y)$$

$$= 0,$$

which is a contradiction. Thus f is an active morphism of pointed sets, so there exists a map f^- such that $(f^-)^+ = f$ (Pointed Sets, Item 1 of Proposition 6.4.2.1.2).

Essential Surjectivity

Let $(X, \Delta_X, \epsilon_X)$ be a comonoid in Sets_{*}. We claim that

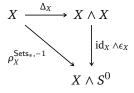
$$\Delta_X(x) = x \wedge x$$

for each $x \in X$ with $x \neq \star_X$. Indeed:

- Suppose that $x \neq \star_X$ and write $\Delta_X(x) = x_1 \wedge x_2$.
- Since $id_X \wedge \epsilon_X$ is pointed, we have

$$[\mathrm{id}_X \wedge \epsilon_X](x_1 \wedge x_2) = \star_{X \wedge S^0}.$$

• The counitality condition for Δ_X , corresponding to the commutativity of the diagram



gives

$$\begin{split} x \wedge 1 &= \rho_X^{\mathsf{Sets}_*, -1}(x) \\ &= [\mathrm{id}_X \wedge \epsilon_X \circ \Delta_X](x) \\ &= [\mathrm{id}_X \wedge \epsilon_X](\Delta_X(x)) \\ &= [\mathrm{id}_X \wedge \epsilon_X](x_1 \wedge x_2) \\ &= \star_{X \wedge S^0}, \end{split}$$

which is a contradiction. Thus $x_1 \neq \star_X$.

- Similarly, if $x \neq \star_X$, then $x_2 \neq \star_X$.
- Next, we claim that $\epsilon_X(x_2) = 1$, as otherwise we would have

$$\begin{split} \star_{X \wedge S^0} &= x_1 \wedge 0 \\ &= [\mathrm{id}_X \wedge \epsilon_X](x_1 \wedge x_2) \\ &= [\mathrm{id}_X \wedge \epsilon_X](\Delta_X(x)) \\ &= [\mathrm{id}_X \wedge \epsilon_X \circ \Delta_X](x) \\ &= \rho_X^{\mathsf{Sets}_*, -1}(x) \\ &= x \wedge 1, \end{split}$$

a contradiction. Thus $\epsilon_X(x_2) = 1$.

- Similarly, if $x \neq \star_X$, then $\epsilon_X(x_1) = 1$.
- Now, since Δ_X is counital, we have

$$\begin{split} x \wedge 1 &= \rho_X^{\mathsf{Sets}_*, -1}(x) \\ &= [\mathrm{id}_X \wedge \epsilon_X \circ \Delta_X](x) \\ &= [\mathrm{id}_X \wedge \epsilon_X](\Delta_X(x)) \\ &= [\mathrm{id}_X \wedge \epsilon_X](x_1 \wedge x_2) \\ &= x_1 \wedge 1, \end{split}$$

so $x = x_1$.

• Similarly, $x = x_2$, and we are done.

Next, notice that $X \cong \epsilon_X^{-1}(0) \coprod \epsilon_X^{-1}(1)$, and let $x \in \epsilon_X^{-1}(0)$. We then have

$$[(\mathrm{id}_X \wedge \epsilon_X) \circ \Delta_X](x) = [\mathrm{id}_X \wedge \epsilon_X](x \wedge x)$$
$$= x \wedge 0$$
$$= \star_{X \wedge S^0}.$$

The counitality condition for Δ_X then gives $x = \star_X$, so $\epsilon_X^{-1}(0) = \{\star_X\}$. Thus we have $(\epsilon_X^{-1}(1))^+ \cong X$, and this isomorphism is compatible with the comonoid structures when equipping $\epsilon_X^{-1}(1)$ with its unique comonoid structure. This shows that $(-)^+$ is essentially surjective.

Equivalence

Since $(-)^+$ is fully faithful and essentially surjective, it is an equivalence by Categories, Item 1b of Item 1 of Proposition 11.6.7.1.2.

00HA 7.6 Miscellany

00HC

OOHB 7.6.1 The Smash Product of a Family of Pointed Sets

Let $\{(X_i, x_0^i)\}_{i \in I}$ be a family of pointed sets.

DEFINITION 7.6.1.1.1 ► THE SMASH PRODUCT OF A FAMILY OF POINTED SETS

The **smash product of the family** $\{(X_i, x_0^i)\}_{i \in I}$ is the pointed set $\bigwedge_{i \in I} X_i$ consisting of:

• *The Underlying Set.* The set $\bigwedge_{i \in I} X_i$ defined by

$$\bigwedge_{i \in I} X_i \stackrel{\text{def}}{=} \left(\prod_{i \in I} X_i \right) / \sim,$$

where \sim is the equivalence relation on $\prod_{i \in I} X_i$ obtained by declaring

$$(x_i)_{i \in I} \sim (y_i)_{i \in I}$$

if there exist $i_0 \in I$ such that $x_{i_0} = x_0$ and $y_{i_0} = y_0$, for each $(x_i)_{i \in I}, (y_i)_{i \in I} \in \prod_{i \in I} X_i$.

• *The Basepoint*. The element $[(x_0)_{i \in I}]$ of $\bigwedge_{i \in I} X_i$.

Appendices

A Other Chapters

Preliminaries

- 1. Introduction
- 2. A Guide to the Literature

Sets

- 3. Sets
- 4. Constructions With Sets
- 5. Monoidal Structures on the Category of Sets
- 6. Pointed Sets
- 7. Tensor Products of Pointed Sets

Relations

- 8. Relations
- 9. Constructions With Relations

10. Conditions on Relations

Categories

- 11. Categories
- 12. Presheaves and the Yoneda Lemma

Monoidal Categories

13. Constructions With Monoidal Categories

Bicategories

14. Types of Morphisms in Bicategories

Extra Part

15. Notes

References

[PS19] Maximilien Péroux and Brooke Shipley. "Coalgebras in Symmetric Monoidal Categories of Spectra". In: *Homology Homotopy Appl.* 21.1 (2019), pp. 1–18. ISSN: 1532-0073. DOI: 10.4310/HHA.2019.v21.n1. a1. URL: https://doi.org/10.4310/HHA.2019.v21.n1.a1 (cit. on p. 148).