

KLPT TWo : Algebraic pathfinding in dimension two

(The capitalization is not a mistake)

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Setting the frame

For the whole presentation, we fix

- A prime $p = 3 \bmod 4$ of cryptographic size,
- A small prime ℓ . Typically $\ell \in \{2, 3\}$
- $E_0 : y^2 : x^3 + x$, the curve with j-invariant 1728 over \mathbb{F}_{p^2} ,
- $\text{End}(E_0) \simeq \mathcal{O}_0 = \langle 1, i, \frac{i+j}{2}, \frac{1+k}{2} \rangle$,
- $B_{p,\infty} = \mathcal{O}_0 \otimes \mathbb{Q}$, the underlying quaternion algebra,
- $A_0 := E_0 \times E_0$, our base abelian surface,
- λ_0 , the (principal) product polarization of A_0 .

In this presentation, **every** elliptic curve is supersingular

Introduction : The ℓ -isogeny path problem

The ℓ -isogeny path problem

Let E_1, E_2 be two elliptic curves over \mathbb{F}_{p^2} . Let ℓ be a small prime.

Compute an isogeny $\varphi : E_1 \rightarrow E_2$ with degree ℓ^e .

$$E_1 \xrightarrow{\varphi} E_2$$

Deuring
 \longleftrightarrow

The quaternion ℓ^e -isogeny path problem

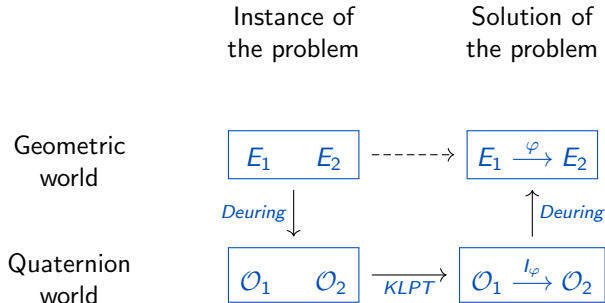
Let $\mathcal{O}_1, \mathcal{O}_2$ be two maximal orders in the quaternion algebra $B_{p,\infty}$.

Compute an ideal I of norm ℓ^e such that $\mathcal{O}_L(I) \simeq \mathcal{O}_1$ and $\mathcal{O}_R(I) \simeq \mathcal{O}_2$.

$$\mathcal{O}_1 \xrightarrow{I} \mathcal{O}_2$$

[Isogeny Club – S1E4] : **Antonin Leroux**, *A new algorithm for the constructive Deuring correspondence: making SQISign faster*

Overview of KLPT



An analogue in dimension 2

- Replace the elliptic curves by *abelian surfaces*
- Replace the maximal orders by matrices
- Replace the Deuring correspondence by the Ibukiyama-Katsura-Oort correspondence.
- **Replace KLPT by KLPT²**

Organization of the talk

1. Principally polarized superspecial abelian surfaces
2. The Ibukiyama-Katsura-Oort correspondence
3. KLPT²
4. Constructive IKO correspondence and applications

Act I – Understanding the objects we manipulate

Act I : Principally Polarized Superspecial Abelian Surfaces ?

1.1 – Abelian surfaces

Definition (Abelian varieties)

An abelian variety is an algebraic group that can be embedded in a projective space.

It is an abstract object \rightsquigarrow scary !

A simple classification of abelian varieties

$$\begin{aligned} \dim = 1 : & \quad E \\ \dim = 2 : & \quad \begin{cases} E_1 \times E_2 \\ \text{Jac}(H) \end{cases}, \text{ or} \\ \dim = 3 : & \quad \dots \end{aligned}$$

with H an hyperelliptic curve of genus 2

An abelian variety of dimension 2 is called an *abelian surface*.

1.1 – It's time to d-d-d-dual !

To any abelian variety, we canonically associate a “mirror” variety called its *dual*.

$$A \xrightarrow{\varphi} B$$

$$A^{\vee} \xleftarrow{\hat{\varphi}} B^{\vee}$$

Definition (Dual variety)

The dual variety of A is the *Picard group* $\text{Pic}^0(A)$. Its elements are divisors.

Remark

The dual isogeny $\varphi : B^{\vee} \rightarrow A^{\vee}$ is **not** what we call a dual isogenies for elliptic curves !

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To any abelian variety, we canonically associate a “mirror” variety called its *dual*. Any isogeny $\varphi : A \rightarrow B$ induces an isogeny $\hat{\varphi}$ between the duals.

$$A \xrightarrow{\varphi} B$$

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1.2 – Supersingularity vs superspeciality

Let A be an abelian surface (a Jacobian or a product of elliptic curves).

Supersingularity

A is supersingular if it is *isogenous* to some $E_1 \times E_2$.

The supersingular isogeny graph

Contains infinitely many vertices. \times

Superspeciality

A is superspecial if it is *isomorphic* to some $E_1 \times E_2$.

The superspecial isogeny graph

Contains a single vertex. \times

Theorem (Deligne)

For all E_1, E_2, E_3, E_4 , we have

$$E_1 \times E_2 \simeq E_3 \times E_4$$

1.3 – Polarizations

Informal Definition (Polarization)

A polarization on A is an isogeny

$$\begin{array}{rcl} \lambda_D & : & A \rightarrow A^\vee \\ & & P \mapsto [t_P^*(D) - (D)] \end{array}$$

where D is an ample divisor and t_P^* is the pullback of the translation-by- P map.

Important properties of polarizations

- Not all isogenies $A \rightarrow A^\vee$ are polarizations.
- If a polarization has degree 1, it is called *principal*.
- We write $\text{PPol}(A)$ for the set of principal polarizations of A .

1.3 – Isogenies between polarized varieties

Definition (Polarized isogeny)

Let (A, λ_A) and (B, λ_B) be two polarized varieties.

An isogeny $\varphi : (A, \lambda_A) \rightarrow (B, \lambda_B)$ is an isogeny $\varphi : A \rightarrow B$ between the underlying varieties such that the following diagram commutes.

$$\begin{array}{ccc} A & \xrightarrow{\varphi} & B \\ N\lambda_A \downarrow & & \downarrow \lambda_B \\ A^\vee & \xleftarrow{\hat{\varphi}} & B^\vee \end{array}$$

i.e. we have $\hat{\varphi}\lambda_B\varphi = N\lambda_A$, for some integer N called the *reduced degree*.

1 – Wrapping up

Principally polarized



$$\lambda : A \xrightarrow{\sim} A^\vee$$

Superspecial



$$A \simeq E_0 \times E_0$$

**as non-
polarized
variety**

Abelian Surface



$$\text{Jac}(H) \text{ or } E_1 \times E_2$$

The polarized superspecial isogeny graph

The graph of principally polarized superspecial abelian surfaces over \mathbb{F}_p contains $O(p^3)$ vertices. ✓

Among which we have :

- $O(p^3)$ Jacobians.
- $O(p^2)$ products of elliptic curves.

A small sanity check

Example 1 : E_0

$E_0 : y^2 = x^3 + x$. It is a supersingular curve.

It is equipped with a canonical principal polarization

$$\begin{array}{ccc} \lambda & : & E_0 \rightarrow E_0^\vee \\ & & P \mapsto (P) - (\infty) \end{array}$$

It is the only possible polarization on E_0 .

Example 2 : (A_0, λ_0)

$A_0 = E_0^2$. It is superspecial.

It can be equipped with a natural polarization λ_0 called the *product polarization* inherited from E_0 .

There are a lot of non-equivalent polarizations on A_0 .

Example 3 : (A, λ)

$A = \text{Jac}(H)$ for $H/\mathbb{F}_p : y^2 = x^6 + 1$. It is superspecial if $p \equiv 5 \pmod{6}$.

The equation for H implicitly induces a polarization λ .

Act II : The Ibukiyama-Katsura-Oort Correspondence

$$\left\{ \begin{array}{l} \text{Abelian surfaces} \\ (A, \lambda_A) \\ \text{up to polarized} \\ \text{isomorphisms} \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{Polarizations} \\ \lambda \text{ of } A_0 \\ \text{up to equivalence} \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{Matrices} \\ g \in M_2(\mathcal{O}_0) \\ \text{up to congruence} \end{array} \right\}$$

2.1 – From surfaces to polarizations

Goal

Given an abelian surface (A, λ_A) , encode it as a polarization λ on A_0 .

Polarizations pullbacks

Given (A, λ_A) , A_0 and an **unpolarized** isomorphism $\varphi : A_0 \rightarrow A$, one can compute

$$\lambda = \hat{\varphi} \lambda_A \varphi$$

This is a polarization of A_0 .

$$\begin{array}{ccc} A & \xleftarrow{\varphi} & A_0 \\ \lambda_A \downarrow & & \downarrow \lambda \\ A^\vee & \xrightarrow{\hat{\varphi}} & A_0^\vee \end{array}$$

[GSS25] : **Gaudry-Soumier-Spaenlehauer**, *Isogeny-based Cryptography using Isomorphisms of Superspecial Abelian Surfaces*

2.2 – From polarizations to matrices : Deuring for the PPol

Goal

Given a polarization λ on A_0 , encode it as an endomorphism of A_0 .
Then, write the endomorphism as a 2x2 matrix with quaternions coefficients.

Step 1 :

We simply apply the map

$$\begin{array}{ccc} \mu & : & \text{PPol}(A_0) \rightarrow \text{End}(A_0) \\ & & \lambda \mapsto \lambda_0^{-1} \lambda \end{array}$$

$$\begin{array}{c} \circlearrowright \\ \text{g} \end{array} A_0 \begin{array}{c} \xrightarrow{\lambda} \\ \xleftarrow{\lambda_0^{-1}} \end{array} A_0^\vee$$

Step 2 :

By the Deuring correspondence, $\text{End}(A_0) = M_2(\text{End}(E_0))$ is isomorphic to $M_2(\mathcal{O}_0)$.

2.2 – From polarizations to matrices : Deuring for the PPol

The image of μ (after translating into quaternions) is the set

$$\text{Mat}(A_0) := \left\{ \begin{pmatrix} s & r \\ \bar{r} & t \end{pmatrix}, \quad s, t \in \mathbb{Z}_{>0}, r \in \mathcal{O}_0, st - r\bar{r} = 1 \right\} \subset \text{GL}_2(\mathcal{O}_0)$$

Elements of this set will be the input of KLPT^2 .

The IKO correspondence

	Geometric world	Quaternion world
Vertices of the graph	(A, λ_A)	$g \in \text{Mat}(A_0)$
Edges of the graph	Isogenies $\varphi : (A_1, \lambda_1) \rightarrow (A_2, \lambda_2)$	Connecting matrices $u \in M_2(\mathcal{O}_0)$
Adjoint map	Adjoint isogeny $\tilde{\varphi} = \lambda_1^{-1} \hat{\varphi} \lambda_2$	Conjugate-transpose $u = \begin{pmatrix} \bar{a} & \bar{c} \\ \bar{b} & \bar{d} \end{pmatrix}$
Structure-preserving property	$\hat{\varphi} \lambda_2 \varphi = N \lambda_1$	$u^* g_2 u = N g_1$
Reduced norm	N	$\mathcal{N}(u)$

The quaternion isogeny path problem in dimension 2

Recall : The 2D isogeny path problem

Compute an isogeny $\varphi : (A_1, \lambda_1) \rightarrow (A_2, \lambda_2)$ with reduced norm $N = \ell^e$.

$$\begin{array}{ccc} A_1 & \xrightarrow{\varphi} & A_2 \\ N\lambda_1 \downarrow & & \downarrow \lambda_2 \\ A_1^\vee & \xleftarrow{\hat{\varphi}} & A_2^\vee \end{array}$$

Theorem

The 2D isogeny path problem reduces to computing $\psi \in \text{End}(A_0)$ such that the following diagram commutes

$$\begin{array}{ccccccc} A_1 & \xleftarrow{\varphi_1} & A_0 & \xrightarrow{\psi} & A_0 & \xrightarrow{\varphi_2} & A_2 \\ N\lambda_1 \downarrow & & \lambda_0^{-1} \uparrow \downarrow N\lambda'_1 & & \lambda'_2 \downarrow \uparrow \lambda_0^{-1} & & \downarrow \lambda_2 \\ A_1^\vee & \xrightarrow{\hat{\varphi}_1} & A_0^\vee & \xleftarrow{\hat{\psi}} & A_0^\vee & \xleftarrow{\hat{\varphi}_2} & A_2^\vee \end{array}$$

i.e. such that $\hat{\psi}\lambda'_2\psi = N\lambda'_1$ ($\iff \gamma^*g_2\gamma = Ng_1$).

We can then output $\varphi = \varphi_2 \circ \psi \circ \varphi_1^{-1}$.

Act III : The KLPT^2 algorithm

Main theorem

Let $g_1, g_2 \in \text{Mat}^0(\mathcal{O}_0)$. There is a PPT algorithm that computes $\gamma \in M_2(\mathcal{O}_0)$ such that

$$\gamma^* g_2 \gamma = N g_1$$

with $N \in O(p^{25})$ is smooth.

3.1 – Some useful lemmas

Definition (Connecting matrix)

Let h_1, h_2, u be matrices in $M_2(\mathcal{O}_0)$.

We say that $u \in M_2(\mathcal{O}_0)$ is a connecting matrix between h_1 and h_2 if it satisfies

$$u^* h_2 u = \mathcal{N}(u) h_1$$

we write $u : h_1 \rightarrow h_2$.

Lemma (Inversion lemma)

If $u : h_1 \rightarrow h_2$ is invertible in $M_2(B_{p,\infty})$,
then $\mathcal{N}(u)u^{-1} \in M_2(\mathcal{O}_0)$ and $\mathcal{N}(u)u^{-1} : h_2 \rightarrow h_1$.

A commutative diagram illustrating the relationship between h_1 and h_2 via the connecting matrix u and its inverse-like operation $\mathcal{N}(u)u^{-1}$. The diagram consists of two nodes, h_1 on the left and h_2 on the right. A curved arrow points from h_1 to h_2 and is labeled u . A second curved arrow points from h_2 back to h_1 and is labeled $\mathcal{N}(u)u^{-1}$.

3.1 – Some useful lemmas

Lemma (Composition lemma)

Let h_1, h_2, h_3, u_1, u_2 be matrices such that

$$\begin{cases} u_1 : h_1 \rightarrow h_2 \\ u_2 : h_2 \rightarrow h_3 \end{cases}$$

Then, $u_1 u_2 : h_1 \rightarrow h_3$.

Proof.

This lemma comes from the fact that $u_i : h_i \rightarrow h_{i+1}$ corresponds to the identity

$$u_i^* h_{i+1} u_i = \mathcal{N}(u_i) h_i$$

and from the multiplicativity of the reduced norm $\mathcal{N}(-)$. □

$$h_1 \xrightarrow{u_1} h_2 \xrightarrow{u_2} h_3$$

Outline of the strategy

Let $g_1, g_2 \in \text{Mat}(A_0)$. A solution is easily computed in the following case :

Lemma

If $g_1 = \begin{pmatrix} D & r_1 \\ \bar{r}_1 & t_1 \end{pmatrix}$ and $g_2 = \begin{pmatrix} D & r_2 \\ \bar{r}_2 & t_2 \end{pmatrix}$, for some $D, t_1, t_2 \in \mathbb{Z}$ and $r_1, r_2 \in \mathcal{O}_0$, with $\det(g_1) = \det(g_2)$, then $\tau := \begin{pmatrix} D & r_1 - r_2 \\ 0 & D \end{pmatrix}$ satisfies

$$\tau^* g_2 \tau = D^2 g_1$$

if D is a power of ℓ , we're done.

The high-level approach

1. Find $u_i : h_i \rightarrow g_i$ for some h_i of the form $\begin{pmatrix} \ell^{e_2} & r'_i \\ \bar{r}'_i & t'_i \end{pmatrix}$, with $\mathcal{N}(u_i) = \ell^{e_1}$.
2. Compute $\tau : h_1 \rightarrow h_2$ with the above lemma. Its norm is ℓ^{2e_2} .
3. Output $\gamma = \mathcal{N}(u_1)u_2\tau u_1^{-1}$. Its norm is $\ell^{2(e_1+e_2)}$.

$$\begin{array}{ccc} & h_1 & \xrightarrow{\tau} & h_2 \\ & \swarrow u_1 & & \searrow u_2 \\ g_1 & \xrightarrow{\gamma = \mathcal{N}(u_1)u_2\tau u_1^{-1}} & g_2 \end{array}$$

3.2 – Computing the $u : h \rightarrow g$

Strategy for computing u

Given $g = \begin{pmatrix} s & r \\ \bar{r} & t \end{pmatrix} \in \text{Mat}(A_0)$, compute $u \in M_2(\mathcal{O}_0)$ such that

1. $h = u^* g u$ is of the form $\begin{pmatrix} \ell^{e_2} & r' \\ \bar{r}' & t' \end{pmatrix}$
2. $\mathcal{N}(u) = \ell^{e_1}$
3. e_1 and e_2 don't depend on g .

For $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, an explicit computation yields

$$u^* g u = \begin{pmatrix} s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \text{tr}(\bar{c} \bar{r} a) & r' \\ \bar{r}' & s \cdot \mathbf{n}(b) + t \cdot \mathbf{n}(d) + \text{tr}(\bar{b} \bar{r} d) \end{pmatrix}$$

where $\mathbf{n}(-)$ is the usual norm in the quaternion algebra.

The top-left entry only depends on a and c !

↳ Fix a and c to satisfy 1.

↳ Fix b and d to satisfy 2.

3.2 – Computing the $u : h \rightarrow g$

Strategy for computing u

Let $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ and $h := u^* g u = \begin{pmatrix} s' & r' \\ \bar{r}' & t' \end{pmatrix}$.

1. Find $a, c \in \mathcal{O}_0$ such that s' equals some ℓ^{e_2} .
↳ Solve a diophantine equation.
2. Given a, c , find values $b, d \in \mathcal{O}_0$ such that $\mathcal{N}(u) = \ell^{e_1}$.
↳ Solve a pathfinding problem in 1D \rightarrow KLPT !

We actually start with step 2.

Finding b and d : We put KLPTs in your KLPT²

Here, we assume we have $u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ with a and c fixed and coprime.
We want to find a pair $(b, d) \in \mathcal{O}_0^2$ such that

$$\mathcal{N}(u) = \mathbf{n}(a)\mathbf{n}(d) + \mathbf{n}(c)\mathbf{n}(c) - \mathbf{tr}(\bar{a}b\bar{d}c)$$

Reducing the problem to a pathfinding problem in 1D

1. View \mathcal{O}_0^2 as a free right \mathcal{O}_0 -module of rank 2.
2. Compute Bézout's coefficients $ua + cv = 1$.
3. Let $M_1 = (a, c)\mathcal{O}_0$ and $M_2 = (u \cdot \mathbf{n}(c)a, -v \cdot \mathbf{n}(a)c)B_{p,\infty} \cap \mathcal{O}_0^2$ be two submodules.
4. Note that $\mathcal{O}_0^2 = M_1 \oplus M_2$.

Theorem

The submodule M_2 is isomorphic to the right \mathcal{O}_0 -ideal $I = \mathbf{n}(c)\mathcal{O}_0 + a\bar{c}\mathcal{O}_0$

Finding b and d : We put KLPTs in your KLPT

The isomorphism $f : M_2 \rightarrow I$ is a $\mathbf{n}(c)$ -homothety.

Finding b and d from KLPT1

5. Using KLPT, we can find some $\omega \in I$ with norm $\mathbf{n}(c)\ell^{e_0} \in O(p^3)$
6. We translate ω into an element $(b, d) = f^{-1}(\omega)$ of M_2 with norm $\mathbf{n}(\omega)/\mathbf{n}(c) = \ell^{e_0}$.

The resulting matrix u has norm $\ell^{e_1} \in O(p^6)$ and can be written as

$$u = \begin{pmatrix} a & v \cdot \mathbf{n}(c)x + v\bar{c}y \\ c & -u\bar{a}x - u \cdot \mathbf{n}(a)y \end{pmatrix}$$

where the quaternion ω equals $\mathbf{n}(c)x + a\bar{c}y$ and $e_1 = 2e_0$.

Remark

u can be rewritten as $\begin{pmatrix} a & x \\ c & -y \end{pmatrix} \begin{pmatrix} 1 & -u\bar{a}x + v\bar{c}y \\ 0 & 1 \end{pmatrix}$.

Since the second matrix has determinant 1 , we can work with the left one only.

Finding a and c : Finalising the algorithm

We want to find $a, c \in \mathcal{O}_0$ such that

$$s' := s \cdot \mathbf{n}(a) + t \cdot \mathbf{n}(c) + \mathbf{tr}(\bar{c}\bar{r}a) = \ell^{e_2}$$

↳ Similar to KLPT1

The strategy

1. Use the fact that \mathcal{O}_0 contains the suborder $\mathbb{Z} + \mathbb{Z}i + \mathbb{Z}j + \mathbb{Z}k$
2. Restrict a and c to subspaces of \mathcal{O}_0 so the trace vanishes.
3. Fix c and use Cornacchia to compute a suitable value for a .

With some pre-processing on g , we can bound its entries and guarantee that $s' = \ell^{e_2} \in O(p^{6.5})$ and $\mathbf{n}(a)$ and $\mathbf{n}(c)$ are coprime.

3 – Wrapping up

We showed how to compute $u_i : h_i \rightarrow g_i$ such that

- $u_i \in \mathcal{O}_0$
- $\mathcal{N}(u_i) = \ell^{e_1} \in O(p^6)$
- $h_i = \begin{pmatrix} \ell^{e_2} & r'_i \\ \bar{r}'_i & t'_i \end{pmatrix}$ with $\ell^{e_2} \in O(p^{6.5})$.

The output matrix

The output $\gamma \in M_2(\mathcal{O}_0)$ of the algorithm comes from the composition

$$\begin{array}{ccccc} & h_1 & \xrightarrow{\tau} & h_2 & \\ u_1 \swarrow & & & & \searrow u_2 \\ g_1 & \xrightarrow{\gamma = \mathcal{N}(u_1) \tau u_2 u_1^{-1}} & & & g_2 \end{array}$$

Its norm is $\mathcal{N}(\gamma) = \ell^{e_1} \cdot \ell^{e_1} \cdot \ell^{2e_2} \in O(p^{25})$.

Act IV – Constructive IKO Correspondence & Applications

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Constructive IKO Correspondence

- Variety-to-Matrix :
 - ↳ Products of elliptic curves : [GSS25] ✓,
 - ↳ Jacobians : Possibly (private communications)
- Isogeny-to-Matrix :
 - ↳ For (2,2)-isogenies : This work ✓
- Matrix-to-Isogeny :
 - ↳ For powersmooth degrees : [Chu21] ✓

Applications

- Cryptanalysis of 2D CGL without trusted setup
- Relaxed constraints for isogeny representations in 2D
- A brand new SQISign2D ???

[Chu21] : **Hao-Wei Chu**, *Algorithms for abelian surfaces over finite fields and their applications to cryptography* Phd thesis

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~ Thank you for your attention ! ~