The genus-2 isogeny setting

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Genus-2 curves and their Jacobians

What's a genus-2 curve?

Elliptic Curve \mathcal{E}

- Smooth, projective curve of genus-1 over a field K¹ with a specified base point.
- If $char(K) \neq 2$, an elliptic curve admits an equation of the form

$$\mathcal{E}: y^2 = f(x), \text{ with } \deg(f) = 3,$$

and $\operatorname{disc}(f) \neq 0$, the Weierstrass equation.

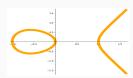


Figure 1: $y^2 = x(x^2 - 1)$

Today

- We consider smooth, projective curves of genus-2.
 If char(K) ≠ 2, a genus-2 curve
- admits an equation of the form

$$C: y^2 = f(x), \text{ with } \deg(f) \in \{5, 6\},\$$

and $\mathrm{disc}(f) \neq 0$, the Weierstrass equation.



Figure 2: $y^2 = x(x^2 - 1)(x^2 - 4)$

¹Throughout the presentation, all fields are perfect.

Points of genus-2 curves

The set of points of a genus-2 curve $C: y^2 = f(x)$ is given by

$$\mathcal{C}(\bar{K}) = \{(u,v) \in \bar{K}^2 \mid v^2 = f(u)\} \cup \begin{cases} \{\infty\} & \text{if } \deg(f) = 5 \\ \{\infty_+, \infty_-\} & \text{if } \deg(f) = 6 \end{cases}.$$

A point $P\in\mathcal{C}(\bar{K})$ is K-rational if its coordinates are in K. The set of K-rational points is denoted $\mathcal{C}(K)$.

Example

 $\mathcal{C}: y^2 = x(x^2-1)(x^2-4)$ over \mathbb{F}_7 . The curve \mathcal{C} has precisely 8 \mathbb{F}_7 -rational points. More precisely,

$$C(\mathbb{F}_7) = \{\infty, (0,0), (1,0), (2,0), (5,0), (6,0), (3,1), (3,6)\}.$$



9 In contrast to elliptic curves, the set $\mathcal{C}(\bar{K})$ is **not** a group.

Weierstrass points

Let $C: y^2 = f(x)$ be a genus-2 curve.

The hyperelliptic involution $\tau:\mathcal{C}\to\mathcal{C}$ is defined as $\tau(u,v)=(u,-v)$ on affine points and $\tau(\infty_\pm)=\infty_\mp$ if $\deg(f)=6$, and $\tau(\infty)=\infty$ if $\deg(f)=5$.

The Weierstrass points of $\mathcal C$ are the points fixed by au.

- Every genus-2 curve has precisely 6 Weierstrass points in $\mathcal{C}(\bar{K})$.
- For example

$$\{\infty, (0,0), (1,0), (-1,0), (2,0), (-2,0)\}$$

are the Weierstrass points of the curve $y^2=x(x^2-1)(x^2-4).$

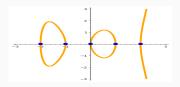


Figure 3: deg(f) = 5

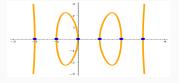


Figure 4: deg(f) = 6

The divisor group

A **divisor** on a curve C/K is a formal sum of points:

$$D = \sum_{P \in \mathcal{C}(\bar{K})} n_P \cdot P, \text{ with } n_P \in \mathbb{Z}$$

and $n_P = 0$ for all but finitely many points P.

- The set of divisors on $\mathcal C$ forms a group, denoted $\mathrm{Div}_{\mathcal C}.$
- The degree of D is $\deg(D) = \sum_{P \in \mathcal{C}(\bar{K})} n_P.$
- The subgroup of divisors of degree-0 is denoted Div_C⁰.
- A divisor D is K-rational, if it is fixed by the action of Gal(K̄/K).
 Notation: Div_C(K) and Div_C⁰(K).

Example $y^2 = x(x^2 - 1)(x^2 - 4)$ over \mathbb{F}_7

- $D_1 = 3 \cdot (0,0) 2 \cdot (3,1) \in Div_{\mathcal{C}}.$
- Set $D_2 = (1,0) (0,0)$, then $D_1 + D_2 = (1,0) + 2 \cdot (0,0) 2 \cdot (3,1)$.
- $deg(D_1) = 3 + (-2) = 1$.
- We have $D_3 =$ $(4,i) + (4,-i) \in \operatorname{Div}_{\mathcal{C}}(\mathbb{F}_7),$ but $D_4 = (4,i) \notin \operatorname{Div}_{\mathcal{C}}(\mathbb{F}_7).$

Equivalence of divisors

To a rational function $\phi \in \bar{K}(\mathcal{C})^*$, we associate the divisor

$$\operatorname{div}(\phi) = \sum_{P \in \mathcal{C}(\bar{K})} \operatorname{ord}_{P}(\phi) P \in \operatorname{Div}_{\mathcal{C}}^{0},$$

where $\operatorname{ord}_P(\phi)$ is the order of vanishing of ϕ at P. A divisor of this form is called **principal**.

- Broadly: div(φ) is the formal sum of the zeros and poles of φ, counted with multiplicity.
- $D, D' \in \text{Div}_{\mathcal{C}}$ are called equivalent $(D \sim D')$ if D - D' is a principal divisor.
- The equivalence classes of divisors form a group, the Picard group ${\rm Pic}_{\mathcal C}.$
- Similar to before, one defines $\operatorname{Pic}_{\mathcal{C}}^{0}, \operatorname{Pic}_{\mathcal{C}}(K)$ and $\operatorname{Pic}_{\mathcal{C}}^{0}(K)$.

Example $y^2 = x(x^2 - 1)(x^2 - 4)$ over \mathbb{F}_7

- $D_1 = \operatorname{div}(x-3) =$ $(3,1) + (3,6) - 2 \cdot \infty.$
- $D_2 = (3,1) + (2,0) (3,1) (3,6) \sim D_3 = (3,1) + (2,0) - 2 \cdot \infty,$ because $D_3 - D_2 = D_1.$



The Jacobian of a genus-2 curve

The **Jacobian** $\mathcal{J}(\mathcal{C})$ of a (genus-2) curve \mathcal{C} over K is the 2-dimensional abelian variety such that over each field $K \subset L \subset \overline{K}$, we have $\mathcal{J}(\mathcal{C})(L) = \operatorname{Pic}_{\mathcal{C}}^{0}(L)$.

Two ways of viewing elements in $\mathcal{J}(\mathcal{C})(K)$:

1. $\mathcal{J}(\mathcal{C})(K) = \operatorname{Pic}_{\mathcal{C}}^{0}(K)$, and for any $R \in \mathcal{J}(\mathcal{C})(K) \setminus \{0\}$, there exist unique points $P_1, P_2 \in \mathcal{C}(\bar{K})$ with $\tau(P_1) \neq P_2$, so that

$$R = [P_1 + P_2 - D_{\infty}], \text{ with } D_{\infty} = \begin{cases} 2 \cdot \infty & \text{if } \deg(f) = 5, \\ \infty_+ + \infty_- & \text{if } \deg(f) = 6. \end{cases}$$

- 2. $\mathcal{J}(\mathcal{C})$ is a variety, i.e. the zero locus of a set of polynomials.
 - For example $\mathcal{J}(\mathcal{C})$ can be written as the zero locus of 72 polynomials in \mathbb{P}^{15} , so a point $R \in J(\mathcal{C})$ is of the form

$$R = (r_0 : r_1 : \cdots : r_{15}).$$

• Comparison: Abelian varieties of dimension 1 are elliptic curves, and can be written as the zero locus of one polynomial in \mathbb{P}^2 :

$$\mathcal{E}: Y^2 Z = X^3 + aXZ^2 + bZ^3.$$

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Mumford presentation

Let $R\in\mathcal{J}(\mathcal{C})(K)$ and consider the unique presentation from the previous slide, i.e. $R=[P_1+P_2-D_\infty]$ and for simplicity assume that $P_1=(u_1,v_1)$, $P_2=(u_2,v_2)$ are affine points. We define

- $a = (x u_1)(x u_2) \in K[x],$
- $b = b_1 x + b_0$, so that $b(u_1) = v_1$ and $b(u_2) = v_2$.

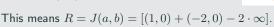
Then (a,b) is called the **Mumford presentation** of R and we denote R=J(a,b).

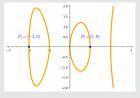
Example: $y^2 = x(x^2 - 1)(x^2 - 4)$ over \mathbb{F}_7

Consider $(a, b) = (x^2 + x - 2, 0)$.

We have a = (x-1)(x+2), hence

- $u_1 = 1, u_2 = -2$ and
- $v_1 = b(1) = 0$, $v_2 = b(-2) = 0$.





Isogenies of Jacobians of genus-2 curves

Torsion elements over a finite field (char(K) = p)

Elliptic Curve $\mathcal{E}: y^2 = f(x)$

- $\mathcal{E}[m] \cong (\mathbb{Z}/m\mathbb{Z})^2$ for $m \in \mathbb{N}$ with $p \nmid m$.
- The Weil pairing

$$e_m: \mathcal{E}[m] \times \mathcal{E}[m] \to \boldsymbol{\mu}_m$$

is a bilinear, alternating pairing.

Example: m = 2, $f = \prod_{i=1}^{3} (x - r_i)$

- $\mathcal{E}[2] \setminus \{0\} = \{P_i = (r_i, 0) \mid i \in \{1, 2, 3\}\}.$
 - \Rightarrow Correspondence between Weierstrass points of $\mathcal E$ and 2-torsion elements of $\mathcal E$.
- $e_2(P_i, P_j) = \begin{cases} -1 & \text{if } i \neq j, \\ 1 & \text{otherwise.} \end{cases}$

Genus-2 curve $C: y^2 = f(x)$

- $\mathcal{J}(\mathcal{C})[m] \cong (\mathbb{Z}/m\mathbb{Z})^4$ for $m \in \mathbb{N}$ with $p \nmid m$.
- The Weil pairing

$$e_m: \mathcal{J}(\mathcal{C})[m] \times \mathcal{J}(\mathcal{C})[m] \to \boldsymbol{\mu}_m$$

is a bilinear, alternating pairing.

Example: m = 2, $f = \prod_{i=1}^{6} (x - r_i)$

- $\mathcal{J}(\mathcal{C})[2] \setminus \{0\} = \{R_{ij} = J((x-r_i)(x-r_j),0) \mid i \neq j\}.$
 - \Rightarrow Correspondence between pairs of Weierstrass points of $\mathcal C$ and 2-torsion elements of $\mathcal J(\mathcal C)$.

$$e_2\left(R_{ij},R_{kl}\right) = \begin{cases} -1 & \text{if } |\{i,j\} \cap \{k,l\}| = 1, \\ 1 & \text{otherwise.} \end{cases}$$

(ℓ,ℓ) -isogenies with $\ell \neq p$

Elliptic Curves

- An ℓ -isogeny is an isogeny $\phi: \mathcal{E} \to \mathcal{E}' = \mathcal{E}/G$, where $G \cong \mathbb{Z}/\ell\mathbb{Z}$ (and $e_{\ell|_G} \equiv id$).
- Let (P,Q) be a (symplectic) basis for $\mathcal{E}[\ell]$. Then for any $a \in \mathbb{Z}/\ell\mathbb{Z}$, the group

$$G = \langle P + aQ \rangle$$

defines an ℓ -isogeny.

• In total: $\ell+1$ different ℓ -isogenies at $\mathcal E$ (we are missing the isogeny with kernel $G=\langle Q \rangle$ in the description above).

Jacobians of genus-2 curves

- An (ℓ,ℓ) -isogeny is an isogeny $\phi: \mathcal{J}(\mathcal{C}) \to \mathcal{A} = \mathcal{J}(\mathcal{C})/G$, where $G \cong (\mathbb{Z}/\ell\mathbb{Z})^2$ and $e_{\ell|_G} \equiv id$. $\Rightarrow G$ is called maximal ℓ -isotropic.
- Let (R_1, R_2, S_1, S_2) be a symplectic basis for $\mathcal{J}(\mathcal{C})[\ell]$, then for any $a, b, c \in \mathbb{Z}/\ell\mathbb{Z}$, the group

$$G = \langle R_1 + aS_1 + bS_2, R_2 + bS_1 + cS_2 \rangle$$

defines an (ℓ, ℓ) -isogeny.

• In total: $\ell^3 + \ell^2 + \ell + 1$ different ℓ -isogenies at $\mathcal{J}(\mathcal{C})$ (we are missing $\ell^2 + \ell + 1$ isogenies in the description above).

 $^{^2}$ In general, ${\cal A}$ is a principally polarized abelian surface. In most cases this is again the Jacobian of a genus-2 curve ${\cal C}'.$

(2,2)-Isogenies

Let $C: y^2 = g_1(x)g_2(x)g_3(x)$ with $g_i = g_{2,i}x^2 + g_{1,i}x + g_{0,i}$ and write

$$\delta = \det \begin{pmatrix} g_{1,0} & g_{1,1} & g_{1,2} \\ g_{2,0} & g_{2,1} & g_{2,2} \\ g_{3,0} & g_{3,1} & g_{3,2} \end{pmatrix}.$$

- The group $G = \langle J(g_1,0), J(g_2,0) \rangle = \{0, J(g_1,0), J(g_2,0), J(g_3,0)\}$ is maximal 2-isotropic.
- If $\delta \neq 0$, then $\mathcal{J}(\mathcal{C})/G = \mathcal{J}(\mathcal{C}')$, where

$$C': y^2 = h_1(x)h_2(x)h_3(x)$$
 with $h_i = \delta^{-1}(g'_{i+1}g_{i+2} - g_{i+1}g'_{i+2})$.

The isogeny $\phi: \mathcal{J}(\mathcal{C}) \to \mathcal{J}(\mathcal{C}')$ is called **Richelot isogeny**

Example
$$C: y^2 = x(x^2 - 1)(x^2 - 4)$$
 over \mathbb{F}_{11}

Set $G = \langle J(x^2 - x, 0), J(x^2 + 3x + 2, 0) \rangle$. This means

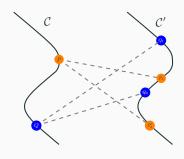
Hence
$$C': y^2 = 4x^6 + 5x^5 - 5x^4 - 2x^3 + x^2 - 2x - 1$$

Richelot correspondence

To compute the images of points under the Richelot isogeny $\phi: \mathcal{J}(\mathcal{C}) \to \mathcal{J}(\mathcal{C}')$, one can use the **Richelot correspondence**:

$$\mathcal{R}: \quad 0 = g_1(u)h_1(u') + g_2(u)h_2(u')$$
$$vv' = g_1(u)h_1(u')(u - u')$$

for points $(P, P') = ((u, v), (u', v')) \in \mathcal{C} \times \mathcal{C}'$.



The correspondence induces a map $\mathcal{J}(\mathcal{C}) o \mathcal{J}(\mathcal{C}')$:

$$[P+Q-D_{\infty}] \mapsto \underbrace{[P_1+P_2+Q_1+Q_2-2D_{\infty}']} = [P'+Q'-D_{\infty}'].$$

unreduced representation

Application of the Richelot correspondence

Example
$$C: y^2 = x(x^2 - 1)(x^2 - 4)$$

With $G = \langle J(x^2-x,0), J(x^2+3x+2,0) \rangle$, we obtain the correspondence

$$\mathcal{R}: \quad 0 = 4uu'^2 - u^2 - 5uu' + 2u'^2 - 2u + 3u' + 4,$$
$$vv' = (u^2 - u)(-u'^2 + 4u' - 3)(u - u').$$

Let's compute the image of the element $R = J(x^2 - x - 1, 2x - 4)$.

- $R = [(4,4) + (8,1) 2 \cdot \infty].$
- Set P = (4, 4) and Q = (8, 1).

$$\mathcal{R}_{(u,v)=P}$$
: $0 = -4(u'^2 - 4u' + 5) = -4(u' - 2 - i)(u' - 2 + i)$
 $4v' = -2u' - 3.$

So
$$P_1=(2+i,1-5i),\ P_2=(2-i,1+5i).$$
 Similarly: $Q_1=(-3,0),Q_2=(-4,-2).$

• $\phi(R) = [P_1 + P_2 + Q_1 + Q_2 - 2D_{\infty}] \in \mathcal{J}(\mathcal{C}')$ and it remains to compute the reduced form $[P' + Q' - D_{\infty}]$ using Cantor's algorithm.

Different methods for the evaluation of

Richelot isogenies

Methods I

Goal: Given an element $J(a,b) \in \mathcal{J}(\mathcal{C})(K)$, compute $\phi(J(a,b)) \in \mathcal{J}(\mathcal{C})(K)$.

- 0. Standard Algorithm (from the last slide):
 - Requires factorization of the polynomial a.
 - Divisors $[P_1 + P_2 D_{\infty}']$ and $[Q_1 + Q_2 D_{\infty}']$ are possibly not K-rational.
- Gröbner basis approach [Castryck-Decru '22]: Define

$$I = (a, y - b, y^{2} - f(x), g_{1}(x)h_{1}(x') + g_{2}(x)h_{2}(x'),$$
$$yy' - g_{1}(x)h_{1}(x')(x - x')) \subset K[x, y, x', y']$$

and compute the elimination ideal J with respect to x,y, i.e.

$$J = I \cap K[x', y'].$$

In the general case: $J=(a_{new}(x'),y'-b_{new}(x'))$, where $\deg(a_{new})=4$ and $\deg(b_{new})=3$. The pair (a_{new},b_{new}) is the (unreduced) Mumford presentation of $[P_1+P_2+Q_1+Q_2-2D_{\infty}]$.

- No factorizations or field extensions required.
- Gröbner basis computation is "short" and can also be made explicit (see
 e.g. the Sagemath implementation of the attack [Oudompheng, Pope '22]).

2. Explicit Formulae [K. '22]

General idea: Perform computations symbolically with coefficients in $\mathbb{Z}[g_{00},\ldots,g_{23},a_1,a_0,b_1,b_0].$

- $\Rightarrow \text{ Explicit formulae for the coefficients of the polynomials} \\ a_{new} = x^4 + a_3'x^3 + a_2'x^2 + a_1'x + a_0', \ b_{new} = b_3'x^3 + b_2'x^2 + b_1'x + b_0' \\ \text{with } a_i', b_i' \in \mathbb{Z}[g_{00}, \dots, g_{23}, a_1, a_0, b_1, b_0].$
- Problem: These formulae are huge and less efficient then the Gröbner basis computation with explicit values.

Solution: Introduce a new form of hyperelliptic equation (similar to Montgomery form for elliptic curves):

$$C: y^2 = E \cdot x(x^2 - Ax + 1)(x^2 - Bx + C)$$

- \Rightarrow Compact formulae for the polynomials $a_{new}\prime, b_{new}\prime$.
- As in approach 2, the computation of factorizations and field extensions is avoided.

3. Kummer surface approach

Recall: As a a variety, $\mathcal{J}(\mathcal{C})$ can be written as the zero-locus of 72 equations in \mathbb{P}^{15} . We consider the Kummer surface $\mathcal{K}=\mathcal{J}(\mathcal{C})/\langle\pm1\rangle$. Explicit representation in \mathbb{P}^3 :

$$\mathcal{K}: F(x_0, x_1, x_2, x_3) = 0$$
 for a quartic $F \in K[x_0, x_1, x_2, x_3]$.

We denote $K(\mathcal{C}) = \mathcal{K}$.

- $\mathcal K$ is *not* an abelian variety. In particular, the points on $\mathcal K$ do not form a group.
- Analogue to x-only arithmetic for elliptic curves.
- There exists an explicit representation for $\phi: \mathcal{K}(\mathcal{C}) \to \mathcal{K}(\mathcal{C}')$ corresponding to a (2,2)-isogeny $\phi: \mathcal{J}(\mathcal{C}) \to \mathcal{J}(\mathcal{C}')$ [Cassels-Flynn '96].
- There also exist (2, 2)-isogeny formulas on squared Kummer surfaces [Gaudry '07, Costello '18].

return [v0,v1,v2,v3]

Using the curve form $\mathcal{C}: y^2=(x^2-1)(x^2-A)(Ex^2-Bx+C)$, the map $\phi: \mathcal{K}(\mathcal{C}) \to \mathcal{K}(\mathcal{C}')$

has a very compact representation $\phi:(x_0,x_1,x_2,x_3)\mapsto M\cdot(x_0^2,x_0x_1,\ldots,x_3^2)$ with $M\in\mathbb{Z}[A,B,C,E]^{4\times 10}$, [K. (in preparation)].

```
def KummerRichelot(coefficients, point):
    [A,B,C,E] = coefficients
    [x0,x1,x2,x3] = point

y0 = (A*(E-C) - C)*x0^2 + C*x1^2 - B*x1*x2 + E*x2^2 + x0*x3
    y1 = A*B*x0^2 -2 (A*(C + E) + C)*x0*x1 + 2(A*E + C)*(C + E)/B*x1^2
    + B*(A + 1)*x0*x2 - 2*(A*E + C - E)*x1*x2 + B*x2^2 + x1*x3
    y2 = A*C*x0^2 - A*B*x0*x1 + A*E*x1^2 - (A*E - C + E)*x2^2 + x2*x3
    y3 = (A^2*(4*E^2 - B^2) - A*B^2)*x0^2 + A*B^2*x1^2 + 4*A*(2*C*E - A*B)*x0*x2
    - ((A + 1)*B^2 - 4*C^2)*x2^2 + 4*A*E*x0*x3 + 4*C*x2*x3 + x3^2
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