

# **Linear Algebra Methods for Data Mining**

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## **Lecture 3: QR, least squares, linear regression**

# QR decomposition

- Any matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ , can be transformed to upper triangular form by an orthogonal matrix:

$$\mathbf{A} = \mathbf{Q} \begin{pmatrix} \mathbf{R} \\ \mathbf{0} \end{pmatrix}$$

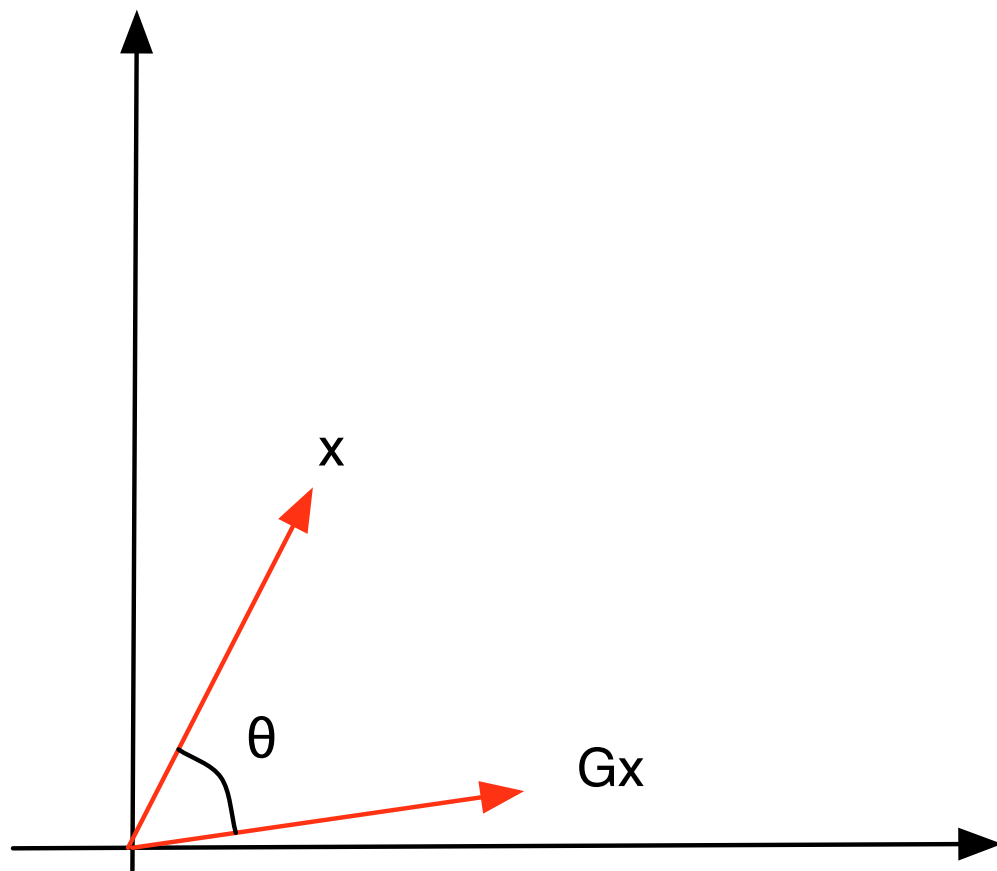
- If the columns of  $\mathbf{A}$  are linearly independent, then  $\mathbf{R}$  is non-singular.

## How? By using the Givens rotation:

Let  $\mathbf{x}$  be a vector. The parameters  $c$  and  $s$ ,  $c^2 + s^2 = 1$ , can be chosen so that multiplication of  $\mathbf{x}$  by

$$\mathbf{G} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & c & 0 & s \\ 0 & 0 & 1 & 0 \\ 0 & -s & 0 & c \end{pmatrix}$$

will zero the element 4 in vector  $\mathbf{x}$  by a rotation in plane (2,4). How?



# "Skinny" QR decomposition

Partition  $\mathbf{Q} = (\mathbf{Q}_1 \ \mathbf{Q}_2)$ , where  $\mathbf{Q}_1 \in \mathbb{R}^{m \times n}$ :

$$\mathbf{A} = (\mathbf{Q}_1 \ \mathbf{Q}_2) \begin{pmatrix} \mathbf{R}_1 \\ \mathbf{0} \end{pmatrix} = \mathbf{Q}_1 \mathbf{R}_1.$$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \\ 1 & 4 & 16 \end{bmatrix}$$

`[Q,R]=qr(A) %the QR decomposition`

$$Q = \begin{bmatrix} -0.5000 & 0.6708 & 0.5000 & 0.2236 \\ -0.5000 & 0.2236 & -0.5000 & -0.6708 \\ -0.5000 & -0.2236 & -0.5000 & 0.6708 \\ -0.5000 & -0.6708 & 0.5000 & -0.2236 \end{bmatrix}$$

$$R = \begin{bmatrix} -2.0000 & -5.0000 & -15.0000 \\ 0 & -2.2361 & -11.1803 \\ 0 & 0 & 2.0000 \\ 0 & 0 & 0 \end{bmatrix}$$

```
[Q,R]=qr(A,0)    %the skinny version of QR
```

```
Q =
```

```
-0.5000    0.6708    0.5000  
-0.5000    0.2236   -0.5000  
-0.5000   -0.2236   -0.5000  
-0.5000   -0.6708    0.5000
```

```
R =
```

```
-2.0000   -5.0000  -15.0000  
         0   -2.2361  -11.1803  
         0         0    2.0000
```

## Uniqueness?

Suppose  $\mathbf{A} \in \mathbb{R}^{m \times n}$  has full column rank (i.e. the column vectors are linearly independent). The "skinny" QR factorization

$$\mathbf{A} = \mathbf{Q}_1 \mathbf{R}_1$$

is unique where  $\mathbf{Q}_1$  has orthonormal columns and  $\mathbf{R}_1$  is upper triangular with positive diagonal entries.



# What is QR good for?

- It will come up when we discuss the computation of some matrix decompositions
- It can also be used for solving the least squares problem.
- Other applications exist.

# Least squares for linear regression

- Consider problems of the following form: given a number of measurements  $\mathbf{X} = [\mathbf{x}_1 \dots \mathbf{x}_n]$  and an outcome  $y$ , build a linear model

$$\hat{y} = b_0 + \sum_{j=1}^n \mathbf{x}_j b_j,$$

which uses the measurements  $\mathbf{X}$  to predict the outcome  $y$ .

- $\mathbf{X}$  = clinical measures of patients,  $y$  = level of cancer specific antigen.
- $\mathbf{X}$  = atmospheric measurements of each day,  $y$  = occurrence of spontaneous particle formation.

# Least squares for linear regression

- The model  $\hat{y} = b_0 + \sum_{j=1}^n \mathbf{x}_j b_j$  can be written in the form

$$\hat{y} = \mathbf{X}^T \mathbf{b}, \quad \mathbf{b} = (b_1 \dots b_n b_0)^T.$$

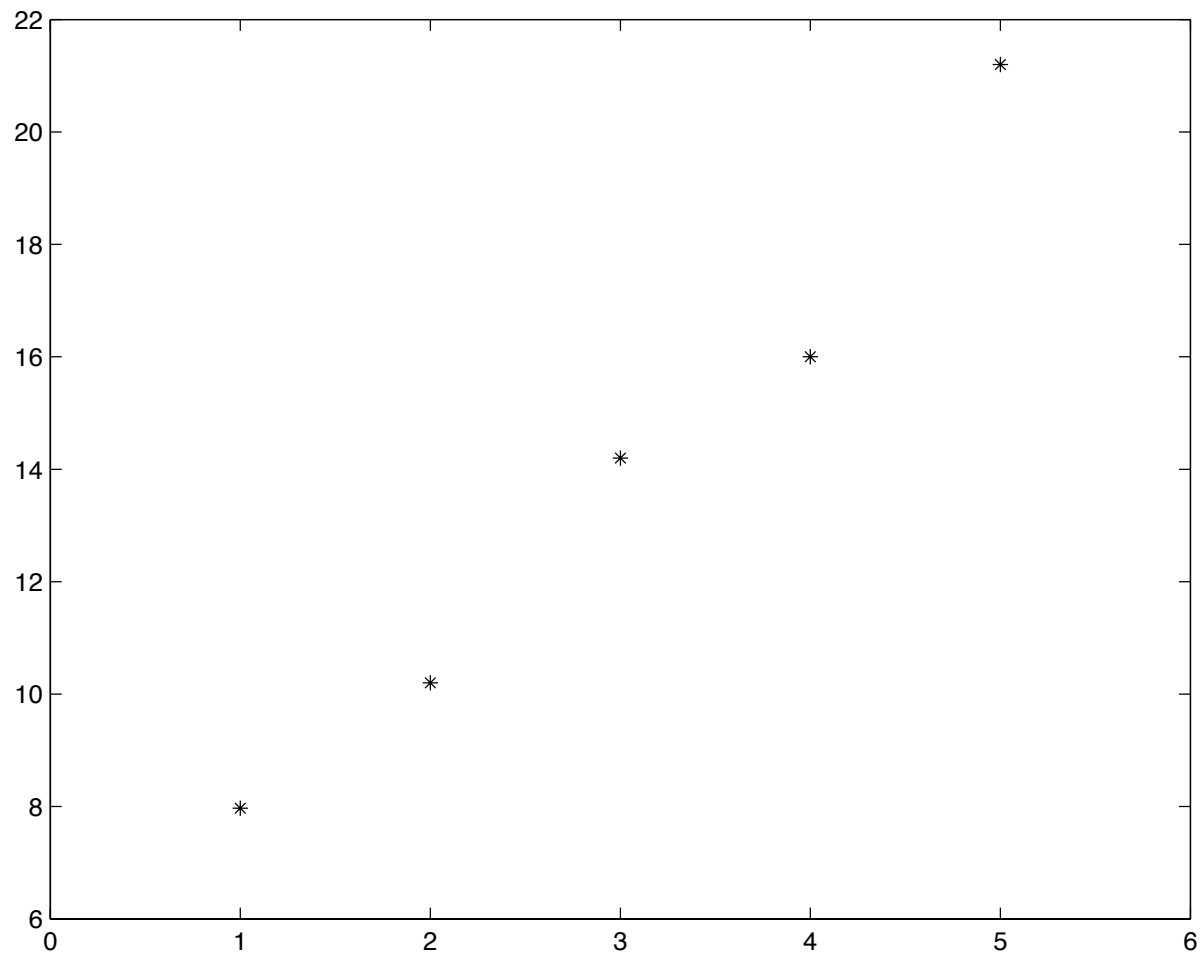
To do this, one must append  $\mathbf{X} = [\mathbf{x}_1 \dots \mathbf{x}_n \mathbf{x}_{n+1}]$ , where  $\mathbf{x}_{n+1}$  is a vector of ones.

- Fitting a linear model to data is usually done using the method of least squares.
- Note:  $\mathbf{X}$  need not be a square matrix!

# Example

We have measurement data:

$x$	1	2	3	4	5
$y$	7.97	10.2	14.2	16.0	21.2



## Example (continued)

$x$	1	2	3	4	5
$y$	7.97	10.2	14.2	16.0	21.2

We wish to find  $\alpha$  and  $\beta$  such that  $\alpha x + \beta = y$ . Thus

$$\alpha + \beta = 7.97$$

$$2\alpha + \beta = 10.2$$

$$3\alpha + \beta = 14.2$$

$$4\alpha + \beta = 16.0$$

$$5\alpha + \beta = 21.2$$

## Example (continued)

In matrix form:

$$\begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \\ 4 & 1 \\ 5 & 1 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 7.97 \\ 10.2 \\ 14.2 \\ 16.0 \\ 21.2 \end{pmatrix}$$

Overdetermined! (More equations than unknowns.)

Solve using the least squares method.

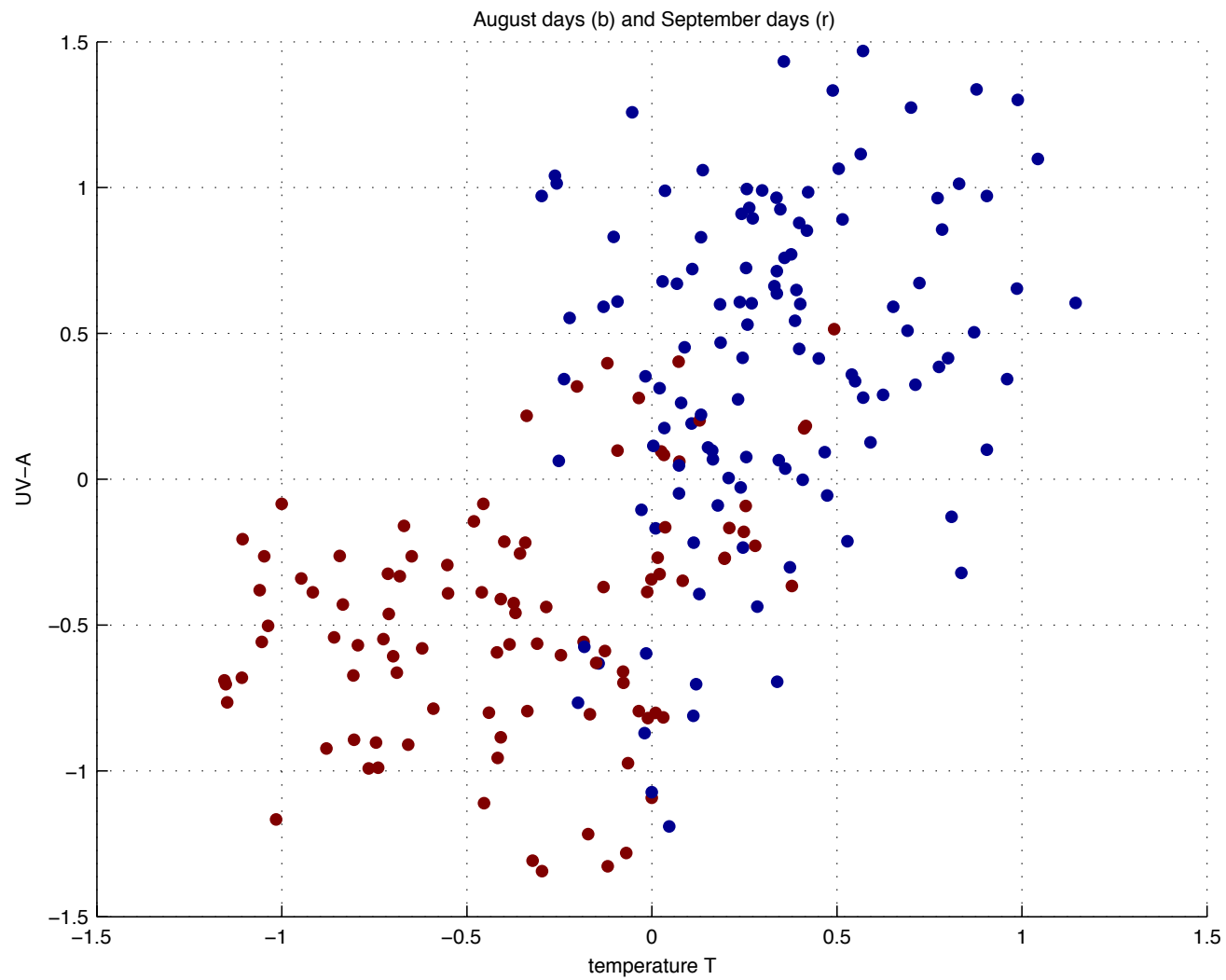
## Example

- $\mathbf{X}$  = atmospheric measurements of each day: temperature, UV-A:

$$\mathbf{X} = \begin{pmatrix} t_1 & t_2 & \dots & t_n \\ r_1 & r_2 & \dots & r_n \end{pmatrix} = \begin{pmatrix} \text{temperatures} \\ \text{UV-A measurements} \end{pmatrix}$$

- $\mathbf{y}$  = which month each day belongs to. Choices are:  
August ( $y = 0$ ) or September ( $y = 1$ ).
- Looking for  $\mathbf{b}$  such that  $\hat{\mathbf{y}} = \mathbf{X}^T \mathbf{b}$  and  $\hat{\mathbf{y}} \approx \mathbf{y}$ .  
Use method of least squares.





# The least squares problem

- Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ . The system

$$\mathbf{Ax} = \mathbf{b}$$

is called **overdetermined**: more equations than unknown. Usually such a system has no solution.

# Example

$$m = 3, n = 2.$$

## What to do?

- make the **residual vector**

$$\mathbf{r} = \mathbf{b} - \mathbf{A}\mathbf{x}$$

as small as possible. But how?

- Make  $\mathbf{r}$  orthogonal to the columns of  $\mathbf{A}$ :

$$\mathbf{r}^T (\mathbf{a}_1 \quad \mathbf{a}_2 \quad \dots \quad \mathbf{a}_n) = \mathbf{r}^T \mathbf{A} = 0.$$

- Now write  $\mathbf{r} = \mathbf{b} - \mathbf{A}\mathbf{x}$  to get the **normal equations**

$$\mathbf{A}^T \mathbf{A} \mathbf{x} = \mathbf{A}^T \mathbf{b}; \quad \text{solve for } \mathbf{x}.$$

# Example

```
A=      1      1      b= 7.97
        2      1      10.2
        3      1      14.2
        4      1      16.0
        5      1      21.2
```

```
C=A' * A      %Normal equations
```

```
C=      55      15
        15       5
```

```
x=C \ (A' * b)
```

```
x=      3.2260
        4.2360
```

- If the column vectors of  $\mathbf{A}$  are linearly independent, then the normal equations

$$\mathbf{A}^T \mathbf{A} \mathbf{x} = \mathbf{A}^T \mathbf{b}$$

are non-singular and have a unique solution

- BUT: the normal equations have two significant drawbacks:
  - forming  $\mathbf{A}^T \mathbf{A}$  leads to loss of information.
  - the condition number of  $\mathbf{A}^T \mathbf{A}$  is the square of that of  $\mathbf{A}$ :

$$\kappa(\mathbf{A}^T \mathbf{A}) = (\kappa(\mathbf{A}))^2$$

# Example

A =

1	1
2	1
3	1
4	1
5	1

$\text{cond}(A) = 8.3657$

$\text{cond}(A' * A) = 69.9857$

## Worse example

A =

101	1
102	1
103	1
104	1
105	1

$\text{cond}(A) = 7.5038\text{e}+03$

$\text{cond}(A' * A) = 5.6307\text{e}+07$



# Solving least squares problem using QR

$$\begin{aligned}\|\mathbf{r}\|^2 &= \|\mathbf{b} - \mathbf{A}\mathbf{x}\|^2 = \|\mathbf{b} - \mathbf{Q} \begin{pmatrix} \mathbf{R} \\ \mathbf{0} \end{pmatrix} \mathbf{x}\|^2 = \|\mathbf{Q}(\mathbf{Q}^T \mathbf{b} - \begin{pmatrix} \mathbf{R} \\ \mathbf{0} \end{pmatrix} \mathbf{x})\|^2 \\ &= \|\mathbf{Q}^T \mathbf{b} - \begin{pmatrix} \mathbf{R} \\ \mathbf{0} \end{pmatrix} \mathbf{x}\|^2\end{aligned}$$

Partition  $\mathbf{Q} = (\mathbf{Q}_1 \ \mathbf{Q}_2)$ , where  $\mathbf{Q}_1 \in \mathbb{R}^{m \times n}$ , and denote

$$\mathbf{Q}^T \mathbf{b} = \begin{pmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \end{pmatrix} := \begin{pmatrix} \mathbf{Q}_1^T \mathbf{b} \\ \mathbf{Q}_2^T \mathbf{b} \end{pmatrix}.$$

Then

$$\|\mathbf{r}\|^2 = \left\| \begin{pmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \end{pmatrix} - \begin{pmatrix} \mathbf{R} \\ \mathbf{0} \end{pmatrix} \mathbf{x} \right\|^2 = \|\mathbf{b}_1 - \mathbf{R}\mathbf{x}\|^2 + \|\mathbf{b}_2\|^2.$$

Minimize  $\|\mathbf{r}\|$  by making the first term equal to zero: i.e. solve

$$\mathbf{R}\mathbf{x} = \mathbf{b}_1.$$

# LS by QR

**Theorem.** Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$  have full column rank and a thin QR-decomposition  $\mathbf{A} = \mathbf{Q}_1 \mathbf{R}$ . Then the least squares problem

$$\min_x \|\mathbf{Ax} - \mathbf{b}\|_2$$

has the unique solution

$$\mathbf{x} = \mathbf{R}^{-1} \mathbf{Q}_1^T \mathbf{b}.$$

# Example

```
A=      1      1      b= 7.97
      2      1      10.2
      3      1      14.2
      4      1      16.0
      5      1      21.2
```

```
[Q1,R]=qr(A,0) %skinny QR
```

```
Q1 = -0.1348    -0.7628
     -0.2697    -0.4767
     -0.4045    -0.1907
     -0.5394     0.0953
     -0.6742     0.3814
```

$$R = \begin{pmatrix} -7.4162 & -2.0226 \\ 0 & -0.9535 \end{pmatrix}$$

$$x = R \backslash (Q1' * b)$$

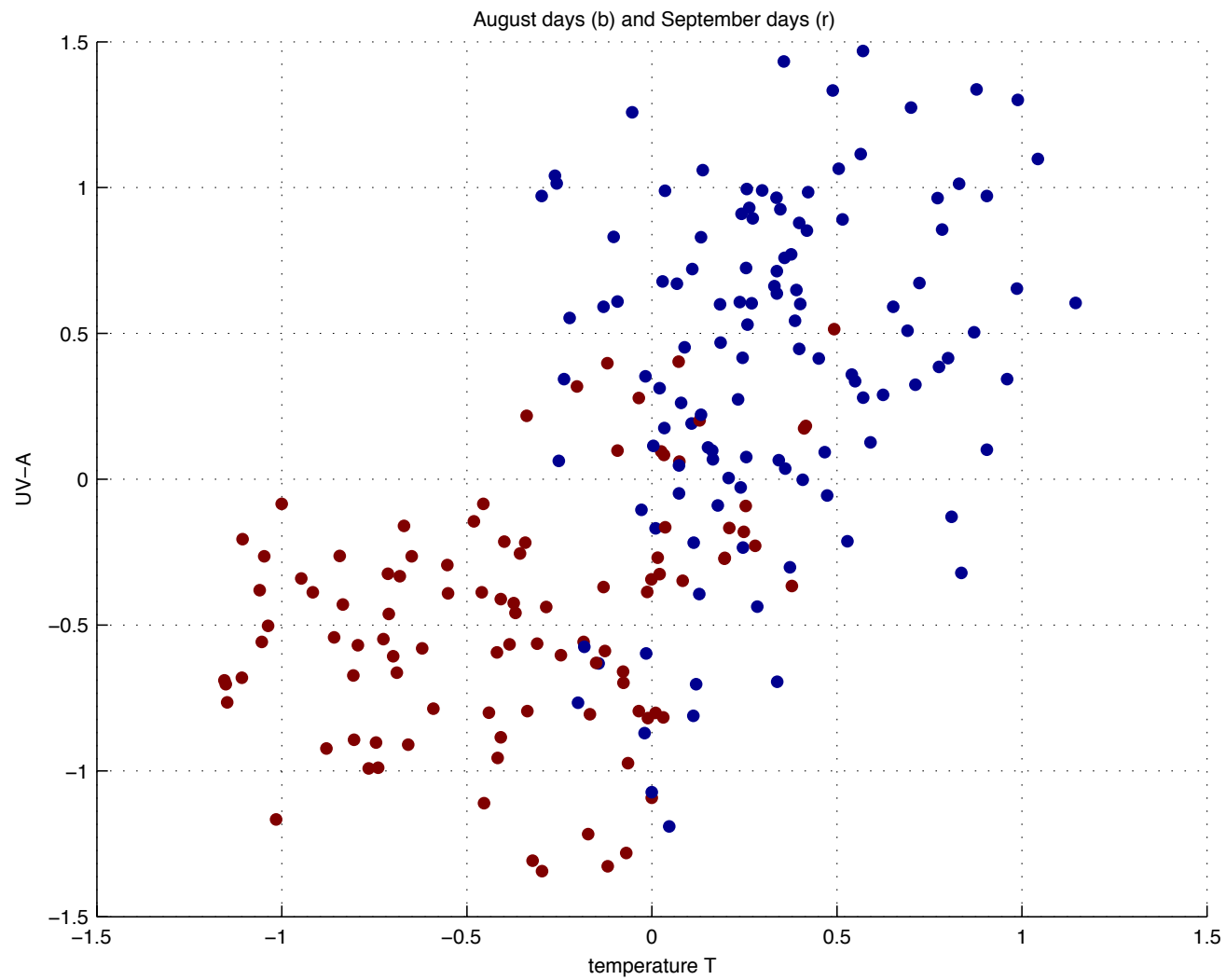
$$x = \begin{pmatrix} 3.2260 \\ 4.2360 \end{pmatrix}$$

## Back to this example:

- $\mathbf{X}$  = atmospheric measurements of each day: temperature, UV-A:

$$\mathbf{X} = \begin{pmatrix} t_1 & t_2 & \dots & t_n \\ r_1 & r_2 & \dots & r_n \end{pmatrix} = \begin{pmatrix} \text{temperatures} \\ \text{UV-A measurements} \end{pmatrix}$$

- $y$  = which month each day belongs to. Choices are:  
August ( $y = 0$ ) or September ( $y = 1$ ).
- Looking for  $\mathbf{b}$  such that  $\hat{y} = \mathbf{X}^T \mathbf{b}$  and  $\hat{y} \approx y$ .  
Use method of least squares.



## Example

%X (transpose of) data matrix, 1st col: temperature, 2nd col: UV-A  
%y month vector, y(j)=0 if August and 1 if September

```
[length(find(y==0)) length(find(y==1))] =    116    99
                                     %number of August and September days
```

```
size(X) =    215    2    %size of data matrix
Xap=[X ones(215,1)];
```

```
[Q1,R]=qr(Xap,0);
```

```
b=R\ (Q1'*y) %this is the same as b=inv(R)*(Q1'*y)
b=    -0.4355
      -0.2923
       0.4605
```



```

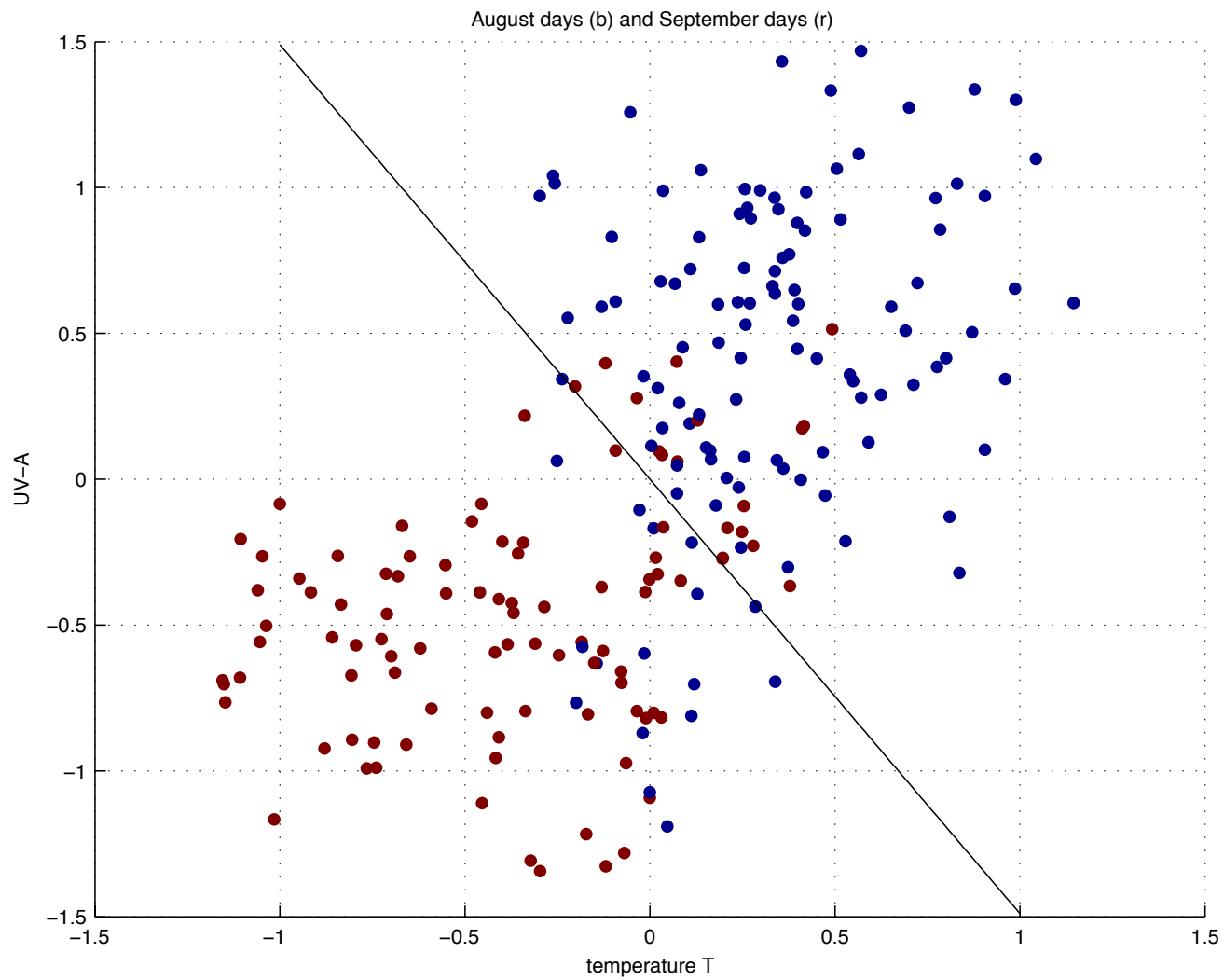
yhat=Xap*b; %least squares solution
[min(yhat) max(yhat)] =    -0.3506    1.2436

alpha=0.5;          %day classified as September if x'y>alpha
length(find(1.0*(yhat>alpha)-y)) =    34          %misclassifications
x=-1:0.01:1;db=(alpha-b(3)-b(1)*x)/b(2);%decision boundary x'b=alpha

%attn: in reality, choose alpha with more care!

scatter(Xnorm(:,1),Xnorm(:,2),20,y,'filled')
hold;plot(x,db,'k')

```



# Updating the solution of the LS problem

Assume we have reduced the matrix and the right hand side

$$(\mathbf{A} \quad \mathbf{b}) \rightarrow \mathbf{Q}^T(\mathbf{A} \quad \mathbf{b}) = \begin{pmatrix} \mathbf{R} & \mathbf{Q}_1^T \mathbf{b} \\ \mathbf{0} & \mathbf{Q}_2^T \mathbf{b} \end{pmatrix}.$$

From this the solution of the LS problem is readily available.

Assume we have not saved  $\mathbf{Q}$ .

We then get a new observation  $(\mathbf{a} \quad b)$ ,  $\mathbf{a} \in \mathbb{R}^n$ ,  $b \in \mathbb{R}$ .

Do we have to recompute the whole solution?

# Updating the solution of the LS problem

No. Instead, write the reduction on the previous slide as

$$\begin{pmatrix} \mathbf{A} & \mathbf{b} \\ \mathbf{a}^T & b \end{pmatrix} \rightarrow \begin{pmatrix} \mathbf{Q}^T & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \mathbf{A} & \mathbf{b} \\ \mathbf{a}^T & b \end{pmatrix} = \begin{pmatrix} \mathbf{R} & \mathbf{Q}_1^T \mathbf{b} \\ \mathbf{0} & \mathbf{Q}_2^T \mathbf{b} \\ \mathbf{a}^T & b \end{pmatrix}.$$

And reduce this to triangular form using plane rotations.

# References

- [1] Lars Eldén: Matrix Methods in Data Mining and Pattern Recognition, SIAM 2007.
- [2] G. H. Golub and C. F. Van Loan. Matrix Computations. 3rd ed. Johns Hopkins Press, Baltimore, MD., 1996.
- [3] T. Hastie, R. Tibshirani, J. Friedman: The Elements of Statistical Learning. Data mining, Inference and Prediction, Springer Verlag, New York, 2001.