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by Jakub Bomba (axon)

When deciding on the best sorting algorithm we often look at its worst-case running time, and base our decision solely on that factor. That is why beginning programmers often overlook quicksort as a viable option because of its T(n^2) worst-case running time, which could be made exponentially unlikely with a little effort. In fact, quicksort is the currently fastest known sorting algorithm and is often the best practical choice for sorting, as its average expected running time is $O(n \log(n))$.

Quicksort, like mergesort, is a divide-and-conquer recursive algorithm. The basic divide-and-conquer process for sorting a subarray S[p..r] is summarized in the following three easy steps:

Divide: Partition S[p..r] into two subarrays S[p..q-1] and S[q+1..r] such that each element of S[p..q-1] is less than or equal to S[q], which is, in turn, less than or equal to each element of S[q+1..r]. Compute the index q as part of this partitioning procedure

Conquer: Sort the two subarrays S[p...q-1] and S[q+1..r] by recursive calls to quicksort.

Combine: Since the subarrays are sorted in place, no work is needed to combing them: the entire array S is now sorted.

Before a further discussion and analysis of guicksort a presentation of its implementation procedure below:

```
QUICKSORT(S, P, r)
1 \text{ If } p < r
2
        then q <- PARTITION(S, p, r)
3
                 QUICKSORT(S, p, q-1)
4
                  QUICKSORT(S, q+1, r)
```

note: to sort the whole array S, the initial parameters would be: QUICKSORT(S, 1, length[A])

```
PARTITION(S, p, r)
1 \times < - S[r]
2 i <- p-1
```

Quicksort's running time depends on the result of the partitioning routine - whether it's balanced or unbalanced. This is determined by the **pivot** element used for partitioning. If the result of the partition is unbalanced, quicksort can run as slowly as insertion sort; if it's balanced, the algorithm runs asymptotically as fast as merge sort. That is why picking the "best" pivot is a crucial design decision.

The Wrong Way: the popular way of choosing the pivot is to use the first element; this is acceptable only if the input is random, but if the input is presorted, or in the reverse order, then the first elements provides a bad, unbalanced, partition. All the elements go either into S[p...q-1] or S[q+1..r]. If the input is presorted and as the first element is chosen consistently throughout the recursive calls, quicksort has taken quadratic time to do nothing at all.

The Safe Way: the safe way to choose a pivot is to simply pick one randomly; it is unlikely that a random pivot would consistently provide us with a bad partition throughout the course of the sort.

Median-of-Three Way: best case partitioning would occur if PARTITION produces two subproblems of almost equal size - one of size [n/2] and the other of size [n/2]-1. In order to achieve this partition, the pivot would have to be the median of the entire input; unfortunately this is hard to calculate and would consume much of the time, slowing down the algorithm considerably. A decent estimate can be obtained by choosing three elements randomly and using the median of these three as the pivot.

Short Example of a Quicksort Routine (Pivots chosen "randomly")

```
Input: [13 81 92 65 43 31 57 26 75 0]
Pivot: 65
Partition: [13 0 26 43 31 57] 65 [ 92 75 81]
Pivot: 31 81
Partition: [13 0 26] 31 [43 57] 65 [75] 81 [92]
Pivot: 13
Partition: [0] 13 [26] 31 [43 57] 65 [75] 81 [92]
Combine: [0 13 26] 31 [43 57] 65 [75 81 92]
Combine: [0 13 26 31 43 57] 65 [75 81 92]
Combine: [0 13 26 31 43 57 65 75 81 92]
```

Summary

Quicksort is a relatively simple sorting algorithm using the divide-and-conquer recursive procedure. It is the quickest comparison-based sorting algorithm in practice with an average running time of O(n log(n)). Crucial to quicksort's speed is a balanced partition decided by a well chosen pivot. Quicksort has the advantage of sorting in place, and it works well even in virtual memory environments.

Previous: Merge Sort