Computer Architecture and Operating SystemsMONSOON SEMESTER 2019

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Custom System Call

To find and print content from the task_struct of a process from its "pid" and save it to a file.

Synopsis of Implementation:

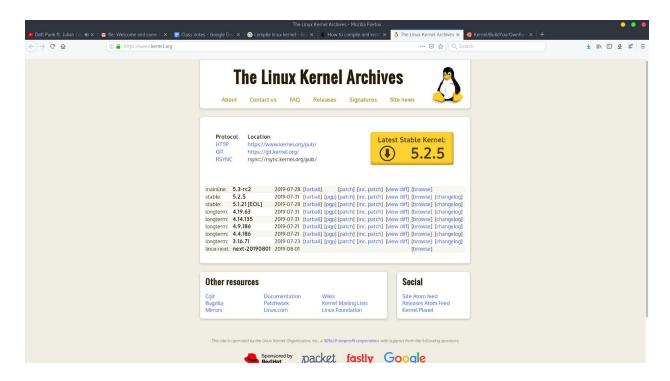
The /kernel/pid.c has defined the method pid_task which can be used to retrieve the task_struct of a process.

```
struct task_struct *pid_task(struct pid *pid, enum pid_type
type)
{
    //
}
```

The input process is then loaded in the task struct. The task struct loads from the /include/linux/sched.h. Any of the parameters of the task_struct specified in sched.h can be printed.

Since only other kernel system calls can be used in a system call, hence to write content to a file, a pointer to array of pointers of long is passed in the system call which is then populated by parameters of *task_struct* using the *copy_from_user* and *copy_to_user* syscalls.

Step 1: Start by downloading the linux kernel from kernel.org.



Step 2: Extract the kernel and make a copy of it.

```
root@Alium:~/Downloads# unxz -v linux-5.2.5.tar.xz balls
linux-5.2.5.tar.xz (1/1) with gpg command
100 % 102.1 MiB / 831.0 MiB = 0.123 127 MiB/s 0:06
root@Alium:~/Downloads#
```

Step 3: Install the necessary development tools and GCC.

```
root@kali:~/Downloads/linux-5.2.5# apt-get install build-essential libncurses-dev bison f
lex libssl-dev libelf-dev
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following additional packages will be installed:
   binutils binutils-common binutils-x86-64-linux-gnu cpp cpp-8 g++ g++-8 gcc gcc-8
   gcc-8-base gcc-9-base libasan5 libatomic1 libbinutils libbison-dev libccl-0 libdwl
   libelf1 libfl-dev libfl2 libgcc-8-dev libgcc1 libgomp1 libisl19 libitm1 liblsan0
```

Step 4: Create a new directory in one of the copies of the extracted linux kernel. Create the system call in this dir.

Step 5: Using asmlinkage, we tell compiler to look on the CPU stack for the function parameters, instead of registers.

Step 6: We pass the pid(int), the filename(char*) and a buffer(long**) as parameters for the system call.

Step 7: Using *find_vpid*, we search for our valid pid in the task_struct. If the struct value returns NULL, then the pid is not valid.

Step 8: Since, only other system calls can be used, we use printk to print messages from the kernel which can be checked using dmesg.

Step 9: To populate our buffer, we use the *copy_from_user* and *copy_to_user* syscalls.

Step 10: Compile the syscall with the Makefile and fix any error that shows up.

Step 11: The custom syscall is added to the systemcall table located at /arch/x8/entry/syscalls/syscall_64.tbl. Add the syscall at a new id.

333 common sys_sh_task_info sys_sh_task_info

Step 12: The custom syscall is to be now added to syscalls.h which is located at /include/linux/syscalls.h. Add the syscall before the #endif.

asmlinkage long sys_sh_task_info(int pid,char *filename,long **buf);
#endif

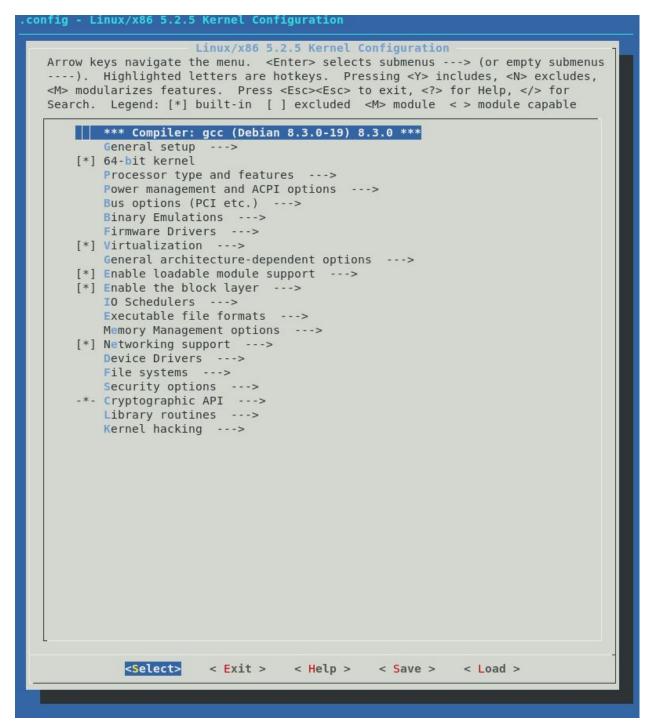
Step 14: Configure the Makefile of the kernel located at the parent directory. Find the below string:

```
core-y += kernel/ certs/ mm/ fs/ ipc/ security/ crypto/
block/
```

And Replace it with:

```
core-y += kernel/ certs/ mm/ fs/ ipc/ security/ crypto/
block/ <directory with custom syscall>
```

Step 15: Compile the linux kernel. Save the .config file using *make menuconfig* command.



Step 16: Customize the kernel at the menuconfig.

Step 17: Compile the kernel.

Command: make -j \$(nproc)

```
arch/x86/tools/relocs 64.0
       arch/x86/tools/relocs common.o
HOSTCC
HOSTLD
       arch/x86/tools/relocs
UPD
        include/config/kernel.release
WRAP
        arch/x86/include/generated/uapi/asm/bpf perf event.h
WRAP
        arch/x86/include/generated/uapi/asm/poll.h
WRAP
       arch/x86/include/generated/uapi/asm/socket.h
WRAP
        arch/x86/include/generated/uapi/asm/sockios.h
WRAP
       arch/x86/include/generated/asm/dma-contiguous.h
WRAP
       arch/x86/include/generated/asm/early ioremap.h
WRAP
       arch/x86/include/generated/asm/export.h
WRAP
        arch/x86/include/generated/asm/mcs spinlock.h
WRAP
        arch/x86/include/generated/asm/mm-arch-hooks.h
WRAP
        arch/x86/include/generated/asm/mmiowb.h
UPD
        include/generated/uapi/linux/version.h
UPD
        include/generated/utsrelease.h
HOSTCC
       scripts/genksyms/genksyms.o
        scripts/genksyms/parse.tab.c
H0STCC
       scripts/genksyms/parse.tab.o
LEX
        scripts/genksyms/lex.lex.c
        scripts/genksyms/parse.tab.h
HOSTCC
       scripts/genksyms/lex.lex.o
HOSTLD scripts/genksyms/genksyms
HOSTCC scripts/selinux/genheaders/genheaders
HOSTCC scripts/selinux/mdp/mdp
HOSTCC scripts/bin2c
HOSTCC scripts/kallsyms
```

Step 18: On successful compilation, install the modules.

Command: make modules_install

```
@kali:~/Downloads/linux-5.2.6# make -j $(nproc)
  CALL scripts/checksyscalls.sh
         scripts/atomic/check-atomics.sh
 CALL
 DESCEND objtool
         include/generated/compile.h
Kernel: arch/x86/boot/bzImage is ready (#1)
  Building modules, stage 2.
 MODPOST 3297 modules
 oot@kali:~/Downloads/linux-5.2.6# make modules install
 INSTALL arch/x86/crypto/aes-x86 64.ko
  INSTALL arch/x86/crypto/aesni-intel.ko
 INSTALL arch/x86/crypto/blowfish-x86 64.ko
 INSTALL arch/x86/crypto/camellia-aesni-avx-x86 64.ko
 INSTALL arch/x86/crypto/camellia-aesni-avx2.ko
 INSTALL arch/x86/crypto/camellia-x86 64.ko
  INSTALL arch/x86/crypto/cast5-avx-x86 64.ko
 INSTALL arch/x86/crypto/cast6-avx-x86 64.ko
 INSTALL arch/x86/crypto/chacha-x86 64.ko
 INSTALL arch/x86/crypto/crc32-pclmul.ko
 INSTALL arch/x86/crypto/crc32c-intel.ko
 INSTALL arch/x86/crvpto/crct10dif-pclmul.ko
```

Step 19: Install the kernel and reboot.

Command: make install

```
kali:~/Downloads/linux-5.2.6# sudo make install
sh ./arch/x86/boot/install.sh 5.2.6 arch/x86/boot/bzImage \
       System.map "/boot"
run-parts: executing /etc/kernel/postinst.d/apt-auto-removal 5.2.6 /boot/vmlinuz
run-parts: executing /etc/kernel/postinst.d/initramfs-tools 5.2.6 /boot/vmlinuz-
5.2.6
update-initramfs: Generating /boot/initrd.img-5.2.6
WARNING: Setting CRYPTSETUP in /etc/initramfs-tools/initramfs.conf is deprecated
and will stop working in the future. Use /etc/cryptsetup-initramfs/conf-hook in
run-parts: executing /etc/kernel/postinst.d/unattended-upgrades 5.2.6 /boot/vmli
nuz-5.2.6
run-parts: executing /etc/kernel/postinst.d/zz-update-grub 5.2.6 /boot/vmlinuz-5
Generating grub configuration file ...
Found background image: /usr/share/images/desktop-base/desktop-grub.png
Found linux image: /boot/vmlinuz-5.2.6
Found initrd image: /boot/initrd.img-5.2.6
Found linux image: /boot/vmlinuz-4.15.0-kali2-amd64
Found initrd image: /boot/initrd.img-4.15.0-kali2-amd64
```

A custom Linux has been successfully installed.

Step 20: Check the custom syscall in a test C file.

FIN!

Files: sys_task_info.c

```
#include<linux/kernel.h>
#include<linux/init.h>
#include<linux/sched.h>
#include<linux/syscalls.h>
#include<linux/sched.h>
#include <linux/slab.h>
asmlinkage long sys_sh_task_info(int pid,char *filename,long **buf)
  struct task_struct *task;
  struct pid *pid_str;
  pid_str=find_vpid(pid);
  task=pid_task(pid_str, PIDTYPE_PID);
  if (task == NULL)
    printk(KERN_ERR "No Process with given PID\n");
    return 3;
 else
    long buf_kernel[50];
```

```
long *user_ptrs[50];
    unsigned long res;
    int i;
    printk(KERN_ERR "Process: %s\n", task->comm);
    printk(KERN_ERR "PID: %ld\n", (long)task_pid_nr(task));
    printk(KERN_ERR "Process State: %ld\n", (long)task->state);
    printk(KERN_ERR "Priority: %ld\n", (long)task->prio);
    printk(KERN_ERR "Process Exit State: %ld\n",
(long)task->exit_state);
    printk(KERN_ERR "Process Exit Code: %ld\n",
(long)task->exit_code);
    printk(KERN_ERR "Process Exit Signal: %ld\n",
(long)task->exit_signal);
    printk(KERN_ERR "Process RT Priority: %ld\n",
(long)task->rt_priority);
    printk(KERN_ERR "Process Static Priority: %ld\n",
(long)task->static_prio);
    printk(KERN_ERR "Process Normal Priority: %ld\n",
(long)task->normal_prio);
    printk(KERN_ERR "Creating File....");
    buf_kernel[0]=(long)task_pid_nr(task);
    buf_kernel[1]=(long)task->state;
    buf_kernel[2]=(long)task->prio;
```

```
buf_kernel[3]=(long)task->exit_state;
    buf_kernel[4]=(long)task->exit_code;
    buf_kernel[5]=(long)task->exit_signal;
    buf_kernel[6]=(long)task->rt_priority;
    buf_kernel[7]=(long)task->static_prio;
    buf_kernel[8]=(long)task->normal_prio;
    res = copy_from_user(user_ptrs,buf,sizeof(long *)* 50);
    for (i=0; i<50; i++)
      res=copy_to_user(user_ptrs[i],&buf_kernel[i],sizeof(long));
    return 0;
}
```

Makefile for System Call

Test C file for System Call

```
#include <stdio.h>
#include <linux/kernel.h>
#include <sys/syscall.h>
#include <unistd.h>
#include <stdlib.h>
#define sys_sh_task_info 333
int main()
{
     const int size = 10;
     long **buf = malloc(sizeof(long *) * size);
     for(int i=0; i<size; i++) buf[i] = malloc(sizeof(long));</pre>
     int sys = syscall(sys_sh_task_info,"232145","lol.txt",buf);
     printf("%d\n", sys);
     if (sys==3)
     {
```

```
printf("Error Code: %ld\n", sys);
     printf("Error Name: ESRCH 3 No such process.PID Wrong!");
}
else if(sys==-1)
{
     printf("Error Code: %ld\n", sys);
     printf("Error Name: EIO 5 Input/output error");
}
else
{
     printf("PID: %ld\n", *buf[0]);
     printf("Process State: %ld\n", *buf[1]);
     printf("Priority: %ld\n", *buf[2]);
     printf("Process Exit State: %ld\n", *buf[3]);
     printf("Process Exit Code: %ld\n", *buf[4]);
     printf("Process Exit Signal: %ld\n", *buf[5]);
     printf("Process RT Priority: %ld\n", *buf[6]);
     printf("Process Static Priority: %ld\n", *buf[7]);
```

```
printf("Process Normal Priority: %ld\n", *buf[8]);
printf("Creating File....\n");
FILE *fp = fopen("lol.txt", "ab+");
fprintf(fp, "----\n");
fprintf(fp, "PID: %ld\n", *buf[0]);
fprintf(fp, "Process State: %ld\n", *buf[1]);
fprintf(fp, "Priority: %ld\n", *buf[2]);
fprintf(fp, "Process Exit State: %ld\n", *buf[3]);
fprintf(fp, "Process Exit Code: %ld\n", *buf[4]);
fprintf(fp, "Process Exit Signal: %ld\n", *buf[5]);
fprintf(fp, "Process RT Priority: %ld\n", *buf[6]);
fprintf(fp, "Process Static Priority: %ld\n", *buf[7]);
fprintf(fp, "Process Normal Priority: %ld\n", *buf[8]);
fclose(fp);
```

}

```
// printf("%ld", *buf[0]);
return 0;
}
```