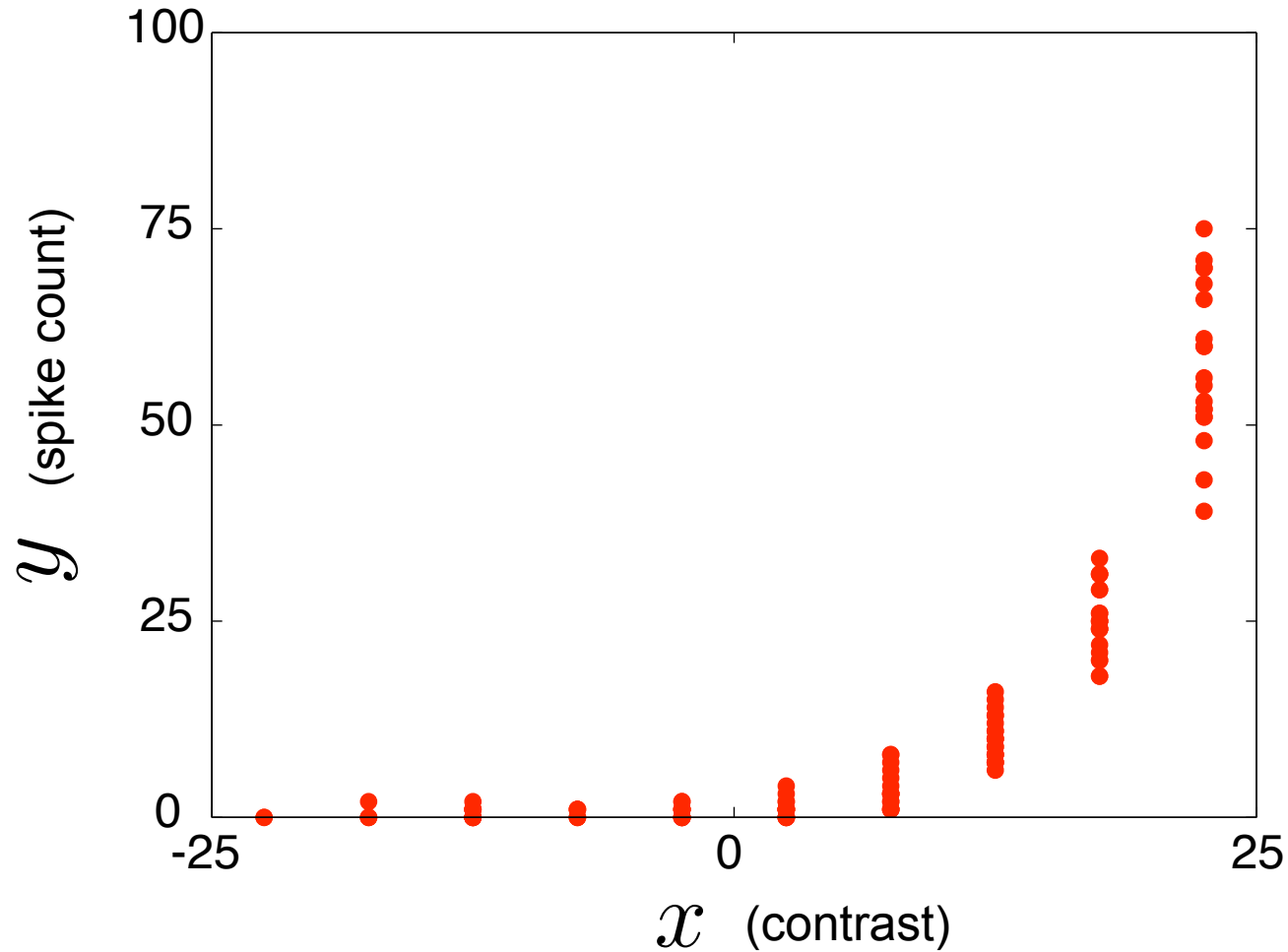


Statistical modeling and analysis of neural data
NEU 560, Spring 2018
Lecture 9

Generalized Linear Models (GLMs)

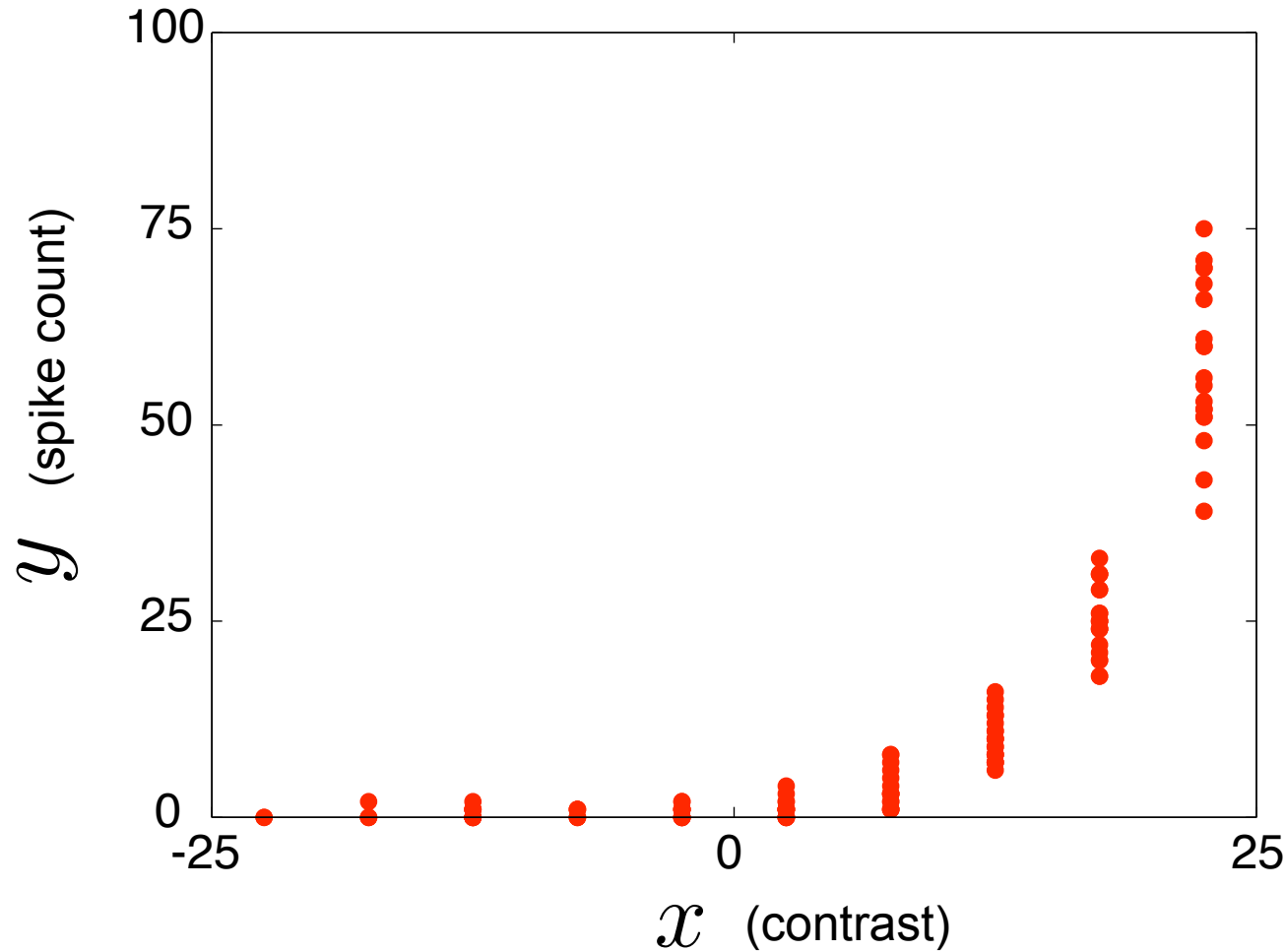
Jonathan Pillow

Example 3: unknown neuron



Be the computational neuroscientist: what model would you use?

Example 3: unknown neuron



More general setup: $y \sim \text{Pois}(\lambda)$

$$\lambda = f(\theta x)$$

for some nonlinear
function f

Quick Quiz:

The distribution $P(y|x, \theta)$ can be considered as a function of y , x , or θ .

spikes stimulus parameters



What is $P(y|x, \theta)$:

1. as a function of y ?

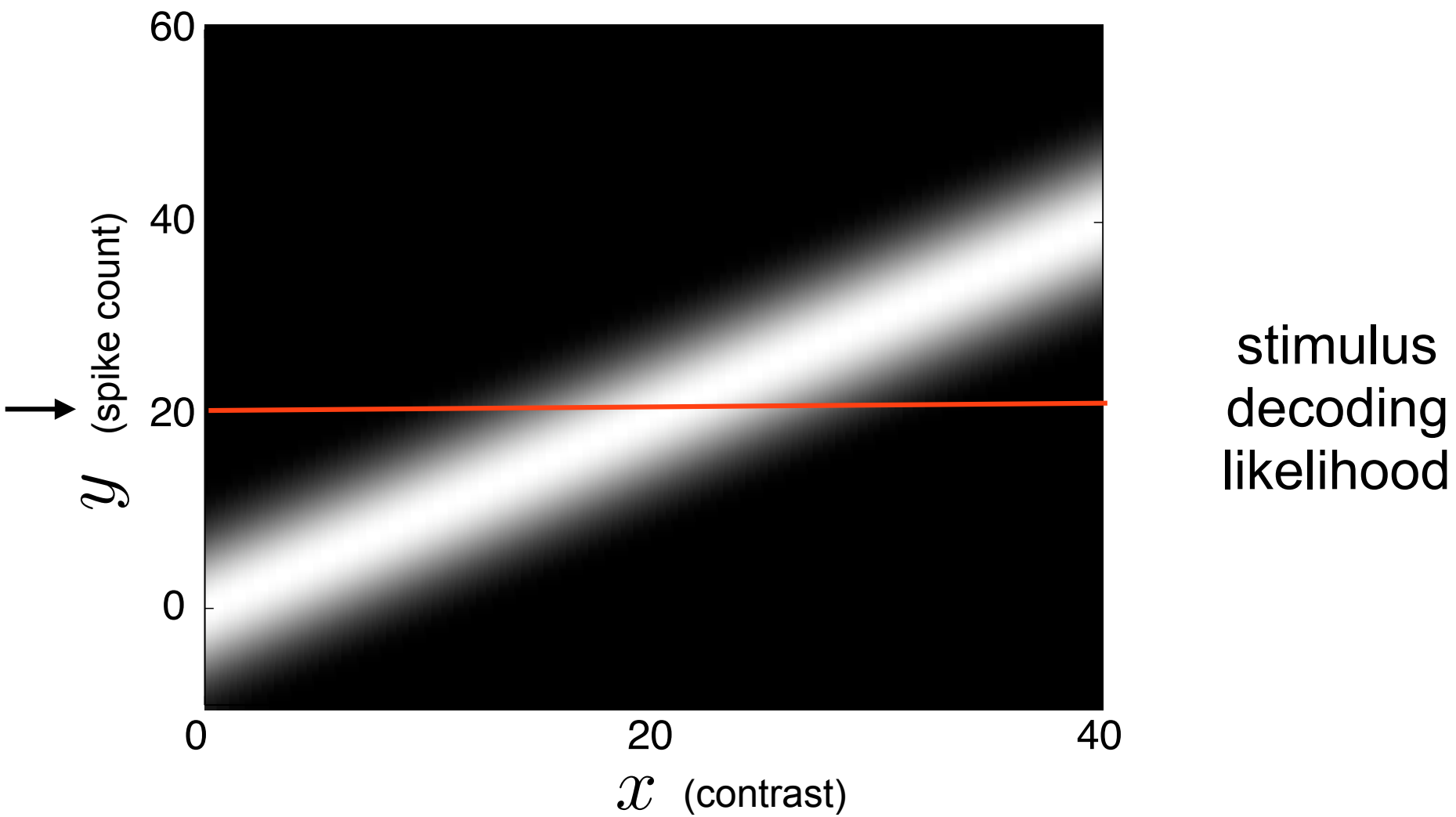
Answer: **encoding distribution** - probability distribution over spike counts

2. as a function of θ ?

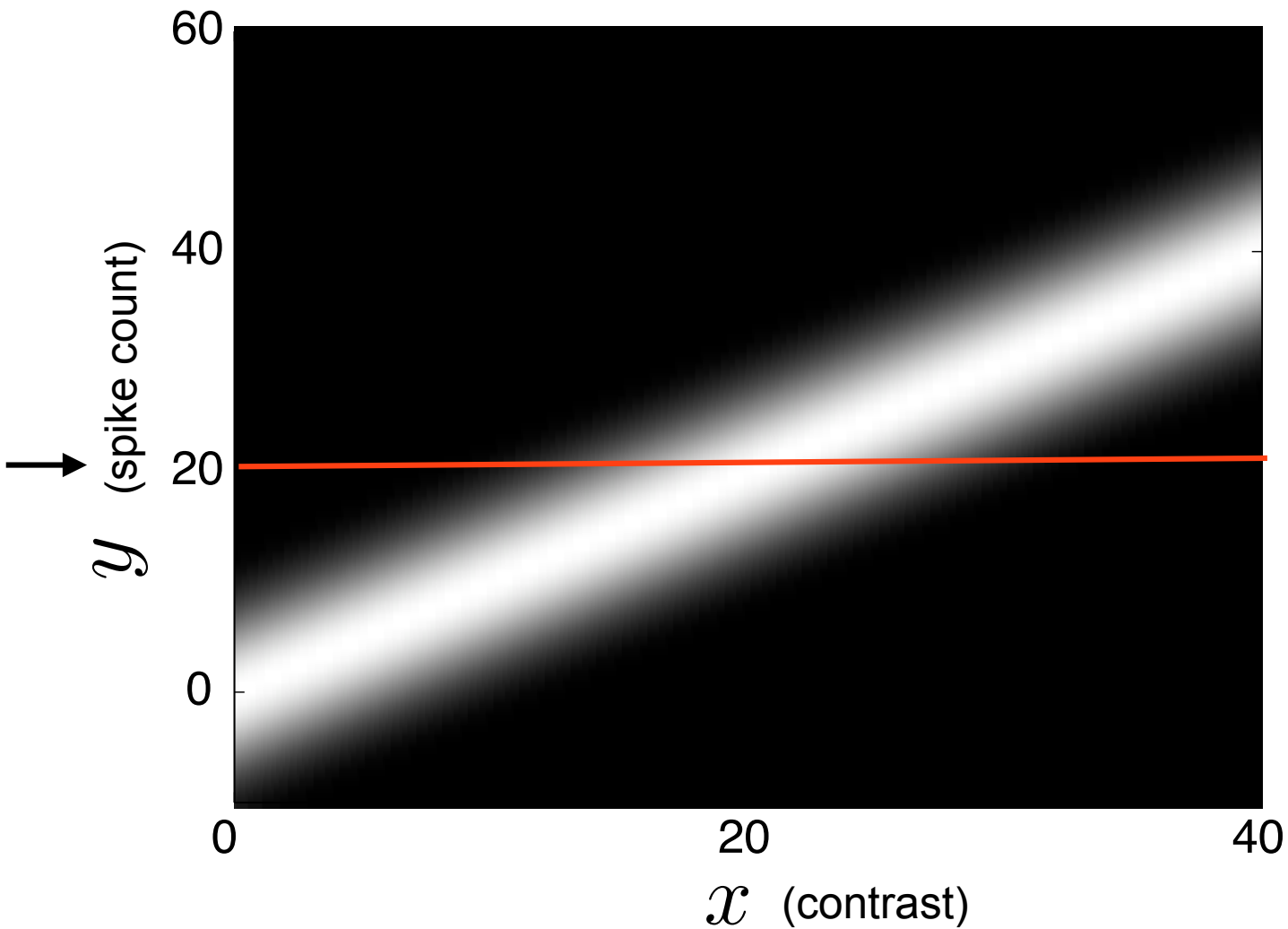
Answer: **likelihood function** - the probability of the data given model params

3. as a function of x ?

Answer: **stimulus likelihood function** - useful for ML stimulus decoding!

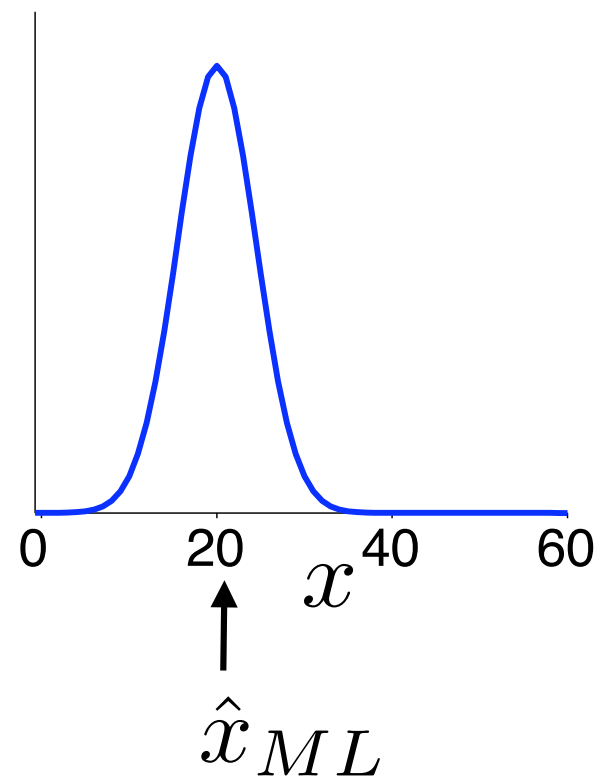


What is this?



Stimulus likelihood function
(for decoding)

$$P(y = 20|x, \theta)$$



GLMs

- Be careful about terminology:

GLM

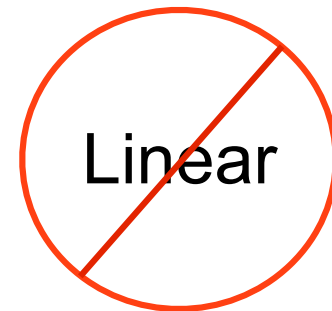
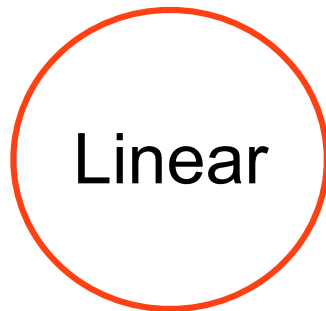
General Linear Model

≠

GLM

Generalized Linear Model

(Nelder 1972)



2003 interview with John Nelder...

Stephen Senn: I must confess to having some confusion when I was a young statistician between general linear models and generalized linear models. Do you regret the terminology?

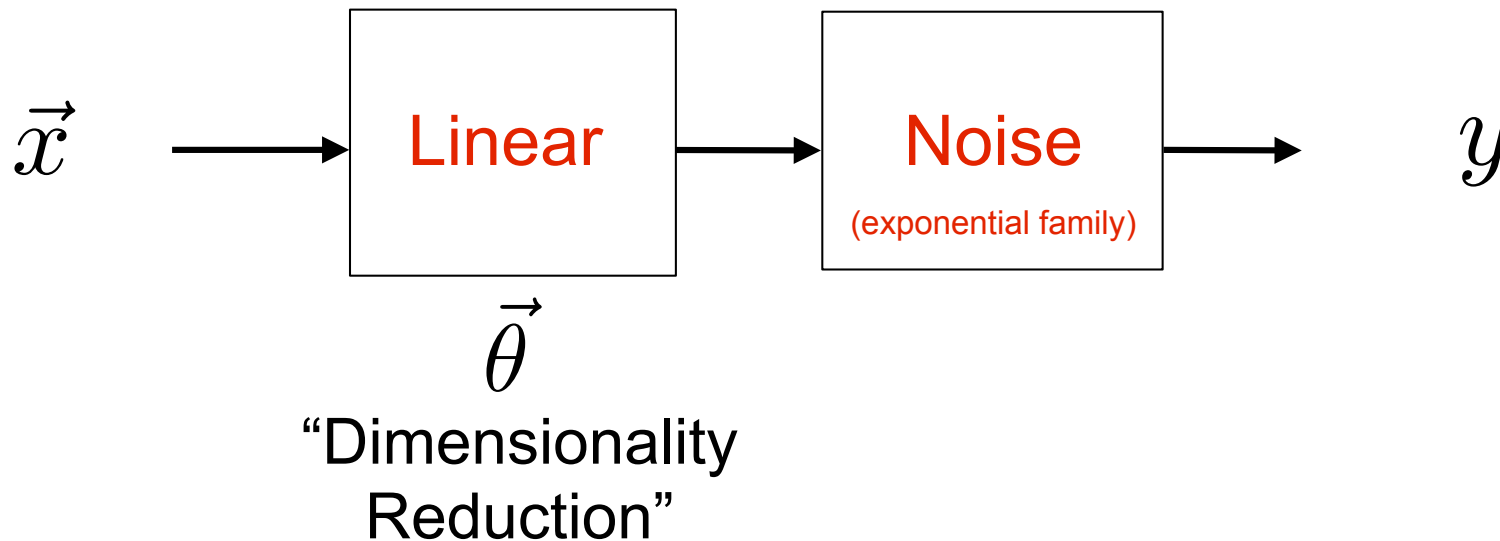
John Nelder: I think probably I do. I suspect we should have found some more fancy name for it that would have stuck and not been confused with the general linear model, although general and generalized are not quite the same. I can see why it might have been better to have thought of something else.

Senn, (2003). *Statistical Science*

Moral:

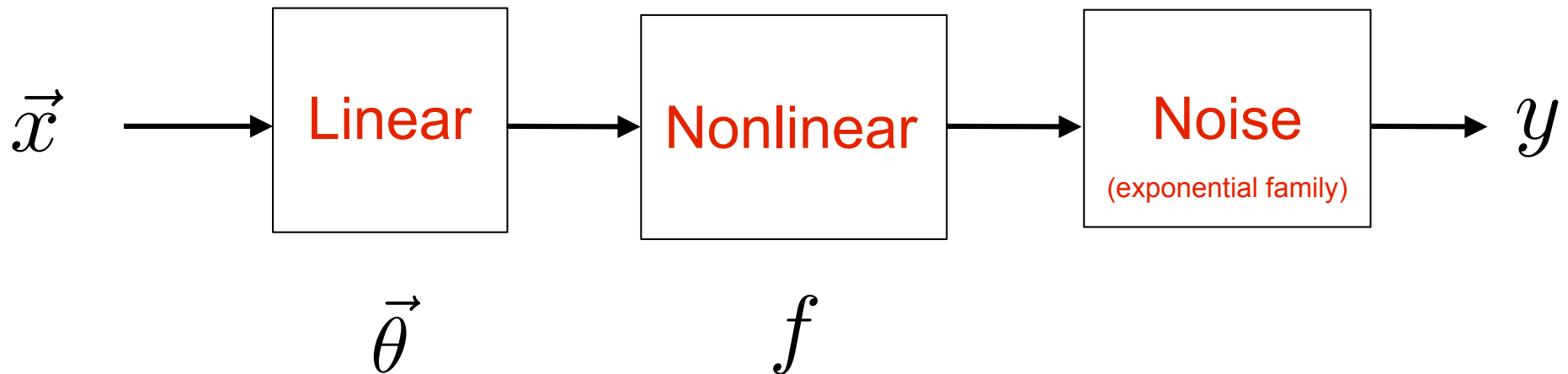
Be careful when naming your model!

1. General Linear Model



- Examples:
1. Gaussian $y = \vec{\theta} \cdot \vec{x} + \epsilon$
 2. Poisson $y \sim \text{Pois}(\vec{\theta} \cdot \vec{x})$

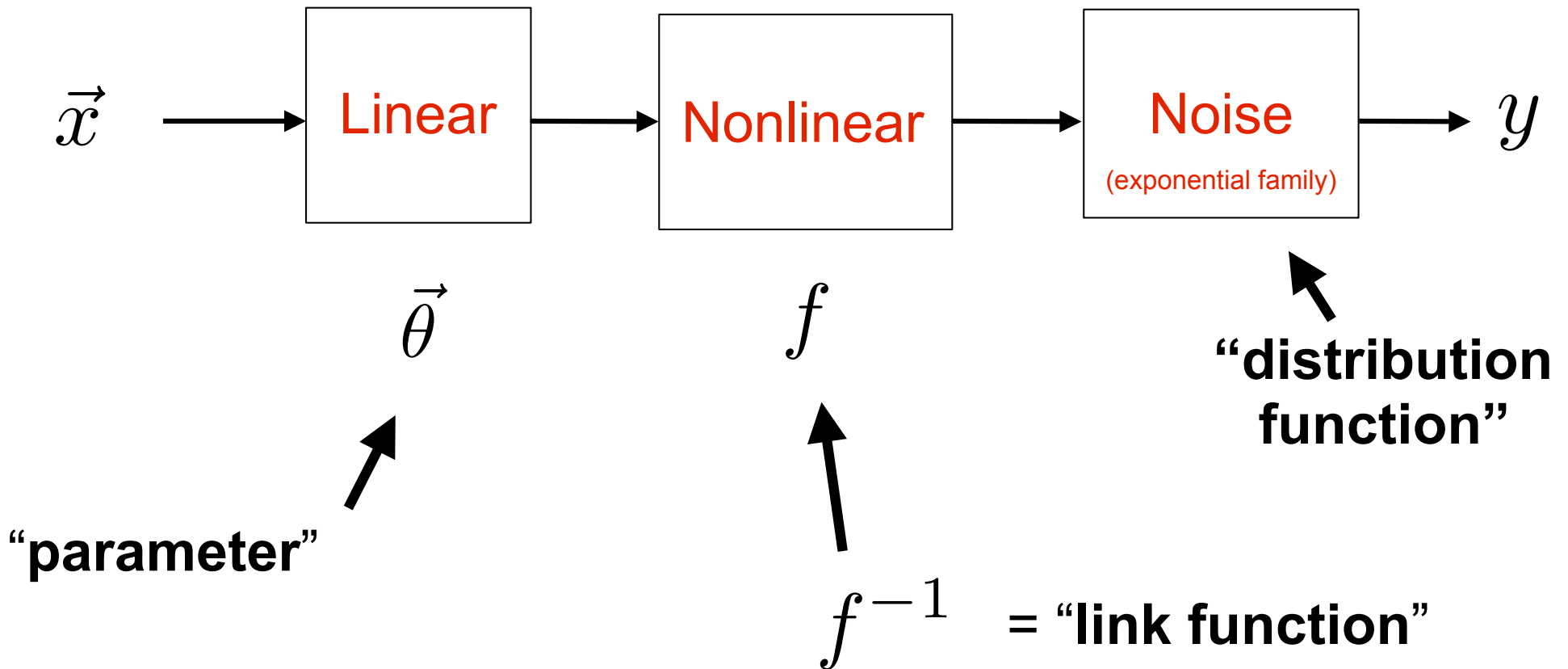
2. Generalized Linear Model



- Examples:
1. Gaussian $y = f(\vec{\theta} \cdot \vec{x}) + \epsilon$
 2. Poisson $y \sim \text{Pois}(f(\vec{\theta} \cdot \vec{x}))$

2. Generalized Linear Model

Terminology:



From spike counts to spike trains:

response
at time t

$$y_t = \vec{k} \cdot \vec{x}_t + \text{noise}$$

$N(0, \sigma^2)$

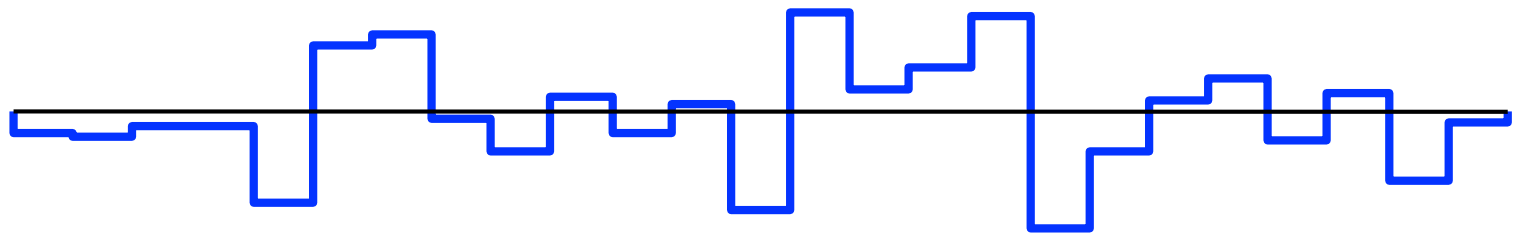
linear
filter

vector stimulus
at time t

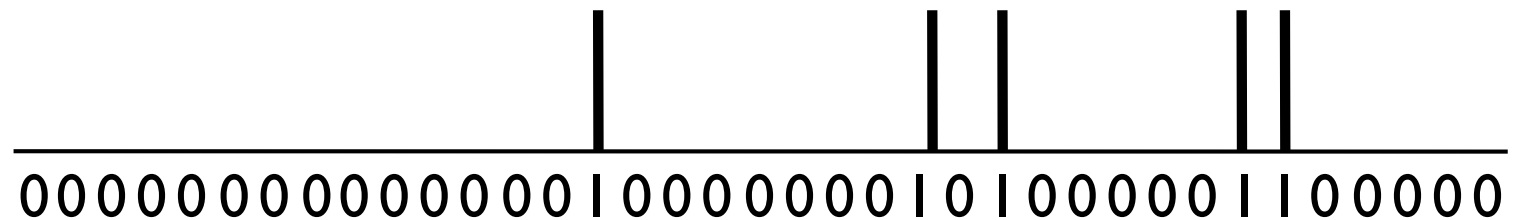
$$y_t = \vec{k} \cdot \vec{x}_t + \epsilon_t$$

first idea: linear-Gaussian model!

stimulus



response



time \longrightarrow

response
at time t

$$y_t = \vec{k} \cdot \vec{x}_t + \text{noise}$$

linear
filter

vector stimulus
at time t

$N(0, \sigma^2)$

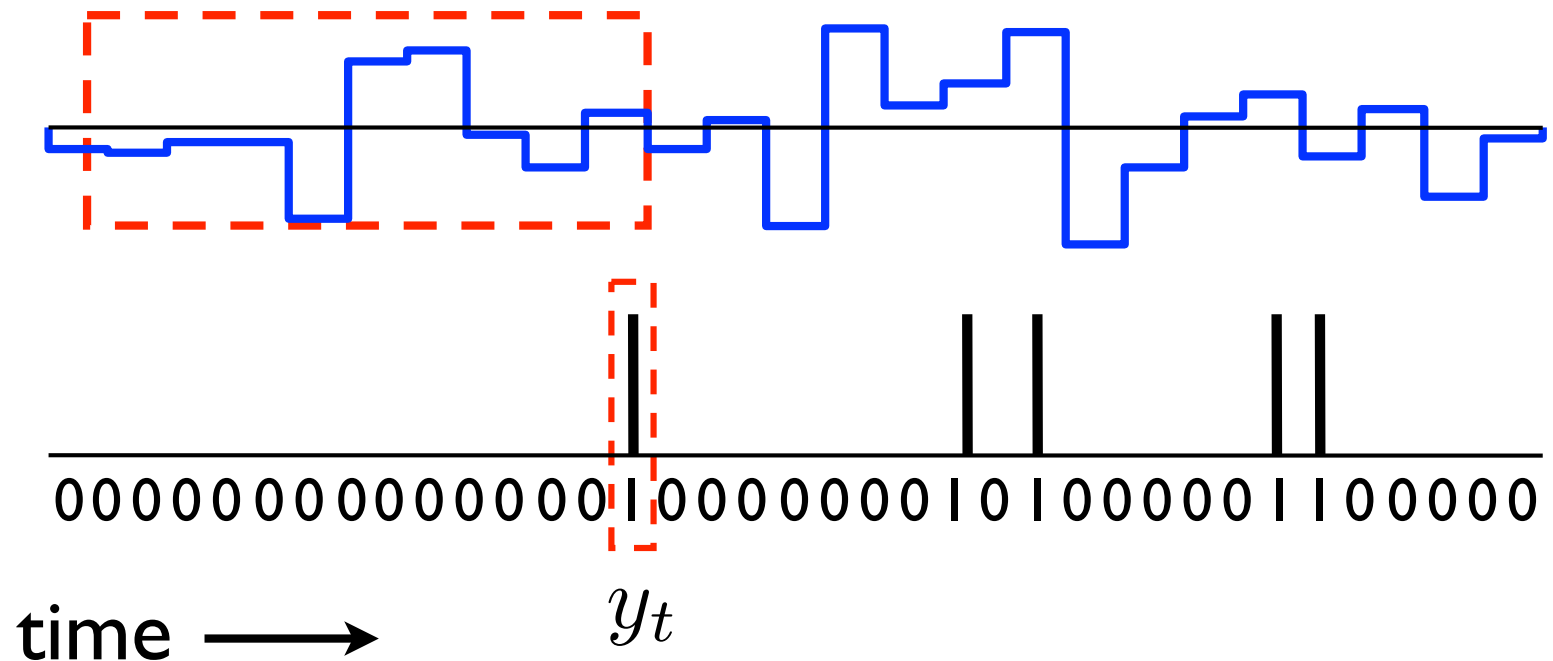
walk through the data
one time bin at a time

$t = 2$

stimulus

\vec{x}_t

response



$$y_t = \vec{k} \cdot \vec{x}_t + \text{noise}$$

linear filter

vector stimulus at time t

$N(0, \sigma^2)$

t = 3

stimulus

response

time \longrightarrow

 y_t

response
at time t

$$y_t = \vec{k} \cdot \vec{x}_t + \text{noise}$$

linear
filter

vector stimulus
at time t

$N(0, \sigma^2)$

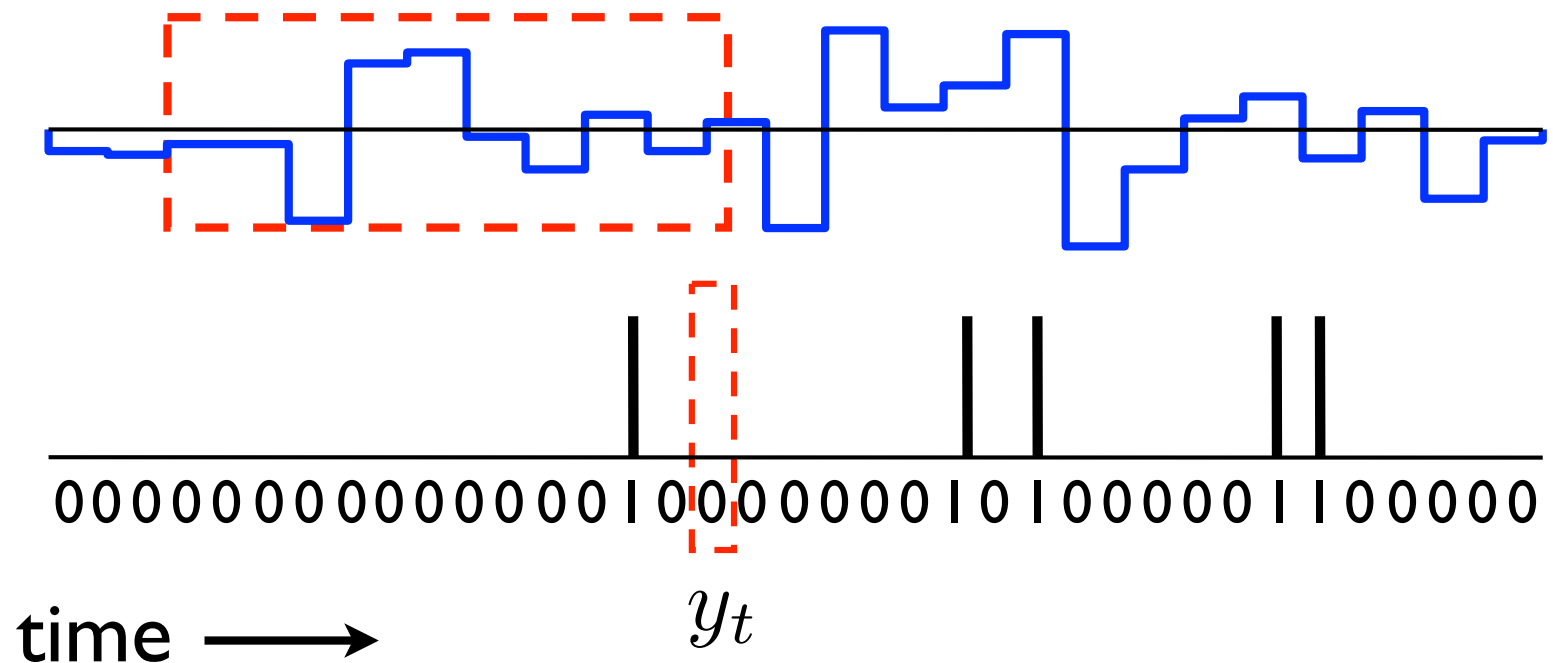
walk through the data
one time bin at a time

$t = 4$

stimulus

\vec{x}_t

response



response
at time t

$$y_t = \vec{k} \cdot \vec{x}_t + \text{noise}$$

linear
filter

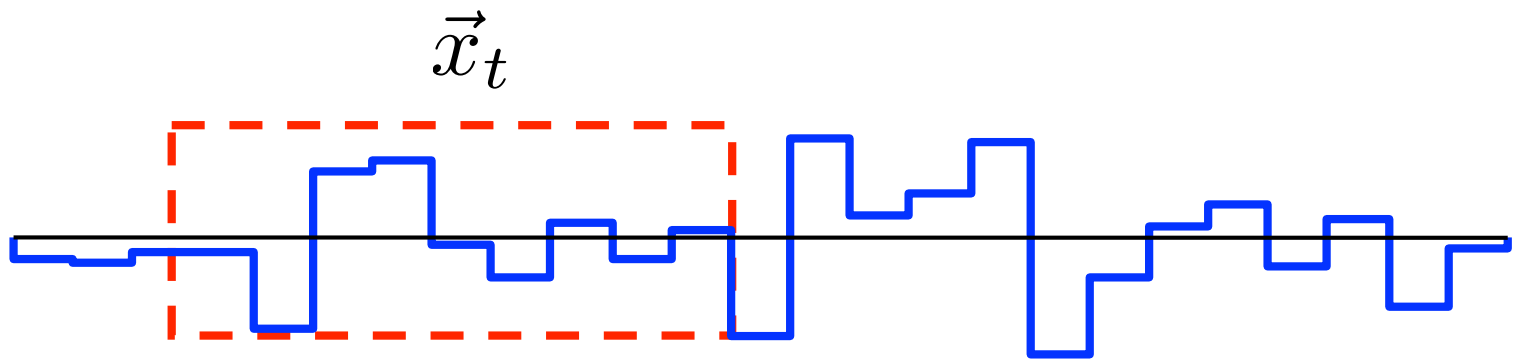
vector stimulus
at time t

$N(0, \sigma^2)$

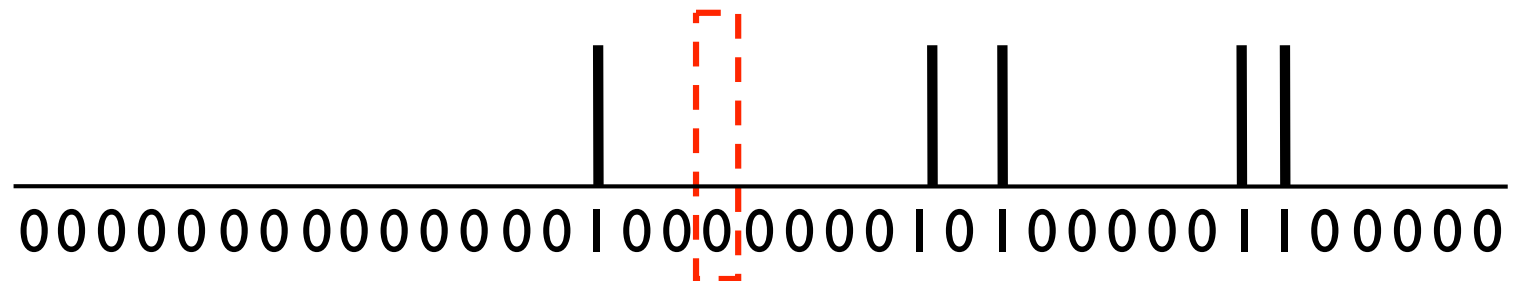
walk through the data
one time bin at a time

$t = 5$

stimulus



response



time \longrightarrow

y_t

response
at time t

$$y_t = \vec{k} \cdot \vec{x}_t + \text{noise}$$

linear
filter

vector stimulus
at time t

$N(0, \sigma^2)$

walk through the data
one time bin at a time

$t = 6$

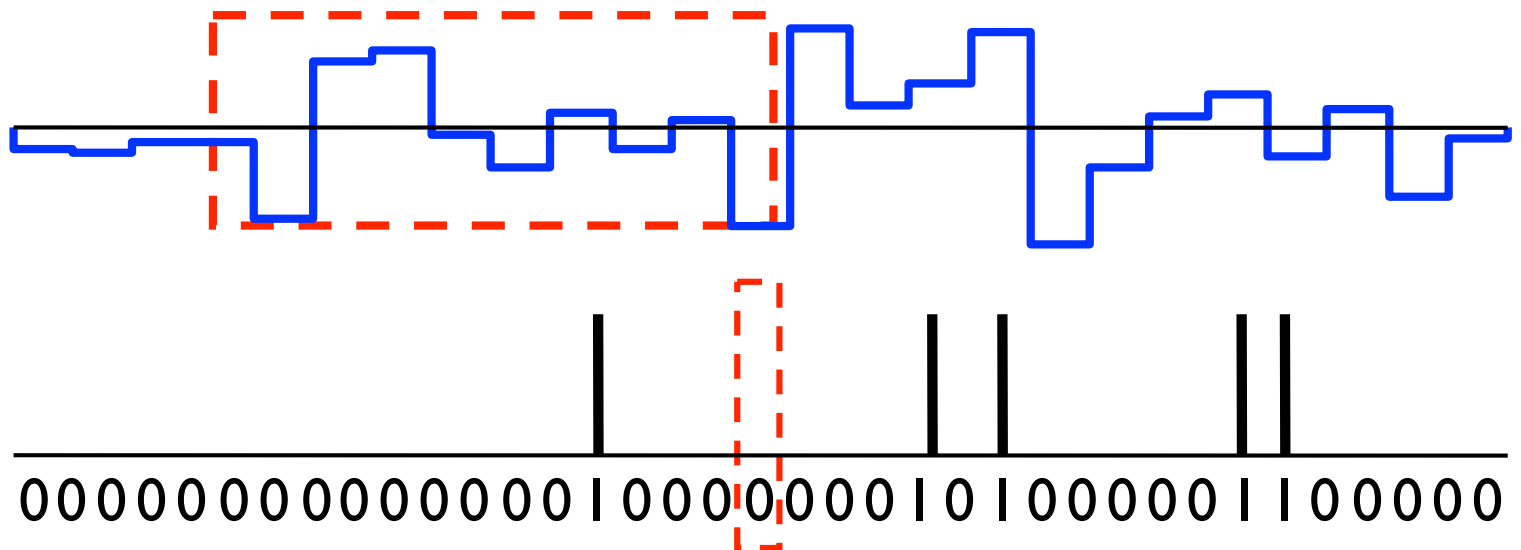
stimulus

\vec{x}_t

response

time \longrightarrow

y_t



Build up to following matrix version:

$$Y = X \vec{k} + \text{noise}$$

time
↓

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix} = \begin{bmatrix} \text{blue step function} \\ \text{blue step function} \\ \text{blue step function} \\ \vdots \end{bmatrix} \begin{bmatrix} \vec{k} \end{bmatrix}$$

design matrix

Build up to following matrix version:

$$Y = X \vec{k} + \text{noise}$$

time
↓

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix} = \begin{bmatrix} \text{stimulus trace 1} \\ \text{stimulus trace 2} \\ \text{stimulus trace 3} \\ \vdots \end{bmatrix} \begin{bmatrix} \vec{k} \end{bmatrix}$$

least squares solution:

$$\hat{k} = \underbrace{(X^T X)^{-1}}_{\text{stimulus covariance}} \underbrace{X^T Y}_{\text{spike-triggered avg (STA)}}$$

(maximum likelihood estimate for
“Linear-Gaussian” GLM)

Formal treatment: scalar version

model: $y_t = \vec{k} \cdot \vec{x}_t + \epsilon_t$

$N(0, \sigma^2)$
Gaussian noise with variance σ^2

equivalent to writing: $y_t | \vec{x}_t, \vec{k} \sim \mathcal{N}(\vec{x}_t \cdot \vec{k}, \sigma^2)$

or

$$p(y_t | \vec{x}_t, \vec{k}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_t - \vec{x}_t \cdot \vec{k})^2}{2\sigma^2}}$$

For entire dataset: $p(Y|X, \vec{k}) = \prod_{t=1}^T p(y_t | \vec{x}_t, \vec{k})$ (independence across time bins)

$$= (2\pi\sigma^2)^{-\frac{T}{2}} \exp\left(-\sum_{t=1}^T \frac{(y_t - \vec{x}_t \cdot \vec{k})^2}{2\sigma^2}\right)$$

$$\log P(Y|X, \vec{k}) = -\sum_{t=1}^T \frac{(y_t - \vec{x}_t \cdot \vec{k})^2}{2\sigma^2} + \text{const} \quad \text{log-likelihood}$$

Formal treatment: vector version

$$\begin{array}{c} \text{time} \\ \downarrow \end{array} \quad Y = X \vec{k} + \vec{\epsilon}$$

$N(0, \sigma^2 I)$
iid Gaussian noise vector

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix} = \begin{bmatrix} \text{step function} \\ \text{step function} \\ \text{step function} \\ \vdots \end{bmatrix} \begin{bmatrix} \vec{k} \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \vdots \end{bmatrix}$$

equivalent to writing: $Y|X, \vec{k} \sim \mathcal{N}(X\vec{k}, \sigma^2 I)$

or

Take log,
differentiate and
set to zero.

$$P(Y|X, \vec{k}) = \frac{1}{|2\pi\sigma^2 I|^{\frac{T}{2}}} \exp \left(-\frac{1}{2\sigma^2} (Y - X\vec{k})^\top (Y - X\vec{k}) \right)$$

But noise is *not* Gaussian!

$$\begin{array}{c} \text{time} \\ \downarrow \end{array} \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix} \approx f\left(\begin{bmatrix} \text{[blue step function]} \\ \text{[blue step function]} \\ \text{[blue step function]} \\ \vdots \end{bmatrix} \begin{bmatrix} \vec{k} \end{bmatrix} \right)$$

Bernoulli GLM:

(coin flipping model,
 $y = 0$ or 1)

$$p_t = f(\vec{x}_t \cdot \vec{k})$$

nonlinearity
probability of
spike at bin t

$$p(y_t = 1 | \vec{x}_t) = p_t$$

Equivalent ways of writing:

$$y_t | \vec{x}_t, \vec{k} \sim \text{Ber}(f(\vec{x}_t \cdot \vec{k}))$$

or $p(y_t | \vec{x}_t, \vec{k}) = f(\vec{x}_t \cdot \vec{k})^{y_t} (1 - f(\vec{x}_t \cdot \vec{k}))^{1-y_t}$

log-likelihood: $\mathcal{L} = \sum_{t=1}^T \left(y_t \log f(\vec{x}_t \cdot \vec{k}) + (1 - y_t) \log(1 - f(\vec{x}_t \cdot \vec{k})) \right)$

Logistic regression

time
↓

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix} \approx f\left(\begin{bmatrix} \text{step function} \\ \text{step function} \\ \text{step function} \\ \vdots \end{bmatrix} \begin{bmatrix} \vec{k} \end{bmatrix} \right)$$

Bernoulli GLM:

(coin flipping model,
 $y = 0$ or 1)

$$p_t = f(\vec{x}_t \cdot \vec{k})$$

probability of
spike at bin t

$$p(y_t = 1 | \vec{x}_t) = p_t$$

Logistic regression:

$$f(x) = \frac{1}{1 + e^{-x}}$$

logistic function

- so logistic regression is a special case of a Bernoulli GLM

Poisson regression

Poisson GLM:

(integer $y \geq 0$)

$$\lambda_t = f(\vec{x}_t \cdot \vec{k})$$

nonlinearity

firing rate

$$y_t | \vec{x}_t, \vec{k} \sim \text{Pois}(\Delta \lambda_t)$$

time bin size

encoding distribution:

$$p(y_t | \vec{x}_t, \vec{k}) = \frac{(\Delta \lambda_t)^{y_t}}{y_t!} e^{-\Delta \lambda_t}$$

log-likelihood:

$$\begin{aligned} \mathcal{L} = \log p(Y|X, \vec{k}) &= \sum_t \left(y_t \log f(\vec{x}_t \cdot \vec{k}) - f(\vec{x}_t \cdot \vec{k}) \right) + \text{const} \\ &= Y^\top \log f(X \vec{k}) - \mathbf{1}^\top f(X \vec{k}) + \text{const} \end{aligned}$$

Summary:

1. “Linear-Gaussian” GLM: $Y|X, \vec{k} \sim \mathcal{N}(X\vec{k}, \sigma^2 I)$

$$\hat{k} = (X^T X)^{-1} X^T Y$$

2. Bernoulli GLM: $y_t|\vec{x}_t, \vec{k} \sim \text{Ber}(f(\vec{x}_t \cdot \vec{k}))$

$$\mathcal{L} = Y^\top \log f(X\vec{k}) - (1 - Y)^\top \log(1 - f(X\vec{k}))$$

3. Poisson GLM: $y_t|\vec{x}_t, \vec{k} \sim \text{Pois}(\Delta\lambda_t)$

$$\mathcal{L} = Y^\top \log f(X\vec{k}) - \mathbf{1}^\top f(X\vec{k})$$