

Algebraic Subtyping for Algebraic Types and Effects

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Voorwoord

I would like to thank everybody who kept me busy the last year, especially my promoter and my assistants. I would also like to thank the jury for reading the text.

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Samenvatting

Algebraic effects and handlers are a very active area of research. An important aspect is the development of an optimising compiler. $\rm E_{FF}$ is an ML-style language with support for effects and forms the testbed for the optimising compiler. However, the type-&-effect system of $\rm E_{FF}$ is unsatisfactory. This is due to the lack of some elegant properties. It is also awkward to implement and use in practice.

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Introduction

The specification for a type-&-effect system with algebraic subtyping for algebraic effects and handlers is given in this document. The formal properties of this system are studied in order to find which properties are satisfied compared to other type-&-effect systems. The proposed type-&-effect system builds on two very recent developments in the area of programming language theory.

Algebraic subtyping

In his December 2016 PhD thesis, Stephen Dolan (University of Cambridge, UK), has presented a novel type system that combines subtyping and parametric polymorphism in a particulary attractive and elegant fashion. A cornerstone of his design are the algebraic properties that the subtyping relation should respect.

Algebraic effects and handlers

These are a new formalism for formally modelling side-effects (e.g. mutable state or non-determinism) in programming languages, developed by Matija Pretnar (University of Ljubjana) and Gordon Plotkin (University of Edinburgh). This approach is gaining a lot of traction, not only as a formalism but also as a practical feature in actual programming languages (e.g. the Koka language developed by Microsoft Research). We are collaborating with Matija Pretnar on the efficient implementation of one such language, called Eff. Axel Faes has contributed to this collaboration during a project he did for the Honoursprogramme of the Faculty of Engineering Science.

1.1 Motivation

Algebraic effects and handlers benefit from a custom type-&-effect system, a type system that also tracks which effects can happen in a program. Several such type-&-effect systems have been proposed in the literature, but all are unsatisfactory. We attribute this to the lack of the elegant properties of Dolan's type system. Indeed the existing type-&-effect systems are not only theoretically unsatisfactory, but they are also awkward to implement and use in practice.

Research questions

- How can Dolan's elegant type system be extended with effect information?
- Which properties are preserved and which aren't preserved?
- What advantages are there to an type-&-effect system based on Dolan's elegant type system?

1.2 Goals

The goal of this thesis is to derive a type-&-effect system that extends Dolan's elegant type system with effect information. This type-&-effect system should inherit Dolan's harmonious combination of subtyping (in our case induced by a lattice structure on the effect information) with parametric polymorphism and preserve all of its desirable properties (both low-level algebraic properties and high-level meta-theoretical properties like type soundness and the existence of principal types). Afterwards this type-&-effect system The following approach is taken:

- 1. Study of the relevant literature and theoretical background.
- 2. Design of a type-&-effect system derived from Dolan's, that integrates effects.
- 3. Proving the desirable properties of the proposed type-&-effect system: type soundness, principal typing, ...
- 4. Time permitting: Design of a type inference algorithm that derives the principal types of programs without type annotations and proving its correctness.
- 5. Time permitting: Implementation of the algorithm and comparing it to other algorithms (such as row polymorphism based type-&-effect systems).

1.3 Results

Describe what the resulting product is and how it is useful or provides an advantage over other solutions.

Background

In this section, I will provide the background necessary to be able to read the text. This includes an introduction into programming languages (and programming language theory) and algebraic effect handlers

Dolan's type system and ${\rm EFF}$ are discussed in further chapters and thus shouldn't need to be explained in this section.

Related Work (Algebraic Subtyping)

Subtyping is a partial order which is a reflexive transitive binary relation satisfying antisymmetry (subtyping rules). The subtyping order also forms a distributive lattice (equivalence rules).

Related Work (Eff)

The type-&-effect system that is used in EFF is based on subtyping and dirty types [1].

4.1 Types and terms

Terms

Figure 4.1 shows the two types of terms in Eff . There are values v and computations c. Computations are terms that can contain effects. Effects are denoted as operations Op which can be called.

```
value v := x
                                                     variable
                                                     true
                  true
                                                     false
                  false
                                                     function
                  \lambda x.c
                                                     handler
                                                        return case
                      return x \mapsto c_r,
                      [\operatorname{Op} y \, k \mapsto c_{\operatorname{Op}}]_{\operatorname{Op} \in O}
                                                        operation cases
                                                     application
\mathsf{comp}\ c\quad ::=\ v_1\,v_2
                  let rec f x = c_1 in c_2 rec definition
                  \mathtt{return}\ v
                                                     returned val
                  0p v
                                                     operation call
                   do x \leftarrow c_1 ; c_2
                                                     sequencing
                  handle c with v
                                                     handling
```

Figuur 4.1: Terms of ${\rm Eff}$

Types

Figure 4.2 shows the types of Eff. There are two main sorts of types. There are (pure) types A, B and dirty types $\underline{C}, \underline{D}$. A dirty type is a pure type A tagged with a finite set of operations Δ , which we call dirt, that can be called. This finite set Δ is an over-approximation of the operations that are actually called. The type $\underline{C} \Rightarrow \underline{D}$ is used for handlers because a handler takes an input computation \underline{C} , handles the effects in this computation and outputs computation \underline{D} as the result.

Figuur 4.2: Types of ${\rm Eff}$

4.2 Type System

4.2.1 Subtyping

The dirty type $A \,!\, \Delta$ is assigned to a computation returning values of type A and potentially calling operations from the set Δ . This set Δ is always an over-approximation of the actually called operations, and may safely be increased, inducing a natural subtyping judgement $A \,!\, \Delta \leq A \,!\, \Delta'$ on dirty types. As dirty types can occur inside pure types, we also get a derived subtyping judgement on pure types. Both judgements are defined in Figure 4.3. Observe that, as usual, subtyping is contravariant in the argument types of functions and handlers, and covariant in their return types.

Figuur 4.3: Subtyping for pure and dirty types of EFF

4.2.2 Typing rules

Figure 4.4 defines the typing judgements for values and computations with respect to a standard typing context Γ .

Values

The rules for subtyping, variables, and functions are entirely standard. For constants we assume a signature Σ that assigns a type A to each constant k, which we write as $(k:A) \in \Sigma$.

A handler expression has type $A ! \Delta \cup O \Rightarrow B ! \Delta$ iff all branches (both the operation cases and the return case) have dirty type $B ! \Delta$ and the operation cases cover the set of operations O. Note that the intersection $\Delta \cap O$ is not necessarily empty. The handler deals with the operations O, but in the process may re-issue some of them (i.e., $\Delta \cap O$).

When typing operation cases, the given signature for the operation $(0p:A_{0p}\to B_{0p})\in \Sigma$ determines the type A_{0p} of the parameter x and the domain B_{0p} of the continuation k. As our handlers are deep, the codomain of k should be the same as the type $B!\Delta$ of the cases.

Computations

With the following exceptions, the typing judgement $\Gamma \vdash c : \underline{C}$ has a straightforward definition. The return construct renders a value v as a pure computation, i.e., with empty dirt. An operation invocation $\operatorname{Op} v$ is typed according to the operation's signature, with the operation itself as its only operation. Finally, rule WITH shows that a handler with type $\underline{C} \Rightarrow \underline{D}$ transforms a computation with type \underline{C} into a computation with type \underline{D} .

Figuur 4.4: Typing of $\operatorname{E}_{\operatorname{FF}}$

Core Language (EffCore)

 ${\it EFFCORE}$ is a language with row-based effects, intersection and union types and effects and is subtyping based.

Define your problem very clearly. Provide a formal definition if possible, using mathematical definitions.

5.1 Types and terms

Terms

Figure 5.1 shows the two types of terms in EFFCORE. There are values v and computations c. Computations are terms that can contain effects. Effects are denoted as operations Op which can be called. The function term is explicitly annotated with a type and type abstraction and type application has been added to the language. These terms only work on pure types.

Types

Figure 5.2 shows the types of EFFCORE. There are two main sorts of types. There are (pure) types A, B and dirty types C, D. A dirty type is a pure type A tagged with a finite set of operations Δ , which we call dirt, that can be called. It can also be an union or intersection of dirty types. In further sections, the relations between dirty intersections or unions and pure intersections or unions are explained. The finite set Δ is an over-approximation of the operations that are actually called. Row variables are introduced as well as intersection and unions. The .(DOT) is used to close rows that do not end with a row variable. The type $C \Rightarrow D$ is used for handlers because a handler takes an input computation C, handles the effects in this computation and outputs computation D as the result.

```
\lambda-variable
value v ::= x
                   â
                                                     let-variable
                                                     true
                   true
                   false
                                                     false
                                                     function
                   \lambda x.c
                                                     handler
                                                        return case
                       return x \mapsto c_r,
                                                        operation cases
                       [\operatorname{Op} y k \mapsto c_{\operatorname{Op}}]_{\operatorname{Op} \in O}
\mathsf{comp}\ c \quad ::= \ v_1\,v_2
                                                     application
                   let \hat{\mathbf{x}} = c_1 in c_2
                                                     let
                   if e then c_1 else c_2
                                                    conditional
                                                     returned val
                   return v
                                                     operation call
                   0p ν
                   \mathtt{handle}\; c\;\mathtt{with}\; v
                                                     handling
```

Figuur 5.1: Terms of EffCore

```
(pure) type A, B ::= bool
                                                      bool type
                               A \to \underline{C}
                                                      function type
                                                      handler type
                                                      type variable
                                \mu\alpha.A
                                                      recursive type
                                Т
                                                      top
                                                      bottom
                               A \sqcap B
                                                      intersection
                               A \sqcup B
                                                      union
  dirty type \underline{C}, \underline{D} ::= A ! \Delta
              \mathsf{dirt}\ \Delta\ ::=
                               Op
                                                      operation
                                \delta
                                                      row variable
                                                      empty dirt
                               \Delta_1\sqcap\Delta_2
                                                      intersection
                               \Delta_1 \sqcup \Delta_2
                                                      union
All operations \Omega ::= \{0p_i | 0p_i \in \Sigma\}
```

Figuur 5.2: Types of EffCore

$$A_{1} \leqslant A_{2} \leftrightarrow A_{1} \sqcup A_{2} \equiv A_{2}$$

$$A_{1} \leqslant A_{2} \leftrightarrow A_{1} \equiv A_{1} \sqcap A_{2}$$

$$\Delta_{1} \leqslant \Delta_{2} \leftrightarrow \Delta_{1} \sqcup \Delta_{2} \equiv \Delta_{2}$$

$$\Delta_{1} \leqslant \Delta_{2} \leftrightarrow \Delta_{1} \equiv \Delta_{1} \sqcap \Delta_{2}$$

$$\underline{C}_{1} \leqslant \underline{C}_{2} \leftrightarrow \underline{C}_{1} \sqcup \underline{C}_{2} \equiv \underline{C}_{2}$$

$$\underline{C}_{1} \leqslant \underline{C}_{2} \leftrightarrow \underline{C}_{1} \equiv \underline{C}_{1} \sqcap \underline{C}_{2}$$

Figuur 5.3: Relationship between Equivalence and Subtyping

$$A \sqcup A \equiv A$$

$$A \sqcap A \equiv A$$

$$A_1 \sqcup A_2 \equiv A_2 \sqcup A_1$$

$$A_1 \sqcup (A_2 \sqcup A_3) \equiv (A_1 \sqcup A_2) \sqcup A_3$$

$$A_1 \sqcap (A_2 \sqcap A_3) \equiv (A_1 \sqcap A_2) \equiv A_1$$

$$A_1 \sqcap (A_1 \sqcup A_2) \equiv A_1$$

$$A_1 \sqcap A \equiv A$$

$$A_1 \sqcap A \equiv A$$

$$A_1 \sqcup A_2 \sqcup A_3 \equiv (A_1 \sqcup A_2) \sqcap (A_1 \sqcup A_3)$$

$$A_1 \sqcap (A_2 \sqcup A_3) \equiv (A_1 \sqcap A_2) \sqcup (A_1 \sqcap A_3)$$

Figuur 5.4: Equations of distributive lattices for types

5.2 Type system

5.3 Typing rules

Figure 5.8 defines the typing judgements for values and computations with respect to a standard typing context Γ .

$$(A_1 \to A_2) \sqcup (A_3 \to A_4) \equiv (A_1 \sqcap A_3) \to (A_2 \sqcup A_4)$$

$$(A_1 \to A_2) \sqcap (A_3 \to A_4) \equiv (A_1 \sqcup A_3) \to (A_2 \sqcap A_4)$$

$$(A_1 \Rightarrow A_2) \sqcup (A_3 \Rightarrow A_4) \equiv (A_1 \sqcap A_3) \Rightarrow (A_2 \sqcup A_4)$$

$$(A_1 \Rightarrow A_2) \sqcap (A_3 \Rightarrow A_4) \equiv (A_1 \sqcup A_3) \Rightarrow (A_2 \sqcup A_4)$$

$$(A_1 \Rightarrow A_2) \sqcap (A_3 \Rightarrow A_4) \equiv (A_1 \sqcup A_3) \Rightarrow (A_2 \sqcap A_4)$$

$$(\underline{C}_1 \sqcup \underline{C}_2) \equiv (A_1 ! \Delta_1 \sqcup A_2 ! \Delta_2) \equiv (A_1 \sqcup A_2) ! (\Delta_1 \sqcup \Delta_2)$$

$$(\underline{C}_1 \sqcap \underline{C}_2) \equiv (A_1 ! \Delta_1 \sqcap A_2 ! \Delta_2) \equiv (A_1 \sqcap A_2) ! (\Delta_1 \sqcap \Delta_2)$$

Figuur 5.5: Equations for function, handler and dirty types

$$\Delta \sqcup \Delta \equiv \Delta$$

$$\Delta_1 \sqcup \Delta_2 \equiv \Delta_2 \sqcup \Delta_1$$

$$\Delta_1 \sqcap \Delta_2 \equiv \Delta_2 \sqcap \Delta_1$$

$$\Delta_1 \sqcup (\Delta_2 \sqcup \Delta_3) \equiv (\Delta_1 \sqcup \Delta_2) \sqcup \Delta_3$$

$$\Delta_1 \sqcap (\Delta_2 \sqcap \Delta_3) \equiv (\Delta_1 \sqcap \Delta_2) \sqcap \Delta_3$$

$$\Delta_1 \sqcup (\Delta_1 \sqcap \Delta_2) \equiv \Delta_1$$

$$\Delta_1 \sqcap (\Delta_1 \sqcup \Delta_2) \equiv \Delta_1$$

$$0 \sqcup \Delta \equiv \Delta$$

$$\Omega \sqcup \Delta \equiv 0$$

$$\Omega \sqcup \Delta \equiv \Delta$$

$$\Delta_1 \sqcup (\Delta_2 \sqcap \Delta_3) \equiv (\Delta_1 \sqcup \Delta_2) \sqcap (\Delta_1 \sqcup \Delta_3)$$

$$\Delta_1 \sqcup (\Delta_2 \sqcap \Delta_3) \equiv (\Delta_1 \sqcup \Delta_2) \sqcup (\Delta_1 \sqcap \Delta_3)$$

Figuur 5.6: Equations of distributive lattices for dirts

Values

The rules for subtyping, variables, type abstraction, type application and functions are entirely standard. For constants we assume a signature Σ that assigns a type A to each constant k, which we write as $(k:A) \in \Sigma$.

A handler expression has type $A ! \Delta \cup O \Rightarrow B ! \Delta$ iff all branches (both the operation cases and the return case) have dirty type $B ! \Delta$ and the operation cases cover the set of

$$\begin{array}{|c|c|c|} \hline \textbf{Subtyping of dirts} \\ \hline & SUB-!-RoW-RoW \\ & n \geq 0 \quad m \geq 0 \quad p \geq 0 \quad \{Op_1,...,Op_n,Op_{n+m+1},...,Op_{n+m+p},\delta_1\} \leq \\ & \quad \{Op_1,...,Op_n,Op_{n+1},...,Op_{n+m},\delta_2\} \\ \hline & \quad \{\delta_1\} \leqslant \{Op_{n+1},...,Op_{n+m},\delta_3\} \quad \{\delta_3\} = \{Op_{n+m},...,Op_{n+m+p},\delta_2\} \\ \hline & SUB-!-DOT-ROW \\ & n \geq 0 \quad m \geq 0 \quad p \geq 0 \\ \hline & \quad \{Op_1,...,Op_n,Op_{n+m+1},...,Op_{n+m+p},.\} \leqslant \quad \{Op_1,...,Op_n,Op_{n+1},...,Op_{n+m},\delta_2\} \\ \hline & \quad \emptyset \leqslant \{Op_{n+1},...,Op_{n+m},\delta_3\} \quad \{\delta_3\} = \{Op_{n+m},...,Op_{n+m+p},\delta_2\} \\ \hline & \quad SUB-!-ROW-DOT \\ & \quad n \geq 0 \quad m \geq 0 \quad \{Op_1,...,Op_n,\delta_1\} \leqslant \{Op_1,...,Op_n,Op_{n+1},Op_{n+m},.\} \\ \hline & \quad \{\delta_1\} \leqslant \{Op_{n+1},Op_{n+m},.\} \\ \hline & \quad SUB-!-DOT-DOT \\ & \quad n \geq 0 \quad m \geq 0 \quad \{Op_1,...,Op_n,.\} \leqslant \{Op_1,...,Op_n,Op_{n+1},...,Op_{n+m},.\} \\ \hline & \quad \emptyset \leqslant \{Op_{n+1},Op_{n+m},.\} \\ \hline & \quad \emptyset \leqslant \{Op_{n+1},Op_{n+m},.\} \\ \hline \end{array}$$

Figuur 5.7: Subtyping for dirts of EffCore

operations O. Note that the intersection $\Delta \cap O$ is not necessarily empty (with \cap being the intersection of the operations, not to be confused with the \sqcap type). The handler deals with the operations O, but in the process may re-issue some of them (i.e., $\Delta \cap O$).

When typing operation cases, the given signature for the operation (Op: $A_{\rm Op} \to B_{\rm Op}$) $\in \Sigma$ determines the type $A_{\rm Op}$ of the parameter x and the domain $B_{\rm Op}$ of the continuation k. As our handlers are deep, the codomain of k should be the same as the type $B \,!\, \Delta$ of the cases.

Computations

With the following exceptions, the typing judgement $\Gamma \vdash c : \underline{C}$ has a straightforward definition. The return construct renders a value v as a pure computation, i.e., with empty dirt. In this case, this is defined as a set with the .(DOT) as the only element. An operation invocation $\operatorname{Op} v$ is typed according to the operation's signature, with the operation itself as its only operation. Finally, rule WITH shows that a handler with type $\underline{C} \Rightarrow \underline{D}$ transforms a computation with type \underline{C} into a computation with type \underline{D} .

5.4 Reformulated typing rules

5.5 Semantics

Figuur 5.8: Typing of EffCore

monomorphic typing contexts
$$\Xi ::= \epsilon \mid \Xi, x : A$$
 polymorphic typing contexts $\Pi ::= \epsilon \mid \Pi, \hat{x} : [\Xi]A \mid \Pi, \hat{x} : [\Xi]C$

Expressions

$$\frac{SUB-VAL}{\Pi \Vdash v : [\Xi_1]A_1} \quad [\Xi_1]A_1 \leqslant^{\forall} [\Xi_2]A_2 \qquad \qquad VAR-\lambda \qquad \qquad VAR-\lambda \qquad \qquad VAR-\lambda \qquad \qquad (\hat{x} : [\Xi]A) \in \Pi$$

$$\Pi \Vdash v : [\Xi_2]A_2 \qquad \qquad \Pi \Vdash x : [x : A]A \qquad \qquad \Pi \Vdash \hat{x} : [\Xi]A$$

$$\frac{TRUE}{\Pi \Vdash true : []bool} \qquad \frac{FALSE}{\Pi \Vdash true : []bool} \qquad \frac{FUN}{\Pi \Vdash x : [x : A]A} \qquad \frac{FUN}{\Pi \Vdash x : [\Xi, x : A]C}$$

$$\frac{FUN}{\Pi \Vdash x : [\Xi, x : A]C} \qquad \qquad \frac{FUN}{\Pi \Vdash x : [\Xi, x : A]C} \qquad \frac{FUN}{\Pi \Vdash x : [\Xi, x : A]C}$$

$$\frac{(0p : A_{0p} \rightarrow B_{0p}) \in \Sigma}{\Gamma, x : A_{0p}, k : B_{0p} \rightarrow B ! \Delta \vdash c_{0p} : B ! \Delta} \qquad 0_{peo}$$

$$\Gamma \vdash \{return \ x \mapsto c_r, [0p \ y \ k \mapsto c_{0p}]_{0peo}\} : \qquad A ! \Delta \cup O \Rightarrow B ! \Delta$$

$$\frac{Computations}{\Pi \Vdash c : [\Xi_1]C_1} \qquad \frac{[\Xi_1]C_1}{\Pi \Vdash c : [\Xi]C} \qquad \frac{APP}{\Pi \Vdash v : [\Xi]A \rightarrow C} \qquad \Pi \Vdash v_2 : [\Xi]A$$

$$\frac{COND}{\Pi \Vdash v : [\Xi]bool} \qquad \Pi \Vdash c_1 : [\Xi]C \qquad \Pi \Vdash c_2 : [\Xi]C$$

$$\frac{COND}{\Pi \Vdash v : [\Xi]bool} \qquad \Pi \Vdash c_1 : [\Xi]C \qquad \Pi \Vdash c_2 : [\Xi]C$$

$$\frac{COND}{\Pi \Vdash v : [\Xi]bool} \qquad \Pi \Vdash c_1 : [\Xi]C \qquad \Pi \Vdash c_2 : [\Xi]C$$

$$\frac{COND}{\Pi \Vdash v : [\Xi]bool} \qquad \frac{RET}{\Pi \Vdash v : [\Xi]A} \qquad C : [\Xi]B ! \{0p : R\}$$

$$\frac{COP}{(0p : A \rightarrow B) \in \Sigma} \qquad \Pi \Vdash v : [\Xi]A \qquad C : [\Xi]B ! \{0p : R\}$$

$$\frac{LET}{\Pi \Vdash c_1 : [\Xi_1]A ! \Delta} \qquad \Pi, x : [\Xi_1]A \Vdash c_2 : [\Xi_2]B ! \Delta$$

$$\frac{LET}{\Pi \Vdash c_1 : [\Xi_1]A ! \Delta} \qquad \Pi, x : [\Xi_1]A \Vdash c_2 : [\Xi_2]B ! \Delta$$

$$\frac{WITH}{\Pi \Vdash v : [\Xi]C} \Rightarrow D \qquad \Pi \Vdash c : [\Xi]C$$

$$\Pi \Vdash \text{handle } c \text{ with } v : [\Xi]C$$

Figuur 5.9: Reformulated typing rules of EffCore

Type Inference

6.1 Elaboration of Eff into EffCore

The elaboration show how the source language can be transformed into EFFCORE.

$$\begin{array}{c} \text{typing contexts } \Gamma \, ::= \, \epsilon \, \mid \, \Gamma, x : A \, \mid \, \Gamma, x : \forall \bar{\alpha}.B \\ \hline \\ \textbf{Expressions} \\ \hline \begin{matrix} \text{VAL} \\ \hline \Gamma \vdash \nu : A \leadsto \nu' \\ \hline \hline \Gamma \vdash \nu : B \leadsto \nu' \end{matrix} \end{matrix} \qquad \begin{matrix} \text{VAR} \\ \hline \begin{matrix} (x : S) \in \Gamma \\ \hline \hline \Gamma \vdash x : A[\bar{S}/\bar{\alpha}] \leadsto x \, \bar{S} \end{matrix} \end{matrix} \qquad \begin{matrix} \text{Const} \\ \hline \begin{matrix} (k : A) \in \Sigma \\ \hline \hline \Gamma \vdash k : A \leadsto k' \end{matrix} \end{matrix} \\ \hline \begin{matrix} F\text{UN} \\ \hline \hline \begin{matrix} \Gamma, x : A \vdash c : \underline{C} \leadsto c' \\ \hline \hline \hline \begin{matrix} \Gamma \vdash \lambda x.c : A \to \underline{C} \leadsto \text{fun } x : A \mapsto c' : A \to \underline{C} \end{matrix} \end{matrix} \\ \hline \begin{matrix} H\text{AND} \\ \hline \begin{matrix} \Gamma, x : A \vdash c_r : B \, ! \, \Delta \\ \hline \begin{matrix} (0p : A_{0p} \to B_{0p}) \in \Sigma \end{matrix} \end{matrix} \qquad \begin{matrix} \Gamma, x : A_{0p}, k : B_{0p} \to B \, ! \, \Delta \vdash c_{0p} : B \, ! \, \Delta \\ \hline \begin{matrix} \Gamma \vdash \{\text{return } x \mapsto c_r, [0p \, y \, k \mapsto c_{0p}]_{0p \in O}\} : \quad A \, ! \, \Delta \cup O \Longrightarrow B \, ! \, \Delta \\ \hline \begin{matrix} \Gamma \vdash \{\text{return } x \mapsto c_r, [0p \, y \, k \mapsto c_{0p}]_{0p \in O}\} : \quad A \, ! \, \Delta \cup O \Longrightarrow B \, ! \, \Delta \end{matrix} \end{matrix}$$

Figuur 6.1: Elaboration of source to core language: expressions

6.2 Constraint Generation

Figure 6.3 and Figure 6.4 show the constraint generation algorithm for EffCore.

$$\begin{array}{c} \text{typing contexts } \Gamma \, ::= \, \epsilon \, \mid \, \Gamma, x : A, x : \forall \bar{\alpha}.B \\ \hline \textbf{Computations} \\ \hline \frac{\text{COMP}}{\Gamma \vdash c : \underline{C} \leadsto c'} \quad \underline{C} \leqslant \underline{D} \\ \hline \Gamma \vdash v_1 : A \to \underline{C} \leadsto v_1' \quad \Gamma \vdash v_2 : A \leadsto v_2' \\ \hline \Gamma \vdash v_1 v_2 : \underline{C} \leadsto v_1' v_2' : \underline{C} \\ \hline \\ \hline RET \\ \hline \Gamma \vdash v : A \leadsto v' \\ \hline \hline \Gamma \vdash \text{return } v : A \mid \emptyset \leadsto \text{return } v' : A \mid \emptyset \\ \hline \\ OP \\ (0p : A \to B) \in \Sigma \quad \Gamma \vdash v : A \leadsto v' \\ \hline \hline \Gamma \vdash 0p v : B \mid \{0p\} \leadsto 0p v' : B \mid \{0p,.\} \\ \hline \\ Do \\ \hline \Gamma \vdash c_1 : \underline{C} \leadsto c_1' \\ \hline \Gamma \vdash \text{do } x \longleftarrow c_1 : c_2 : \underline{D} \leadsto (\text{fun } x : A \mapsto c_2')(\Lambda \bar{\alpha}.c_1') \\ \hline \\ WITH \\ \hline \Gamma \vdash v : \underline{C} \Longrightarrow \underline{D} \leadsto v' \quad \Gamma \vdash c : \underline{C} \leadsto c' \\ \hline \Gamma \vdash \text{handle } c \text{ with } v : \underline{D} \leadsto \text{handle } c' \text{ with } v' : \underline{D} \\ \hline \end{array}$$

Figuur 6.2: Elaboration of source to core language: computations

6.3 Polar types

6.4 Unification

$$\begin{array}{c|c} \text{typing contexts } \Gamma ::= & \epsilon & \mid \Gamma, x : A, x : \forall \bar{\alpha}.B \\ \hline \\ \textbf{Expressions} \\ \hline \\ \hline \begin{matrix} V \text{AL} \\ \hline \Gamma \vdash v : A \leadsto v' & A \leqslant B \end{matrix} & \begin{matrix} V \text{AR} \\ (x : S) \in \Gamma & S = \forall \bar{\alpha}.A \\ \hline \Gamma \vdash x : A[\bar{S}/\bar{\alpha}] \leadsto x \, \bar{S} \end{matrix} & \begin{matrix} C \text{ONST} \\ (k : A) \in \Sigma \end{matrix} \\ \hline \hline \Gamma \vdash k : A \leadsto k' \end{matrix} \\ \hline \\ \hline \begin{matrix} F \text{UN} \\ \hline \Gamma, x : A \vdash c : \underline{C} \leadsto c' \\ \hline \Gamma \vdash \lambda x.c : A \to \underline{C} \leadsto \text{fun } x : A \mapsto c' : A \to \underline{C} \end{matrix} \\ \hline \\ H \text{AND} \\ \hline \begin{matrix} \Gamma, x : A \vdash c_r : B \mid \Delta \end{matrix} \\ \hline \begin{matrix} (\text{Op} : A_{\text{Op}} \to B_{\text{Op}}) \in \Sigma \end{matrix} & \begin{matrix} \Gamma, x : A_{\text{Op}}, k : B_{\text{Op}} \to B \mid \Delta \vdash c_{\text{Op}} : B \mid \Delta \end{matrix} \\ \hline \begin{matrix} \Gamma \vdash \{\text{return } x \mapsto c_r, [\text{Op } y \mid k \mapsto c_{\text{Op}}]_{\text{Op} \in \mathcal{O}} \} : & A \mid \Delta \cup \mathcal{O} \Longrightarrow B \mid \Delta \end{matrix} \\ \hline \begin{matrix} (\text{op } : A : \Delta \cup \mathcal{O} \Longrightarrow B \mid \Delta \end{matrix} \\ \hline \begin{matrix} \Gamma \vdash \{\text{return } x \mapsto c_r, [\text{Op } y \mid k \mapsto c_{\text{Op}}]_{\text{Op} \in \mathcal{O}} \} : & A \mid \Delta \cup \mathcal{O} \Longrightarrow B \mid \Delta \end{matrix} \\ \hline \begin{matrix} (\text{op } : A : \Delta \cup \mathcal{O} \Longrightarrow B \mid \Delta \end{matrix} \\ \hline \begin{matrix} \Gamma \vdash \{\text{return } x \mapsto c_r, [\text{Op } y \mid k \mapsto c_{\text{Op}}]_{\text{Op} \in \mathcal{O}} \} : & A \mid \Delta \cup \mathcal{O} \Longrightarrow B \mid \Delta \end{matrix} \end{matrix} \\ \hline \begin{matrix} \Gamma \vdash \{\text{return } x \mapsto c_r, [\text{Op } y \mid k \mapsto c_{\text{Op}}]_{\text{Op} \in \mathcal{O}} \} : & A \mid \Delta \cup \mathcal{O} \Longrightarrow B \mid \Delta \end{matrix} \end{matrix}$$

Figuur 6.3: Constraint generation within expressions

$$\begin{array}{c} \text{typing contexts } \Gamma \, ::= \, \epsilon \, \mid \, \Gamma, x : A, x : \forall \bar{\alpha}.B \\ \hline \textbf{Computations} \\ \hline \begin{array}{c} C_{\text{OMP}} \\ \hline \Gamma \vdash c : \underline{C} \leadsto c' \quad \underline{C} \leqslant \underline{D} \\ \hline \Gamma \vdash c : \underline{D} \leadsto c' \\ \hline \end{array} \qquad \begin{array}{c} A_{\text{PP}} \\ \hline \Gamma \vdash v_1 : A \to \underline{C} \leadsto v_1' \quad \Gamma \vdash v_2 : A \leadsto v_2' \\ \hline \Gamma \vdash v_1 v_2 : \underline{C} \leadsto v_1' v_2' : \underline{C} \\ \hline \end{array} \\ \hline \begin{array}{c} L_{\text{ETREC}} \\ \hline \Gamma, f : A \to \underline{C}, x : A \vdash c_1 : \underline{C} \leadsto c_1's \quad \Gamma, f : A \to \underline{C} \vdash c_2 : \underline{D} \leadsto c_2' \\ \hline \Gamma \vdash \text{let rec } f x = c_1 \text{ in } c_2 : \underline{D} \quad \leadsto \text{let rec } f x = c_1' \text{ in } c_2' : \underline{D} \\ \hline \end{array} \\ \hline \begin{array}{c} R_{\text{ET}} \\ \hline \Gamma \vdash v : A \leadsto v' \\ \hline \hline \Gamma \vdash \text{return } v : A ! \emptyset \leadsto \text{return } v' : A ! \emptyset \\ \hline \\ \begin{array}{c} O_{\text{P}} \\ (\text{Op} : A \to B) \in \Sigma \quad \Gamma \vdash v : A \leadsto v' \\ \hline \Gamma \vdash \text{Op} v : B ! \{\text{Op}\} \leadsto \text{Op} v' : B ! \{\text{Op},.\} \\ \hline \end{array} \\ \hline \\ \begin{array}{c} D_{\text{O}} \\ \hline \Gamma \vdash c_1 : \underline{C} \leadsto c_1' \\ \hline \Gamma \vdash \text{do } x \longleftrightarrow c_1 ; c_2 : \underline{D} \leadsto (\text{fun } x : A \mapsto c_2') (\Lambda \bar{\alpha}.c_1') \\ \hline \end{array} \\ \begin{array}{c} W_{\text{ITH}} \\ \hline \Gamma \vdash v : \underline{C} \Longrightarrow \underline{D} \leadsto v' \quad \Gamma \vdash c : \underline{C} \leadsto c' \\ \hline \Gamma \vdash \text{handle } c \text{ with } v : \underline{D} \leadsto \text{handle } c' \text{ with } v' : \underline{D} \\ \hline \end{array}$$

Figuur 6.4: Constraint generation within computations

```
(pure) type A^+, B^+ ::= bool
                                                              bool type
                                                              function type
                                                              handler type
                                                              type variable
                                \mid \mu\alpha.A^+
                                                              recursive type
                                | ____
                                                              bottom
                                A^+ \sqcup B^+
                                                              union
 \text{dirty type } \underline{C}^+,\underline{D}^+ \ ::= \ A^+ \ ! \ \Delta^+
(pure) type \overline{A}^-, \overline{B}^- ::= bool
                                                              bool type
                               function type
                                                              handler type
                                                              type variable
                                \mid \mu\alpha.A^{-}
                                                              recursive type
                                     Т
                                                              top
                                A^- \sqcap B^-
                                                              intersection
 \begin{array}{rcl} \text{dirty type } \underline{C}^-,\underline{D}^- & ::= & A^- \; ! \; \Delta^- \\ & \text{dirt } \Delta & ::= & \text{Op} \end{array}
                                                              operation
                                                              row variable
                                                              empty dirt
                                     \Delta_1 \sqcap \Delta_2
                                                              intersection
                                     \Delta_1 \sqcup \Delta_2
                                                              union
   All operations \Omega ::= \{0p_i | 0p_i \in \Sigma\}
```

Figuur 6.5: Polar types of EffCore

Proofs

Implementation

Describe the approach itself, in such detail that a reader could also implement this approach if s/he wished to do that.

Evaluation

Novel approaches to problems are often evaluated empirically. Describe the evaluation process in such detail that a reader could reproduce the results. Describe in detail the setup of an experiment. Argue why this experiment is useful, and what you could learn from it. Be precise about what you want to measure, or about the hypothesis that you are testing. Discuss and interpret the results in terms of your experimental questions. Summarize the conclusions of the experimental evaluation.

Conclusion

Briefly recall what the goal of the work was. Summarize what you have done, summarize the results, and present conclusions. Conclusions include a critical assessment: where the original goals reached? Discuss the limitations of your work. Describe how the work could possibly be extended in the future, mitigating limitations or solving remaining problems.

Bijlagen

Bibliografie

[1] A. Bauer and M. Pretnar. An effect system for algebraic effects and handlers. *Logical Methods in Computer Science*, 10(4), 2014.

Fiche masterproef

Student: Axel Faes

Titel: Algebraic Subtyping for Algebraic Types and Effects

UDC:

Korte inhoud:

Thesis voorgedragen tot het behalen van de graad van Master of Science in de ingenieurswetenschappen: computerwetenschappen, hoofdoptie Artificiële intelligentie

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