

Algebraic Subtyping for Algebraic Effects and Handlers

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Preface

 stuff

Axel Faes

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Abstract

Algebraic effects and handlers are a very active area of research. An important aspect is the development of an optimising compiler. EFF is an ML-style language with support for effects and forms the testbed for the optimising compiler. However, the type-&-effect system of EFF is unsatisfactory. This is due to the lack of some elegant properties. It is also awkward to implement and use in practice. This thesis proposes a new type-&-effect system using intersections and unions for both types and effects. The type-&-effect system and the type-&-effect inference algorithm are given and are critically discussed. Several aspects of the system are formally proven. Finally, the system is experimentally validated using an implementation which is compared to several existing type-&-effect systems.

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List of Abbreviations and Symbols

Abbreviations

LoG Laplacian-of-Gaussian MSE Mean Square error

PSNR Peak Signal-to-Noise ratio

Symbols

LoG Laplacian-of-Gaussian MSE Mean Square error

PSNR Peak Signal-to-Noise ratio

Introduction

The specification for a type-&-effect system with algebraic subtyping for algebraic effects and handlers is given in this document. The formal properties of this system are studied in order to find which properties are satisfied compared to other type-&-effect systems. The proposed type-&-effect system builds on two very recent developments in the area of programming language theory.

Algebraic subtyping In his December 2016 PhD thesis, Stephen Dolan (University of Cambridge, UK), has presented a novel type system that combines subtyping and parametric polymorphism in a particulary attractive and elegant fashion. A cornerstone of his design are the algebraic properties that the subtyping relation should respect.

Algebraic effects and handlers These are a new formalism for formally modelling side-effects (e.g. mutable state or non-determinism) in programming languages, developed by Matija Pretnar (University of Ljubjana) and Gordon Plotkin (University of Edinburgh). This approach is gaining a lot of traction, not only as a formalism but also as a practical feature in actual programming languages (e.g. the Koka language developed by Microsoft Research). We are collaborating with Matija Pretnar on the efficient implementation of one such language, called Eff. Axel Faes has contributed to this collaboration during a project he did for the Honoursprogramme of the Faculty of Engineering Science.

1.1 Motivation

Algebraic effects and handlers benefit from a custom type-&-effect system, a type system that also tracks which effects can happen in a program. Several such type-&-effect systems have been proposed in the literature, but all are unsatisfactory. We attribute this to the lack of the elegant properties of Dolan's type system. Indeed the existing type-&-effect systems are not only theoretically unsatisfactory, but they are also awkward to implement and use in practice.

1.2 Research questions

- How can Dolan's elegant type system be extended with effect information?
- Which properties are preserved and which aren't preserved?
- What advantages are there to an type-&-effect system based on Dolan's elegant type system?

1.3 Goals

The goal of this thesis is to derive a type-&-effect system that extends Dolan's elegant type system with effect information. This type-&-effect system should inherit Dolan's harmonious combination of subtyping (in our case induced by a lattice structure on the effect information) with parametric polymorphism and preserve all of its desirable properties (both low-level algebraic properties and high-level meta-theoretical properties like type soundness and the existence of principal types). Afterwards this type-&-effect system The following approach is taken:

- 1. Study of the relevant literature and theoretical background.
- 2. Design of a type-&-effect system derived from Dolan's, that integrates effects.
- 3. Proving the desirable properties of the proposed type-&-effect system: type soundness, principal typing, ...
- 4. Time permitting: Design of a type inference algorithm that derives the principal types of programs without type annotations and proving its correctness.
- 5. Time permitting: Implementation of the algorithm and comparing it to other algorithms (such as row polymorphism based type-&-effect systems).

Background

Related Work (Eff)

The type-&-effect system that is used in EFF is based on subtyping and dirty types [1].

3.1 Types and terms

Terms Figure \sim 3.1 shows the two types of terms in EFF. There are values v and computations c. Computations are terms that can contain effects. Effects are denoted as operations Op which can be called.

Types Figure~3.2 shows the types of Eff. There are two main sorts of types. There are (pure) types A, B and dirty types C, D. A dirty type is a pure type A tagged with a finite set of operations Δ , which we call dirt, that can be called. This finite set Δ is an over-approximation of the operations that are actually called. The type $C \Rightarrow D$ is used for handlers because a handler takes an input computation C, handles the effects in this computation and outputs computation D as the result.

3.2 Type System

3.2.1 Subtyping

The dirty type A! Δ is assigned to a computation returning values of type A and potentially calling operations from the set Δ . This set Δ is always an overapproximation of the actually called operations, and may safely be increased, inducing a natural subtyping judgement A! $\Delta \leq A$! Δ' on dirty types. As dirty types can occur inside pure types, we also get a derived subtyping judgement on pure types. Both judgements are defined in Figure~3.3. Observe that, as usual, subtyping is contravariant in the argument types of functions and handlers, and covariant in their return types.

```
variable
value v :=
                                                  constant
                  k
                                                  function
                  fun x \mapsto c
                                                  handler
                                                     return case
                     return x \mapsto c_r,
                     [\operatorname{Op} y k \mapsto c_{\operatorname{Op}}]_{\operatorname{Op} \in O}
                                                     operation cases
                                                  application
comp c ::=
                 v_1 v_2
                                                  rec definition
                  let rec f x = c_1 in c_2
                  return v
                                                  returned val
                                                  operation call
                  0p v
                  do x \leftarrow c_1 ; c_2
                                                  sequencing
                                                  handling
                  handle c with v
```

FIGURE 3.1: Terms of Eff

```
(pure) type A, B ::= bool \mid int basic types  \mid A \to \underline{C} \qquad \text{function type}   \mid \underline{C} \Rightarrow \underline{D} \qquad \text{handler type}   \text{dirty type } \underline{C}, \underline{D} ::= A ! \Delta   \text{dirt } \Delta ::= \{ \mathbb{Op}_1, \dots, \mathbb{Op}_n \}
```

FIGURE 3.2: Types of Eff

3.2.2 Typing rules

Figure~3.4 defines the typing judgements for values and computations with respect to a standard typing context Γ .

Values The rules for subtyping, variables, and functions are entirely standard. For constants we assume a signature Σ that assigns a type~A to each constant~k, which we write as $(k : A) \in \Sigma$.

A handler expression has type $A ! \Delta \cup O \Rightarrow B ! \Delta$ iff all branches (both the operation cases and the return case) have dirty type $B ! \Delta$ and the operation cases cover the set of operations O. Note that the intersection $\Delta \cap O$ is not necessarily empty. The handler deals with the operations O, but in the process may re-issue some of them (i.e., $\Delta \cap O$).

When typing operation cases, the given signature for the operation $(Op: A_{Op} \rightarrow B_{Op}) \in \Sigma$ determines the type A_{Op} of the parameter x and the domain B_{Op} of the continuation k. As our handlers are deep, the codomain of k should be the same as the type $B ! \Delta$ of the cases.

FIGURE 3.3: Subtyping for pure and dirty types of Eff

Computations With the following exceptions, the typing judgement $\Gamma \vdash c : \underline{C}$ has a straightforward definition. The **return** construct renders a value v as a pure computation, i.e., with empty dirt. An operation invocation $\mathfrak{Op}\,v$ is typed according to the operation's signature, with the operation itself as its only operation. Finally, rule With shows that a handler with type $\underline{C} \Rightarrow \underline{D}$ transforms a computation with type \underline{C} into a computation with type \underline{D} .

FIGURE 3.4: Typing of Eff

Problem Statement

Planning

Core language (EffCore)

EFFCORE is a language with row-based effects, intersection and union types and effects and is subtyping based.

6.1 Types and terms

Terms Figure ~ 6.1 shows the two types of terms in EFFCORE. There are values v and computations c. Computations are terms that can contain effects. Effects are denoted as operations Op which can be called. The function term is explicitly annotated with a type and type abstraction and type application has been added to the language. These terms only work on pure types.

Types Figure~6.2 shows the types of EffCore. There are two main sorts of types. There are (pure) types A, B and dirty types C, D. A dirty type is a pure type A tagged with a finite set of operations Δ , which we call dirt, that can be called. It can also be an union or intersection of dirty types. In further sections, the relations between dirty intersections or unions and pure intersections or unions are explained. The finite set Δ is an over-approximation of the operations that are actually called. Row variables are introduced as well as intersection and unions. The .(DOT) is used to close rows that do not end with a row variable. The type $C \Rightarrow D$ is used for handlers because a handler takes an input computation C, handles the effects in this computation and outputs computation D as the result.

6.2 Type system

6.2.1 Subtyping

The subtyping rules are given in Figure~6.3, Figure~6.4 and Figure~6.5. Figure~6.3 contains all subtyping rules related to types. Figure~6.4 contains the distributative subtyping rules. Finally Figure~6.5 contains the subtyping rules that govern the dirts.

```
value v :=
                                                 variable
                 x
                                                 constant
                 k
                                                 function
                 fun x:A\mapsto c
                 \Lambda \alpha. v
                                                 type abstraction
                                                 type application
                 vA
                                                 handler
                    return x \mapsto c_r,
                                                    return case
                    [\operatorname{Op} y k \mapsto c_{\operatorname{Op}}]_{\operatorname{Op} \in O}
                                                    operation cases
comp c ::= v_1 v_2
                                                 application
                                                 conditional
                 if e then c_1 else c_2
                 let rec f x = c_1 in c_2
                                                 rec definition
                                                 returned val
                 return v
                                                 operation call
                 0pv
                                                 sequencing
                 do x \leftarrow c_1 ; c_2
                 handle c with v
                                                 handling
```

FIGURE 6.1: Terms of EffCore

The dirty type A ! Δ is assigned to a computation returning values of type A and potentially calling operations from the set Δ . This set Δ is always an overapproximation of the actually called operations, and may safely be increased, inducing a natural subtyping judgement A ! $\Delta \leq A$! Δ' on dirty types. As dirty types can occur inside pure types, we also get a derived subtyping judgement on pure types. Observe that, as usual, subtyping is contravariant in the argument types of functions and handlers, and covariant in their return types.

Dirt intersection and union There are several possible methods to compute the dirt intersection and union. If row variables were to be disregarded, dirt union and intersection could be defined as set union and intersection. This methods allows unions and intersections to be eliminated. This has an advantage, eliminating unions and intersections simplifies the effect system. However, we cannot disregard row variables.

Thus, set union and intersection cannot simply be used. It would be possible to define two extra types, namely $\delta_1 \sqcup \delta_2$ and $\delta_1 \sqcap \delta_2$. Using these types, it is possible to use a form of set union and intersection. The following union $\{Op_1, ..., Op_n, \delta_1\} \sqcup \{Op_{n+1}, ..., Op_{n+m}, \delta_2\}$ could be defined as $\{Op_1, ..., Op_n, Op_{n+1}, ..., Op_{n+m}, (\delta_1 \sqcup \delta_2)\}$. A similar construction can be used for intersection. This simplifies the subtyping rules since the more complicated aspects are enclosed within the row variables.

```
(pure) type A, B ::= bool \mid int
                                                 basic types
                                                  function type
                                                 handler type
                                                 type variable
                              \forall \alpha.A
                                                 polytype
                               Т
                                                 top
                                                 bottom
                              A \sqcap B
                                                 intersection
                              A \sqcup B
                                                 union
 dirty type \underline{C}, \underline{D} ::= A ! \Delta
                              C \sqcap D
                                                 intersection
                              C \sqcup D
                                                 union
             \operatorname{dirt} \Delta ::= \{R\}
                   R ::= Op; R
                                                 row
                              δ
                                                 row variable
                                                 closed row
                              \delta_1 \sqcap \delta_2
                                                 row intersection
                              \delta_1 \sqcup \delta_2
                                                 row union
                              R_1 \sqcap R_2
                                                 intersection
                              R_1 \sqcup R_2
                                                 union
```

FIGURE 6.2: Types of EffCore

6.2.2 Typing rules

Figure \sim 6.7 defines the typing judgements for values and computations with respect to a standard typing context Γ .

Values The rules for subtyping, variables, type abstraction, type application and functions are entirely standard. For constants we assume a signature Σ that assigns a type-A to each constant-k, which we write as $(k : A) \in \Sigma$.

A handler expression has type $A ! \Delta \cup O \Rightarrow B ! \Delta$ iff all branches (both the operation cases and the return case) have dirty type $B ! \Delta$ and the operation cases cover the set of operations O. Note that the intersection $\Delta \cap O$ is not necessarily empty (with \cap being the intersection of the operations, not to be confused with the \cap type). The handler deals with the operations O, but in the process may re-issue some of them (i.e., $\Delta \cap O$).

When typing operation cases, the given signature for the operation $(Op: A_{Op} \rightarrow B_{Op}) \in \Sigma$ determines the type A_{Op} of the parameter x and the domain B_{Op} of the continuation k. As our handlers are deep, the codomain of k should be the same as the type $B ! \Delta$ of the cases.

FIGURE 6.3: Subtyping for pure and dirty types of EffCore

Computations With the following exceptions, the typing judgement $\Gamma \vdash c : \underline{C}$ has a straightforward definition. The **return** construct renders a value v as a pure computation, i.e., with empty dirt. In this case, this is defined as a set with the .(DOT) as the only element. An operation invocation $\operatorname{Op} v$ is typed according to the operation's signature, with the operation itself as its only operation. Finally, rule WITH shows that a handler with type $\underline{C} \Rightarrow \underline{D}$ transforms a computation with type \underline{C} into a computation with type \underline{D} .

Distributivity Subtyping of pure and dirty types					
Sub-Dist-Func-Inter		SUB-DIST-FUNC-UNION			
$\overline{(A \to \underline{C}) \sqcap (A \to \underline{D}) \leqslant A \to (\underline{C})}$	$\overline{\underline{C} \sqcap \underline{D}}$	$\overline{(A \to \underline{C}) \sqcap (B \to \underline{C}) \leqslant (A \sqcup B) \to \underline{C}}$			
Sub-Dist-Hand-Inter	Sub-Dist-Hand-Union				
$\overline{(A \Rightarrow \underline{C}) \sqcap (A \Rightarrow \underline{D}) \leqslant A \Rightarrow (\underline{C})}$	$\overline{(A \Rightarrow \underline{C}) \sqcap (B \Rightarrow \underline{C}) \leqslant (A \sqcup B) \Rightarrow \underline{C}}$				
Sub-Dist-All	ER-UNION				
$\overline{\forall \alpha.A \sqcap \forall \alpha.B \leqslant \forall \alpha.A \sqcap B} \qquad \overline{(A_1 \sqcap A_3) \sqcup (A_2 \sqcap A_4) \leqslant (A_1 \sqcup A_2) \sqcap (A_3 \sqcup A_4)}$					
Sub-Union-Inter					
$\overline{(A_1 \sqcup A_3) \sqcap (A_2 \sqcup A_4) \leqslant (A_1 \sqcap A_2) \sqcup (A_3 \sqcap A_4)}$					

Figure 6.4: Distributivity Subtyping for pure and dirty types of ${\tt EffCore}$

Subtyping of dirts
$$\frac{\text{Sub-l-Empty}}{\{.\} \leqslant \Delta} \qquad \frac{\text{Sub-l-Top}}{\{Op_1,...,Op_n,.\} \leqslant \{Op_1,...,Op_n,\delta\}}$$

$$\frac{\text{Sub-l-Refl.}}{\Delta \leqslant \Delta} \qquad \frac{\text{Sub-l-Trans}}{\Delta_1 \leqslant \Delta_2} \qquad \Delta_2 \leqslant \Delta_3$$

$$\frac{\Delta_1 \leqslant \Delta_2}{\Delta_1 \leqslant \Delta_3} \qquad \Delta_1 \leqslant \Delta_3$$

$$\frac{\text{Sub-l-Row-Row}}{\{Op_1,...,Op_n,Op_{n+m+1},...,Op_{n+m+p},\delta_1\} \leqslant \{Op_1,...,Op_n,Op_{n+m},\delta_2\}}{\{\delta_1\} \leqslant \{Op_{n+1},...,Op_{n+m},\delta_2\}} \qquad Op_{n+m},...,Op_{n+m+p} \subseteq \delta_2}$$

$$\frac{\text{Sub-l-Dot-Row}}{\{Op_1,...,Op_n,Op_{n+m+1},...,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m+p} \subseteq \delta_2\}}{\{Op_1,...,Op_n,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m},\delta_2\}} \qquad Op_{n+m},...,Op_{n+m+p} \subseteq \delta_2}$$

$$\frac{\text{Sub-l-Row-Dot}}{\{0p_1,...,Op_n,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m+p} \subseteq \delta_2\}}{\{Op_{n+1},...,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+m+p},\cdot\} \leqslant \{Op_1,...,Op_n,Op_{n+1},Op_{n+m+p},\cdot\} \leqslant \{Op_{n+1},Op_{n+m+p},\cdot\} \leqslant \{Op_{n+1},Op_{n+$$

Figure 6.5: Subtyping for dirts of EffCore

$$\begin{array}{|c|c|c|} \hline \textbf{Subtyping of dirts} \\ \hline \textbf{Sub-!-Empty} & \textbf{Sub-!-Refl} & \frac{\textbf{Sub-!-Trans}}{\delta_1 \leqslant \delta_2} & \frac{\textbf{Sub-Inter-!}}{\delta_1 \leqslant \delta_2} & \delta_3 \leqslant \delta_4 \\ \hline \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \hline \textbf{Sub-Union-!} & \textbf{Sub-Inter-G-!} & \textbf{Sub-Inter-G-!} \\ \hline \frac{\delta_1 \leqslant \delta_2}{\delta_1 \sqcup \delta_3} \leqslant \delta_2 \sqcup \delta_4 & \frac{\textbf{Sub-Inter-G-!}}{\delta_1 \leqslant \delta_2} & \frac{\textbf{Sub-Inter-Lb-!}}{\delta_1 \leqslant \delta_2} & \vdots \\ \hline \frac{\delta_1 \leqslant \delta_2}{\delta_1 \sqcup \delta_3} \leqslant \delta_2 \sqcup \delta_4 & \frac{\delta_1 \leqslant \delta_2}{\delta_1 \leqslant \delta_3} & \frac{\textbf{Sub-Union-Ub-!}}{\delta_1 \leqslant \delta_3} & \vdots \\ \hline \frac{Sub-Union-L-!}{\delta_2 \leqslant \delta_1} & \frac{\textbf{Sub-Union-Ub-!}}{\delta_1 \leqslant \delta_2 \sqcup \delta_3} & \vdots \\ \hline & \vdots \leqslant \{1;2\} \\ \hline & (\delta_2 \sqcup \delta_3) \leqslant \delta_1 & \vdots \\ \hline & (\delta_2 \sqcup \delta_3) \leqslant \delta_1 & \vdots \\ \hline & Sub-Union-Ub-!} \\ \hline & (\delta_1 \sqcup \delta_3) \sqcup (\delta_2 \sqcup \delta_4) \leqslant (\delta_1 \sqcup \delta_2) \sqcup (\delta_3 \sqcup \delta_4) \\ \hline & \underline{\textbf{Sub-Union-Inter-!}} \\ \hline & (\delta_1 \sqcup \delta_3) \sqcup (\delta_2 \sqcup \delta_4) \leqslant (\delta_1 \sqcup \delta_2) \sqcup (\delta_3 \sqcup \delta_4) \\ \hline & \underline{\textbf{Sub-Union-Inter-!}} \\ \hline & (\delta_1 \sqcup \delta_3) \sqcup (\delta_2 \sqcup \delta_4) \leqslant (\delta_1 \sqcup \delta_2) \sqcup (\delta_3 \sqcup \delta_4) \\ \hline & \underline{\textbf{Dirt-Var-Union-!}} \\ \hline & \underline{\textbf{Op_1}, ..., \textbf{Op_n, Op_{n+1}, ..., Op_{n+m}, (\delta_1 \sqcup \delta_2)} \leqslant \\ \hline & \underline{\textbf{Op_1}, ..., Op_n, \delta_1} \sqcup \{Op_{n+1}, ..., Op_{n+m}, (\delta_1 \sqcup \delta_2)\} \leqslant \\ \hline & \underline{\textbf{Op_1}|Op_i \in \{Op_1, ..., Op_n\} \land Op_i \in \{Op_{n+1}, ..., Op_{n+m}, \delta_2\}} \\ \hline & \underline{\textbf{Dirt-Var-Intersection-!}} \\ \hline & \underline{\textbf{Op_1}|Op_i \in \{Op_1, ..., Op_n, \delta_1\} \sqcap \{Op_{n+1}, ..., Op_{n+m}, \delta_2\}} \\ \hline \end{array}$$

FIGURE 6.6: Subtyping for dirts of EFFCORE using row variable unions and intersections

FIGURE 6.7: Typing of EffCore

Type Inference

The elaboration show how the source language can be transformed into EffCore.

Figure 7.1: Elaboration of source to core language: expressions

Figure 7.2: Elaboration of source to core language: computations

Semantics

Proofs

Implementation

Evaluation

Conclusion

[1] Bauer, A. and Pretnar, M. 2014. An effect system for algebraic effects and handlers. *Logical Methods in Computer Science*. 10, 4 (2014). DOI:https://doi.org/10.2168/LMCS-10(4:9)2014.

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