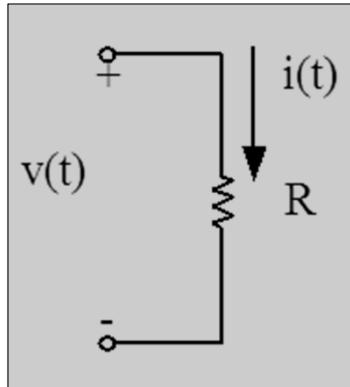


RL Laplace

- Laplace Impedances
- First Order RL
 - Schematic
 - Gain (Transfer Function)
 - Response to step (manual, MATLAB, Multisim)

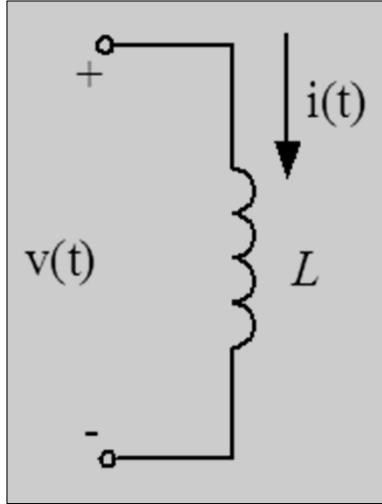
Resistor's Laplace Impedance



$$v_R(t) =$$

$$Z_R(s) =$$

Inductor's Laplace Impedance



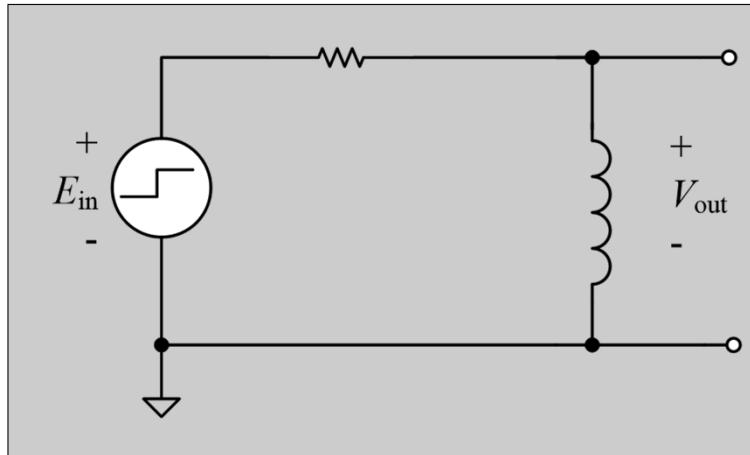
$$v_L(t) =$$

$$Z_L(s) =$$

TABLE A-1 (continued)

No.	$F(s)$
7.	$\frac{As}{s^2 + \omega^2}$
8.	$aF(s)$
9.	$\frac{n!}{s^{n+1}}$
10.	$sF(s) - f(0)$
11.	$s^2F(s) - sf(0) - \frac{df(0)}{dt}$
12.	$\frac{F(s)}{s}$
13a.	$\frac{A}{\tau s + 1}$
13b.	$\frac{A}{s + a}$
14a.	$\frac{A}{s - j\omega_0}$

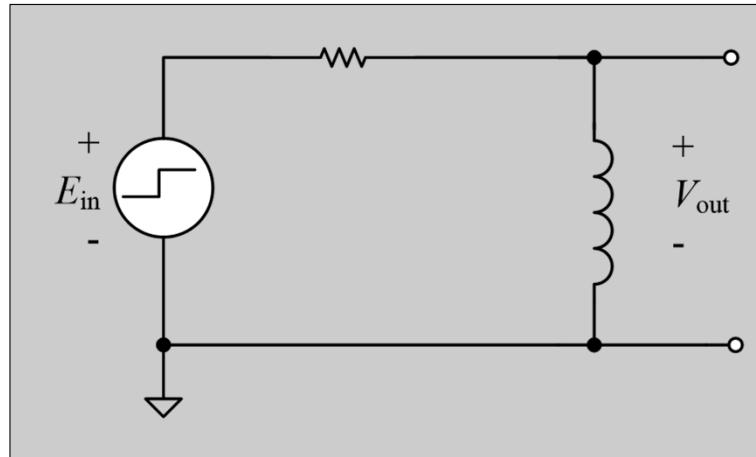
RL Circuit – Transfer Function



$$V_{\text{out}}(s) =$$

$$\frac{V_{\text{out}}(s)}{E_{\text{in}}(s)} =$$

RL Circuit – Response to 5 V step



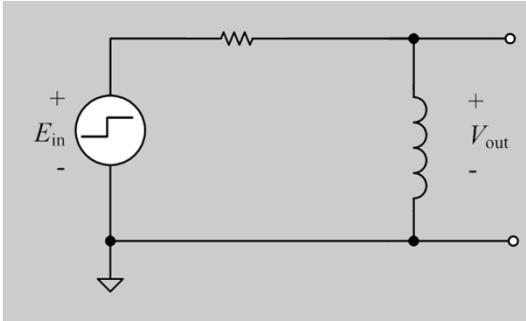
$$\frac{V_{\text{out}}(s)}{E_{\text{in}}(s)} =$$

$$V_{\text{out}} =$$

$$E_{\text{in step}} =$$

TABLE A-1 LAPLACE TRANSFORMS

No.	$F(s)$	$f(t)$	Comments
1.	1	$\delta(t)$	Unit impulse
2.	$\frac{A}{s}$	$A(t) = \begin{cases} 0 & t < 0 \\ A & t \geq 0 \end{cases}$	Step
3.	$\frac{1}{s}$	$U(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$	Unit step
4.	$\frac{A}{s^2}$	At	Ramp
5.	$\frac{2A}{s^3}$	At^2	Parabola
6.	$\frac{A\omega}{s^2 + \omega^2}$	$A \sin \omega t$	Sine



RL Circuit – Response to 5 V step

$$V_{\text{out}}(s) =$$

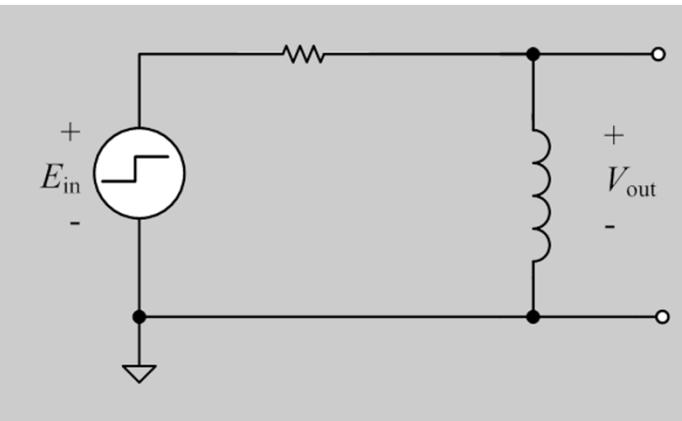
TABLE A-1 (continued)

No.	$F(s)$	$f(t)$	Comments
7.	$\frac{As}{s^2 + \omega^2}$	$A \cos \omega t$	Cosine
8.	$aF(s)$	$af(t)$	
9.	$\frac{n!}{s^{n+1}}$	t^n	
10.	$sF(s) - f(0)$	$\frac{df(t)}{dt}$	
11.	$s^2F(s) - sf'(0) - \frac{df(0)}{dt}$	$\frac{d^2f(t)}{dt^2}$	
12.	$\frac{F(s)}{s}$	$\int f(t) dt$	
13a.	$\frac{A}{\tau s + 1}$	$\frac{A}{\tau} e^{-\nu t}$	Free response of first-order system
13b.	$\frac{A}{s + a}$	Ae^{-at}	
14a.	$\frac{A}{(\tau_1 s + 1)(\tau_2 s + 1)}$	$\frac{A}{\tau_1 - \tau_2} (e^{-\nu_1 t} - e^{-\nu_2 t})$	Free response of second-order system ($\zeta > 1$)
14b.	$\frac{A}{(s + a)(s + b)}$	$\frac{A}{b - a} (e^{-\nu_1 t} - e^{-\nu_2 t})$	
15a.	$\frac{A}{(\tau s + 1)^2}$	$\frac{At}{\tau^2} e^{-\nu t}$	Free response of second-order system ($\zeta = 1$)
15b.	$\frac{A}{(s + a)^2}$	$At e^{-at}$	
16.	$\frac{A\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2}$	$\frac{A\omega_n e^{-\xi\nu t}}{\sqrt{1 - \xi^2}} \sin(\omega_n \sqrt{1 - \xi^2} t)$	Second-order system, free response ($\zeta < 1$)
17a.	$\frac{A}{s(\tau s + 1)}$	$A(1 - e^{-\nu t})$	First-order system response to a step input
17b.	$\frac{A}{s(s + a)}$	$\frac{A}{a}(1 - e^{-\nu t})$	
18a.	$\frac{A}{s^2(\tau s + 1)}$	$A\tau \left(e^{-\nu t} + \frac{t}{\tau} - 1 \right)$	First-order system response to a ramp input
18b.	$\frac{A}{s^2(s + a)}$	$\frac{A}{a^2} (e^{-\nu t} + at - 1)$	

$$V_{\text{out}}(t) =$$

$$V_{\text{out}}(t = 0+) =$$

$$V_{\text{out}}(t \rightarrow \infty) =$$



RL Circuit – Response to 5 V step

$$V_{\text{out}}(s) =$$

$$V_{\text{out}}(t) =$$

```

clc
clear

s=tf('s')
R=
L=
tau=
Ein=
```

```

G=
Vout=
ltiview(Vout)
```

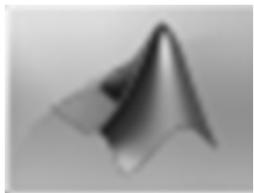
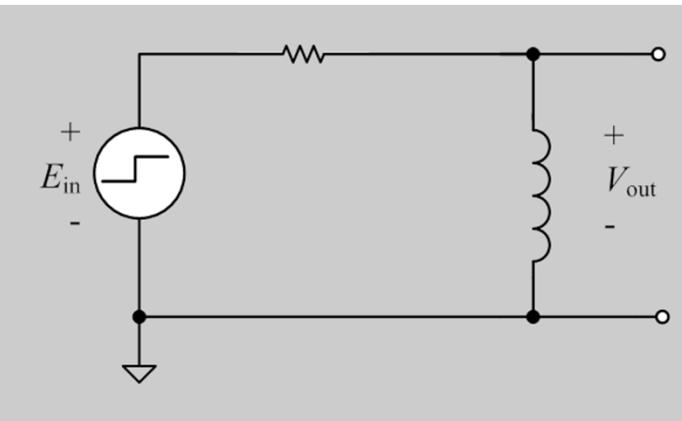


TABLE A-1 LAPLACE TRANSFORMS

No.	$F(s)$	$f(t)$	Comments
1.	1	$\delta(t)$	Unit impulse
2.	$\frac{A}{s}$	$A(t) = \begin{cases} 0 & t < 0 \\ A & t \geq 0 \end{cases}$	Step
3.	$\frac{1}{s}$	$U(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$	Unit step



RL Circuit – Response to 5 V step

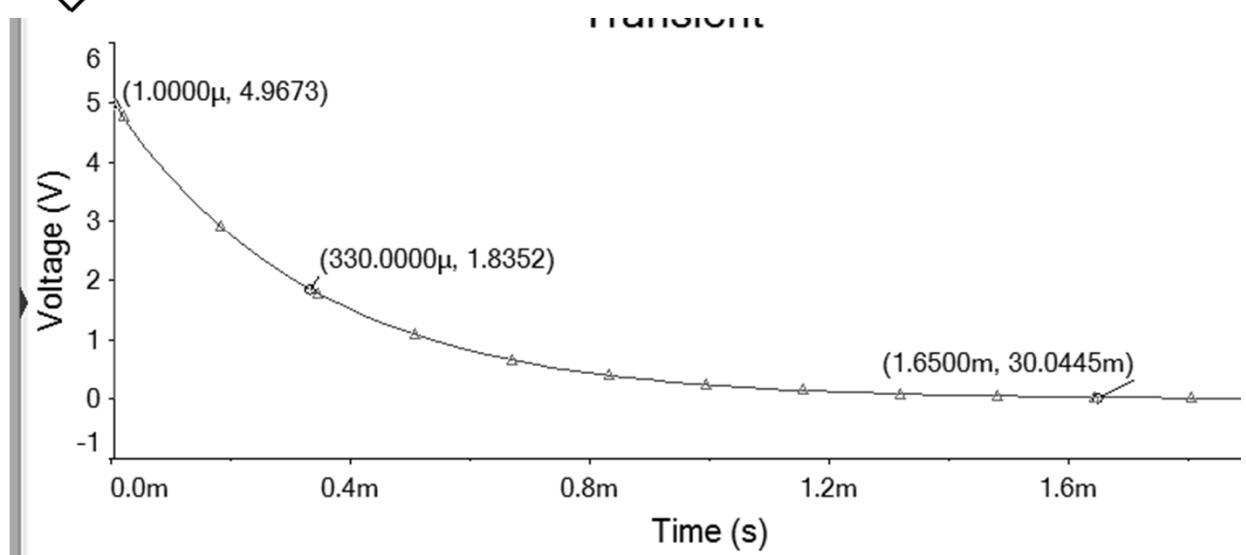
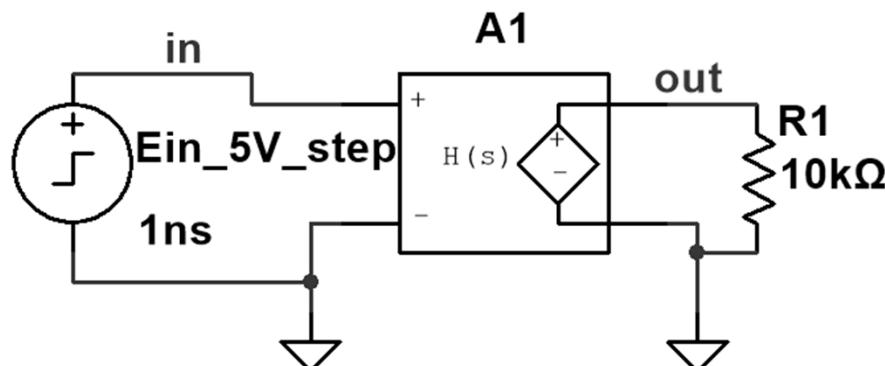
$$R = \underline{\hspace{2cm}}$$

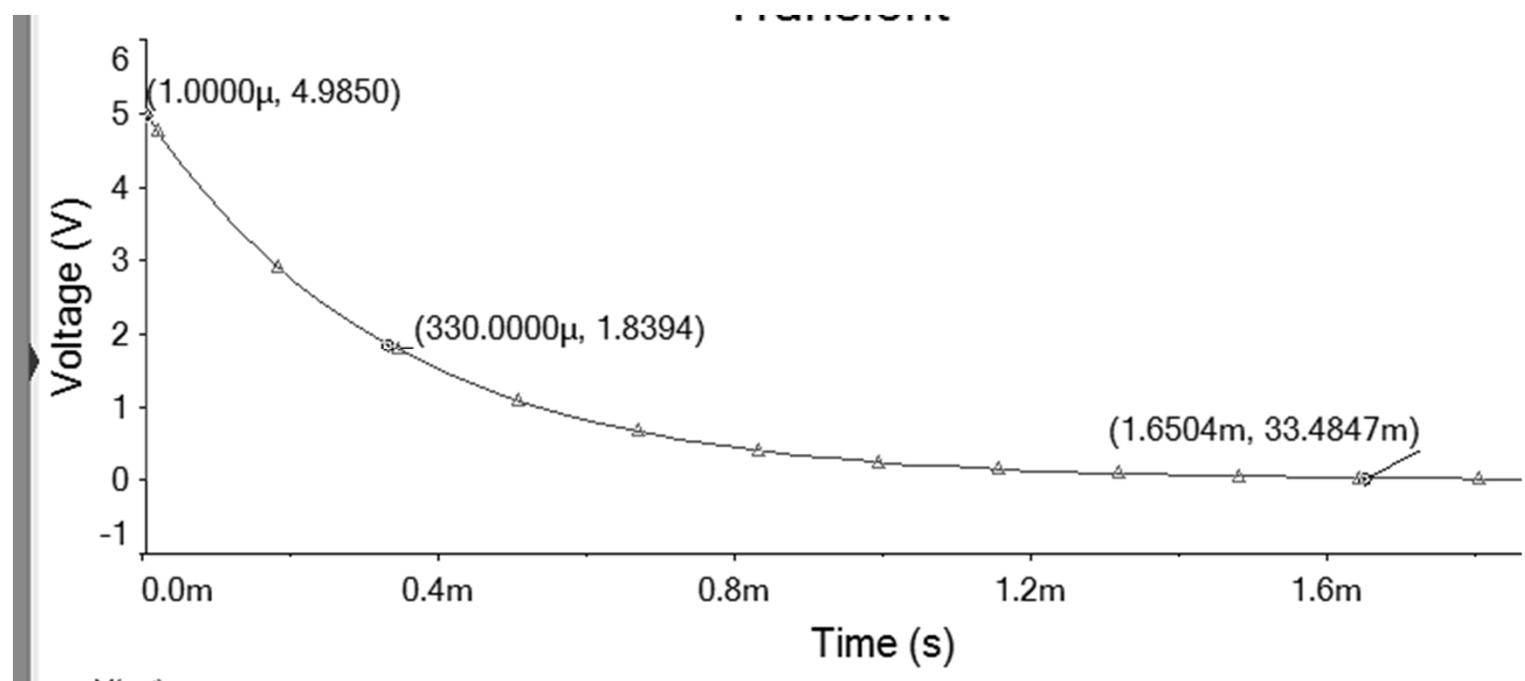
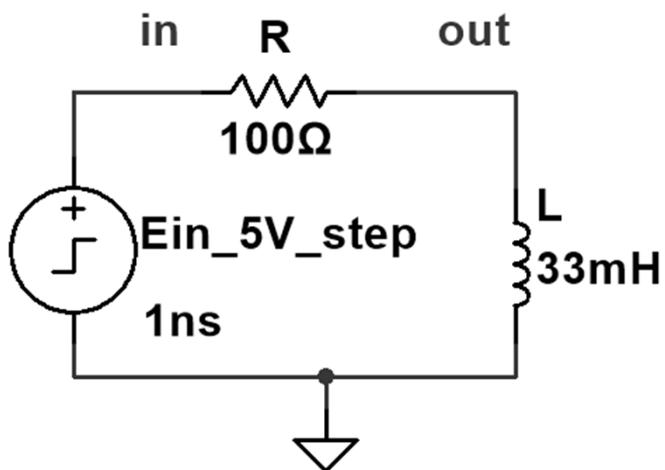
$$\tau = \underline{\hspace{2cm}}$$

$$L = \underline{\hspace{2cm}}$$

$$\frac{V_{\text{out}}(s)}{E_{\text{in}}(s)} = \underline{\hspace{2cm}}$$

$$330e-6 \cdot s / (330e-6 \cdot s + 1) = \frac{1}{\tau s + 1}$$





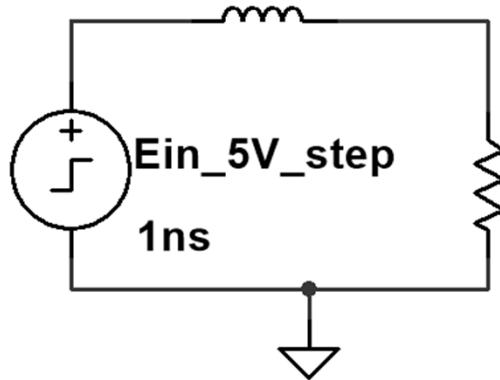


TABLE A-1 (continued)

No.	$F(s)$	$f(t)$	Comments
7.	$\frac{As}{s^2 + \omega^2}$	$A \cos \omega t$	Cosine
8.	$aF(s)$	$af(t)$	
9.	$\frac{n!}{s^{n+1}}$	t^n	
10.	$sF(s) - f(0)$	$\frac{df(t)}{dt}$	
11.	$s^2F(s) - sf(0) - \frac{df(0)}{dt}$	$\frac{d^2f(t)}{dt^2}$	
12.	$\frac{F(s)}{s}$	$\int f(t) dt$	
13a.	$\frac{A}{\tau s + 1}$	$\frac{A}{\tau} e^{-\nu t}$	Free response of first-order system
13b.	$\frac{A}{s + a}$	Ae^{-at}	
14a.	$\frac{A}{(\tau_1 s + 1)(\tau_2 s + 1)}$	$\frac{A}{\tau_1 - \tau_2} (e^{-\nu \tau_1} - e^{-\nu \tau_2})$	Free response of second-order system ($\zeta > 1$)
14b.	$\frac{A}{(s + a)(s + b)}$	$\frac{A}{b - a} (e^{-at} - e^{-bt})$	
15a.	$\frac{A}{(\tau s + 1)^2}$	$\frac{At}{\tau^2} e^{-\nu t}$	Free response of second-order system ($\zeta = 1$)
15b.	$\frac{A}{(s + a)^2}$	$At e^{-at}$	
16.	$\frac{A\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$	$\frac{A\omega_n e^{-\zeta \omega_n t}}{\sqrt{1 - \zeta^2}} \sin(\omega_n \sqrt{1 - \zeta^2} t)$	Second-order system, free response ($\zeta < 1$)
17a.	$\frac{A}{s(\tau s + 1)}$	$A(1 - e^{-\nu t})$	First-order system response to a step input
17b.	$\frac{A}{s(s + a)}$	$\frac{A}{a}(1 - e^{-\nu t})$	
18a.	$\frac{A}{s^2(\tau s + 1)}$	$A\tau \left(e^{-\nu t} + \frac{t}{\tau} - 1 \right)$	First-order system response to a ramp input
18b.	$\frac{A}{s^2(s + a)}$	$\frac{A}{a^2} (e^{-at} + at - 1)$	

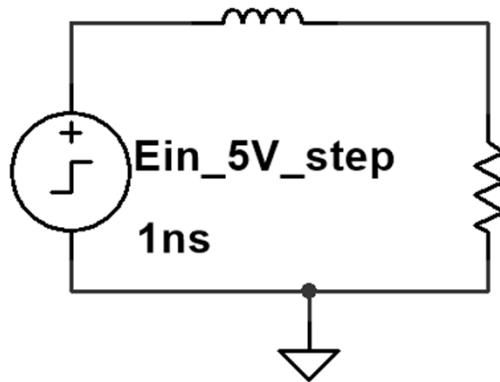
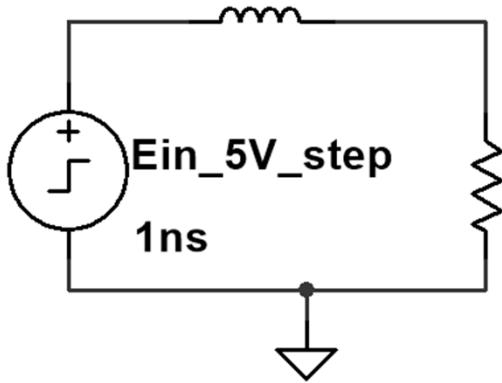


TABLE A-1 (continued)

No.	$F(s)$	$f(t)$	Comments
7.	$\frac{As}{s^2 + \omega^2}$	$A \cos \omega t$	Cosine
8.	$aF(s)$	$af(t)$	
9.	$\frac{n!}{s^{n+1}}$	t^n	
10.	$sF(s) - f(0)$	$\frac{df(t)}{dt}$	
11.	$s^2F(s) - sf(0) - \frac{df(0)}{dt}$	$\frac{d^2f(t)}{dt^2}$	
12.	$\frac{F(s)}{s}$	$\int f(t) dt$	
13a.	$\frac{A}{ts + 1}$	$\frac{A}{\tau} e^{-\nu t}$	Free response of first-order system
13b.	$\frac{A}{s + a}$	Ae^{-at}	
14a.	$\frac{A}{(\tau_1 s + 1)(\tau_2 s + 1)}$	$\frac{A}{\tau_1 - \tau_2} (e^{-\nu \tau_1} - e^{-\nu \tau_2})$	Free response of second-order system ($\zeta > 1$)
14b.	$\frac{A}{(s + a)(s + b)}$	$\frac{A}{b - a} (e^{-at} - e^{-bt})$	
15a.	$\frac{A}{(ts + 1)^2}$	$\frac{At}{\tau^2} e^{-\nu t}$	Free response of second-order system ($\zeta = 1$)
15b.	$\frac{A}{(s + a)^2}$	$At e^{-at}$	
16.	$\frac{A\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$	$\frac{A\omega_n e^{-\zeta \omega_n t}}{\sqrt{1 - \zeta^2}} \sin(\omega_n \sqrt{1 - \zeta^2} t)$	Second-order system, free response ($\zeta < 1$)
17a.	$\frac{A}{s(ts + 1)}$	$A(1 - e^{-\nu t})$	First-order system response to a step input
17b.	$\frac{A}{s(s + a)}$	$\frac{A}{a}(1 - e^{-\nu t})$	
18a.	$\frac{A}{s^2(ts + 1)}$	$A\tau \left(e^{-\nu t} + \frac{t}{\tau} - 1 \right)$	First-order system response to a ramp input
18b.	$\frac{A}{s^2(s + a)}$	$\frac{A}{a^2} (e^{-at} + at - 1)$	



LR Circuit – Response to 5 V step

$$R=100 \Omega, \quad L=33 \text{ mH}$$

$$V_{\text{out}}(s) =$$

$$V_{\text{out}}(t) =$$

```
clc
clear
```

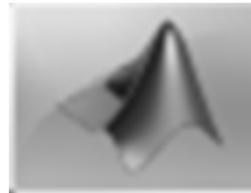
```
s=tf('s')
```

```
R=
```

```
L=
```

```
tau=
```

```
Ein=
```

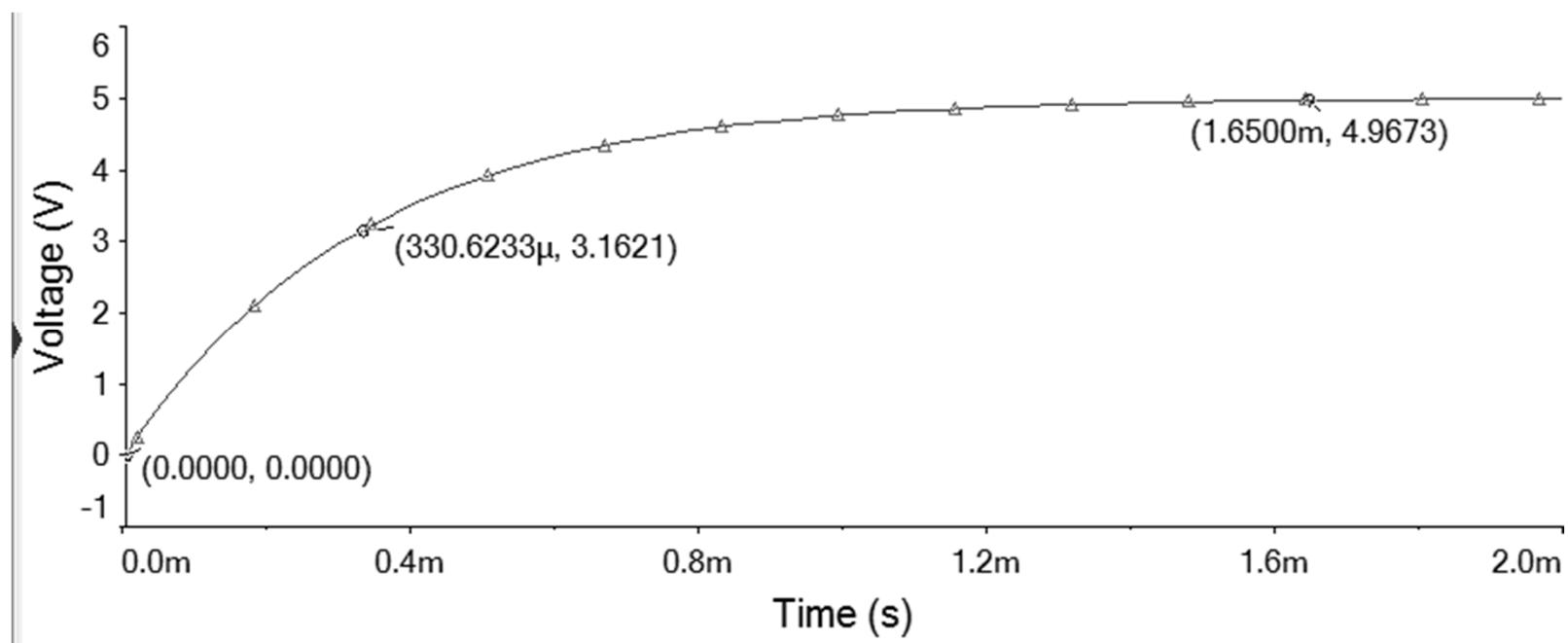
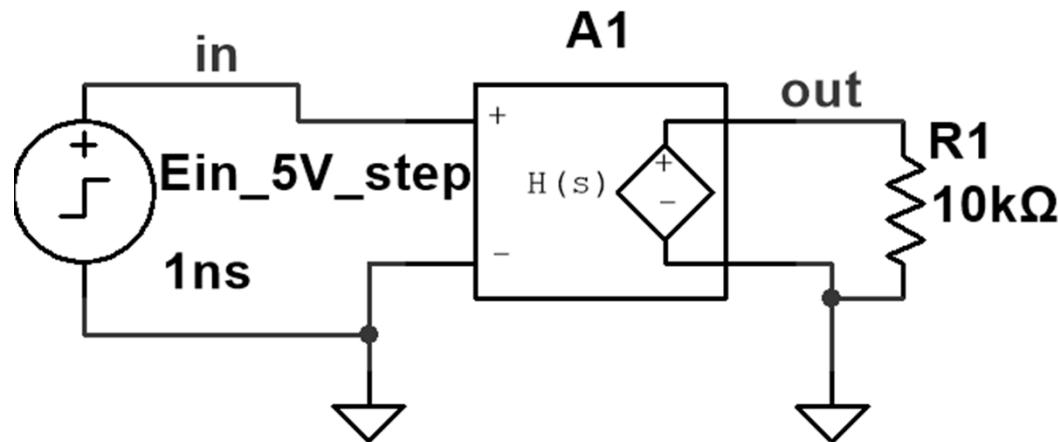


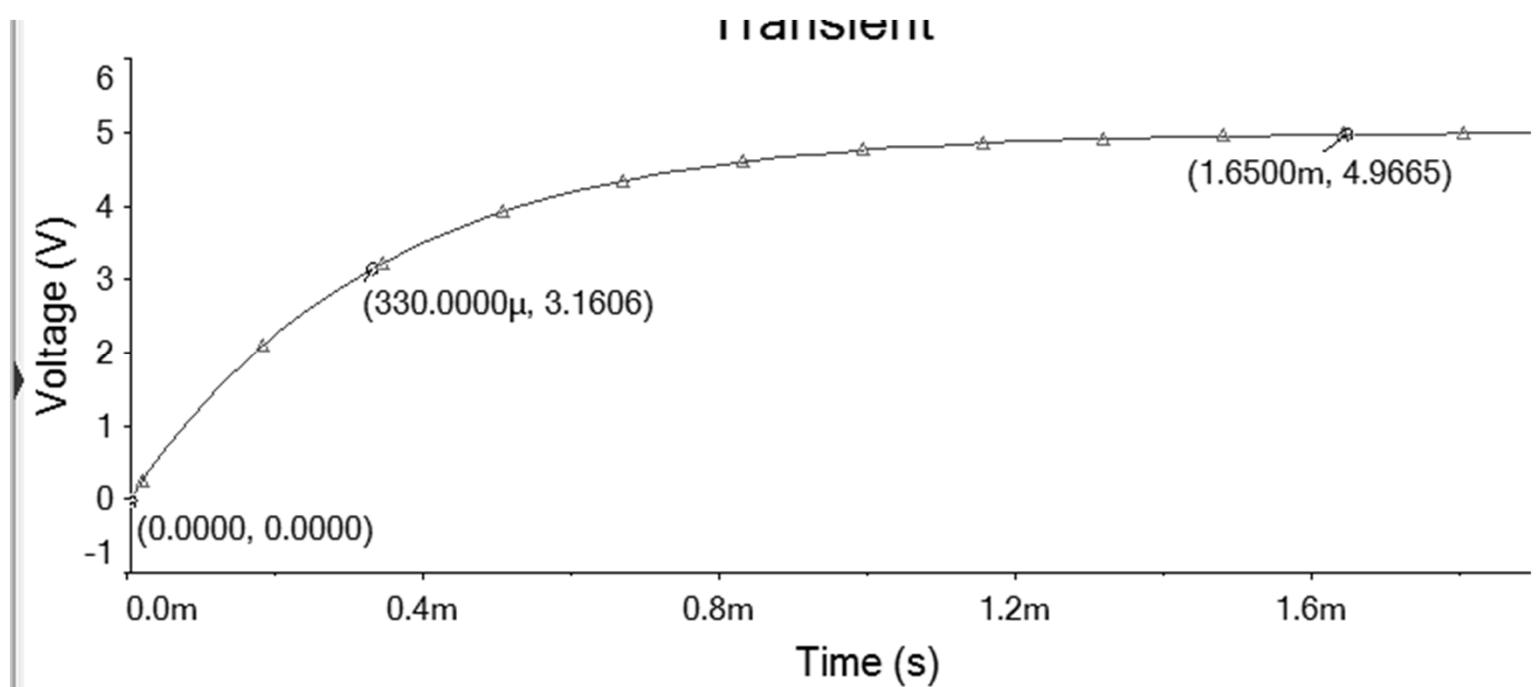
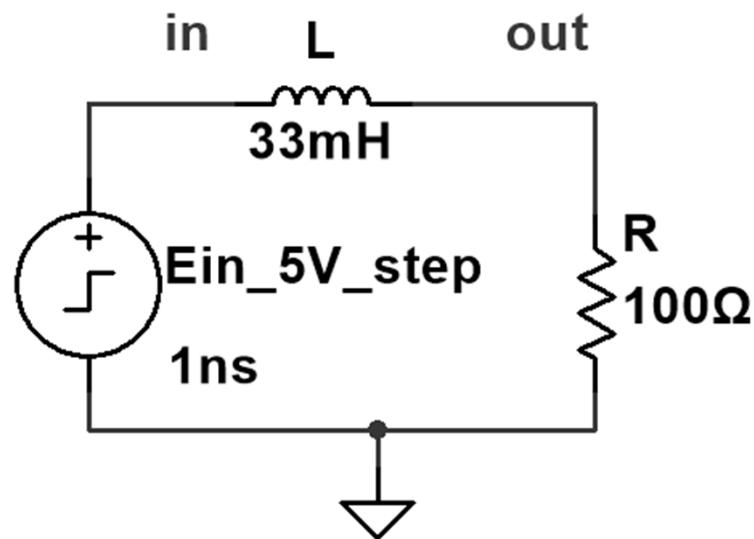
```
G=
```

```
Vout=
```

```
ltiview(Vout)
```

$$1/(330e-6*s+1)$$





Transform Definition => calculus => tables!

TABLE A-1 LAPLACE TRANSFORMS

No.	$F(s)$	$f(t)$	Comments
1.	1	$\delta(t)$	Unit impulse
2.	$\frac{A}{s}$	$A(t) = \begin{cases} 0 & t < 0 \\ A & t \geq 0 \end{cases}$	Step
3.	$\frac{1}{s}$	$U(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$	Unit step
4.	$\frac{A}{s^2}$	At	Ramp
5.	$\frac{2A}{s^3}$	At^2	Parabola
6.	$\frac{A\omega}{s^2 + \omega^2}$	$A \sin \omega t$	Sine
TABLE A-1 (continued)			
No.	$F(s)$	$f(t)$	Comments
7.	$\frac{As}{s^2 + \omega^2}$	$A \cos \omega t$	Cosine
8.	$aF(s)$	$af(t)$	
9.	$\frac{n!}{s^{n+1}}$	t^n	
10.	$sF(s) - f(0)$	$\frac{df(t)}{dt}$	
11.	$s^2F(s) - sf(0) - \frac{df(0)}{dt}$	$\frac{d^2f(t)}{dt^2}$	
12.	$\frac{F(s)}{s}$	$\int f(t) dt$	
13a.	$\frac{A}{ts + 1}$	$\frac{A}{\tau} e^{-\nu t}$	Free response of first-order system
13b.	$\frac{A}{s + a}$	Ae^{-at}	
14a.	$\frac{A}{(\tau_1 s + 1)(\tau_2 s + 1)}$	$\frac{A}{\tau_1 - \tau_2} (e^{-\nu_1 t} - e^{-\nu_2 t})$	Free response of second-order system ($\zeta > 1$)
14b.	$\frac{A}{(s + a)(s + b)}$	$\frac{A}{b - a} (e^{-at} - e^{-bt})$	
15a.	$\frac{A}{(ts + 1)^2}$	$\frac{At}{\tau^2} e^{-\nu t}$	Free response of second-order system ($\zeta = 1$)
15b.	$\frac{A}{(s + a)^2}$	$At e^{-at}$	
16.	$\frac{A\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$	$\frac{A\omega_n e^{-\zeta\omega_n t}}{\sqrt{1 - \zeta^2}} \sin(\omega_n \sqrt{1 - \zeta^2} t)$	Second-order system, free response ($\zeta < 1$)
17a.	$\frac{A}{s(ts + 1)}$	$A(1 - e^{-\nu t})$	First-order system response to a step input
17b.	$\frac{A}{s(s + a)}$	$\frac{A}{a}(1 - e^{-\nu t})$	
18a.	$\frac{A}{s^2(ts + 1)}$	$A\tau \left(e^{-\nu t} + \frac{t}{\tau} - 1 \right)$	First-order system response to a ramp input
18b.	$\frac{A}{s^2(s + a)}$	$\frac{A}{a^2} (e^{-at} + at - 1)$	

TABLE A-1 (continued)

No.	$F(s)$	$f(t)$	Comments
19a.	$\frac{A\omega}{(s^2 + \omega^2)(ts + 1)}$	$\frac{A\omega t}{1 + \omega^2 t^2} e^{-\nu t} + \frac{A}{\sqrt{1 + \omega^2 t^2}} \sin(\omega t - \psi)$ where $\psi = \tan^{-1} \omega t$ ($0 < \psi < \pi$)	First-order system response to a sine input
19b.	$\frac{A\omega}{(s^2 + \omega^2)(s + a)}$	$\frac{A\omega e^{-at}}{\omega^2 + a^2} + \frac{A}{\sqrt{\omega^2 + a^2}} \sin(\omega t - \psi)$ where $\psi = \tan^{-1} \omega/a$ ($0 < \psi < \pi$)	
20a.	$\frac{A}{s(\tau_1 s + 1)(\tau_2 s + 1)}$	$A \left(\frac{\tau_1 e^{-\nu_1 t} - \tau_2 e^{-\nu_2 t}}{\tau_2 - \tau_1} \right)$	Second-order system response to a step input ($\zeta > 1$)
20b.	$\frac{A}{s(s + a)(s + b)}$	$\frac{A}{ab} \left(1 + \frac{ae^{-bt} - be^{-at}}{b - a} \right)$	Second-order system response to a step input ($\zeta = 1$)
21a.	$\frac{A}{s(ts + 1)^2}$	$A \left(1 - \frac{\tau + t}{\tau} e^{-\nu t} \right)$	
21b.	$\frac{A}{s(s + a)^2}$	$\frac{A}{a^2} [1 - (1 + at)e^{-\nu t}]$	
22.	$\frac{A\omega_n^2}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)}$	$A \left[1 + \frac{e^{-\zeta\omega_n t}}{\sqrt{1 - \zeta^2}} \sin(\omega_n \sqrt{1 - \zeta^2} t - \psi) \right]$ where $\psi = \tan^{-1} \frac{\sqrt{1 - \zeta^2}}{-\zeta}$ ($0 < \psi < \pi$)	Second-order system response to a step input ($\zeta < 1$)
23a.	$\frac{A}{s^2(\tau_1 s + 1)(\tau_2 s + 1)}$	$A \left(t - \tau_1 - \tau_2 - \frac{\tau_2^2 e^{-\nu_1 t} - \tau_1^2 e^{-\nu_2 t}}{\tau_1 - \tau_2} \right)$	Second-order system response to a ramp input ($\zeta > 1$)
23b.	$\frac{A}{s^2(s + a)(s + b)}$	$\frac{A}{ab} \left[t - \frac{a+b}{ab} - \frac{(b/a)e^{-bt} - (a/b)e^{-at}}{b-a} \right]$	
24a.	$\frac{A}{s^2(ts + 1)^2}$	$A[t - 2\tau + (t + 2\tau)e^{-\nu t}]$	Second-order system response to a ramp input ($\zeta = 1$)
24b.	$\frac{A}{s^2(s + a)^2}$	$\frac{A}{a^2} \left[t - \frac{2}{a} + \left(t + \frac{2}{a} \right) e^{-\nu t} \right]$	
25.	$\frac{A\omega_n^2}{s^2(s^2 + 2\zeta\omega_n s + \omega_n^2)}$	$A \left[t - \frac{2\zeta}{\omega_n} + \frac{e^{-\zeta\omega_n t}}{\omega_n \sqrt{1 - \zeta^2}} \sin(\omega_n \sqrt{1 - \zeta^2} t - \psi) \right]$ where $\psi = 2 \tan^{-1} \frac{\sqrt{1 - \zeta^2}}{-\zeta}$ ($0 < \psi < \pi$)	Second-order system response to a ramp input ($\zeta < 1$)

Source: Floyd E. Nixon, *Handbook of Laplace Transformation: Fundamentals, Applications, Tables and Examples*, 21e, © 1965, Referenced and adapted by permission of Prentice-Hall, Inc., Englewood Cliffs, New Jersey.

Transform Operations

$$\begin{aligned} f'(t) & \quad sF(s) - f(0) \\ \int_0^t f(t) dt & \quad \frac{F(s)}{s} \end{aligned}$$

UN KNOWN

Ψ	R	C	L
$i(t)$	$\frac{v(t)}{R}$	$C \cdot \frac{dv(t)}{dt}$	$\frac{1}{L} \int_0^t v(t) dt + I_o$
$v(t)$	$R \cdot i(t)$	$\frac{1}{C} \int_0^t i(t) dt + V_o$	$L \cdot \frac{di(t)}{dt}$