

Maths for Informatics: 4b Geomaty  
Revision Notes  
Ver 0.1

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## 1 Introduction

This document is a set of revision notes for the Geomaty for Informatics course at the Univerisy of Edinburgh.

## 2 Mapping

### 2.1 Matrix

If a matrix is orthoginal in  $\mathbb{R}^3$  on can show that  $MM^T = I$  then:

**If  $\det(m) = 1$**

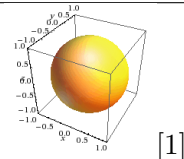
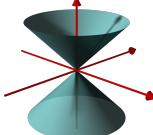
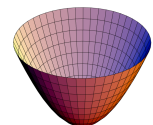
This ia a rotation around some line  $L \in \mathbb{R}^3$  that passes through  $0(0,0,0)$  at angle  $\alpha$ .

If you find the *Eigan Vector* that is a line parralles to  $L$ , set it to  $(0,0,0)$  and we have the line.

**If  $\det(m) = -1$**

This is a reflection in a plane.

## 3 Shapes

Example	Name	Visual Representation
$x^2 + y^2 + z^2 = 1$	Sphere	
$x^2 + y^2 = z^2$	Conic	
$x^2 + y^2 = z$	Paraboloid	

### 3.1 Types

**Ellipse**

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

**Hyperbola**

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

**Parabola**

$$y^2 = 4ax$$

**Other**

Union of two line	
Line	Shortest distance between two points
Point	A zero dimensional object
Empty	Nothing

$$\left| \begin{array}{l} y = Mx + c \\ (x, y) \\ \{\} \end{array} \right.$$
**3.2 Generalisation**

$$Ax^2 + Bxy^2 + Cy^2 + Dx^2 + F = 0$$

or

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} A & \frac{B}{2} \\ \frac{B}{2} & C \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} D \\ E \end{bmatrix} + F = 0$$

**3.3 Identification**

$$N = \begin{bmatrix} A & \frac{B}{2} & \frac{D}{2} \\ \frac{B}{2} & C & \frac{E}{2} \\ \frac{D}{2} & \frac{E}{2} & F \end{bmatrix} M = \begin{bmatrix} A & \frac{B}{2} \\ \frac{B}{2} & C \end{bmatrix}$$

**Ellipse**

$$4AC - B^2 > 0 \text{ and } \det(N)(A + C) < 0$$

**Hyperbola**

$$4AC - B^2 < 0 \text{ and } \det(N) \neq 0$$

**Parabola**

$$4AC - B^2 = 0 \text{ and } \det(N) \neq 0$$

## 4 Examples

### 4.1 Example 1

Note: Simmilar to assignment

#### Question

$$S : x^2 + y^2 - z^2 = 1$$

$$S \subset \mathbb{R}^3$$

If you are given a point and asked to find all lines that pass through it

Hint: There will allways be two

#### Answer

$$pt(1, 1, 1)$$

$$P \leq L \leq S \subseteq \mathbb{R}^3$$

$$L = (1 + a\alpha, 1 + b\alpha, 1 + c\alpha)$$

Inserted into questions formula

$$(1 + a\alpha)^2 + (1 + b\alpha)^2 + (1 + c\alpha)^2 = 1 \forall \alpha$$

Expand to

$$1 + \dots = 1$$

seperate variables

$$\alpha(2a + 2b - 2c) + \alpha^2(a^2 + b^2 - c^2) = 0$$

Divide by  $\alpha$

$$(2a + 2b - 2c) = 0 \text{ or } (a^2 + b^2 - c^2) = 0$$

let  $a = 1$  (as 1 is modulo all numbers)

$$(1, b, c)$$

$$1 + b^2 - c^2 = 0 \text{ and } 1 + b - c = 0$$

$$b = 0 \text{ and } c = 1$$

Form to a equation

(are intial point and are new derived point)

$$\underline{(1, 1, 1) + \alpha(1, 0, 1)}$$

## 5 Matrix and Vector

### 5.1 Matrix

TODO

### 5.2 Vector

TODO

### 5.3 Mix

**Orthogonal**  $a \cdot b = 1$

**Parrallel**  $a \cdot b = 0$

**Cross Product**  $\begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$

**Dot Product**  $(a_1xb_1) + (a_2xb_2) + (a_3xb_3)$

**Angle**  $\cos(\theta) = \frac{a \cdot b}{|a||b|}$

**Determinate**  $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

**Determinate**  $\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = \begin{matrix} a & b & c & \nearrow \\ d & e & f & \nearrow \\ g & h & i & \nearrow \\ a & b & c & \searrow \\ d & e & f & \searrow \\ g & h & i & \searrow \end{matrix} \begin{matrix} Y \\ X - Y \\ X \end{matrix}$

## References

- [1] "Sphere Graphic", Author="Wolfram—Alpha", Publisher"Wolfram Alpha LLC", Accessed="26-April-2011", Year="2011", "<http://www.wolframalpha.com/input/?i=x^2%2By^2%2Bz^2%3D1>"