

TEAM



Dr.-Ing. Sören Kerner (39), Head of Automation and Embedded Systems
Profession: Computer Science, Electrical Engineering, Multi-Agent Systems, ROS
Role: Robotic Expert, Project Management



Dennis Lünsch (30), Research Assistant
Profession: Computer Science, Navigation, ROS, Interfaces
Role: Software Development



Christian Blesing (32), Research Assistant
Profession: Computer Science, Multi-Agent System, 2D/3D Vision Systems
Role: Software Development

MOTIVATION

We are convinced that only agent-controlled cellular transport systems can provide the flexibility needed for the future of facility logistics



MARKET

PROBLEM TO SOLVE

flexible, self-organizing, scalable
and cost efficient facility logistics
automation



(AGV) MARKET SIZE

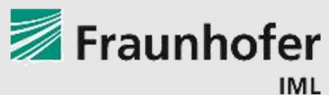
1.4 Billion Euros in 2018 with a
growing rate of 9.8%

POTENTIAL CUSTOMERS

Automotive, Manufacturing,
Retail, Contract Logistics, ...

BUISINESS MODEL

customized control system
solution or sell/rent full systems
(Automation as a Service)



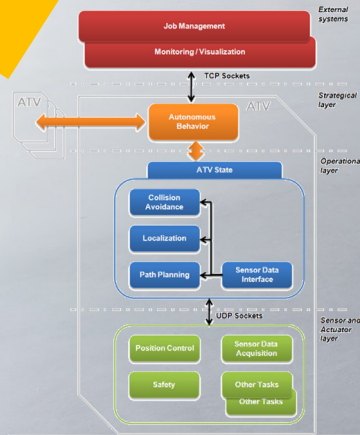
TECHNOLOGY

2

Multi sensor concept (inertial and safety laser range finder)

1

Hybrid system consists of bin storage and multimodal vehicle (agv)



3

Full system architecture multi agent system

UNFAIR ADVANTAGE

IP and background of **15** years experience in multi agent systems

Data of 5 years Living Lab autonomous swarm intelligence

25 years experience with AGVs

several million Euros R&D effort already invested

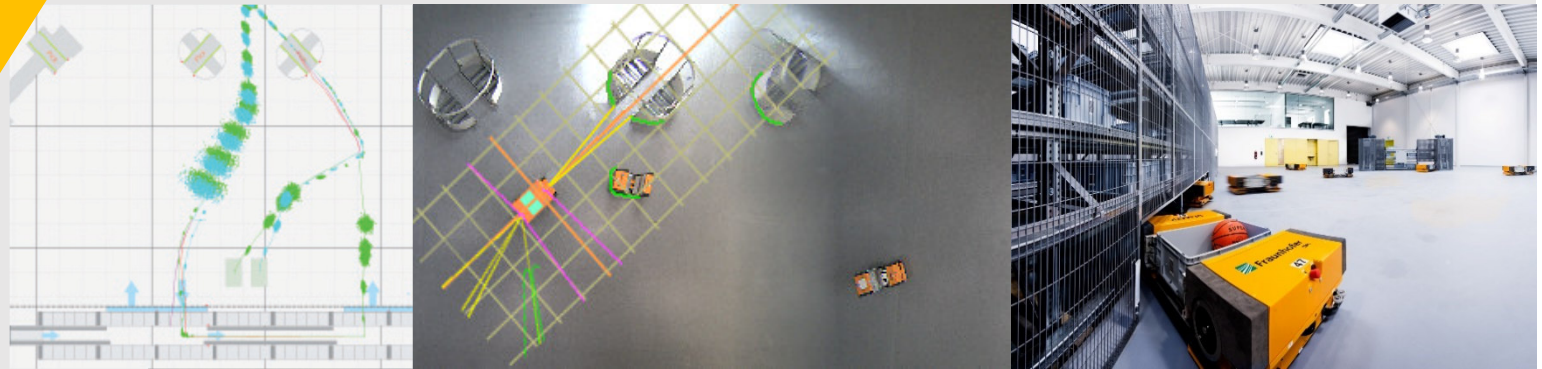
4

Autonomous behavior and swarm intelligence

5

Layout-flexible solution through free navigation

OFFER



WE OFFER

Technical expertise in the field of multi agent systems, decentralized control and autonomous agv

WE ARE LOOKING FOR

Full founding team
Economical expertise
Managing director and investors

THE INCENTIVE

Breakthrough technology with an enormous market potential
Cutting edge solution to change the facility logistics

THE EXPECTATIONS

Entrepreneurial experience and market access
Interested in industrializing of highly complex technical solutions