



AI VIET NAM

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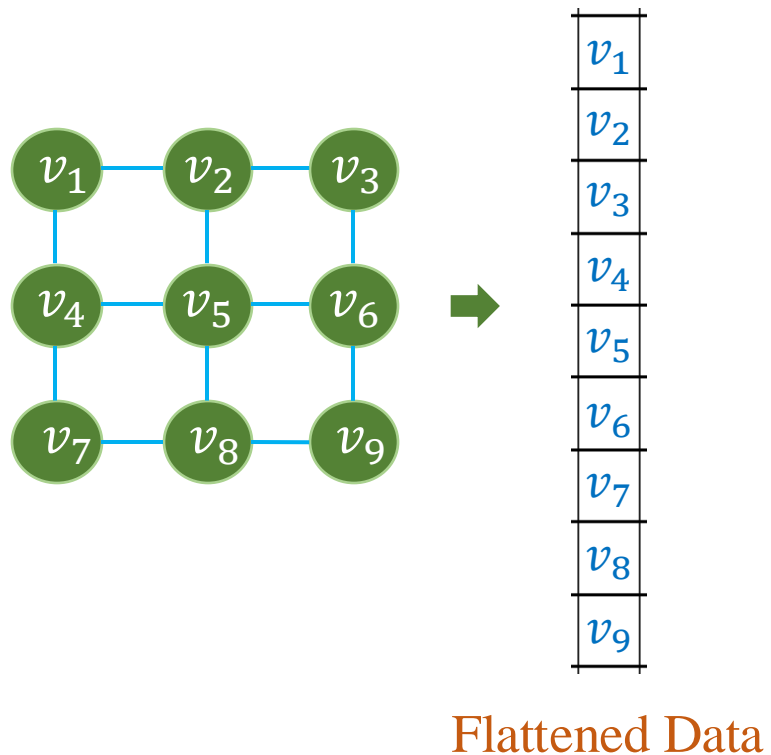
# From MLP to CNN

## Introduction to CNN

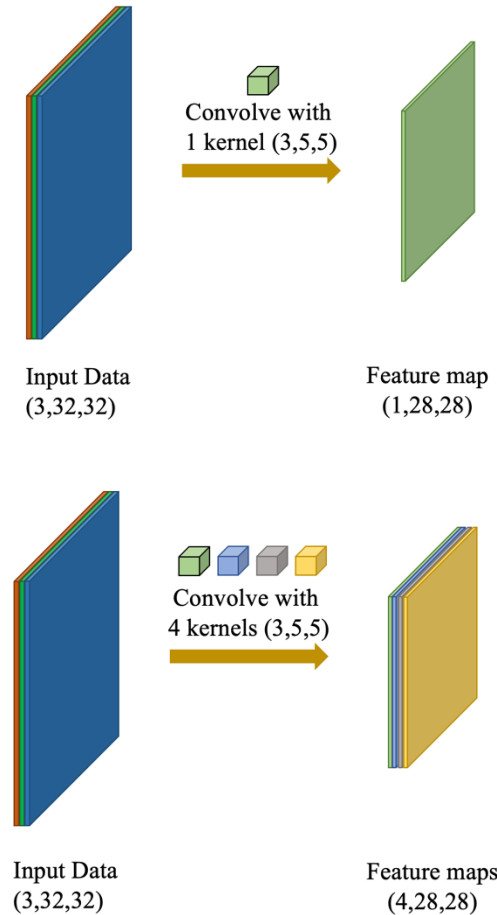
Quang-Vinh Dinh  
Ph.D. in Computer Science

# Objectives

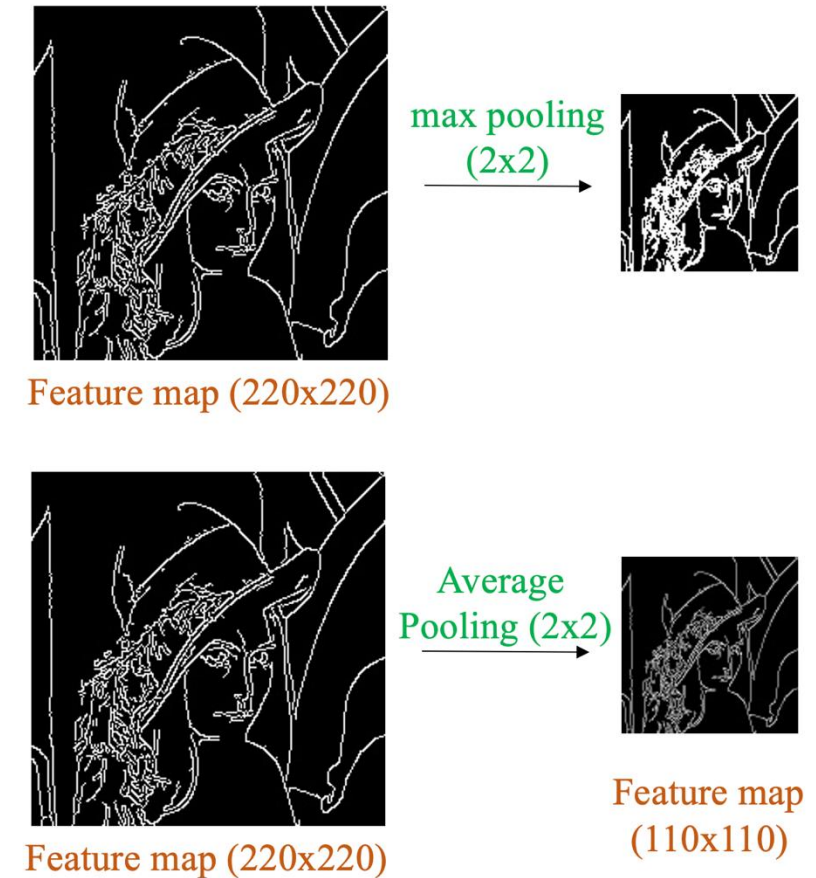
## MLP Limitations



## Convolutional Layer



## Standard CNNs



# Outline

## SECTION 1

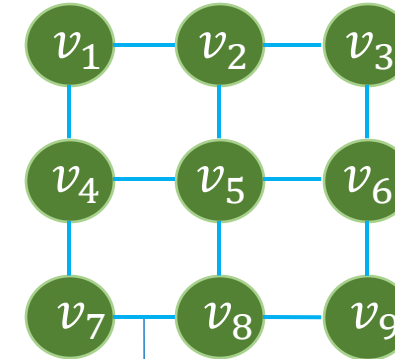
### MLP Limitations

## SECTION 2

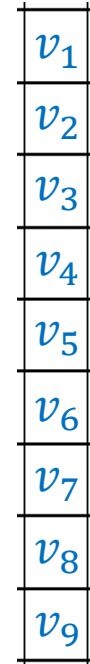
### Convolutional Layer

## SECTION 3

### Standard CNNs



Spatial Information



Flattened Data

**Fashion-MNIST dataset**

Grayscale images

Resolution=28x28

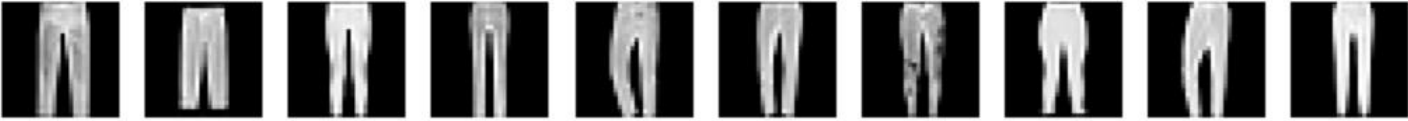
Training set: 60000 samples

Testing set: 10000 samples

T-shirt



Trouser



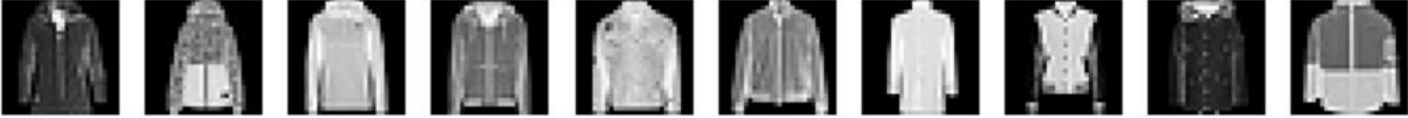
Pullover



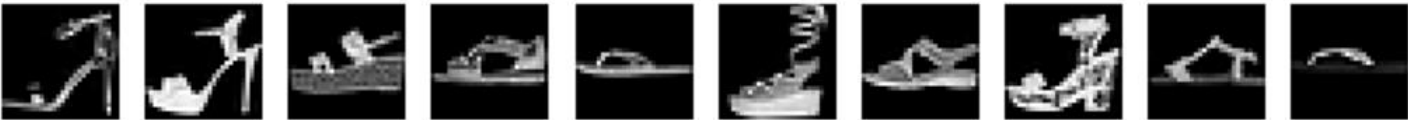
Dress



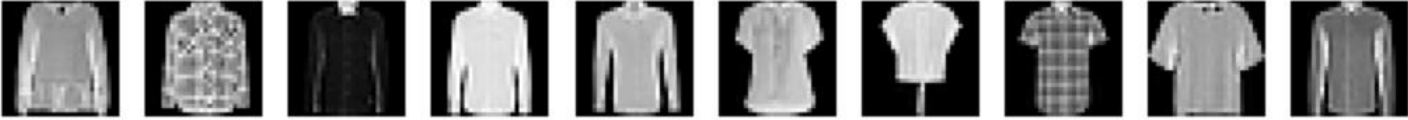
Coat



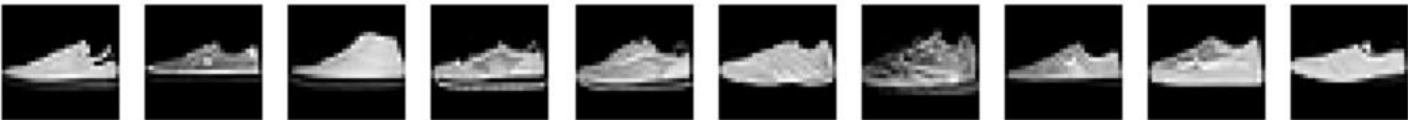
Sandal



Shirt



Sneaker



Bag

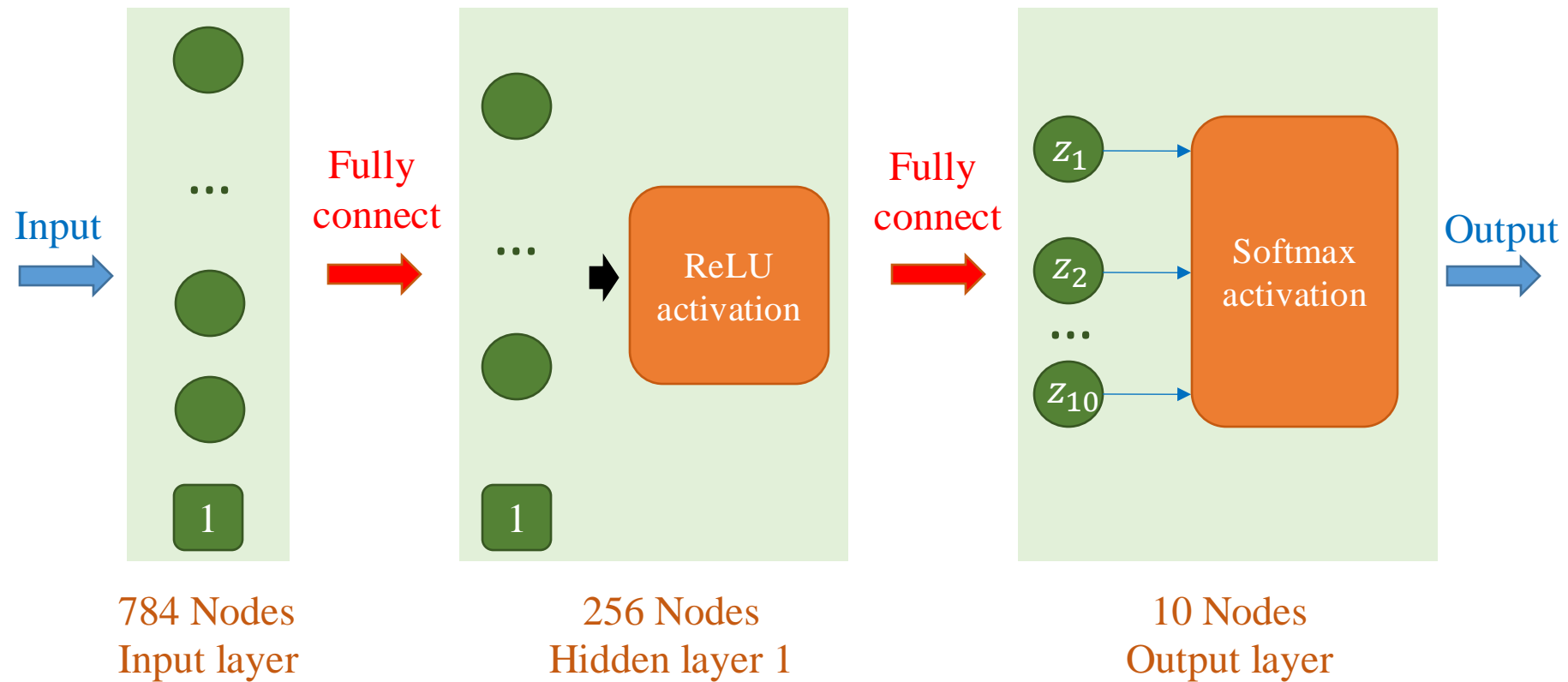


Ankle  
Boot



## ❖ ReLU, He and Adam

Case 1



## ❖ ReLU, He and Adam

```
# model
model = nn.Sequential(
    nn.Flatten(),
    nn.Linear(784, 256),
    nn.ReLU(),
    nn.Linear(256, 10)
)
```

```
# Initialize the weights
for layer in model:
    if isinstance(layer, nn.Linear):
        init.kaiming_uniform_(layer.weight,
                               nonlinearity='relu')
        if layer.bias is not None:
            layer.bias.data.fill_(0)
```

```
# loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(),
                        lr=0.001)
```

```
# Load CFashionMNIST dataset
transform = Compose([transforms.ToTensor(),
                     transforms.Normalize((0.5,),
                                         (0.5,))])

trainset = FashionMNIST(root='data',
                        train=True,
                        download=True,
                        transform=transform)

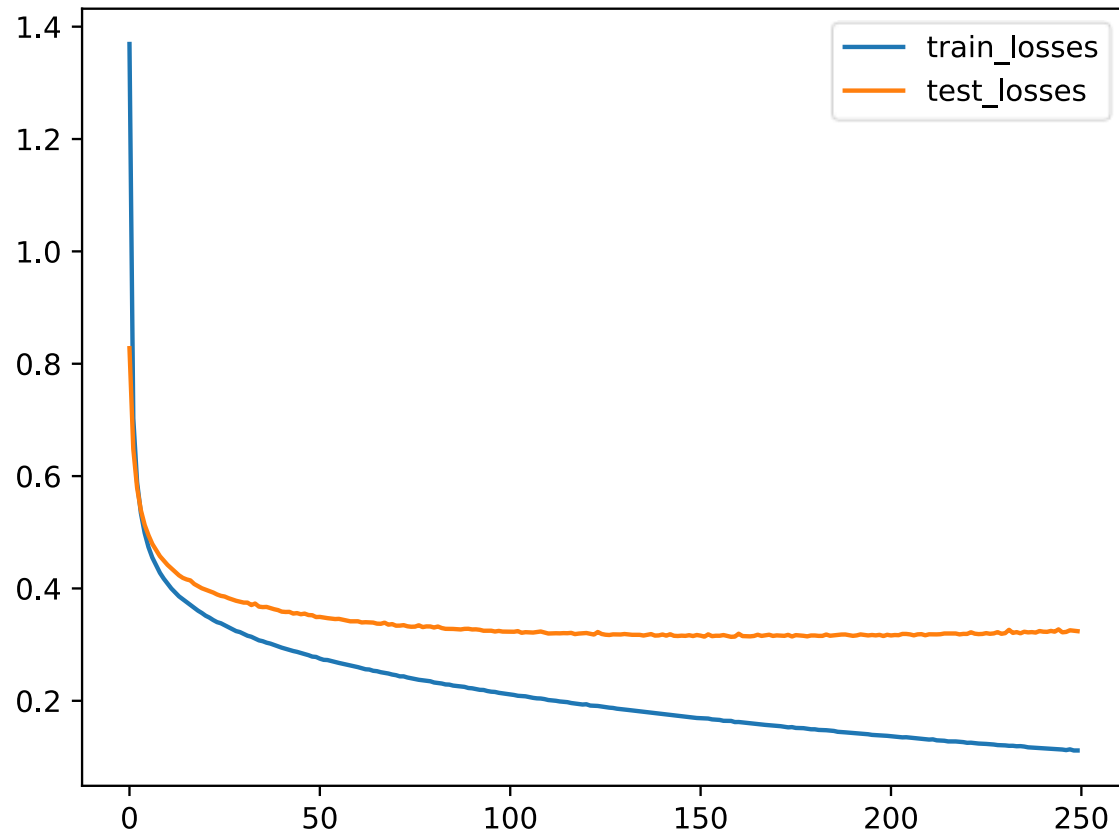
trainloader = DataLoader(trainset,
                        batch_size=1024,
                        num_workers=10,
                        shuffle=True,
                        drop_last=True)

testset = FashionMNIST(root='data',
                      train=False,
                      download=True,
                      transform=transform)

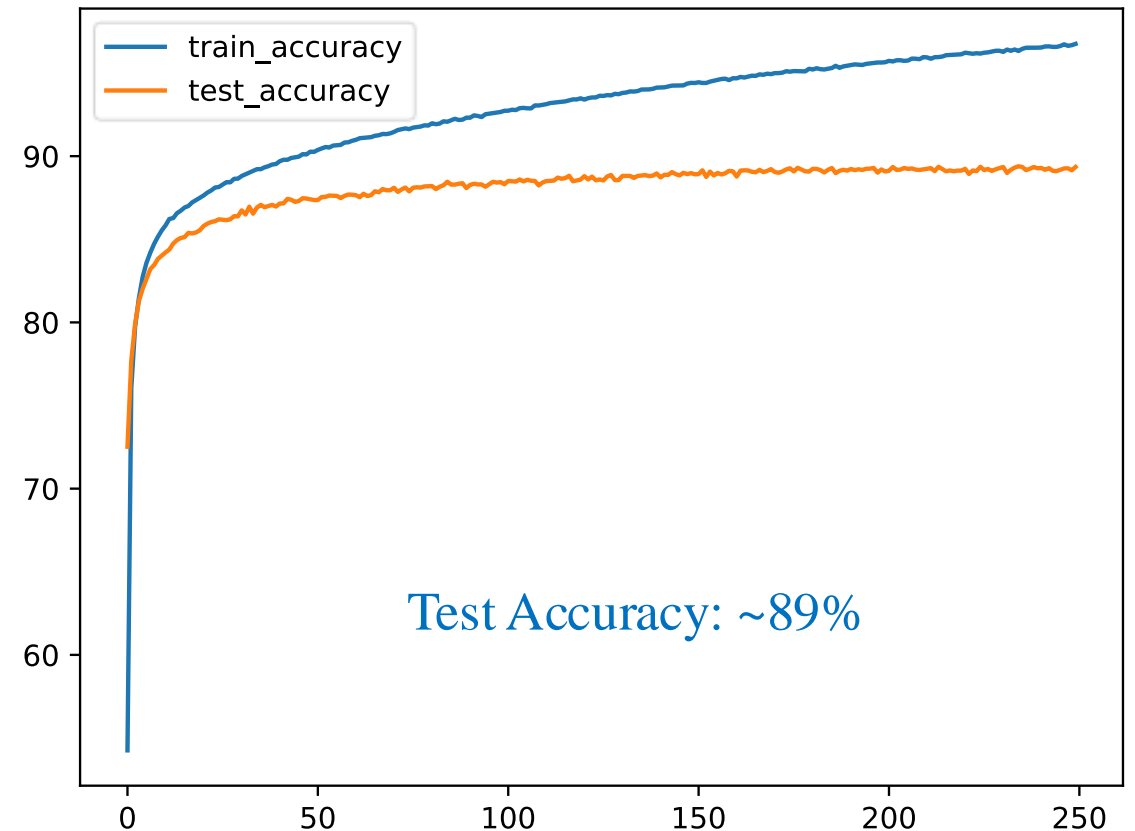
testloader = DataLoader(testset,
                      batch_size=1024,
                      num_workers=10,
                      shuffle=False)
```

## ❖ ReLU, He and Adam

Case 1



Adam with learning rate of  $1e-4$



Test Accuracy: ~89%

Perform reasonably



## Cifar-10 dataset

Color images

Resolution=32x32

Training set: 50000 samples

Testing set: 10000 samples

airplane



automobile



bird



cat



deer



dog



frog



horse



ship



truck

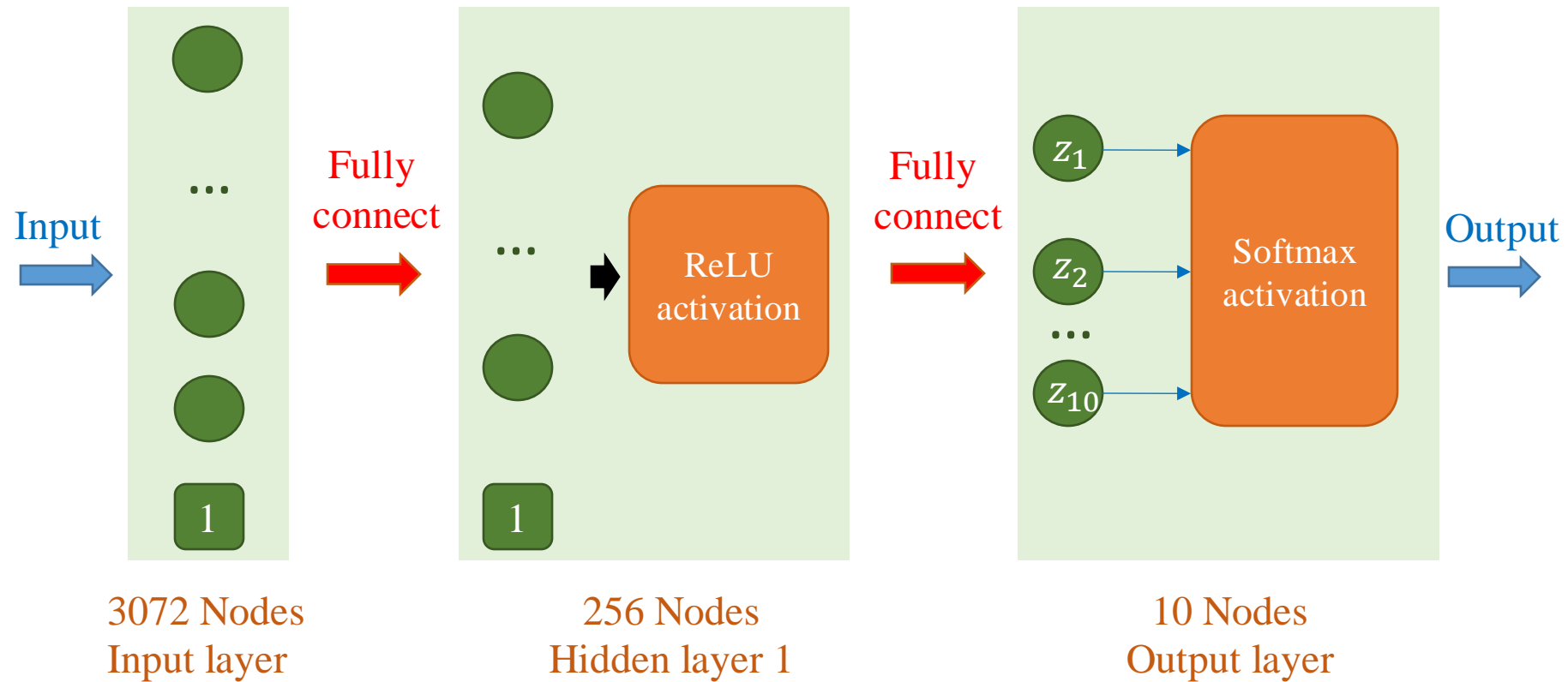




# MLP for Cifar-10

## ❖ ReLU, He and Adam

Case 2



## ❖ ReLU, He and Adam

```
# model
model = nn.Sequential(
    nn.Flatten(),
    nn.Linear(32*32*3, 256),
    nn.ReLU(),
    nn.Linear(256, 10)
)
```

```
# Initialize the weights
for layer in model:
    if isinstance(layer, nn.Linear):
        init.kaiming_uniform_(layer.weight,
                               nonlinearity='relu')
        if layer.bias is not None:
            layer.bias.data.fill_(0)
```

```
# Loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(),
                        lr=0.001)
```

```
# Load CIFAR10 dataset
transform = Compose([ToTensor(),
                     Normalize((0.5,0.5, 0.5),
                               (0.5,0.5, 0.5))])

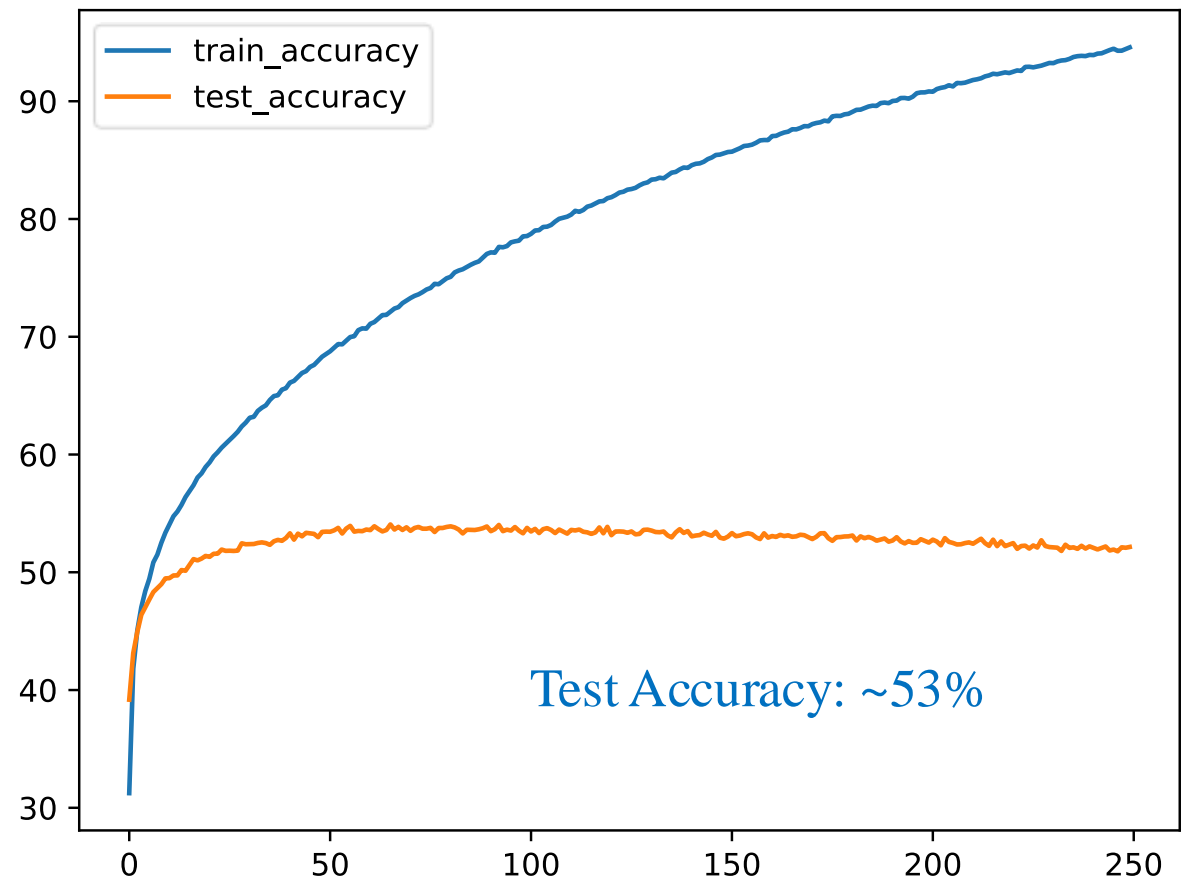
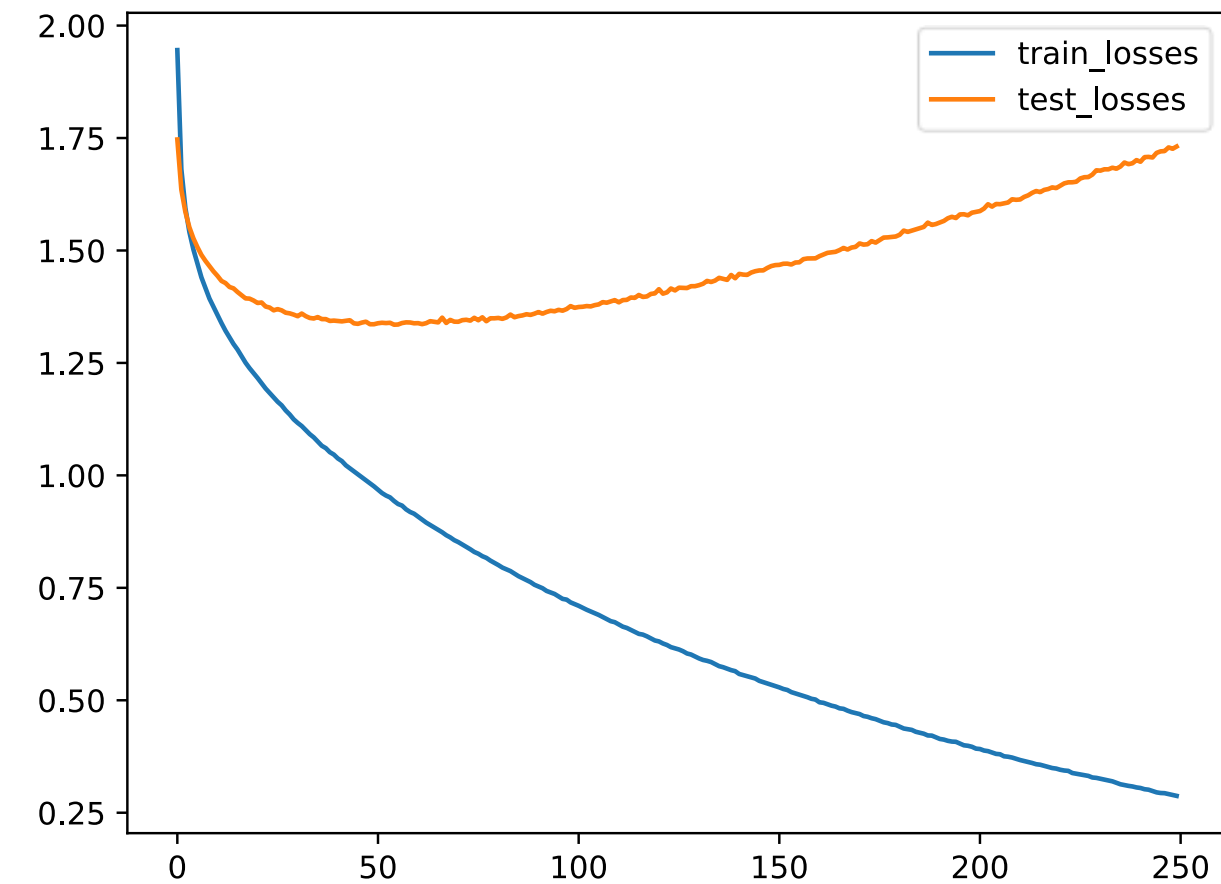
trainset = CIFAR10(root='data',
                   train=True,
                   download=True,
                   transform=transform)
trainloader = DataLoader(trainset,
                        batch_size=1024,
                        num_workers=10,
                        shuffle=True,
                        drop_last=True)

testset = CIFAR10(root='data',
                  train=False,
                  download=True,
                  transform=transform)
testloader = DataLoader(testset,
                       batch_size=1024,
                       num_workers=10,
                       shuffle=False)
```

# MLP for Cifar-10

## ❖ ReLU, He and Adam

Case 2

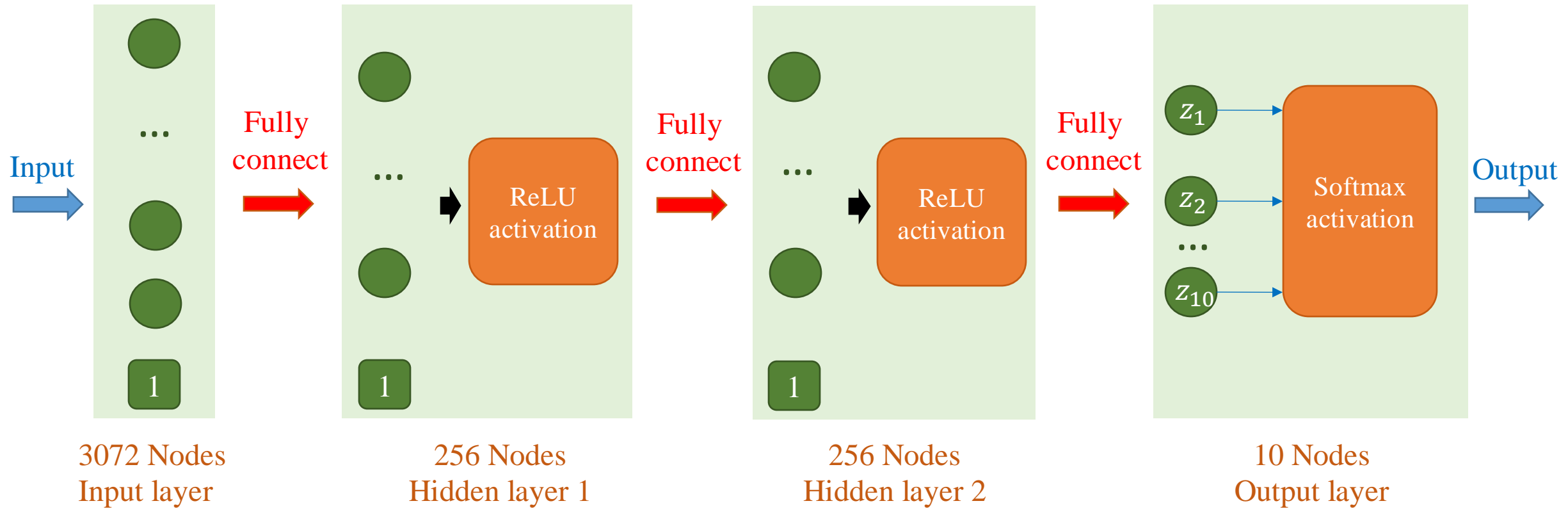


Perform disappointedly

# MLP for Cifar-10

## ❖ ReLU, He and Adam: add more layers

Case 3



## ❖ ReLU, He and Adam

```
# model
model = nn.Sequential(
    nn.Flatten(),
    nn.Linear(32*32*3, 256),
    nn.ReLU(),
    nn.Linear(256, 256),
    nn.ReLU(),
    nn.Linear(256, 10)
)

# Initialize the weights
for layer in model:
    if isinstance(layer, nn.Linear):
        init.kaiming_uniform_(layer.weight,
                               nonlinearity='relu')
        if layer.bias is not None:
            layer.bias.data.fill_(0)

# loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(),
                        lr=0.001)
```

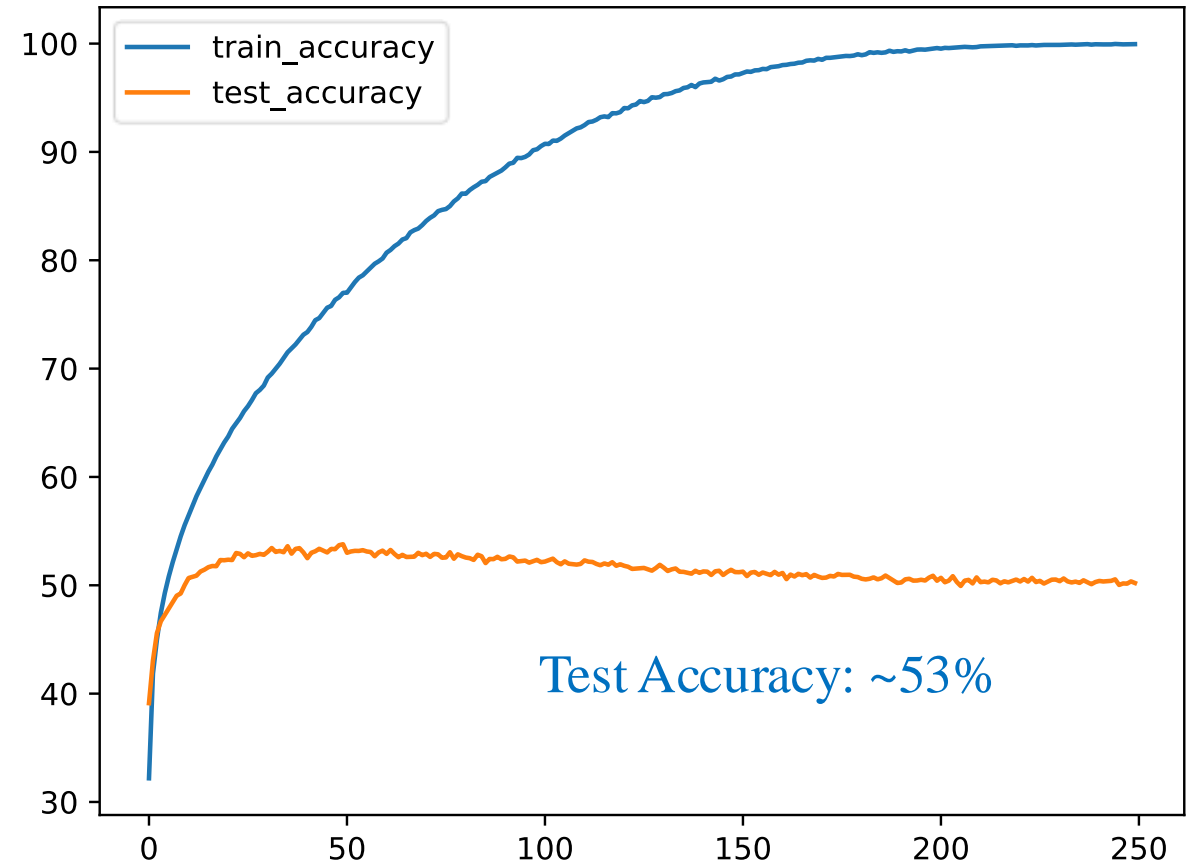
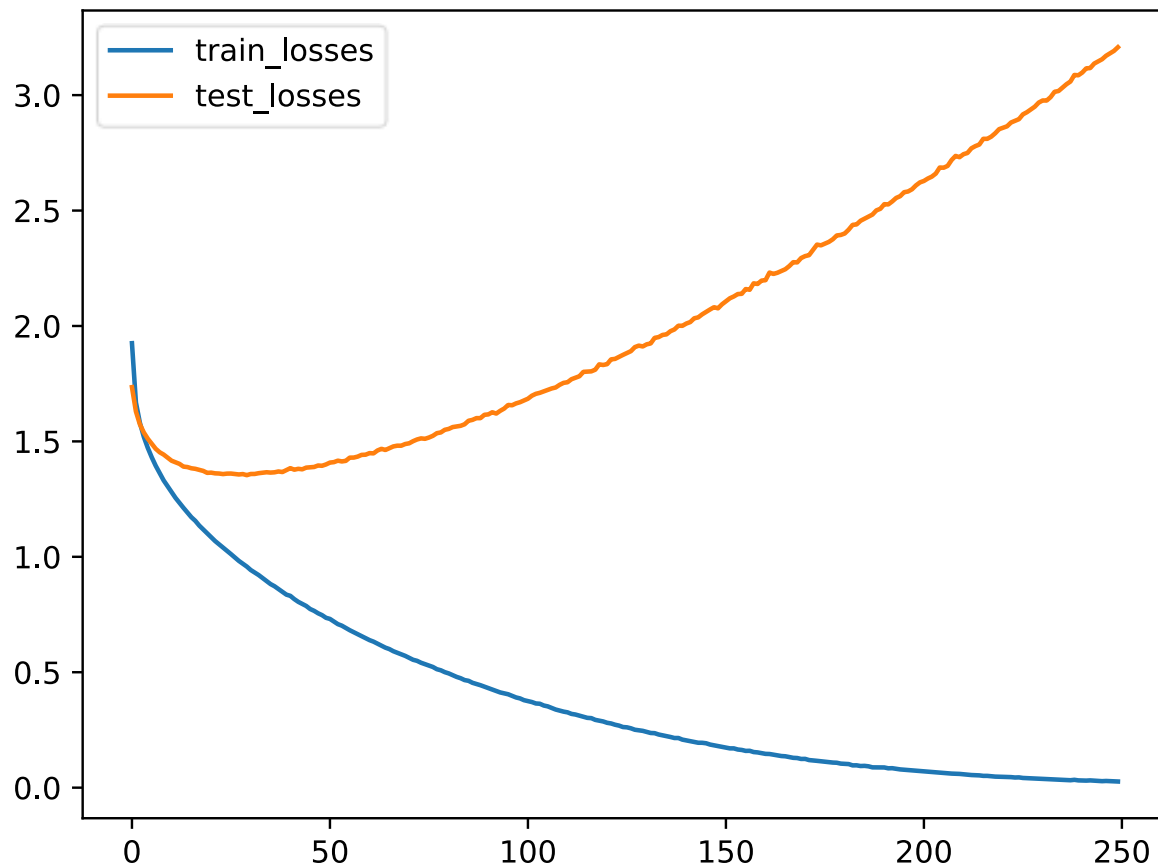
```
# Load CIFAR10 dataset
transform = Compose([ToTensor(),
                      Normalize((0.5,0.5, 0.5),
                                (0.5,0.5, 0.5))])

trainset = CIFAR10(root='data',
                   train=True,
                   download=True,
                   transform=transform)
trainloader = DataLoader(trainset,
                        batch_size=1024,
                        num_workers=10,
                        shuffle=True,
                        drop_last=True)

testset = CIFAR10(root='data',
                  train=False,
                  download=True,
                  transform=transform)
testloader = DataLoader(testset,
                       batch_size=1024,
                       num_workers=10,
                       shuffle=False)
```

## ❖ ReLU, He and Adam

Case 3



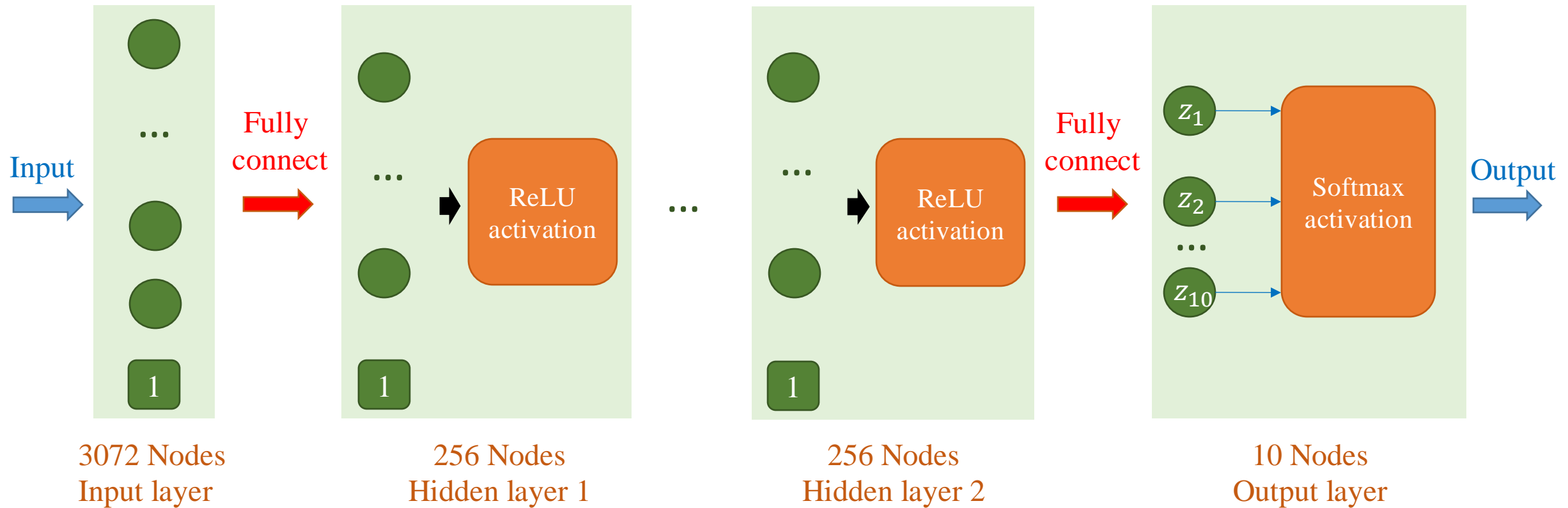
Still Perform poorly



# MLP for Cifar-10

## ❖ ReLU, He and Adam

Case 4



## ❖ ReLU, He and Adam

```
# model
model = nn.Sequential(
    nn.Flatten(), nn.Linear(32*32*3, 256),
    nn.ReLU(), nn.Linear(256, 256),
    nn.ReLU(), nn.Linear(256, 256),
    nn.ReLU(), nn.Linear(256, 10)
)

# Initialize the weights
for layer in model:
    if isinstance(layer, nn.Linear):
        init.kaiming_uniform_(layer.weight,
                               nonlinearity='relu')
        if layer.bias is not None:
            layer.bias.data.fill_(0)

# Loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(),
                        lr=0.001)
```

```
# Load CIFAR10 dataset
transform = Compose([ToTensor(),
                     Normalize((0.5,0.5, 0.5),
                               (0.5,0.5, 0.5))])

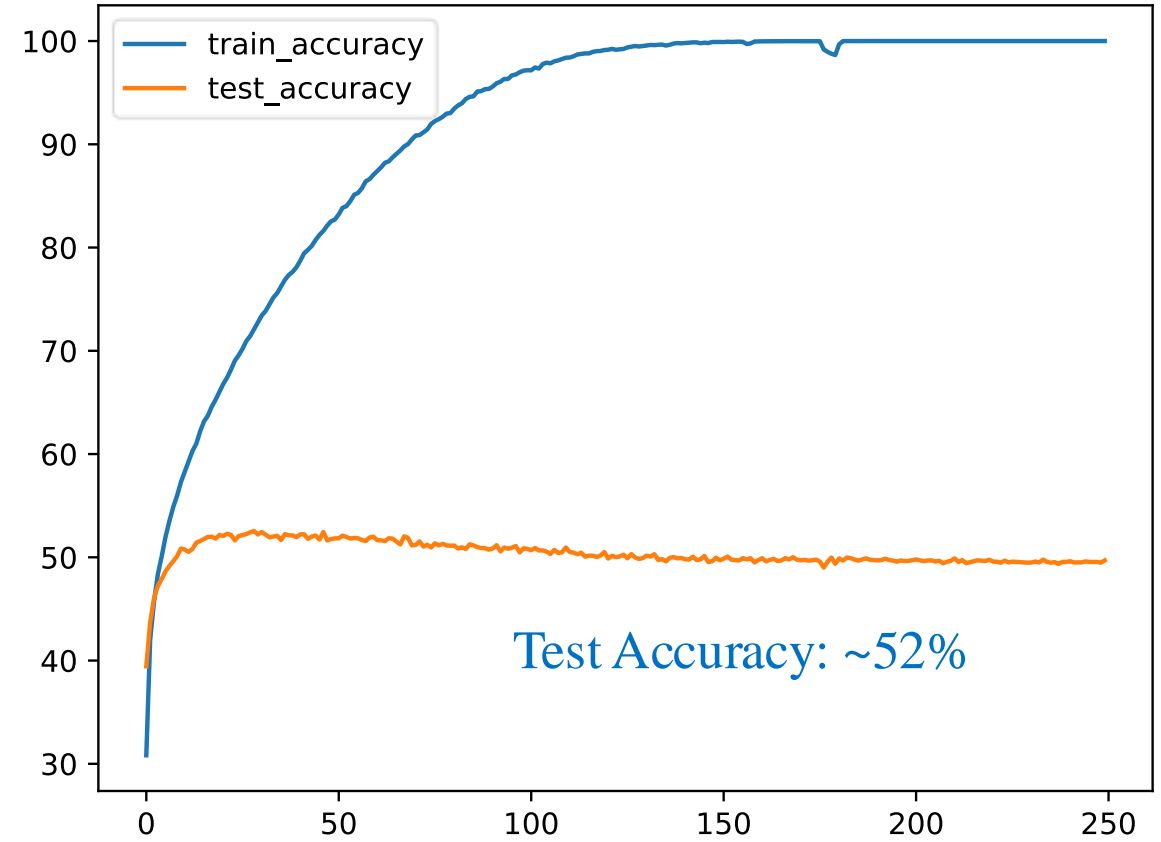
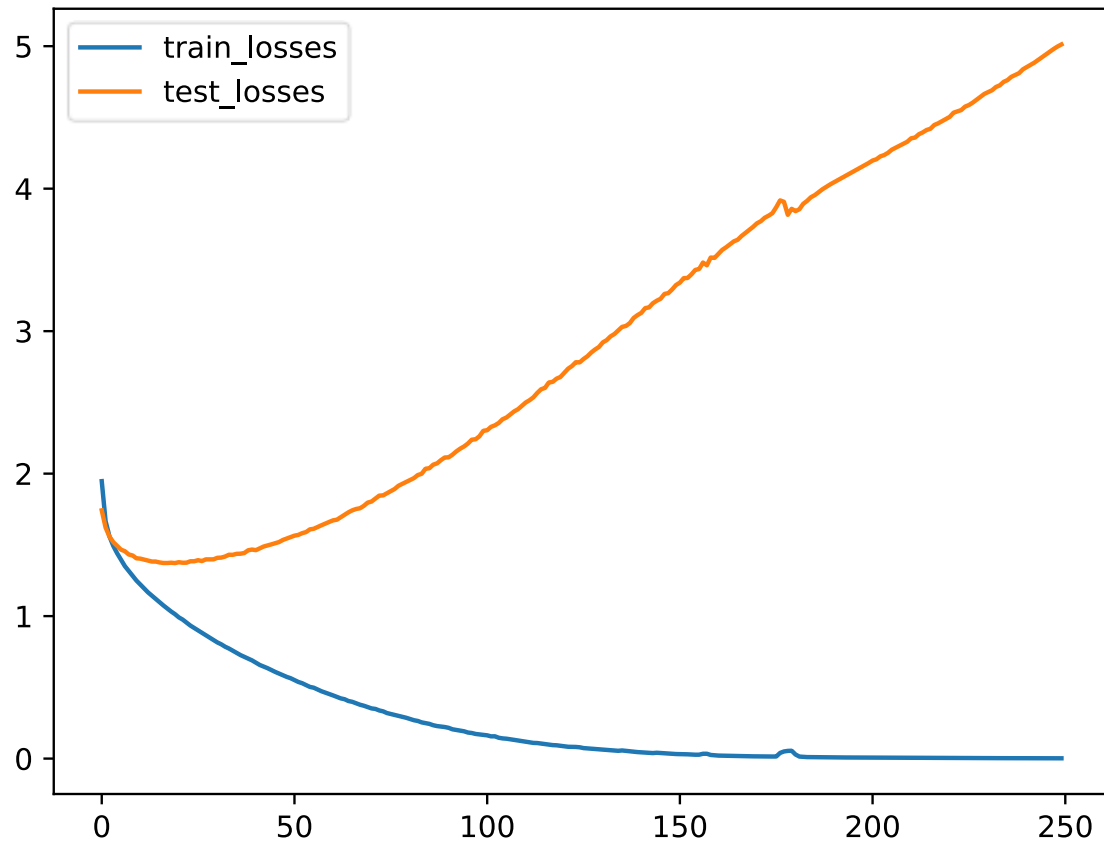
trainset = CIFAR10(root='data',
                   train=True,
                   download=True,
                   transform=transform)
trainloader = DataLoader(trainset,
                        batch_size=1024,
                        num_workers=10,
                        shuffle=True,
                        drop_last=True)

testset = CIFAR10(root='data',
                 train=False,
                 download=True,
                 transform=transform)
testloader = DataLoader(testset,
                      batch_size=1024,
                      num_workers=10,
                      shuffle=False)
```

# MLP for Cifar-10

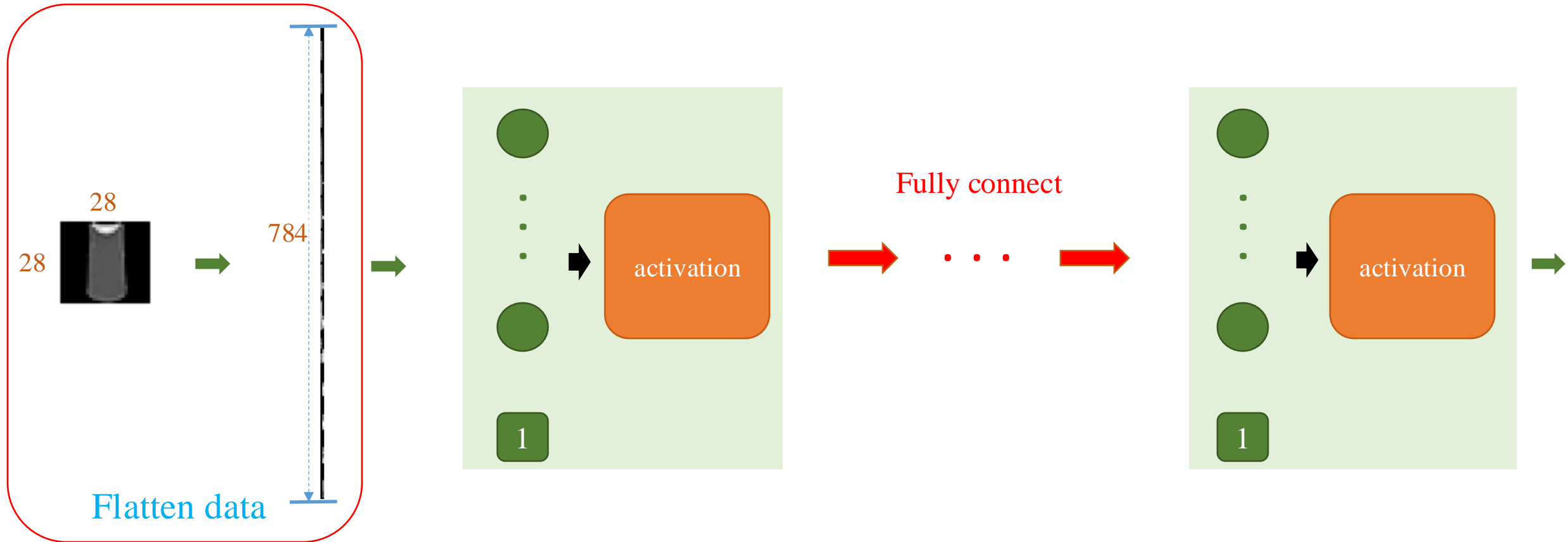
## ❖ ReLU, He and Adam: Using 3 hidden layers

Case 4



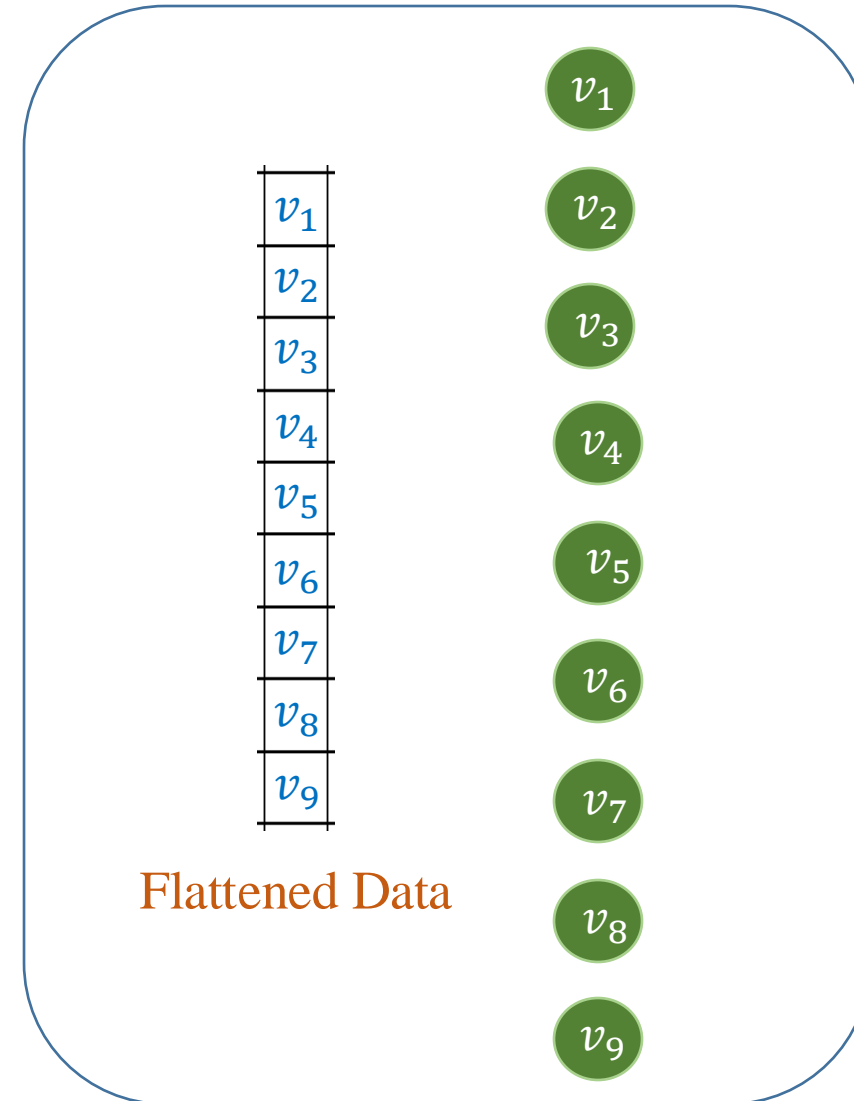
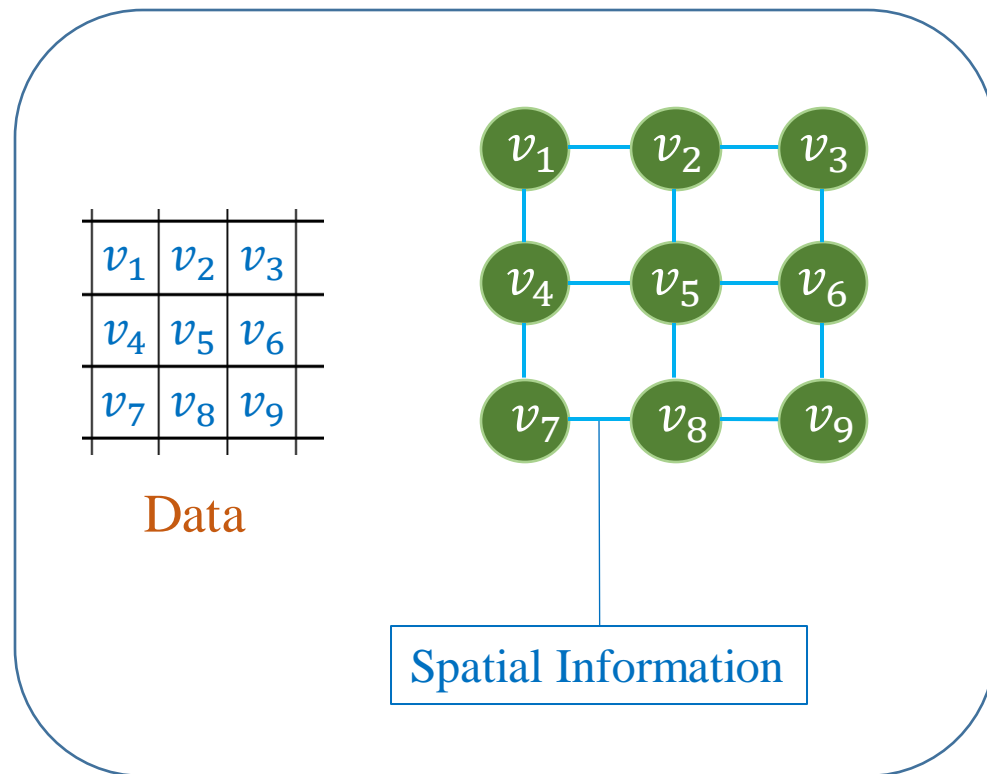
Perform even worse

## ❖ Multi-layer Perceptron



Problem: Remove spatial information of the data  
Inefficiently have a large amount of parameters

## ❖ Problem of flattening data



Remove spatial information of the data

# Outline

## SECTION 1

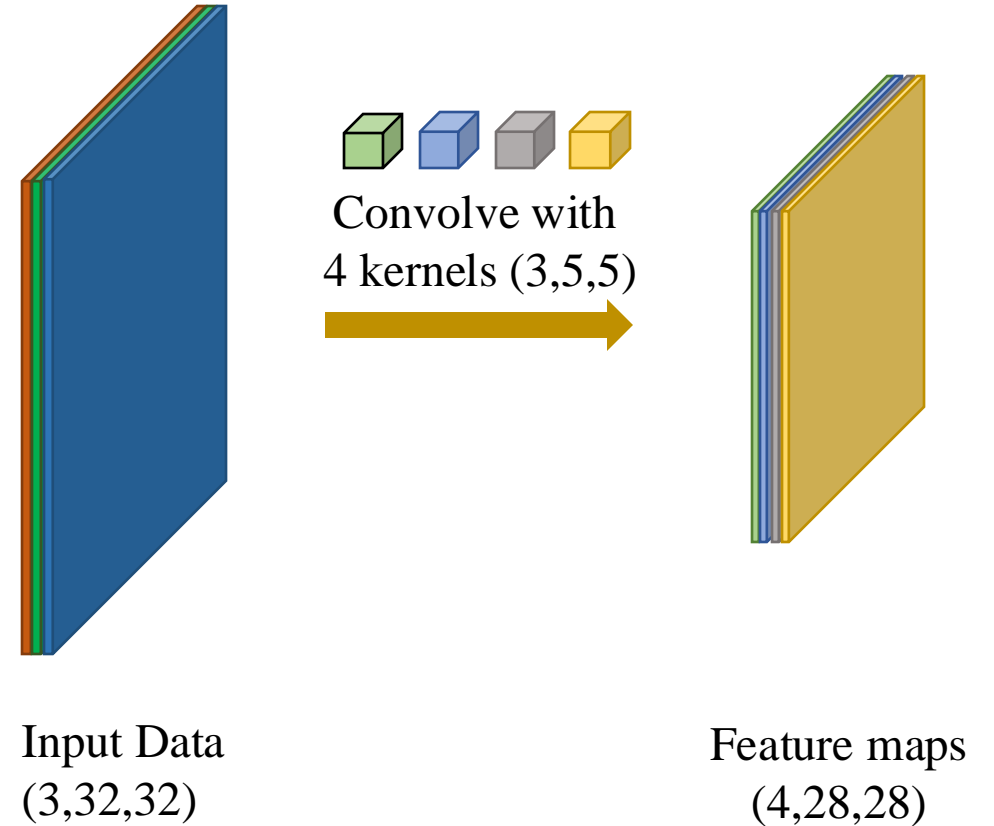
### MLP Limitations

## SECTION 2

### Convolutional Layer

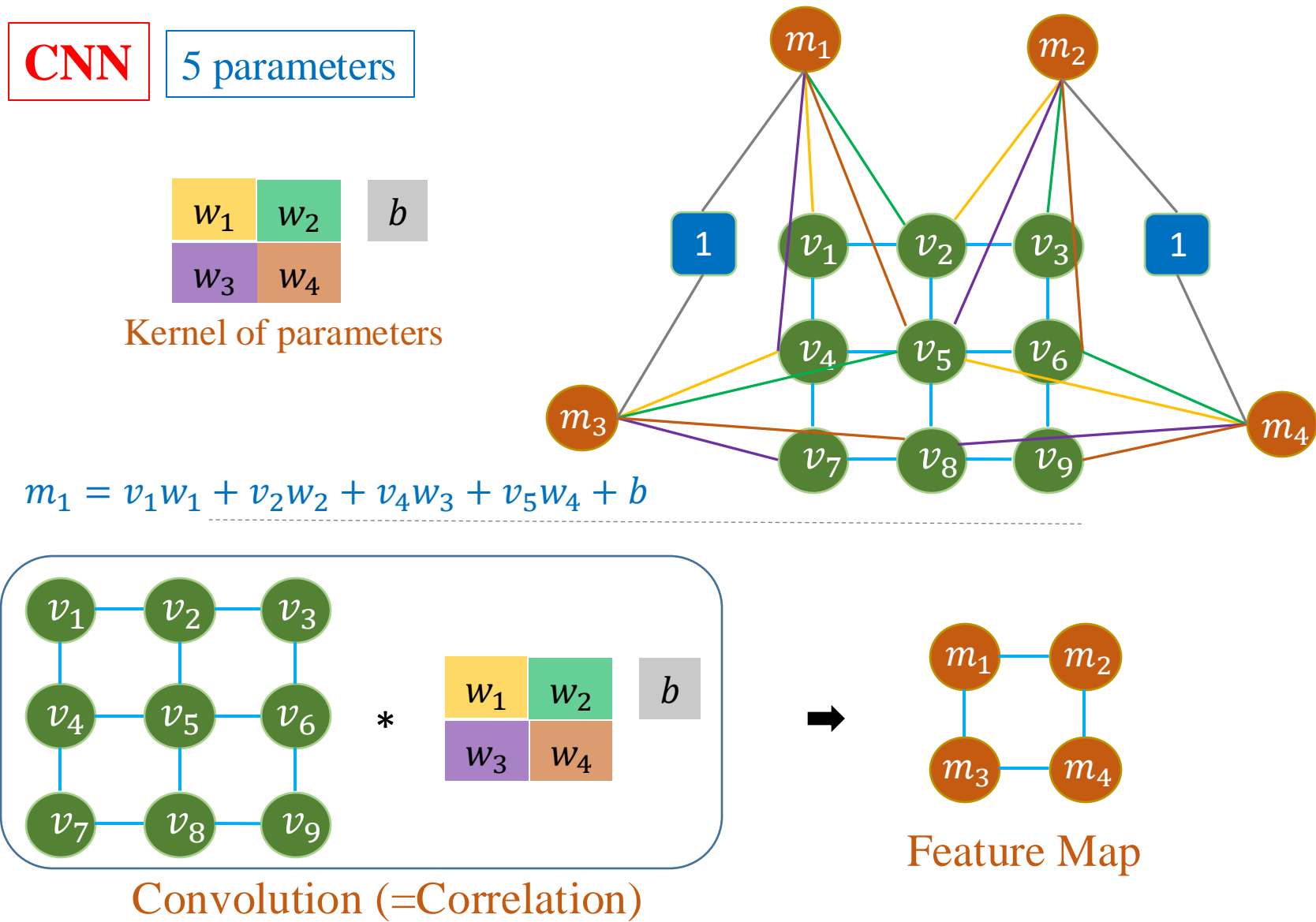
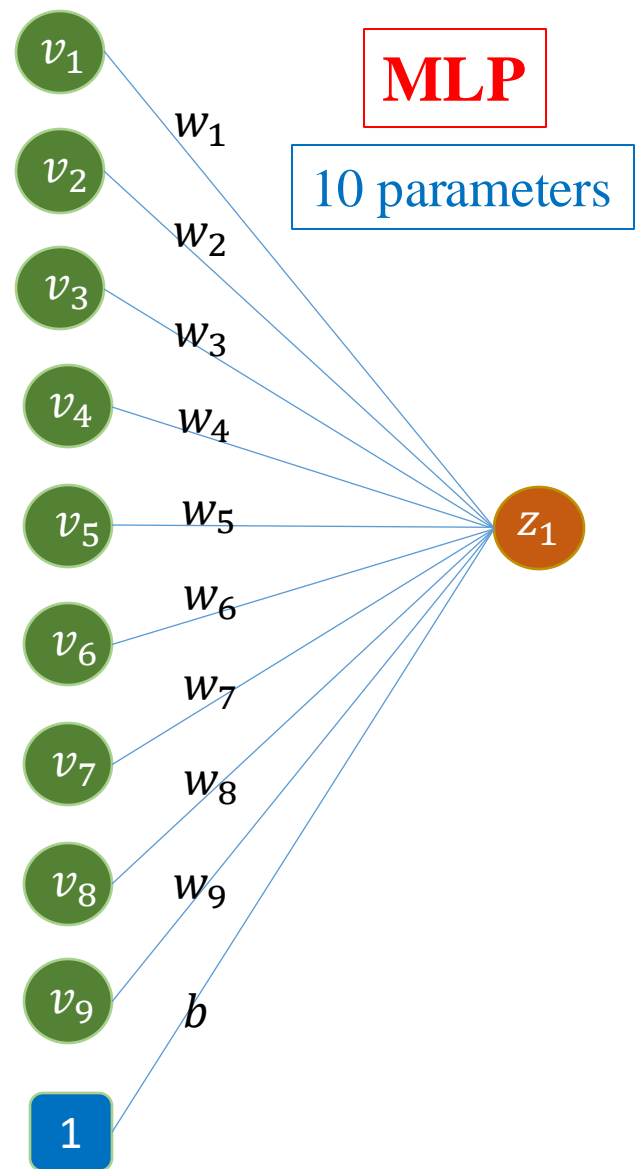
## SECTION 3

### Standard CNNs

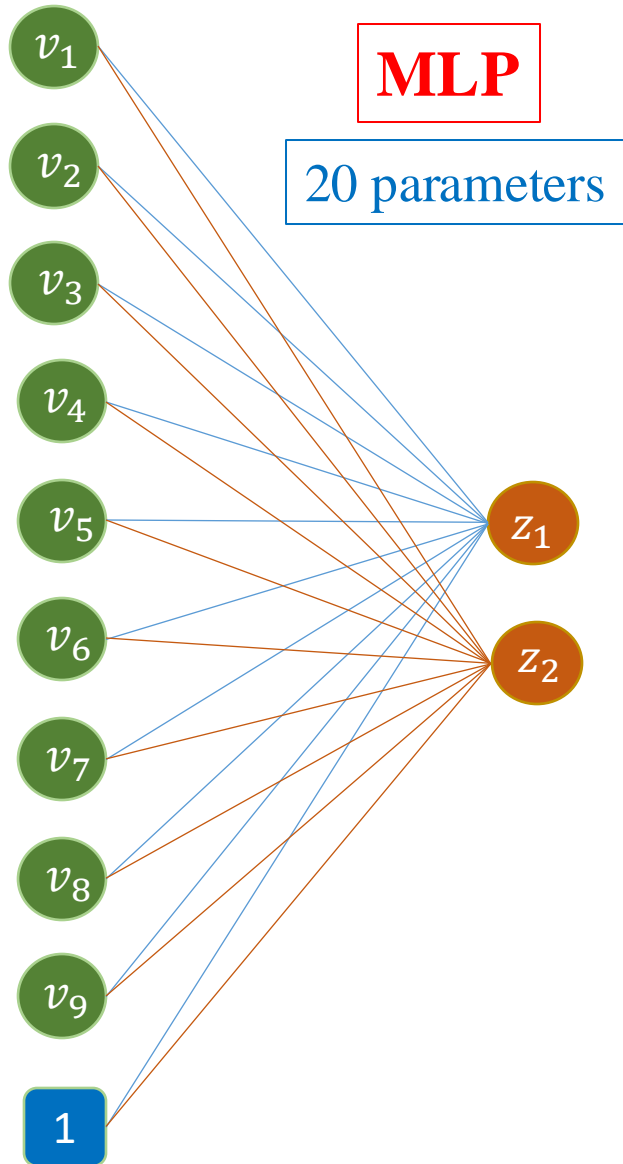




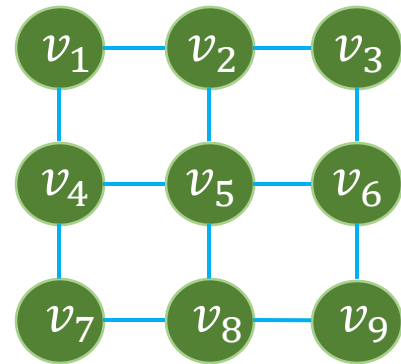
# From MLP to CNN



# From MLP to CNN



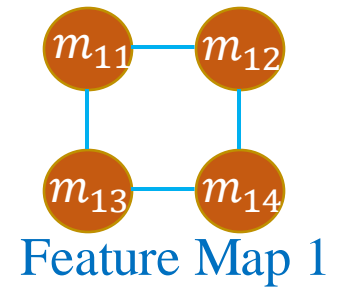
**CNN** 10 parameters



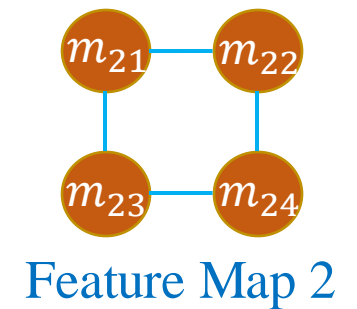
Kernel 1  $\neq$  Kernel 2



Kernel 1



Kernel 2

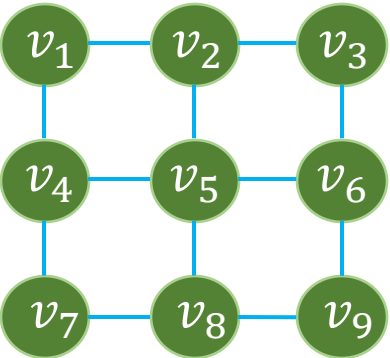


Global vs. Local?

Parameter size?

# From MLP to CNN

## ❖ Understand convolution



Shape=(1,3,3)

(Channel=1, Height=3, Width=3)

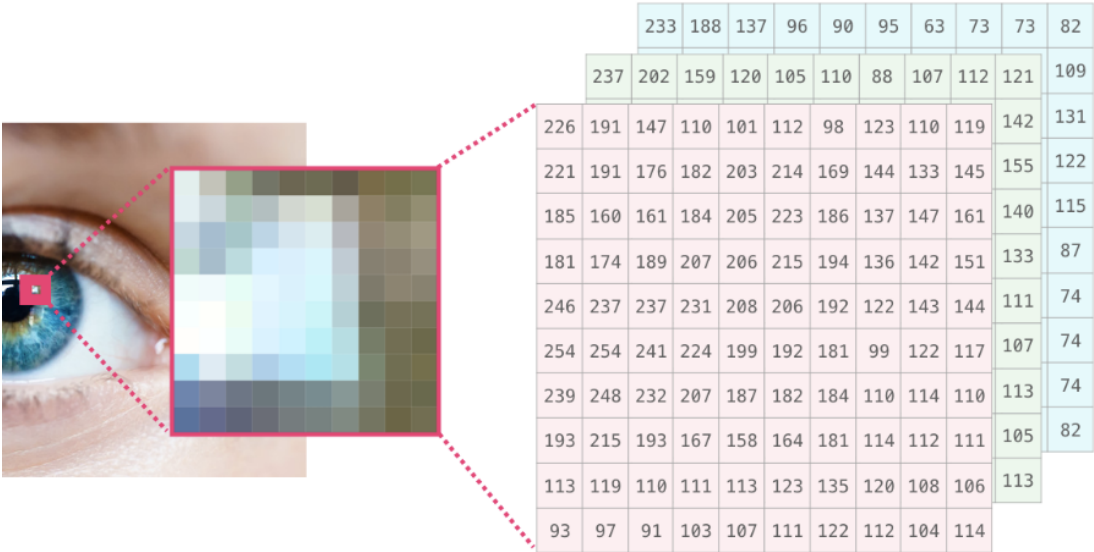
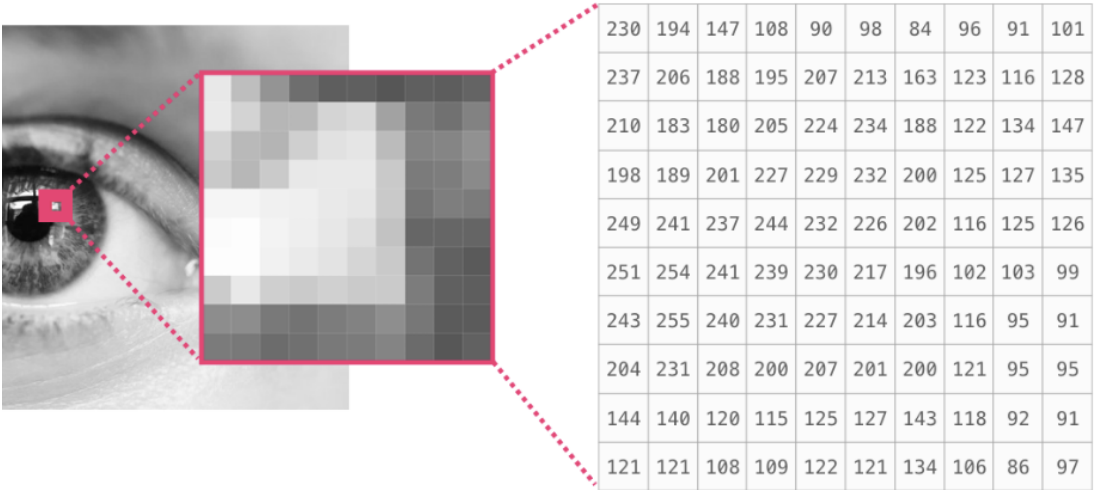
\*



Shape=(1,2,2)

#parameters (+bias) = 5

$b$



#channels of data must = #channels of kernel



# Convolutional Layer

❖ How many cases?

0	0	1	2	2
1	2	2	1	2
0	2	0	2	1
0	1	1	1	0
1	0	0	0	1

Data **D**

0.0	0.1	-0.1
-0.2	0.0	0.1
0.0	0.0	0.1

Kernel **K**

Bias  $b = 0.0$

<table><tr><td>0</td><td>0</td><td>1</td><td>2</td><td>2</td></tr><tr><td>1</td><td>2</td><td>2</td><td>1</td><td>2</td></tr><tr><td>0</td><td>2</td><td>0</td><td>2</td><td>1</td></tr><tr><td>0</td><td>1</td><td>1</td><td>1</td><td>0</td></tr><tr><td>1</td><td>0</td><td>0</td><td>0</td><td>1</td></tr></table>	0	0	1	2	2	1	2	2	1	2	0	2	0	2	1	0	1	1	1	0	1	0	0	0	1	<table><tr><td>0</td><td>0</td><td>1</td><td>2</td><td>2</td></tr><tr><td>1</td><td>2</td><td>2</td><td>1</td><td>2</td></tr><tr><td>0</td><td>2</td><td>0</td><td>2</td><td>1</td></tr><tr><td>0</td><td>1</td><td>1</td><td>1</td><td>0</td></tr><tr><td>1</td><td>0</td><td>0</td><td>0</td><td>1</td></tr></table>	0	0	1	2	2	1	2	2	1	2	0	2	0	2	1	0	1	1	1	0	1	0	0	0	1	<table><tr><td>0</td><td>0</td><td>1</td><td>2</td><td>2</td></tr><tr><td>1</td><td>2</td><td>2</td><td>1</td><td>2</td></tr><tr><td>0</td><td>2</td><td>0</td><td>2</td><td>1</td></tr><tr><td>0</td><td>1</td><td>1</td><td>1</td><td>0</td></tr><tr><td>1</td><td>0</td><td>0</td><td>0</td><td>1</td></tr></table>	0	0	1	2	2	1	2	2	1	2	0	2	0	2	1	0	1	1	1	0	1	0	0	0	1
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0	0	1	2	2																																																																									
1	2	2	1	2																																																																									
0	2	0	2	1																																																																									
0	1	1	1	0																																																																									
1	0	0	0	1																																																																									
0	0	1	2	2																																																																									
1	2	2	1	2																																																																									
0	2	0	2	1																																																																									
0	1	1	1	0																																																																									
1	0	0	0	1																																																																									

# Convolutional Layer

## ❖ Example

0	0	1	2	2
1	2	2	1	2
0	2	0	2	1
0	1	1	1	0
1	0	0	0	1

Data **D**

Bias  $b = 0.0$

0.0	0.1	-0.1
-0.2	0.0	0.1
0.0	0.0	0.1

Kernel **K**

$m_1$		

Output

Data size =  $5 \times 5$   
Kernel size =  $3 \times 3$   
Stride = 1

$$\begin{aligned} m_1 = & 0 \times 0.0 + 0 \times 0.1 + 1 \times -0.1 + \\ & 1 \times -0.2 + 2 \times 0.0 + 2 \times 0.1 + \\ & 0 \times 0.0 + 2 \times 0.0 + 0 \times 0.1 \end{aligned}$$



$$m_1 = -0.1$$



# Convolutional Layer

## ❖ Example

$$S_o = \left\lfloor \frac{S_D - K}{S} \right\rfloor + 1$$

0	0	1	2	2
1	2	2	1	2
0	2	0	2	1
0	1	1	1	0
1	0	0	0	1

Data **D**

Data size =  $5 \times 5$

Bias  $b = 0.0$

0.0	0.1	-0.1
-0.2	0.0	0.1
0.0	0.0	0.1

Kernel **K**

Kernel size =  $3 \times 3$

-0.1	-0.1	-0.2
0.3	-0.2	0.1
0.3	-0.3	0.1

Output

Stride = 1

# Convolutional Layer

## ❖ Example

0	0	1	2	2
1	2	2	1	2
0	2	0	2	1
0	1	1	1	0
1	0	0	0	1

Data **D**

Bias  $b = 0.0$

0.0	0.1	-0.1
-0.2	0.0	0.1
0.0	0.0	0.1

Kernel **K**

$m_1$	

Output

Data size =  $5 \times 5$   
Kernel size =  $3 \times 3$   
Stride = 2

$$\begin{aligned} m_1 = & 0 \times 0.0 + 0 \times 0.1 + 1 \times -0.1 + \\ & 1 \times -0.2 + 2 \times 0.0 + 2 \times 0.1 + \\ & 0 \times 0.0 + 2 \times 0.0 + 0 \times 0.1 \end{aligned}$$



$$m_1 = -0.1$$

# Convolutional Layer

## ❖ Example

$$S_o = \left\lfloor \frac{S_D - K}{S} \right\rfloor + 1$$

0	0	1	2	2
1	2	2	1	2
0	2	0	2	1
0	1	1	1	0
1	0	0	0	1

Data **D**

Data size =  $5 \times 5$

Bias  $b = 0.0$

0.0	0.1	-0.1
-0.2	0.0	0.1
0.0	0.0	0.1

Kernel **K**

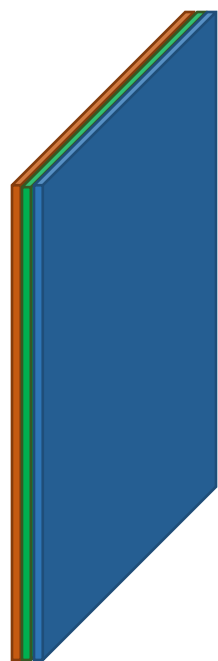
Kernel size =  $3 \times 3$

-0.1	-0.2
0.3	0.1

Output

Stride = 2

## ❖ Understand convolutional layers



Input Data  
(3,32,32)



Convolve with  
1 kernel (3,5,5)



Feature map  
(1,28,28)



Input Data  
(3,32,32)

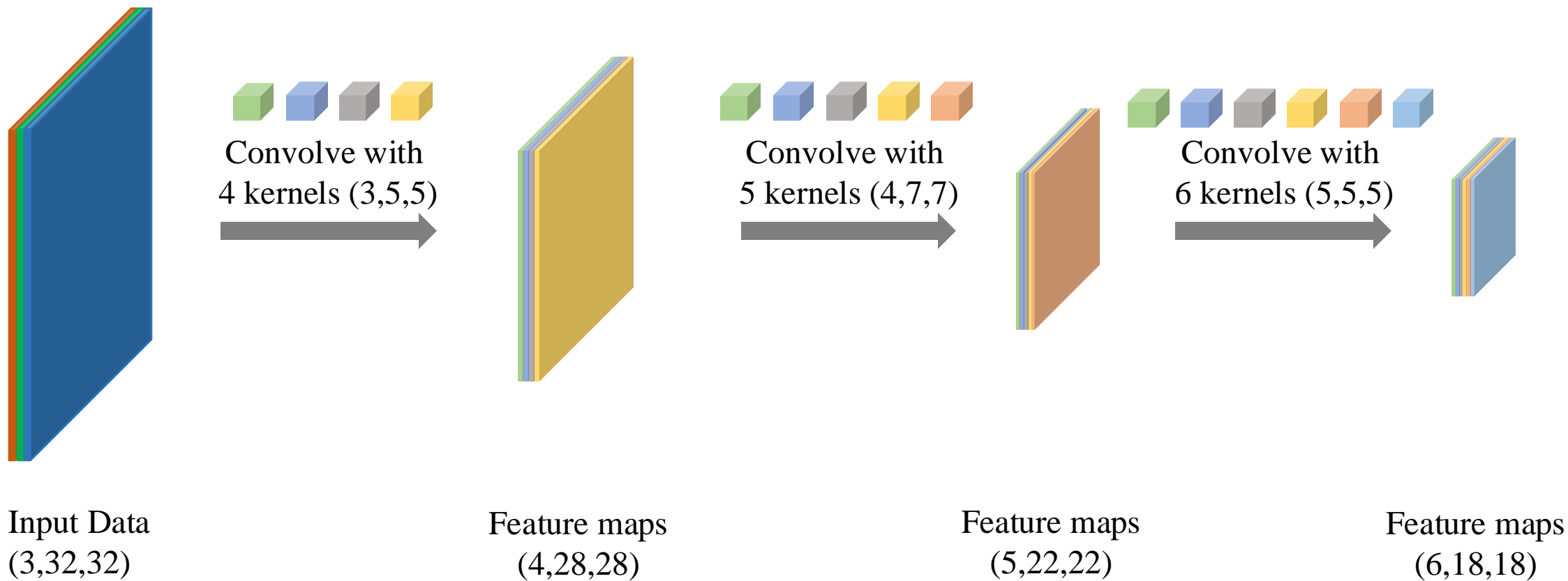


Convolve with  
4 kernels (3,5,5)

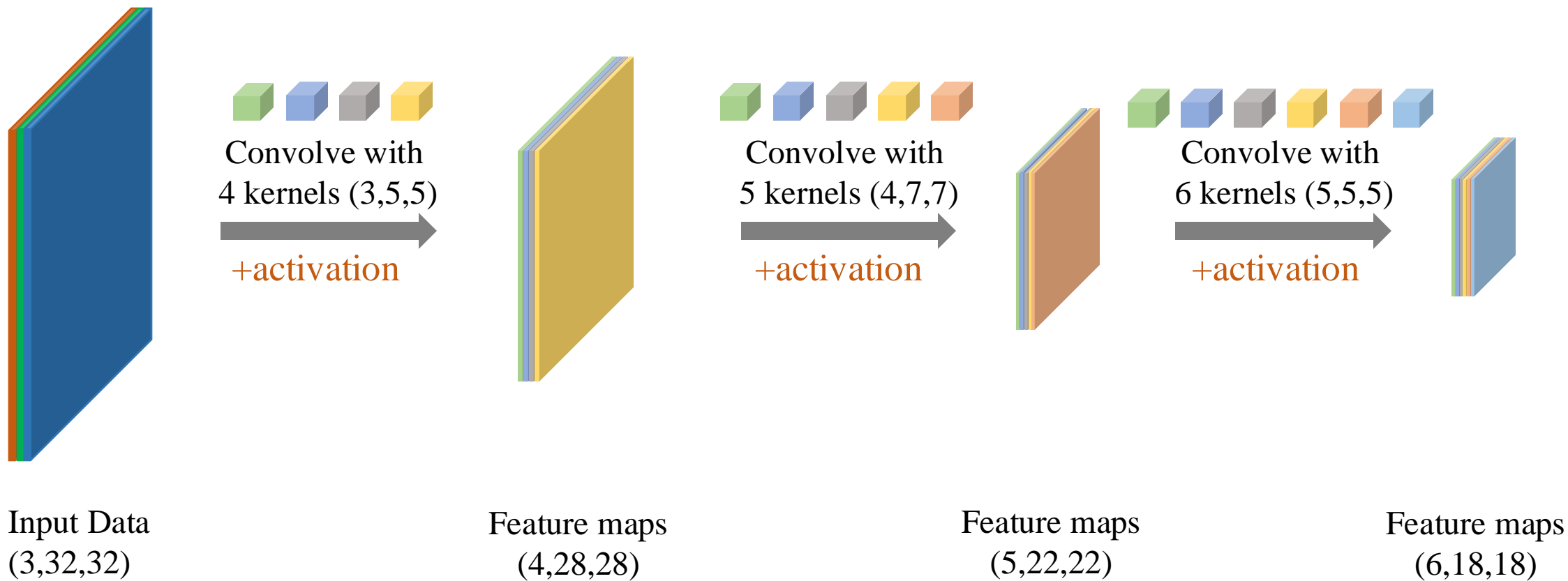


Feature maps  
(4,28,28)

## ❖ A stack of convolutional layers



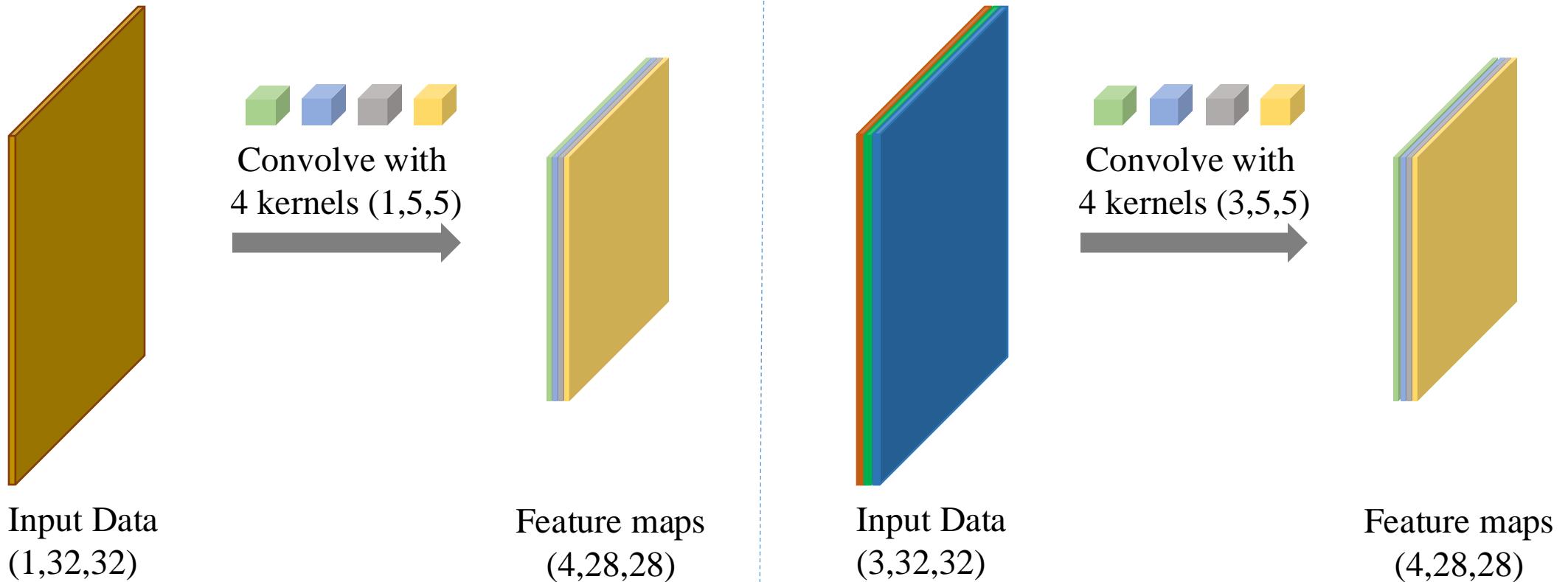
## ❖ A stack of pairs of convolutional layer + activation





## ❖ Convolutional layer in PyTorch

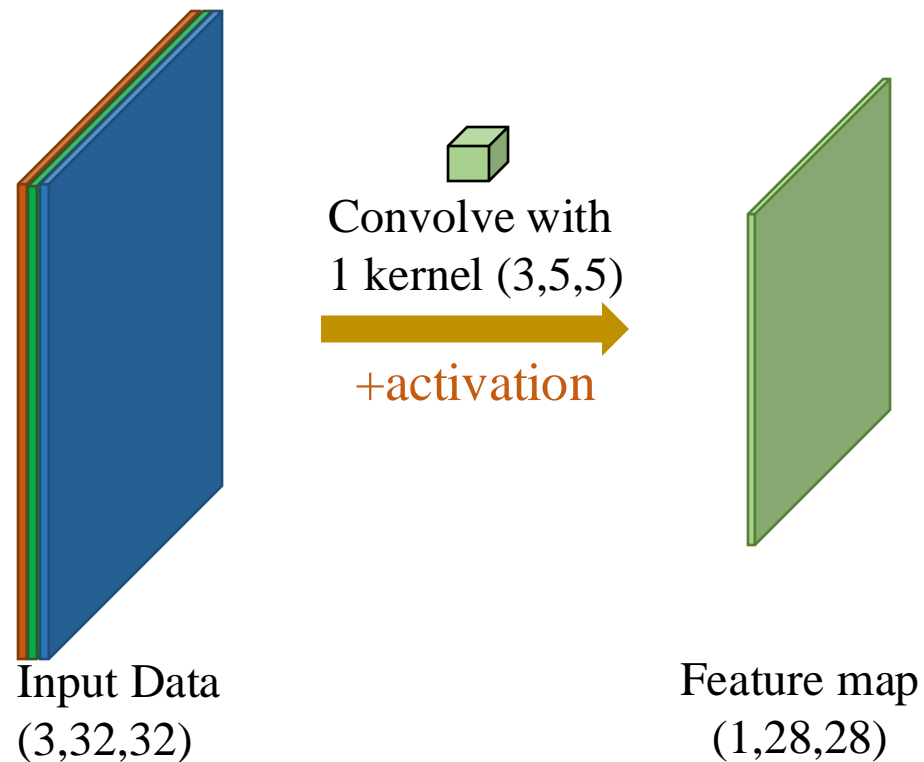
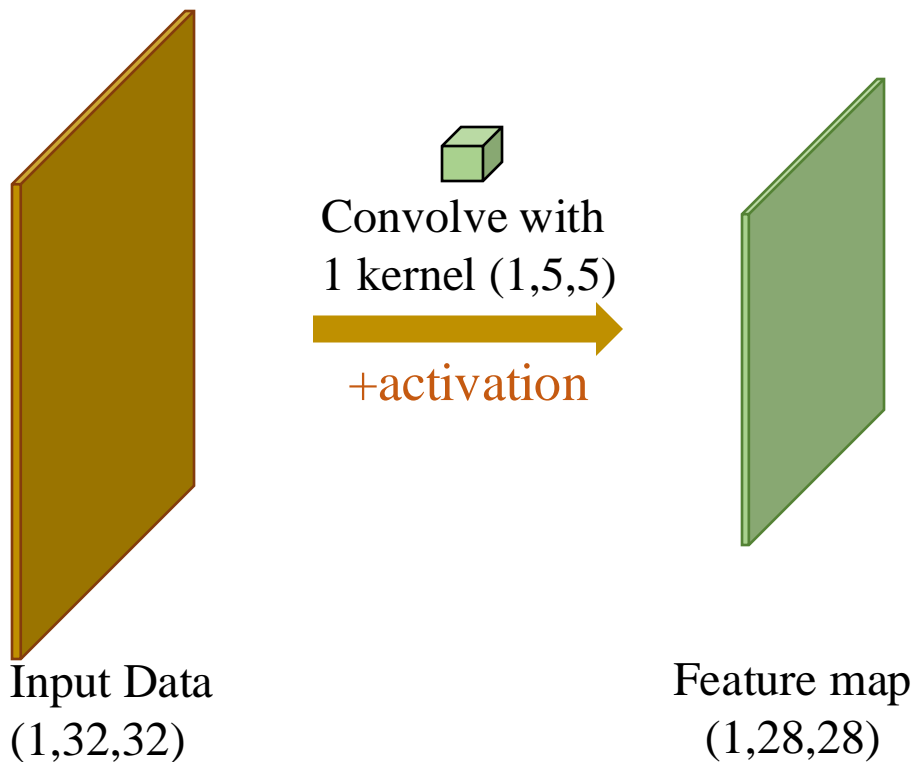
```
nn.Conv2d(in_channels, out_channels, kernel_size)
```



## ❖ Convolutional layer in PyTorch

demo

```
nn.Conv2d(in_channels, out_channels, kernel_size)  
nn.ReLU()
```



# Convolutional Neural Network

## Fashion-MNIST dataset

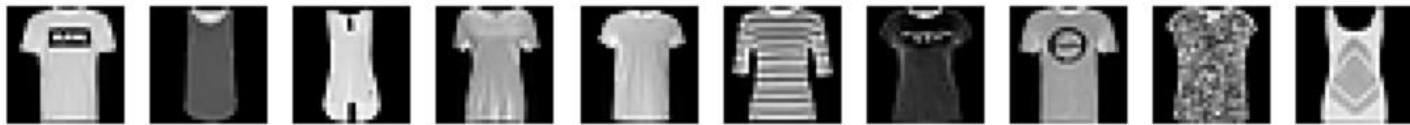
Grayscale images

Resolution=28x28

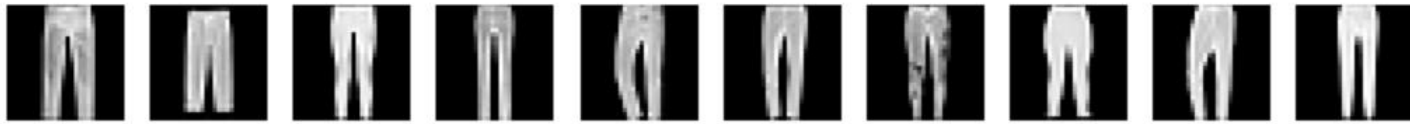
Training set: 60000 samples

Testing set: 10000 samples

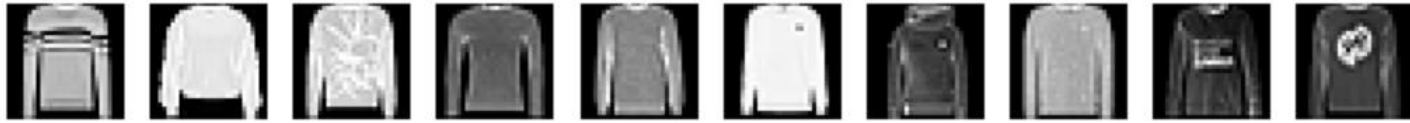
T-shirt



Trouser



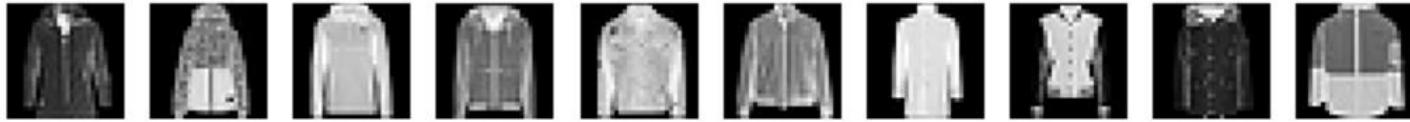
Pullover



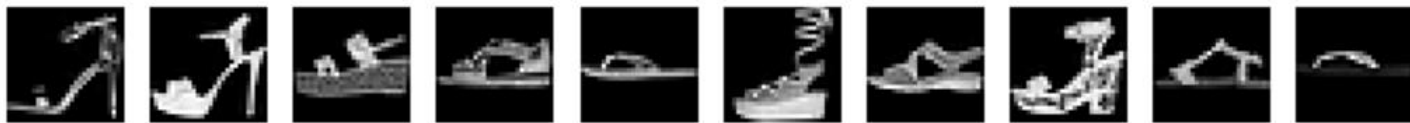
Dress



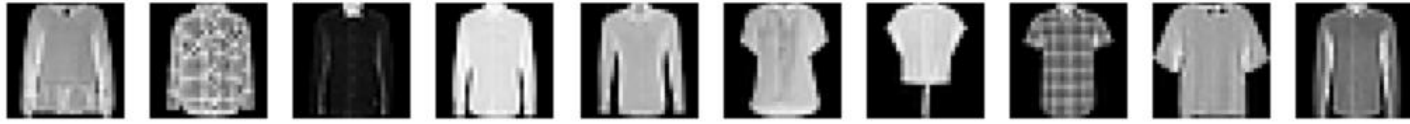
Coat



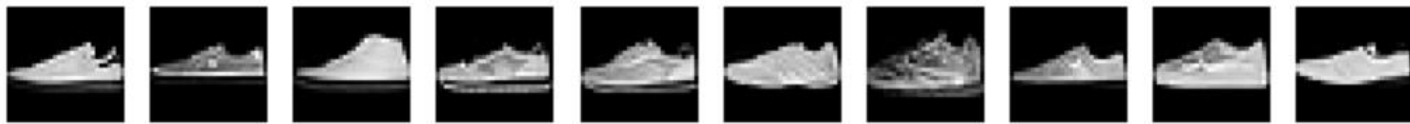
Sandal



Shirt



Sneaker



Bag

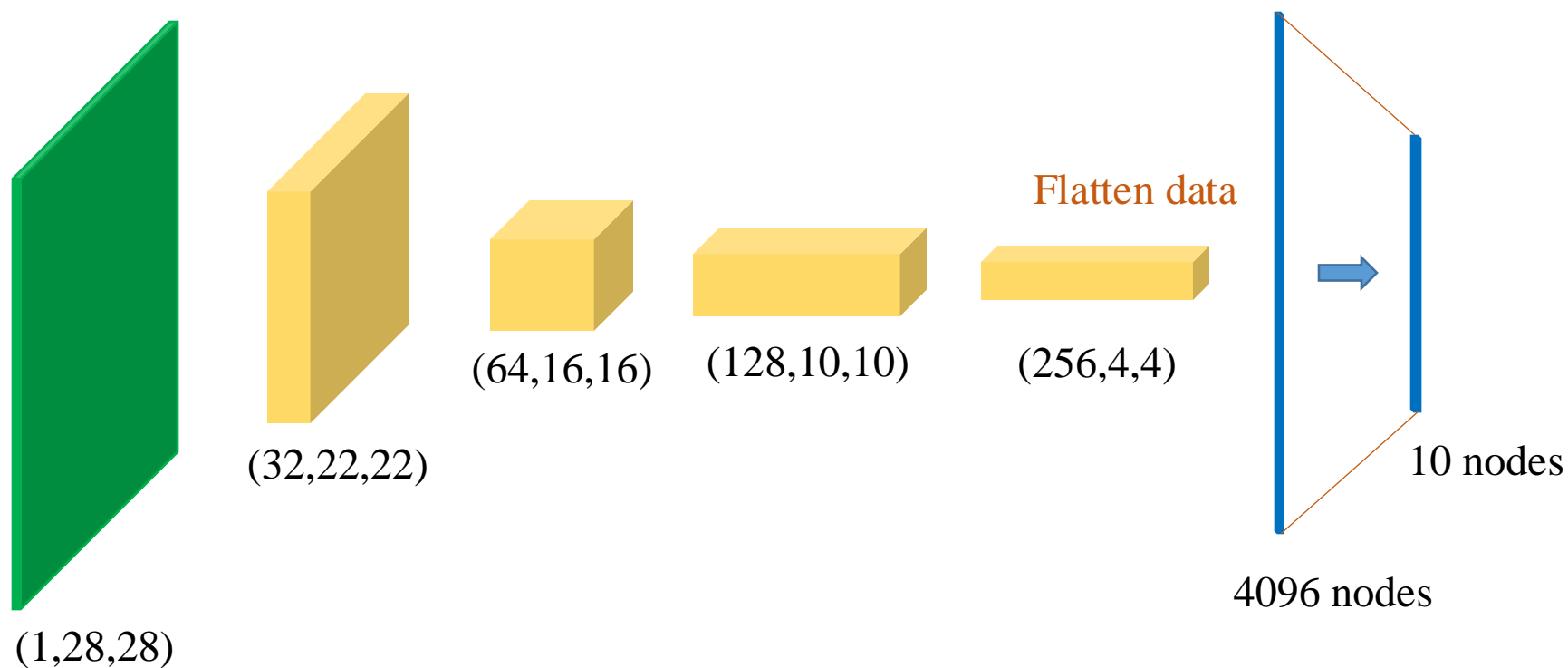


Ankle  
Boot



# Convolutional Neural Network

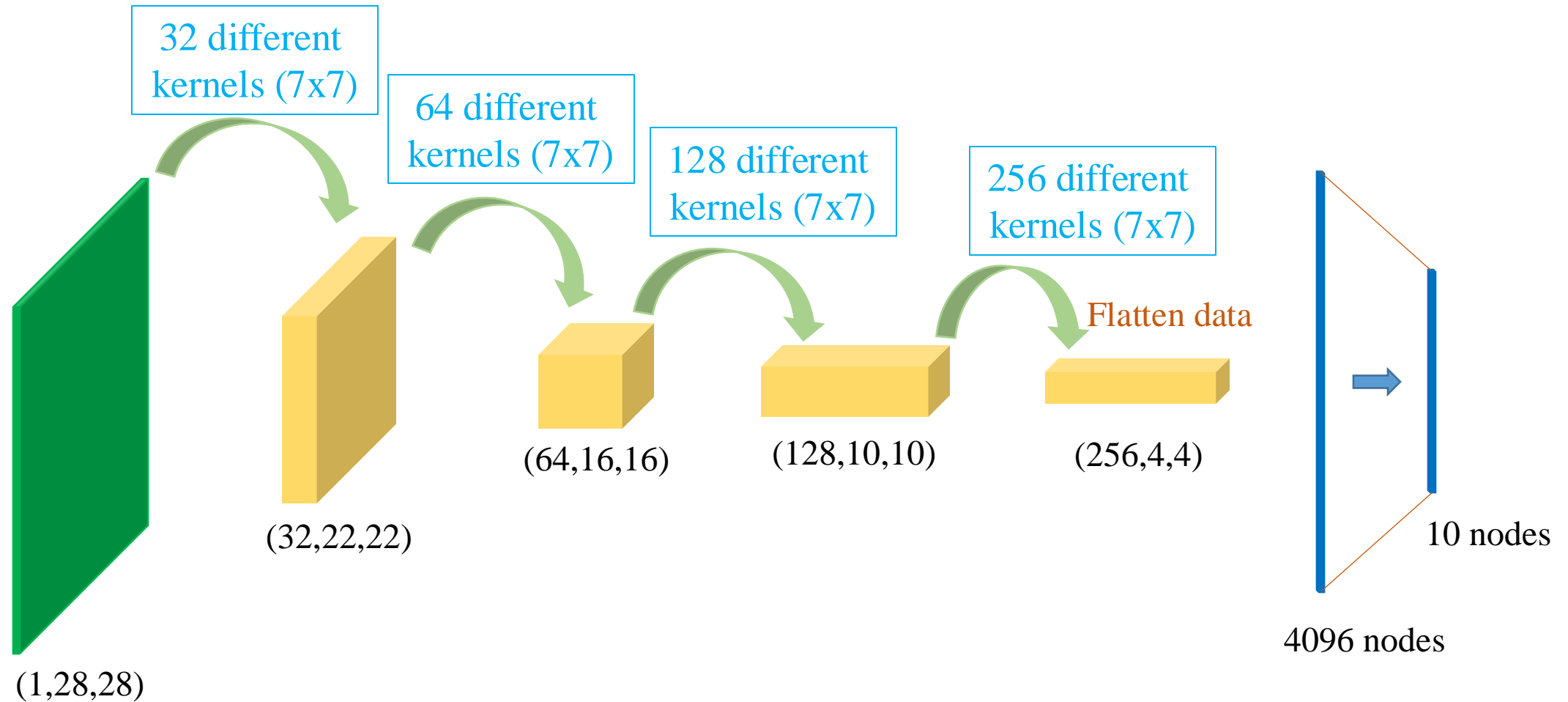
## ❖ Apply for Fashion-MNIST dataset



# Convolutional Neural Network

## ❖ Apply for Fashion-MNIST dataset

demo



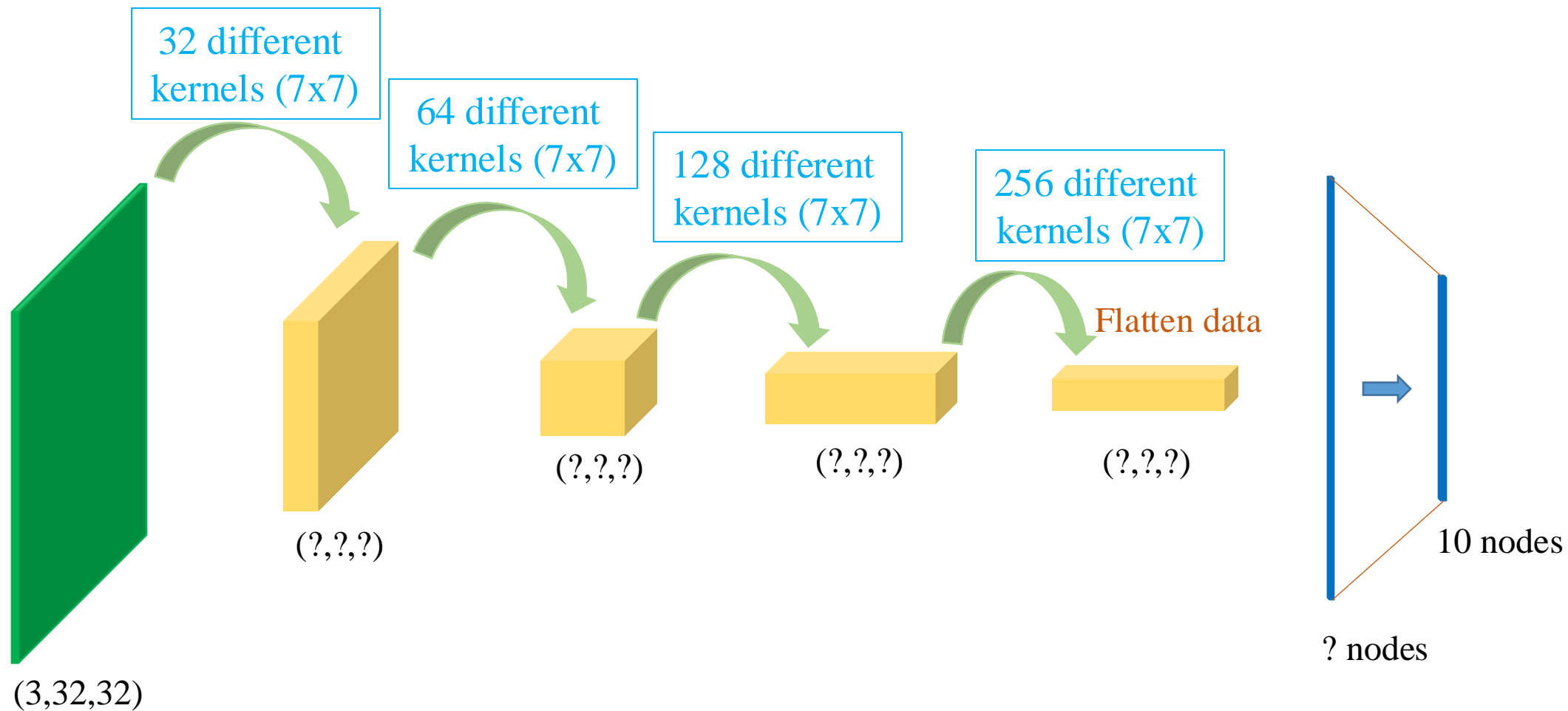
# Simple Convolutional Neural Network

```
class CustomModel(nn.Module):  
    def __init__(self):  
        super(CustomModel, self).__init__()  
        self.conv1 = nn.Conv2d(1, 32, kernel_size=7)  
        self.conv2 = nn.Conv2d(32, 64, kernel_size=7)  
        self.conv3 = nn.Conv2d(64, 128, kernel_size=7)  
        self.conv4 = nn.Conv2d(128, 256, kernel_size=7)  
        self.flatten = nn.Flatten()  
        self.dense = nn.Linear(4*4*256, 10)  
        self.relu = nn.ReLU()  
  
    def forward(self, x):  
        x = self.relu(self.conv1(x))  
        x = self.relu(self.conv2(x))  
        x = self.relu(self.conv3(x))  
        x = self.relu(self.conv4(x))  
        x = self.flatten(x)  
        x = self.dense(x)  
        return x  
  
model = CustomModel()
```

# Convolutional Neural Network

## ❖ Apply for Cifar-10 dataset

demo

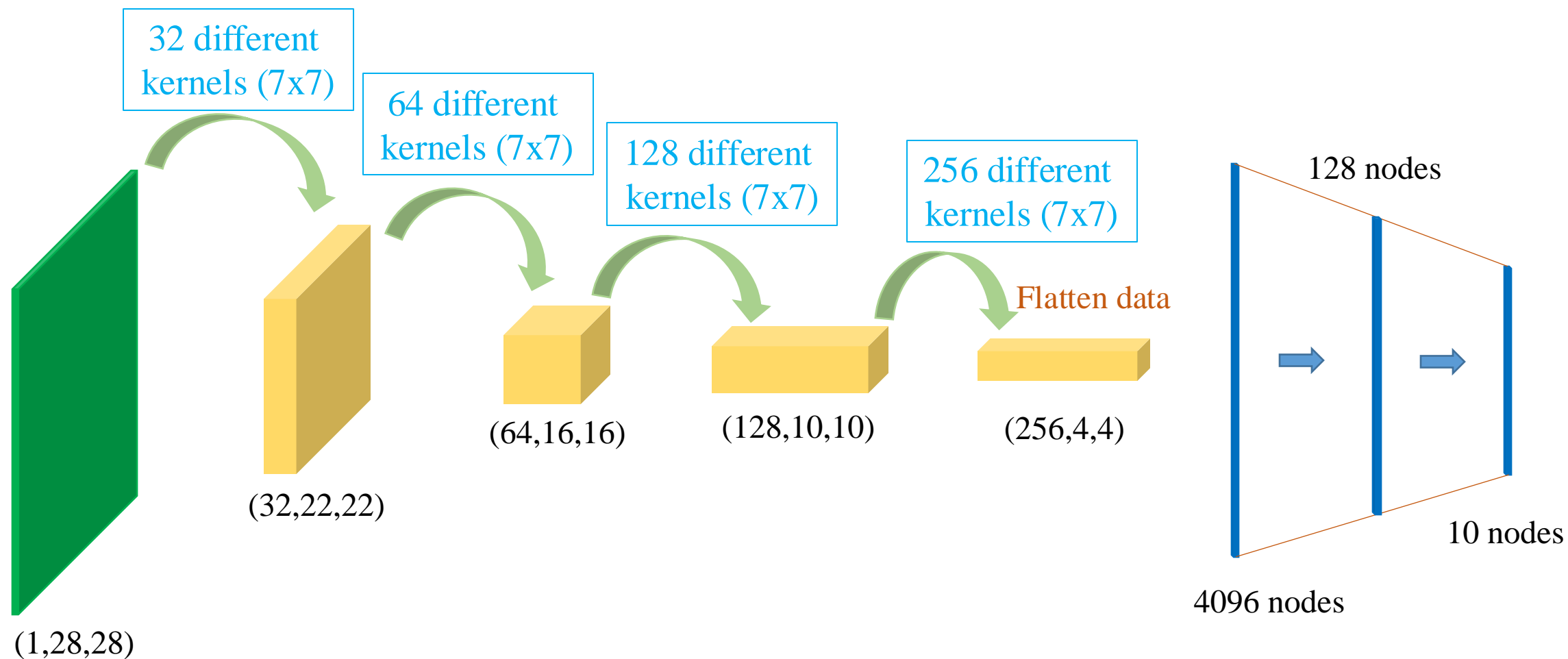


## More Examples



# Convolutional Neural Network

## ❖ Apply for Fashion-MNIST dataset: case 1



```

class CustomModel(nn.Module):
    def __init__(self):
        super(CustomModel, self).__init__()
        self.conv1 = nn.Conv2d(1, 32, kernel_size=7)
        self.conv2 = nn.Conv2d(32, 64, kernel_size=7)
        self.conv3 = nn.Conv2d(64, 128, kernel_size=7)
        self.conv4 = nn.Conv2d(128, 256, kernel_size=7)
        self.flatten = nn.Flatten()
        self.dense1 = nn.Linear(4*4*256, 128)
        self.dense2 = nn.Linear(128, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.relu(self.conv1(x))
        x = self.relu(self.conv2(x))
        x = self.relu(self.conv3(x))
        x = self.relu(self.conv4(x))
        x = self.flatten(x)
        x = self.relu(self.dense1(x))
        x = self.dense2(x)
        return x

model = CustomModel()
model = model.to(device)

```

```

# Load FashionMNIST dataset
transform = Compose([ToTensor(),
                      Normalize((0.5,),
                                (0.5,))])

trainset = FashionMNIST(root='data',
                        train=True,
                        download=True,
                        transform=transform)

trainloader = DataLoader(trainset,
                        batch_size=1024,
                        num_workers=10,
                        shuffle=True,
                        drop_last=True)

testset = FashionMNIST(root='data',
                      train=False,
                      download=True,
                      transform=transform)

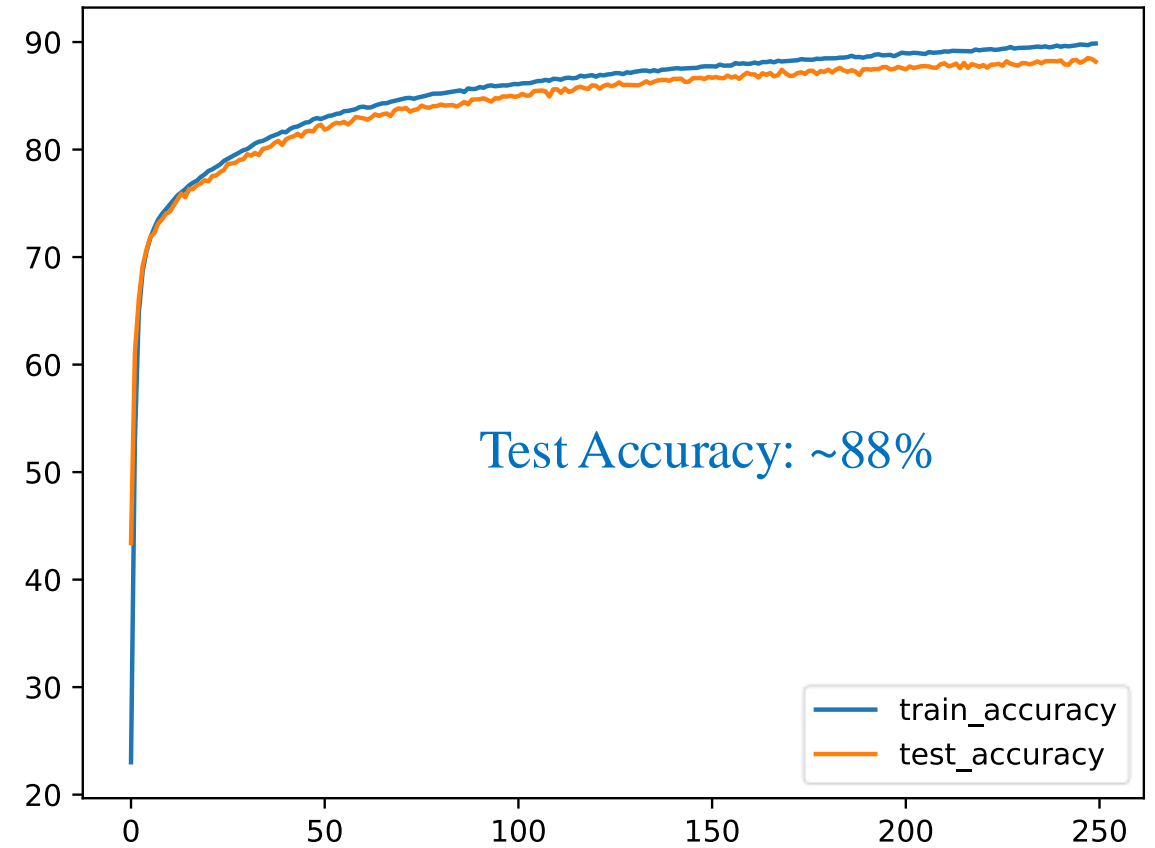
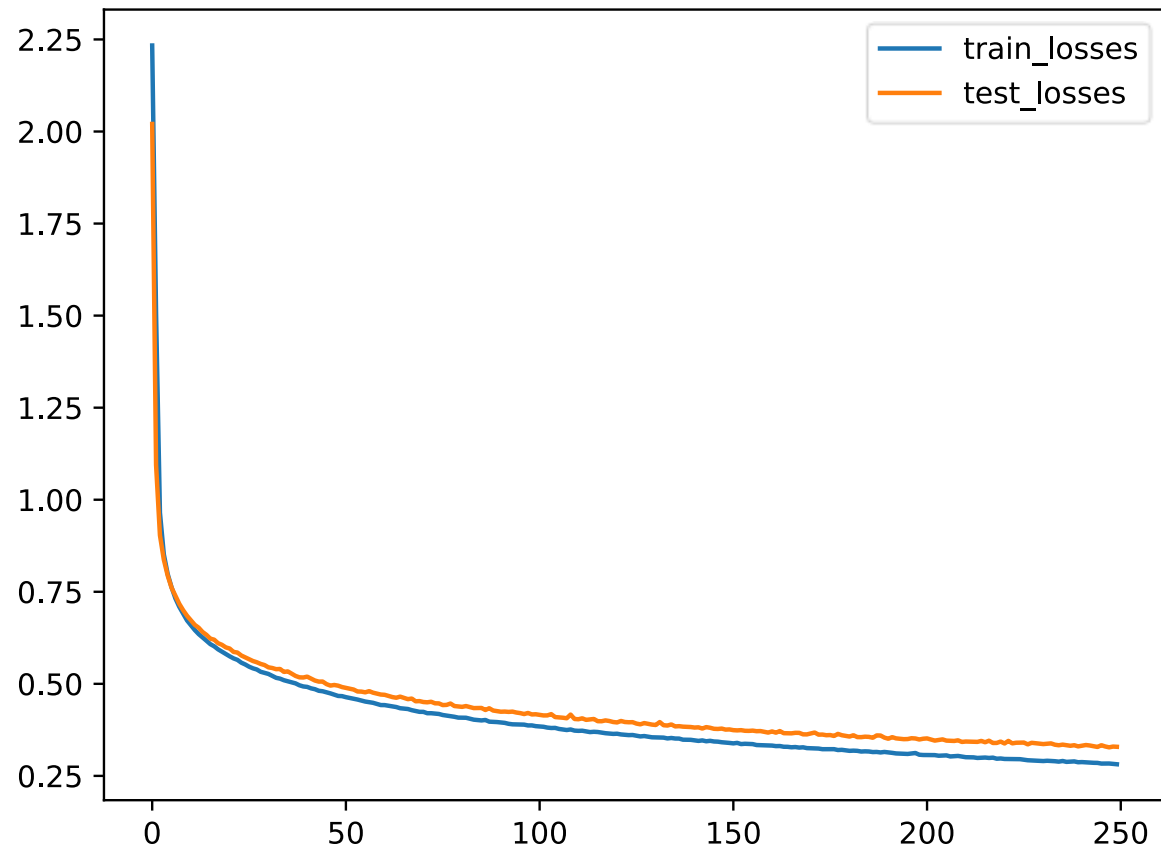
testloader = DataLoader(testset,
                      batch_size=1024,
                      num_workers=10,
                      shuffle=False)

# Loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=1e-5)

```

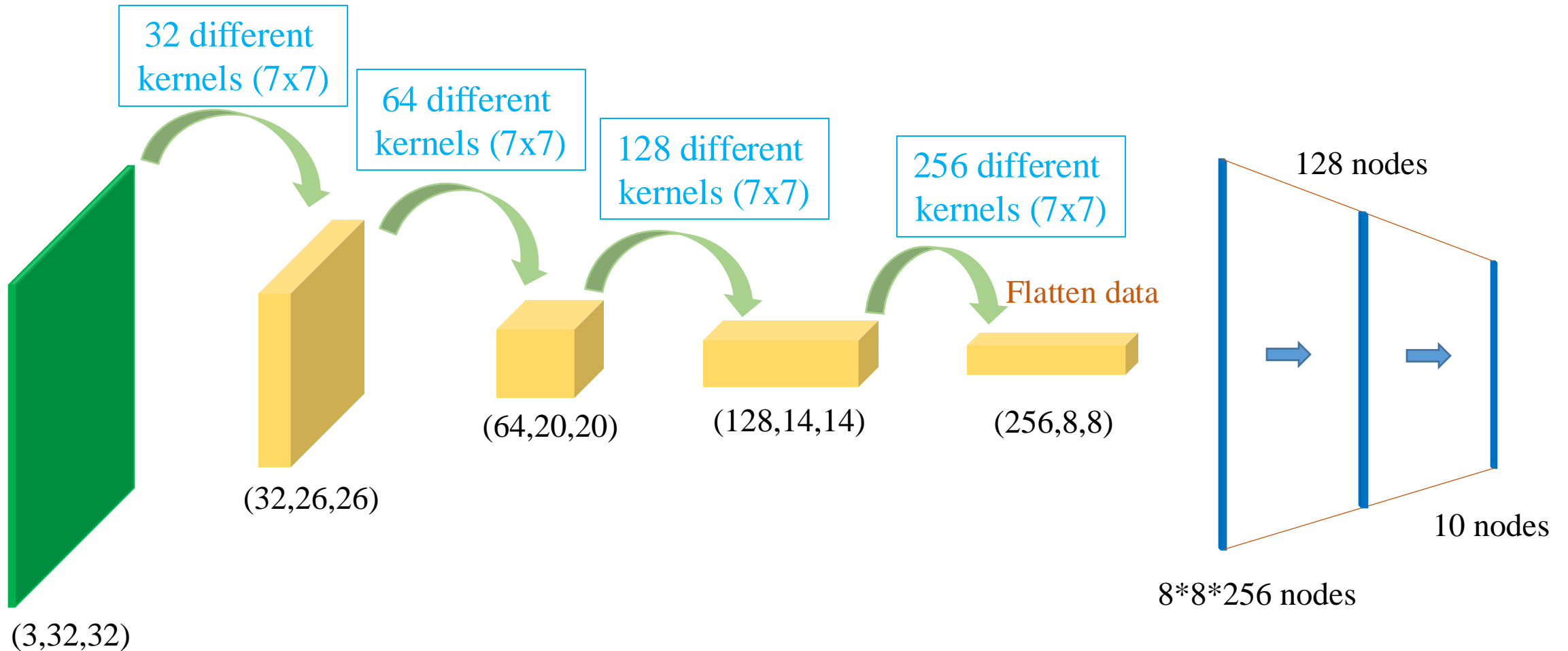
# Convolutional Neural Network

## ❖ Apply for Fashion-MNIST dataset: case 1



# Convolutional Neural Network

## ❖ Apply for Cifar-10 dataset: case 2



```

class CustomModel(nn.Module):
    def __init__(self):
        super(CustomModel, self).__init__()
        self.conv1 = nn.Conv2d(3, 32, kernel_size=7)
        self.conv2 = nn.Conv2d(32, 64, kernel_size=7)
        self.conv3 = nn.Conv2d(64, 128, kernel_size=7)
        self.conv4 = nn.Conv2d(128, 256, kernel_size=7)
        self.flatten = nn.Flatten()
        self.dense1 = nn.Linear(8*8*256, 128)
        self.dense2 = nn.Linear(128, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.relu(self.conv1(x))
        x = self.relu(self.conv2(x))
        x = self.relu(self.conv3(x))
        x = self.relu(self.conv4(x))
        x = self.flatten(x)
        x = self.relu(self.dense1(x))
        x = self.dense2(x)
        return x

model = CustomModel()
model = model.to(device)

```

```

# Load CIFAR10 dataset
transform = Compose([ToTensor(),
                      Normalize((0.5,0.5, 0.5),
                                (0.5,0.5, 0.5))])

trainset = CIFAR10(root='data',
                   train=True,
                   download=True,
                   transform=transform)
trainloader = DataLoader(trainset,
                        batch_size=1024,
                        num_workers=10,
                        shuffle=True,
                        drop_last=True)

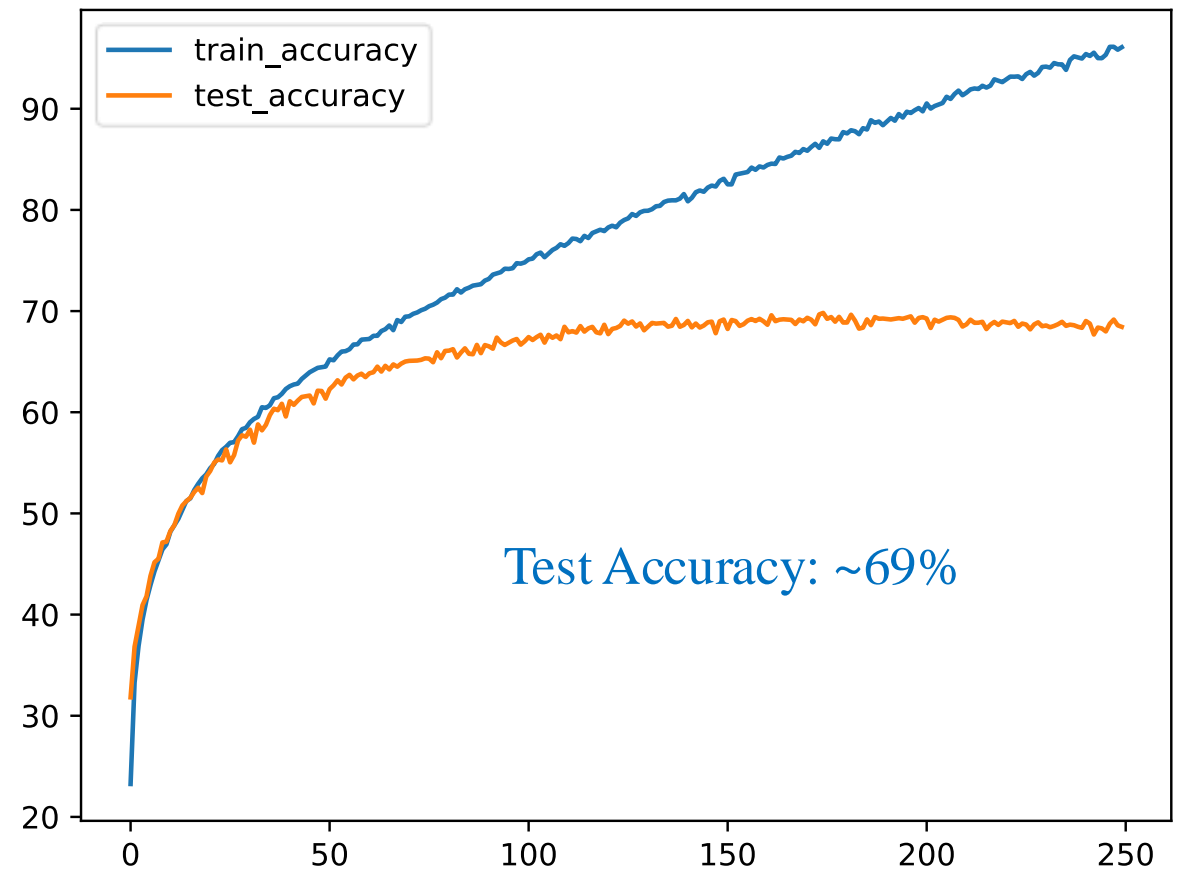
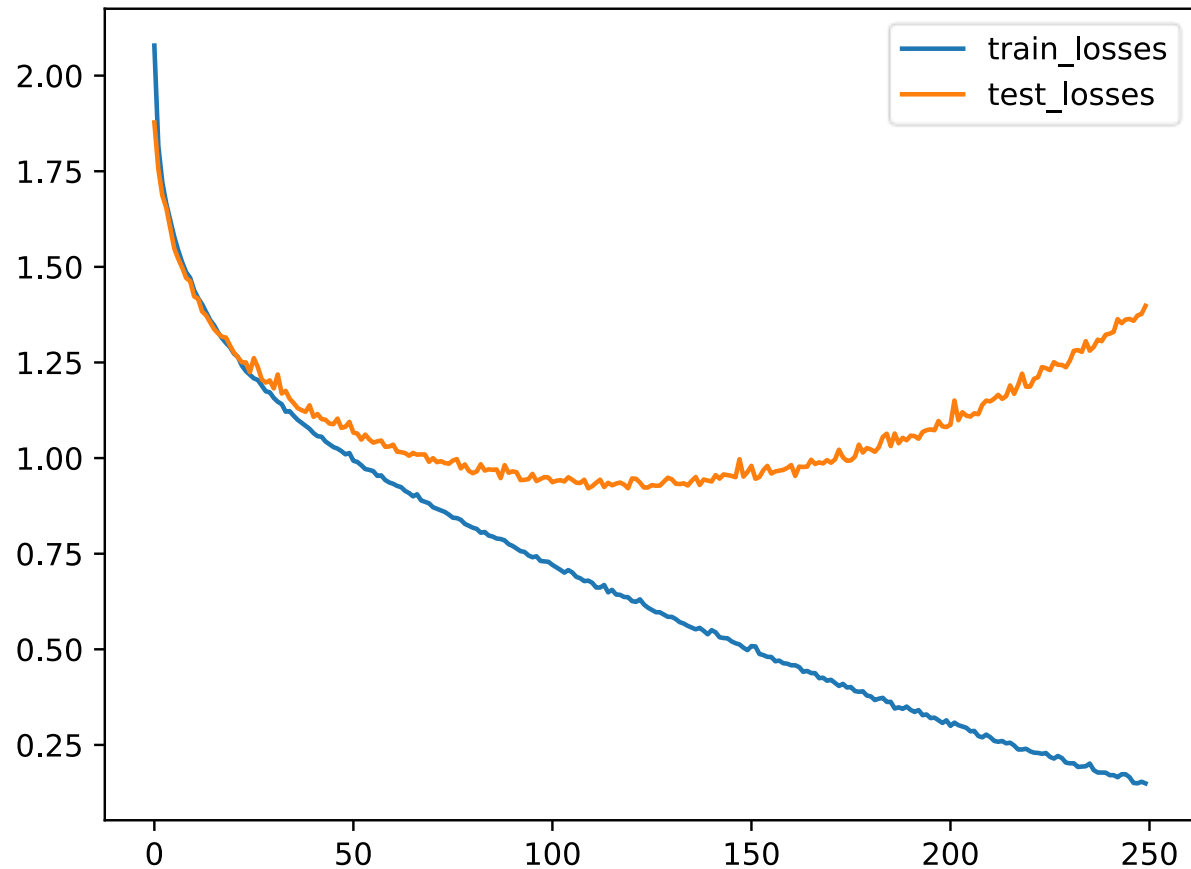
testset = CIFAR10(root='data',
                  train=False,
                  download=True,
                  transform=transform)
testloader = DataLoader(testset,
                      batch_size=1024,
                      num_workers=10,
                      shuffle=False)

# Loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=1e-5)

```

# Convolutional Neural Network

## ❖ Apply for Cifar-10 dataset: case 2



Test Accuracy from MLP: ~53%

Test Accuracy: ~69%

# Outline

## SECTION 1

### MLP Limitations

## SECTION 2

### Convolutional Layer

## SECTION 3

### Standard CNNs



Feature map (220x220)

max pooling  
(2x2)



Feature map (220x220)

Average  
Pooling (2x2)



Feature map  
(110x110)

# Down-sample Feature Map

❖ Max pooling: Features are preserved

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

Data

2x2 max pooling (

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

) =

$m_1$	$m_2$
$m_3$	$m_4$

$$m_1 = \max(v_1, v_2, v_5, v_6)$$

$$m_2 = \max(v_3, v_4, v_7, v_8)$$

$$m_3 = \max(v_9, v_{10}, v_{13}, v_{14})$$

$$m_4 = \max(v_{11}, v_{12}, v_{15}, v_{16})$$

nn.MaxPool2d(2, 2)



Feature map (220x220)

max pooling  
(2x2)



Feature map  
(110x110)

max pooling  
(2x2)

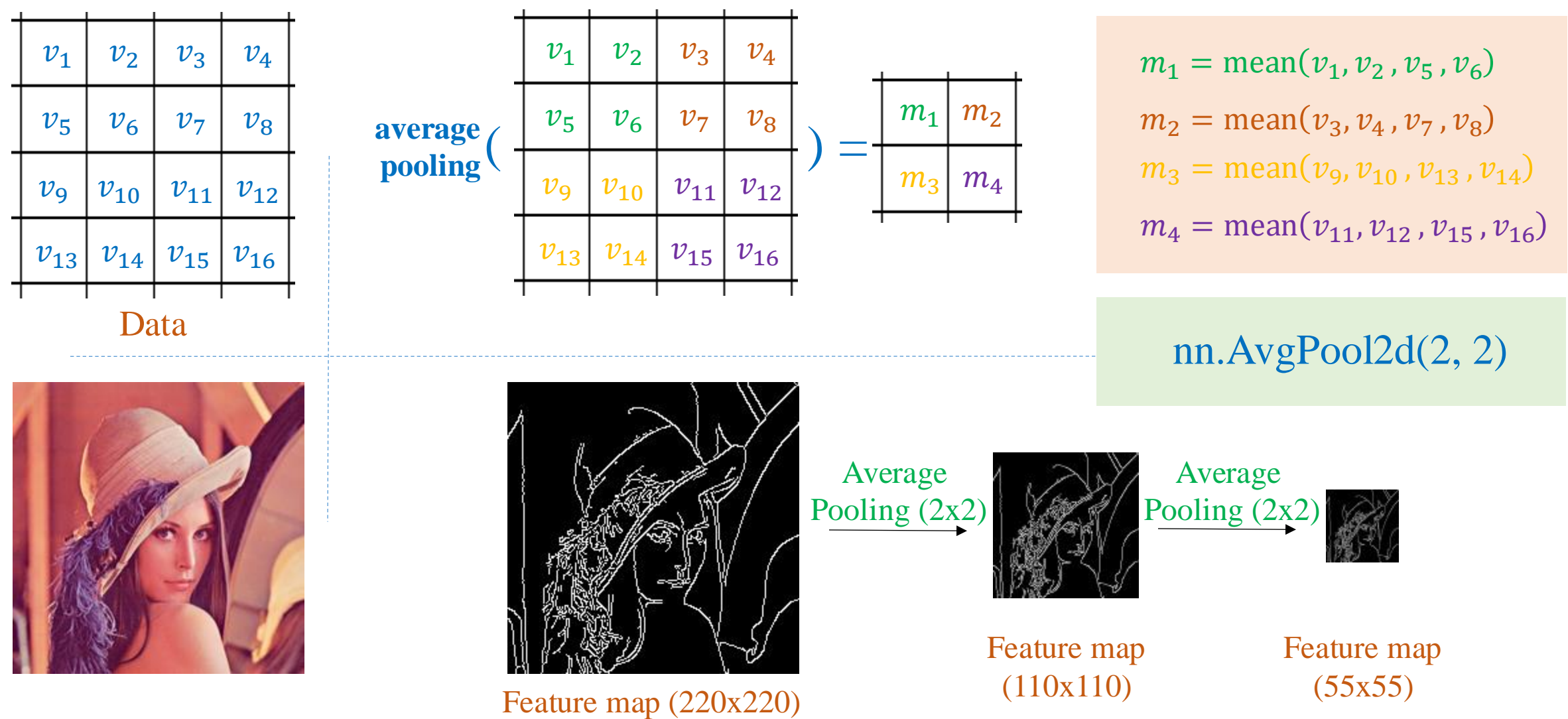


Feature map  
(55x55)



# Down-sample Feature Map

❖ Average pooling: Features are preserved



# Down-sample Feature Map

## ❖ Max pooling vs. Average pooling

`nn.MaxPool2d(2, 2)`



Feature map (220x220)

max pooling  
(2x2)



max pooling  
(2x2)



Feature map  
(55x55)

`nn.AvgPool2d(2, 2)`



Feature map (220x220)

Average  
Pooling (2x2)



Feature map  
(110x110)

Average  
Pooling (2x2)



Feature map  
(55x55)

```

class CustomModel(nn.Module):
    def __init__(self):
        super(CustomModel, self).__init__()
        self.conv1 = nn.Conv2d(1, 32, kernel_size=3)
        self.conv2 = nn.Conv2d(32, 64, kernel_size=3)
        self.conv3 = nn.Conv2d(64, 128, kernel_size=3)
        self.conv4 = nn.Conv2d(128, 256, kernel_size=3)
        self.conv5 = nn.Conv2d(256, 512, kernel_size=3)
        self.relu = nn.ReLU()
        self.pool = nn.MaxPool2d(2, 2) # 2x2 Max pooling
        self.flatten = nn.Flatten()
        self.dense = nn.Linear(2*2*512, 10)

```

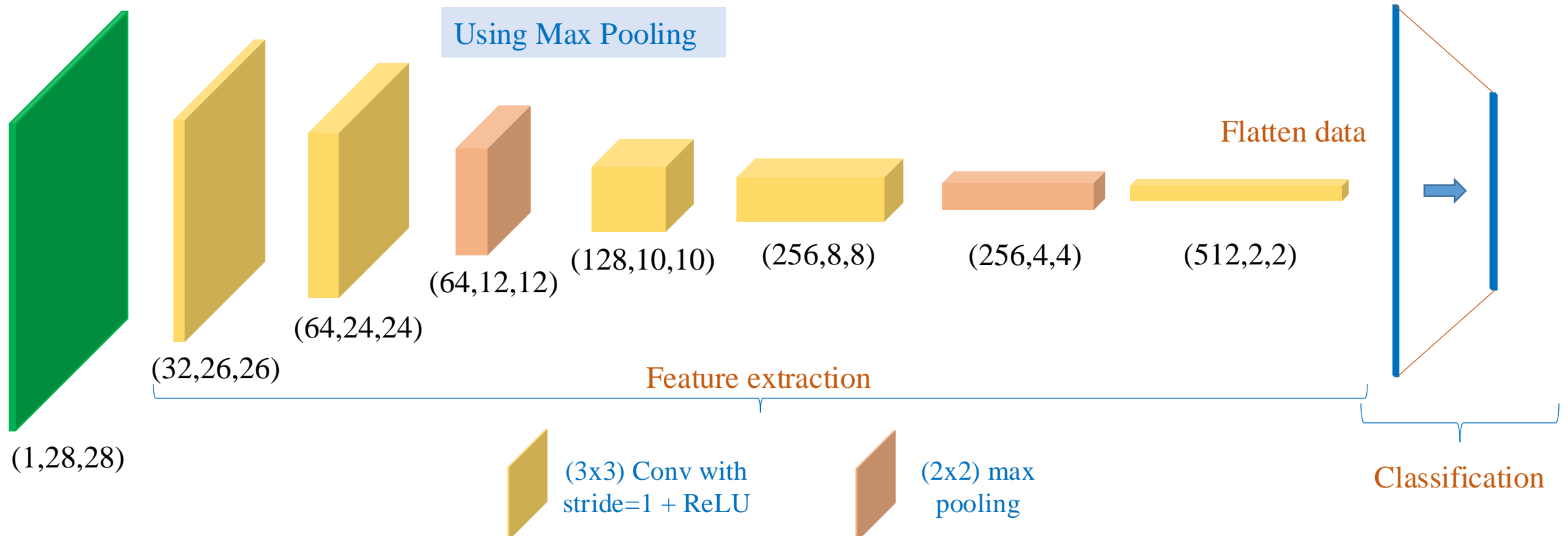
```

def forward(self, x):
    x = self.relu(self.conv1(x))
    x = self.relu(self.conv2(x))
    x = self.pool(x)

    x = self.relu(self.conv3(x))
    x = self.relu(self.conv4(x))
    x = self.pool(x)

    x = self.relu(self.conv5(x))
    x = self.flatten(x)
    x = self.dense(x)
    return x

```

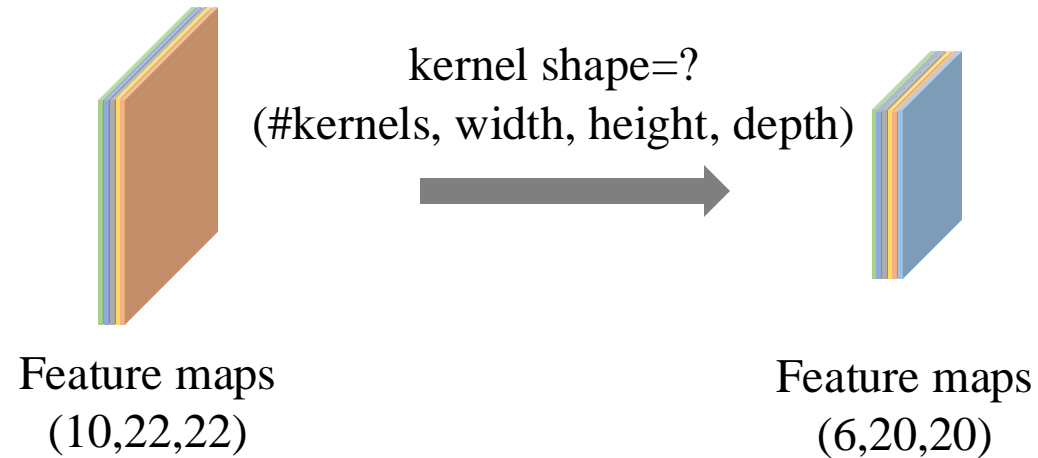






# Question 1

❖ Giả sử chúng ta dùng kernel có width=3 và height=3, shape của kernel là gì (#kernels là số lượng kernel)?



a) (10, 3, 3, 10)

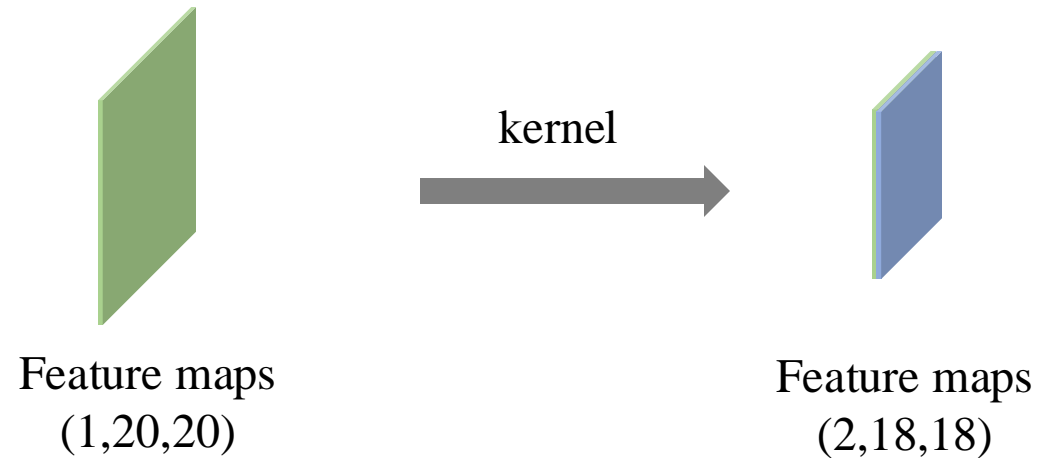
b) (10, 3, 3, 6)

c) (6, 3, 3, 10)

d) Không xác định

# Question 2

❖ Giả sử chúng ta dùng kernel có width=3 và height=3, tổng số lượng tham số của kernel là bao nhiêu?



a) Có 9 tham số

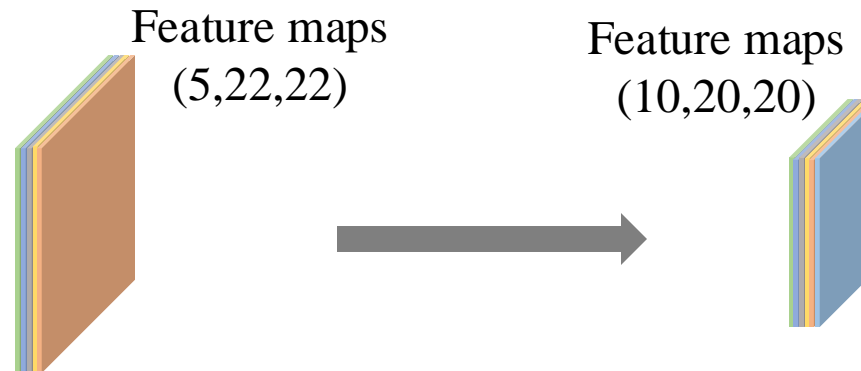
b) Có 10 tham số

c) Có 18 tham số

d) Có 20 tham số

# Question 3

❖ Code Pytorch nào áp dụng đúng cho hình sau?



C1

```
nn.Conv2d(5, 10, kernel_size=3)
```

C2

```
nn.Conv2d(10, 10, kernel_size=3)
```

C3

```
nn.Conv2d(5, 5, kernel_size=3)
```

C4

```
nn.Conv2d(10, 5, kernel_size=3)
```

# Question 4

❖ Input (cho model) có shape là (1, 50, 50) thì output có shape là gì (bỏ qua phần batch size)?

```
class CustomModel(nn.Module):  
    def __init__(self):  
        super(CustomModel, self).__init__()  
        self.conv = nn.Conv2d(1, 32, kernel_size=3)  
        self.pool = nn.MaxPool2d(2, 2)  
        self.relu = nn.ReLU()  
  
    def forward(self, x):  
        x = self.conv(x)  
        x = self.relu(x)  
        x = self.pool(x)  
        return x  
  
model = CustomModel()  
summary(model, (1, 50, 50))
```

a) (1, 48, 48)

b) (1, 24, 24)

c) (32, 48, 48)

d) (32, 24, 24)



# Question 5

❖ Input (cho model) có shape là (1, 50, 50) thì output có shape là gì (bỏ qua phần batch size)?

```
class CustomModel(nn.Module):  
    def __init__(self):  
        super(CustomModel, self).__init__()  
        self.conv1 = nn.Conv2d(1, 32, kernel_size=3)  
        self.pool1 = nn.MaxPool2d(2, 2)  
        self.conv2 = nn.Conv2d(32, 32, kernel_size=5)  
        self.pool2 = nn.MaxPool2d(2, 2)  
        self.relu = nn.ReLU()  
  
    def forward(self, x):  
        x = self.relu(self.conv1(x))  
        x = self.pool1(x)  
        x = self.relu(self.conv2(x))  
        x = self.pool2(x)  
        return x  
  
model = CustomModel()  
summary(model, (1, 50, 50))
```

a) (32, 24, 24)

b) (32, 10, 10)

c) (32, 8, 8)

d) (32, 6, 6)

# Question 6

❖ Input (cho model) có shape là (1, 50, 50) thì output có shape là gì (bỏ qua phần batch size)?

```
class CustomModel(nn.Module):  
    def __init__(self):  
        super(CustomModel, self).__init__()  
        self.conv1 = nn.Conv2d(1, 32, kernel_size=3)  
        self.conv2 = nn.Conv2d(1, 32, kernel_size=3)  
        self.relu = nn.ReLU()  
  
    def forward(self, x):  
        x = self.relu(self.conv1(x))  
        x = self.relu(self.conv2(x))  
        return x  
  
model = CustomModel()  
summary(model, (1, 50, 50))
```

a) shape=(32, 50, 50)

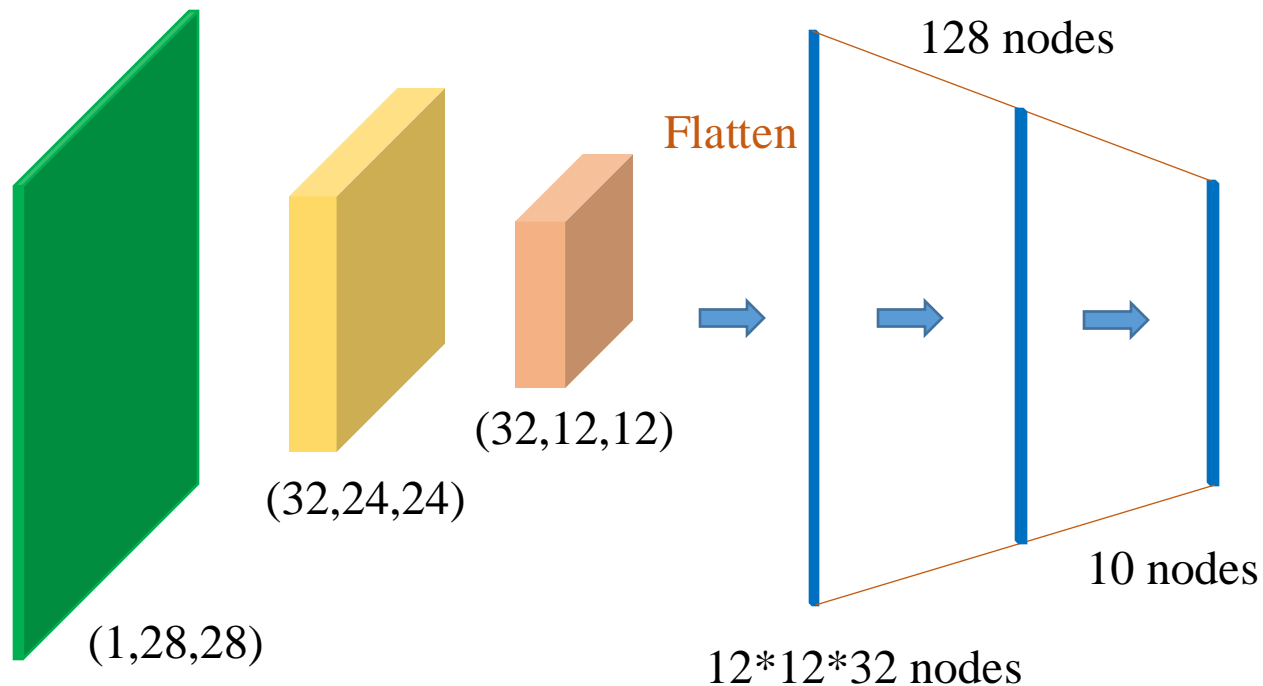
b) shape=(32, 48, 48)

c) shape=(32, 46, 46)

d) Có lỗi

# Comparison of down-samplings

## Model Design



## Implementation 1

```
class CustomModel(nn.Module):
    def __init__(self):
        super(CustomModel, self).__init__()
        self.conv = nn.Conv2d(1, 32, kernel_size=5)
        self.pool = nn.MaxPool2d(2, 2)
        self.flatten = nn.Flatten()
        self.dense1 = nn.Linear(12*12*32, 128)
        self.dense2 = nn.Linear(128, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.conv(x)
        x = self.relu(x)
        x = self.pool(x)
        x = self.flatten(x)
        x = self.relu(self.dense1(x))
        x = self.dense2(x)
        return x

# create model
model = CustomModel()
model = model.to(device)

# loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=1e-5)
```

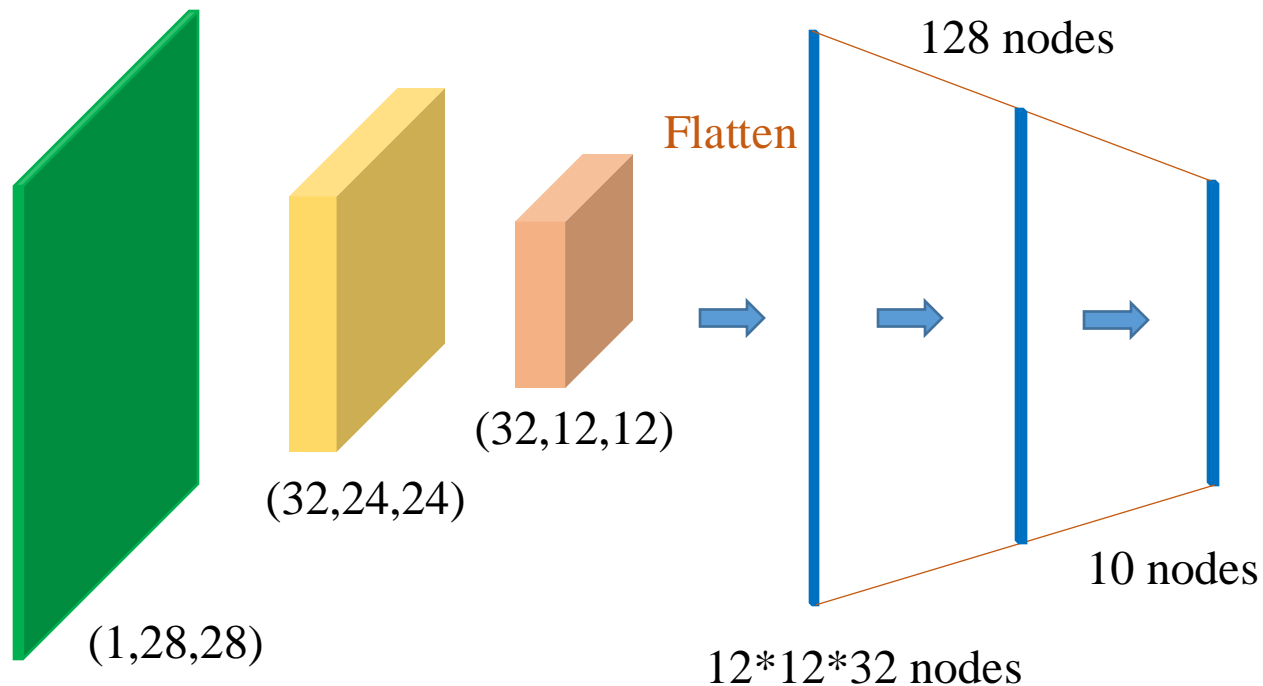
max pooling

(5x5) Conv with  
stride=1 + ReLU

(2x2) down-  
sampling

# Comparison of down-samplings

## Model Design



## Implementation 2

```
class CustomModel(nn.Module):  
    def __init__(self):  
        super(CustomModel, self).__init__()  
        self.conv = nn.Conv2d(1, 32, kernel_size=5)  
        self.pool = nn.AvgPool2d(2, 2)  
        self.flatten = nn.Flatten()  
        self.dense1 = nn.Linear(12*12*32, 128)  
        self.dense2 = nn.Linear(128, 10)  
        self.relu = nn.ReLU()
```

```
    def forward(self, x):  
        x = self.conv(x)  
        x = self.relu(x)  
        x = self.pool(x)  
        x = self.flatten(x)  
        x = self.relu(self.dense1(x))  
        x = self.dense2(x)  
        return x
```

average pooling

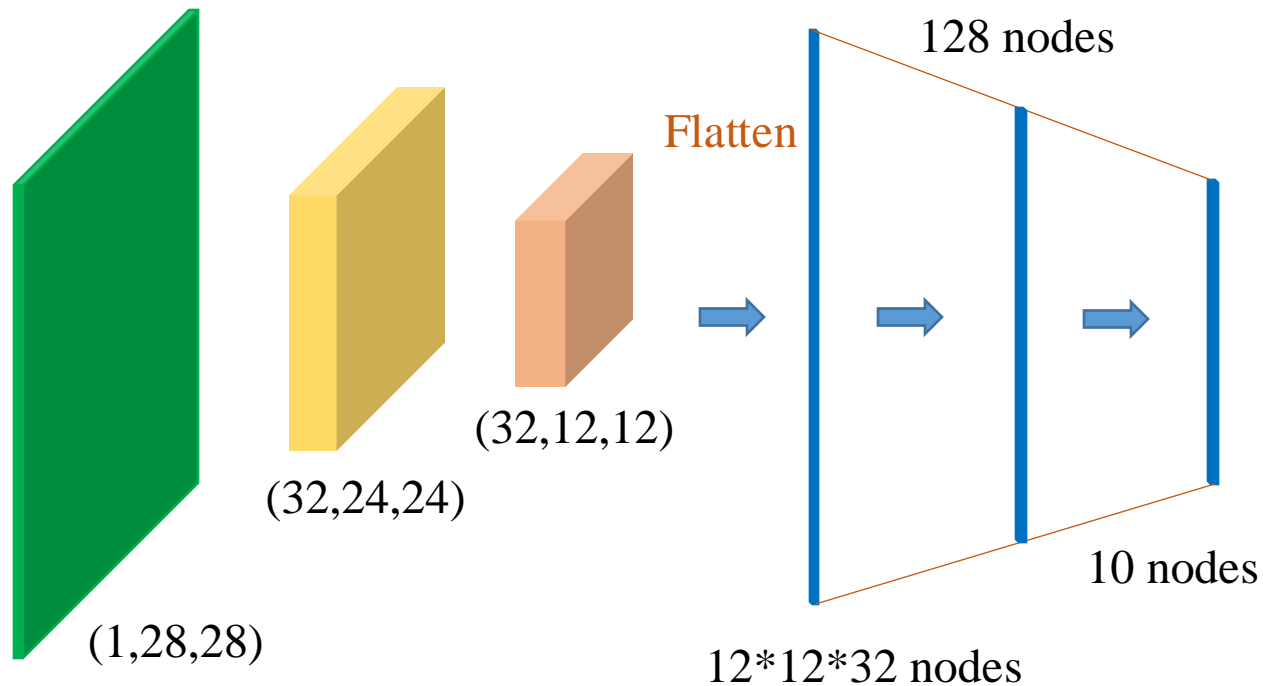
```
# create model  
model = CustomModel()  
model = model.to(device)  
  
# loss and optimizer  
criterion = nn.CrossEntropyLoss()  
optimizer = optim.Adam(model.parameters(), lr=1e-5)
```

(5x5) Conv with  
stride=1 + ReLU

(2x2) down-  
sampling

# Comparison of down-samplings

## Model Design



(5x5) Conv with  
stride=1 + ReLU

(2x2) down-  
sampling

```
class ResizeLayer(nn.Module):
    def __init__(self, scale_factor, mode='bilinear',
                  align_corners=False):
        super(ResizeLayer, self).__init__()
        self.scale_factor = scale_factor
        self.mode = mode
        self.align_corners = align_corners

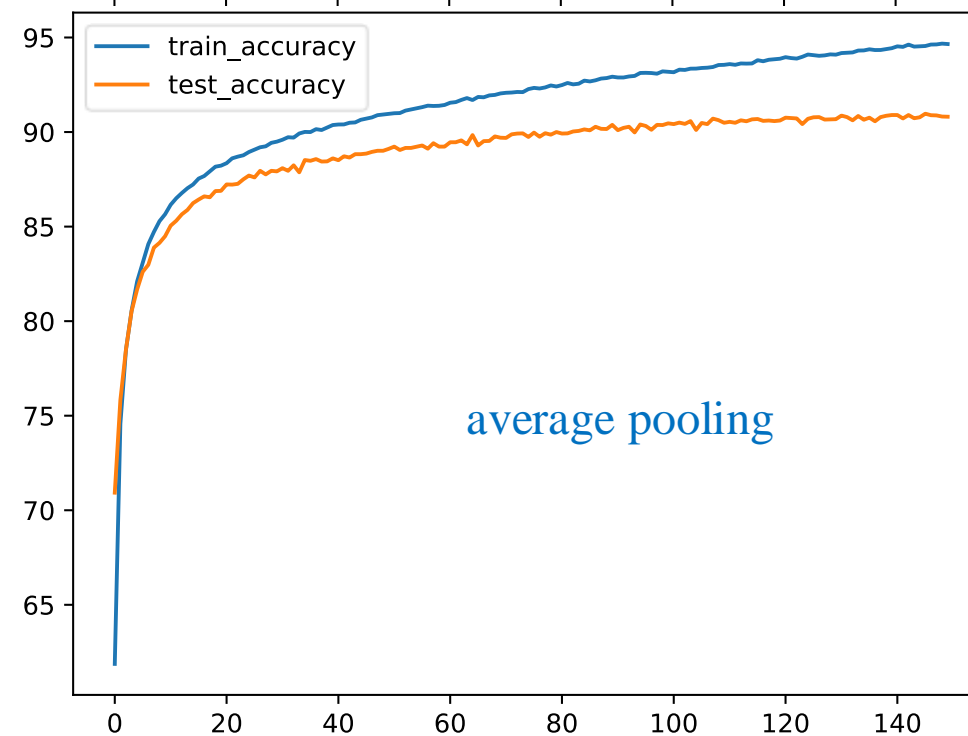
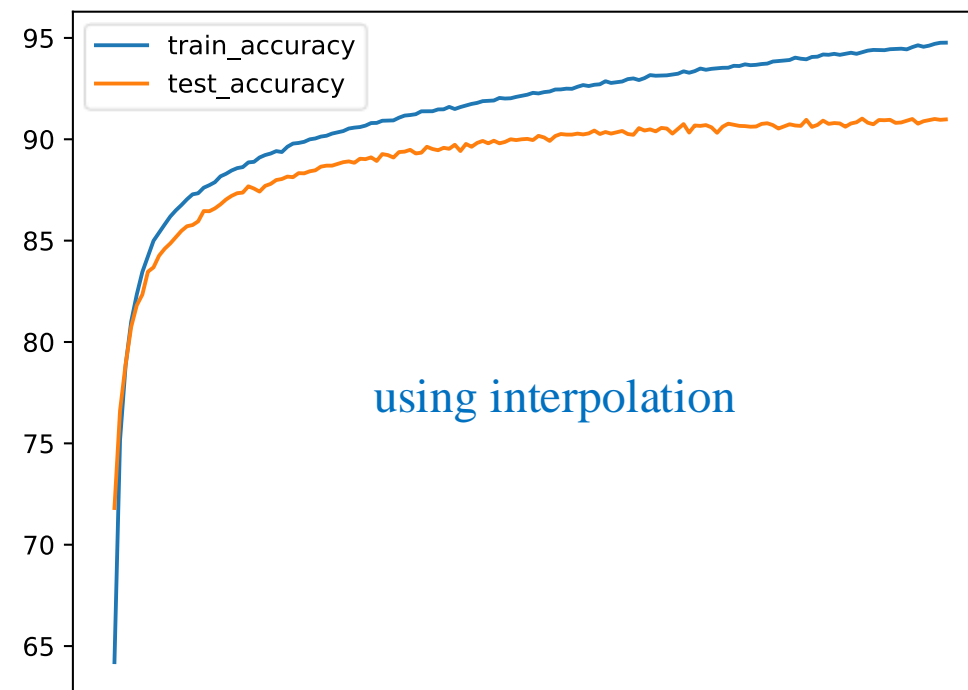
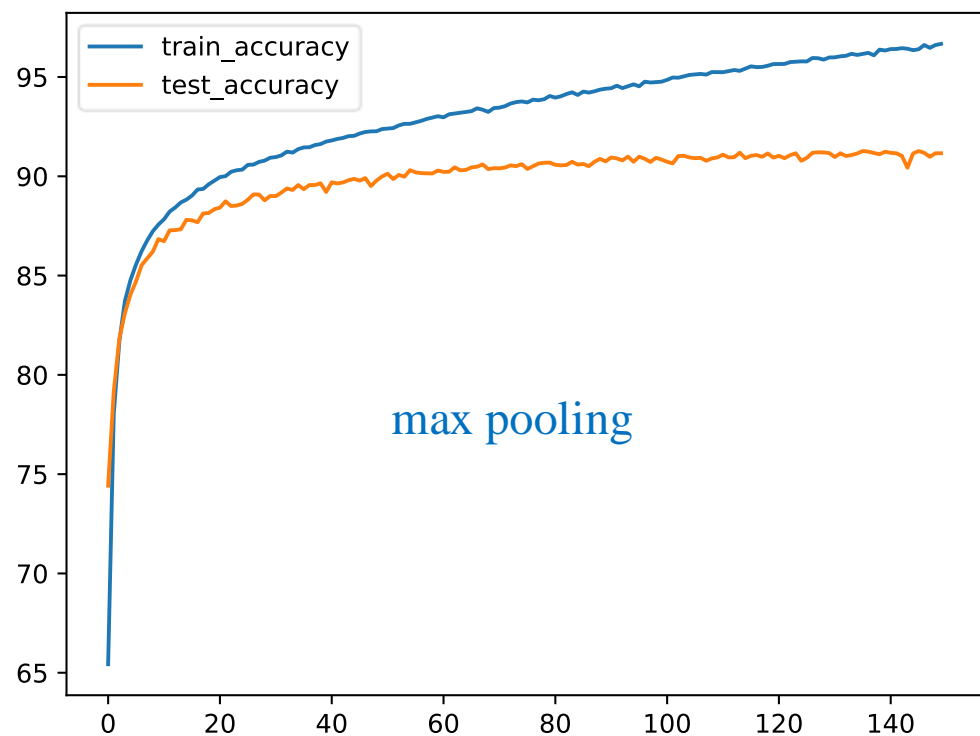
    def forward(self, x):
        return F.interpolate(x, scale_factor=self.scale_factor,
                              mode=self.mode,
                              align_corners=self.align_corners)

class CustomModel(nn.Module):
    def __init__(self):
        super(CustomModel, self).__init__()
        self.conv = nn.Conv2d(1, 32, kernel_size=5)
        self.resize = ResizeLayer(0.5)
        self.flatten = nn.Flatten()
        self.dense1 = nn.Linear(12*12*32, 128)
        self.dense2 = nn.Linear(128, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.relu(self.conv(x))
        x = self.resize(x)
        x = self.flatten(x)
        x = self.relu(self.dense1(x))
        x = self.dense2(x)
        return x
```

interpolation

# Comparison of down-samplings



# Down-sample Feature Map

❖ Convolve with stride

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

Data **D**

$w_1$	$w_2$	$b$
$w_3$	$w_4$	

Kernel of parameters

Convolve **D**  
with stride=1

$m_1$	$m_2$	$m_3$
$m_4$	$m_5$	$m_6$
$m_7$	$m_8$	$m_9$

Output

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

# Down-sample Feature Map

## ❖ Convolve with stride

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

Data **D**

$w_1$	$w_2$	$b$
$w_3$	$w_4$	

Kernel of parameters

Convolve **D**  
with stride=2

$m_1$	$m_2$
$m_3$	$m_4$

Output

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

```
nn.Conv2d(in_channels, out_channels, kernel_size, stride=1)
```

```
nn.Conv2d(in_channels, out_channels, kernel_size, stride=2)
```

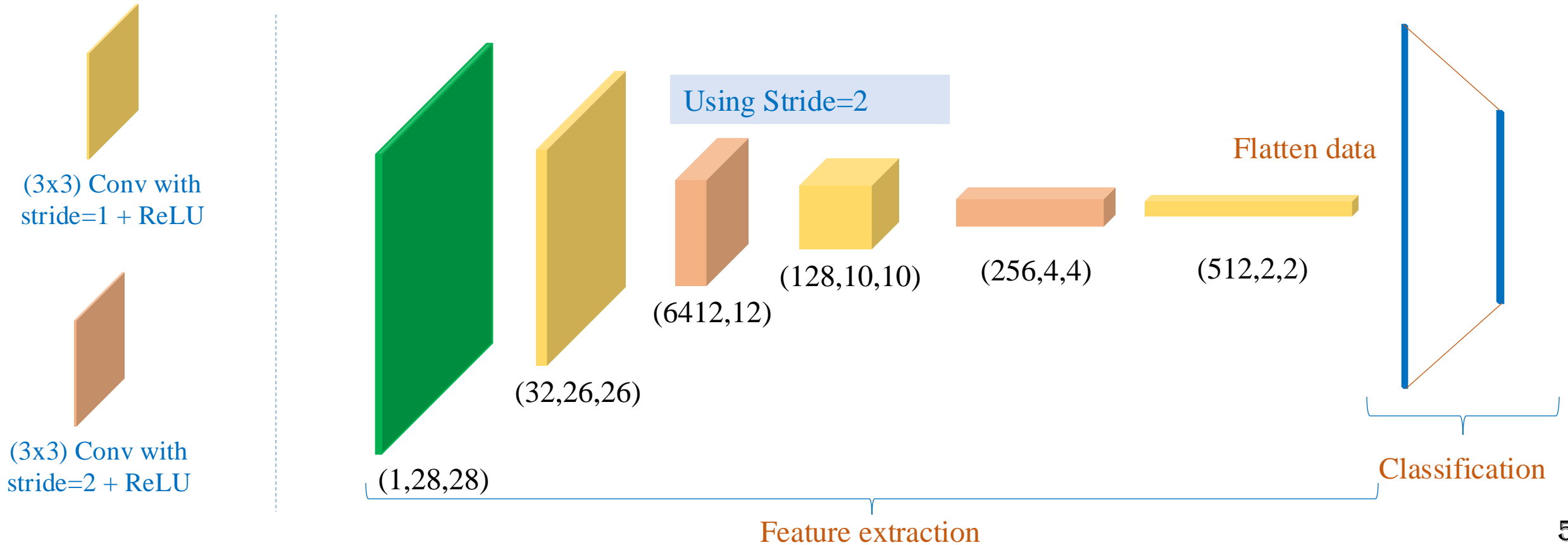


```
class CustomModel(nn.Module):
    def __init__(self):
        super(CustomModel, self).__init__()
        self.conv1 = nn.Conv2d(1, 32, kernel_size=3)
        self.conv2 = nn.Conv2d(32, 64, kernel_size=3, stride=2)
        self.conv3 = nn.Conv2d(64, 128, kernel_size=3)
        self.conv4 = nn.Conv2d(128, 256, kernel_size=3, stride=2)
        self.conv5 = nn.Conv2d(256, 512, kernel_size=3)
        self.relu = nn.ReLU()
        self.flatten = nn.Flatten()
        self.dense = nn.Linear(2*2*512, 10)
```

```
def forward(self, x):
    x = self.relu(self.conv1(x))
    x = self.relu(self.conv2(x))

    x = self.relu(self.conv3(x))
    x = self.relu(self.conv4(x))

    x = self.relu(self.conv5(x))
    x = self.flatten(x)
    x = self.dense(x)
    return x
```



# Padding

$$S_o = \left\lfloor \frac{S_D - K + 2P}{S} \right\rfloor + 1$$

Keep resolution of feature map

$v_1$	$v_2$	$v_3$	$v_4$
$v_5$	$v_6$	$v_7$	$v_8$
$v_9$	$v_{10}$	$v_{11}$	$v_{12}$
$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$

Data  $D$   
(4x4)

$w_1$	$w_2$	$w_3$
$w_4$	$w_5$	$w_6$
$w_7$	$w_8$	$w_9$

$b$

Kernel of parameters

Without using padding  
or padding=0

Convolve with stride=1 ( $D$ ) =

$m_1$	$m_2$
$m_4$	$m_5$

Output  
(2x2)

Padding = 1

$v$	$v$	$v$	$v$	$v$	$v$
$v$	$v_1$	$v_2$	$v_3$	$v_4$	$v$
$v$	$v_5$	$v_6$	$v_7$	$v_8$	$v$
$v$	$v_9$	$v_{10}$	$v_{11}$	$v_{12}$	$v$
$v$	$v_{13}$	$v_{14}$	$v_{15}$	$v_{16}$	$v$
$v$	$v$	$v$	$v$	$v$	$v$

Data  $D_p$

Convolve with stride=1 ( $D_p$ ) =

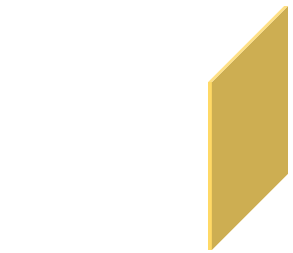
$m_1$	$m_2$	$m_3$	$m_4$
$m_5$	$m_6$	$m_7$	$m_8$
$m_9$	$m_{10}$	$m_{11}$	$m_{12}$
$m_{13}$	$m_{14}$	$m_{15}$	$m_{16}$

Output  
(4x4)

# Padding

```
model = nn.Sequential(  
    nn.Conv2d(1, 32, kernel_size=3, padding='same', stride=1), nn.ReLU(),  
    nn.Conv2d(32, 64, kernel_size=3, padding=1, stride=2), nn.ReLU(),  
    nn.Conv2d(64, 128, kernel_size=3, padding=1, stride=1), nn.ReLU(),  
    nn.Conv2d(128, 256, kernel_size=3, padding=1, stride=2), nn.ReLU(),  
    nn.Conv2d(256, 512, kernel_size=3, padding=1, stride=1), nn.ReLU(),  
    nn.Flatten(), nn.Linear(7*7*512, 10)  
)
```

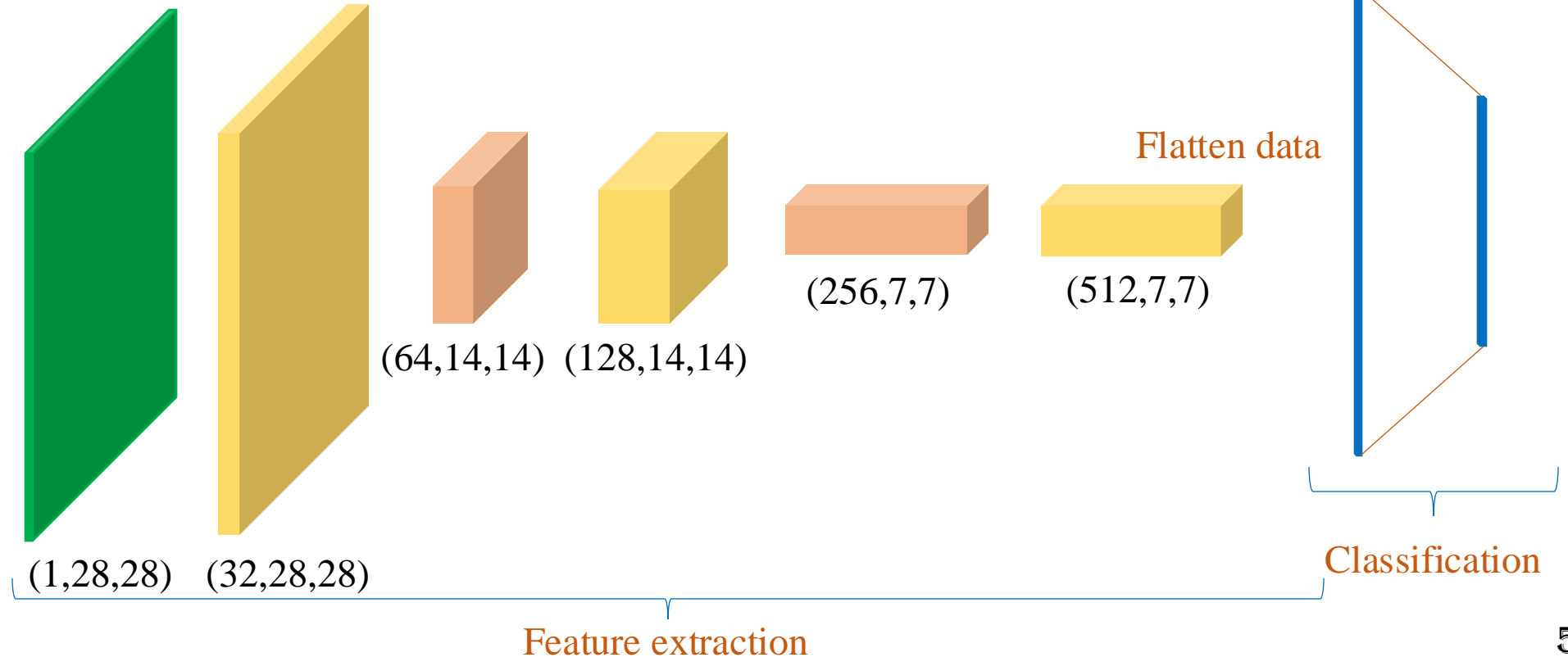
## ❖ Example



(3x3) Conv with stride=1,  
padding='same' + ReLU



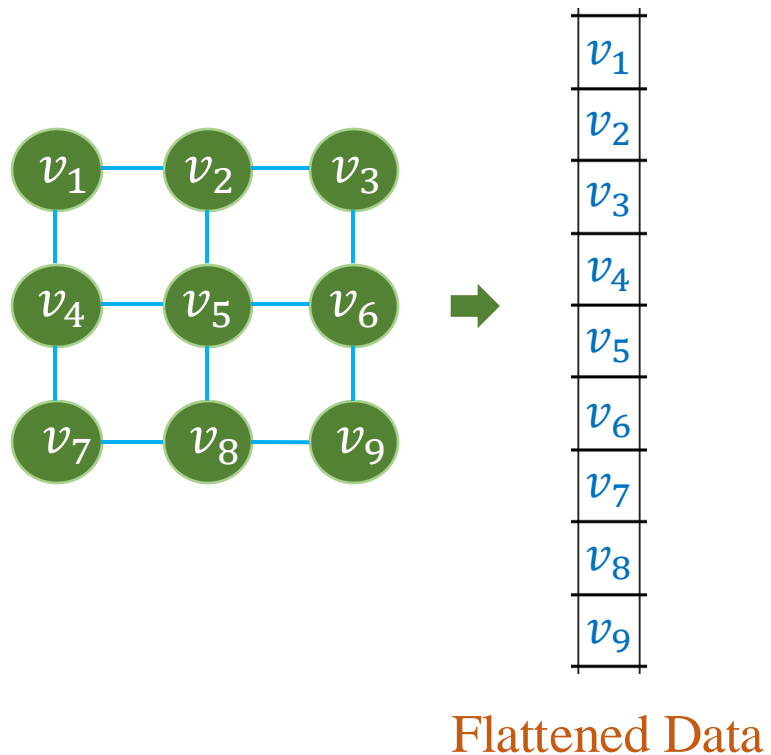
(3x3) Conv with stride=2,  
padding='same' + ReLU



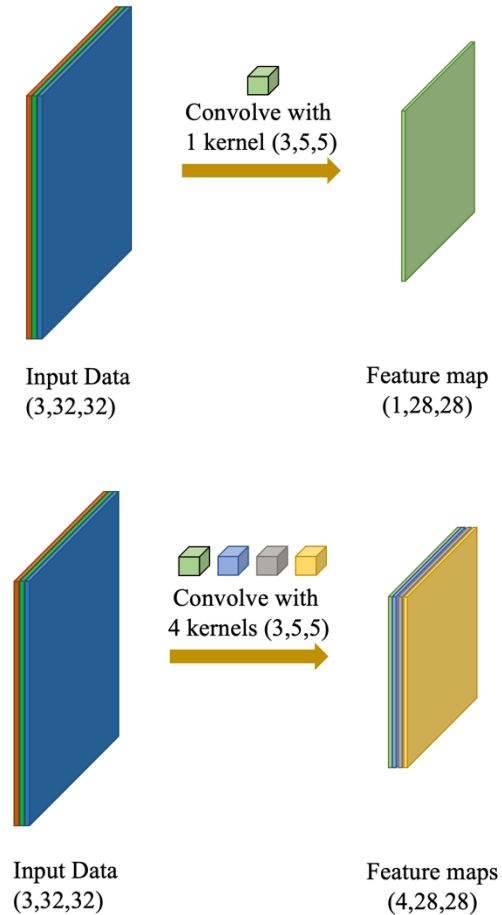


# Summary

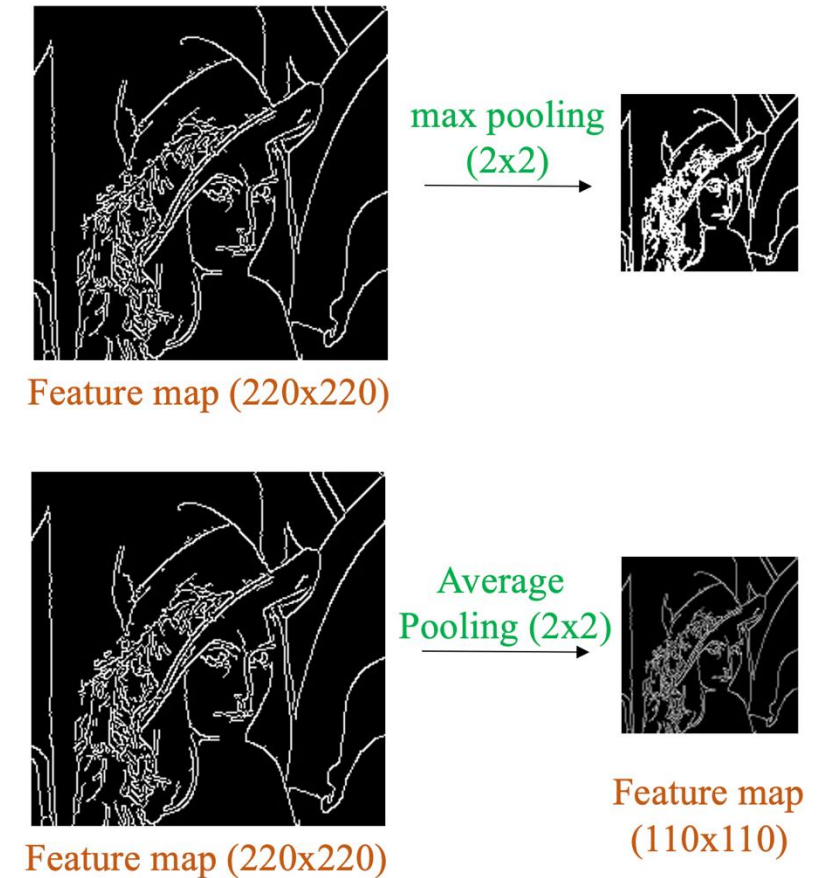
## MLP Limitations



## Convolutional Layer



## Standard CNNs



## ❖ Reading

<https://cs231n.github.io/convolutional-networks/>

<https://towardsdatascience.com/a-comprehensive-guide-to-convolutional-neural-networks-the-eli5-way-3bd2b1164a53>

<https://stanford.edu/~shervine/teaching/cs-230/cheatsheet-convolutional-neural-networks>

