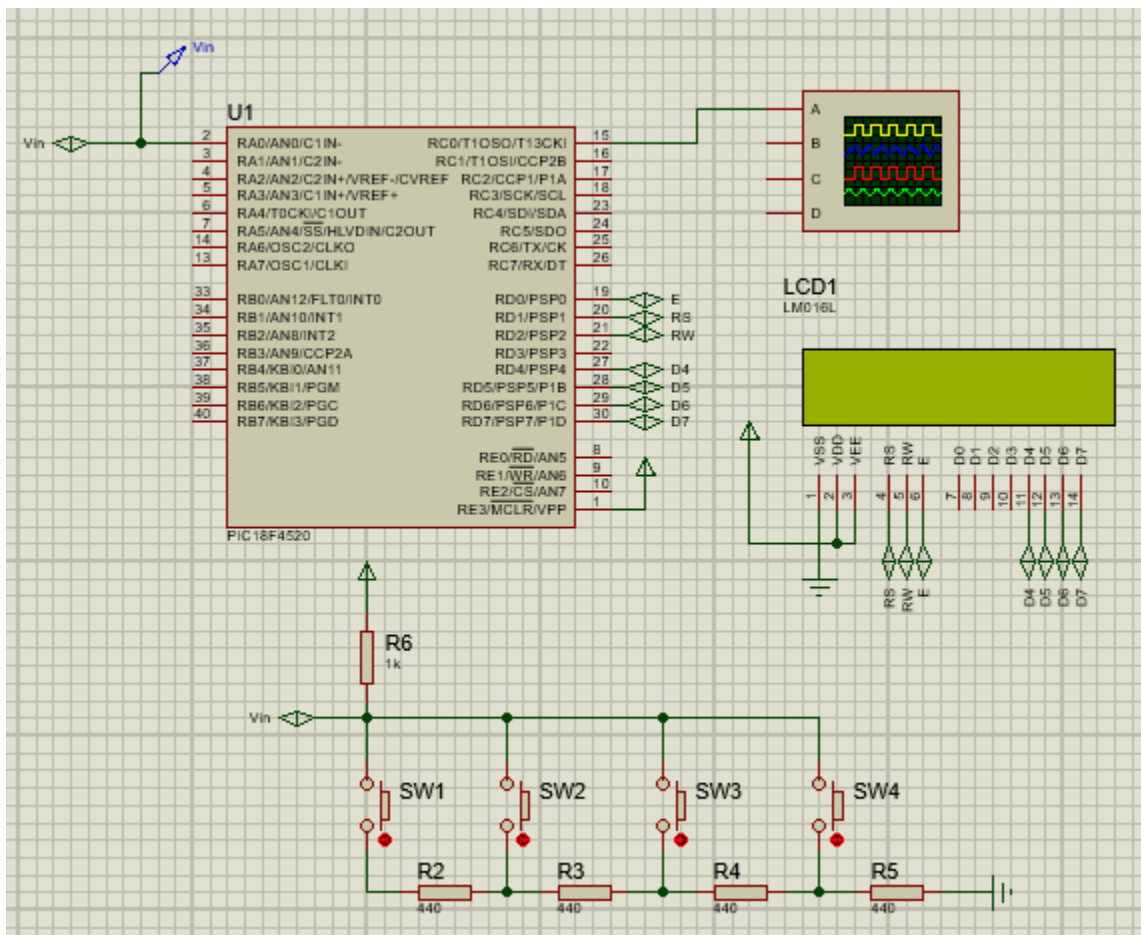
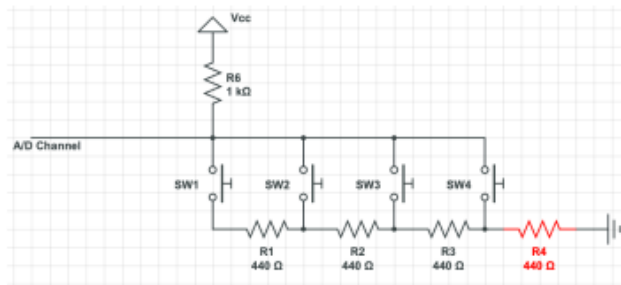


The Microchip PIC 18F4520 has several interruptible TIMER overflow circuits. In class we covered TIMER 0 and TIMER 1 overflow circuits and the mathematics that dominate the circuits.

Design a C program for the 18F4520 capable of determining which push button was pressed based on a single analog measurement.



```

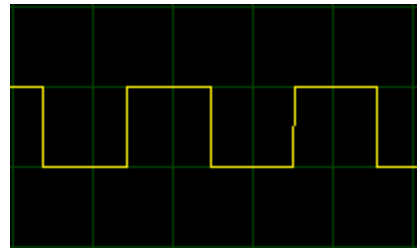
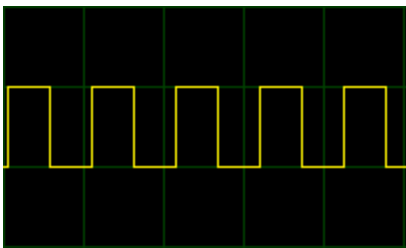
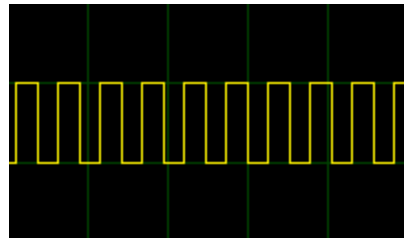
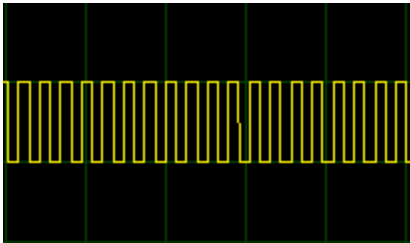
1  #include <18f4520.h>
2  #use delay (clock = 20000000)
3  #fuses HS, NOWDT, NOLVP
4  #include "../Library/myLibrary.h"
5  #include "../Library/modifiedlcd.h"
6
7  float Vin = 0;
8
9  #INT_AD
10 void int_ad_isr() {
11     Vin = *Q * (5.0 / 1023.0 );
12 }
13
14 #INT_TIMER1
15 void int_timer1_isr() {
16     *LATC ^= 0x01;
17 }
18
19 main(){
20     // Initialize LCD
21     lcd_init();
22
23     // Analog setup
24     *TRISA = 0x01;
25     ADCON1 -> PCFGx = 0xE;
26     ADCON0 -> ADON = 1;
27     ADCON0 -> CHSx = 0;    // Channel 0
28     ADCON1 -> VCFG0 = 0;
29     ADCON1 -> VCFG1 = 0;
30     ADCON2 -> ADFM = 1;    // Right Justified
31     ADCON2 -> ACQTx = 5;
32     ADCON2 -> ADCSx = 5;
33
34     // Timer 1 setup
35     *TRISC = 0x00;
36     T1CON -> TMR1ON = 1;
37     T1CON -> TMR1CS = 0;
38     T1CON -> T1OSCEN = 0;
39     T1CON -> T1CKPSx = 0;
40     PIE1 -> TMR1IE = 1;
41
42     // Interrupt setup
43     PIE1 -> ADIE = 1;
44     INTCON -> PEIE = 1;
45     INTCON -> GIE = 1;
46

```

```

46
47 while(1){
48     ADCON0->GODONE=1;    // Trigger
49     delay_ms( 250 );
50
51     if( Vin > 3.18 && Vin < 3.20 ) {
52         printf(lcd_putc, "\fSW1 - 1:1");
53         T1CON -> T1CKPSx = 0;
54     }
55     else if( Vin > 2.80 && Vin < 2.90 ) {
56         printf(lcd_putc, "\fSW2");
57         T1CON -> T1CKPSx = 1;
58     }
59     else if( Vin > 2.30 && Vin < 2.40 ) {
60         printf(lcd_putc, "\fSW3");
61         T1CON -> T1CKPSx = 2;
62     }
63     else if( Vin > 1.50 && Vin < 1.60 ) {
64         printf(lcd_putc, "\fSW4");
65         T1CON -> T1CKPSx = 3;
66     }
67     else {
68         printf(lcd_putc, "\fPush somethin'");
69         T1CON -> T1CKPSx = 0;
70     }
71 }
72 }
73

```



SW1 = 1:1 Prescaler

$$T_{1C} = \frac{4*1}{20MHz} = 0.2\mu S$$

$$T_{1F} = 2^{16} * 0.2\mu S = 13.1\mu S$$

$$T_{GPIO} = 2 * 13.1\mu S = 26.2\mu S$$

SW2 = 1:2 Prescaler

$$T_{1C} = \frac{4*2}{20MHz} = 0.4\mu S$$

$$T_{1F} = 2^{16} * 0.4\mu S = 26.2\mu S$$

$$T_{GPIO} = 2 * 26.2\mu S = 52.4\mu S$$

SW3 = 1:4 Prescaler

$$T_{1C} = \frac{4*4}{20MHz} = 0.8\mu S$$

$$T_{1F} = 2^{16} * 0.8\mu S = 52.4\mu S$$

$$T_{GPIO} = 2 * 52.4\mu S = 104.8\mu S$$

SW4 = 1:8 Prescaler

$$T_{1C} = \frac{4*8}{20MHz} = 1.6\mu S$$

$$T_{1F} = 2^{16} * 1.6\mu S = 104.8\mu S$$

$$T_{GPIO} = 2 * 104.8\mu S = 209.7\mu S$$

This math is my own work.