Assignment 1

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Table of Contents

```
Table of Contents
Problem Formulation
   State
   Initial state
   <u>Actions</u>
   Transition model
   Goal test
   Path cost
GitHub Repository
Explanation
   <u>H3</u>
   Milestone 1
   Milestone 2
   Result
Analysis
   Python List Implementation
   Heapq Implementation
   Comment
Appendix
   Code
       Actions.py
       Analytics.py
       AstarSearch.py
       Generator.py
       Heuristics.py
       Node.py
       Problem.pv
       main.py
   Results
       8 Puzzle
       15 Puzzle
       24 Puzzle
References
```

Problem Formulation

State

s: [] * 9

Represent the 8-puzzle, such that 8/9 tiles must have number 1-8, and 1 blank tile

Initial state

si = any: s

Actions

a: {U, D, L, R}

Represent up, down, left, right respectively

Transition model

Let xs: s = current state Let xa: a = current action

U(xs): move tile below blank space up D(xs): move tile above blank space down L(xs): move tile right of blank space left R(xs): move tile left of blank space right Result(xs, xa): s with tiles moved accordingly

Goal test

sg = [1,2,3,4,5,6,7,8,nil]

1	2	3
4	5	6
7	8	

Path cost

Let xy: s = result state Cost(xs, xa, xy) = 1

GitHub Repository

See here: https://github.com/TheChroniclerr/CP468/

Explanation

H3

Our h3 was implemented using Euclidean distance. It is similar to Manhattan distance, except it calculates the actual geometric distance by using the Pythagorean theorem between the current state coordinates and goal state coordinates and sums them up. This is slightly worse than Manhattan and a lot better than Misplaced Tiles. Manhattan **dominates** Euclidean as Euclidean represents the direct distance, and Manhattan represents the components of that distance, so Manhattan will yield larger h(n) most of the time by the rule of Triangular Inequality.

Milestone 1

Initially, the code was implemented using list and list.sort() (see here). It was extremely problematic as it is too slow and could not run in most cases. It was also implemented before timeouts, so it was impossible to determine whether the endless running was due to a bug or actual timeout.

To prove that the implementation was correct, we did some performance tests and calculations. In a 10-second execution of that version, 3865 nodes were expanded, that is a rate of 386.5 nodes/second.

Note that without backtracking, even cases that are not that deep (i.e. have many steps for the optimal solution) can potentially expand a huge amount of nodes. This is due to the heuristics—including Manhattan—not finding the optimal expansion, and numerous suboptimal nodes expanded into dead ends, wasting computation power.

In which case, the largest 8-puzzle can expand up to 9!/2 = 362,800 = 181400 nodes. 181,400 nodes / 386.5 $n/sec \approx 469$ sec/60 $sec/min \approx 8$ minutes.

Although by remaining at a fixed computation rate, it can complete any 8-puzzle in up to 8 minutes, in practice it takes a lot longer. That is because the size of the frontier becomes larger and larger, and sorting takes longer and longer after each iteration. At one point, the program just runs into a choking point where it essentially "stops" running. We were able to verify this by leaving one process running for over 30 minutes, where instead of finishing, only 40k nodes were expanded.

This becomes problematic as for most instances, it seems the code either finishes running in <1 second or never finishes running - it is hard to tell whether it is because the instance is taking too long to run or if it is just bugged. At that point, we needed a **proof of concept** to verify that our code indeed still works for medium-sized expansions, confirming our theory that the unending execution is not actually a bug, but just an instance that requires an overly large number of expansions.

After many runs of the program. We found a good instance: [1, 5, 4, 2, None, 3, 6, 8, 7]. It expanded ~10k nodes for Euclidean and Manhattan and ~15k for Misplaced Tiles. This takes 2–3 seconds to run. This instance was a milestone for us, as it increased our confidence that our code was indeed not bugged.

386.5/second for 9! = 362800 cases, that would take approximately $1000sec/(60~sec/min) \approx 15.6~minutes$. So the deepest would take about 15–17 minutes, whereas the shallowest of (ideally) 24 steps would take 0 seconds.

Milestone 2

The performance of our code is drastically improved with the utilization of "heapq" for sorting f(n)—or we could've simply chosen to not use Python, but oh well. The reason being "heapq" uses hashes that drastically improves the average case time complexity, as we will talk about later in section "Analysis". Here, let's calculate the performance of our most recent version shared in "Code".

After a brief testing, in 2 seconds, it produced 61773, 49462, 48723 node expansions for Misplaced Tiles, Manhattan, and Euclidean respectively. Rounding it to 50k, we get 25k nodes/second. 25000 nodes/second / 386.5 nodes/second ~65. In other words, **heapq is 65x faster than list sort**. In 10 seconds, heapq can expand 250k nodes - that is enough to fully complete the 8-puzzle.

However, even this also hits a limit for larger puzzles, as evident from the TIMEOUT indicated in our CSV file results.

Note here, we also implemented a timeout function after becoming aware that there can be instances where even heapy will take forever.

Our next milestone is reached where for a generateRandom(5, 70, 70) (i.e. 24-puzzle generated by randomly scrambling 70 times) and a timeout of 5 seconds, only 1/100 instance failed (surpassing timeout period): [1, 3, 8, 15, 5, 6, 2, 19, 14, 10, 11, 7, 4, 18, 20, 16, 12, 13, None, 9, 21, 17, 22, 23, 24].

However, heapq is not the limit. The performance can be further improved by reducing other bottlenecks in the code, such as deepcopy(). Lastly, coding in a faster language such as C can result in even better performance.

Result

Our result is generated by a timeout of 5 seconds for scrambling 70 times, 100 times, and 70 times for 8, 15, and 24 puzzle respectively. These results are then stored in a CSV file.

The "TIMEOUT" indicates a timeout, where the code was not able to attain a result in 5 seconds. Of course, I did not notate ># here because it should be self-evident. Given 25k nodes/second from our calculation before, then 5*25k = 125k. Anything with a timeout likely reached at least >125k node expansions. This would be quite common for Misplaced Tiles.

The "step" in our result is calculated from getting the total amount of states passed from initial to goal state. This is actually 1 more than the path cost, as it does not take 1 step for the initial state to get to itself. For our result, we had it with +1.

Analyzing our result, we can see that all of our steps are odd. That makes sense, as our generator value in main.py actually scrambles 70, 100, 70 times respectively where the scramble does not shift back to the previous state. The parity of the moves should be the same as the parity of the steps. However, since in our case we have +1, then the parity would be opposite.

The difference between the three heuristics is negligible at the start, but grows over time. Misplaced Tiles seem to have as much as over 10x more nodes expanded by Manhattan. On the other hand, the difference between Manhattan and Euclidean is much smaller, where the difference only becomes more prominent reaching the 4th digit.

Going up to 15-puzzle, we saw that timeout starts occurring for Misplaced Tiles, starting at depth 27; whereas it starts at depth 37 for Euclidean; and for Manhattan, it went all the way to 43, and still hasn't timed out.

The disparity between nodes expanded for the same depth seems to become much greater for larger puzzle sizes. This means the heuristic becomes much less accurate and therefore has worse predictability for larger puzzles.

In the 24-puzzle for much larger values, the advantage of Manhattan became much more apparent. Take [1, 7, 2, 4, 5, 6, 3, 14, 8, 10, 16, 13, 12, 9, 18, 21, 11, 24, None, 15, 22, 23, 17, 20, 19], it has 291, 1919, 165250 nodes expanded for Manhattan, Euclidean, and Misplaced Tiles respectively. In which case, Manhattan expanded 6.5x less node than Euclidean and 568x less node than Misplaced Tiles.

Analysis

Python List Implementation

This is the time complexity calculated for the implementation described in "Milestone 1". Here, we use a Python list to implement the queue.

- 1. Node with optimal f(n) popped from queue
- 2. Node Expanded
- 3. For each expanded node
 - a. Solve for f(n)
 - b. Insert back to queue
- 4. Sort queue by f(n)
- 5. Repeat back to 1.

Let s be the state space (all reachable states). For a*a-puzzle, the state space is a!/2. Let P be the size of the puzzle. O(P) can be considered O(1) since puzzle have fixed sizes.

Node expansion (2.) - O(1)

- Find valid actions find blank space O(P) + simple algebraic calculations O(1) = O(1)
- Shift = O(1)

f(n) calculation (3a.) - O(1)

- g(n) path so far + action cost (in this case 1) = O(1)
- h(n) O(P) = loop through tiles = O(1)
- g(n) + h(n) simple addition = O(1)

Queue operations (Python list)

- Insert (3b.) = O(1)
- Pop (1.) pop from front of queue have to shift the whole data structure = O(s)
- Sort queue (4.) sort in general takes O(n log n). In this problem, it sorts a frontier queue that can have up to the size of state space = O(s log s)

Loop (5.) - looping through everything described above O(s) * the sort operation that is bottleneck inside the loop $O(s \log s) = O(s^2 \log s)$

Heapq Implementation

Heapq improves performance as it is an ordered data structure. Instead of sorting, it amortizes the cost by inserting into and retrieving from an ordered structure via search.

- 1. Node with optimal f(n) popped from heapq
- 2. Node Expanded

CP468-A1-Group10 15/10/2025

- 3. For each expanded node
 - a. Solve for f(n)
 - b. Insert back to heapq, auto sort
- 4. Repeat back to 1.

Heapq operations

- Retrieve binary search O(log s) + retrieval O(1) = O(log s)
- Insert binary search for insertion spot O(log s) + insert O(1) = O(log s)

Loop (5.) - looping through is again O(s) * amortized bottleneck $O(\log s) = O(s \log s)$

Comment

 $O(s log s) < O(s^2 log s)$

Here, we see that implementing heapq improved the Time Complexity significantly. This is evident from our performance calculation, resulting in a 65x improved rate.

This is important because by running the code ourselves, we can see an actual physical difference in running time between these implementations, demonstrating that theoretical concepts such as Time Complexity can have real and tangible differences.

Appendix

Code

We have created 8 py files to work with. They are as follows:

```
Actions.py
The code reads as follows:
 import math
from copy import deepcopy
 from typing import Literal
ActionsType = Literal["U", "D", "L", "R"]
 class Actions:
     def __init__(self, s: list) -> None:
         """Class constructor.
         Args:
             s (list): State to perform action to.
         assert s and isinstance(s, list) and math.sqrt(len(s)).is_integer(), "Invalid
 puzzle size."
         self.s = s
         self.width: int = int(math.sqrt(len(s))) # get the n of n-puzzle (n by n)
         self.blankPos: int | None = self._findBlankTileIndex() # index of blank tile
         assert self.blankPos != -1, "Invalid puzzle, no blank tile."
         self.validActions: list[str] = self. findValidActions() # list of valid
 actions
     def result(self, a: ActionsType) -> list | None:
         """Transition Model - Alternative method of action call using ActionType
 keys.
         Args:
             a (ActionsType): A valid type of action.
         Returns:
             list | None: Return list if move successful, else None.
```

```
actionsMap: dict = {
        "U": self.up,
        "D": self.down,
        "L": self.left,
        "R": self.right
    }
    return actionsMap[a]()
def up(self) -> list | None:
    """Action - Move the tile below the blank tile upwards.
    Returns:
        list | None: Return list if move successful, else None.
    if "U" in self.validActions:
        newS: list = deepcopy(self.s)
        self._shiftTile(newS, self.blankPos + self.width)
        return newS
    return None
def down(self) -> list | None:
    """Action - Move the tile above the blank tile downward.
    Returns:
        list | None: Return list if move successful, else None.
    ....
    if "D" in self.validActions:
        newS: list = deepcopy(self.s)
        self._shiftTile(newS, self.blankPos - self.width)
        return newS
    return None
def left(self) -> list | None:
    """Action - Move the tile right of the blank tile leftward.
    Returns:
        list | None: Return list if move successful, else None.
    if "L" in self.validActions:
        newS: list = deepcopy(self.s)
        self._shiftTile(newS, self.blankPos + 1)
        return newS
```

```
return None
def right(self) -> list | None:
    """Action - Move the tile left of the blank tile rightward.
    Returns:
        list | None: Return list if move successful, else None.
    if "R" in self.validActions:
        newS: list = deepcopy(self.s)
        self. shiftTile(newS, self.blankPos - 1)
        return newS
    return None
def _shiftTile(self, newS: list, srcPos: int) -> list:
    """Shift the tile in the desired direction.
    Shift from a copy of the puzzle.
    Args:
        newS (list): A copy to shift from.
        srcPos (int): Index of tile to be shifted.
    Returns:
        list: Final state.
    newS[self.blankPos], newS[srcPos] = newS[srcPos], None
    return newS
# Configuration functions
def findBlankTileIndex(self) -> int:
   """Find the blank tile in the n-puzzle.
    Returns:
        int: Index of the blank tile.
    for i, tile in enumerate(self.s):
        if tile is None:
            return i
    return -1
def _findValidActions(self) -> list:
    """Check if it is possible to move up/down/left/right.
```

```
Returns:
    list: All valid actions.
"""

validActions: list = [];

if 0 <= self.blankPos + self.width < len(self.s): validActions.append("U")

# check bottom
    if 0 <= self.blankPos - self.width < len(self.s): validActions.append("D")

# check top
    if (self.blankPos % self.width) != 0: validActions.append("R") # check Left
    if (self.blankPos % self.width) != (self.width - 1): validActions.append("L")

# check right</pre>
```

return validActions

Analytics.py

```
The code reads as follows:
 import os
import csv
from Problem import Problem # type hint
DEFAULT_DIR: str = "a1/output"
 FILENAMES: dict = {
    9: "/8_Puzzle.csv",
    16: "/15 Puzzle.csv",
    25: "/24 Puzzle.csv"
 }
CSV HEADER: list = [
     "initial_state", "h1_steps", "h1_expanded", "h2_steps", "h2_expanded",
 "h3_steps", "h3_expanded"
 class Analytics:
    def init (self, problem: Problem):
        self.initialState: str = str(problem.initialState)
        # self.filePointer # points to location in CSV
        self.fileDir: str = DEFAULT DIR +
 FILENAMES[len(problem.initialState)]
         self.data: list[dict] = self._loadExistingCSV() # a copy of
whole CSV data to modify and overwrite back to
         self.changes: dict = {  # record data to be added/changed, key
 - column name, value - stored data
            f"{problem.hTag}_steps": 0,
            f"{problem.hTag} expanded": 0
         }
    def recordSteps(self, steps: int) -> None:
        for key in self.changes:
             if "steps" in key:
                 self.changes[key] = steps
    def incrementNodesExpanded(self) -> None:
        for key in self.changes:
             if "expanded" in key:
                 self.changes[key] += 1
```

```
def writeCSV(self) -> None:
    # find record if already exists
    record = None
    for row in self.data:
        if row["initial_state"] == self.initialState:
            record = row
            break
    # create record if not exist, append to data
    if record is None:
        record = self._newRecord()
        self.data.append(record)
    # apply changes to data (using record) and overwrite CSV
    for columnName, newValue in self.changes.items():
        record[columnName] = newValue
    self._overwrite()
def newRecord(self) -> dict:
    record: dict = {
        "initial_state": self.initialState
    for h in ["h1", "h2", "h3"]:
        record[f"{h} steps"] = "TIMEOUT"
        record[f"{h}_expanded"] = "TIMEOUT"
    return record
def loadExistingCSV(self) -> list:
    if not os.path.exists(self.fileDir):
        with open(self.fileDir, 'w', newline='') as f:
            writer = csv.DictWriter(f, fieldnames=CSV HEADER)
            writer.writeheader()
        return []
    with open(self.fileDir, 'r', newline='') as f:
        reader = csv.DictReader(f)
        return list(reader)
def _overwrite(self) -> None:
    with open(self.fileDir, 'w', newline='') as f:
        writer = csv.DictWriter(f, fieldnames=CSV_HEADER)
```

writer.writeheader()
writer.writerows(self.data)

AstarSearch.py

```
The code reads as follows:
 import heapq
 import Problem
from Node import Node
from Analytics import Analytics
from Actions import Actions # type hint
def AstarSearch(problem: Problem) -> Node | None:
     """Using A^st search algorithm to solve the problem instances as graphs.
    Args:
        problem (Problem): The problem instance.
    Returns:
        Node: The node of the goal state.
    rootNode: Node = Node(problem.initialState, None, None, 0)
    frontierHeap: list[tuple[float, Node]] = [(problem.h(rootNode.state),
              # use heapq for performance
 rootNode)]
    visited: set = set() # hash-set to track visited nodes
    visited.add(tuple(problem.initialState)) # convert list to hashable
 tuple
    analytics: Analytics = Analytics(problem)
    while frontierHeap:
        _, currNode = heapq.heappop(frontierHeap)
        analytics.incrementNodesExpanded()
        # check if current state reached goal state
        if problem.reachGoal(currNode.state):
             analytics.recordSteps(len(Node.getAncestors(currNode)))
             analytics.writeCSV()
             return currNode
        currActions: Actions = problem.setAction(currNode.state)
        for actionName in currActions.validActions:
            # find new state
            newState: list | None = currActions.result(actionName)
            if newState is None:
                 continue
            # skip already visited node
```

return None

Generator.py

```
The code reads as follows:
 import random
blank = None
def isSolvable(state, n):
    a = [x for x in state if x != blank]
    inversions = 0
    for i in range(len(a)):
         for j in range(i + 1, len(a)):
             if a[i] > a[j]:
                 inversions += 1
    if n % 2 == 1:
         return inversions % 2 == 0
    else:
         blank i = state.index(blank)
         blank_distance_top = blank_i // n - 1
         blank_distance_bottom = n - blank_distance_top
         return (inversions + blank distance bottom) % 2 == 0
def allMoves(state, n):
    blank i = state.index(None)
    r, c = divmod(blank i, n)
    moves = []
    if r > 0:
        moves.append(-n) # up
    if r < n - 1:
         moves.append(n) # down
    if c > 0:
         moves.append(-1) # Left
    if c < n - 1:
         moves.append(1) # right
    return moves
```

```
def doMove(state, move):
    new_state = state.copy()
    blank i = new state.index(None)
    target_index = blank_i + move
    new_state[blank_i], new_state[target_index] = (
        new state[target index],
        new_state[blank_i],
    )
    return new_state
def generateRandom(n: int, min: int, max: int) -> list:
    """Generate a random nxn-Puzzle in a []*n list.
    Args:
        n (int): The size of the puzzle; nxn
        min (int): The minimum shifts from original puzzle
        max (int): The maximum shifts from original puzzle
    Returns:
        list: The generated puzzle
    rand = random.randint(min, max)
    state = [i for i in range(1, n * n)] + [blank]
    for i in range(rand):
        moves = allMoves(state, n)
        move = random.choice(moves)
        state = doMove(state, move)
    return state
# #testing
\# n=3
# min=20
# max=40
# state = [i for i in range(1, n*n)] + [blank]
# print("3x3:",isSolvable(state,n))
\# state = [i for i in range(1, 7)] + [8] + [7] + [blank]
```

```
# print("3x3:",isSolvable(state,n))
# state=generateRandom(n,min,max)
# print("3x3:",isSolvable(state,n))
# print(state)
# n=4
# state = [i for i in range(1, n*n)] + [blank]
# print("4x4:",isSolvable(state,n))
# state = [i \text{ for } i \text{ in } range(1, 14)] + [15] + [14] + [blank]
# print("4x4:",isSolvable(state,n))
# state=generateRandom(n,min,max)
# print("4x4:",isSolvable(state,n))
# print(state)
# n=5
# state = [i for i in range(1, n*n)] + [blank]
# print("5x5:",isSolvable(state,n))
# state = [i for i in range(1, 23)] + [24] + [23] + [blank]
# print("5x5:",isSolvable(state,n))
# state=generateRandom(n,min,max)
# print("5x5:",isSolvable(state,n))
# print(state)
```

```
Heuristics.py
```

```
The code reads as follows:
 import math
from typing import Literal, Callable
Type = Literal["h1", "h2", "h3"]
def h1(s: list, g: list) -> int:
     """Heuristic - estimate true cost from current state to goal state via
 number of misplaced tiles.
    Args:
         s (list): Current state.
         g (list): Goal state.
    Returns:
         int: Number of misplaced tiles.
    # current state must be a list, and list must have size = n*n, for
    assert type(s) == list and math.sqrt(len(s)).is integer() , "Invalid
heuristic."
    misplacedTiles: int = 0
    for i in range(0, len(s)):
         misplacedTiles += 1 if s[i] != g[i] else 0
    return misplacedTiles
def h2(s: list, g: list) -> int:
     """Heuristic - estimate true cost from current state to goal state via
total Manhattan distance.
    Manhattan distance is the sum of the distances of the tiles from their
goal positions.
    Args:
         s (list): Current state.
         g (list): Goal state.
    Returns:
         int: total Manhattan distance
```

```
return int(_findSumOfDists(s, g, lambda currRow, currCol, goalRow,
             # Manhattan distance formula
        abs(currRow - goalRow) + abs(currCol - goalCol)
    ))
def h3(s: list, g: list) -> float:
    """Heuristic - estimate true cost from current state to goal state via
total Euclidean distance.
    Euclidean distance is the distance between two points (current state &
goal state in this case) in Euclidean space.
   Args:
        s (list): Current state.
        g (list): Goal state.
    Returns:
        int: Euclidean distance
    return findSumOfDists(s, g, lambda currRow, currCol, goalRow, goalCol:
# Euclidean distance formula
        math.dist((currRow, currCol), (goalRow, goalCol))
    )
def _findSumOfDists(s: list, g: list, getDist: Callable) -> int | float:
    """Auxillary function, find the sum of distances by the type of
distance calculation used.
    Args:
        s (list): Current state.
        g (list): Goal state.
    Returns:
        int: Total distance.
    assert type(s) == list and math.sqrt(len(s)).is_integer() , "Invalid
heuristic."
    totalDistance: int = 0
    width: int = int(math.sqrt(len(s))) # qet the n of n-puzzle (n by n)
    indexMap: list = _createIndexMap(g)
    for currPos, tileNum in enumerate(s):
```

```
if tileNum is None: continue
       goalPos: int = indexMap[tileNum]
       # find the x/y position of s and g, then calculate the Manhattan
distance
       currRow, currCol = divmod(currPos, width)
       goalRow, goalCol = divmod(goalPos, width)
       totalDistance += getDist(currRow, currCol, goalRow, goalCol)
   return totalDistance
def createIndexMap(s: list) -> list:
   """Auxillary function, map the tile number to its goal index.
   Let list key represent the tile number, and list value represent the
goal index.
   Args:
       s (list): Goal state.
   Returns:
       list: Index map.
   indexMap: list = [None] * (len(s) + 1) # index position 0 is not
used, since tile number starts on 1
   for goalPos, tileNumb in enumerate(s):
       if tileNumb is None: continue
       indexMap[tileNumb] = goalPos  # goalPos start at 0
   return indexMap
Function: dict[str, Callable] = {
    "h1": h1,
    "h2": h2,
    "h3": h3
}
```

Node.py

The code reads as follows: class Node: def __init__(self, state: any, parent: any, action: str | None, pathCost: int = 1) -> None: """Node constructor Args: state (any): Current state. parent (any): Parent node. action (str | None): Action parent node took to reach current state, None for root node. pathCost (int, optional): g(n) - the cost from initial state to current state. Defaults to 1. self.state = state self.parent = parent self.action = action self.pathCost = pathCost # q(n)def str_(self) -> str: return f"Node(state={self.state}, action={self.action}, pathCost={self.pathCost})" def lt (self, other): return self.pathCost < other.pathCost</pre> def getAncestors(self) -> list: """Retrieves all direct ancestors of current node. Returns: list: A list of direct ancestors ordered from ancestors to descendants. ancestors: list = [self] while ancestors[-1].parent: ancestors.append(ancestors[-1].parent)

return ancestors[::-1] # slice notation - reverse list

Problem.py

```
The code reads as follows:
 import Heuristics
from Actions import Actions
from typing import Callable
class Problem:
    def init (self, initialState: list, goalState: list, heuristic:
Heuristics.Type):
         """Class constructor.
         Args:
             initialState (list): The starting state.
             goalState (list): The final state to reach.
             heuristic (Heuristics.Type): The type of heuristic used to
 approximate cost.
         .....
         self.initialState = initialState
         self.goalState = goalState
         self.hTag = heuristic
    def h(self, s: list) -> int | float:
         """Gate function that forces Heuristics function to be called in
Problem instance.
         Find the heuristic value for the current state and pre-defined goal
 state.
         Args:
             s (list): Current state.
         Returns:
             int: estimated cost from current state to goal state.
         return Heuristics.Function[self.hTag](s, self.goalState)
    def setAction(self, s: list) -> Actions:
         """Gate function that forces Actions instantiation from Problem
 instance.
         Create an Actions instance for current state.
         Args:
             s (list): Current state.
```

```
Returns:
            Actions: Actions instance.
        return Actions(s)
    def reachGoal(self, s: list) -> bool:
        """Goal Test - Determines whether a given state is the goal state.
        Args:
            s (list): Current state.
        Returns:
            bool: True if goal state is reached, else False.
        return s == self.goalState
   def getPathCost(self, sX: list = None, a: Callable | None = None, nY:
list = None) -> int:
        """Path Cost - Assigns a numeric cost to each path (action) from
previous to current state.
        For this specific problem, the action cost is always 1.
        Args:
            sX (list, optional): Initial state. Defaults to None.
            a (function | None, optional): Action function. Defaults to
None.
            nY (list, optional): Final state. Defaults to None.
        Returns:
            int: 1
        ....
        return 1
```

main.py

```
The code reads as follows:
import multiprocessing
import Generator
from Problem import Problem
from AstarSearch import AstarSearch
from typing import Callable
from Node import Node # type hint
# Default values
TIMEOUT = 5 # seconds
GENERATIONS = 100 # amount generated
_8_PUZZLE_GOAL_STATE = [1, 2, 3, 4, 5, 6, 7, 8, None] # 3x3
_15_PUZZLE_GOAL_STATE = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15,
None] # 4x4
_24_PUZZLE_GOAL_STATE = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15,
16, 17, 18, 19, 20, 21, 22, 23, 24, None] # 5x5
def runWithTimeout(timeout : int, func: Callable, args=()):
    with multiprocessing.Pool(1) as pool:
        result = pool.apply async(func, args)
        try:
            return result.get(timeout=timeout )
        except multiprocessing.TimeoutError:
            # print("Timeout reached. Terminating process.")
            pool.terminate() # force stop safely
            pool.join()
            return None
if name == " main ":
    # comment one of the for loop out to not generate
    # change GENERATIONS in range for different number of problem instances
to solve
    #!there can be duplicate generations, double check CSV for 100 unique
initial states.
    for i in range(0, GENERATIONS): # 8-puzzle
        initialState: list = Generator.generateRandom(3, 70, 70)
Generate puzzle
        print("ini: " + str(initialState))
        for heuristic in ["h1", "h2", "h3"]:
```

```
problem: Problem = Problem(initialState, 8 PUZZLE GOAL STATE,
heuristic)
            result: Node | None = runWithTimeout(TIMEOUT, AstarSearch,
(problem,))
            if result:
                print(heuristic + ": Success")
            else:
                print(heuristic + ": Timeout")
    for i in range(0, GENERATIONS): # 15-puzzle
        initialState: list = Generator.generateRandom(4, 100, 100)
Generate puzzle
        print("ini: " + str(initialState))
        for heuristic in ["h1", "h2", "h3"]:
            problem: Problem = Problem(initialState, _15_PUZZLE_GOAL_STATE,
heuristic)
            result: Node | None = runWithTimeout(TIMEOUT, AstarSearch,
(problem,))
            if result:
                print(heuristic + ": Success")
            else:
                print(heuristic + ": Timeout")
    for i in range(0, GENERATIONS): # 24-puzzle
        initialState: list = Generator.generateRandom(5, 70, 70)
Generate puzzle
        print("ini: " + str(initialState))
        for heuristic in ["h1", "h2", "h3"]:
            problem: Problem = Problem(initialState, 24 PUZZLE GOAL STATE,
heuristic)
            result: Node | None = runWithTimeout(TIMEOUT, AstarSearch,
(problem,))
            if result:
                print(heuristic + ": Success")
            else:
                print(heuristic + ": Timeout")
# # SINGLE TEST CASE
# problem = Problem([1, 5, 4, 2, None, 3, 6, 8, 7],                           <u>_8 PUZZLE_GOAL_STATE</u>,
"h3")
# print(problem.hTag)
# goalNode: Node = AstarSearch(problem) # Run A* search on the
problem instance
```

```
# print(goalNode)
# FIXED - closed set
# failed cases: [6, 4, 2, 1, None, 5, 7, 8, 3]
# [5, 4, None, 7, 6, 1, 8, 2, 3]
# MILESTONE - proof of concept case, convincing me that code is not bugged
for larger cases
# suceeded case: [1, 5, 4, 2, None, 3, 6, 8, 7]
# FIXED - heapq better perf (if it's way too large, then it simply takes
forever to run, not a bug)
# failed cases: [5, 4, 3, 7, 6, 1, 2, 8, 13, 11, 12, 15, 14, 10, 9, None]
# MILETONE - the only 1/100 24-puzzle that failed for generateRandom(5, 70,
70)
# failed case: [1, 3, 8, 15, 5, 6, 2, 19, 14, 10, 11, 7, 4, 18, 20, 16, 12,
13, None, 9, 21, 17, 22, 23, 24]
```

Results

The outputs were neatly formatted as CSV files. They are adapted into typeset tables as below:

8_Puzzle

initial_state
[7, 4, 1, 2, 3, 5, 8, 6, None]
[None, 4, 6, 3, 1, 2, 7, 5, 8] 13 91 13 28 13 [6, 4, 2, 1, 5, 3, 7, 8, None] 13 99 13 29 13 [2, 8, 3, 5, 6, 7, None, 1, 4] 19 1280 19 121 19 [5, 3, None, 2, 1, 8, 4, 6, 7] 15 198 15 43 15 [1, 2, 3, 4, None, 6, 7, 5, 8] 3 3 3 3 3 3 [1, 5, 6, 7, None, 4, 8, 3, 2] 19 1868 19 342 19 [2, 3, 6, 7, 4, 8, 5, 1, None] 15 238 15 52 15 [1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[6, 4, 2, 1, 5, 3, 7, 8, None] 13 99 13 29 13 [2, 8, 3, 5, 6, 7, None, 1, 4] 19 1280 19 121 19 [5, 3, None, 2, 1, 8, 4, 6, 7] 15 198 15 43 15 [1, 2, 3, 4, None, 6, 7, 5, 8] 3 3 3 3 3 3 3 [1, 5, 6, 7, None, 4, 8, 3, 2] 19 1868 19 342 19 [2, 3, 6, 7, 4, 8, 5, 1, None] 15 238 15 52 15 [1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[2, 8, 3, 5, 6, 7, None, 1, 4] 19 1280 19 121 19 [5, 3, None, 2, 1, 8, 4, 6, 7] 15 198 15 43 15 [1, 2, 3, 4, None, 6, 7, 5, 8] 3 3 3 3 3 3 3 [1, 5, 6, 7, None, 4, 8, 3, 2] 19 1868 19 342 19 [2, 3, 6, 7, 4, 8, 5, 1, None] 15 238 15 52 15 [1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[5, 3, None, 2, 1, 8, 4, 6, 7] [1, 2, 3, 4, None, 6, 7, 5, 8] [1, 5, 6, 7, None, 4, 8, 3, 2] [2, 3, 6, 7, 4, 8, 5, 1, None] [3, 4, 7, 8, 2, None, 6, 3] [4, 5, None, 7, 6, 1, 8, 3, 2] 15 188 19 15 188 19 19 1868 19 19 19 19 10 10 10 10 11 10 11 11
[1, 2, 3, 4, None, 6, 7, 5, 8] 3 3 3 3 [1, 5, 6, 7, None, 4, 8, 3, 2] 19 1868 19 342 19 [2, 3, 6, 7, 4, 8, 5, 1, None] 15 238 15 52 15 [1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[1, 5, 6, 7, None, 4, 8, 3, 2] 19 1868 19 342 19 [2, 3, 6, 7, 4, 8, 5, 1, None] 15 238 15 52 15 [1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[2, 3, 6, 7, 4, 8, 5, 1, None] 15 238 15 52 15 [1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[1, 6, 2, 3, None, 7, 8, 4, 5] 21 4615 21 625 21 [1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[1, 5, 4, 7, 8, 2, None, 6, 3] 17 534 17 89 17 [4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
[4, 5, None, 7, 6, 1, 8, 3, 2] 17 499 17 69 17
IF 2 Nove 7 2 2 2 4 41 24 2500 24 400 24
[5, 3, None, 7, 2, 6, 8, 4, 1] 21 3586 21 498 21
[None, 1, 5, 4, 3, 6, 7, 2, 8] 11 45 11 23 11
[None, 2, 5, 4, 6, 1, 7, 8, 3] 19 1422 19 362 19
[None, 3, 6, 1, 4, 5, 7, 8, 2] 13 111 13 42 13
[None, 1, 3, 4, 5, 6, 7, 8, 2] 13 134 13 62 13
[None, 1, 5, 4, 3, 2, 7, 8, 6] 9 21 9 16 9
[7, 4, 3, 8, 1, 6, None, 5, 2] 17 551 17 101 17
[1, 2, 6, 3, 5, 7, 8, 4, None] 19 1414 19 288 19
[1, 2, 3, 6, 7, 4, 5, 8, None] 17 633 17 159 17
[8, 6, None, 3, 2, 1, 5, 4, 7] 25 18494 25 1435 25 2
[None, 4, 2, 5, 1, 3, 7, 8, 6] 9 17 9 12 9
[6, 2, 4, 1, 3, 5, 7, 8, None] 23 8632 23 1432 23 1
[1, 8, 3, 5, 2, 6, 4, 7, None] 17 657 17 199 17
[1, 5, 2, 4, None, 3, 7, 8, 6] 5 5 5 5
[None, 6, 2, 1, 3, 8, 7, 5, 4] 17 582 17 91 17
[1, 8, None, 5, 3, 2, 7, 4, 6] 19 1618 19 376 19
[7, 1, 3, 2, 8, 4, 5, 6, None] 15 208 15 35 15

[2, 1, 5, 3, None, 7, 8, 6, 4]	23	10291	23	1079	23	1512
[5, 6, 2, 4, None, 3, 1, 7, 8]	19	1908	19	455	19	501
[2, 8, 3, 1, 6, 4, 5, 7, None]	21	3636	21	580	21	720
[None, 7, 6, 1, 3, 4, 5, 2, 8]	19	1368	19	136	19	194
[1, 3, 6, 4, None, 8, 2, 5, 7]	15	295	15	79	15	87
[4, 8, 3, 1, 6, 2, 7, 5, None]	21	3856	21	766	21	925
[1, 8, None, 7, 4, 2, 6, 5, 3]	15	210	15	24	15	31
[8, 2, None, 4, 1, 3, 7, 5, 6]	17	651	17	188	17	209
[None, 5, 2, 6, 1, 4, 7, 3, 8]	21	3575	21	445	21	604
[6, 3, 2, 1, None, 8, 5, 4, 7]	17	677	17	64	17	93
[4, 8, 1, 7, None, 3, 5, 6, 2]	17	669	17	84	17	102
[7, 4, 1, 3, None, 6, 2, 5, 8]	21	3976	21	443	21	584
[6, 1, 2, 7, None, 3, 4, 5, 8]	17	801	17	169	17	198
[1, 4, 5, 2, 6, 8, 7, 3, None]	23	9041	23	1555	23	1936
[1, 6, None, 4, 2, 5, 7, 3, 8]	15	280	15	109	15	112
[5, 2, None, 8, 7, 6, 4, 3, 1]	23	8112	23	824	23	1157
[None, 1, 2, 4, 5, 3, 7, 8, 6]	5	5	5	5	5	5
[2, 1, 3, 4, 7, 6, 5, 8, None]	19	1654	19	507	19	545
[3, 1, 6, 2, None, 4, 7, 5, 8]	13	115	13	39	13	39
[3, 1, 5, 2, None, 6, 7, 4, 8]	15	294	15	73	15	78
[4, 7, 2, 1, 3, 6, None, 5, 8]	19	1374	19	288	19	320
[6, 1, 8, 4, None, 7, 2, 5, 3]	25	22382	25	1496	25	2578
[8, 1, 7, 4, 5, 2, 3, 6, None]	25	17635	25	955	25	1850
[1, 5, 3, 7, None, 2, 4, 8, 6]	19	2144	19	670	19	726
[3, 8, 4, 1, 5, 2, None, 7, 6]	21	3323	21	488	21	590
[4, 1, 5, 3, None, 8, 7, 6, 2]	15	274	15	53	15	65
[None, 3, 6, 4, 2, 7, 1, 8, 5]	21	3430	21	640	21	738
[2, 4, 5, 3, 1, 6, 7, 8, None]	17	556	17	134	17	154
[2, 8, 1, 3, 6, 5, 4, 7, None]	21	3264	21	401	21	500
[4, 2, 6, 8, None, 7, 3, 5, 1]	23	9632	23	827	23	1242
[1, 2, 3, 8, None, 4, 6, 7, 5]	13	139	13	43	13	44
[1, 2, 3, 8, 7, 5, 4, 6, None]	9	22	9	11	9	12
[4, 5, 1, 6, 8, 2, None, 7, 3]	17	513	17	88	17	98
[4, 2, 6, 3, 5, 7, None, 1, 8]	23	8089	23	1238	23	1506
[None, 3, 6, 1, 4, 2, 7, 5, 8]	9	17	9	11	9	11

[None, 5, 3, 2, 7, 4, 1, 8, 6]	17	591	17	141	17	155
[4, 6, 3, 1, 2, 8, 7, 5, None]	19	1675	19	446	19	495
[4, 1, 8, 2, 7, 5, None, 3, 6]	21	3343	21	298	21	457
[None, 4, 2, 1, 8, 3, 5, 6, 7]	21	3727	21	721	21	846
[4, 6, 3, 7, 2, 5, 1, 8, None]	21	3772	21	682	21	838
[4, 3, 1, 8, None, 2, 7, 6, 5]	15	289	15	61	15	67
[7, 4, 1, 8, 5, 6, 3, 2, None]	23	7408	23	688	23	953
[2, 4, None, 1, 5, 8, 7, 6, 3]	17	573	17	127	17	146
[5, 8, 4, 1, None, 6, 7, 3, 2]	19	1706	19	182	19	260
[None, 1, 3, 6, 2, 8, 5, 4, 7]	13	90	13	18	13	19
[1, 8, 2, 4, 6, 3, 7, 5, None]	11	50	11	24	11	24
[1, 2, 3, 5, None, 6, 4, 7, 8]	5	5	5	5	5	5
[3, 8, None, 1, 6, 5, 4, 2, 7]	19	1296	19	176	19	210
[None, 1, 5, 3, 2, 8, 4, 7, 6]	17	604	17	147	17	170
[1, 5, 4, 7, 8, 2, 6, 3, None]	19	1282	19	154	19	204
[1, 3, 6, 4, 8, 5, None, 7, 2]	13	117	13	48	13	50
[4, 3, 1, 7, None, 2, 8, 5, 6]	13	108	13	43	13	43
[7, 5, 1, 8, 2, 3, 4, 6, None]	19	1295	19	201	19	224
[None, 5, 6, 2, 7, 3, 4, 1, 8]	21	3721	21	750	21	882
[6, 4, 2, 7, 5, 3, 8, 1, None]	21	3372	21	376	21	525
[5, 4, 2, 1, 6, 8, None, 7, 3]	15	211	15	47	15	52
[1, 4, 3, 5, None, 7, 8, 2, 6]	19	1969	19	398	19	482
[5, 8, 4, 1, 6, 2, None, 7, 3]	17	475	17	29	17	44
[4, 8, 1, 7, 3, 5, None, 6, 2]	19	1285	19	105	19	146
[2, 8, 3, 1, 7, 6, 5, 4, None]	17	632	17	132	17	152
[1, 2, None, 4, 6, 8, 7, 3, 5]	13	112	13	42	13	48
[1, 6, 3, 7, 4, 5, None, 2, 8]	15	278	15	101	15	106
[2, 5, 3, 8, 1, 6, 4, 7, None]	19	1561	19	397	19	448
[None, 5, 6, 4, 3, 1, 7, 2, 8]	17	592	17	111	17	138
[3, 5, 6, 1, None, 2, 4, 7, 8]	13	115	13	42	13	42
[None, 3, 1, 7, 4, 2, 8, 6, 5]	19	1322	19	251	19	288
[1, 5, 2, 4, 6, 7, None, 3, 8]	19	1402	19	213	19	285
[None, 1, 8, 4, 6, 2, 7, 5, 3]	15	237	15	58	15	62
[5, 3, 7, 8, None, 2, 4, 1, 6]	21	4226	21	370	21	567
[2, 4, None, 5, 1, 3, 8, 7, 6]	19	1553	19	340	19	408

CP468-A1-Group10 15/10/2025

[3, 2, 5, 4, None, 6, 1, 8, 7]	21	4175	21	727	21	814
[[o, =, o, .,oo, o, ., o, .]]						J

15_Puzzle

initial_state	h1_steps	h1_expanded	h2_steps	h2_expanded	h3_steps	h3_expanded
[3, 4, 7, 11, 5, 2, 12, 8, 1, 6, None, 15, 9, 13, 14, 10]	TIMEOUT	TIMEOUT	33	19067	33	44456
[10, 9, 2, 3, 7, 1, 6, 4, 13, 5, 11, 8, 14,	0.5	40400	0.5	070	0.5	000
None, 15, 12] [1, 8, 7, 3, 5, 2, 15, None, 10, 6, 12, 4,	25	18490	25	372	25	662
9, 13, 11, 14]	25	26079	25	826	25	1148
[1, 6, None, 8, 5, 7, 2, 3, 9, 14, 12, 10, 13, 11, 15, 4]	25	51560	25	1340	25	1962
[13, 1, 2, 3, 5, 7, 14, 4, 6, 11, None, 8, 10, 9, 15, 12]	25	23249	25	317	25	655
[1, 3, None, 8, 5, 15, 11, 4, 13, 2, 6, 7, 10, 9, 14, 12]	25	23420	25	367	25	801
[2, 6, 3, 4, 5, 1, 13, 8, 10, 7, None, 11, 14, 9, 15, 12]	21	4154	21	178	21	367
[5, 7, None, 4, 9, 1, 3, 8, 6, 11, 2, 14, 13, 10, 15, 12]	23	11563	23	421	23	846
[2, 4, None, 3, 1, 6, 15, 8, 5, 14, 12, 7, 13, 9, 10, 11]	TIMEOUT	TIMEOUT	29	6207	29	12774
[1, 3, 7, 4, 5, 2, 14, 8, 6, 9,	23	21507	23	2166	23	2985

11, 12, 13,						
None, 10, 15]						
[4, 7, 8, 3, 1, 5, 2, 12, 9, 11, 6, 15, 13, 14, 10, None]	TIMEOUT	TIMEOUT	31	11144	31	21917
[1, 13, 2, 3, 6, None, 7, 4, 5, 9, 14, 8, 10, 11, 12, 15]	27	112165	27	1782	27	4302
[None, 6, 3, 4, 5, 1, 8, 12, 13, 2, 11, 7, 10, 9, 14, 15]	23	5476	23	432	23	602
[6, 7, 8, 3, 2, 9, 4, None, 1, 10, 5, 11, 13, 14, 15, 12]	27	95436	27	2678	27	4436
[1, 6, None, 8, 5, 11, 4, 2, 9, 7, 3, 12, 13, 10, 14, 15]	17	347	17	40	17	46
[6, 1, 2, 3, 5, 10, 8, 4, 9, 14, 15, 11, 13, 7, 12, None]	27	109670	27	5123	27	8357
[9, 5, 2, 4, 6, 3, 11, None, 1, 8, 12, 7, 13, 10, 14, 15]		TIMEOUT	29	6285	29	10341
[2, 4, None, 3, 1, 9, 6, 11, 5, 7, 8, 14, 13, 10, 15, 12]	TIMEOUT	TIMEOUT	31	21616	31	44163
[1, 3, 4, 8, 2, 6, 7, 12, 5, 13, 14, 11, 9, None, 10, 15]	19	477	19	110	19	125

0.5	2224		20.12	0.5	4700
25	60211	25	2943	25	4780
23	27252	23	2567	23	3191
23	6664	23	201	23	303
19	1857	19	150	19	174
TIMEOUT	TIMEOUT	31	34692	31	55187
TIMEOUT	TIMEOUT	37	42740	37	140291
TIMEOUT	TIMEOUT	31	10251	31	26369
TIMEOUT	TIMEOUT	29	16916	29	25081
17	363	17	150	17	155
TIMEOUT	TIMEOUT	33	108934	TIMEOUT	TIMEOUT
	19 TIMEOUT TIMEOUT TIMEOUT 17	23 27252 23 6664 19 1857 TIMEOUT TIMEOUT TIMEOUT TIMEOUT TIMEOUT TIMEOUT 363	23 27252 23 23 6664 23 19 1857 19 TIMEOUT TIMEOUT 37 TIMEOUT TIMEOUT 31 TIMEOUT TIMEOUT 29	23 27252 23 2567 23 6664 23 201 19 1857 19 150 TIMEOUT TIMEOUT 31 34692 TIMEOUT TIMEOUT 37 42740 TIMEOUT TIMEOUT 31 10251 TIMEOUT TIMEOUT 29 16916	23 27252 23 2567 23 23 6664 23 201 23 19 1857 19 150 19 TIMEOUT TIMEOUT 31 34692 31 TIMEOUT TIMEOUT 37 42740 37 TIMEOUT TIMEOUT 31 10251 31 TIMEOUT TIMEOUT 29 16916 29

[2, 1, 6, 4, 13, None, 10, 3, 14, 12, 7, 9, 15, 5, 11, 8]	TIMEOUT	TIMEOUT	39	139881	TIMEOUT	TIMEOUT
[1, 3, 4, 6, 10, None, 2, 5, 14, 15, 7, 8,						
13, 9, 11, 12]	TIMEOUT	TIMEOUT	31	7342	33	71558
[5, 2, 7, 3, 9, 6, 11, 4, 1, 8, None, 12, 13, 10, 14, 15]	23	11731	23	1134	23	1312
[6, 11, 1, 12, 2, None, 4, 15, 13, 8, 9, 7, 10, 5, 3,						
14]	TIMEOUT	TIMEOUT	43	176430	TIMEOUT	TIMEOUT
[2, 10, 8, 3, 5, 1, 9, 4, None, 11, 6, 12, 13, 7, 14, 15]	25	22358	25	311	25	635
[None, 2, 8, 3, 5, 6, 1, 4, 9, 10, 7, 11, 14, 15, 13,						
12]	TIMEOUT	TIMEOUT	29	10592	29	15607
[2, 3, 6, 4, 10, 9, 5, None, 1, 7, 11, 8, 13, 14, 15, 12]	19	906	19	36	19	49
[9, 4, 5, 11, 2, None, 1, 3, 14, 10, 8, 7, 6, 13, 15, 12]	TIMEOUT	TIMEOUT	31	592	31	2850
[5, 1, 7, 6, 3, 11, 2, 4, 13, 14, None, 8, 10, 9, 15, 12]	TIMEOUT	TIMEOUT	29	1795	29	5982
[5, 1, 7, 2, 9, 3, 10, 4, 6, 14, 8, 15, 13, 11, 12, None]	25	13456	25	325	25	567
14, 8, 15, 13, 11, 12, None]	25	13456	25	325	25	5

[1, 11, None, 3, 5, 15, 2, 4, 9, 6, 10, 7, 13, 14, 8, 12]	25	64024	25	1701	25	3129
[3, 11, None, 4, 6, 2, 1, 8, 9, 7, 14, 15, 10, 5, 12, 13]	TIMEOUT	TIMEOUT	35	12335	35	43615
[None, 10, 4, 8, 2, 13, 6, 7, 1, 5, 15, 3, 9, 14, 11, 12]	TIMEOUT	TIMEOUT	35	70662	35	152968
[5, 1, 3, 4, 2, None, 7, 9, 13, 10, 11, 12, 14, 15, 6, 8]	TIMEOUT	TIMEOUT	33	69311	33	141044
[2, 1, 4, 8, 6, None, 3, 12, 7, 5, 10, 11, 9, 13, 14, 15]	25		25	1821	25	2296
[1, 3, None, 4, 5, 2, 7, 15, 9, 14, 8, 10, 13, 12, 6, 11]	21	4901	21	67	21	197
[1, 2, 6, 4, 5, 12, 11, 8, None, 9, 7, 15, 13, 3, 10, 14]	TIMEOUT	TIMEOUT	29	10896	29	21873
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24_Puzzle

initial_state	h1_st eps	h1_exp anded	h2_st eps	h2_exp anded	h3_st eps	h3_exp anded
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27	3845	27	222	27	280
17	65	17	24	17	24
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21	1385	21	186	21	264
27	35326	27	425	27	922
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TIME OUT	TIMEO UT	35	33029	35	96329
TIME OUT	TIMEO UT	37	14183	37	30780
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21	782	21	75	21	83
27	15712	27	312	27	379
27	4635	27	227	27	427
29	53468	29	312	29	791
27	64578	27	1813	27	3235
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13	137	13	71	13	71
TIME OUT	TIMEO UT	37	23525	37	85101
TIME	TIMEO UT	37	3998	37	29062
	27 17 25 21 27 19 29 TIME OUT TIME OUT 23 21 27 27 27 19 37 TIME OUT TIME OUT TIME OUT	27 3845 17 65 25 20656 21 1385 27 35326 19 295 29 121046 TIME TIMEO OUT UT 23 2684 21 782 27 15712 27 4635 29 53468 27 64578 TIME TIMEO OUT 13 137 TIME TIMEO OUT 13 137 TIME TIMEO OUT	27 3845 27 17 65 17 25 20656 25 21 1385 21 27 35326 27 19 295 19 29 121046 29 TIME OUT 35 TIME TIMEO OUT 37 23 2684 23 21 782 21 27 15712 27 29 53468 29 27 64578 27 TIME OUT 33 13 137 13 TIME OUT 37 TIME TIMEO OUT 37 TIME TIMEO OUT 37 TIME TIMEO 37	27 3845 27 222 17 65 17 24 25 20656 25 279 21 1385 21 186 27 35326 27 425 19 295 19 55 29 121046 29 496 TIME OUT 0T 35 33029 TIME OUT 0T 37 14183 23 2684 23 278 21 782 21 75 27 15712 27 312 27 4635 27 227 29 53468 29 312 27 64578 27 1813 TIME OUT 0T 33 16062 13 137 13 71 TIME OUT 0T 37 23525 TIME TIMEO 0T 37 23525	27 3845 27 222 27 17 65 17 24 17 25 20656 25 279 25 21 1385 21 186 21 27 35326 27 425 27 19 295 19 55 19 29 121046 29 496 29 TIME TIMEO OUT 35 33029 35 TIME TIMEO OUT 37 14183 37 23 2684 23 278 23 21 782 21 75 21 27 15712 27 312 27 29 53468 29 312 29 27 64578 27 1813 27 TIME TIMEO OUT 33 16062 33 13 137 13 71 13 TIME TIMEO OUT 37 23525 37 TIME TIMEO 37 23525 37

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19	804	19	108	19	139
25	988	25	39	25	43
21	2170	21	518	21	587
TIME	TIMEO UT	29	4080	29	10668
25	21603	25	986	25	1556
27	5387	27	63	27	163
29	46214	29	529	29	1757
23	810	23	73	23	92
15	186	15	39	15	39
27	15974	27	879	27	1281
TIME OUT	TIMEO UT	33	979	33	4498
TIME OUT	TIMEO UT	37	52953	TIME OUT	TIMEO UT
27	11120	27	205	27	303
TIME OUT	TIMEO UT	43	42413	TIME OUT	TIMEO UT
TIME OUT	TIMEO UT	37	14709	37	60484
23	673	23	95	23	95
25	15906	25	153	25	240
1	3023	19	757	19	848
	25 23 19 25 21 TIME OUT 25 27 29 23 15 TIME OUT TIME OUT TIME OUT TIME OUT TIME OUT 27 TIME OUT	25 66922 23 752 19 804 25 988 21 2170 TIME TIMEO TIMEO TIME TIMEO TIMEO TIME TIMEO TI	25 66922 25 23 19 804 19 25 988 25 21 21 21 21 21 21 21	25 66922 25 658 23 752 23 62 19 804 19 108 25 988 25 39 21 2170 21 518 TIME DOUT 29 4080 25 21603 25 986 27 5387 27 63 29 46214 29 529 23 810 23 73 15 186 15 39 27 15974 27 879 TIME TIMEO OUT 33 979 TIME TIMEO OUT 37 52953 27 11120 27 205 TIME TIMEO OUT 43 42413 TIME TIMEO OUT 37 14709 23 673 23 95 25 15906 25 153	25 66922 25 658 25 23 752 23 62 23 19 804 19 108 19 25 988 25 39 25 21 2170 21 518 21 TIME OUT 29 4080 29 25 21603 25 986 25 27 5387 27 63 27 29 46214 29 529 29 23 810 23 73 23 15 186 15 39 15 27 15974 27 879 27 TIME OUT 33 979 33 TIME OUT 37 52953 OUT 27 11120 27 205 27 TIME OUT 43 42413 OUT TIME OUT 37 14709 37 23 673 23 95 23 25 15906 25 153

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[1, 2, 3, 4, 5, 6, 13, 7, 9, 10, 11, 18, None, 12, 24, 17,	TIME	TIMEO				
8, 14, 20, 23, 16, 21, 15, 22, 19]	OUT	UT	37	14385	37	93174

References

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