## MAT436 problem set 3

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## I. Suggested Problem 1

Suppose first that U is unitary. Of course, U is bijective, so it is surjective. Moreover, since we are in a Hilbert space, we assume the norm is induced from the inner product and get

$$||Uv||_{H_2} = \sqrt{\langle Uv, Uv \rangle_{H_2}} = \sqrt{\langle U^*Uv, v \rangle_{H_1}} = \sqrt{\langle v, v \rangle_{H_1}} = ||v||_{H_1}$$

$$\tag{1}$$

which implies that U is an isometry. Now, assume that U is a surjective isometry. We need to show that U is angle-preserving. Indeed, we have the polarization identity (assuming the inner product is anti-linear in the second argument, where we take the Hilbert space to be, generally, complex)

$$\langle x, y \rangle = \frac{1}{4} \sum_{k=0}^{3} i^k ||x + i^k y||^2$$
 (2)

so we have, since U is an isometry,

$$\langle Ux, Uy \rangle_{H_2} = \frac{1}{4} \sum_{k=0}^{3} i^k ||Ux + i^k Uy||_{H_2}^2 = \frac{1}{4} \sum_{k=0}^{3} i^k ||U(x + i^k y)||_{H_2}^2 = \frac{1}{4} \sum_{k=0}^{3} i^k ||x + i^k y||_{H_1}^2 = \langle x, y \rangle_{H_1}$$
(3)

as desired. Now, suppose the third statement holds, and we have U which is surjective and angle-preserving. U will be injective as if Ux = 0, then  $\langle Ux, Ux \rangle_{H_2} = 0$ , implying  $\langle x, x \rangle_{H_1} = 0$ , implying x = 0. Note that  $U^{-1}$  will preserve inner products as

$$\langle U^{-1}v, U^{-1}v \rangle_{H_1} = \langle UU^{-1}v, UU^{-1}v \rangle_{H_2} = \langle v, v \rangle_{H_2}$$
 (4)

Thus, we have

$$\langle (U^{-1} - U^*)v, (U^{-1} - U^*)v \rangle = (\langle U^*v, U^*v \rangle - \langle U^{-1}v, U^*v \rangle) + (\langle U^{-1}v, U^{-1}v \rangle - \langle U^*v, U^{-1}v \rangle)$$
 (5)

$$= \langle U^*v, U^*v \rangle - \langle v, UU^*v \rangle + \langle U^{-1}v, U^{-1}v \rangle - \langle v, v \rangle = 0$$
 (6)

so  $U^{-1}v = U^*v$  for all v, implying  $U^{-1} = U^*$ , and U is unitary.

## II. Suggested Problem 2

**Part A.** Note that S is not surjective as its image contains no element of the form  $(1, x_1, x_2, ...)$ , so it cannot be unitary. On the other hand,

$$||Sx|| = \sqrt{0^2 + \sum_{j=1}^{\infty} |x_j|^2} = \sqrt{\sum_{j=1}^{\infty} |x_j|^2} = ||x||$$
 (7)

so the map is an isometry.

**Part B.** By definition,  $\langle Sx, y \rangle = \langle x, S^*y \rangle$ . Of course,

$$\sum_{j=1}^{\infty} x_j \overline{y_{j+1}} \tag{8}$$

so we have  $S^*$  as the left-shift operator which sends  $(y_1, y_2, \dots)$  to  $(y_2, y_3, \dots)$ . To see that  $S^*$  has an uncountable number of eigenvalues, pick some  $r \in \mathbb{R}$ . Define  $y = (y_1, y_2, \dots)$  with  $y_k = r^k$ . We then have

$$Sy = S(r, r^2, \dots) = (r^2, r^3, \dots) = r \cdot (r, r^2, \dots) = ry$$
 (9)

so r is an eigenvalue. It follows that  $S^*$  is not diagonalizable, as by definition, diagonalizing an operator requires choosing a countable basis of eigenvectors, but there will always exist