

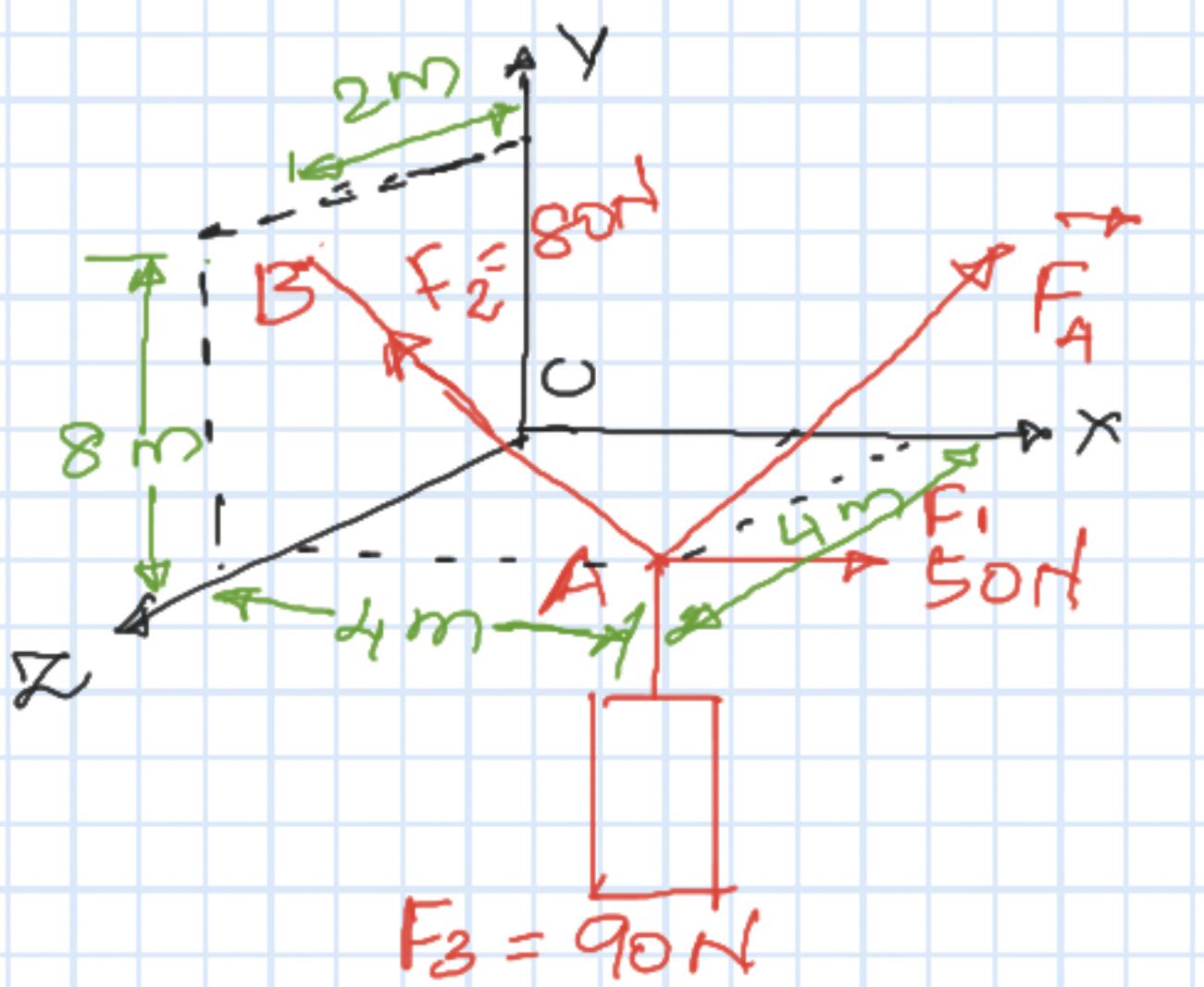
Inclination of the resultant force with the axes.

$$\phi_x = \cos^{-1} \frac{R_x}{R} = \cos^{-1} \left(\frac{40}{216.87} \right) = 79.37^\circ$$

$$\phi_y = \cos^{-1} \frac{R_y}{R} = \cos^{-1} \left(\frac{-150.72}{216.87} \right) = 134.02^\circ$$

$$\phi_z = \cos^{-1} \frac{R_z}{R} = \cos^{-1} \left(\frac{150.72}{216.87} \right) = 46.24^\circ$$

2. Three concurrent forces in space are acting at point A as shown.
An unknown force \vec{F} attached to the system makes the particle
A to be in equilibrium. Evaluate the magnitude and
direction of the unknown force \vec{F} .



Sol . Particle is in equilibrium

$$R = 0$$

$$\sum F_x = 0 \quad \textcircled{1}$$

$$\sum F_y = 0 \quad \textcircled{2}$$

$$\sum F_z = 0 \quad \textcircled{3}$$

Unknowns are
 $F_{x_A}, F_{y_A}, F_{z_A}$

$$A(4, 0, h)$$

$$B(0, 8, 2)$$

$$\vec{F}_1 = F_1 \vec{i} = 50 \vec{i} \quad - \textcircled{1}$$

$$\vec{F}_3 = F_3(-\vec{j}) = -90 \vec{j} \quad - \textcircled{2}$$

$$\vec{F}_2 = F_2 (\lambda_{AB}) = F_2 \left(\frac{\overrightarrow{AB}}{AB} \right) = 80 \left[\frac{(0-4)\vec{i} + (8-0)\vec{j} + (-2-4)\vec{k}}{\sqrt{4^2 + 8^2 + 2^2}} \right]$$

$$\vec{F}_4 = F_{x4} \vec{i} + F_{y4} \vec{j} + F_{z4} \vec{k} \quad - \textcircled{4} \quad = -34 \cdot 92 \vec{i} + 69 \cdot 83 \vec{j} - 17 \cdot 46 \vec{k} \quad - \textcircled{3}$$

$$\vec{R} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4 = 0$$

$$50 \vec{i} - 90 \vec{j} - 34 \cdot 92 \vec{i} + 69 \cdot 83 \vec{j} - 17 \cdot 46 \vec{k} + F_{x4} \vec{i} + F_{y4} \vec{j} + F_{z4} \vec{k} = 0$$

$$(F_{x4} + 15.085) \vec{i} + (F_{y4} - 20.17) \vec{j} + (F_{z4} - 17.46) \vec{k} = 0$$

$$F_{x4} + 15.085^- = 0 \Rightarrow F_{x4} = -15.085^-$$

$$F_{y4} - 20.17 = 0 \Rightarrow F_{y4} = 20.17$$

$$F_{z4} - 17.46 = 0 \Rightarrow F_{z4} = 17.46$$

Magnitude of \vec{F}_4

$$F_4 = \sqrt{15.085^2 + 20.17^2 + 17.46^2}$$

$$= 30.65 \text{ N}$$

Inclination of F_4 with the axes

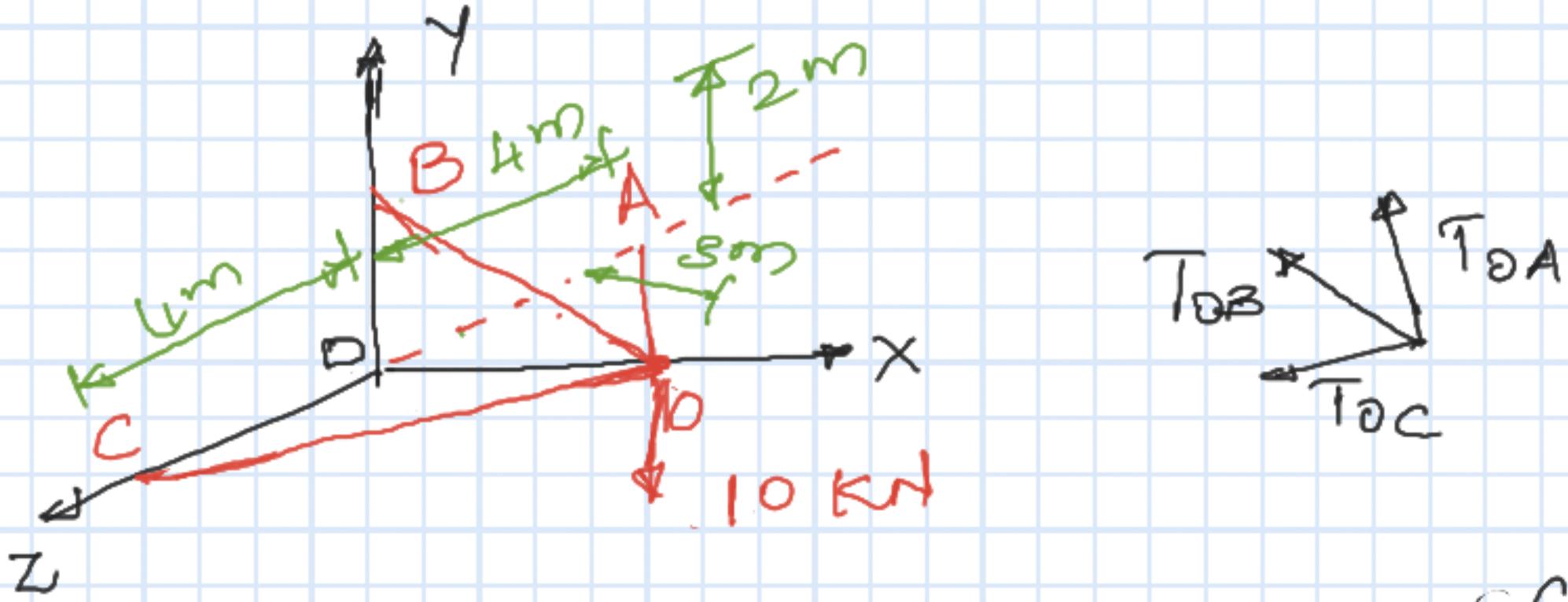
$$\alpha_x = \cos^{-1} \frac{F_x}{F} = 119.48^\circ$$

$$\alpha_y = \cos^{-1} \frac{F_y}{F} = 48.84^\circ$$

$$\alpha_z = \cos^{-1} \frac{F_z}{F} = 55.27^\circ$$

3. Problem for practice.

Members OA, OB, OC form a three member frame. A weight of 20 kN is hanging from joint O. Find the force induced in all the three members.



Sol

$$\overrightarrow{T_{OA}} = T_{OA}(\lambda_{OA})$$

$$\overrightarrow{T_{OB}} = T_{OB}(\lambda_{OB})$$

$$\overrightarrow{T_{OC}} = T_{OC}(\lambda_{OC})$$

$$A(0, 0, -4) \quad D(0, 0, 0)$$

$$B(0, 2, 0) \quad O(3, 0, 0)$$

$$C(0, 0, 4)$$

$$\lambda_{OA} = \frac{\overrightarrow{OA}}{OA} = \frac{(0-3)\vec{i} + (0-0)\vec{j} + (-4-0)\vec{k}}{\sqrt{3^2 + 4^2}} = -\frac{3\vec{i} - 4\vec{k}}{\sqrt{3^2 + 4^2}} = -0.6\vec{i} - 0.8\vec{k}$$

$$\lambda_{OB} = \frac{\overrightarrow{OB}}{OB} = \frac{(0-3)\vec{i} + (2-0)\vec{j} + (0-0)\vec{k}}{\sqrt{3^2 + 2^2}} = -0.832\vec{i} + 0.555\vec{j}$$

$$\lambda_{OC} = \frac{\overrightarrow{OC}}{OC} = \frac{(0-3)\vec{i} + (0-0)\vec{j} + (4-0)\vec{k}}{\sqrt{3^2 + 4^2}} = -0.6\vec{i} + 0.8\vec{k}$$

$$\vec{T}_{OA} = T_{OA}(-0.6\vec{i} - 0.8\vec{k}) = -0.6T_{OA}\vec{i} - 0.8T_{OA}\vec{k} \quad \textcircled{1}$$

$$\vec{T}_{OB} = T_{OB}(-0.832\vec{i} + 0.555\vec{j}) = -0.832T_{OB}\vec{i} + 0.555T_{OB}\vec{j} \quad \textcircled{2}$$

$$\vec{T}_{oc} = T_{oc} (-0.6\vec{i} + 0.8\vec{k}) = -0.6 \vec{T}_{oc} i + 0.8 \vec{T}_{oc} k \quad \text{--- (3)}$$

Since the truck is in equilibrium $R = 0$

$$R_x = \sum F_x = 0$$

$$R_y = \sum F_y = 0$$

$$R_z = \sum F_z = 0$$

$$\vec{R} = \vec{T}_{OA} + \vec{T}_{OB} + \vec{T}_{oc} = (-0.6T_{OA} - 0.832T_{OB} - 0.6T_{oc})\vec{i} + (-10 + 0.555T_{OB})\vec{j} + (-0.8T_{OA} + 0.8T_{oc})\vec{k} = 0$$

$$-0.6T_{OA} - 0.832T_{OB} - 0.6T_{oc} = 0 \quad \text{--- (4)}$$

$$+ 0.555T_{OB} - 10 = 0 \quad \text{--- (5)}$$

$$-0.8T_{OA} + 0.8T_{oc} = 0 \quad \text{--- (6)}$$

Solve (4), (5) & (6)

$$T_{OA} = 12.5 \text{ kN (C)}$$

$$T_{OB} = 18.02 \text{ kN (T)}$$

$$T_{oc} = 12.5 \text{ kN (C)}$$

Equilibrium of rigid bodies in 3D

Moment of a force about a point



Position Vector

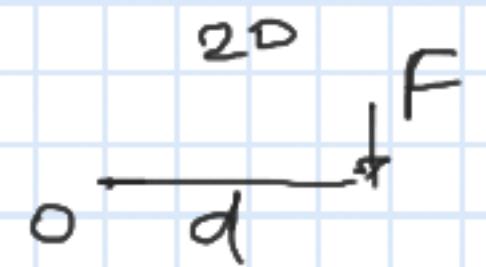
$$\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$$

$$\vec{F} = F_x\vec{i} + F_y\vec{j} + F_z\vec{k}$$

$$\vec{M}_O = \vec{r} \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x & y & z \\ F_x & F_y & F_z \end{vmatrix}$$

$$= (F_y z - F_z y)\vec{i} - (F_z x - F_x z)\vec{j} + (F_x y - F_y x)\vec{k}$$



$$M_O = (F)(d)$$

$$\vec{M}_o = M_x \vec{i} + M_y \vec{j} + M_z \vec{k}$$

Magnitude

$$M_o = \sqrt{M_x^2 + M_y^2 + M_z^2}$$

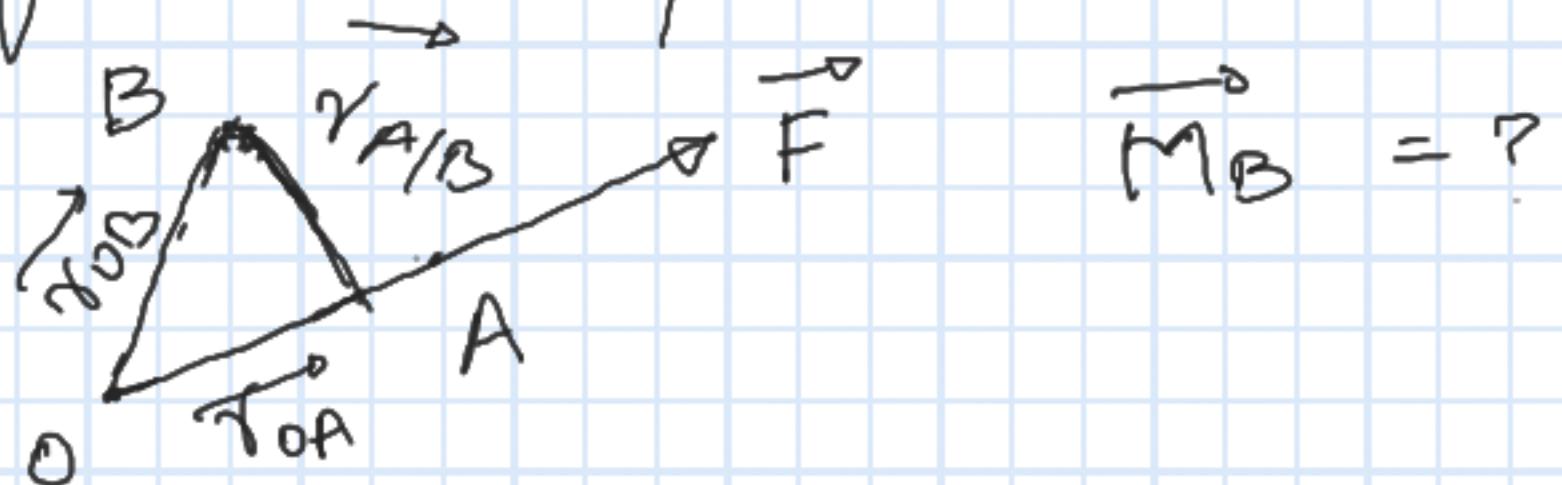
Direction

$$\alpha_x = \cos^{-1} \frac{M_x}{M}$$

$$\alpha_y = \cos^{-1} \frac{M_y}{M}$$

$$\alpha_z = \cos^{-1} \frac{M_z}{M}$$

1. A force $\vec{F} = 9\vec{i} + 3\vec{j} - 6\vec{k}$ passes through a point A whose position vector is $4\vec{i} - 2\vec{j} + 9\vec{k}$. Calculate the moment of the force about point B whose position vector is $6\vec{i} - 3\vec{j} - 7\vec{k}$



$$\vec{M}_B = ?$$

Sol. $\vec{r}_{A/B} = (\vec{r}_{OA} - \vec{r}_{OB}) = (4\vec{i} - 2\vec{j} + 9\vec{k}) - (6\vec{i} - 3\vec{j} - 7\vec{k}) = (-2\vec{i} + \vec{j} + 16\vec{k})$

$$\vec{M}_B = \vec{r}_{A/B} \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -2 & 1 & 16 \\ 9 & 3 & -6 \end{vmatrix} = -54\vec{i} + 132\vec{j} - 15\vec{k}$$

2. A force vector $\vec{F} = 6\vec{i} + 2\vec{j} - 3\vec{k}$ acts at a point A of coordinate $(1, 2, 3)$. Find the moment of the force about point B $(-2, 3, 4)$.



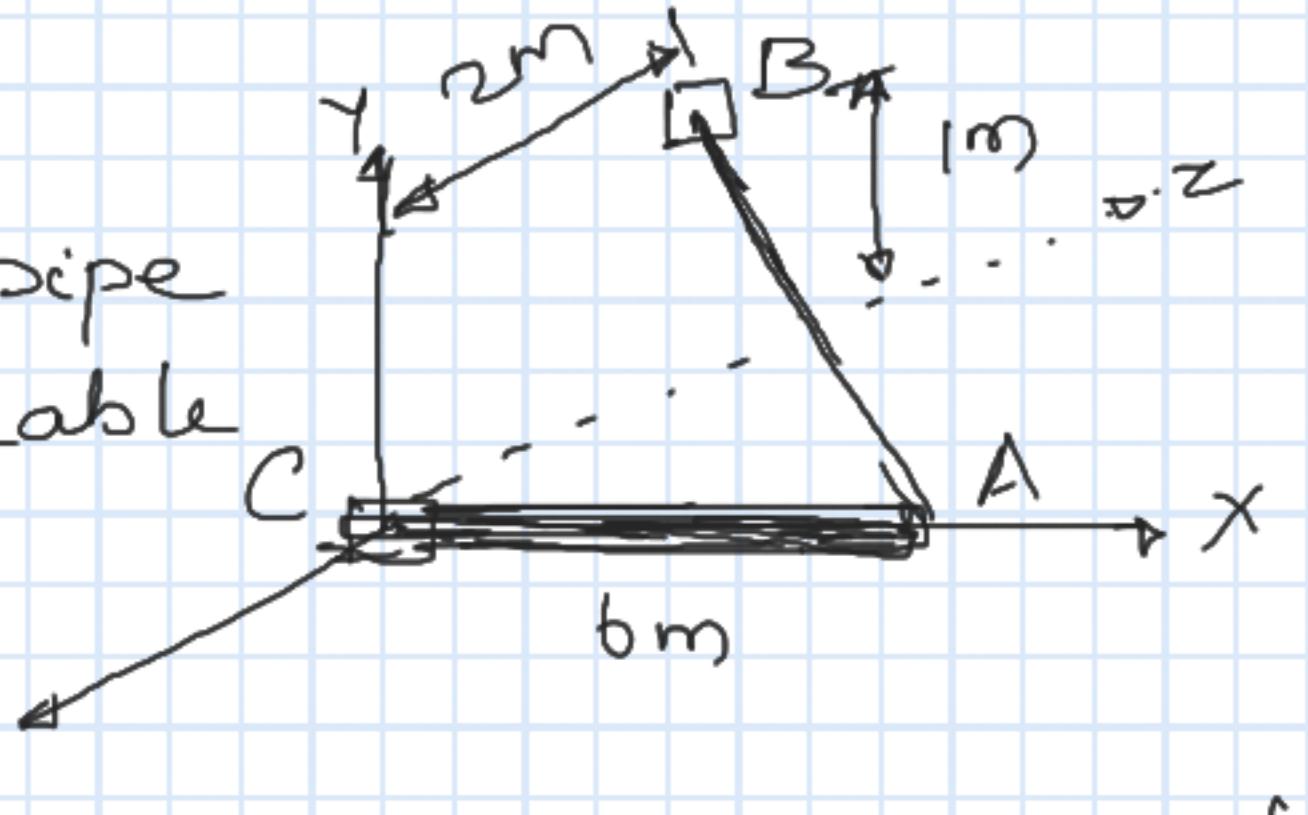
$$\begin{aligned}\vec{r}_{A/B} &= (x_A - x_B)\vec{i} + (y_A - y_B)\vec{j} + (z_A - z_B)\vec{k} \\ &= (1 + 2)\vec{i} + (2 - 3)\vec{j} + (3 - 4)\vec{k} \\ &= 3\vec{i} - \vec{j} - \vec{k}\end{aligned}$$

$$\begin{aligned}\vec{M}_B &= \vec{r}_{A/B} \times \vec{F} \\ &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & 3 \\ 6 & 2 & -3 \end{vmatrix} = 5\vec{i} + 3\vec{j} + 12\vec{k}\end{aligned}$$

3.

AC-pipe

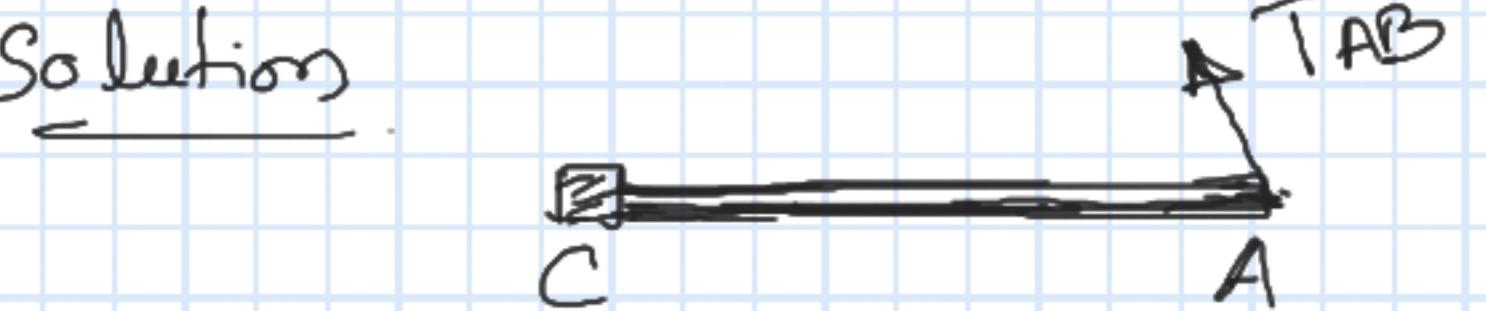
AB-cable



Evaluate the moment of force at A about C

$$\overrightarrow{T}_{AB} = 400 \text{ N}$$

Solution



$$\overrightarrow{M}_C = \overrightarrow{\gamma}_{AC} \times \overrightarrow{T}_{AB}$$

$$\overrightarrow{\gamma}_{AC} = (6-0)\vec{i} = 6\vec{i}$$

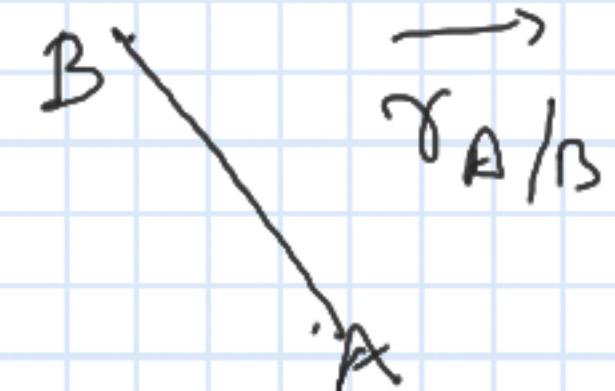
$$\overrightarrow{T}_{AB} = T_{AB}(\lambda_{AB})$$

$$\lambda_{AB} = \frac{\overrightarrow{T}_{AB}}{\overrightarrow{AB}} = \frac{(0-6)\vec{i} + (1-0)\vec{j} + (-2-0)\vec{k}}{\sqrt{6^2 + 1^2 + 2^2}}$$

$$A(6, 0, 0)$$

$$B(0, 1, -2)$$

$$C(0, 0, 0)$$



$$\vec{r}_{AB} = -6\vec{i} + \vec{j} - 2\vec{k}$$

6.4

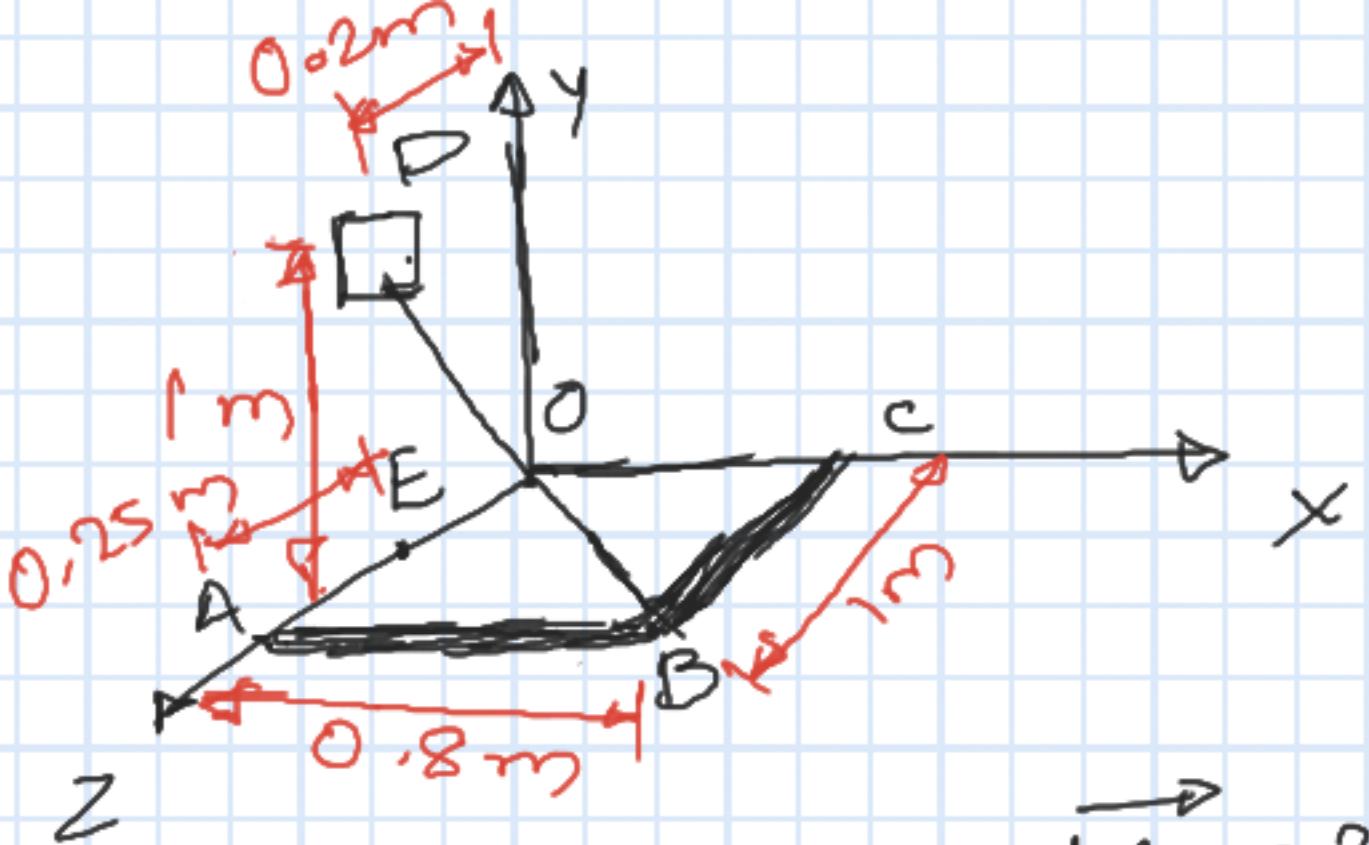
$$\vec{M}_c = \vec{r}_{A/C} \times \vec{T}_{AB}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 6 & 0 & 0 \\ -375 & 62.5 & -125 \end{vmatrix}$$

$$\vec{M}_c = 750\vec{j} + 375\vec{k}$$

$$= 750\vec{j} + 375\vec{k}$$

4. A rectangular plate $1\text{m} \times 0.8\text{m}$ is supported by two pins and by a wire BD. If the tension in the wire is 140N , calculate the moment about A. Also calculate the moment about point E'



Sol

$$O(0, 0, 0)$$

$$A(0, 0, 1)$$

$$B(0.8, 0, 1)$$

$$C(0.8, 0, 0)$$

$$D(0, 1, 0.2)$$

$$E(0, 0, 0.75)$$

$$M_A = ?$$

$$\vec{M}_A = \vec{r}_{BA} \times \vec{T}_{BD}$$

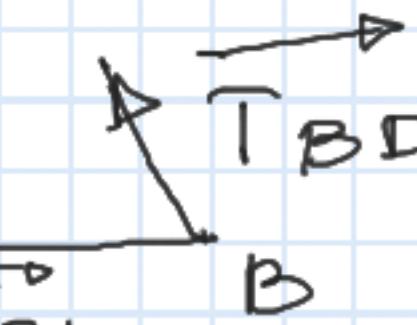
$$\vec{T}_{BD} = \vec{T}_{BD} (\lambda_{BD})$$

$$\lambda_{BD} = \frac{(0 - 0.8)\vec{i} + ((-0))\vec{j} + (0.2 - 1)\vec{k}}{\sqrt{0.8^2 + 1^2 + 0.8^2}}$$

$$= \frac{-0.8\vec{i} + \vec{j} - 0.8\vec{k}}{\sqrt{3.2}}$$

$$= -0.8\vec{i} + \vec{j} - 0.8\vec{k}$$

1.51



$$\vec{T}_{BD} = 140 \left(\frac{-0.8\vec{i} + \vec{j} - 0.8\vec{k}}{1.51} \right)$$

$$= -74.17\vec{i} + 92.71\vec{j} - 74.17\vec{k}$$

$$\vec{M}_A = \vec{\gamma}_{B/A} \times \vec{T}_{BD}$$

$$\vec{\gamma}_{B/A} = (0.8 - 0)\vec{i} + (0 - 0)\vec{j} + (1 - 1)\vec{k}$$

$$= 0.8\vec{i}$$

$$\vec{M}_A = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 0 & 0 \\ -74.17 & 92.71 & -74.17 \end{vmatrix}$$

$$\vec{M}_A = 59.34\vec{j} + 74.17\vec{k}$$

$$\vec{M}_E = \vec{\gamma}_{B/E} \times \vec{T}_{BD}$$

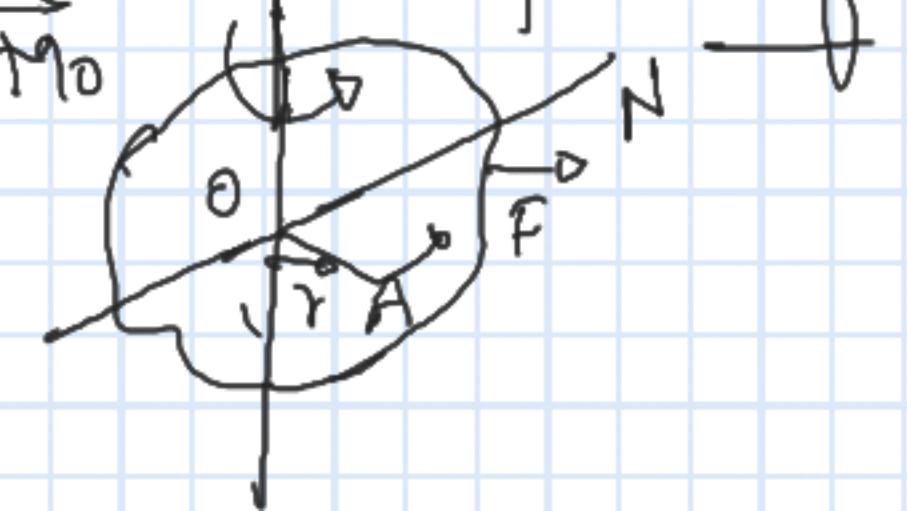
$$\vec{\gamma}_{B/E} = (0.8 - 0)\vec{i} + (0 - 0)\vec{j} + (-0.75)\vec{k}$$

$$= +0.8\vec{i} + 0.25\vec{k}$$

$$\vec{M}_E = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 0 & 0.25 \\ +0.8 & 0 & 0.25 \\ -74.17 & 92.71 & -74.17 \end{vmatrix}$$

$$= -23.18\vec{i} + 40.8\vec{j} + 74.17\vec{k}$$

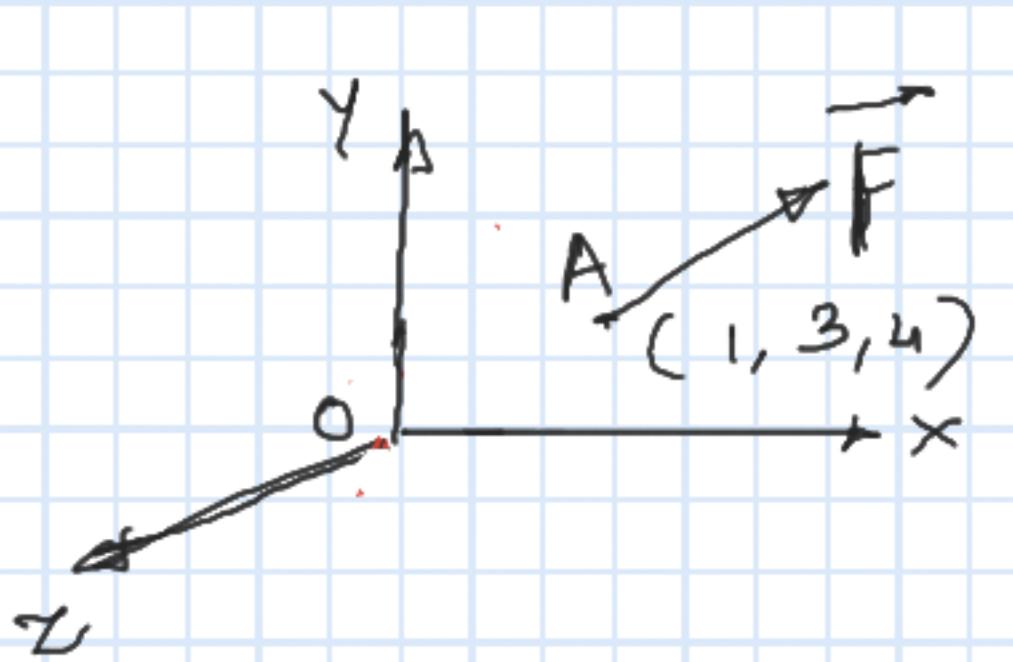
Moment of a force about an axis



(component of moment about any particular direction)

$$\overrightarrow{M_{0N}} = \gamma_{0N} \cdot \overrightarrow{M_0}$$

1. A force $\vec{F} = 3\vec{i} - 5\vec{j} + 7\vec{k}$ acts at point 'A' (1, 3, 4). Evaluate the moment produced by \vec{F} about origin 'O' (0, 0, 0) and about the three coordinate axes.



$$\begin{aligned}
 & \text{of} \\
 \overrightarrow{M_0} &= \overrightarrow{r_{0/A}} \times \vec{F} \\
 \overrightarrow{r_{0/A}} &= (1-0)\vec{i} + (3-0)\vec{j} + (4-0)\vec{k} \\
 \overrightarrow{M_0} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 3 & 4 \\ 3 & -5 & 7 \end{vmatrix} \\
 \overrightarrow{M_0} &= 21\vec{i} + 5\vec{j} - 14\vec{k}
 \end{aligned}$$

The component of the moment about x-axis

$$M_{0x} = \vec{i} \cdot \vec{M}_0 = \vec{i} \cdot (4\vec{i} + 5\vec{j} - 14\vec{k})$$

$$M_{0x} = 41$$

Similarly along y axis

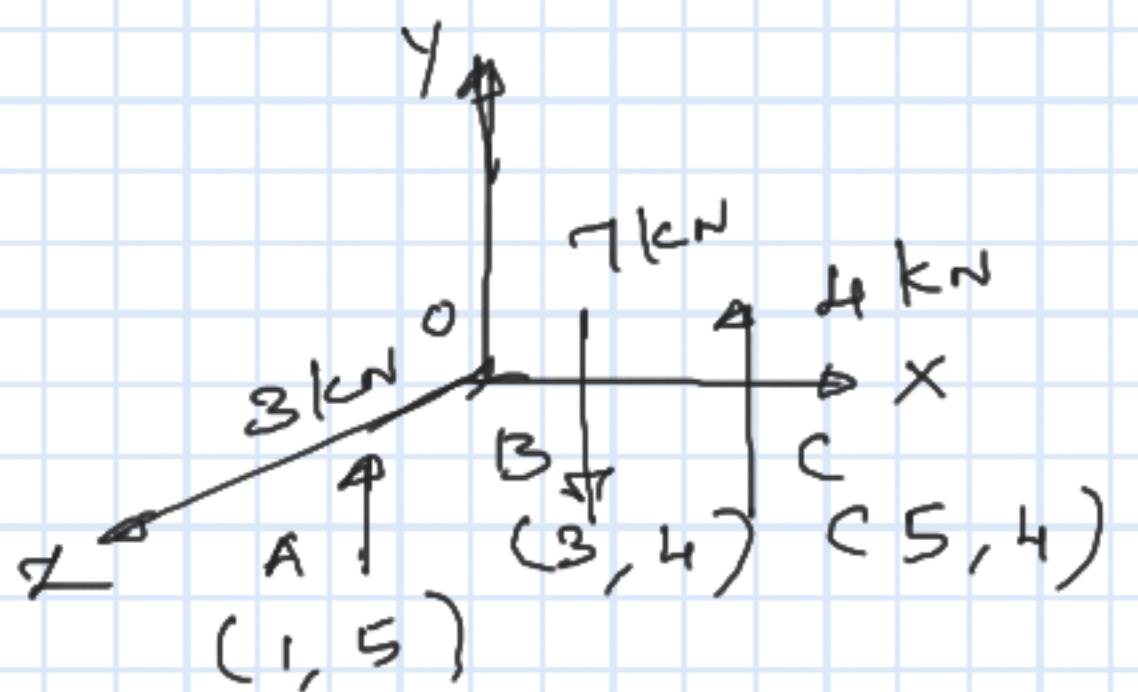
$$M_{0y} = \vec{j} \cdot \vec{M}_0 = \vec{j} \cdot (4\vec{i} + 5\vec{j} - 14\vec{k})$$

$$M_{0y} = 5$$

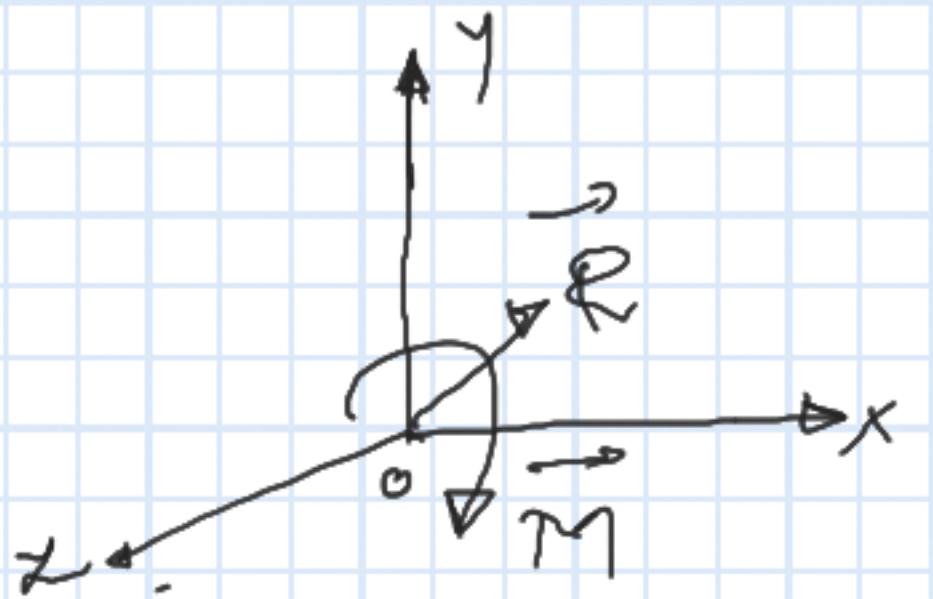
along z-axis

$$\begin{aligned} M_{0z} &= \vec{k} \cdot \vec{M}_0 = \vec{k} \cdot (4\vec{i} + 5\vec{j} - 14\vec{k}) \\ &= -14 \end{aligned}$$

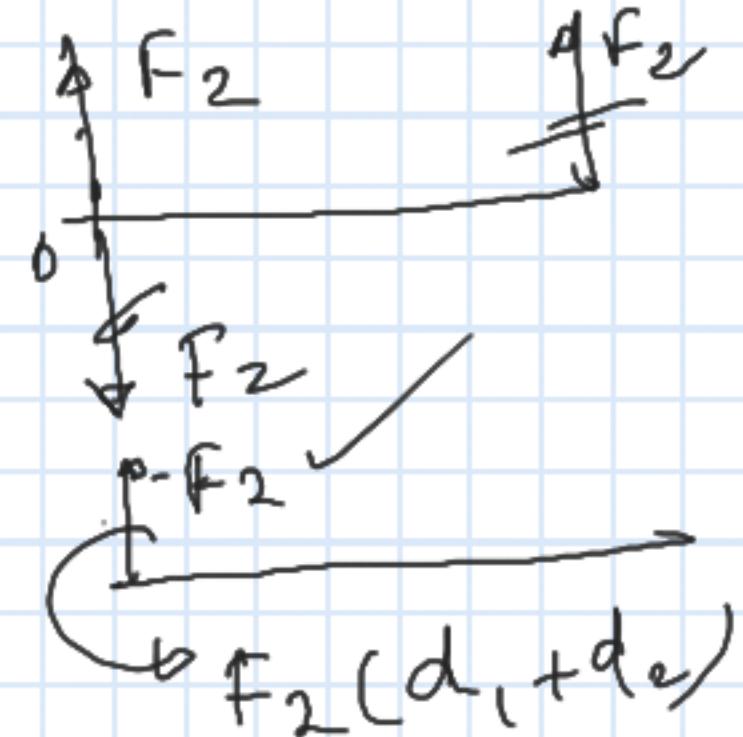
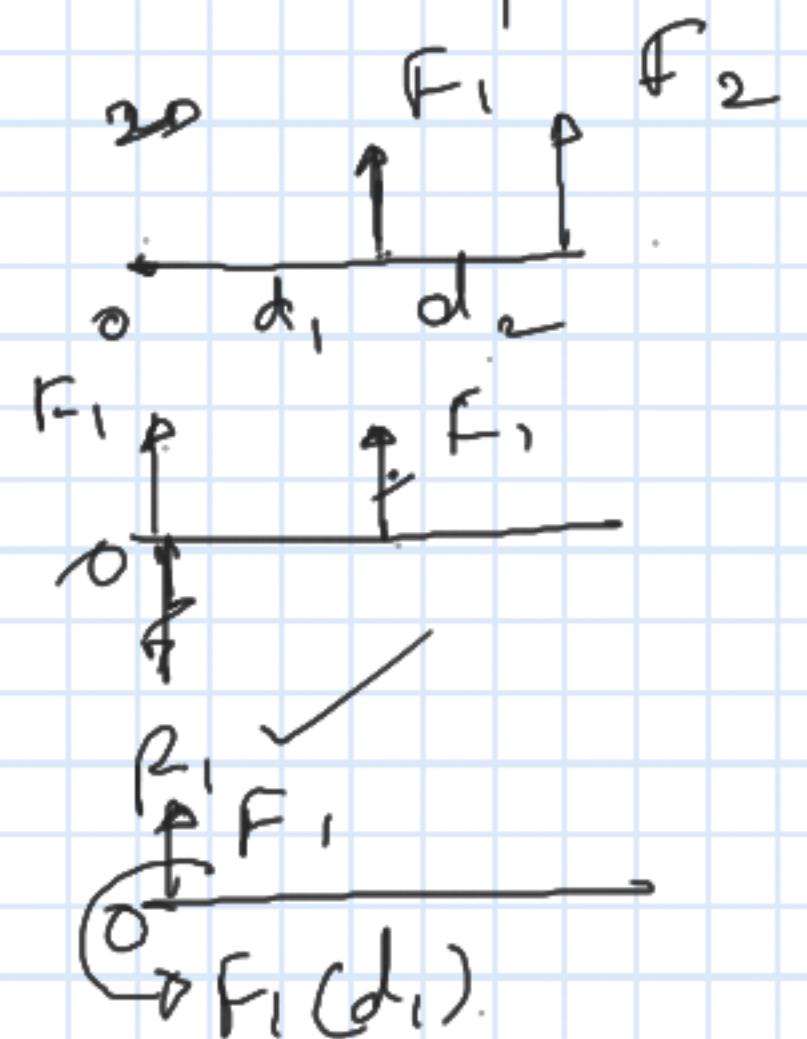
2. Determine the resultant of the given force with respect to origin



Sol.



$$\begin{aligned} \vec{R} &= \vec{F_A} + \vec{F_B} + \vec{F_C} \\ &= 3\vec{j} - 7\vec{j} + 4\vec{j} = 0 \end{aligned}$$



$$\vec{M} = (\vec{r}_{0/A} \times \vec{F}_A) + (\vec{r}_{0/B} \times \vec{F}_B) + (\vec{r}_{0/C} \times \vec{F}_C)$$

$$\vec{r}_{0/A} = (\vec{i} + 5\vec{k})$$

$$\vec{r}_{0/B} = (3\vec{i} + 4\vec{k})$$

$$\vec{r}_{0/C} = (5\vec{i} + 4\vec{k})$$

$$\vec{M} = \begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 5 \\ 0 & 3 & 0 \end{pmatrix} + \begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ 3 & 0 & 4 \\ 0 & -7 & 0 \end{pmatrix} + \begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ 5 & 0 & 4 \\ 0 & 4 & 0 \end{pmatrix}$$

$$= -3\vec{i} + 2\vec{k}$$

$$M = \sqrt{3^2 + 2^2} = 3 \cdot 6 \text{ Nm}$$