

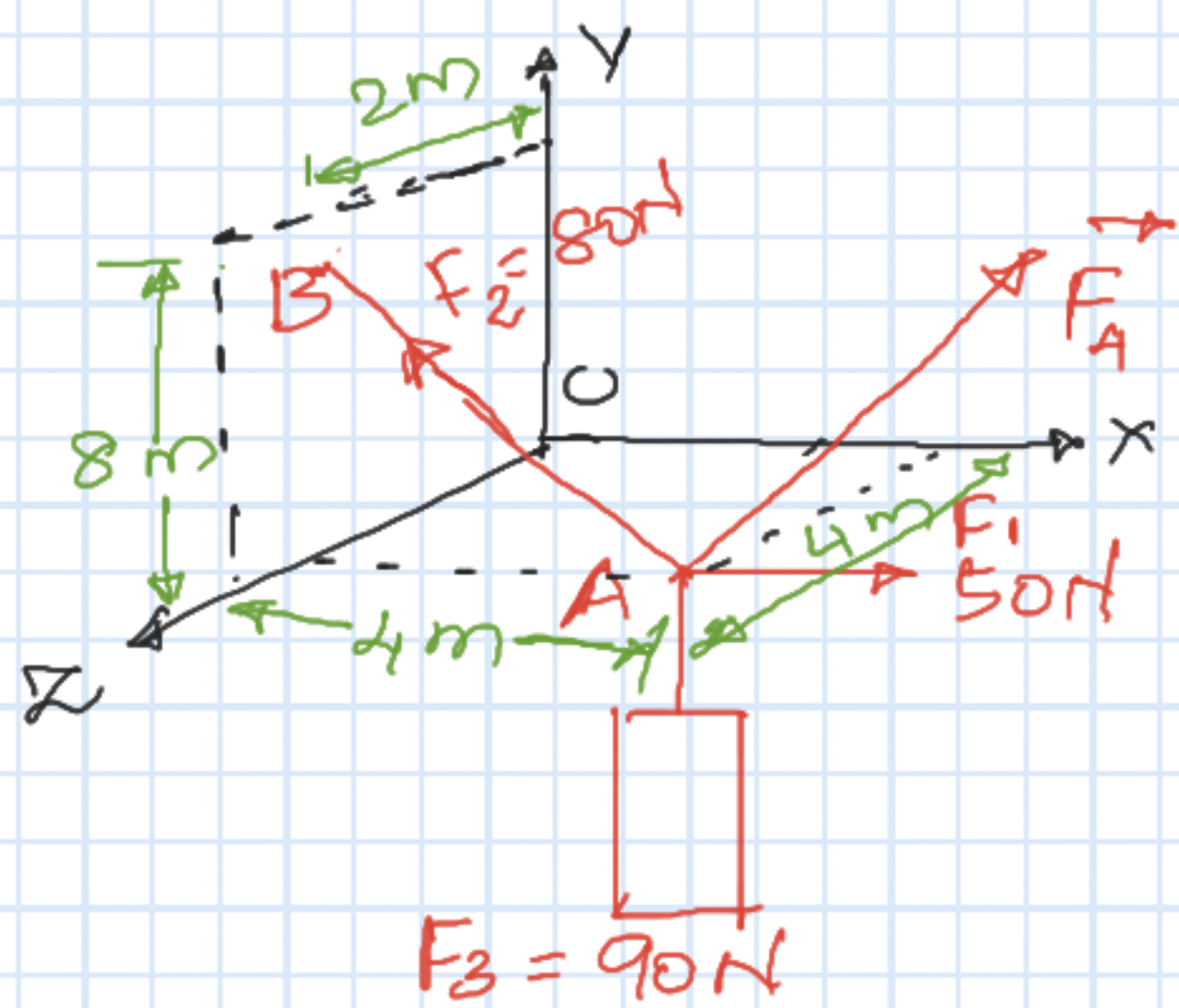
Inclination of the resultant force with the axes.

$$\phi_x = \cos^{-1} \frac{R_x}{R} = \cos^{-1} \left(\frac{40}{216.87} \right) = 79.37^\circ$$

$$\phi_y = \cos^{-1} \frac{R_y}{R} = \cos^{-1} \left(\frac{-150.72}{216.87} \right) = 134.02^\circ$$

$$\phi_z = \cos^{-1} \frac{R_z}{R} = \cos^{-1} \left(\frac{150.72}{216.87} \right) = 46.24^\circ$$

2. Three concurrent forces in space are acting at point A as shown. An unknown force \vec{F} attached to the system makes the particle A to be in equilibrium. Evaluate the magnitude and direction of the unknown force \vec{F} .



Sol. Particle is in equilibrium

$$R = 0$$

Unknowns are
 $F_{x_A}, F_{y_A}, F_{z_A}$

$$\sum F_x = 0 \quad - (1)$$

$$\sum F_y = 0 \quad - (2)$$

$$\sum F_z = 0 \quad - (3)$$

$$A(4, 0, 4)$$

$$B(0, 8, 2)$$

$$\vec{F}_1 = F_1 \vec{i} = 50 \vec{i} \quad \text{--- (1)}$$

$$\vec{F}_3 = F_3(-\vec{j}) = -90 \vec{j} \quad \text{--- (2)}$$

$$\vec{F}_2 = F_2(\lambda_{AB}) = F_2 \left(\frac{\vec{AB}}{AB} \right) = 80 \left[\frac{(0-4)\vec{i} + (8-0)\vec{j} + (2-4)\vec{k}}{\sqrt{4^2 + 8^2 + 2^2}} \right]$$

$$\vec{F}_4 = F_{x4}\vec{i} + F_{y4}\vec{j} + F_{z4}\vec{k} \quad \text{--- (4)} \quad = -34.92\vec{i} + 69.83\vec{j} - 17.46\vec{k} \quad \text{--- (3)}$$

$$\vec{R} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4 = 0$$

$$50\vec{i} - 90\vec{j} - 34.92\vec{i} + 69.83\vec{j} - 17.46\vec{k} + F_{x4}\vec{i} + F_{y4}\vec{j} + F_{z4}\vec{k} = 0$$

$$(F_{x4} + 15.085)\vec{i} + (F_{y4} - 20.17)\vec{j} + (F_{z4} - 17.46)\vec{k} = 0$$

$$F_{x4} + 15.085 = 0 \Rightarrow F_{x4} = -15.085$$

$$F_{y4} - 20.17 = 0 \Rightarrow F_{y4} = 20.17$$

$$F_{z4} - 17.46 = 0 \Rightarrow F_{z4} = 17.46$$

Magnitude of \vec{F}_4

$$F_4 = \sqrt{15.085^2 + 20.17^2 + 17.46^2}$$

$$= 30.65 \text{ N}$$

Inclination of F_4 with the axes

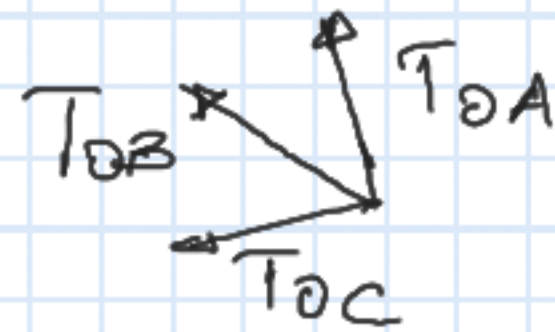
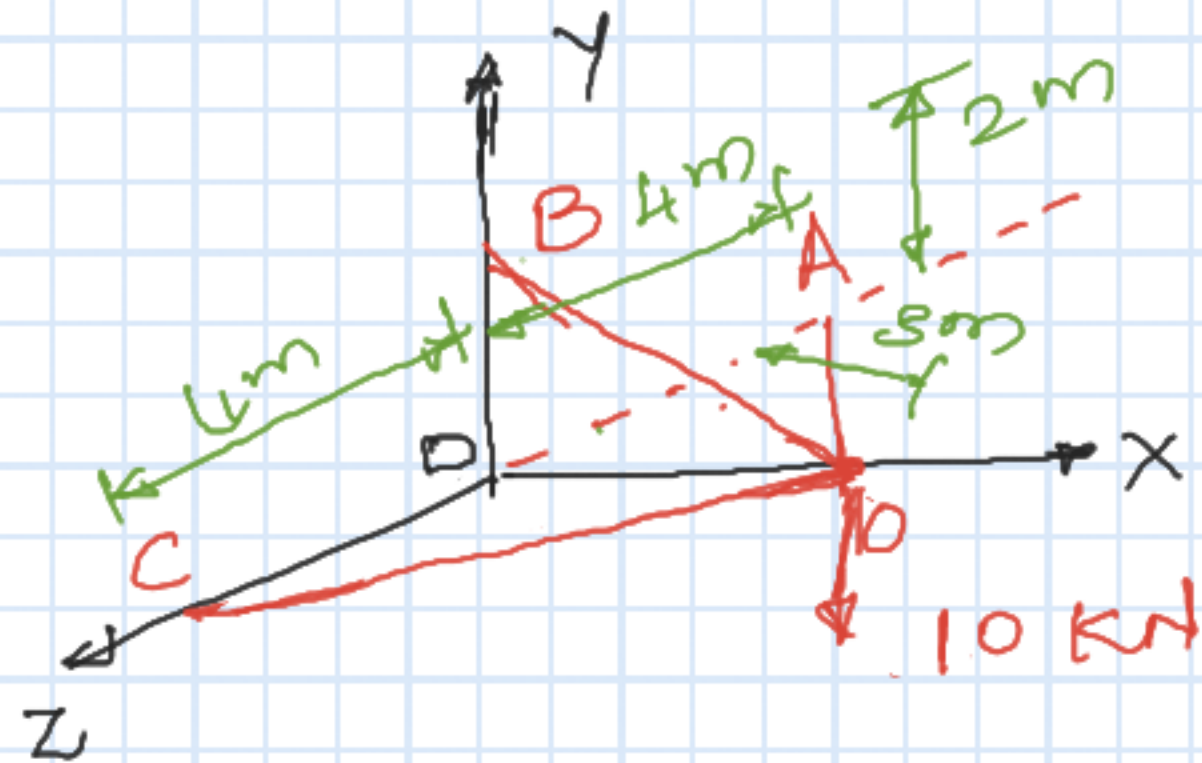
$$\alpha_x = \cos^{-1} \frac{F_x}{F} = 119.48^\circ$$

$$\alpha_y = \cos^{-1} \frac{F_y}{F} = 48.84^\circ$$

$$\alpha_z = \cos^{-1} \frac{F_z}{F} = 55.27^\circ$$

3. Problem for practice.

Members OA, OB, OC form a three member truss. A weight of 20 kN is hanging from joint O. Find the force induced in all the three members.



Sol

$$\vec{T}_{OA} = T_{OA}(\lambda_{OA})$$

$$\vec{T}_{OB} = T_{OB}(\lambda_{OB})$$

$$\vec{T}_{OC} = T_{OC}(\lambda_{OC})$$

$$A(0,0,-4) \quad D(0,0,0)$$

$$B(0,2,0) \quad O(3,0,0)$$

$$C(0,0,4)$$

$$\lambda_{OA} = \frac{\vec{OA}}{OA} = \frac{(0-3)\vec{i} + (0-0)\vec{j} + (-4-0)\vec{k}}{\sqrt{3^2 + 4^2}} \\ = \frac{-3\vec{i} - 4\vec{k}}{5} = -0.6\vec{i} - 0.8\vec{k}$$

$$\lambda_{OB} = \frac{\vec{OB}}{OB} = \frac{(0-3)\vec{i} + (2-0)\vec{j} + (0-0)\vec{k}}{\sqrt{3^2 + 2^2}} \\ = \frac{-0.832\vec{i} + 0.555\vec{j}}{1}$$

$$\lambda_{OC} = \frac{\vec{OC}}{OC} = \frac{(0-3)\vec{i} + (0-0)\vec{j} + (4-0)\vec{k}}{\sqrt{3^2 + 4^2}} \\ = \frac{-0.6\vec{i} + 0.8\vec{k}}{1}$$

$$\vec{T}_{OA} = T_{OA} (-0.6\vec{i} - 0.8\vec{k}) = -0.6 T_{OA} \vec{i} - 0.8 T_{OA} \vec{k} \quad \text{--- (1)}$$

$$\vec{T}_{OB} = T_{OB} (-0.832\vec{i} + 0.555\vec{j}) = -0.832 T_{OB} \vec{i} + 0.555 T_{OB} \vec{j} \quad \text{--- (2)}$$

$$\vec{T}_{OC} = T_{OC}(-0.6\vec{i} + 0.8\vec{k}) = -0.6T_{OC}\vec{i} + 0.8T_{OC}\vec{k} \quad \text{--- (3)}$$

Since the truss is in equilibrium $R = 0$

$$\therefore R_x = \sum F_x = 0$$

$$R_y = \sum F_y = 0$$

$$R_z = \sum F_z = 0$$

$$\vec{R} = \vec{T}_{OA} + \vec{T}_{OB} + \vec{T}_{OC} = (-0.6T_{OA} - 0.832T_{OB} - 0.6T_{OC})\vec{i} + (-10 + 0.555T_{OB})\vec{j} + (-0.8T_{OA} + 0.8T_{OC})\vec{k} = 0$$

$$-0.6T_{OA} - 0.832T_{OB} - 0.6T_{OC} = 0 \quad \text{--- (4)}$$

$$+0.555T_{OB} - 10 = 0 \quad \text{--- (5)}$$

$$-0.8T_{OA} + 0.8T_{OC} = 0 \quad \text{--- (6)}$$

Solve (4), (5) & (6)

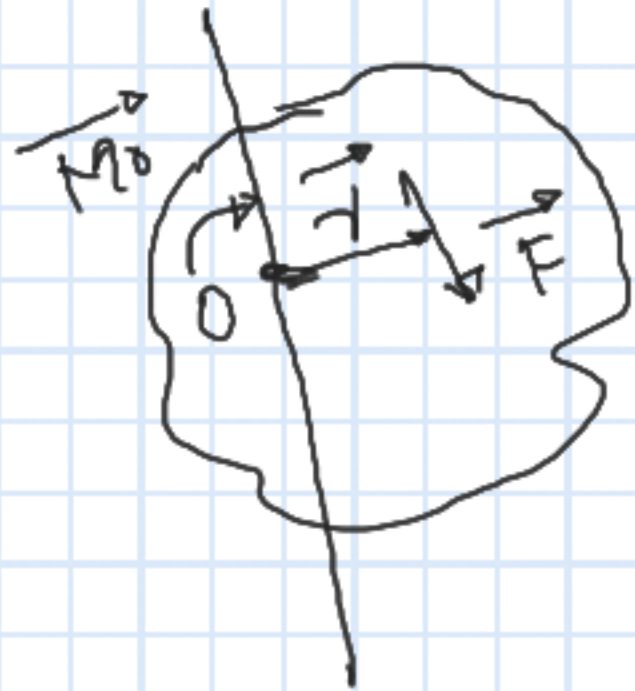
$$T_{OA} = 12.5 \text{ kN (C)}$$

$$T_{OB} = 18.02 \text{ kN (T)}$$

$$T_{OC} = 12.5 \text{ kN (C)}$$

Equilibrium of rigid bodies in 3D

Moment of a force about a point



Position vector

$$\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$$

$$\vec{F} = F_x\vec{i} + F_y\vec{j} + F_z\vec{k}$$

$$\begin{aligned}\vec{M}_O &= \vec{r} \times \vec{F} \\ &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x & y & z \\ F_x & F_y & F_z \end{vmatrix}\end{aligned}$$

$$= (F_z y - F_y z)\vec{i} - (F_z x - F_x z)\vec{j} + (F_y x - F_x y)\vec{k}$$

$$M_O = (F)(d)$$

$$\vec{M}_0 = M_x \vec{i} + M_y \vec{j} + M_z \vec{k}$$

Magnitude

$$M_0 = \sqrt{M_x^2 + M_y^2 + M_z^2}$$

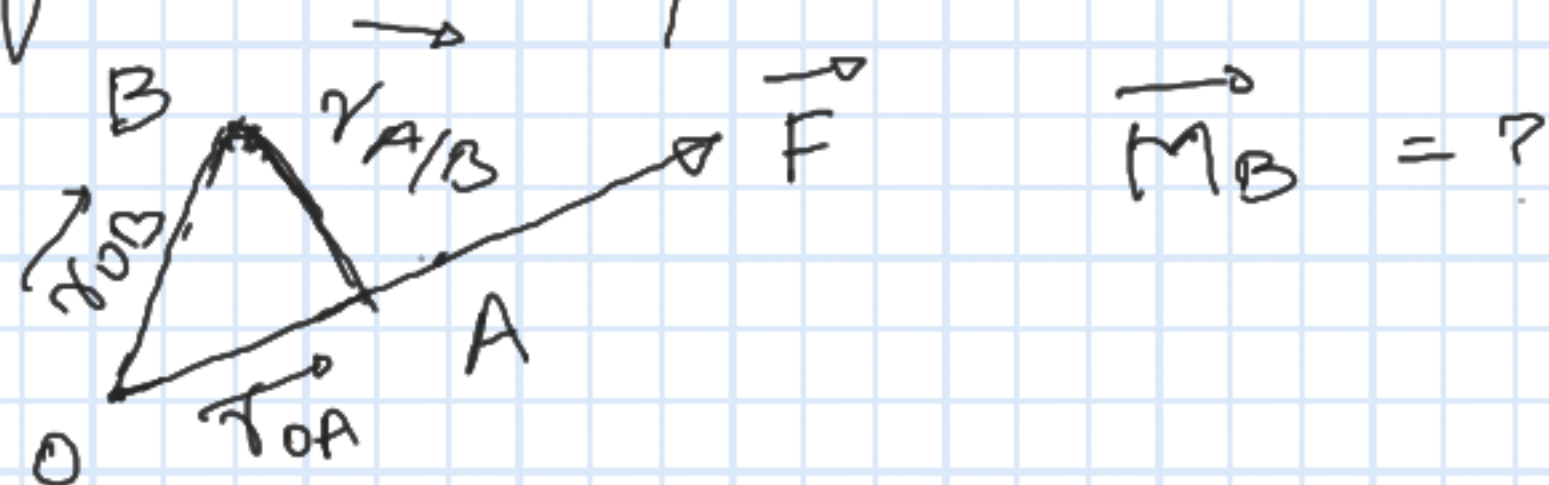
Direction

$$\alpha_x = \cos^{-1} \frac{M_x}{M}$$

$$\alpha_y = \cos^{-1} \frac{M_y}{M}$$

$$\alpha_z = \cos^{-1} \frac{M_z}{M}$$

1. A force $\vec{F} = 9\vec{i} + 3\vec{j} - 6\vec{k}$ passes through a point A whose position vector is $4\vec{i} - 2\vec{j} + 9\vec{k}$. Calculate the moment of the force about point B whose position vector is $6\vec{i} - 3\vec{j} - 7\vec{k}$.



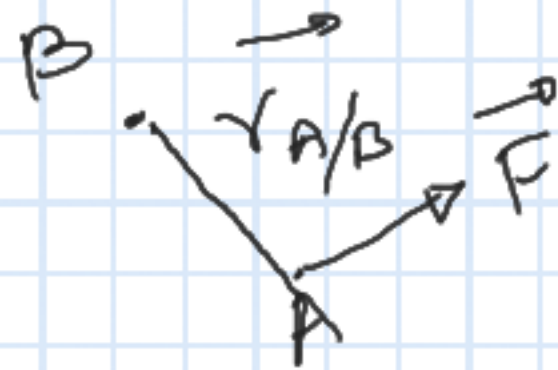
Sol. $\vec{r}_{A/B} = (\vec{r}_{OA} - \vec{r}_{OB}) = (4\vec{i} - 2\vec{j} + 9\vec{k}) - (6\vec{i} - 3\vec{j} - 7\vec{k})$

$$= (-2\vec{i} + \vec{j} + 16\vec{k})$$

$$\vec{M}_B = \vec{r}_{A/B} \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -2 & 1 & 16 \\ 9 & 3 & -6 \end{vmatrix} = -54\vec{i} + 132\vec{j} - 15\vec{k}$$

2. A force vector $\vec{F} = 6\vec{i} + 2\vec{j} - 3\vec{k}$ acts at a point A of coordinates $(1, 2, 3)$. Find the moment of the force about point B $(-2, 3, 4)$.



$$\vec{r}_{A/B} = (x_A - x_B)\vec{i} + (y_A - y_B)\vec{j} + (z_A - z_B)\vec{k}$$

$$= (1 - (-2))\vec{i} + (2 - 3)\vec{j} + (3 - 4)\vec{k}$$

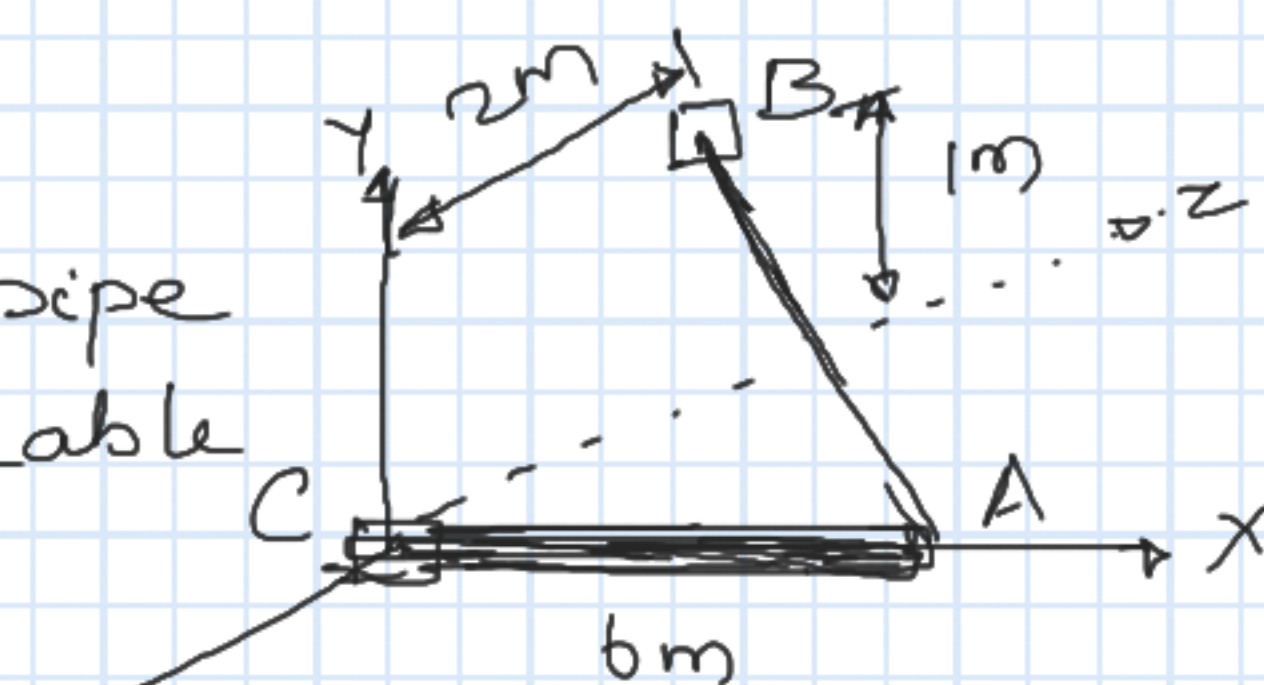
$$= 3\vec{i} - 1\vec{j} - 1\vec{k}$$

$$\vec{M}_B = \vec{r}_{A/B} \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 3 & -1 & -1 \\ 6 & 2 & -3 \end{vmatrix} = 5\vec{i} + 3\vec{j} + 12\vec{k}$$

3.

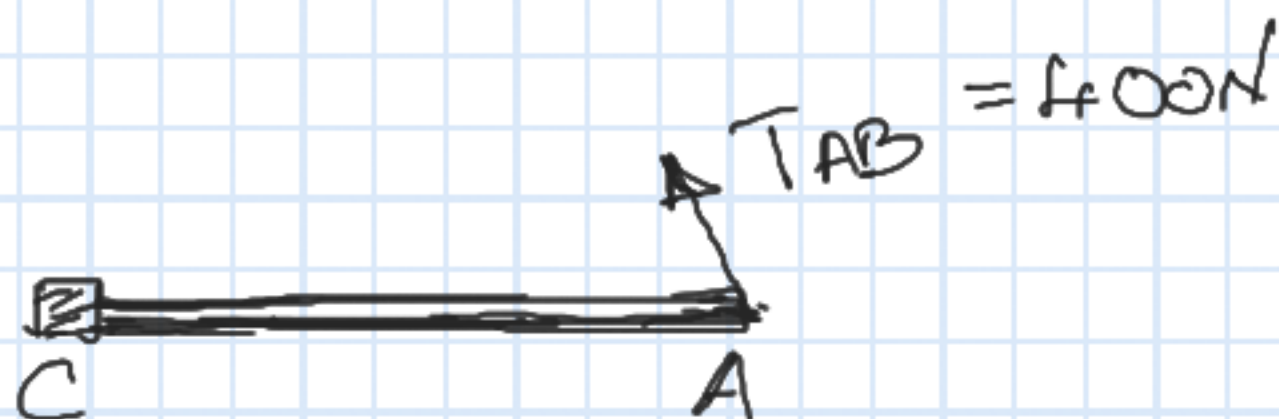
AC - pipe
AB - cable



Evaluate the moment of force at A about C.

$$T_{AB} = 400 \text{ N}$$

Solution



$$\vec{M}_C = \vec{r}_{AC} \times \vec{T}_{AB}$$

$$\vec{r}_{AC} = (6-0)\vec{i} = 6\vec{i}$$

$$\vec{T}_{AB} = T_{AB} (\lambda_{AB})$$

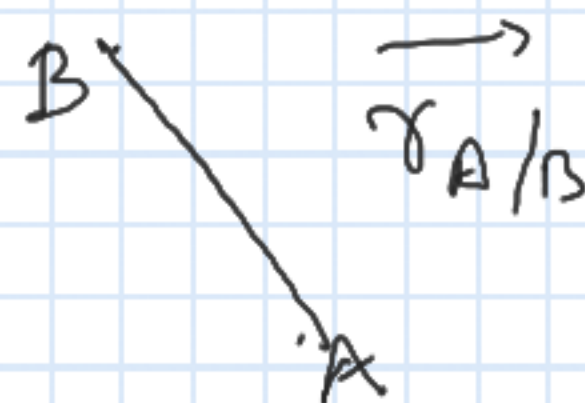
$$\lambda_{AB} = \frac{\vec{AB}}{AB}$$

$$= \frac{(0-6)\vec{i} + (1-0)\vec{j} + (-2-0)\vec{k}}{\sqrt{6^2 + 1^2 + 2^2}}$$

$$A(6, 0, 0)$$

$$B(0, 1, -2)$$

$$C(0, 0, 0)$$



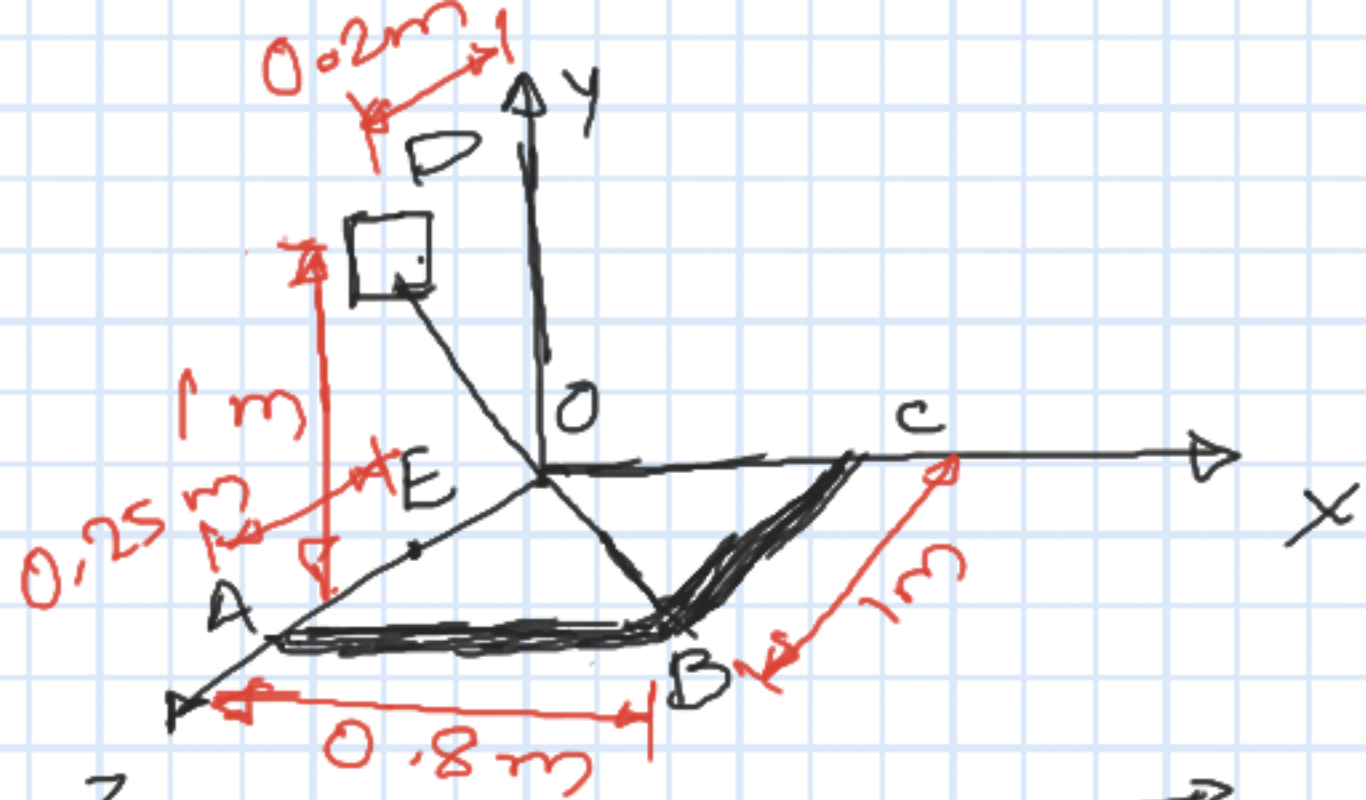
$$\vec{T}_{AB} = \frac{-6\vec{i} + \vec{j} - 2\vec{k}}{6.4}$$

$$\vec{M}_C = \vec{r}_{AC} \times \vec{T}_{AB}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 6 & 0 & 0 \\ -375 & 62.5 & -125 \end{vmatrix} = 750\vec{j} + 375\vec{k}$$

$$\vec{M}_C = 750\vec{j} + 375\vec{k}$$

4. A rectangular plate $1\text{ m} \times 0.8\text{ m}$ is supported by two pins and by a wire BD. If the tension in the wire is 140 N , calculate the moment about A. Also calculate the moment about point E.



Sol

- o (0, 0, 0)
- A (0, 0, 1)
- B (0.8, 0, 1)
- C (0.8, 0, 0)
- D (0, 1, 0.2)
- E (0, 0, 0.75)

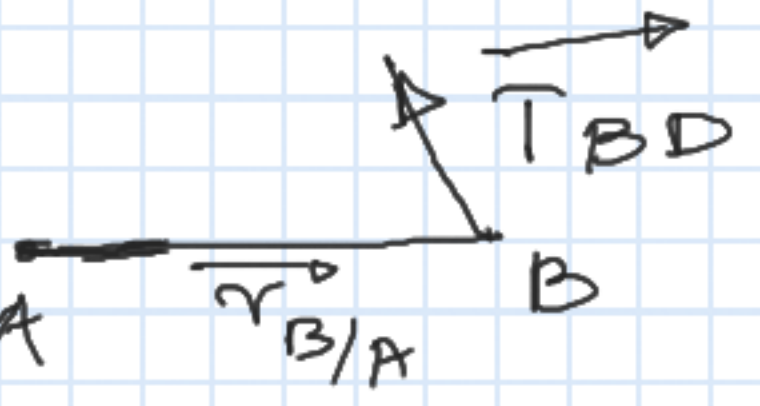
$$\vec{M}_A = ?$$

$$\vec{M}_A = \vec{r}_{B/A} \times \vec{T}_{BD}$$

$$\vec{T}_{BD} = T_{BD} (\lambda_{BD})$$

$$\lambda_{BD} = \frac{(0 - 0.8)\vec{i} + (1 - 0)\vec{j} + (0.2 - 1)\vec{k}}{\sqrt{0.8^2 + 1^2 + 0.8^2}}$$

$$= \frac{-0.8\vec{i} + \vec{j} - 0.8\vec{k}}{1.51}$$



$$\vec{T}_{BD} = 140 \left(\frac{-0.8\vec{i} + \vec{j} - 0.8\vec{k}}{1.51} \right)$$

$$= -74.17\vec{i} + 92.71\vec{j} - 74.17\vec{k}$$

$$\vec{M}_A = \vec{r}_{B/A} \times \vec{T}_{BD}$$

$$\vec{r}_{B/A} = (0.8 - 0)\vec{i} + (0 - 0)\vec{j} + (1 - 1)\vec{k}$$

$$= 0.8\vec{i}$$

$$\vec{M}_A = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0.8 & 0 & 0 \\ -74.17 & 92.71 & -74.17 \end{vmatrix}$$

$$\vec{M}_A = 59.34\vec{j} + 74.17\vec{k}$$

$$\vec{M}_E = \vec{r}_{B/E} \times \vec{T}_{BD}$$

$$\vec{r}_{B/E} = (0.8 - 0)\vec{i} + (0 - 0)\vec{j} + (1 - 0.75)\vec{k}$$

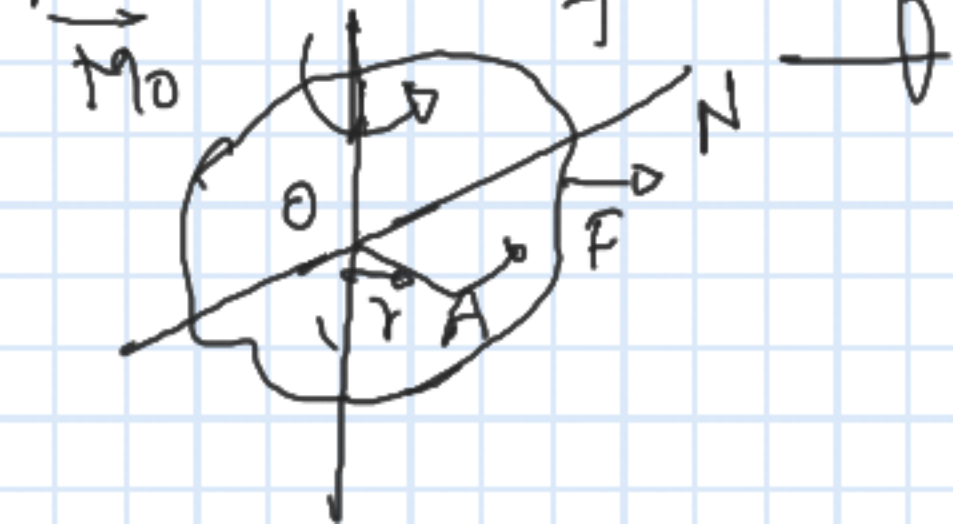
$$= +0.8\vec{i} + 0.25\vec{k}$$

$$\vec{M}_E = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ +0.8 & 0 & 0.25 \\ -74.17 & 92.71 & -74.17 \end{vmatrix}$$

$$= -23.18\vec{i} + 40.8\vec{j} + 74.17\vec{k}$$

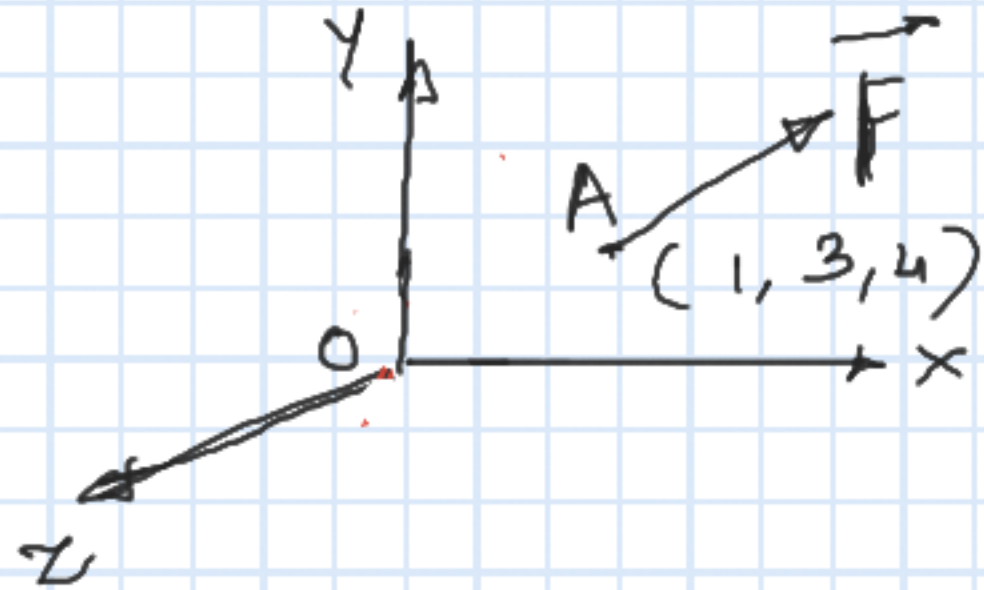
Moment of a force about an axis

(component of moment about any particular direction)



$$\vec{M}_{O/A} = \lambda_{O/A} \cdot \vec{M}_O$$

1. A force $\vec{F} = 3\vec{i} - 5\vec{j} + 7\vec{k}$ acts at point 'A' (1, 3, 4). Evaluate the moment produced by \vec{F} about origin 'O' (0, 0, 0) and about the three coordinate axes.



$$\vec{M}_O = \vec{r}_{O/A} \times \vec{F}$$

$$\vec{r}_{O/A} = (1-0)\vec{i} + (3-0)\vec{j} + (4-0)\vec{k}$$

$$\vec{M}_O = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 3 & 4 \\ 3 & -5 & 7 \end{vmatrix}$$

$$\vec{M}_O = 21\vec{i} + 5\vec{j} - 14\vec{k}$$

The component of the moment about x-axis

$$M_{0x} = \vec{i} \cdot \vec{M}_0 = \vec{i} \cdot (41\vec{i} + 5\vec{j} - 14\vec{k})$$

$$M_{0x} = 41$$

Similarly along y axis

$$M_{0y} = \vec{j} \cdot \vec{M}_0 = \vec{j} \cdot (41\vec{i} + 5\vec{j} - 14\vec{k})$$

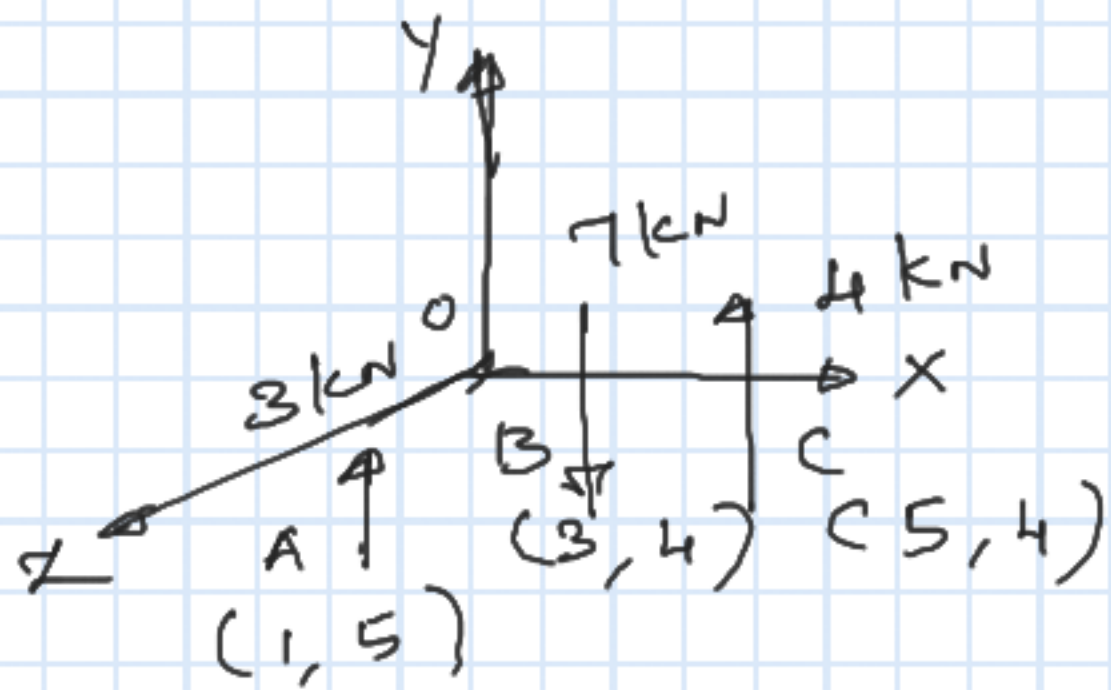
$$M_{0y} = 5$$

along z-axis

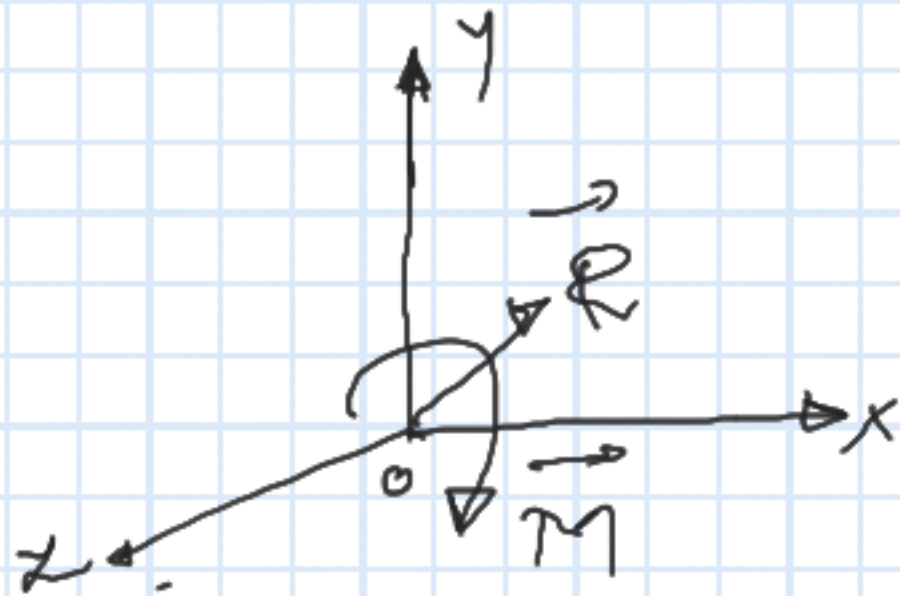
$$M_{0z} = \vec{k} \cdot \vec{M}_0 = \vec{k} \cdot (41\vec{i} + 5\vec{j} - 14\vec{k})$$

$$= -14$$

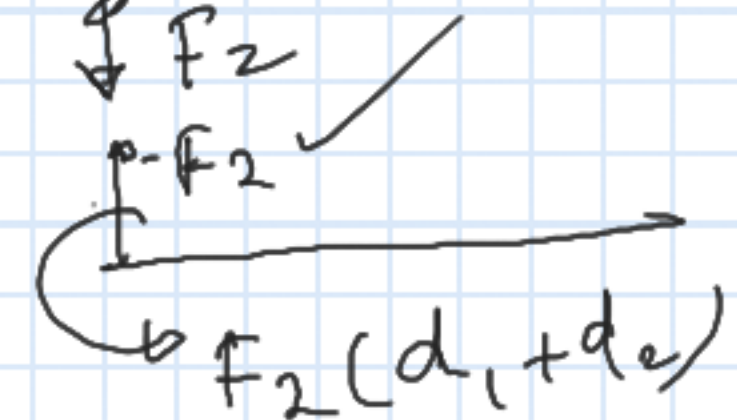
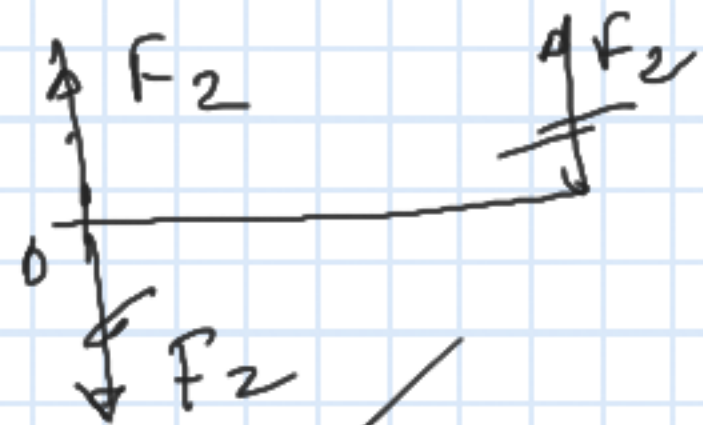
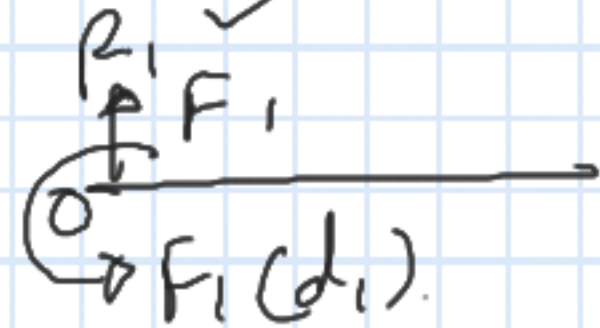
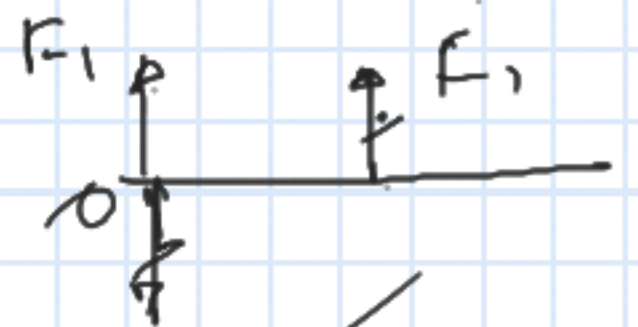
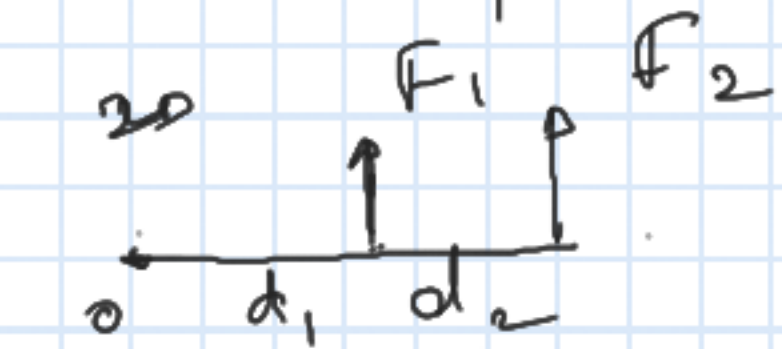
2. Determine the resultant of the given force with respect to origin.



Sol.



$$\begin{aligned} \vec{R} &= \vec{F}_A + \vec{F}_B + \vec{F}_C \\ &= 3\vec{j} - 7\vec{j} + 4\vec{j} = 0 \end{aligned}$$



$$\vec{M} = (\vec{r}_{O/A} \times \vec{F}_A) + (\vec{r}_{O/B} \times \vec{F}_B) + (\vec{r}_{O/C} \times \vec{F}_C)$$

$$\vec{r}_{O/A} = (\vec{i} + 5\vec{k})$$

$$\vec{r}_{O/B} = (3\vec{i} + 4\vec{k})$$

$$\vec{r}_{O/C} = (5\vec{i} + 4\vec{k})$$

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 5 \\ 0 & 3 & 0 \end{vmatrix} + \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 3 & 0 & 4 \\ -7 & 0 & 0 \end{vmatrix} + \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 5 & 0 & 5 \\ 0 & 4 & 0 \end{vmatrix}$$

$$= -3\vec{i} + 2\vec{k}$$

$$M = \sqrt{3^2 + 2^2} = 3.6 \text{ kNm}$$