

# Settlement Algebra and Verified Constant-Product Invariants for Batch DEX Execution

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## Abstract

We present a small, compositional mathematical model for decentralized exchange (DEX) execution and prove key safety invariants for constant-product market makers (CPMMs), including a closed-form expression for the *exact* per-swap increase in the product invariant. The development is mechanized in Lean 4/Mathlib.

The paper has three main layers: (i) an additive *settlement algebra* capturing token flows as a commutative group, with a homomorphism  $\Delta$  to a scalar “net flow”; (ii) a correctness-by-construction objective for batch auctions maximizing executed volume and surplus in lexicographic order; and (iii) a CPMM state-transition model with verified  $K$ -monotonicity and an exact “ $K$ -gap” remainder theorem, lifted compositionally to batches and bridged to the settlement/objective layers by a refinement lemma.

## 1 Overview and scope

This draft explains the mathematics and formal logic embodied by the Lean files:

- `lean-mathlib/Proofs/SettlementAlgebra.lean`: additive settlement model and the homomorphism  $\Delta$ .
- `lean-mathlib/Proofs/BatchOptimality.lean`: batch objective  $(A, B)$  (volume, surplus) and lexicographic comparison.
- `lean-mathlib/Proofs/CPMMInvariants.lean`: CPMM safety theorems, including the closed-form  $K$ -gap.
- `lean-mathlib/Proofs/CPMMSettlement.lean`: bridge from CPMM swaps to settlements.
- `lean-mathlib/Proofs/BatchCPMMUnification.lean`: unification: batch settlement safety, batch optimality additivity, and compositional  $K$  theorems for sequential swap batches.

**Important semantic caveat.** Throughout, we distinguish:

- *Scalar net-flow*  $\Delta(s) = \Delta x + \Delta y$  which adds different token units and is therefore *not* a notion of economic value conservation; and
- the *CPMM invariant*  $K = x \cdot y$  which is the standard, economically meaningful conservation law for constant-product pools.

The Lean development makes this distinction explicit and proves  $K$ -monotonicity as the primary invariant.

## 2 Preliminaries

We write  $\mathbb{N} = \{0, 1, 2, \dots\}$  and  $\mathbb{Z}$  for the integers. For  $d \in \mathbb{N}$  with  $d > 0$ , Euclidean division states that for every  $N \in \mathbb{N}$  there exist unique  $q, r \in \mathbb{N}$  such that

$$N = dq + r \quad \text{and} \quad 0 \leq r < d, \quad (1)$$

where  $q = \lfloor N/d \rfloor$  and  $r = N \bmod d$  [1].

## 3 Settlement algebra

### 3.1 Definition

**Definition 1** (Settlement). *Define the settlement space as*

$$\text{Settlement} := \mathbb{Z} \times \mathbb{Z}.$$

*An element  $s = (\Delta x, \Delta y)$  represents signed changes to two pool reserves. Positive means inflow to the pool, negative means outflow.*

**Definition 2** (Composition and identity). *Define composition as componentwise addition:*

$$(\Delta x_1, \Delta y_1) \circ_s (\Delta x_2, \Delta y_2) := (\Delta x_1 + \Delta x_2, \Delta y_1 + \Delta y_2).$$

*The identity settlement is  $0 := (0, 0)$ .*

**Proposition 1** (Abelian group structure).  *$(\text{Settlement}, \circ_s, 0)$  is an abelian group (indeed an `AddCommGroup` in `Mathlib`).*

*Proof.* Componentwise integer addition is associative and commutative, with identity  $(0, 0)$  and inverse  $-(\Delta x, \Delta y) = (-\Delta x, -\Delta y)$ .  $\square$

### 3.2 Net-flow homomorphism and balance

**Definition 3** (Net scalar flow). *Define  $\Delta : \text{Settlement} \rightarrow \mathbb{Z}$  by*

$$\Delta(\Delta x, \Delta y) := \Delta x + \Delta y.$$

**Proposition 2** (Homomorphism).  *$\Delta$  is a group homomorphism:*

$$\Delta(s_1 \circ_s s_2) = \Delta(s_1) + \Delta(s_2), \quad \Delta(0) = 0, \quad \Delta(-s) = -\Delta(s).$$

*Proof.* Immediate from distributivity of addition in  $\mathbb{Z}$ :

$$\Delta((\Delta x_1 + \Delta x_2, \Delta y_1 + \Delta y_2)) = (\Delta x_1 + \Delta x_2) + (\Delta y_1 + \Delta y_2) = (\Delta x_1 + \Delta y_1) + (\Delta x_2 + \Delta y_2).$$

$\square$

**Definition 4** (Balanced settlements). *Call a settlement balanced if  $\Delta(s) = 0$ . Equivalently,*

$$\text{Balanced} := \ker(\Delta) \subseteq \text{Settlement}.$$

**Proposition 3** (Kernel is a subgroup). *Balanced is an additive subgroup of Settlement.*

*Proof.* Kernels of homomorphisms are subgroups; explicitly: if  $\Delta(s_1) = 0$  and  $\Delta(s_2) = 0$ , then  $\Delta(s_1 \circ_s s_2) = 0$ , and if  $\Delta(s) = 0$  then  $\Delta(-s) = 0$ .  $\square$

*Remark 1* (“Safety” as a scalar predicate). The Lean development also defines a *scalar safety* predicate

$$\text{isSafe}(s) \iff \Delta(s) \geq 0.$$

This is closed under composition by the homomorphism property and monotonicity of  $+$  on  $\mathbb{Z}$ , but it should not be conflated with economic safety, since it adds different token units.

### 3.3 Swap-to-settlement embedding

**Definition 5** (Swap settlement). *Given natural amounts  $\text{amt}_{\text{in}}, \text{amt}_{\text{out}} \in \mathbb{N}$ , define the swap settlement (pool perspective)*

$$\text{swap}(\text{amt}_{\text{in}}, \text{amt}_{\text{out}}) := (\text{amt}_{\text{in}}, -\text{amt}_{\text{out}}) \in \mathbb{Z} \times \mathbb{Z}.$$

Then

$$\Delta(\text{swap}(\text{amt}_{\text{in}}, \text{amt}_{\text{out}})) = \text{amt}_{\text{in}} - \text{amt}_{\text{out}}.$$

In particular, if  $\text{amt}_{\text{in}} = \text{amt}_{\text{out}}$  then the settlement is balanced.

## 4 Batch optimality: maximizing volume and surplus

This section formalizes an objective for batch execution that is *correctness-by-construction*: invalid fills (output below minimum) are unrepresentable.

### 4.1 Intents and valid outcomes

**Definition 6** (Intent). *An intent is a pair  $i = (a, m) \in \mathbb{N} \times \mathbb{N}$ , where  $a$  is the input amount and  $m$  is the minimum acceptable output.*

**Definition 7** (Valid outcome). *For a fixed intent  $i = (a, m)$ , a valid outcome is either:*

1. *unfilled, or*
2. *filled( $o$ ) for some  $o \in \mathbb{N}$  with the proof obligation  $o \geq m$ .*

*This is implemented as a dependent inductive type in Lean (`ValidOutcome i`).*

### 4.2 Objective functions

**Definition 8** (Volume and surplus). *For intent  $i = (a, m)$  and valid outcome  $o$ :*

$$\text{volume}(o) := \begin{cases} 0 & \text{if unfilled} \\ a & \text{if filled} \end{cases} \quad \text{surplus}(o) := \begin{cases} 0 & \text{if unfilled} \\ o - m & \text{if filled with output } o \geq m. \end{cases}$$

*Because filled outcomes carry the proof  $o \geq m$ , the subtraction  $o - m$  is well-defined in  $\mathbb{N}$  (no underflow).*

**Definition 9** ( $((A, B)$  pair). Define the objective for a single intent/outcome as

$$\text{AB}(o) := (\text{volume}(o), \text{surplus}(o)) \in \mathbb{N} \times \mathbb{N}.$$

For a batch (a finite list of intent/outcome pairs), define the batch score as componentwise sum:

$$\text{AB}_{\text{batch}} := \sum_j \text{AB}(o_j).$$

In Lean this is `batchAB`, computed by a left fold with `pairAdd`.

### 4.3 Lexicographic comparison

**Definition 10** (Lexicographic order). For  $p = (p_1, p_2), q = (q_1, q_2) \in \mathbb{N} \times \mathbb{N}$ , define

$$p \preceq_{\text{lex}} q \iff (p_1 < q_1) \vee (p_1 = q_1 \wedge p_2 \leq q_2),$$

and strict order  $p \prec_{\text{lex}} q$  analogously with  $p_2 < q_2$ .

**Proposition 4** (Total preorder).  $\preceq_{\text{lex}}$  is reflexive, transitive, and total on  $\mathbb{N} \times \mathbb{N}$ , and the induced equivalence yields antisymmetry for  $\preceq_{\text{lex}}$  on pairs.

*Proof.* Standard case analysis on the first components; see Lean theorems:

- `lexLe_refl`
- `lexLe_trans`
- `lexLe_total`
- `lexLe_antisymm`

□

## 5 CPMM model and invariants

We model a constant-product pool with reserves  $(x, y) \in \mathbb{N}^2$ .

### 5.1 Zero-fee swap semantics

**Definition 11** (Zero-fee output). Given reserves  $(x, y) \in \mathbb{N}^2$  and input  $a \in \mathbb{N}$ , define the (zero-fee) output as

$$q := \left\lfloor \frac{ya}{x+a} \right\rfloor. \tag{2}$$

The updated reserves are

$$x' := x + a, \quad y' := y - q. \tag{3}$$

**State-machine view.** The swap semantics above define a deterministic transition function on states  $(x, y) \in \mathbb{N}^2$  parameterized by an input  $a \in \mathbb{N}$ :

$$\text{step}(x, y; a) := (x', y') \quad \text{where} \quad q = \left\lfloor \frac{ya}{x+a} \right\rfloor, \quad x' = x + a, \quad y' = y - q.$$

Equivalently, a sequential batch execution is just repeated application of `step` with inputs  $a_1, a_2, \dots$ .

**Lemma 1** (Output is reserve-bounded). For all  $x, y, a \in \mathbb{N}$ , the output satisfies  $q \leq y$ .

*Proof.* Since  $a \leq x + a$ , we have  $ya \leq y(x + a)$ . Dividing by the positive denominator  $x + a$  gives  $\frac{ya}{x+a} \leq y$ , and taking floors yields  $q \leq y$ . □

## 5.2 Worked example (single step)

To make the transition concrete, consider reserves  $(x, y) = (100, 200)$  and input  $a = 10$ . Then

$$q = \left\lfloor \frac{ya}{x+a} \right\rfloor = \left\lfloor \frac{200 \cdot 10}{100+10} \right\rfloor = \left\lfloor \frac{2000}{110} \right\rfloor = 18,$$

so the updated reserves are

$$(x', y') = (110, 182).$$

The product increases from  $K = 100 \cdot 200 = 20000$  to  $K' = 110 \cdot 182 = 20020$ . The exact gap identity predicts

$$r = (ya) \bmod (x + a) = 2000 \bmod 110 = 20,$$

and indeed  $K' = K + r$ .

## 5.3 The constant-product invariant and the $K$ -gap

**Definition 12** (Constant product). Define  $K(x, y) := x \cdot y$ .

**Theorem 1** ( $K$ -monotonicity). Under a zero-fee swap update (2)–(3), the product never decreases:

$$K(x', y') \geq K(x, y).$$

*Proof (via the exact  $K$ -gap identity).* We strengthen the claim by showing the exact difference is a Euclidean remainder. Let  $d := x + a$  and  $N := ya$ . By Euclidean division (1), there exist  $q, r \in \mathbb{N}$  with  $N = dq + r$  and  $0 \leq r < d$ . By definition  $q = \lfloor N/d \rfloor = \lfloor ya/(x + a) \rfloor$  which matches (2). Then:

$$\begin{aligned} K(x', y') &= (x + a)(y - q) \\ &= dy - dq \\ &= dy - (N - r) \\ &= (x + a)y - (ya) + r \\ &= xy + r. \end{aligned}$$

Thus  $K(x', y') - K(x, y) = r \geq 0$ . This is mechanized as `k_gap_exact` in `CPMMInvariants.lean`.  $\square$

**Definition 13** ( $K$ -gap remainder). Define the per-swap remainder (the  $K$ -gap) as

$$r(x, y, a) := (ya) \bmod (x + a). \quad (4)$$

Then the exact  $K$ -gap identity is

$$(x + a)(y - \left\lfloor \frac{ya}{x+a} \right\rfloor) = xy + r(x, y, a). \quad (5)$$

**Corollary 1** (Characterizations). For all  $x, y, a \in \mathbb{N}$ :

1.  $K(x', y') \geq K(x, y)$  (nonnegativity),
2.  $K(x', y') < K(x, y) + (x + a)$  (bounded increase, since  $r < x + a$ ),
3.  $K(x', y') = K(x, y)$  iff  $(x + a) \mid (ya)$  (zero remainder).

*Proof.* Each follows from (5) and standard properties of mod. See `k_gap_nonneg`, `k_gap_bounded`, `k_gap_zero_iff`.  $\square$

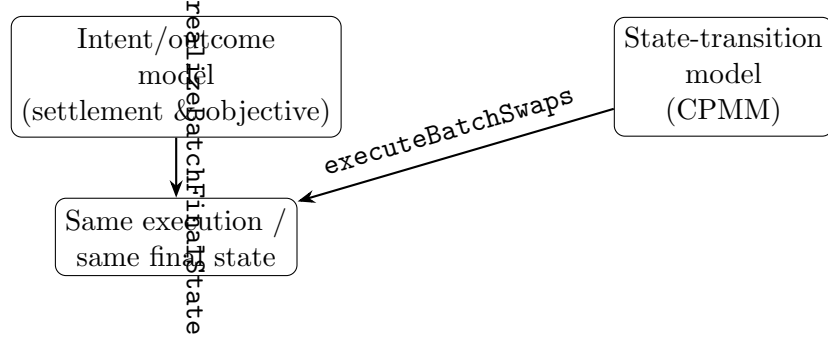


Figure 1: Two views of batch execution that agree by refinement: an intent/outcome view (used for settlement and objective computation) and a reserve state-transition view (used for CPMM invariants).

#### 5.4 Batches: telescoping the exact $K$ -gap

**Definition 14** (Sequential execution). *Fix an initial state  $(x_0, y_0)$  and a list of inputs  $[a_1, \dots, a_n]$ . Define the sequence of states by iterating (2)–(3):  $(x_i, y_i) \mapsto (x_{i+1}, y_{i+1})$  using input  $a_{i+1}$ .*

**Theorem 2** (Exact telescoping sum). *For the sequential execution above,*

$$K(x_n, y_n) = K(x_0, y_0) + \sum_{i=0}^{n-1} r(x_i, y_i, a_{i+1}), \quad (6)$$

where  $r$  is the per-step remainder (4).

*Proof.* Induction on  $n$ . The induction step applies the single-step identity (5) at state  $(x_i, y_i)$  and accumulates remainders. This is mechanized as `executeBatchSwaps_K_gap_sum`.  $\square$

**Corollary 2** (Batch  $K$ -monotonicity). *Since each remainder is nonnegative,  $K(x_n, y_n) \geq K(x_0, y_0)$  for every batch.*

## 6 Unification: settlements, objective, and CPMM state

There are two complementary models for batch execution:

1. **Intent/outcome (settlement & objective) model.** A batch is a list of pairs (intent, valid outcome). It induces: (a) an aggregated settlement in `Settlement` (for  $\Delta$ -analysis) and (b) an aggregated objective score in  $\mathbb{N} \times \mathbb{N}$  (for optimization).
2. **State-transition (CPMM) model.** A batch is a list of inputs  $[a_1, \dots, a_n]$  executed sequentially on reserves, yielding a final reserve state with verified  $K$  properties.

### 6.1 Aggregating settlements

For each intent/outcome pair, the Lean development defines a per-pair settlement: unfilled contributes 0, and filled contributes `swap(a, o)`. The batch settlement is the fold (sum) of these settlements. Using the homomorphism property, scalar net-flow composes:

$$\Delta\left(\sum_j s_j\right) = \sum_j \Delta(s_j).$$

Consequently, if each filled execution satisfies  $a \geq o$  (a *same-unit* condition), then  $\Delta$ -safety composes over the batch (`batch_safe_implies_settlement_safe`).

## 6.2 Refinement bridge and unified safety theorem

The key bridge is that the output-generating function (computing  $q_i$  sequentially) reaches the same final state as the pure state-transition fold:

$$\text{realizeBatchFinalState}(s, \vec{a}) = \text{executeBatchSwaps}(s, \vec{a}).$$

This is proved as `realizeBatch_final_state` in `BatchCPMMUnification.lean`.

As a consequence, the CPMM invariants proven for the state-transition model apply to the same execution that feeds settlement/objective computations. The combined statement is captured by `unified_batch_safety`, which simultaneously establishes:

1.  $K(\text{final}) \geq K(\text{initial})$ ,
2.  $K(\text{final}) = K(\text{initial}) + \sum \text{remainders}$  as in (6),
3. reserve-in accounting:  $x_{\text{final}} = x_{\text{initial}} + \sum_i a_i$ .

## 7 Mechanization notes

The results above are mechanized in Lean 4/Mathlib (no axioms and no `sorry`). To typecheck/build the Lean project:

```
cd lean-mathlib
lake build
```

## 8 Limitations and future work

This development is deliberately minimal and focuses on arithmetic correctness and composition. Several important directions remain:

- Multi-asset generalization: settlements as  $\mathbb{Z}^n$  vectors; richer notions of value conservation.
- Full batch clearing optimality: argmax existence over finite candidate sets and deterministic tie-breaking.
- Multi-hop routing and cross-pool execution: lifting  $K$ -style invariants across routing graphs.
- Overflow-aware models and byte-level constraints matching on-chain execution environments.
- Expanded fee models and protocol-specific mechanics (dynamic fees, rebates, TWAP/oracle guards, etc.).

## References

- [1] Euclid. Elements (Book Vii): Euclidean division. *Classical source*, 300. Standard statement: for  $N, d$  in  $\mathbb{N}$  with  $d > 0$ , there exist unique  $q, r$  s.t.  $N = dq + r$  and  $0 \leq r < d$ .